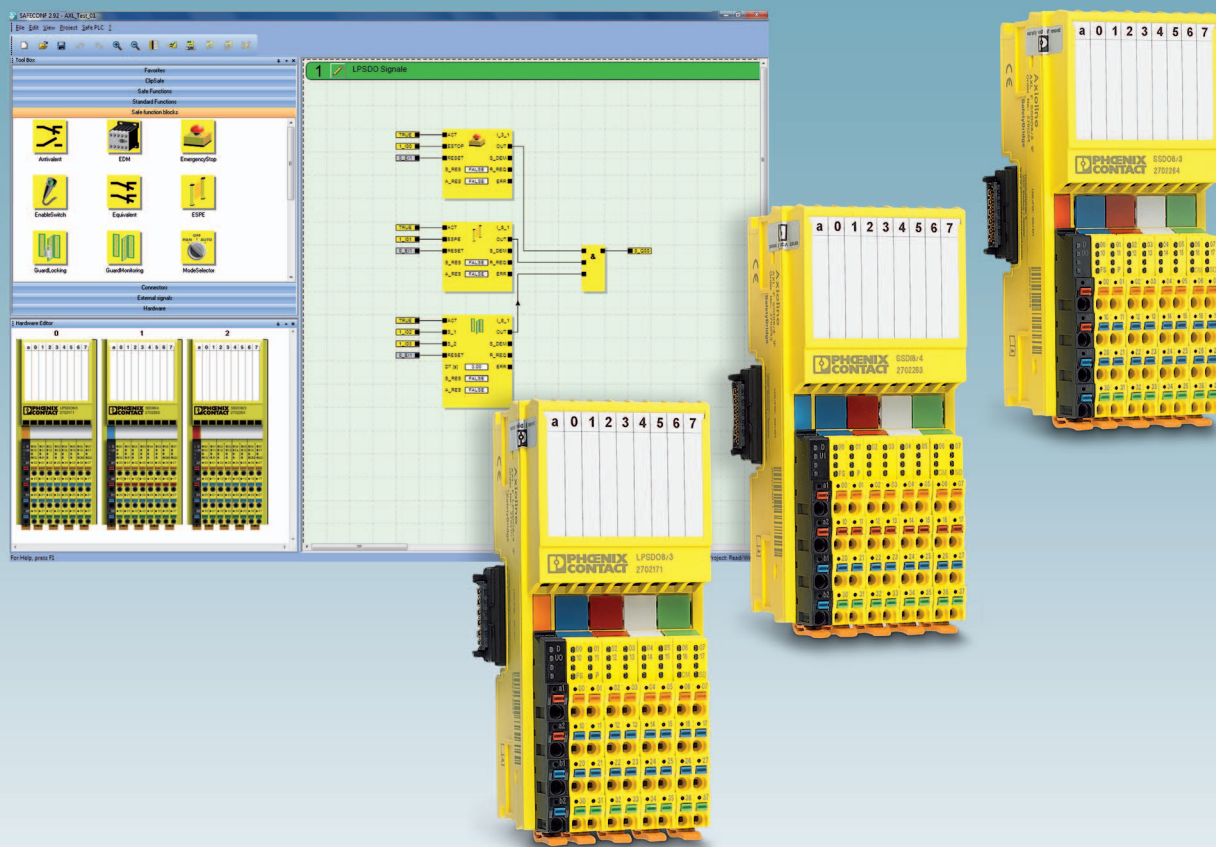




Axioline F SBT V3 configuration on an AXC 1050 controller with PC Worx

Quick start guide

Quick start guide

Axioline F SBT V3 configuration on an AXC 1050 controller with PC Worx

2016-05-18

Designation: UM QS EN AXL F SBT V3 AXC 1050 PC WORX

Revision: 00

Order No.: —

This user manual is valid for:

Designation	From HW/FW/FW version	Order No.
AXL F LPSDO8/3 1F	00/100	2702171
AXL F SSDI8/4 1F	01/200	2702263

Please observe the following notes

User group of this manual

The use of products described in this manual is oriented exclusively to qualified application programmers and software engineers, who are familiar with the safety concepts of automation technology and applicable standards.

Explanation of symbols used and signal words



This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety measures that follow this symbol to avoid possible injury or death.

There are three different categories of personal injury that are indicated with a signal word.

DANGER This indicates a hazardous situation which, if not avoided, will result in death or serious injury.

WARNING This indicates a hazardous situation which, if not avoided, could result in death or serious injury.

CAUTION This indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.



This symbol together with the signal word **NOTE** and the accompanying text alert the reader to a situation which may cause damage or malfunction to the device, hardware/software, or surrounding property.



This symbol and the accompanying text provide the reader with additional information or refer to detailed sources of information.

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Table of contents

1	Introduction	7
1.1	Purpose of this user manual	7
1.2	Requirements	7
1.3	Additional documentation	8
1.4	Safety hotline	8
2	Overview of the integration of the SafetyBridge Technology V3 system	9
3	Example project: two-channel emergency stop monitoring	11
3.1	Download and installation of the Phoenix Contact software	11
3.2	Hardware installation	12
3.2.1	Setting the device DIP switches	12
3.2.2	Mounting and wiring the bus configuration	13
3.3	Configuring the safety logic in SAFECONF	14
3.3.1	Creating a new project	14
3.3.2	Configuring and parameterizing the hardware structure	16
3.3.3	Configuring the safety function	19
3.3.4	Exporting the configuration and parameter data record	21
3.4	Configuring a PC Worx project for AXC 1050	22
3.4.1	Creating a project and configuring the bus configuration	22
3.4.2	Integrating function blocks for SafetyBridge Technology V3	23
3.4.3	Creating the SBT program in PC Worx	24
3.4.4	Process data assignment of the devices	36
3.4.5	Compiling the project and downloading it to the controller	37
3.4.6	Importing the configuration and parameter data record into the project	37
3.5	Startup	40
3.6	Online configuration and connection establishment	41
A	Flowchart for starting up and testing the application	43
B	Alternatives for importing the configuration and parameter data record	44
B 1	Copying the BIN file to the controller via FTP	44
B 2	Importing the st file in PC Worx	44
C	Description of the function blocks for SafetyBridge Technology V3	47
C 1	SBT_V3_Operate_V3_00 function block	49
C 1.1	Input parameters	50
C 1.2	Output parameters	51
C 1.3	I/O parameters	52
C 1.4	Function block diagnostics	53

Table of contents

C 2	SBT_V3_InBuff_V3_00 function block.....	54
C 2.1	Input parameters	54
C 2.2	I/O parameters	54
C 3	SBT_V3_OutBuff_V3_00 function block.....	55
C 3.1	Output parameters	55
C 3.2	I/O parameters	55
C 4	SBT_V3_BinFile_V3_00 function block.....	56
C 4.1	Input parameters	56
C 4.2	I/O parameters	56
C 5	SBT_V3_CrossComm_V3_00 function block.....	57
C 5.1	Input parameters	57
C 5.2	I/O parameters	58
C 6	SBT_V3_DataExch_V3_00 function block	58
C 6.1	Input parameters	59
C 6.2	I/O parameters	59
C 7	SBT_V3_TransTime_V3_00 function block.....	60
C 7.1	Input parameters	61
C 7.2	Output parameters	61
C 7.3	I/O parameters	61
C 8	SBT_V3_ProjHeader_V3_00 function block.....	62
C 8.1	Input parameters	62
C 8.2	Output parameters	63
C 8.3	I/O parameters	63
C 9	SBT_V3_DiagCode_V3_00 function block.....	64
C 9.1	Input parameters	65
C 9.2	Output parameters	65
C 9.3	Diagnostics examples for the function block	65
C 10	SBT_V3_Tracer_V1_00 function block.....	66
C 10.1	Input parameters	66
C 10.2	I/O parameters	66
D	Revision history	67

1 Introduction

1.1 Purpose of this user manual

This quick start guide uses an example project to describe how to integrate SafetyBridge Technology V3 modules into an AXC 1050 controller with PC Worx.

1.2 Requirements

Knowledge

Knowledge of the following is required:

- The components used in the application
- The PC Worx software used
- The Microsoft Windows operating system

Hardware

The following hardware is required in order to start up the example system:

Designation	As of HW/FW	Order No.
AXL F LPDO8/3 1F (logic module)	00/100	2702171
AXL F SSDI8/4 1F (input module)	00/200	2702263
AXL F DI8/1 DO8/1 1H (I/O module)	-	2701916
AXC 1050 (controller)	-	2700988
– Programming device/PC – Other components: emergency stop button, external reset button, signal lamp, contactor (optional)		

Software



The Phoenix Contact software can be found in the download area for the specified product at phoenixcontact.net/products.

The following software is required in order to start up the example system:

Designation	Order No.
SAFECONF V2.92 or later	2986119
Integration package for SafetyBridge Technology V3	2702171
PC Worx V6.30 or later	-
– Other software: Microsoft Windows	

1.3 Additional documentation

Please refer to the documentation for the software used, the components used in the application, and the function blocks used.

The documentation for the SafetyBridge Technology V3 modules used must be strictly observed.

Description	Type	Order No.
User manual: Axioline F module with integrated safety logic and safe digital outputs	UM EN AXL F LPSD08/3 1F	2702171
User manual: Axioline F module with safe digital inputs	UM EN AXL F SSDI8/4 1F	2702263



The documentation for Phoenix Contact devices can be found in the download area for the specified product at phoenixcontact.net/products.

1.4 Safety hotline

Should you have any technical questions, please contact our 24-hour hotline.

Phone: + 49 5281 9-462777

E-mail: safety-service@phoenixcontact.com

2 Overview of the integration of the SafetyBridge Technology V3 system

Safety with the SafetyBridge Technology V3 system

Within a SafetyBridge Technology V3 system, safety can only be ensured by using the modules of this system (AXL F LP8DO8/3 1F and 1 to 16 satellites). None of the other components in the overall system are safety-related components. Errors at non-safety-related components or errors during integration of the SafetyBridge Technology V3 system are reliably detected by the SafetyBridge Technology V3 system components. These errors only reduce the system availability but not the system safety.



No safety controllers are required for the implementation of safety functions.

Table 2-1 Integration of a SafetyBridge Technology V3 island

Step	Process	See...
1	Download and installation of the Phoenix Contact software (not safety-related)	
	– Download and install SAFECONF configuration software	page 11
	– Download and install integration package for SafetyBridge Technology V3	page 11
2	Hardware installation (not safety-related)	
	– Set device DIP switches	page 12
	– Mount and wire bus configuration	page 13 User documentation for the devices
3	Configure safety logic in SAFECONF (safety-related)	
	– Create new project, assign safety island number	page 14, page 16
	– Configure the hardware structure	page 16
	– Parameterize I/O channels	page 17
	– Configure safety function	page 14
	– Export configuration and parameter data record	page 21 SAFECONF online help
4	Configure a PC Worx project for AXC 1050 (not safety-related)	
	– Create project and insert modules	page 22
	– Integrate function blocks for SafetyBridge Technology V3	page 23
	– Create SBT program in PC Worx	page 24 PC Worx online help
	– Process data assignment of the devices	page 36

Overview of the integration of the SafetyBridge Technology V3 system

Table 2-1 Integration of a SafetyBridge Technology V3 island

Step	Process	See...
	– Compile project and download it to the controller – Import configuration and parameter data record	page 37 page 37
5	Startup and overall safety validation (safety-related)	page 40

System overview:

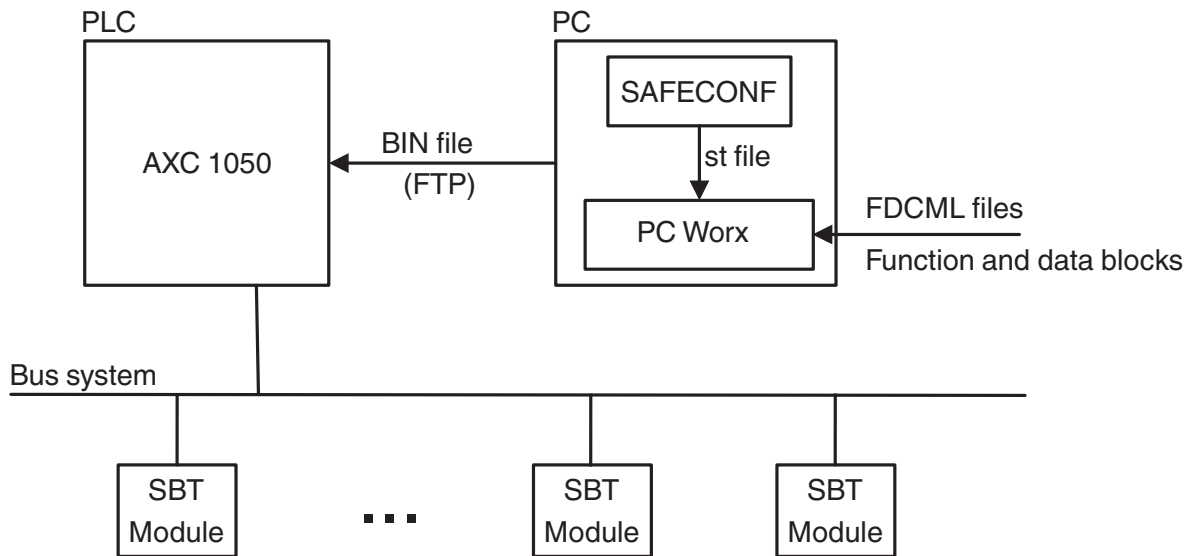


Figure 2-1 System overview of SafetyBridge Technology V3

3 Example project: two-channel emergency stop monitoring

3.1 Download and installation of the Phoenix Contact software



The Phoenix Contact software can be found in the download area for the specified product at phoenixcontact.net/products.

Make sure that you always use the latest version of the integration package as well as the correct version of the function blocks for the PC Worx software version. See "Software" on page 7.

SAFECONF

1. Download the SAFECONF configuration software and install the software (Order No. 2986119).

SBT V3 integration package

2. Download the integration package for SafetyBridge Technology V3 (Order No. 2702171).

Software

	Description	Language	Revision
☒	[exe, 123 MB] Software SafetyBridge technology integration package for controllers from Phoenix Contact, Rockwell and Siemens (S7-1200 from CPU 1214C, S7-1500, S7-300), Schneider as well as CODESYS-based controllers. SBT_V3_PLC_Integration_Packages_2.0.exe	International	2.0

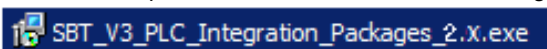
Figure 3-1 Integration package in the download area for Order No. 2702171



The integration package contains additional file formats so that the SAFECONF configuration can be saved as a BIN file for PC Worx. In addition, the integration package installs an exe file which creates the PC Worx function blocks for SafetyBridge.

3. Install the integration package as follows:

- Run setup and select "Phoenix Contact" during installation.



- Open "Windows Start menu, All Programs, Phoenix Contact, SBT V3 for SAFECONF 2.92, Phoenix Contact, SBT V3 Functionblocks".
- Install the Siemens function blocks.



Please make a note of where the library files are installed, as you will need this information later when you open the library in PC Worx.

3.2 Hardware installation

3.2.1 Setting the device DIP switches

To implement the example project, make the following settings at the DIP switches of the SafetyBridge Technology V3 modules before installing the bus configuration.

Table 3-1 Setting the DIP switches

	CM		Island number					Satellite number				
	Operating mode	Reserved	SafetyBridge Technology V3 address: 32 _{dec} (20 _{hex})									
DIP switch	11	10	9	8	7	6	5	4	3	2	1	0
Setting for AXL F LPSDO8/3 1F	off	on	0	0	0	0	1	0	0	0	0	0
			1 _{dec}					0 _{dec}				

	CM		Island number					Satellite number				
	Operating mode	Reserved	SafetyBridge Technology V3 address: 33 _{dec} (21 _{hex})									
DIP switch	11	10	9	8	7	6	5	4	3	2	1	0
Setting for AXL F SSDI8/4 1F	off	on	0	0	0	0	1	0	0	0	0	1
			1 _{dec}					1 _{dec}				



You can display the complete DIP switch setting in the SAFECONF configuration software by right-clicking on the module and selecting "Display address switch". See Figure 3-10 on page 17.

Example project: two-channel emergency stop monitoring

3.2.2 Mounting and wiring the bus configuration



Refer to the user documentation for the devices.
See "Additional documentation" on page 8.

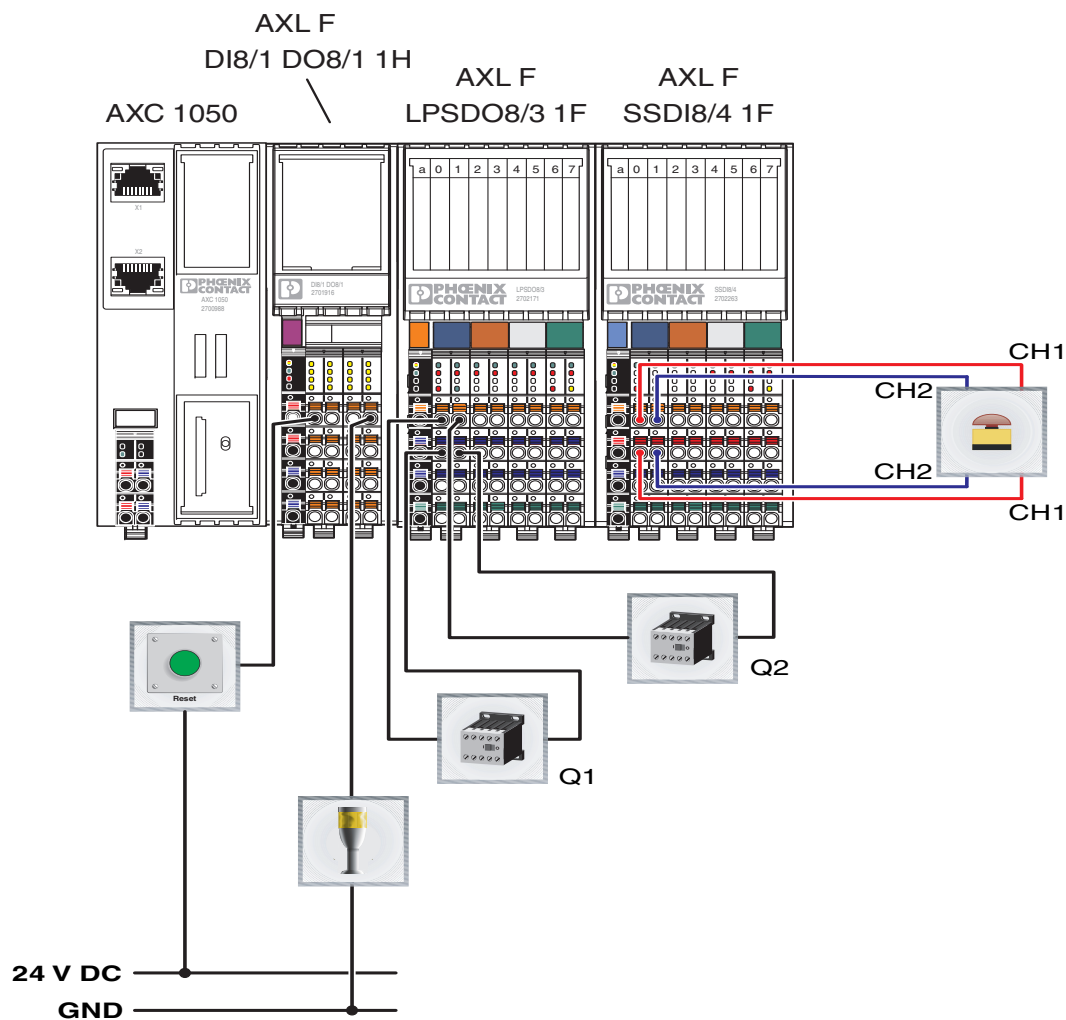


Figure 3-2 Bus configuration for example project

1. After setting the DIP switches on the modules, mount the bus configuration as illustrated.
2. Connect the power supply for the controller and I/O modules in accordance with the corresponding the user documentation.
3. Connect channel 1 of the emergency stop button to terminal points 00 and 10 and channel 2 to terminal points 01 and 11 of the SSDI8/4 module.
4. Connect the external reset button to the AXL F DI8/1 DO8/1 1H module.
5. Connect a signal lamp to the AXL F DI8/1 DO8/1 1H module.
6. Optional: connect contactors to terminal points 00 and 10, as well as to 01 and 11 of the LPDO8/3 module.

3.3 Configuring the safety logic in SAFECONF



If you have any questions about SAFECONF, please refer to the online help for the software.

3.3.1 Creating a new project

- Open the SAFECONF software.
- Create a new project with the Project Wizard.
To do this, select “File, New Project”.
- Specify the name and storage location for the project.



Do not use spaces, dashes or special characters. Note the name and storage location for the project as you will need this information later.

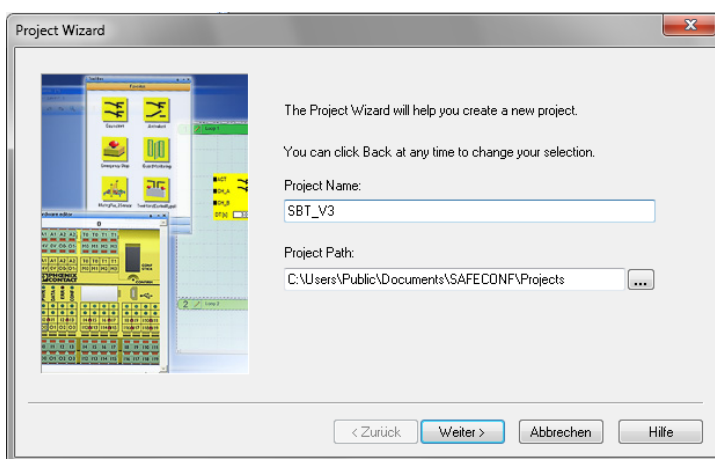


Figure 3-3 Creating the project name and path

Select master device

- Select the AXL F LPSDO8/3 1F master device.

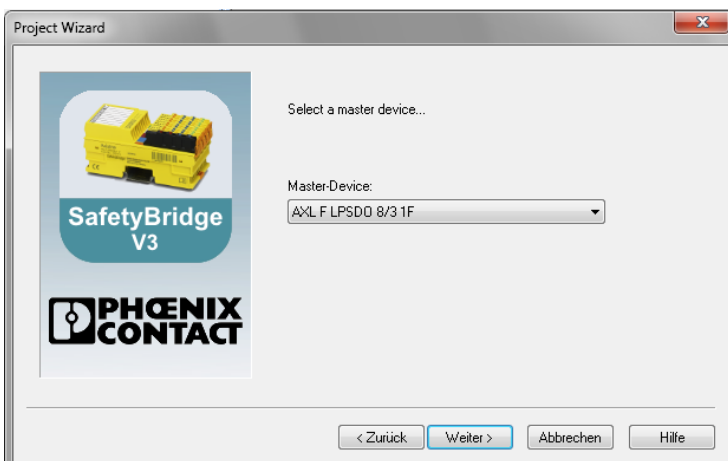


Figure 3-4 Selecting AXL F LPSDO8/3 1F

Example project: two-channel emergency stop monitoring

Select file format

- Select “Binary file” as the file format in which the configuration and parameter data record is to be output.



Alternatively, select “**PC Worx**” to output the configuration and parameter data record as an **st file**. For additional information on this process, please refer to Appendix B on page 44.

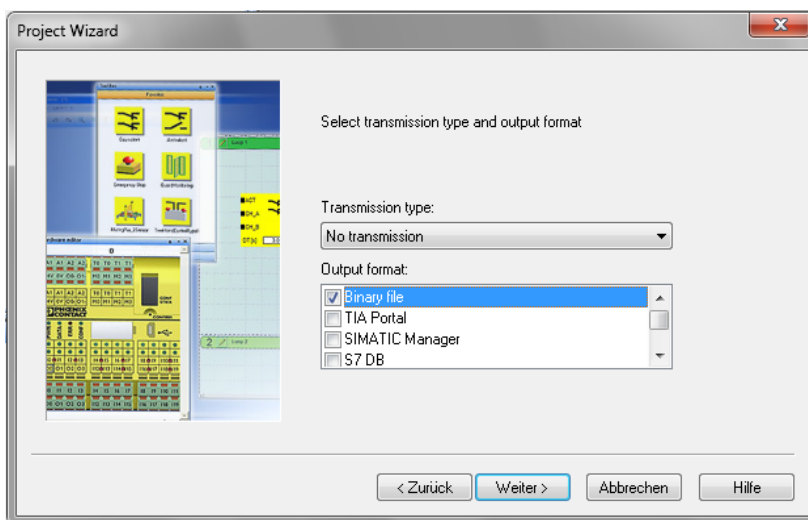


Figure 3-5 Selecting the output format

Enter project description

- Enter a description of the project.



Use a maximum of four characters for the description and version and a maximum of eight characters for the file name.

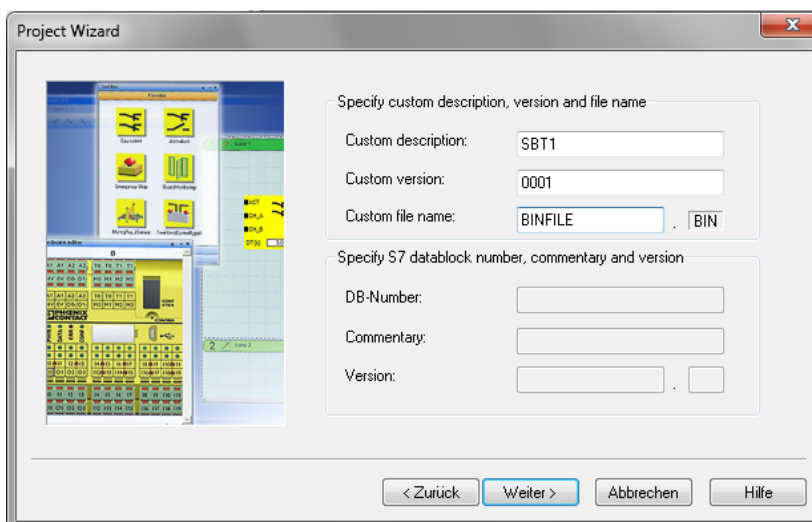


Figure 3-6 Describing the project

Example project: two-channel emergency stop monitoring

Assign safety island number

- Click on “Finish” to complete the project creation process.

When the project is completed, a window opens prompting you to enter the number for the safety island you are configuring.

- Enter an island number (1 in the example).

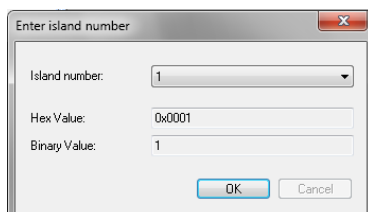


Figure 3-7 Specifying the island number

Specify password

- Specify a password of at least six characters for the project (123456 in the example).



Figure 3-8 Specifying a password

3.3.2 Configuring and parameterizing the hardware structure

- Configure the hardware structure.
To do this, use drag and drop to move the AXL F SSDI8/4 1F module from the “Hardware” toolbox to the hardware editor.

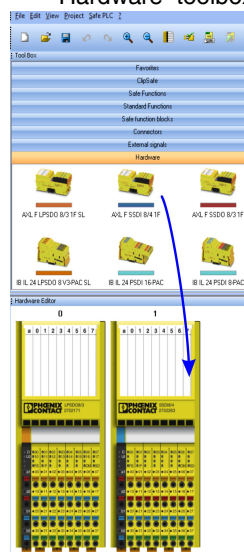


Figure 3-9 Hardware configuration

Example project: two-channel emergency stop monitoring



The corresponding satellite number is displayed via the module.
You can display the complete DIP switch setting by right-clicking on the module and selecting "Display address switch".

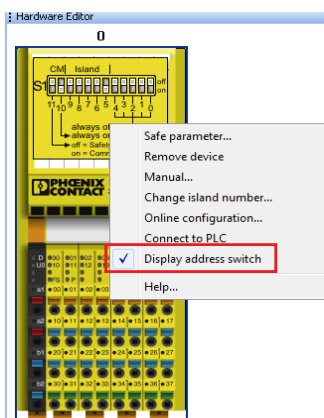


Figure 3-10 Displaying the DIP switch

Parameterize I/O channels

There are two options for parameterizing the input and output channels of the modules:

- 1 In the hardware editor, double-click on the module. This opens the window for parameterizing the entire module.
 - 2 In the hardware editor, double-click on a terminal point. This opens the window for parameterizing the selected terminal point.
- Parameterize the output channels of the LPSDO8/3 module as illustrated (double-click on the module to parameterize).

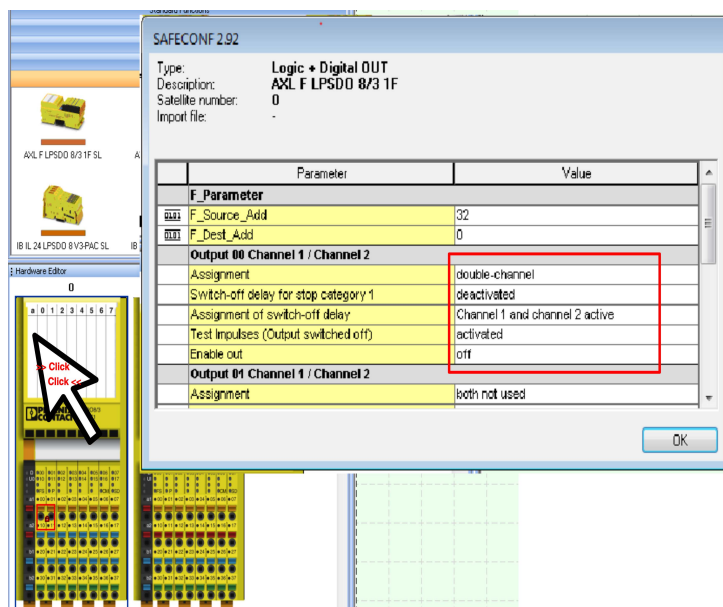


Figure 3-11 Parameterization of the LPSDO8/3

Example project: two-channel emergency stop monitoring

- Parameterize the input channels of the SSDI8/4 module (double-click on the module to parameterize).

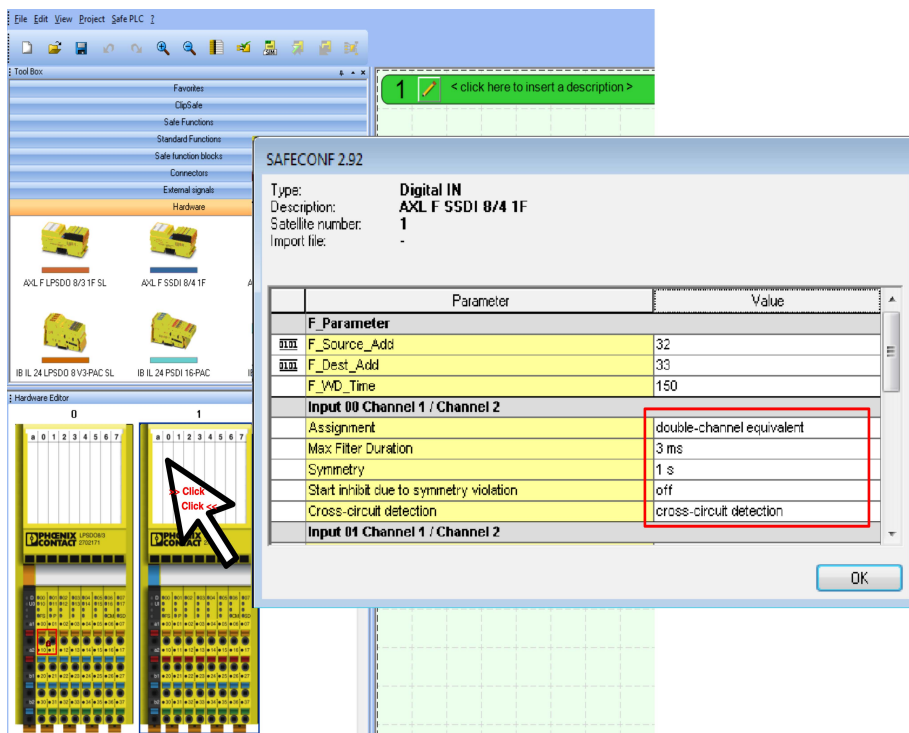


Figure 3-12 Parameterization of the SSDI8/4



Inputs or outputs parameterized for two-channel operation are indicated by a padlock symbol on the module in the hardware editor.

However, the input and output signals are only displayed in single-channel form in the connection editor, even if they are parameterized for two-channel operation. See Figure 3-14 on page 19.

3.3.3 Configuring the safety function

Comment function



You can add comments to both function blocks and signals in SAFECONF. Please refer to the online help for the software.

Insert function blocks

- Configure the safety function. To do this, use drag and drop to move the blocks and signals from the corresponding toolboxes to the connection editor.

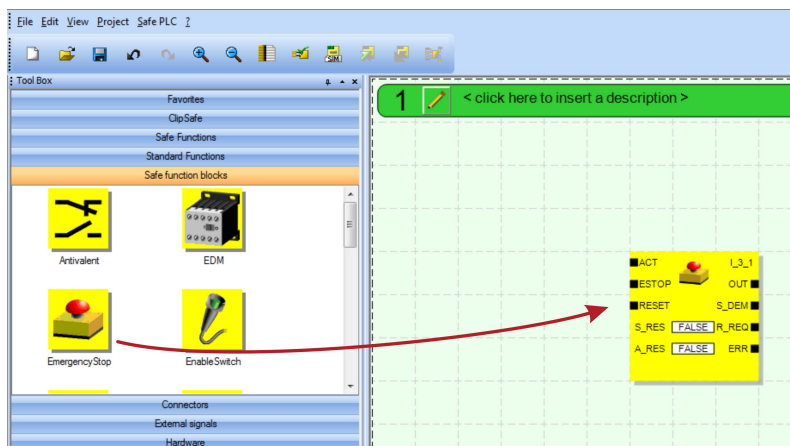


Figure 3-13 Inserting a function block from the "Safe function blocks" toolbox

Insert safe inputs and outputs

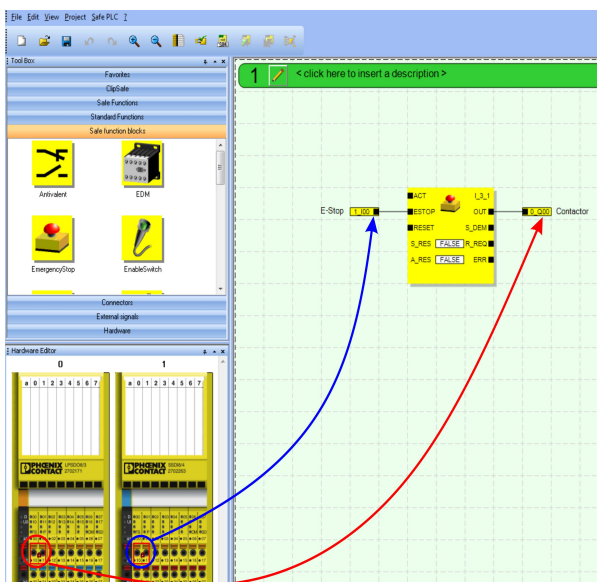


Figure 3-14 Inserting safe inputs and outputs from the hardware editor



When you use drag and drop to place the safety module terminal point directly onto a function block input or output, the connecting line is created automatically.

Example project: two-channel emergency stop monitoring

Insert external signals

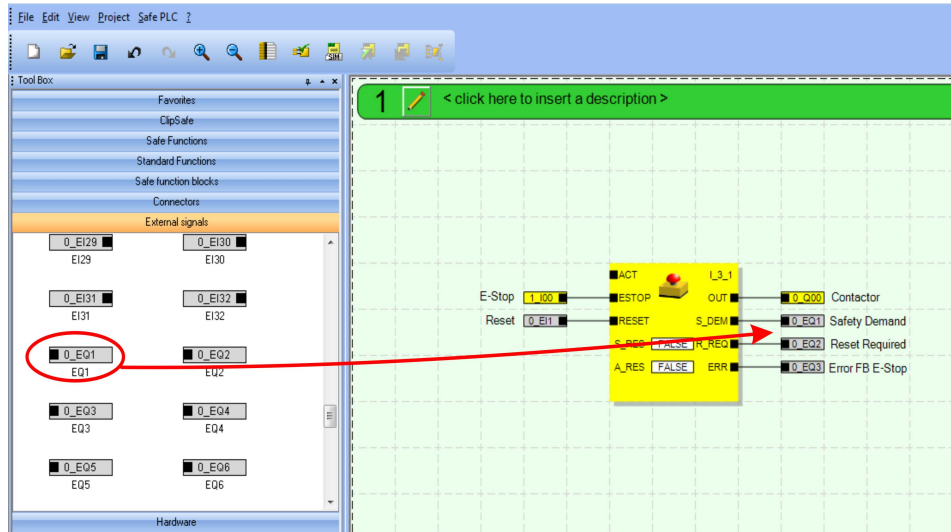
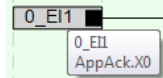


Figure 3-15 Inserting external signals from the “External signals” toolbox



Move your mouse over an external signal to display the corresponding tool tip.



Insert safe functions

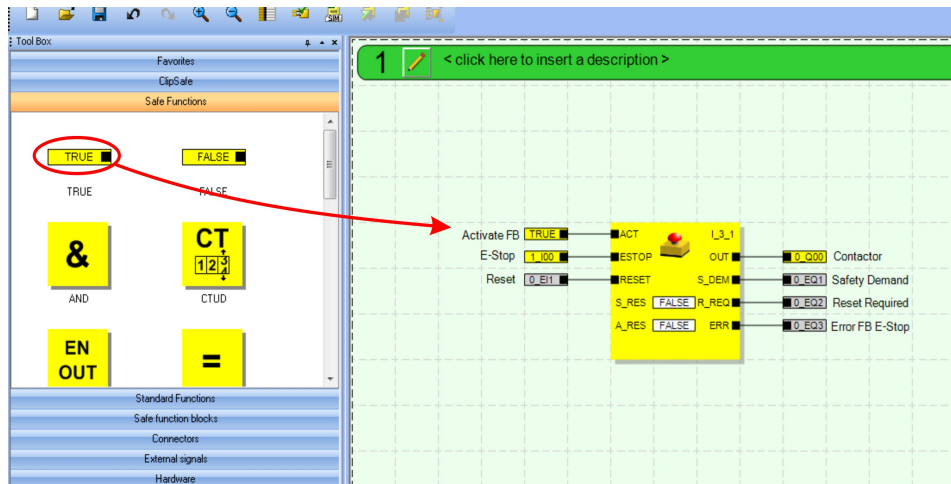


Figure 3-16 Inserting a safe function from the “Safe Functions” toolbox

3.3.4 Exporting the configuration and parameter data record

Check project

- Check the project.
To do this, select the “Project, Check Project” command or confirm by clicking  on the corresponding button.

A message window opens displaying the progress of the check. Once the check is complete, the amount of program memory used by the program is displayed.

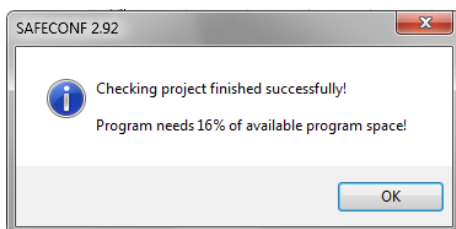


Figure 3-17 Program memory used

BIN file for standard controller

If the check is completed without errors, the configuration and parameter data record is created as a BIN file. This is saved in the path that you have entered for the project (see Figure 3-3 on page 14) in the “FileOutput” folder.



Figure 3-18 BIN file in the “FileOutput” folder

st file for PC Worx (alternative)



If you have selected “**PC Worx**” as the output format for the configuration and parameter data record (see Figure 3-5 on page 15), the **st file** is saved in the “FileOutput” folder. For additional information on this process, please refer to Appendix B on page 44.

3.4 Configuring a PC Worx project for AXC 1050



If you have any questions about PC Worx, please refer to the online help for the software.

3.4.1 Creating a project and configuring the bus configuration

- Create a new project in PC Worx with the AXC 1050 controller.
- Select the following modules in the device catalog and use drag and drop to move them to the bus configuration under the INTERBUS node:
 - AXL F DI8/1 DO8/1 1H (Order No. 2701916)
 - AXL F LPSD08/3 1F (Order No. 2702171)
 - AXL F SSDI8/4 1F (Order No. 2702263)

Insert modules

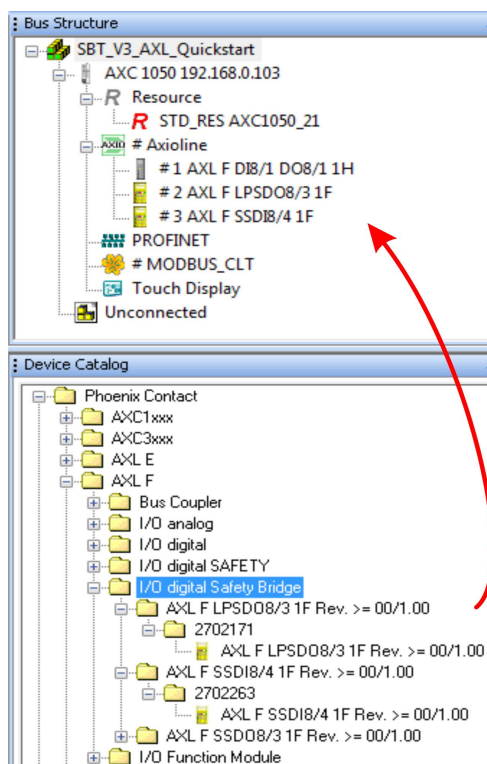


Figure 3-19 Inserting SBT modules in the device overview

Specify IP address

- Specify the device properties.

Table 3-2

Node	Tab	Setting	Example
AXC 1050	IP setting	IP address	192.168.0.2

3.4.2 Integrating function blocks for SafetyBridge Technology V3

Integrate library from integration package

- Switch to “IEC Programming” view.
- In the project tree window, select “Libraries, Insert, User Library”.

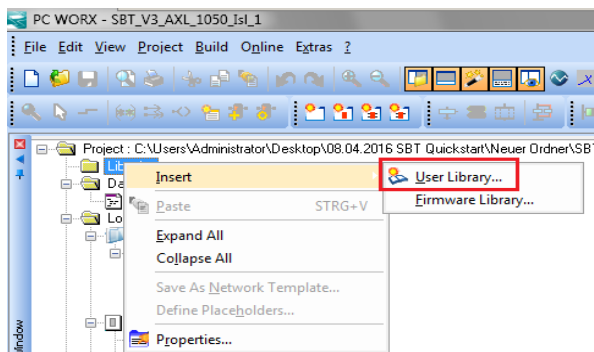


Figure 3-20 Integrating the library I

- Open the directory where the library files from the integration package for SafetyBridge Technology V3 were installed earlier.
See page 11 in Section 3.1, “Download and installation of the Phoenix Contact software”.

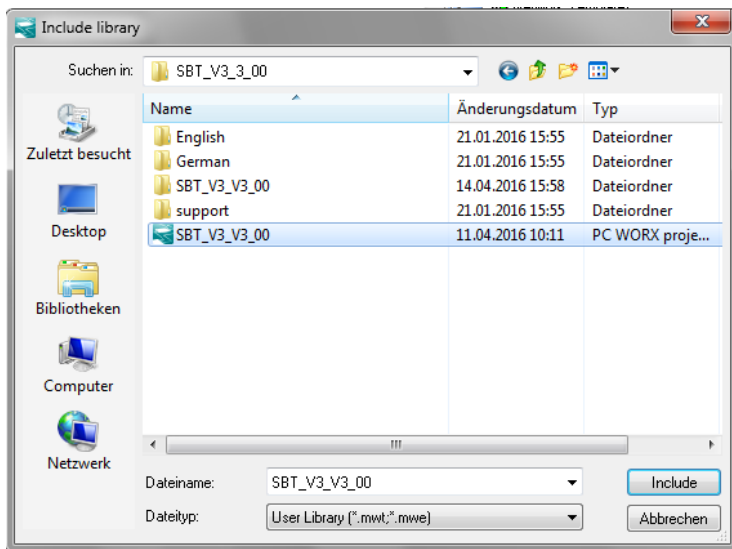


Figure 3-21 Integrating the library II

Example project: two-channel emergency stop monitoring

- Open file “SBT_V3_V3_00.mwt”.

The Edit Wizard window now contains the open “SBT_V3_V3_00” library with the corresponding SafetyBridge function blocks.

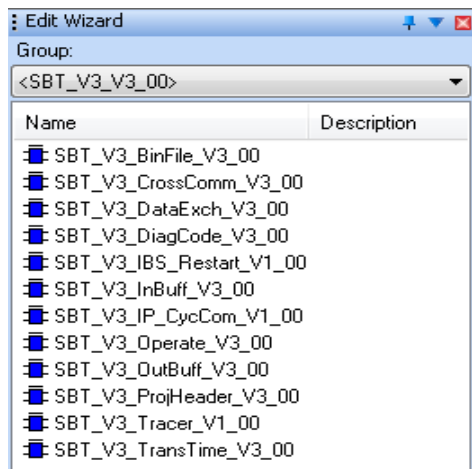


Figure 3-22 Library integrated



A description of the function blocks and data types is provided in Appendix C “Description of the function blocks for SafetyBridge Technology V3”.
Please also use the online help in PC Worx.

3.4.3 Creating the SBT program in PC Worx

Proceed as follows to extend your standard application program using the SafetyBridge function blocks from the “SBT_V3_V3_00” library:

Insert logical POUs

- In the project tree window, insert the “SBT_Island” program under “Logical POUs”.

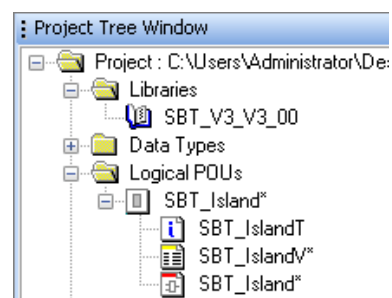


Figure 3-23 Inserting logical POUs

Example project: two-channel emergency stop monitoring

Create cyclic task

Proceed as follows to create a “cyclic task” in the hardware structure:

- Select the “Task” folder and then select “Task...” in the context menu.

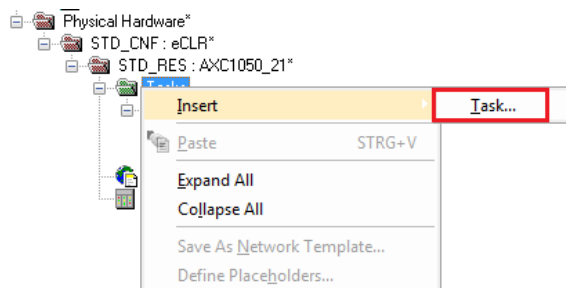


Figure 3-24 Inserting a cyclic task

- Specify “SBT_Run” for the task name and select “CYCLIC” as the task type.

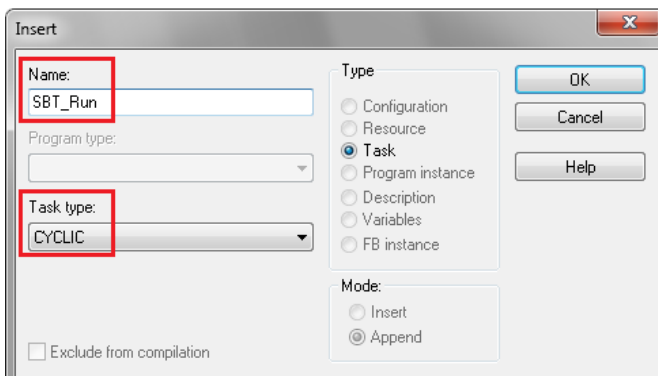


Figure 3-25 Assigning a name and selecting the task type

- In the following window for the task settings, set 10 ms in the “Interval” field.

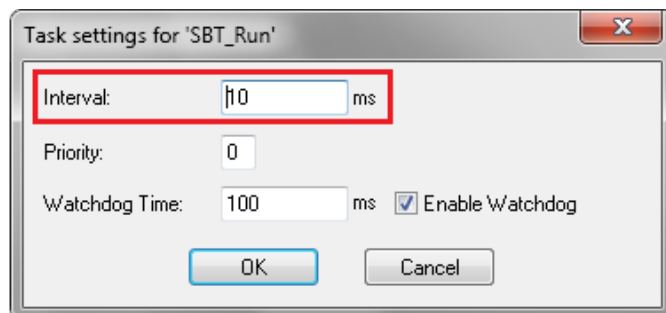


Figure 3-26 Making the task settings



The created task prevents potential communication interruptions by periodically calling the SafetyBridge function blocks at fixed intervals.

Example project: two-channel emergency stop monitoring

Add “SBT_Island” program instance

Add the “SBT_Island” program instance to the task as follows:

- Select the “SBT_Run : CYCLIC” task and then select “Insert, Program instance...” in the context menu.

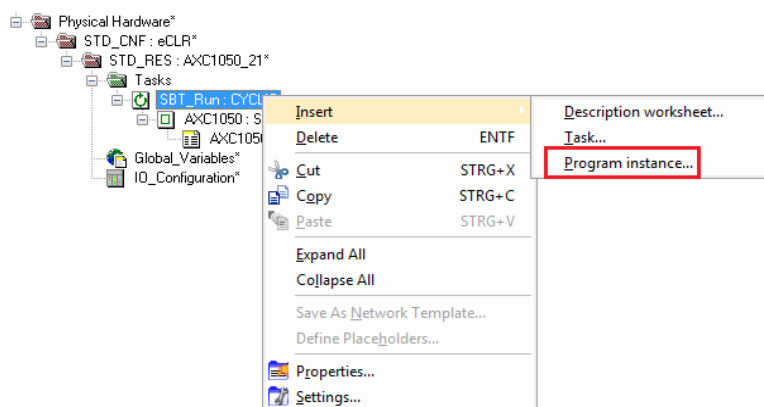


Figure 3-27 Inserting the program instance

- Enter “AXC 1050” in the “Program instance” field and select “SBT_Island” as the program type.

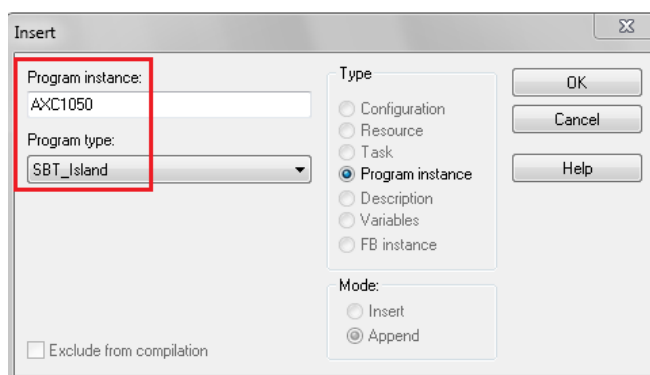


Figure 3-28 Assigning a name and selecting the program type

Complete project tree

The complete project tree now has the following structure.

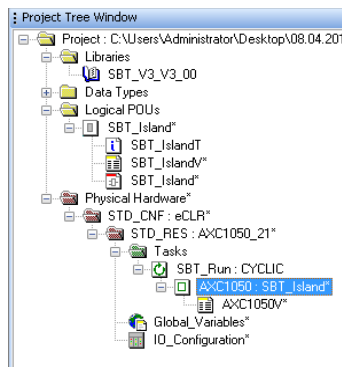


Figure 3-29 Complete project tree

Example project: two-channel emergency stop monitoring

To insert and connect the required SafetyBridge function blocks in your project, proceed as follows:

“SBT_V3_Operate_V3_00” function block

- Select the “SBT_Island” program.
- Insert the “SBT_V3_Operate_V3_00” function block in the program using drag and drop.
- Connect the function block as shown in Figure 3-30.



Observe the notes regarding the connection of the “xActivate”, “IslandNo”, “arrSBTOncntrlBuf”, and “arrSBTOncntrlValBuf” parameters (see page 28).

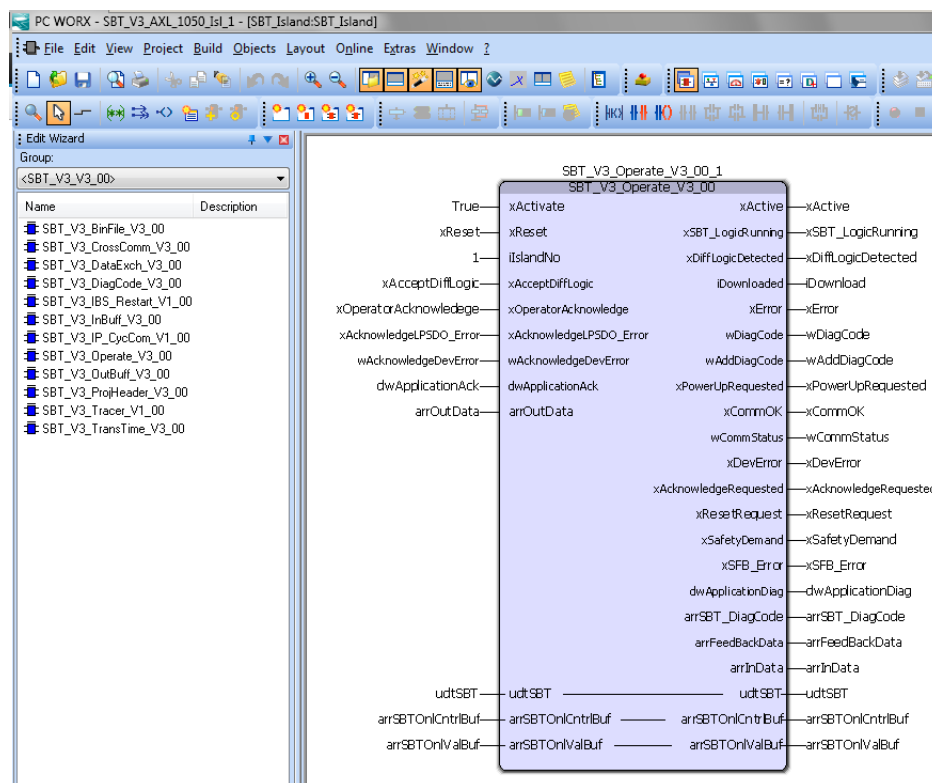


Figure 3-30 “SBT_V3_Operate_V3_00” function block

Example project: two-channel emergency stop monitoring

Notes regarding the connection of I/O parameters:

xActivate

Connect the “xActivate” input parameter to the “True” constant so that the “SBT_V3_Operate_V3_00” function block is activated automatically.

islandNo

Set the “islandNo” input parameter to “1” as per the island number selected in SAFECONF. See “Assign safety island number” on page 16.

arrSBTONlCntrlBuf

For this input parameter, assign the exact same variable name (“arrSBTONlCntrlBuf”) as follows:

1. Open the “Variable Properties” window.
2. In the “Global Variable Groups” field, select the “Default” folder.
3. Select “VAR_GLOBAL” as the usage.
4. Select the “PDD” function via the check box.

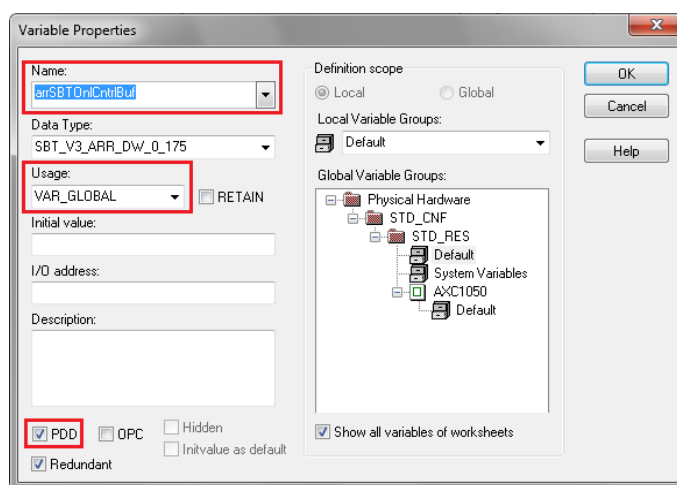


Figure 3-31 Settings for variable “arrSBTONlCntrlBuf”

arrSBTONlValBuf

Proceed as described above for the “arrSBTONlCntrlBuf” input parameter.



The “arrSBTONlCntrlBuf” and “arrSBTONlValBuf” I/O parameters are required for the online mode function in SAFECONF.

Example project: two-channel emergency stop monitoring

“SBT_V3_InBuff_V3_00” function block

- Insert the “SBT_V3_InBuff_V3_00” function block in the program using drag and drop.
- Connect the function block as shown in Figure 3-32.

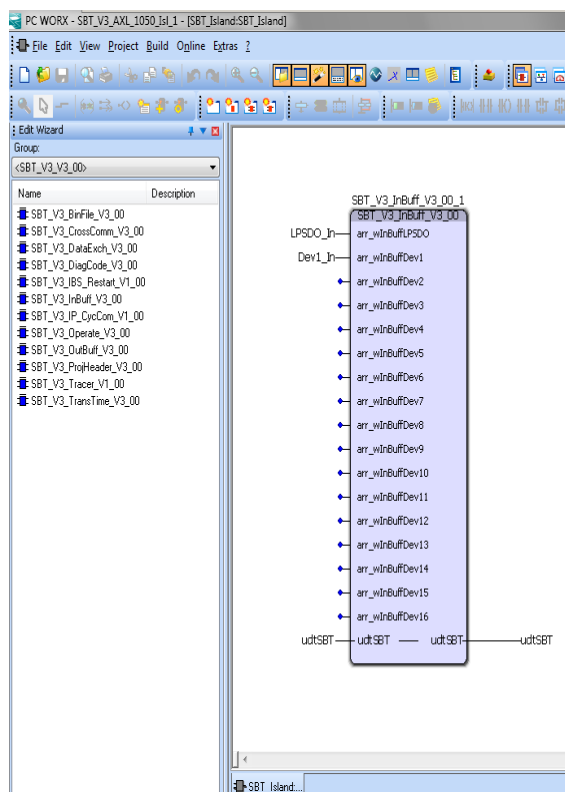


Figure 3-32 “SBT_V3_InBuff_V3_00” function block

- Proceed as follows for variables “LPSDO_In” und “Dev1_In”:
1. Open the “Variable Properties” window.
 2. Select “VAR_GLOBAL_PG” as the usage.

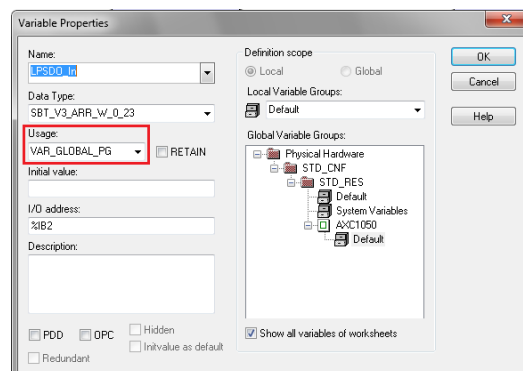


Figure 3-33 Settings for variables “LPSDO_In” and “Dev1_In”

- Link the “udtSBT” structure variable to the same variable as for the “SBT_V3_Operate_V3_00” function block.

Example project: two-channel emergency stop monitoring

“SBT_V3_OutBuff_V3_00” function block

- Insert the “SBT_V3_OutBuff_V3_00” function block in the program using drag and drop.
- Connect the function block as shown in Figure 3-34.

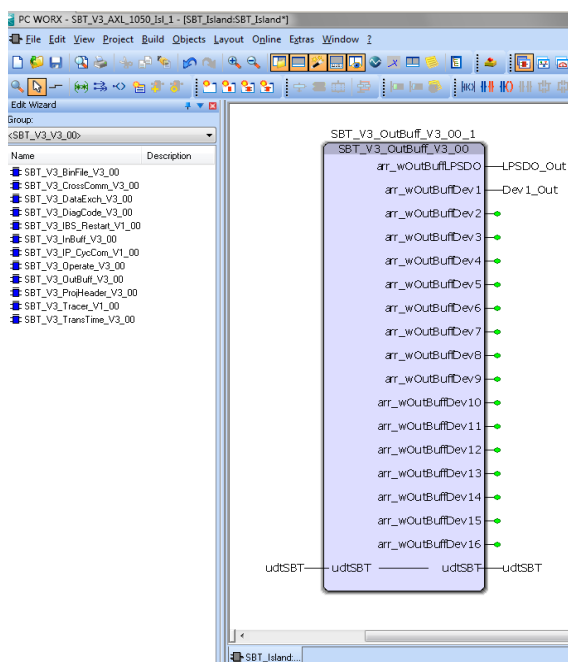


Figure 3-34 “SBT_V3_OutBuff_V3_00” function block

- Proceed as follows for variables “LPSDO_Out” und “Dev1_Out”:
1. Open the “Variable Properties” window.
 2. Select “VAR_GLOBAL_PG” as the usage.

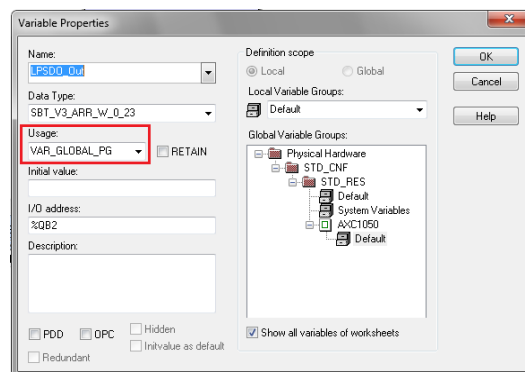


Figure 3-35 Settings for variables “LPSDO_Out” und “Dev1_Out”

- Link the “udtSBT” structure variable to the same variable as for the “SBT_V3_Operate_V3_00” function block.

Example project: two-channel emergency stop monitoring

Observe the sequence of the function blocks

Now arrange the function blocks in the following sequence in the “SBT_Island” program:

1. “SBT_V3_InBuff_V3_00” function block
2. “SBT_V3_Operate_V3_00” function block
3. “SBT_V3_OutBuff_V3_00” function block



Figure 3-36 Sequence of the function blocks in the program

“SBT_V3_BinFile_V3_00” function block



This function block is only required if you selected **“Binary file”** as the output format for the configuration and parameter data record from SAFECONF (see Figure 3-5 on page 15) and wish to download the BIN file to the controller via FTP.

If you selected **“PC Worx”** as the output format, this function block is not required. For additional information on this process, please refer to Appendix B on page 44.

- Insert the “SBT_V3_BinFile_V3_00” function block in the program using drag and drop.
- Connect the function block as shown in Figure 3-37.
- Link the “udtSBT” structure variable to the same variable as for the “SBT_V3_Operate_V3_00” function block.

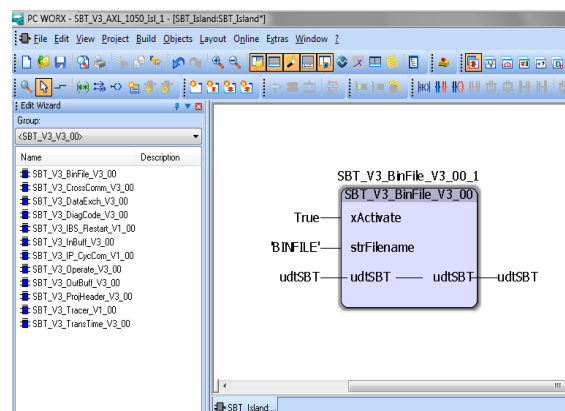


Figure 3-37 “SBT_V3_BinFile_V3_00” function block

Example project: two-channel emergency stop monitoring

“SBT_V3_ProjHeader_V3_00” function block

- Insert the “SBT_V3_ProjHeader_V3_00” function block in the program using drag and drop.
- Connect the function block as shown in Figure 3-38.
- Link the “udtSBT” structure variable to the same variable as for the “SBT_V3_Operate_V3_00” function block.

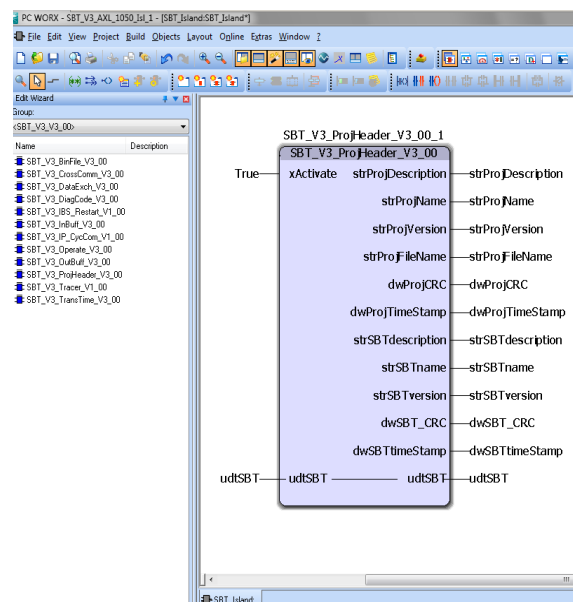


Figure 3-38 “SBT_V3_ProjHeader_V3_00” function block

“SBT_V3_TransTime_V3_00” function block

- Insert the “SBT_V3_TransTime_V3_00” function block in the program using drag and drop.
- Connect the function block as shown in Figure 3-39.
- Link the “udtSBT” structure variable to the same variable as for the “SBT_V3_Operate_V3_00” function block.

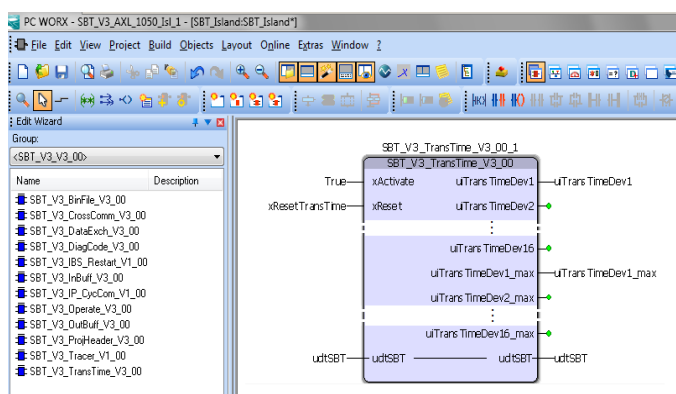


Figure 3-39 “SBT_V3_TransTime_V3_00” function block

Example project: two-channel emergency stop monitoring

“SBT_V3_DiagCode_V3_00” function block

- Insert the “SBT_V3_DiagCode_V3_00” function block in the program using drag and drop.
- Connect the function block as shown in Figure 3-40.
- Link the “udtSBT” structure variable to the same variable as for the “SBT_V3_Operate_V3_00” function block.
- Link the “arr_wSBTDiagCode” array to the same variable as for the “SBT_V3_Operate_V3_00” function block.

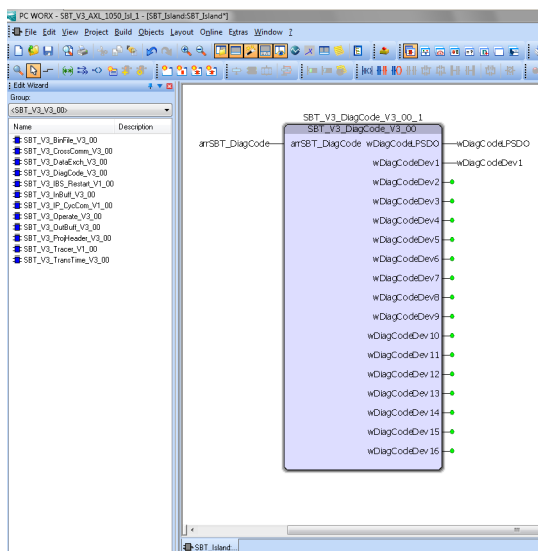


Figure 3-40 “SBT_V3_DiagCode_V3_00” function block

Example project: two-channel emergency stop monitoring

Error acknowledgment

- Create the program shown in Figure 3-41 in order to acknowledge communication and module errors for the AXL F LP5DO8/3 1F and AXL F SSD18/4 1F modules.

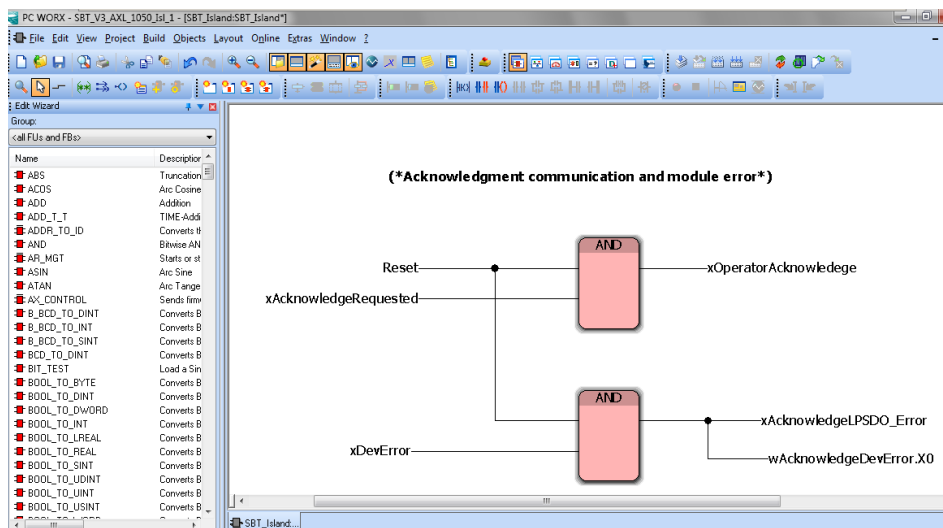


Figure 3-41 Program for error acknowledgment



Communication and module errors can be acknowledged via the "Reset" variable.

Example project: two-channel emergency stop monitoring

Acknowledgment of the safety function

- Create the program shown in Figure 3-42 in order to acknowledge the safety function.

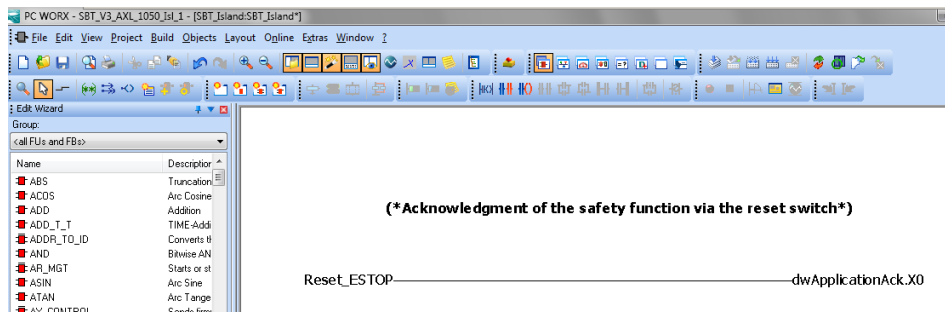


Figure 3-42 Program for acknowledging the safety function



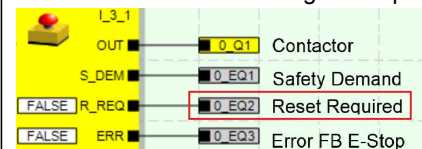
External signal "0_EI1" is controlled via the "Reset_ESTOP" input in SAFECONF.



Figure 3-43 Program for the signal lamp for reset request



External signal "0_EQ2" from SAFECONF writes the "dwApplicationDiag.X1" variable and therefore controls the signal lamp.



Example project: two-channel emergency stop monitoring

3.4.4 Process data assignment of the devices

- Open the process data assignment window in PC Worx.
- Select the “AXC 1050 : SBT_Island” program instance and the AXL F LPSDO8/3 1F module.

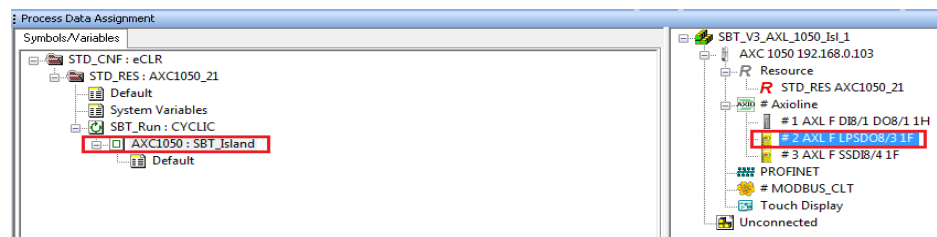


Figure 3-44 Process data assignment

- Connect the control system variables to the process data for the AXL F LPSDO8/3 1F in the bus configuration by carrying out the following steps:
 1. Place the “LPSDO_Out” variable on the “arrOutBuff” process data item.
 2. Place the “LPSDO_In” variable on the “arrInBuff” process data item.

Symbol/Variable	Data Type	Process Data Item	Device	Process Data Item	I/Q	Data Type	Byte.Bit
LPSDO_In	SBT_V3_ARR_W_0_23	# 2 AXL F LPSDO8/3 1F \-IN	# 2 AXL F LPSDO8/3 1F	arrInBuff	I	OCTETSTRING[48]	0.0
LPSDO_Out	SBT_V3_ARR_W_0_23	# 2 AXL F LPSDO8/3 1F \-OUT	# 2 AXL F LPSDO8/3 1F	arrOutBuff	Q	OCTETSTRING[48]	0.0
Dev1_In	SBT_V3_ARR_W_0_3		# 2 AXL F LPSDO8/3 1F	-IN	I	OCTETSTRING[48]	0.0
Dev1_Out	SBT_V3_ARR_W_0_3		# 2 AXL F LPSDO8/3 1F	-OUT	Q	OCTETSTRING[48]	0.0

Figure 3-45 LPSDO8/3 – connecting variables and process data

- Select the AXL F SSDI8/4 1F module.
- Connect the control system variables to the process data for the AXL F SSDI8/4 1F in the bus configuration by carrying out the following steps:
 1. Place the “Dev1_In” variable on the “arrInBuff” process data item.
 2. Place the “Dev1_Out” variable on the “arrOutBuff” process data item.

Symbol/Variable	Data Type	Process Data Item	Device	Process Data Item	I/Q	Data Type	Byte.Bit
LPSDO_In	SBT_V3_ARR_W_0_23	# 2 AXL F LPSDO8/3 1F \-IN	# 3 AXL F SSDI8/4 1F	arrInBuff	I	OCTETSTRING[8]	0.0
LPSDO_Out	SBT_V3_ARR_W_0_23	# 2 AXL F LPSDO8/3 1F \-OUT	# 3 AXL F SSDI8/4 1F	arrOutBuff	Q	OCTETSTRING[8]	0.0
Dev1_In	SBT_V3_ARR_W_0_3	# 3 AXL F SSDI8/4 1F \-arrInBuff	# 3 AXL F SSDI8/4 1F	-IN	I	LWORD	0.0
Dev1_Out	SBT_V3_ARR_W_0_3	# 3 AXL F SSDI8/4 1F \-arrOutBuff	# 3 AXL F SSDI8/4 1F	-OUT	Q	LWORD	0.0

Figure 3-46 SSDI8/4 – connecting variables and process data

- Select the AXL F DI8/1 DO8/1 1H module.
- Connect the control system variables to the “Reset”, “Reset_Estop”, and “Signal lamp” process data for the AXL F DI8/1 DO8/1 1H in the bus configuration.

Example project: two-channel emergency stop monitoring

3.4.5 Compiling the project and downloading it to the controller

- Compile the created project and download it to the controller.

The controller switches to the “Run” state.

The LPSDO8/3 module indicates an error by flashing the FS LED.

Error message: device is not parameterized or parameterization was not applied.

3.4.6 Importing the configuration and parameter data record into the project



This step is only required if you selected “**Binary file**” as the output format for the configuration and parameter data record from SAFECONF (see Figure 3-5 on page 15). If you selected “**PC Worx**” as the output format, this step is not required. For additional information on this process, please refer to Appendix B on page 44.

Transmit BIN file

Download the configuration and parameter record stored as a BIN file to the controller via SAFECONF. Proceed as follows:

- Open SAFECONF.
- In the hardware editor, right-click on the LPSDO8/3 module and select “Online configuration...”.

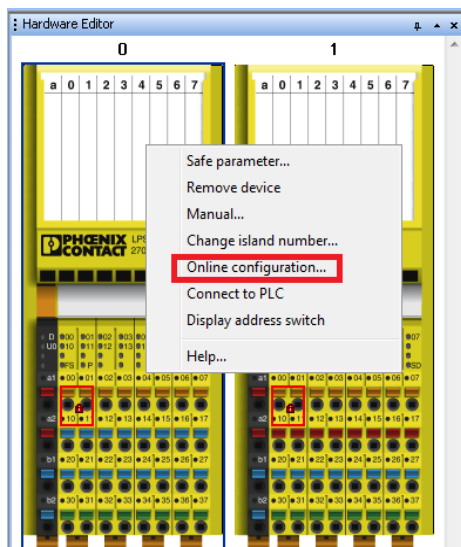


Figure 3-47 Selecting online configuration

Example project: two-channel emergency stop monitoring

- Select the “Phoenix Contact (ILC 1xx, ILC 3xx, RFC 4xx)” interface and click on “Next”.

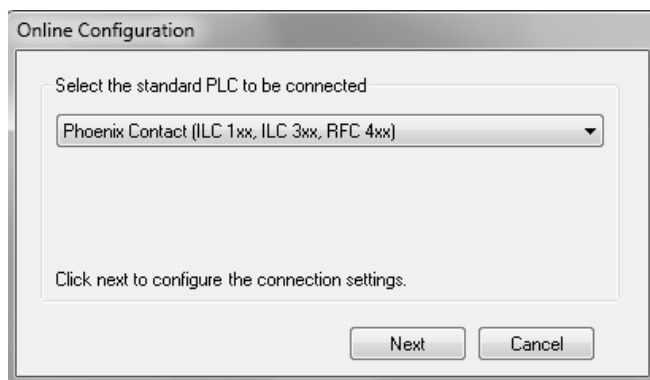


Figure 3-48 Selecting the interface

The “Online Configuration” window opens.

- Enter the IP address of the AXC 1050 controller and click on “Test connection...”.
- Once this test has been completed successfully, click on “Finish”.

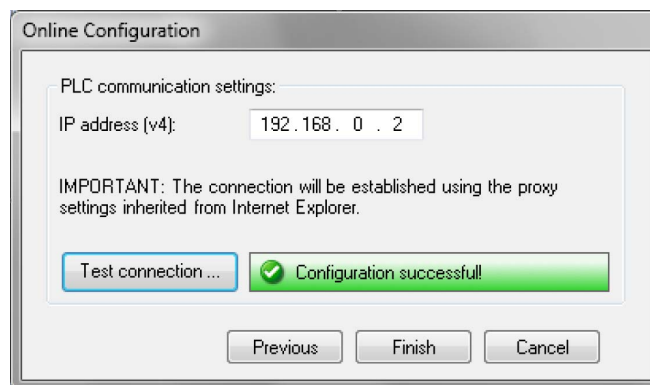


Figure 3-49 SAFECONF “Online Configuration” window

- After a few seconds, the following message appears in the SAFECONF status bar.

Project: Read/Write **PLC: Logged off** **PLC: Connected**

Figure 3-50 SAFECONF status message

Example project: two-channel emergency stop monitoring

- Click on the “Download” button.



Following successful download, the following information window appears.

- Confirm with “OK”.

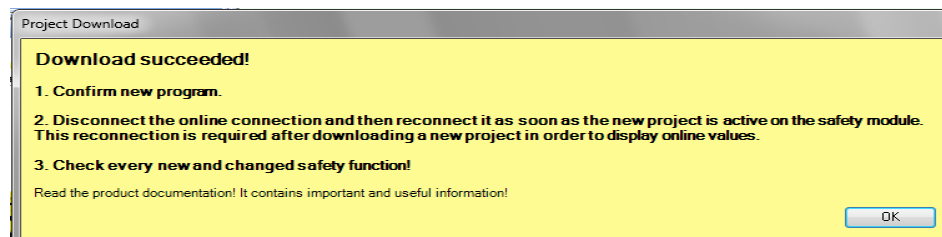


Figure 3-51 SAFECONF information window



See Section “Online configuration and connection establishment” on page 41.

Important when making changes in SAFECONF

Whenever a change is made in the SAFECONF project which affects the checksum (CRC), replace the BIN file in the root directory of the controller. Proceed as described above.

3.5 Startup



A flowchart for starting up and testing the application can be found in Appendix A on page 43.

1. Switch to PC Worx.
2. Open the "SBT_Island" program.
3. Activate the online values in PC Worx.
4. Set the "xReset" input parameter to "1" and check the "xDiffLogicDetected" output parameter. If the value is set to "1", a new SAFECONF project has been detected.
5. Set the "xAcceptDiffLogic" input parameter to "1".

You can check the download progress at the "iDownloaded" output parameter. Download time: approximately 40 seconds (depending on the project size, CPU, and bus speed).

6. Check whether the "xSBTlogicRunning" output parameter outputs "TRUE" and the "wDiagCode" output parameter outputs the value 16#8000.



If a different code is output by the "wDiagCode" output parameter, see "Function block diagnostics" on page 53.

Once successfully downloaded, the safe application is ready.

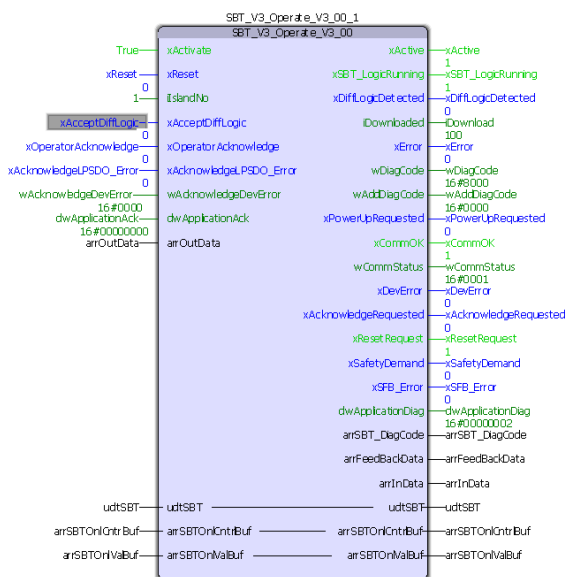


Figure 3-52 Finished project

The diagnostics LEDs of the modules now have the following status:

LEDs off: FS, CM, SD

LEDs on: P, U_O, D

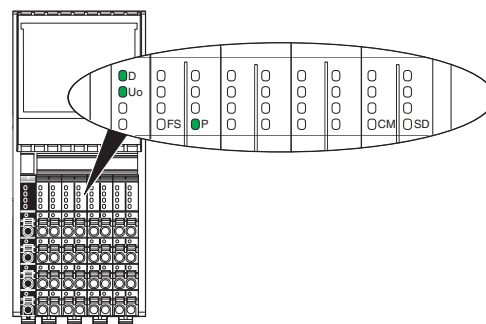


Figure 3-53 Diagnostics LEDs



Perform an overall safety validation after you start up your system.

3.6 Online configuration and connection establishment

Communication between SAFECONF and the “SBT_V3_Operate_V3_00” function block is achieved by the “arrSBTONIContrlBuf” and “arrSBTONIValBuf” I/O parameters.

To view the online values in SAFECONF, proceed as follows:

- Open SAFECONF.
- In the hardware editor, right-click on the LPSDO8/3 module.
- If another online connection is active, disconnect the connection by selecting “Disconnect from PLC”.

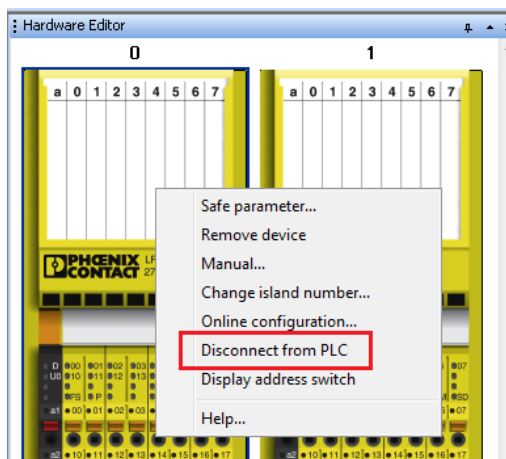


Figure 3-54 Disconnecting an online connection

- In the hardware editor, right-click on the LPSDO8/3 module.
- Establish an online connection by selecting “Connect to PLC”.

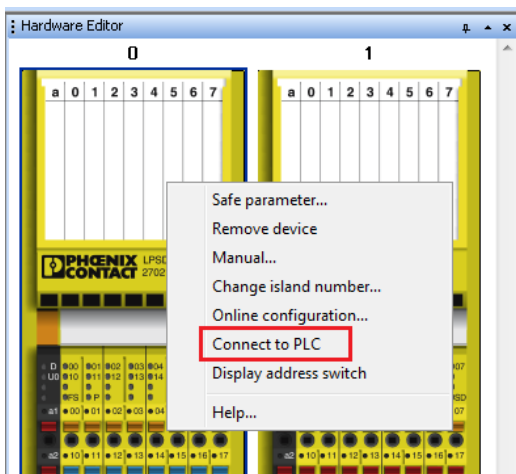


Figure 3-55 Establishing an online connection

Example project: two-channel emergency stop monitoring

- In the SAFECONF tool bar, click on the “Show Online Values” button.

The online values are now displayed in the SAFECONF project.

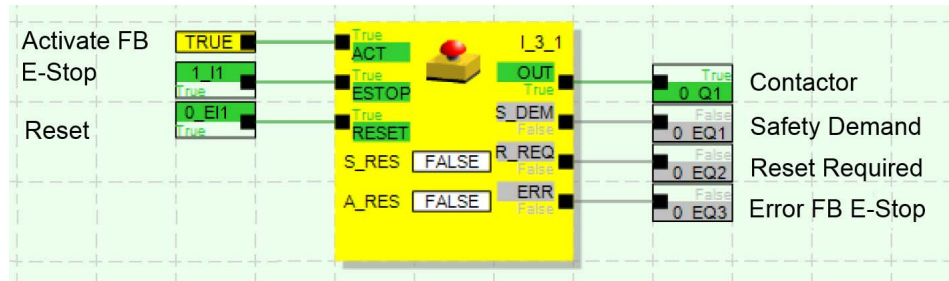


Figure 3-56 Online values in the SAFECONF project

A Flowchart for starting up and testing the application

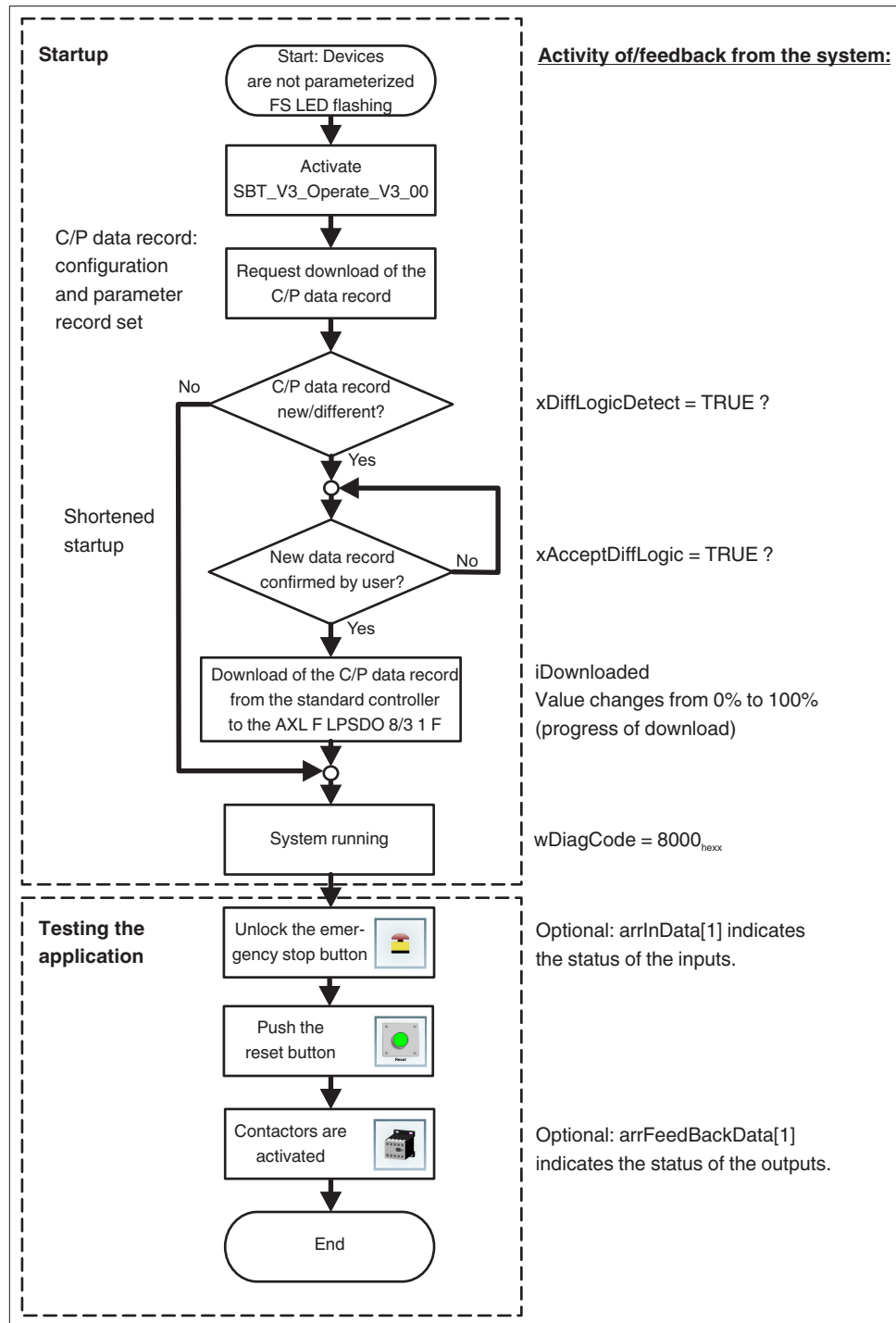


Figure A-1 Flowchart for starting up and testing the application

B Alternatives for importing the configuration and parameter data record

B 1 Copying the BIN file to the controller via FTP

Requirement

“**Binary file**” was selected as the output format for the configuration and parameter data record from SAFECONF (see Figure 3-5 on page 15).

In “Importing the configuration and parameter data record into the project” on page 37, the BIN file was created and saved in the “FileOutput” folder under the previously specified project path (see Figure 3-18 on page 21).

Transmit BIN file

- In Explorer, establish a connection to the controller via FTP (e.g., ftp://192.168.0.2).
- Copy the BIN file to the root directory of the controller.

Important when making changes in SAFECONF

Whenever a change is made in the SAFECONF project which affects the checksum (CRC), replace the BIN file in the root directory of the controller. Proceed as described above.

B 2 Importing the st file in PC Worx

Requirement

“**PC Worx**” was selected as the output format for the configuration and parameter data record from SAFECONF (see Figure 3-5 on page 15).

In “Importing the configuration and parameter data record into the project” on page 37, the st file was created and saved in the “FileOutput” folder under the previously specified project path (see Figure 3-18 on page 21).

Transmit st file

- Open your project in PC Worx.
- Make sure that you are offline.
- Select the “Logical POU” folder.
- Select “File, Import”.
- Select the “Extended IEC 61131-3 Import” entry and confirm your selection with “OK”.

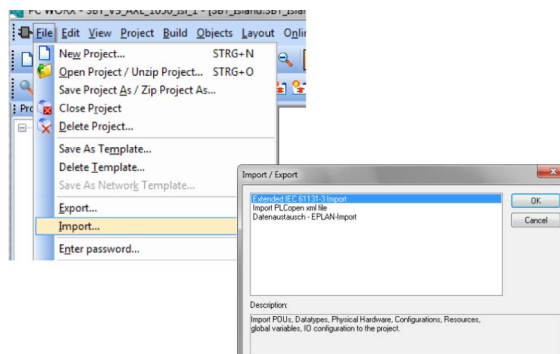


Figure B-1 Extended IEC 61131-3 import

Importing the st file in PC Worx

- Select the POU object and confirm your selection with “OK”.

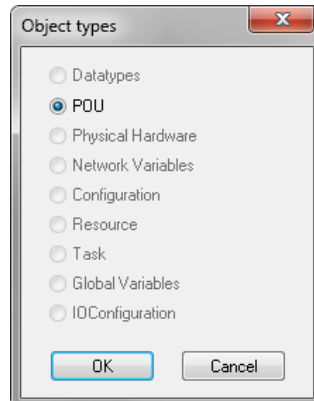


Figure B-2 POU object

- Select the st file and confirm your selection with “OK”.

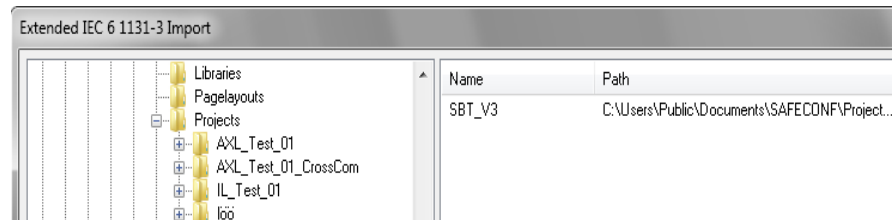


Figure B-3 Selecting the st file

If import is successful, the structure for the SafetyBridge islands (SBTIslands) is created under “Logical POU”.

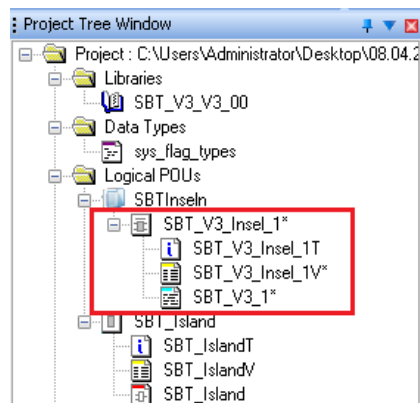


Figure B-4 POU for SafetyBridge island 1 inserted



If an error message appears and the structure is not created, this may be because the name of the file you want to import is too long.

- If this is the case, give the SAFECNF project a shorter name.

Importing the st file in PC Worx

- Select the “SBT_V3” function block from the library and move it to the programming view using drag and drop.
- Connect the function block as shown in Figure B-5.

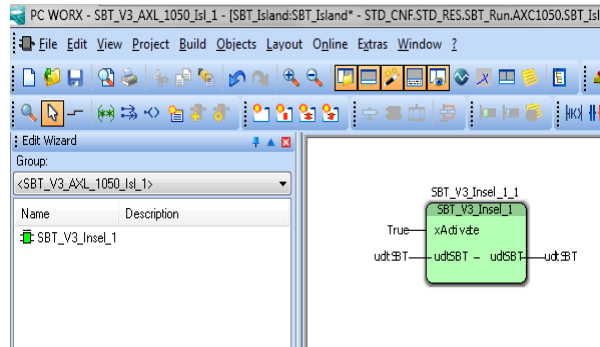


Figure B-5 Connecting the function block

Important when making changes in SAFECONF

Whenever a change is made in the SAFECONF project which affects the checksum (CRC), import a new st file in PC Worx. Proceed as described above.

C Description of the function blocks for SafetyBridge Technology V3



For additional information, please refer to the online help for the PC Worx software.

The described function blocks are valid for the following controllers and software versions.

Validity

Table C-1 Validity of the function blocks

Controller	All controllers from Phoenix Contact			
Bus system	Inline		Axioline	
	INTERBUS	PROFINET	AXIOBUS	PROFINET
Software	PC Worx V6.30 or later			

Function block overview

Table C-2 Function block overview

Function block	Description
SBT_V3_Operate_V3_00	Function block used to operate an SBT island with a maximum of 16 satellites - Download the SAFECONF project - Monitoring of input and output modules See C 1 on page 49
SBT_V3_InBuff_V3_00	Links the IN process data of the modules See C 2 on page 54
SBT_V3_OutBuff_V3_00	Links the OUT process data of the modules See C 3 on page 55
SBT_V3_BinFile_V3_00	The function block reads the project data of the BIN file generated from SAFECONF and makes the data available to the SBT_V3_Operate_V3_00 function block See C 4 on page 56
SBT_V3_CrossComm_V3_00	Cross communication between two or more SBT islands See C 5 on page 57
SBT_V3_DataExch_V3_00	Data exchange if two SBT islands are integrated in different controllers See C 6 on page 58
SBT_V3_ProjHeader_V3_00	Displays information about the SAFECONF project and the project stored on the LPSDO module as output data See C 8 on page 62

Description of the function blocks for SafetyBridge Technology V3

Function block	Description
SBT_V3_TransTime_V3_00	Indicates the data transmission times for each module See C 7 on page 60
SBT_V3_DiagCode_V3_00	Displays the contents of the array of SBT module diagnostic codes (device-specific; see module user documentation) Also indicates the value of the DIP switches if no diagnostic code is present and the modules are not parameterized See C 9 on page 64
SBT_V3_Tracer_V1_00	If a communication error has occurred, the block displays the last four telegrams between the logic module and the satellites See C 10 on page 66

Data types

Table C-3 Data types

Designation	Description
SBT_V3_w_0_16	Internal user-defined data type. For additional information, refer to the descriptions for the respective function block parameters.
SBT_V3_ARR_W_0_16	
SBT_V3_ARR_W_0_175	
SBT_V3_ARR_W_0_23	
SBT_V3_ARR_W_0_3	
SBT_V3_ARR_DW_0_175	
SBT_V3_UDT_SBT_V2	
SBT_V3_ARR_UDT_SBT_V2	
SBT_V3_Data_2	
SBT_V3_Tracer	

C 1 SBT_V3_Operate_V3_00 function block

The function block performs the following functions:

- Download of the configuration and parameter data record from the standard controller to the AXL F LPSDO8/3 1F
- Cyclical routing of the SafetyBridge data flow

Use the function block once per island.

The figure shows the division of the function block into its individual function areas. The parameters used are described in the tables below.

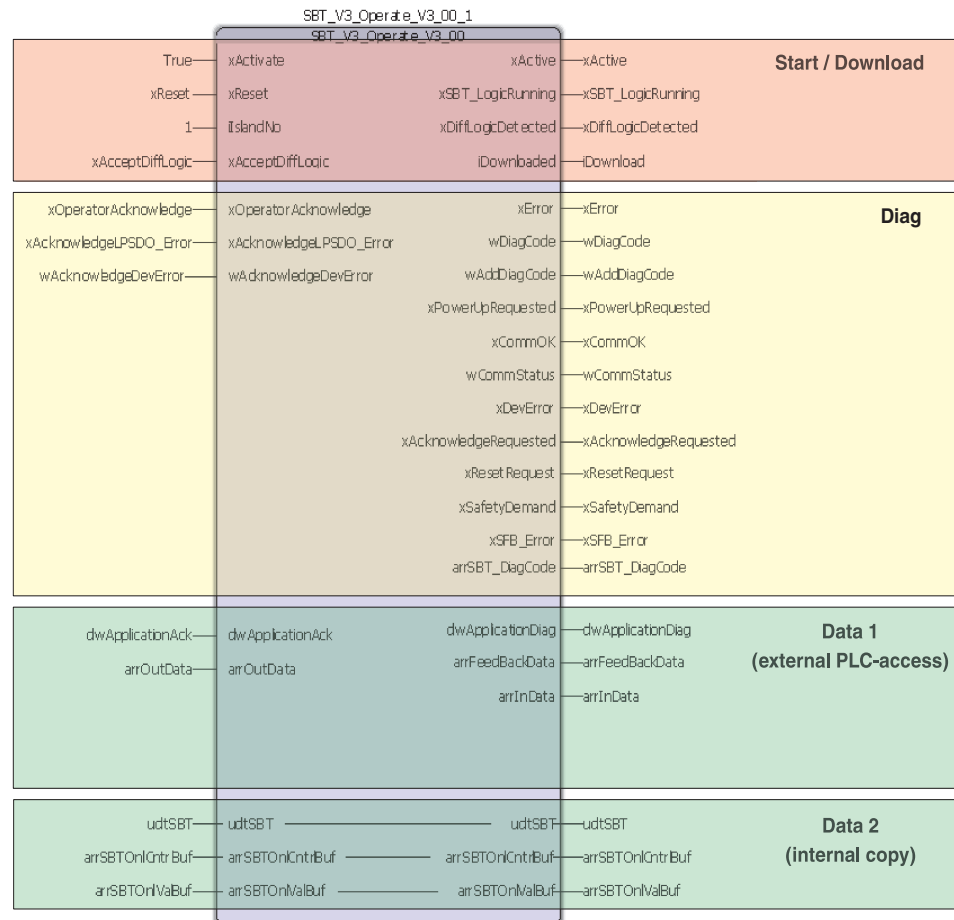


Figure C-1 “SBT_V3_Operate_V3_00” function block

SBT_V3_Operate_V3_00 function block**C 1.1 Input parameters**

Table C-4 Input parameters for the “SBT_V3_Operate_V3_00” function block

Name	Type	Description
xActivate	BOOL	Activation/deactivation of the function block
xReset	BOOL	On a rising edge, the function block is reset and re-initialized
ilIslandNo	INT	SBT island number Valid range: 1 ... 31 (must be the same as the DIP switch position on the LPSDO module and the setting in the SAFECONF project)
xAcceptDiffLogic	BOOL	User confirmation signal that the safety logic differs for the controller and the LPSDO module Rising edge: user has accepted and confirmed the difference (the download then starts)
xOperatorAcknowledge	BOOL	Rising edge: user acknowledgement of a sporadic communication error
xAcknowledgeLPSDO_Error	BOOL	Rising edge: acknowledgment of an LPSDO module error
wAcknowledgeDevError	WORD	Each bit is associated with a module If a bit is set, an error is acknowledged at the corresponding module
dwApplicationAck	DWORD	Freely configurable acknowledgment signals (application data) from the standard controller to the LPSDO module
arrOutData	SBT_V3_w_0_16	Array of outputs from all output modules of the SBT island; the index represents the device number; index 0 stands for the LPSDO module Info: depending on the parameterization of the safe outputs, the enable principle applies here. I.e., the safe outputs can be controlled via the standard controller as long as the safety function is not demanded (the safety logic is “enabled”). If there is a demand of the safety function, this overrides the standard controller and switches off the safe outputs.

SBT_V3_Operate_V3_00 function block**C 1.2 Output parameters**

Table C-5 Output parameters for the "SBT_V3_Operate_V3_00" function block

Name	Type	Description
xActive	BOOL	True: the function block has been initialized successfully and is operating without errors False: error or function block is not initialized
xBT_LogicRunning	BOOL	Safety logic (SAFECONF logic) running on the LPSDO module
xDiffLogicDetected	BOOL	True: detection of different safety logic for the controller and the LPSDO module
iDownloaded	INT	Percentage of SBT logic that has been downloaded
xError	BOOL	True: the function block has detected an error and is no longer operating; re-activation is required
wDiagCode	WORD	Diagnostic code for function block errors
wAddDiagCode	WORD	Additional diagnostic code for function block errors
xPowerUpRequested	BOOL	Error state that cannot be acknowledged; restart is required (voltage reset)
xCommOK	BOOL	True: communication status of the SBT island is OK False: loss of communication for one or more modules
wCommStatus	WORD	Communication status of the individual modules; each bit represents the status of a module (example: bit 1 corresponds to module 1)
xDevError	BOOL	Indicates an error in one or more SBT modules
xAcknowledgeRequested	BOOL	Acknowledgment by the user is required
xResetRequest	BOOL	Reset request signal from one or more safety function blocks is "True" in the logic module
xBafetyDemand	BOOL	Safety demand signal from one or more safety function blocks is "True" in the logic module
xBFB_Error	BOOL	Indicates that the error signal is set in a safety function block
dwApplicationDiag	DWORD	Freely configurable feedback signals from the LPSDO module to the standard controller

SBT_V3_Operate_V3_00 function block

Name	Type	Description
arrSBT_DiagCode	SBT_V3_ARR_W_0_16	Array of SBT module diagnostic codes (device-specific; see module user documentation) Or value of the DIP switches if no diagnostic code is present and the modules are not parameterized The diagnostic codes can be read using the “SBT_V3_DiagCode_V3_00” function block, see C 9 on page 64
arrFeedBackData	Array [0...16] of WORD	Feedback data of all outputs of the LPSDO module and the satellites; the index represents the device number; index 0 stands for the LPSDO module
arrInData	Array [0...16] of WORD	Array of inputs from all input modules (satellites) of the SBT island; the index represents the device number; index 0 stands for the LPSDO module

C 1.3 I/O parameters

Table C-6 I/O parameters for the “SBT_V3_Operate_V3_00” function block

Name	Type	Description
udtSBT	SBT_V3_UDT_SBT_V2	Data structure for data exchange between function blocks
arrSBTONIcntrlBuf	SBT_V3_ARR_DW_0_175	Array for online mode in SAFECONF Important: the parameter must have the same variable name (arrSBTONIcntrlBuf) and be defined as a global variable. The PDD check box must be activated. See Figure C-2.
arrSBTONIvalBuf	SBT_V3_ARR_W_0_175	Array for online mode in SAFECONF Important: the parameter must have the same variable name (arrSBTONIvalBuf) and be defined as a global variable. The PDD check box must be activated. See Figure C-2.

Settings for “arrSBTONIcntrlBuf” and “arrSBTONIvalBuf”:

Name	Type	Usage	Description	Address	Init	Retain	PDD
Default							
arrSBTONIcntrlBuf	SBT_V3_ARR_DW_0_175	VAR_GLOBAL				☐	☒
arrSBTONIvalBuf	SBT_V3_ARR_W_0_175	VAR_GLOBAL				☐	☒

Figure C-2 Settings for “arrSBTONIcntrlBuf” and “arrSBTONIvalBuf”

C 1.4 Function block diagnostics

Diagnostics

Table C-7 Diagnostic codes

DiagCode	Meaning
0000 _{hex}	Function block is not active
8000 _{hex}	Function block is active and operating without errors
8001 _{hex}	Initialization
8100 _{hex}	SAFECONF project and BIN file/POU are being read
	AddDiagCode
	0000 _{hex}
	0001 _{hex}
8200 _{hex}	Reading "ProjectHeader" of LPSDO module
	AddDiagCode
	0000 _{hex}
	0001 _{hex}
8300 _{hex}	Comparing "Header" of LPSDO module and the loaded program
8400 _{hex}	Downloading SAFECONF program to the LPSDO module
	AddDiagCode
	0000 _{hex}
	0001 _{hex}
	0002 _{hex}
	0003 _{hex}
	0004 _{hex}
8500 _{hex}	Download completed successfully
C001 _{hex}	Initialization error
	AddDiagCode
	0004 _{hex}
C002 _{hex}	LPSDO module unavailable Check communication and restart block
C100 _{hex}	Error when reading/copying the SAFECONF project and BIN file/POU
	AddDiagCode
	0001 _{hex}
	0002 _{hex}
	0003 _{hex}
C850 _{hex}	Error during download
	AddDiagCode
	0001 _{hex}

C 2 SBT_V3_InBuff_V3_00 function block

The function block reads the IN process data of the SBT modules.

Use the function block once per island.



Figure C-3 “SBT_V3_InBuff_V3_00” function block

C 2.1 Input parameters

Input parameters

Table C-8 Input parameters for the “SBT_V3_InBuff_V3_00” function block

Name	Type	Description
arr_wInBuffLPDO	SBT_V3_ARR_W_0_23	Output buffer of the LPDO module
arr_wInBuffDev1	SBT_V3_ARR_W_0_3	Output buffer of module 1
arr_wInBuffDev2	SBT_V3_ARR_W_0_3	Output buffer of module 2
⋮	⋮	⋮
arr_wInBuffDev16	SBT_V3_ARR_W_0_3	Output buffer of module 16

C 2.2 I/O parameters

I/O parameters

Table C-9 I/O parameters for the “SBT_V3_InBuff_V3_00” function block

Name	Type	Description
udtSBT	SBT_V3_UDT_SBT_V2	Data exchange structure The following applies when inside an island: Same udtSBT parameter as the “SBT_V3_Operate_V3_00” function block

C 3 SBT_V3_OutBuff_V3_00 function block

The function block writes the OUT process data to the SBT modules.

Use the function block once per island.

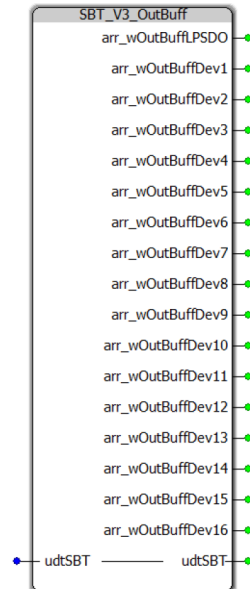


Figure C-4 “SBT_V3_OutBuff_V3_00” function block

C 3.1 Output parameters

Output parameters

Table C-10 Output parameters for the “SBT_V3_OutBuff_V3_00” function block

Name	Type	Description
arr_wOutBuffLPSDO	SBT_V3_ARR_W_0_23	Input buffer of the LPSDO module
arr_wOutBuffDev1	SBT_V3_ARR_W_0_3	Input buffer of module 1
arr_wOutBuffDev2	SBT_V3_ARR_W_0_3	Input buffer of module 2
⋮	⋮	⋮
arr_wOutBuffDev16	SBT_V3_ARR_W_0_3	Input buffer of module 16

C 3.2 I/O parameters

I/O parameters

Table C-11 I/O parameters for the “SBT_V3_OutBuff_V3_00” function block

Name	Type	Description
udtSBT	SBT_V3_UDT_SBT_V2	Data exchange structure The following applies when inside an island: Same udtSBT parameter as the “SBT_V3_Operate_V3_00” function block

C 4 SBT_V3_BinFile_V3_00 function block



This function block is only required if you selected “**Binary file**” as the output format for the configuration and parameter data record from SAFECONF (see Figure 3-5 on page 15).

If you selected “**PC Worx**” as the output format, this function block is not required. For additional information on this process, please refer to Appendix B on page 44.

The function block reads the project data from the BIN file and makes the data available to the “SBT_V3_Operate_V3_00” function block.

Use the function block once per island.

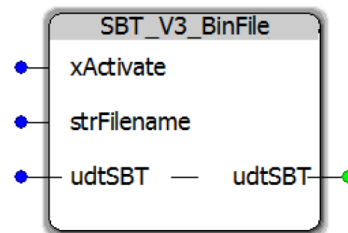


Figure C-5 “SBT_V3_BinFile_V3_00” function block

C 4.1 Input parameters

Input parameters

Table C-12 Input parameters for the “SBT_V3_BinFile_V3_00” function block

Name	Type	Description
xActivate	BOOL	Activation/deactivation of the function block
strFileName	STRING	BIN file from SAFECONF, which is stored on the FTP server of the controller, e.g., “BinFile.BIN” Important: the name must not exceed 24 characters.

C 4.2 I/O parameters

I/O parameters

Table C-13 I/O parameters for the “SBT_V3_BinFile_V3_00” function block

Name	Type	Description
udtSBT	SBT_V3_UDT_SBT_V2	Data exchange structure The following applies when inside an island: Same udtSBT parameter as the “SBT_V3_Operate_V3_00” function block

C 5 SBT_V3_CrossComm_V3_00 function block



This function block is optional. It is not essential in order to operate a SafetyBridge island.

In SafetyBridge Technology V3, islands can communicate with one another. Cross communication takes place via a master/slave model, where one or more islands can act as slaves for other master modules. Each island has the “udtSBT” data structure. The “SBT_V3_CrossComm_V3_00” function block combines the data structures of the individual islands in an array, thereby enabling cross communication between the islands.



The “SBT_V3_CrossComm_V3_00” function block may only be called once per standard controller.

If another island is in another standard controller, use an additional “SBT_V3_DataExch_V3_00” function block. See Appendix C 6 on page 58.

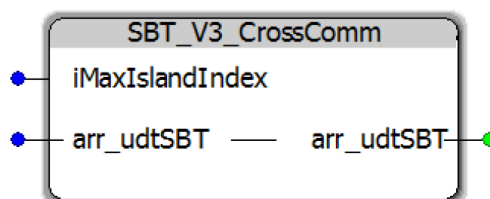


Figure C-6 “SBT_V3_CrossComm_V3_00” function block

C 5.1 Input parameters

Input parameters

Table C-14 Input parameters for the “SBT_V3_CrossComm_V3_00” function block

Name	Type	Description
iMaxIslandIndex	INT	Maximum index that is used in the “arr_udtSBT” array



To increase performance, the “iMaxIslandIndex” parameter limits the cycle for cross communication. If the value is 0, all 31 possible islands are checked by the function block.

C 5.2 I/O parameters

I/O parameters

Table C-15 I/O parameters for the “SBT_V3_CrossComm_V3_00” function block

Name	Type	Description
arr_udtSBT	SBT_V3_ARR_UDT_SBT_V2	Array of data structures for data exchange between function blocks



The “arr_udtSBT” array should contain all “udtSBT” structures of the islands.
The index of the “arr_udtSBT” array is independent of the index of the island.

C 6 SBT_V3_DataExch_V3_00 function block



This function block is optional. It is not essential in order to operate a SafetyBridge island.

If two SBT islands are connected to different controllers but cross communication is required between the two islands, the “SBT_V3_DataExch_V3_00” function block supports data exchange between the master and slave island. The function block uses input and output buffers, which buffer the data that is received from one controller and sent to the other controller. The data transmission method between the two controllers is not specified and can be any of various options, for example Modbus/TCP. However, the data must be transmitted consistently.



If the master island has more than one slave island, call this function block for each slave island.

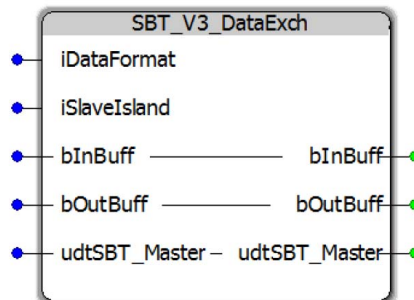


Figure C-7 “SBT_V3_DataExch_V3_00” function block

SBT_V3_DataExch_V3_00 function block

C 6.1 Input parameters

Input parameters

Table C-16 Input parameters for the “SBT_V3_DataExch_V3_00” function block

Name	Type	Description
iDataFormat	INT	Determines the format for data exchange with the other controller 0: exchange data is not swapped 1: exchange data is swapped
iSlaveIsland	INT	In the master program: number of the slave island with which the master island is exchanging data In the slave program: 0 because the island itself is a slave

C 6.2 I/O parameters

I/O parameters

Table C-17 I/O parameters for the “SBT_V3_DataExch_V3_00” function block

Name	Type	Description
arr_InBuff	BYTE	First byte of an array containing exchange data (input) from another island Important: the array must be at least 16 bytes long. Example: If the input buffer from byte 20 to byte 35 is in the PROFINET exchange buffer, connect the PND_INPUTS[20] field.
arr_OutBuff	BYTE	First byte of an array containing exchange data (output) from another island Important: the array must be at least 16 bytes long.
udtSBT_Master	SBT_V3_Data_2	Data structure of the master island In the master program: the same data structure of the “SBT_V3_Operate_V3_00” function block is connected In the slave program: unassigned structure is connected; not the same data structure of the “SBT_V3_Operate_V3_00” function block Example: If slave data structure = udtSBT[3], then master data structure = udtSBT[4]

C 7 SBT_V3_TransTime_V3_00 function block



This function block is optional. It is not essential in order to operate a SafetyBridge island.

The function block measures the data transmission times between the logic module and satellite modules 1 to 16 as well as the maximum transmission time of a module.

Use the function block once per island.



If the data transmission time of a module is greater than the F_WD_Time, a communication error is output at the LPSDO module. In this case, the data transmission time and F_WD_Time should be checked.

Please note that increasing the F_WD_Time has a direct effect on the safety function because it increases response times and therefore delay times and/or safety distances.

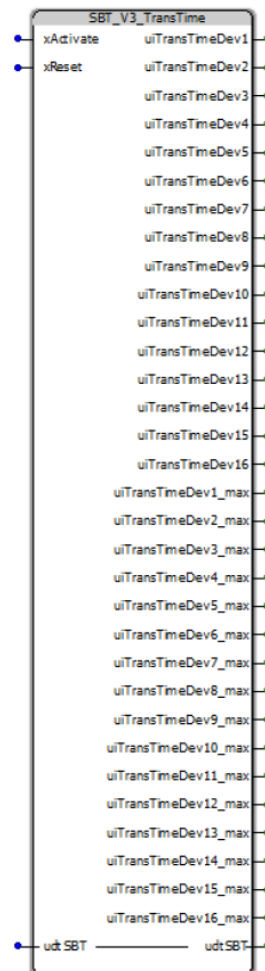


Figure C-8 “SBT_V3_TransTime_V3_00” function block

SBT_V3_TransTime_V3_00 function block

C 7.1 Input parameters**Input parameters**

Table C-18 Input parameters for the “SBT_V3_TransTime_V3_00” function block

Name	Type	Description
xActivate	BOOL	Activation/deactivation of the function block
xReset	BOOL	On a rising edge, the output data transmission times are reset. Important: do not link the parameter to the same variable as the xReset parameter of the “SBT_V3_Operate_V3_00” function block.

C 7.2 Output parameters**Output parameters**

Table C-19 Output parameters for the “SBT_V3_TransTime_V3_00” function block

Name	Type	Description
uiTransTimeDev[1...16]	UINT	Data transmission time between LPSDO and satellite 1 to 16.
uiTransTimeDev[1...16]_max	UINT	Maximum data transmission time between LPSDO and satellite 1 to 16.

C 7.3 I/O parameters**I/O parameters**

Table C-20 I/O parameters for the “SBT_V3_TransTime_V3_00” function block

Name	Type	Description
udtSBT	SBT_V3_UDT_SBT_V2	Data exchange structure The following applies when inside an island: Same udtSBT parameter as the “SBT_V3_Operate_V3_00” function block

C 8 SBT_V3_ProjHeader_V3_00 function block



This function block is optional. It is not essential in order to operate a SafetyBridge island.

The function block contains all information about the SAFECONF project and the project stored on the LPSDO module.

Use the function block once per island.

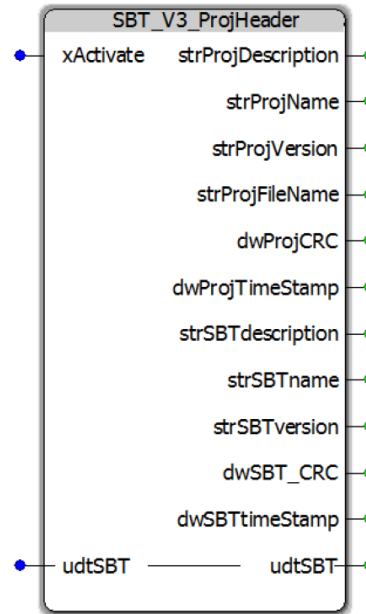


Figure C-9 “SBT_V3_ProjHeader_V3_00” function block

C 8.1 Input parameters

Input parameters

Table C-21 Input parameters for the “SBT_V3_ProjHeader_V3_00” function block

Name	Type	Description
xActivate	BOOL	Activation/deactivation of the function block

SBT_V3_ProjHeader_V3_00 function block**C 8.2 Output parameters****Output parameters**

Table C-22 Output parameters for the “SBT_V3_ProjHeader_V3_00” function block

Name	Type	Description
strProjDescription	STRING	Project description of the SAFECONF project (from BIN file/POU)
strProjName	STRING	Project name of the SAFECONF project (from BIN file/POU)
strProjVersion	STRING	Project version of the SAFECONF project (from BIN file/POU)
strProjFileName	STRING	File name of the SAFECONF project (name of BIN file/POU)
dwProjCRC	DWORD	Checksum of the SAFECONF project
dwProjTimeStamp	DWORD	Time stamp of the SAFECONF project (seconds from 1970-01-01)
strSBTdescription	STRING	Project description of the project stored on the LPSDO module
strSBTname	STRING	Name of the project stored on the LPSDO module
strSBTversion	STRING	Version of the project stored on the LPSDO module
dwSBT_CRC	DWORD	Checksum of the project stored on the LPSDO module
dwSBTtimeStamp	DWORD	Time stamp of the project stored on the LPSDO module (seconds from 1970-01-01)

C 8.3 I/O parameters**I/O parameters**

Table C-23 I/O parameters for the “SBT_V3_ProjHeader_V3_00” function block

Name	Type	Description
udtSBT	SBT_V3_UDT_SBT_V2	Data exchange structure The following applies when inside an island: Same udtSBT parameter as the “SBT_V3_Operate_V3_00” function block

C 9 SBT_V3_DiagCode_V3_00 function block



This function block is optional. It is not essential in order to operate a SafetyBridge island.

The function block makes available the diagnostic data of all the SBT modules.

The diagnostic codes of the individual modules are combined in an array of the “SBT_V3_Operate_V3_00” function block and transferred to the “SBT_V3_DiagCode_V3_00” function block. This function block displays the contents of the array.

If no diagnostic code is present or the modules are not parameterized, the function block indicates the value of the DIP switches.

Use the function block once per island.

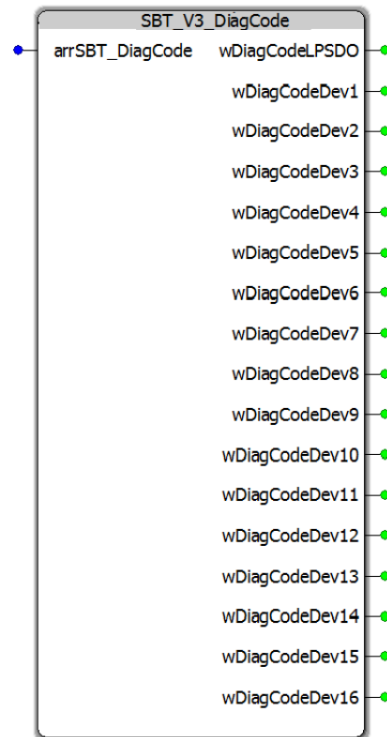


Figure C-10 “SBT_V3_DiagCode_V3_00” function block

SBT_V3_DiagCode_V3_00 function block

C 9.1 Input parameters**Input parameters**

Table C-24 Input parameters for the "SBT_V3_DiagCode_V3_00" function block

Name	Type	Description
arrSBT_DiagCode	SBT_V3_ARR_W_0_16	Array of diagnostic codes from the LPSDO module and satellites 1 to 16. Important: link this input to the arrSBT_DiagCode output of the "SBT_V3_Operate_V3_00" function block.

C 9.2 Output parameters**Output parameters**

Table C-25 Output parameters for the "SBT_V3_DiagCode_V3_00" function block

Name	Type	Description
wDiagCodeLPSDO	WORD	Diagnostic code of the LPSDO module
wDiagCodeDev[1...16]	WORD	Diagnostic code of satellites 1 to 16.

C 9.3 Diagnostics examples for the function block**Diagnostics examples**

Table C-26 Examples for diagnostic codes

Name	Code	Description
wDiagCodeLPSDO	0500 _{hex}	Communication with one or more modules interrupted
	0D00 _{hex}	Acknowledgment of a communication error requested
	8000 _{hex}	SBT island is operating properly
	4xxx _{hex}	Configuration of the DIP switches is displayed
	Other	See diagnostics description in the user manual
wDiagCode[1...16]	8000 _{hex}	Module is operating properly
	4xxx _{hex}	Configuration of the DIP switches is displayed
	Other	See diagnostics description in the user manual

C 10 SBT_V3_Tracer_V1_00 function block



This function block is optional. It is not essential in order to operate a SafetyBridge island.

If a communication error has occurred, the LPSDO module saves the last four telegrams between the module and other devices. The “SBT_V3_Tracer_V1_00” function block reads the telegrams and writes them to the “udtTracer” structure.

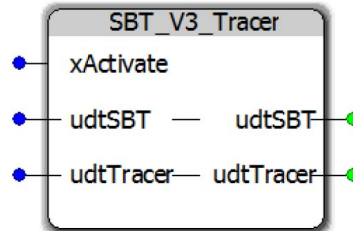


Figure C-11 “SBT_V3_Tracer_V1_00” function block

C 10.1 Input parameters

Input parameters

Table C-27 Input parameters for the “SBT_V3_Tracer_V1_00” function block

Name	Type	Description
xActivate	BOOL	Activation/deactivation of the function block

C 10.2 I/O parameters

I/O parameters

Table C-28 I/O parameters for the “SBT_V3_Tracer_V1_00” function block

Name	Type	Description
udtSBT	SBT_V3_UDT_SBT_V2	Data exchange structure The following applies when inside an island: Same udtSBT parameter as the “SBT_V3_Operate_V3_00” function block
udtTracer	SBT_V3_Tracer	Structure contains the last four telegrams of each module; it is filled when the LPSDO module sets the internal “Trace Trigger” signal to “True”

D Revision history

Revision	Date	Contents
00	2016-05-18	First publication



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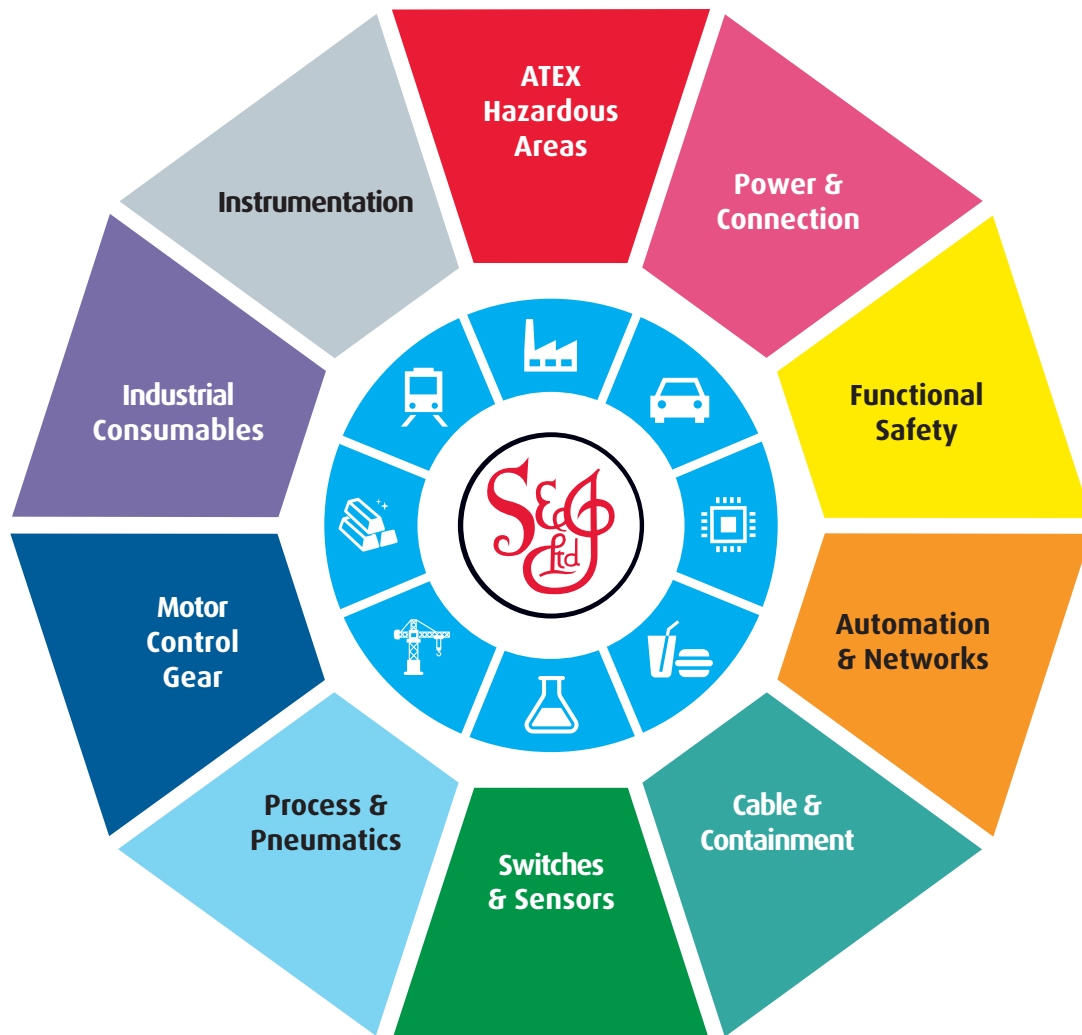
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