



## *Control User Guide*

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***Unidrive M700***

***Unidrive M701***

***Unidrive M702***

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Universal Variable Speed AC drive for  
induction and permanent magnet  
motors

Part Number: 0478-0353-02

Issue: 2

## Original Instructions

For the purposes of compliance with the EU Machinery Directive 2006/42/EC, the English version of this manual is the Original Instructions. Manuals in other languages are Translations of the Original Instructions.

## Documentation

Manuals are available to download from the following locations: <http://www.drive-setup.com/ctdownloads>

The information contained in this manual is believed to be correct at the time of printing and does not form part of any contract. The manufacturer reserves the right to change the specification of the product and its performance, and the contents of the manual, without notice.

## Warranty and Liability

In no event and under no circumstances shall the manufacturer be liable for damages and failures due to misuse, abuse, improper installation, or abnormal conditions of temperature, dust, or corrosion, or failures due to operation outside the published ratings. The manufacturer is not liable for consequential and incidental damages. Contact the supplier of the drive for full details of the warranty terms.

## Environmental policy

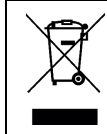
Control Techniques Ltd operates an Environmental Management System (EMS) that conforms to the International Standard ISO 14001.

Further information on our Environmental Policy can be found at: <http://www.drive-setup.com/environment>

## Restriction of Hazardous Substances (RoHS)

The products covered by this manual comply with European and International regulations on the Restriction of Hazardous Substances including EU directive 2011/65/EU and the Chinese Administrative Measures for Restriction of Hazardous Substances in Electrical and Electronic Products.

## Disposal and Recycling (WEEE)



When electronic products reach the end of their useful life, they must not be disposed of along with domestic waste but should be recycled by a specialist recycler of electronic equipment. Control Techniques products are designed to be easily dismantled into their major component parts for efficient recycling. The majority of materials used in the product are suitable for recycling.

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EC Regulation 1907/2006 on the Registration, Evaluation, Authorisation and restriction of Chemicals (REACH) requires the supplier of an article to inform the recipient if it contains more than a specified proportion of any substance which is considered by the European Chemicals Agency (ECHA) to be a Substance of Very High Concern (SVHC) and is therefore listed by them as a candidate for compulsory authorisation.

Further information on our compliance with REACH can be found at: <http://www.drive-setup.com/reach>

## Registered Office

### Nidec Control Techniques Ltd

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Drive Firmware: 01.17.00.00 onwards

Ethernet Firmware: 02.02.02.00 onwards

*For patent and intellectual property related information please go to: [www.ctpatents.info](http://www.ctpatents.info).*

# How to use this guide

This guide is intended to be used in conjunction with the appropriate *Power Installation Guide*. The *Power Installation Guide* gives information necessary to physically install the drive. This guide gives information on drive configuration, operation and optimization.

## NOTE

There are specific safety warnings throughout this guide, located in the relevant sections. In addition, Chapter 1 *Safety information* contains general safety information. It is essential that the warnings are observed and the information considered when working with or designing a system using the drive.

This map of the user guide helps to find the right sections for the task you wish to complete, but for specific information, refer to *Contents* on page 4:

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# EU Declaration of Conformity

**Nidec Control Techniques Ltd**

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**Newtown**

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**SY16 3BE**

**UK**

This declaration is issued under the sole responsibility of the manufacturer. The object of the declaration is in conformity with the relevant European Union harmonization legislation. The declaration applies to the variable speed drive products shown below:

| Model number | Interpretation | Nomenclature aaaa - bbc ddddde                                                                                                                          |
|--------------|----------------|---------------------------------------------------------------------------------------------------------------------------------------------------------|
| aaaa         | Basic series   | M100, M101, M200, M201, M300, M400, M600, M700, M701, M702, M708, M709, M751, M753, M754, F300, H300, E200, E300, HS30, HS70, HS71, HS72, M000, RECT    |
| bb           | Frame size     | 01, 02, 03, 04, 05, 06, 07, 08, 09, 10, 11                                                                                                              |
| c            | Voltage rating | 1 = 100 V, 2 = 200 V, 4 = 400 V, 5 = 575 V, 6 = 690 V                                                                                                   |
| dddd         | Current rating | Example 01000 = 100 A                                                                                                                                   |
| e            | Drive format   | A = 6P Rectifier + Inverter (internal choke), D = Inverter, E = 6P Rectifier + Inverter (external choke), T = 12P Rectifier + Inverter (external choke) |

The model number may be followed by additional characters that do not affect the ratings.

The variable speed drive products listed above have been designed and manufactured in accordance with the following European harmonized standards:

|                             |                                                                                                                                                                                                                                                   |
|-----------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| EN 61800-5-1:2007           | Adjustable speed electrical power drive systems - Part 5-1: Safety requirements - Electrical, thermal and energy                                                                                                                                  |
| EN 61800-3: 2004+A1:2012    | Adjustable speed electrical power drive systems - Part 3: EMC requirements and specific test methods                                                                                                                                              |
| EN 61000-6-2:2005           | Electromagnetic compatibility (EMC) - Part 6-2: Generic standards - Immunity for industrial environments                                                                                                                                          |
| EN 61000-6-4: 2007+ A1:2011 | Electromagnetic compatibility (EMC) - Part 6-4: Generic standards - Emission standard for industrial environments                                                                                                                                 |
| EN 61000-3-2:2014           | Electromagnetic compatibility (EMC) - Part 3-2: Limits for harmonic current emissions (equipment input current ≤16 A per phase)                                                                                                                   |
| EN 61000-3-3:2013           | Electromagnetic compatibility (EMC) - Part 3-3: Limitation of voltage changes, voltage fluctuations and flicker in public, low voltage supply systems, for equipment with rated current ≤16 A per phase and not subject to conditional connection |

EN 61000-3-2:2014 Applicable where input current < 16 A. No limits apply for professional equipment where input power ≥1 kW.

These products comply with the Restriction of Hazardous Substances Directive (2011/65/EU), the Low Voltage Directive (2014/35/EU) and the Electromagnetic Compatibility Directive (2014/30/EU).



**G Williams**

**Vice President, Technology**

**Date: 6th September 2017**

These electronic drive products are intended to be used with appropriate motors, controllers, electrical protection components and other equipment to form complete end products or systems. Compliance with safety and EMC regulations depends upon installing and configuring drives correctly, including using the specified input filters.

The drives must be installed only by professional installers who are familiar with requirements for safety and EMC. Refer to the Product Documentation. An EMC data sheet is available giving detailed information. The assembler is responsible for ensuring that the end product or system complies with all the relevant laws in the country where it is to be used.

# EU Declaration of Conformity (including 2006 Machinery Directive)

**Nidec Control Techniques Ltd**  
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**Newtown**  
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**SY16 3BE**  
**UK**

This declaration is issued under the sole responsibility of the manufacturer. The object of the declaration is in conformity with the relevant Union harmonization legislation. The declaration applies to the variable speed drive products shown below:

| Model No. | Interpretation | Nomenclature aaaa - bbc ddddde                                                                                                                          |
|-----------|----------------|---------------------------------------------------------------------------------------------------------------------------------------------------------|
| aaaa      | Basic series   | M600, M700, M701, M702, M708, M709, M751, M753, M754, F300, H300, E200, E300, HS70, HS71, HS72, M000, RECT                                              |
| bb        | Frame size     | 01, 02, 03, 04, 05, 06, 07, 08, 09, 10, 11                                                                                                              |
| c         | Voltage rating | 1 = 100 V, 2 = 200 V, 4 = 400 V, 5 = 575 V, 6 = 690 V                                                                                                   |
| dddd      | Current rating | Example 01000 = 100 A                                                                                                                                   |
| e         | Drive format   | A = 6P Rectifier + Inverter (internal choke), D = Inverter, E = 6P Rectifier + Inverter (external choke), T = 12P Rectifier + Inverter (external choke) |

The model number may be followed by additional characters that do not affect the ratings.

**This declaration relates to these products when used as a safety component of a machine. Only the Safe Torque Off function may be used for a safety function of a machine. None of the other functions of the drive may be used to carry out a safety function.**

These products fulfil all the relevant provisions of the Machinery Directive 2006/42/EC and the Electromagnetic Compatibility Directive (2014/30/EU).

EC type examination has been carried out by the following notified body:

TUV Rheinland Industrie Service GmbH  
 Am Grauen Stein  
 D-51105 Köln  
 Germany

The harmonized standards used are shown below:

EC type-examination certificate numbers:

01/205/5270.02/17 dated 2017-08-28

Notified body identification number: 0035

|                                                |                                                                                                                             |
|------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------|
| EN 61800-5-1:2016                              | Adjustable speed electrical power drive systems - Part 5-2: Safety requirements - Functional                                |
| EN 61800-5-1:2016<br>(in extracts)             | Adjustable speed electrical power drive systems - Part 5-1: Safety requirements - Electrical, thermal and energy            |
| EN 61800-3: 2004+A1:2012                       | Adjustable speed electrical power drive systems - Part 3: EMC requirements and specific test methods                        |
| EN ISO 13849-1:2015                            | Safety of Machinery, Safety-related parts of control systems, General principles for design                                 |
| EN 62061:2005 + AC:2010<br>+ A1:2013 + A2:2015 | Safety of machinery, Functional safety of safety related electrical, electronic and programmable electronic control systems |
| IEC 61508 Parts 1 - 7:2010                     | Functional safety of electrical/ electronic/programmable electronic safety-related systems                                  |

Person authorised to complete the technical file:

P Knight  
 Conformity Engineer  
 Newtown, Powys, UK

DoC authorised by:



G. Williams

Vice President, Technology

Date: 6th September 2017

Place: Newtown, Powys, UK

#### IMPORTANT NOTICE

These electronic drive products are intended to be used with appropriate motors, controllers, electrical protection components and other equipment to form complete end products or systems. It is the responsibility of the installer to ensure that the design of the complete machine, including its safety-related control system, is carried out in accordance with the requirements of the Machinery Directive and any other relevant legislation. The use of a safety-related drive in itself does not ensure the safety of the machine. Compliance with safety and EMC regulations depends upon installing and configuring drives correctly, including using the specified input filters. The drive must be installed only by professional installers who are familiar with requirements for safety and EMC. The assembler is responsible for ensuring that the end product or system complies with all relevant laws in the country where it is to be used. For more information regarding Safe Torque Off, refer to the Product Documentation.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

# 1 Safety information

## 1.1 Warnings, Cautions and Notes



A Warning contains information which is essential for avoiding a safety hazard.



A Caution contains information which is necessary for avoiding a risk of damage to the product or other equipment.

### NOTE

A Note contains information which helps to ensure correct operation of the product.

## 1.2 Important safety information. Hazards. Competence of designers and installers

This guide applies to products which control electric motors either directly (drives) or indirectly (controllers, option modules and other auxiliary equipment and accessories). In all cases the hazards associated with powerful electrical drives are present, and all safety information relating to drives and associated equipment must be observed.

Specific warnings are given at the relevant places in this guide.

Drives and controllers are intended as components for professional incorporation into complete systems. If installed incorrectly they may present a safety hazard. The drive uses high voltages and currents, carries a high level of stored electrical energy, and is used to control equipment which can cause injury. Close attention is required to the electrical installation and the system design to avoid hazards either in normal operation or in the event of equipment malfunction. System design, installation, commissioning/start-up and maintenance must be carried out by personnel who have the necessary training and competence. They must read this safety information and this guide carefully.

## 1.3 Responsibility

It is the responsibility of the installer to ensure that the equipment is installed correctly with regard to all instructions given in this guide. They must give due consideration to the safety of the complete system, so as to avoid the risk of injury both in normal operation and in the event of a fault or of reasonably foreseeable misuse.

The manufacturer accepts no liability for any consequences resulting from inappropriate, negligent or incorrect installation of the equipment.

## 1.4 Compliance with regulations

The installer is responsible for complying with all relevant regulations, such as national wiring regulations, accident prevention regulations and electromagnetic compatibility (EMC) regulations. Particular attention must be given to the cross-sectional areas of conductors, the selection of fuses or other protection, and protective ground (earth) connections. This guide contains instructions for achieving compliance with specific EMC standards.

All machinery to be supplied within the European Union in which this product is used must comply with the following directives:

2006/42/EC Safety of machinery.

2014/30/EU: Electromagnetic Compatibility.

## 1.5 Electrical hazards

The voltages used in the drive can cause severe electrical shock and/or burns, and could be lethal. Extreme care is necessary at all times when working with or adjacent to the drive. Hazardous voltage may be present in any of the following locations:

- AC and DC supply cables and connections
- Output cables and connections
- Many internal parts of the drive, and external option units

Unless otherwise indicated, control terminals are single insulated and must not be touched.

The supply must be disconnected by an approved electrical isolation device before gaining access to the electrical connections.

The STOP and Safe Torque Off functions of the drive do not isolate dangerous voltages from the output of the drive or from any external option unit.

The drive must be installed in accordance with the instructions given in this guide. Failure to observe the instructions could result in a fire hazard.

## 1.6 Stored electrical charge

The drive contains capacitors that remain charged to a potentially lethal voltage after the AC supply has been disconnected. If the drive has been energized, the AC supply must be isolated at least ten minutes before work may continue.

## 1.7 Mechanical hazards

Careful consideration must be given to the functions of the drive or controller which might result in a hazard, either through their intended behaviour or through incorrect operation due to a fault. In any application where a malfunction of the drive or its control system could lead to or allow damage, loss or injury, a risk analysis must be carried out, and where necessary, further measures taken to reduce the risk - for example, an over-speed protection device in case of failure of the speed control, or a fail-safe mechanical brake in case of loss of motor braking.

**With the sole exception of the Safe Torque Off function, none of the drive functions must be used to ensure safety of personnel, i.e. they must not be used for safety-related functions.**

The Safe Torque Off function may be used in a safety-related application. The system designer is responsible for ensuring that the complete system is safe and designed correctly according to the relevant safety standards.

The design of safety-related control systems must only be done by personnel with the required training and experience. The Safe Torque Off function will only ensure the safety of a machine if it is correctly incorporated into a complete safety system. The system must be subject to a risk assessment to confirm that the residual risk of an unsafe event is at an acceptable level for the application.

## 1.8 Access to equipment

Access must be restricted to authorized personnel only. Safety regulations which apply at the place of use must be complied with.

## 1.9 Environmental limits

Instructions in this guide regarding transport, storage, installation and use of the equipment must be complied with, including the specified environmental limits. This includes temperature, humidity, contamination, shock and vibration. Drives must not be subjected to excessive physical force.

## 1.10 Hazardous environments

The equipment must not be installed in a hazardous environment (i.e. a potentially explosive environment).

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 1.11 Motor

The safety of the motor under variable speed conditions must be ensured.

To avoid the risk of physical injury, do not exceed the maximum specified speed of the motor.

Low speeds may cause the motor to overheat because the cooling fan becomes less effective, causing a fire hazard. The motor should be installed with a protection thermistor. If necessary, an electric forced vent fan should be used.

The values of the motor parameters set in the drive affect the protection of the motor. The default values in the drive must not be relied upon. It is essential that the correct value is entered in the Motor Rated Current parameter.

## 1.12 Mechanical brake control

Any brake control functions are provided to allow well co-ordinated operation of an external brake with the drive. While both hardware and software are designed to high standards of quality and robustness, they are not intended for use as safety functions, i.e. where a fault or failure would result in a risk of injury. In any application where the incorrect operation of the brake release mechanism could result in injury, independent protection devices of proven integrity must also be incorporated.

## 1.13 Adjusting parameters

Some parameters have a profound effect on the operation of the drive. They must not be altered without careful consideration of the impact on the controlled system. Measures must be taken to prevent unwanted changes due to error or tampering.

## 1.14 Electromagnetic compatibility (EMC)

Installation instructions for a range of EMC environments are provided in the relevant Power Installation Guide. If the installation is poorly designed or other equipment does not comply with suitable standards for EMC, the product might cause or suffer from disturbance due to electromagnetic interaction with other equipment. It is the responsibility of the installer to ensure that the equipment or system into which the product is incorporated complies with the relevant EMC legislation in the place of use.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 2 Product information

### 2.1 Introduction

#### Universal AC and servo drive

This product family consists of *Unidrive M700*, *Unidrive M701* and *Unidrive M702*, these deliver maximum machine performance.

#### Common features (Unidrive M700, 701 and 702)

- Universal high performance open and closed loop control for induction, servo, permanent magnet and linear motors
- Automation and motion option module for direct migration of SyPTPro / SM-Applications programs
- Onboard IEC 61131-3 programmable automation and motion control
- Flexibility with speed and position measurement, supporting multiple devices and all common interfaces
- NV Media Card for parameter copying and data storage

#### Optional features (Unidrive M700, 701 and 702)

- Select up to three option modules including programmable automation and motion control.

#### Unidrive M700

- Ethernet fieldbus communications
- Single channel Safe Torque Off (STO) input

#### Unidrive M701

- Provides a direct replacement / upgrade for Unidrive SP
- EIA 485 serial communications interface
- Single channel Safe Torque Off (STO) input

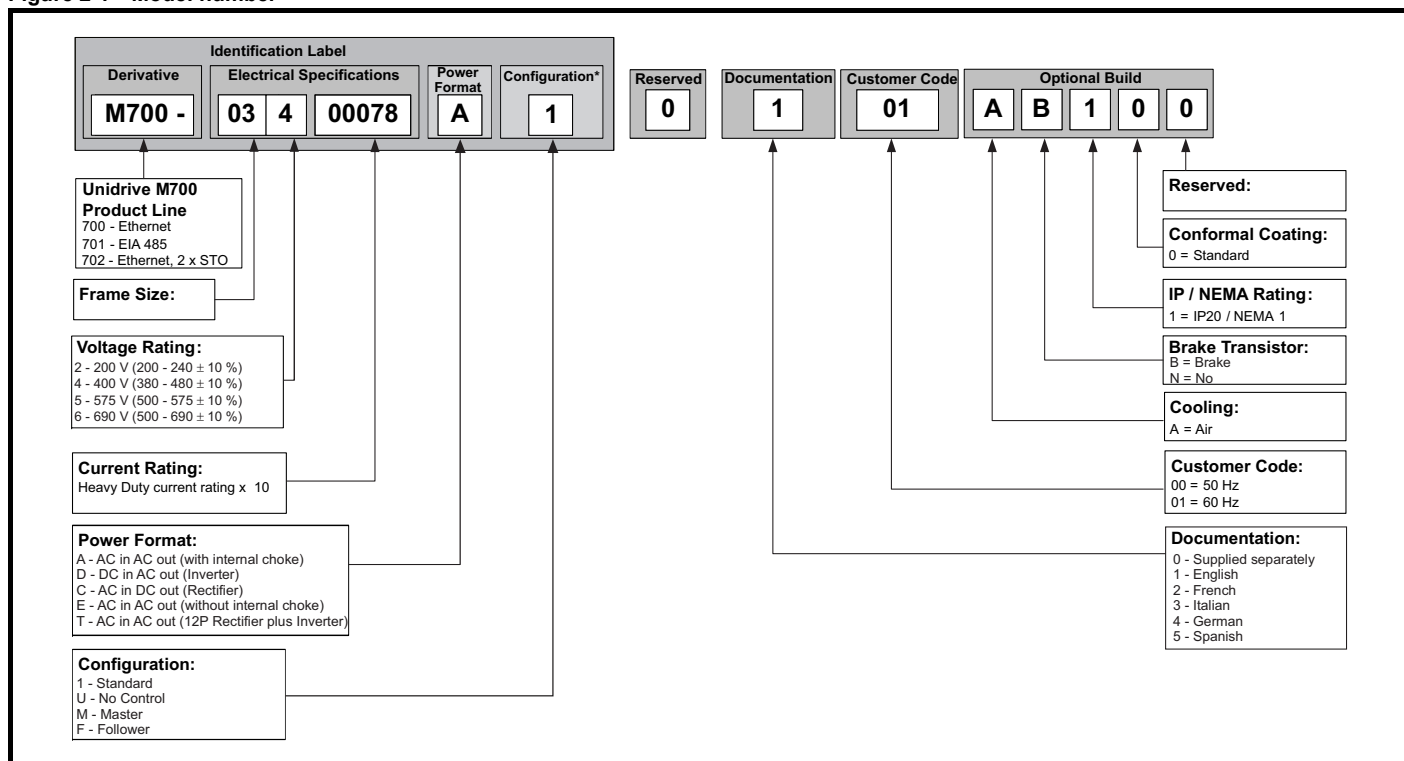
#### Unidrive M702

- Ethernet fieldbus communications
- Dual channel Safe Torque Off (STO) input

### 2.2 Model number

The way in which the model numbers for the *Unidrive M700* range are formed is illustrated below:

Figure 2-1 Model number



\* Only shown on Frame size 9, 10 and 11 identification label.

#### NOTE

For simplicity a Frame 9 drive with no internal choke (i.e. model 09xxxxxxE) is referred to as a Frame 9E and a Frame 9 drive with an internal choke (i.e. model 09xxxxxxA) is referred to as a Frame 9A. Any reference to Frame 9 is applicable to both sizes 9E and 9A.

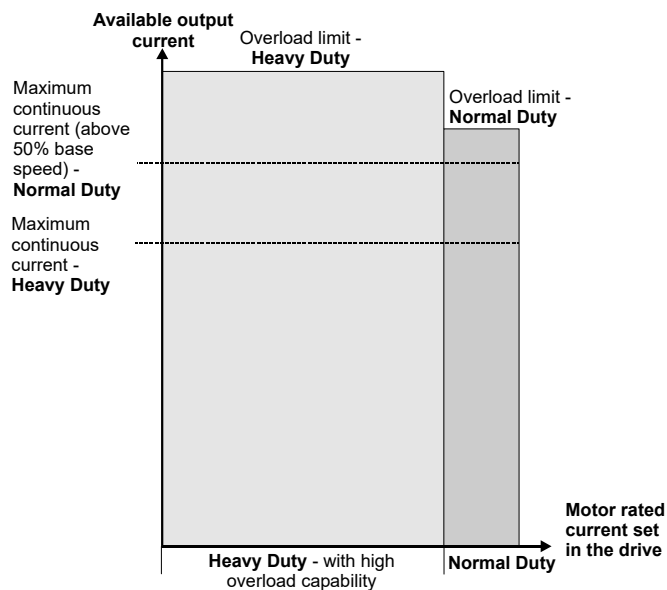
|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 2.3 Ratings

The drive is dual rated.

The setting of the motor rated current determines which rating applies - Heavy Duty or Normal Duty.

The two ratings are compatible with motors designed to IEC60034. The graph aside illustrates the difference between Normal Duty and Heavy Duty with respect to continuous current rating and short term overload limits.



### Normal Duty

For applications which use Self ventilated (TENV/TEFC) induction motors and require a low overload capability, and full torque at low speeds is not required (e.g. fans, pumps).

Self ventilated (TENV/TEFC) induction motors require increased protection against overload due to the reduced cooling effect of the fan at low speed. To provide the correct level of protection the  $I^2t$  software operates at a level which is speed dependent. This is illustrated in the graph below.

#### NOTE

The speed at which the low speed protection takes effect can be changed by the setting of *Low Speed Thermal Protection Mode* (04.025). The protection starts when the motor speed is below 15 % of base speed when Pr 04.025 = 0 (default) and below 50 % when Pr 04.025 = 1.

### Heavy Duty (default)

For constant torque applications or applications which require a high overload capability, or full torque is required at low speeds (e.g. winders, hoists).

The thermal protection is set to protect force ventilated induction motors and permanent magnet servo motors by default.

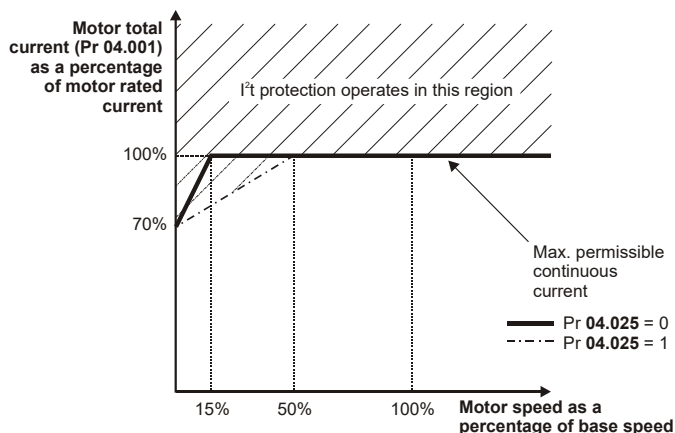
#### NOTE

If the application uses a self ventilated (TENV/TEFC) induction motor and increased thermal protection is required for speeds below 50 % base speed, then this can be enabled by setting *Low Speed Thermal Protection Mode* (04.025) = 1.

### Operation of motor $I^2t$ protection

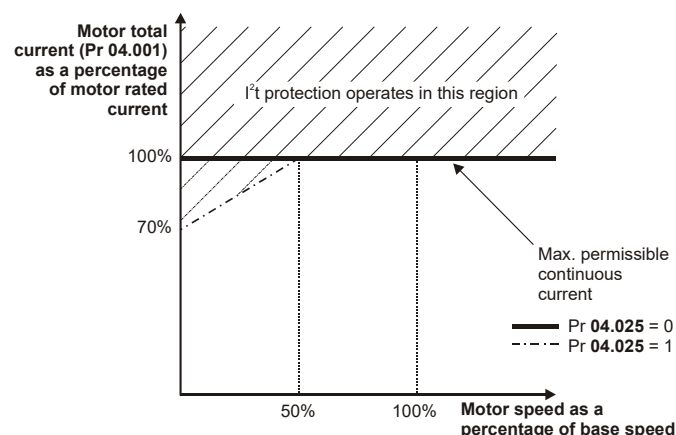
Motor  $I^2t$  protection is fixed as shown below and is compatible with:

- Self ventilated (TENV/TEFC) induction motors



Motor  $I^2t$  protection defaults to be compatible with:

- Forced ventilation induction motors
- Permanent magnet servo motors



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 2.4 Operating modes

The drive is designed to operate in any of the following modes:

1. Open loop mode
  - Open loop vector mode
  - Fixed V/F mode (V/Hz)
  - Quadratic V/F mode (V/Hz)
2. RFC - A
  - With position feedback sensor
  - Without position feedback sensor (Sensorless)
3. RFC - S
  - With position feedback sensor
  - Without position feedback sensor (Sensorless)
4. Regen mode

### 2.4.1 Open loop mode

The drive applies power to the motor at frequencies varied by the user. The motor speed is a result of the output frequency of the drive and slip due to the mechanical load. The drive can improve the speed control of the motor by applying slip compensation. The performance at low speed depends on whether V/F mode or open loop vector mode is selected.

#### Open loop vector mode

The voltage applied to the motor is directly proportional to the frequency except at low speed where the drive uses motor parameters to apply the correct voltage to keep the flux constant under varying load conditions.

Typically 100 % torque is available down to 1 Hz for a 50 Hz motor.

#### Fixed V/F mode

The voltage applied to the motor is directly proportional to the frequency except at low speed where a voltage boost is provided which is set by the user. This mode can be used for multi-motor applications.

Typically 100 % torque is available down to 4 Hz for a 50 Hz motor.

#### Quadratic V/F mode

The voltage applied to the motor is directly proportional to the square of the frequency except at low speed where a voltage boost is provided which is set by the user. This mode can be used for running fan or pump applications with quadratic load characteristics or for multi-motor applications. This mode is not suitable for applications requiring a high starting torque.

### 2.4.2 RFC-A mode

Rotor Flux Control for Asynchronous (induction) motors (**RFC-A**) encompasses closed loop vector control with a position feedback device

#### With position feedback

For use with induction motors with a feedback device installed. The drive directly controls the speed of the motor using the feedback device to ensure the rotor speed exactly as demanded. Motor flux is accurately controlled at all times to provide full torque all the way down to zero speed.

#### Without position feedback (Sensorless)

Sensorless mode provides closed loop control without the need for position feedback by using current, voltages and key motor parameters to estimate the motor speed. It can eliminate instability traditionally associated with open loop control such as operating large motors with light loads at low frequencies.

### 2.4.3 RFC- S mode

Rotor Flux Control for Synchronous (permanent magnet brushless) motors (**RFC-S**) provides closed loop control with position feedback device.

#### With position feedback

For use with permanent magnet brushless motors with a feedback device installed.

The drive directly controls the speed of the motor using the feedback device to ensure the rotor speed is exactly as demanded. Flux control is not required because the motor is self excited by the permanent magnets which form part of the rotor.

Absolute position information is required from the feedback device to ensure the output voltage is accurately matched to the back EMF of the motor. Full torque is available all the way down to zero speed.

#### Without position feedback

For use with permanent magnet brushless motors without a feedback device installed.

Flux control is not required because the motor is self excited by the permanent magnets which form part of the rotor.

Full torque is available all the way down to zero speed, with salient motors.

### 2.4.4 Regen mode

For use as a regenerative front end for four quadrant operation.

Regen operation allows bi-directional power flow to and from the AC supply. This provides far greater efficiency levels in applications which would otherwise dissipate large amounts of energy in the form of heat in a braking resistor.

The harmonic content of the input current is negligible due to the sinusoidal nature of the waveform when compared to a conventional bridge rectifier or SCR/thyristor front end.

#### NOTE

Contact the supplier of the drive for further information.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 2.5 Compatible position feedback devices

**Table 2-1 Supported feedback devices**

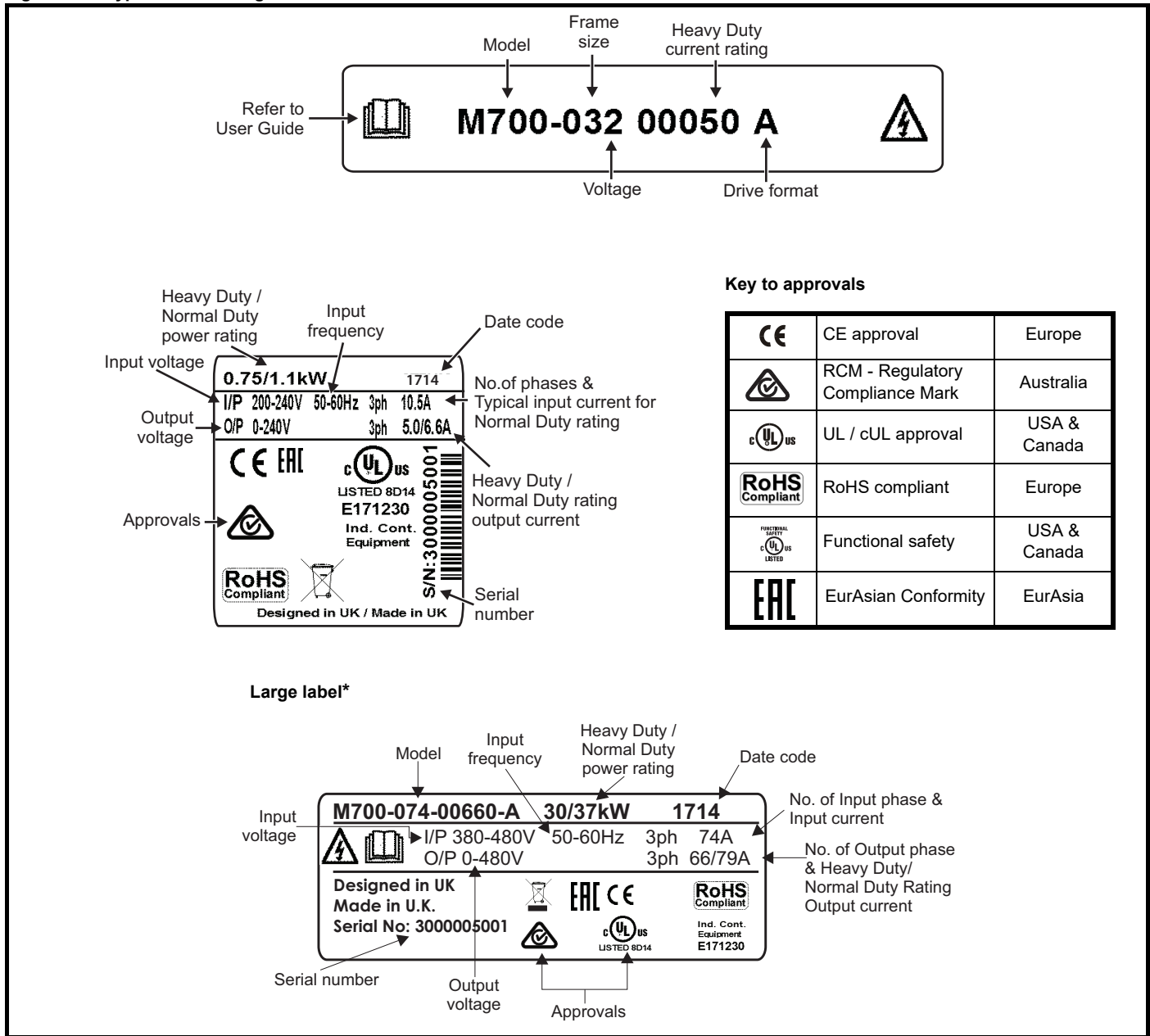
| Encoder type                                                                                                                                             | Pr 3.038 setting                                                                     |
|----------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|
| Quadrature incremental encoders with or without marker pulse                                                                                             | AB (0)                                                                               |
| Quadrature incremental encoders with UVW commutation signals for absolute position for permanent magnet motors with or without marker pulse              | AB Servo (3)                                                                         |
| Forward / reverse incremental encoders with or without marker pulse                                                                                      | FR (2)                                                                               |
| Forward / reverse incremental encoders with UVW commutation signals for absolute position for permanent magnet motors with or without marker pulse       | FR Servo (5)                                                                         |
| Frequency and direction incremental encoders with or without marker pulse                                                                                | FD (1)                                                                               |
| Frequency and direction incremental encoders with UVW commutation signals for absolute position for permanent magnet motors with or without marker pulse | FD Servo (4)                                                                         |
| Sincos incremental encoders                                                                                                                              | SC (6)                                                                               |
| Sincos incremental with commutation signals                                                                                                              | SC Servo (12)                                                                        |
| Heidenhain sincos encoders with EnDat comms for absolute position                                                                                        | SC EnDat (9)                                                                         |
| Stegmann sincos encoders with Hiperface comms for absolute position                                                                                      | SC Hiperface (7)                                                                     |
| Sincos encoders with SSI comms for absolute position                                                                                                     | SC SSI (11)                                                                          |
| Sincos encoders with BiSS (type C) comms for absolute position                                                                                           | SC BiSS (17)                                                                         |
| Sincos incremental with absolute position from single sin and cosine signals                                                                             | SC SC (15)                                                                           |
| SSI encoders (Gray code or binary)                                                                                                                       | SSI (10)                                                                             |
| EnDat communication only encoders                                                                                                                        | EnDat (8)                                                                            |
| BiSS (type C) communication only encoders                                                                                                                | BiSS (13)                                                                            |
| Resolver                                                                                                                                                 | Resolver (14)                                                                        |
| UVW commutation only encoders*                                                                                                                           | Commutation only (16)                                                                |
| Provided by option module                                                                                                                                | Option Slot 1 (18)<br>Option Slot 2 (19)<br>Option Slot 3 (20)<br>Option Slot 4 (21) |

\* This feedback device provides very low resolution feedback and should not be used for applications requiring a high level of performance.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 2.6 Nameplate description

Figure 2-2 Typical drive rating labels



\* This label is only applicable to Size 7 and above.

Refer to Figure 2-1 *Model number* on page 11 for further information relating to the labels.

### Date code format

The date code consists of four numbers, the first two numbers indicate the year and the remaining two numbers indicate the week of the year in which the drive was built.

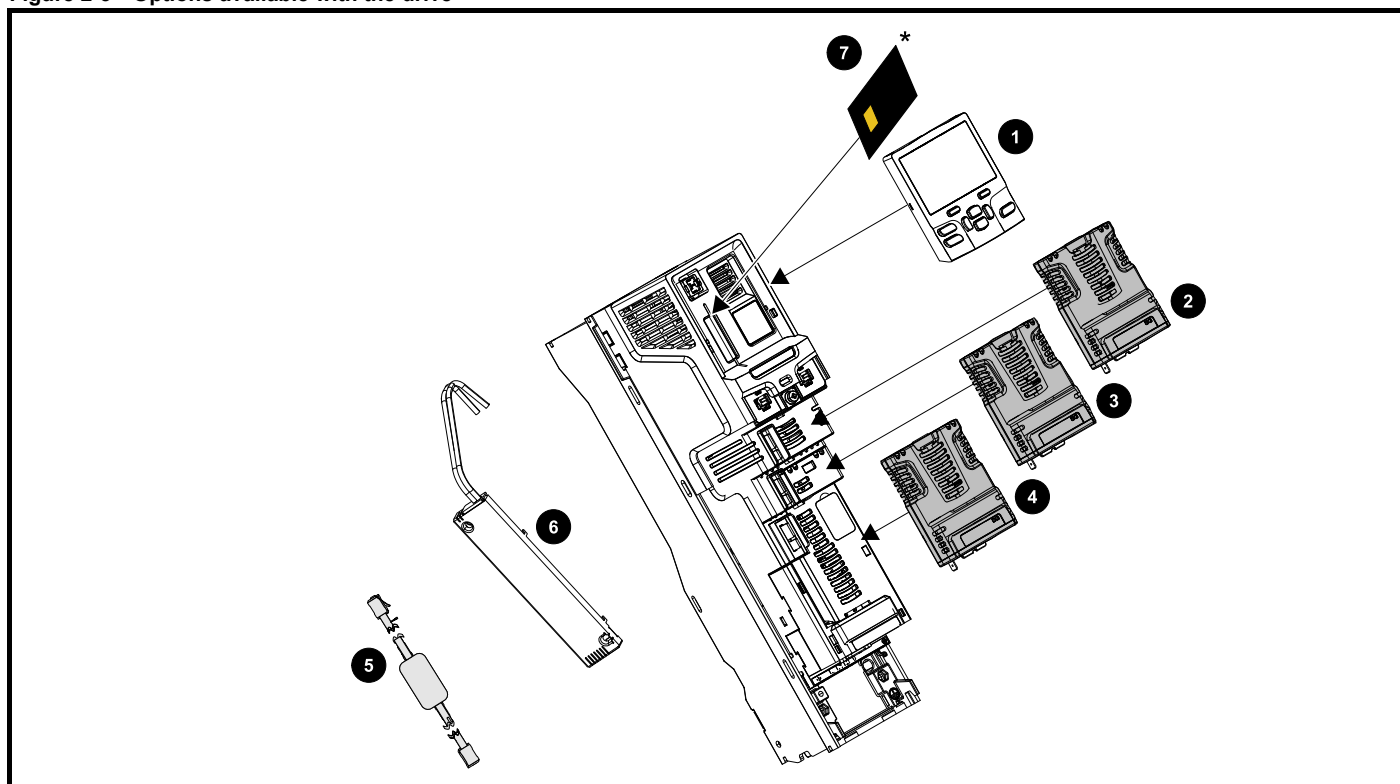
### Example:

A date code of 1714 would correspond to week 14 of the year 2017.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 2.7 Options

Figure 2-3 Options available with the drive



1. Keypad
2. Option module slot 1
3. Option module slot 2
4. Option module slot 3
5. CT USB Comms cable
6. Internal braking resistor (available on size 3, 4 and 5)
7. NV media card

\* For further information, refer to Chapter 10 *NV Media Card Operation* on page 139.

Unidrive M option modules come in two different formats, a standard option module and a large option module. All standard option modules are color-coded in order to make identification easy, whereas the larger option module is black. All modules have an identification label on top of the module. Standard option modules can be installed to any of the available option slots on the drive, whereas the large option modules can only be installed to option slot 3. The following tables shows the color-code key and gives further details on their function.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Table 2-2 Option module identification

| Type                       | Option module                                                                       | Color        | Name                                        | Further Details                                                                                                                                                                                                                                                                        |
|----------------------------|-------------------------------------------------------------------------------------|--------------|---------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Feedback                   |    | N/A          | 15-way D-type converter                     | <b>Drive encoder input converter</b><br>Provides screw terminal interface for encoder wiring and spade terminal for shield                                                                                                                                                             |
|                            |                                                                                     | N/A          | Single ended encoder interface (15V or 24V) | <b>Single ended encoder interface</b><br>Provides an interface for single ended ABZ encoder signals, such as those from hall effect sensors. 15 V and 24 V versions are available                                                                                                      |
| Fieldbus                   |    | N/A          | KI-485 Adaptor                              | <b>EIA 485 Comms Adaptor</b><br>EIA 485 Comms adaptor provides EIA 485 communication interface. This adaptor supports 115 k Baud, node addresses between 1 to 16 and 8 1 NP M serial mode.                                                                                             |
|                            |    | Purple       | SI-PROFIBUS                                 | <b>Profibus option</b><br>PROFIBUS adapter for communications with the drive                                                                                                                                                                                                           |
|                            |    | Medium Grey  | SI-DeviceNet                                | <b>DeviceNet option</b><br>DeviceNet adapter for communications with the drive                                                                                                                                                                                                         |
|                            |    | Light Grey   | SI-CANopen                                  | <b>CANopen option</b><br>CANopen adapter for communications with the drive                                                                                                                                                                                                             |
|                            |    | Beige        | SI-Ethernet                                 | External Ethernet module that supports EtherNet/IP, Modbus TCP/IP and RTMoE. The module can be used to provide high speed drive access, global connectivity and integration with IT network technologies, such as wireless networking                                                  |
|                            |    | Yellow Green | SI-PROFINET V2                              | <b>PROFINET V2 option</b><br>PROFINET V2 adapter for communications with the drive<br>Note: PROFINET V2 replaces PROFINET RT.                                                                                                                                                          |
|                            |   | Brown Red    | SI-EtherCAT                                 | <b>EtherCAT option</b><br>EtherCAT adapter for communications with the drive                                                                                                                                                                                                           |
| Automation (I/O expansion) |  | Orange       | SI-I/O                                      | <b>Extended I/O</b><br>Increases the I/O capability by adding the following combinations: <ul style="list-style-type: none"> <li>• Digital I/O</li> <li>• Digital Inputs</li> <li>• Analog Inputs (differential or single ended)</li> <li>• Analog Output</li> <li>• Relays</li> </ul> |
| Automation (Applications)  |  | Moss Green   | MCi200                                      | <b>Machine Control Studio Compatible Applications Processor</b><br>2nd processor for running pre-defined and/or customer created application software.                                                                                                                                 |
|                            |  | Moss Green   | MCi210                                      | <b>Machine Control Studio Compatible Applications Processor (with Ethernet communications)</b><br>2nd processor for running pre-defined and/or customer created application software with Ethernet communications.                                                                     |
|                            |  | Black        | SI-Applications Plus                        | <b>SyPTPro Compatible Applications Processor (with CTNet)</b><br>2nd processor for running pre-defined and/or customer created application software with CTNet support (can only be used on Slot 3).                                                                                   |
| Feedback                   |  | Light Brown  | SI-Encoder                                  | Incremental encoder input interface module.                                                                                                                                                                                                                                            |
|                            |  | Dark Brown   | SI-Universal Encoder                        | Additional combined encoder input and output interface supporting Incremental, SinCos, HIPERFACE, EnDAT and SSI encoders.                                                                                                                                                              |
| Safety                     |  | Yellow       | SI-Safety                                   | Safety module that provides an intelligent, programmable solution to meet the IEC 61800-5-2 functional safety standard                                                                                                                                                                 |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Table 2-3 Keypad identification

| Type   | Keypad                                                                            | Name              | Further Details                                                                         |
|--------|-----------------------------------------------------------------------------------|-------------------|-----------------------------------------------------------------------------------------|
| Keypad |  | KI-Keypad         | <b>LCD keypad option</b><br>Keypad with a LCD display                                   |
|        |                                                                                   | KI-Keypad RTC     | <b>LCD keypad option</b><br>Keypad with a LCD display and real time clock               |
|        |  | Remote-Keypad RTC | <b>Remote LCD keypad option</b><br>Remote Keypad with a LCD display and real time clock |
|        |  | Remote-Keypad     | <b>Remote LCD keypad option</b><br>Remote Keypad with a LCD display                     |

Table 2-4 Additional options

| Type    | Option                                                                            | Name            | Further Details                                                                |
|---------|-----------------------------------------------------------------------------------|-----------------|--------------------------------------------------------------------------------|
| Back-up |  | SD Card Adaptor | <b>SD Card Adaptor</b><br>Allows the drive to use an SD card for drive back-up |
|         |  | SMARTCARD       | <b>SMARTCARD</b><br>Used for parameter back-up with the drive                  |

|                    |                     |                                |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|--------------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | <b>Mechanical installation</b> | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|--------------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

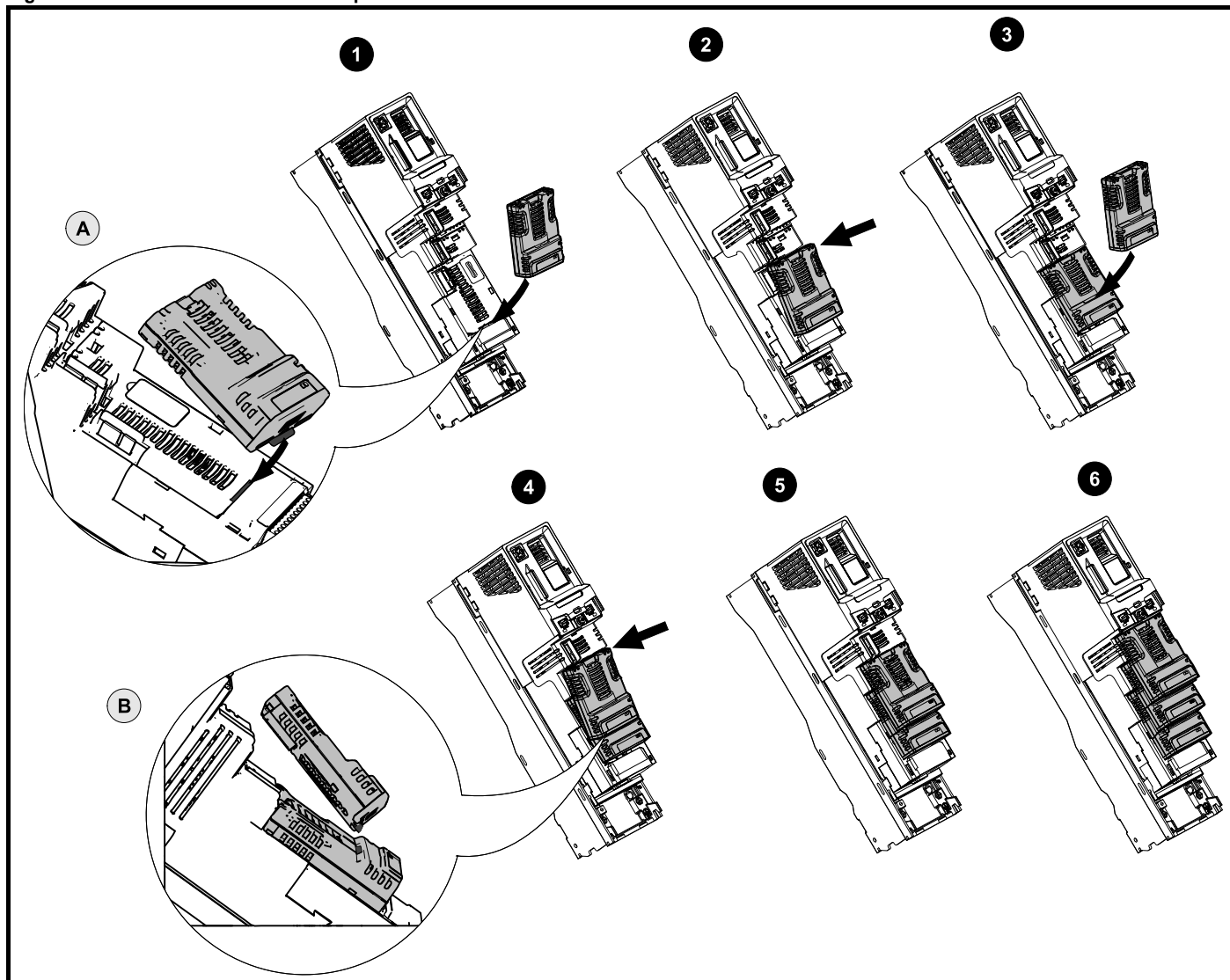
## 3 Mechanical installation

### 3.1 Installing / removing option modules and keypads



Power down the drive before installing / removing the option module. Failure to do so may result in damage to the product.

Figure 3-1 Installation of a standard option module



#### Installing the first option module

##### NOTE

Option module slots must be used in the following order: slot 3, slot 2 and slot 1 (refer to section 2.7 *Options* on page 16 for slot numbers).

- Move the option module in direction shown (1).
- Align and insert the option module tab in to the slot provided (2), this is highlighted in the detailed view (A).
- Press down on the option module until it clicks into place.

#### Installing the second option module

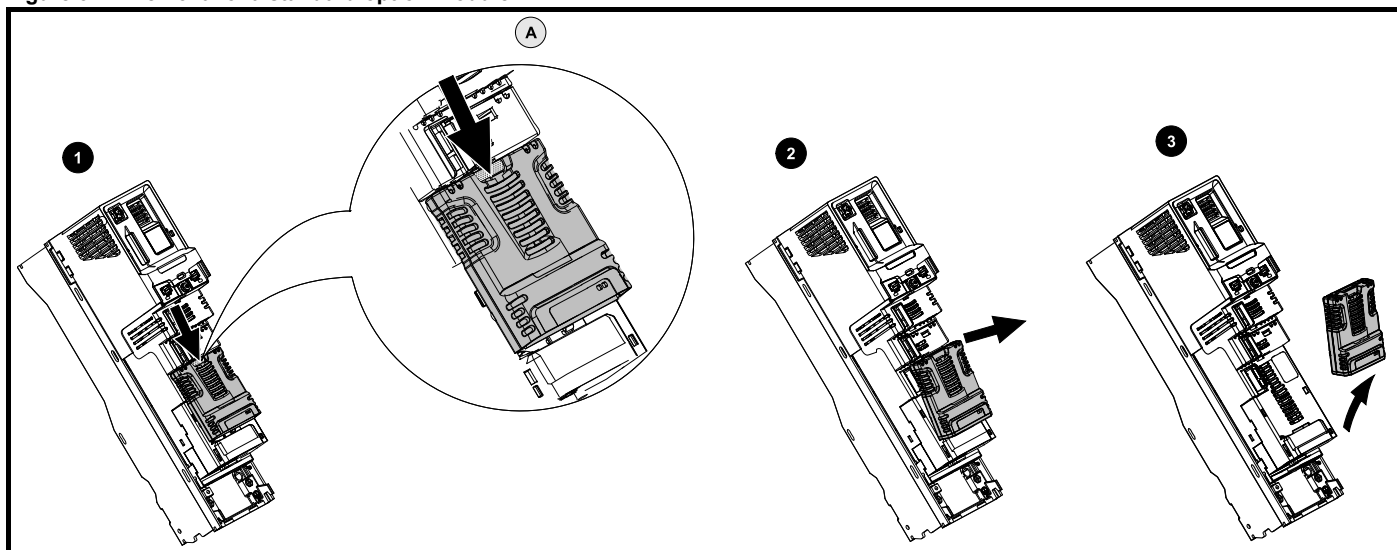
- Move the option module in direction shown (3).
- Align and insert the option module tab in to the slot provided on the already installed option module (4), this is highlighted in the detailed view (B).
- Press down on the option module until it clicks into place. Image (5) shows two option modules fully installed.

#### Installing the third option module

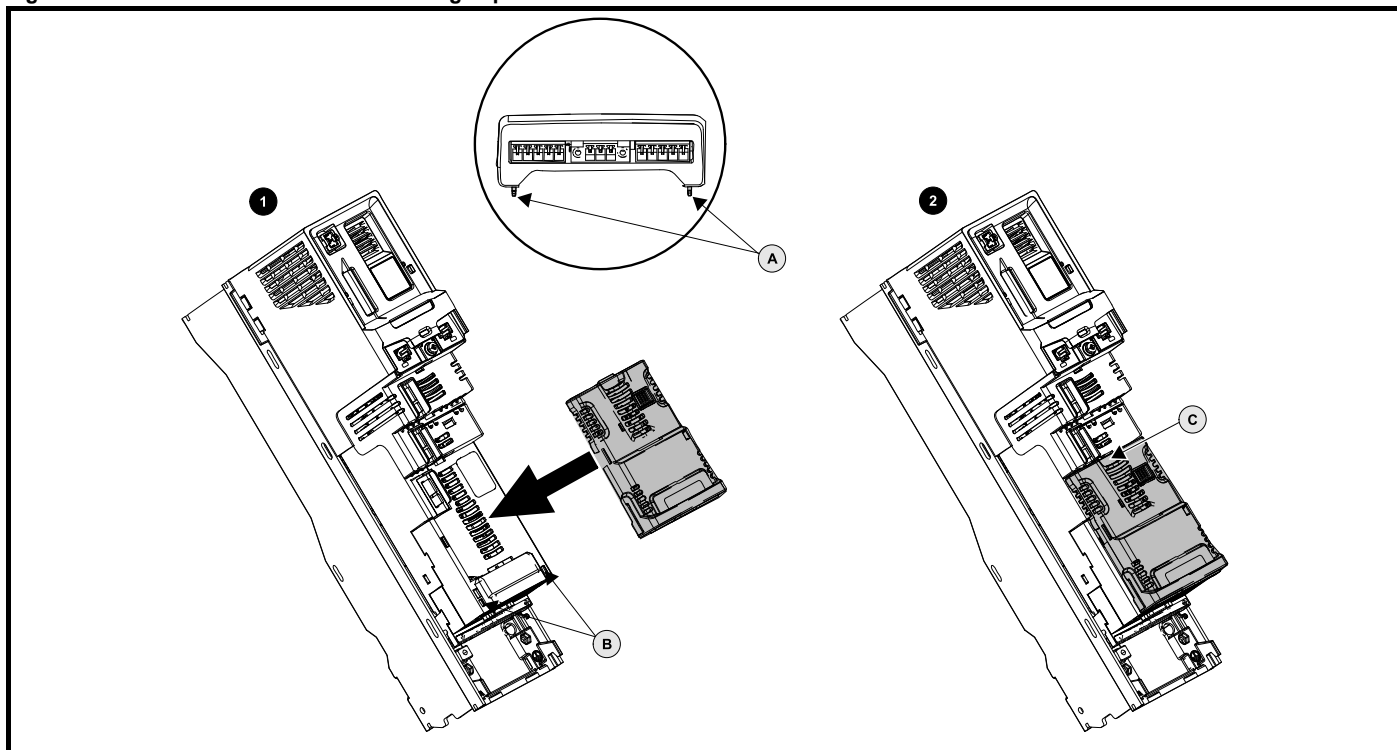
- Repeat the above process.

The drive has the facility for all three option module slots to be used at the same time, image (6) shows the three option modules installed.

|                    |                     |                                |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|--------------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | <b>Mechanical installation</b> | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|--------------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Figure 3-2 Removal of a standard option module**

- Press down on the tab (1) to release the option module from the drive housing, the tab is highlighted in the detailed view (A).
- Tilt the option module towards you as shown (2).
- Totally remove the option module in direction shown (3).

**Figure 3-3 Installation and removal of a large option module****Installing a large option module**

- Move the option module in direction shown (1).
- Align and insert the option module tabs (A) into the slot provided (B).
- Press down on the option module until it clicks into place.

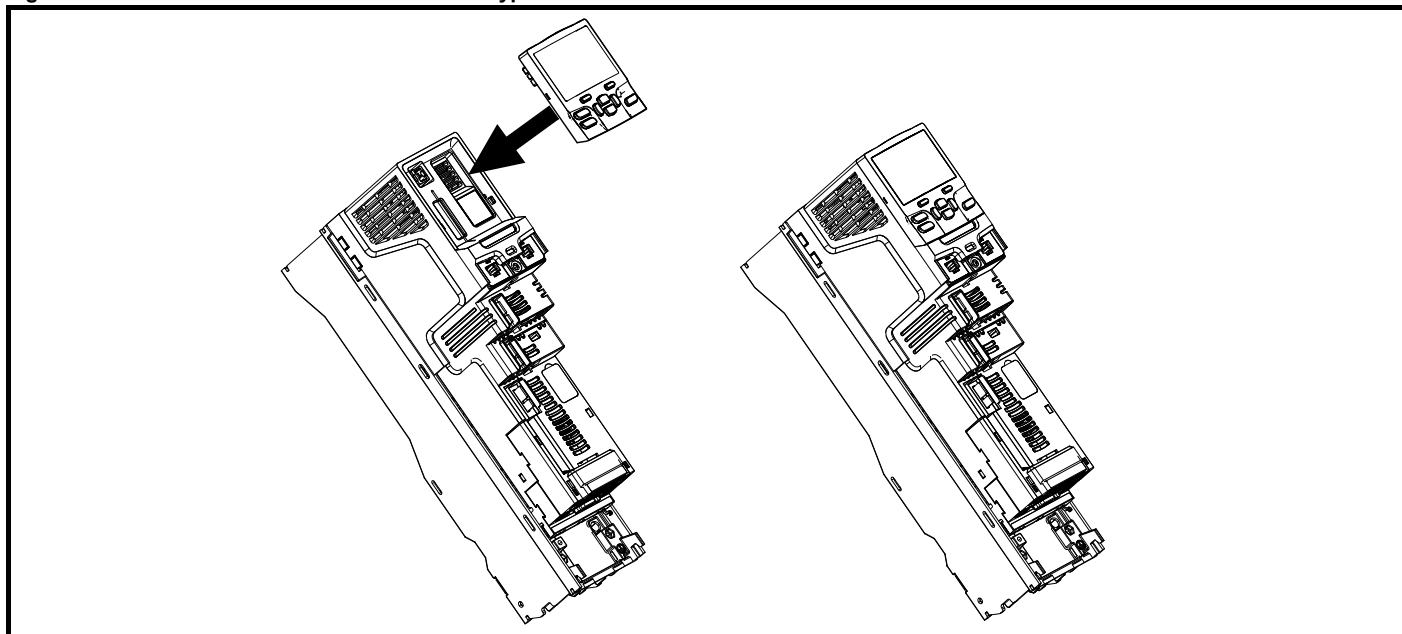
**Removing a large option module**

- Press down on the tab (2C), tilt the option module towards you and remove.

**NOTE**

The large option module can only be inserted into slot 3. Additional standard option modules can still be installed and used in slot 2 and slot 1.

|                    |                     |                                |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|--------------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | <b>Mechanical installation</b> | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|--------------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Figure 3-4 Installation and removal of the KI-Keypad**

To install, align the keypad and press gently in the direction shown until it clicks into position.

To remove, reverse the installation instructions.

**NOTE**

The keypad can be installed / removed while the drive is powered up and running a motor, providing that the drive is not operating in keypad mode.

## 3.2 Real time clock battery replacement

Those keypads which have the real time clock feature contain a battery to ensure the clock works when the drive is powered down. The battery has a long life time but if the battery needs to be replaced or removed, follow the instructions below.

Low battery voltage is indicated by  low battery symbol on the keypad display.

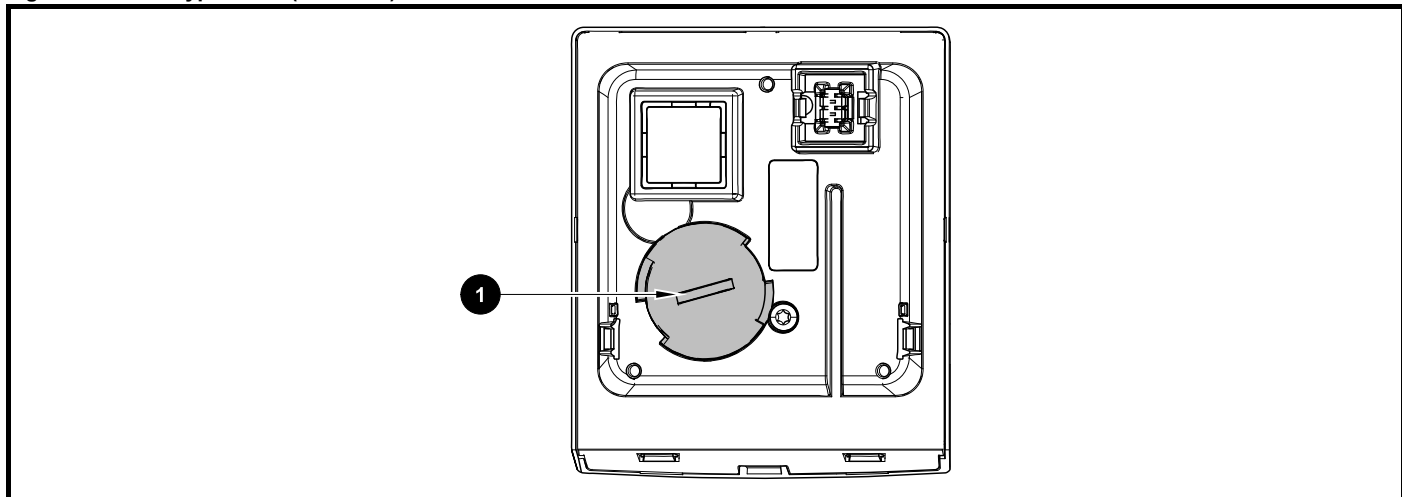
**Figure 3-5 KI-Keypad RTC (rear view)**

Figure 3-5 above illustrates the rear view of the KI-Keypad RTC.

1. To remove the battery cover insert a flat head screwdriver into the slot as shown (1), push and turn anti-clockwise until the battery cover is released.
2. Replace the battery (the battery type is: CR2032).
3. Reverse point 1 above to replace battery cover.

**NOTE**

Ensure the battery is disposed of correctly.

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 4 Electrical installation

### 4.1 24 Vdc supply

The 24 Vdc supply connected to control terminals 1 & 2 provides the following functions:

- It can be used to supplement the drive's own internal 24 V supply when multiple option modules are being used and the current drawn by these module is greater than the drive can supply.
- It can be used as a back-up power supply to keep the control circuits of the drive powered up when the line power supply is removed. This allows any fieldbus modules, application modules, encoders or serial communications to continue to operate.
- It can be used to commission the drive when the line power supply is not available, as the display operates correctly. However, the drive will be in the Under voltage trip state unless either line power supply or low voltage DC operation is enabled, therefore diagnostics may not be possible. (Power down save parameters are not saved when using the 24 V back-up power supply input).
- If the DC bus voltage is too low to run the main SMPS in the drive, then the 24 V supply can be used to supply all the low voltage power requirements of the drive. *Low Under Voltage Threshold Select* (06.067) must also be enabled for this to happen.

#### NOTE

On size 6 and larger, the power 24 Vdc supply (terminals 51, 52) must be connected to enable the 24 V dc supply to be used as a backup supply, when the line power supply is removed. If the power 24 Vdc supply is not connected none of the above mentioned functions can be used, "Waiting For Power Systems" will be displayed on the keypad and no drive operations are possible. The location of the power 24 Vdc can be identified from Figure 4-1 *Location of the 24 Vdc power supply connection on size 6* on page 22.

**Table 4-1 24 Vdc Supply connections**

| Function                               | Sizes 3-5     | Sizes 6-11              |
|----------------------------------------|---------------|-------------------------|
| Supplement the drive's internal supply | Terminal 1, 2 | Terminal 1, 2           |
| Back-up supply for the control circuit | Terminal 1, 2 | Terminal 1, 2<br>51, 52 |

The working voltage range of the control 24 V power supply is as follows:

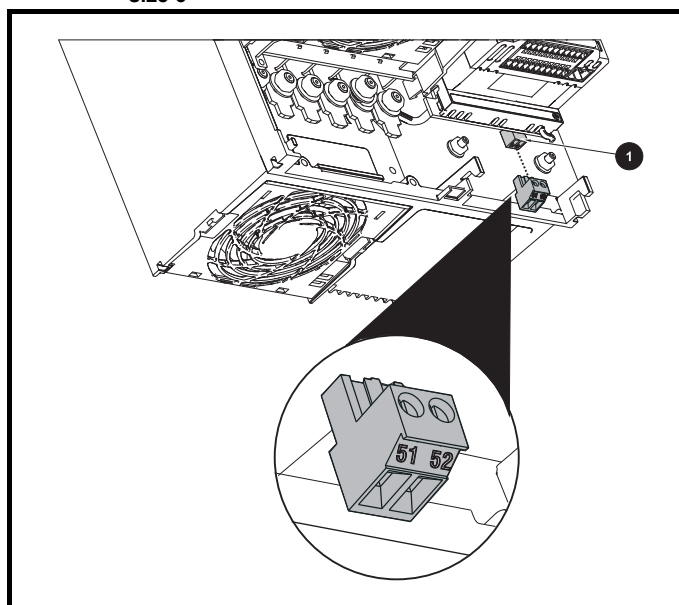
|                                          |                                                        |
|------------------------------------------|--------------------------------------------------------|
| <b>1</b>                                 | <b>0V (Common connection for all external devices)</b> |
| <b>2</b>                                 | <b>+24 Vdc</b>                                         |
| Nominal operating voltage                | 24.0 Vdc                                               |
| Minimum continuous operating voltage     | 19.2 V                                                 |
| Maximum continuous operating voltage     | 28.0 V                                                 |
| Minimum start up voltage                 | 21.6 V                                                 |
| Maximum power supply requirement at 24 V | 40 W                                                   |
| Recommended fuse                         | 3 A, 50 Vdc                                            |

Minimum and maximum voltage values include ripple and noise. Ripple and noise values must not exceed 5 %.

The working range of the 24 V power supply is as follows:

|                                      |                                                        |
|--------------------------------------|--------------------------------------------------------|
| <b>51</b>                            | <b>0V (Common connection for all external devices)</b> |
| <b>52</b>                            | <b>+24 Vdc</b>                                         |
| <b>Size 6</b>                        |                                                        |
| Nominal operating voltage            | 24.0 Vdc                                               |
| Minimum continuous operating voltage | 18.6 Vdc                                               |
| Maximum continuous operating voltage | 28.0 Vdc                                               |
| Minimum startup voltage              | 18.4 Vdc                                               |
| Maximum power supply requirement     | 40 W                                                   |
| Recommended fuse                     | 4 A @ 50 Vdc                                           |
| <b>Size 7 to 11</b>                  |                                                        |
| Nominal operating voltage            | 24.0 Vdc                                               |
| Minimum continuous operating voltage | 19.2 Vdc                                               |
| Maximum continuous operating voltage | 30 Vdc (IEC),<br>26 Vdc (UL)                           |
| Minimum startup voltage              | 21.6 Vdc                                               |
| Maximum power supply requirement     | 60 W                                                   |
| Recommended fuse                     | 4 A @ 50 Vdc                                           |

**Figure 4-1 Location of the 24 Vdc power supply connection on size 6**



1. 24 Vdc power supply connection

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Figure 4-2** Location of the 24 Vdc power supply connection on size 7

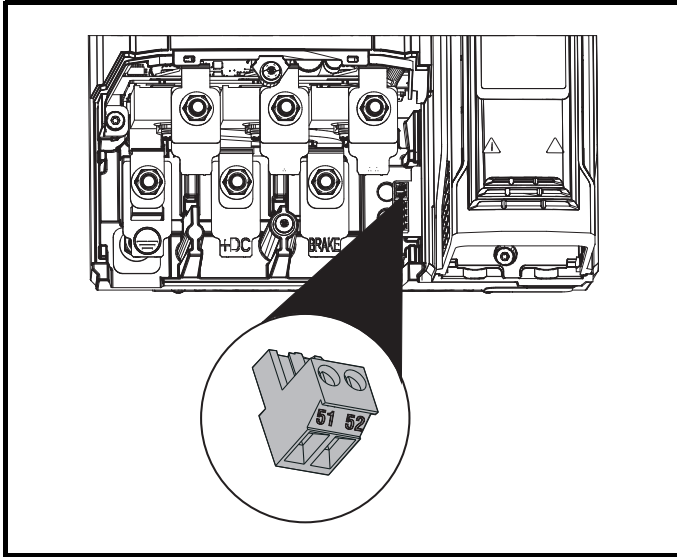
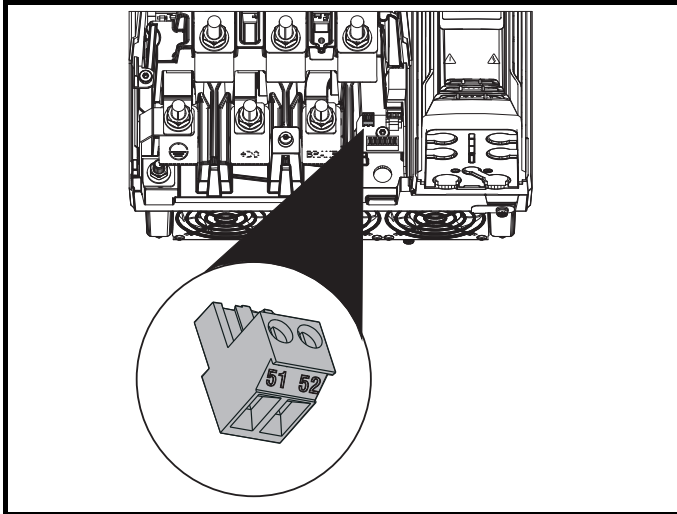


**Figure 4-3** Location of the 24 Vdc power supply connection on size 8 to 11



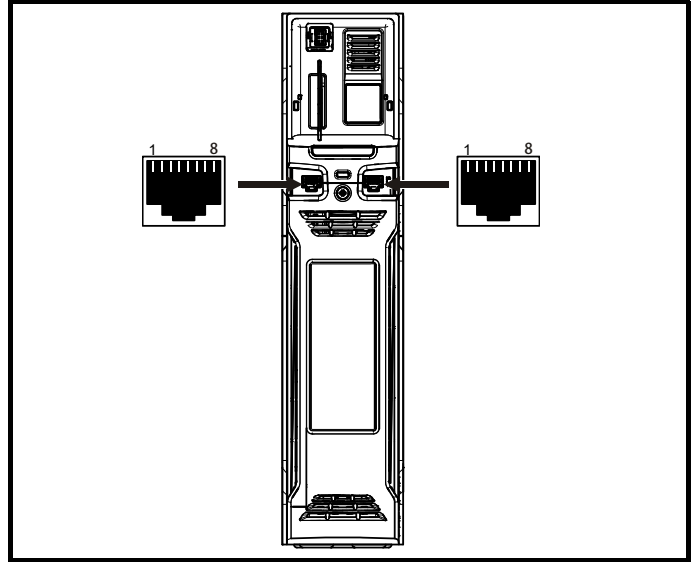
## 4.2 Communication connections

The *Unidrive M700 / M702* drive offers Ethernet fieldbus communications and the *Unidrive M701* drive offers a 2 wire EIA 485 interface. This enables the drive set-up, operation and monitoring to be carried out with a PC or controller if required.

Care must be taken to ensure the correct interface is fitted before a connection is made to the interface, failure to ensure this may result in damage to the interface and/or communication device.

Both the Ethernet and EIA 485 interfaces use an RJ45 connector, the EIA 485 interface is identified by the number "485" printed on the front panel, and the Ethernet interface has the network logo.

**Figure 4-4** Location of the comms connectors



### 4.2.1 Unidrive M700 / M702 Ethernet fieldbus communications

The Ethernet option provides two RJ45 connections with an Ethernet switch for easy network creation.

Standard UTP (unshielded twisted pair) or STP (shielded twisted pair) cables are supported. It is recommended that a minimum specification CAT5e is used in new installations. As the drive supports the 'Auto cross-over detection' a cross-over cable is not required.

#### NOTE

The shell of the RJ45 connector is isolated from the 0V of the drive control terminals but it is connected to ground.

**Table 4-2 Ethernet port pin-outs**

| Pin | Description |
|-----|-------------|
| 1   | Transmit +  |
| 2   | Transmit -  |
| 3   | Receive +   |
| 4   | N/A         |
| 5   | N/A         |
| 6   | Receive -   |
| 7   | N/A         |
| 8   | N/A         |

### 4.2.2 Unidrive M701 EIA 485 serial communications

The EIA 485 interface provides two parallel RJ45 connectors allowing easy daisy chaining. The drive only supports Modbus RTU protocol. See Table 4-3 for the connection details.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**NOTE**

Standard Ethernet cables are not recommended for use when connecting drives on a EIA 485 network as they do not have the correct twisted pairs for the pinout of the serial comms port.



If an Ethernet network adaptor is inadvertently connected to a Unidrive-M701 EIA 485 drive, a low impedance load across the EIA 485 24 V is applied and if connected for a significant period of time can introduce the potential risk of damage.

**Table 4-3 Serial communication port pin-outs**

| Pin   | Function                                                       |
|-------|----------------------------------------------------------------|
| 1     | 120 $\Omega$ Termination resistor                              |
| 2     | RX TX                                                          |
| 3     | Isolated 0V                                                    |
| 4     | +24 V (100 mA) output                                          |
| 5     | Isolated 0V                                                    |
| 6     | TX enable                                                      |
| 7     | RX\ TX\                                                        |
| 8     | RX\ TX\ (if termination resistors are required, link to pin 1) |
| Shell | Isolated 0V                                                    |

Minimum number of connections are 2, 3, 7 and shield.

#### 4.2.3 Unidrive M701 Isolation of the EIA 485 serial communications port

The serial communications port is double insulated and meets the requirements for SELV in EN 50178:1998.



In order to meet the requirements for SELV in IEC60950 (IT equipment) it is necessary for the control computer to be grounded. Alternatively, when a lap-top or similar device is used which has no provision for grounding, an isolation device must be incorporated in the communications lead.

An isolated serial communications lead has been designed to connect the drive to IT equipment (such as laptop computers), and is available from the supplier of the drive. See below for details:

**Table 4-4 Isolated serial comms lead details**

| Part number | Description        |
|-------------|--------------------|
| 4500-0096   | CT USB Comms cable |

The "isolated serial communications" lead has reinforced insulation as defined in IEC60950 for altitudes up to 3,000 m.

#### 4.2.4 Communication networks and cabling

Any isolated signal circuit has the capability to become live through accidental contact with other conductors; as such they should always be double-insulated from live parts. The routing of network and signal wires should be done so as to avoid close proximity to mains voltage cabling.

#### 4.2.5 Unidrive M701 EIA 485 Port polarization (biasing)

The Unidrive M701 EIA 485 serial communications port requires polarization (biasing) of the data lines.

The Modbus standard specifies that to prevent spurious triggering when there is no data being transmitted, the data lines are polarized (biased) with pull-apart resistors, one resistor from the RJ45 pin 2 connection (RX TX) to +V and the other resistor from the RJ45 pin 7 connection (RX / TX) to 0V. These resistors should be in the range 450 to 650 Ohms and fitted in the master controller.

#### 4.2.6 Unidrive M701 EIA 485 Network termination

When a long-distance multi-drop EIA 485 system is used with high baud rates (above 38400) it may be necessary to fit a termination resistor of 120  $\Omega$  across the transmit and receive pair in order to reduce signal reflections.

## 4.3 Control connections

### 4.3.1 Unidrive M700 / M701 control connections

**Table 4-5 The control connections consist of:**

| Function                       | Qty | Control parameters available                                           | Terminal number                              |
|--------------------------------|-----|------------------------------------------------------------------------|----------------------------------------------|
| Differential analog input      | 1   | Mode, offset, invert, scaling                                          | 5, 6                                         |
| Single ended analog input      | 2   | Mode, offset, invert, scaling, destination                             | 7, 8                                         |
| Analog output                  | 2   | Source, scaling                                                        | 9, 10                                        |
| Digital input                  | 3   | Destination, invert                                                    | 27, 28, 29                                   |
| Digital input / output         | 3   | Input / output mode select, destination / source, invert, logic select | 24, 25, 26                                   |
| Relay                          | 1   | Source, invert                                                         | 41, 42                                       |
| Drive enable (Safe Torque Off) | 1   |                                                                        | 31                                           |
| +10 V User output              | 1   |                                                                        | 4                                            |
| +24 V User output              | 1   | Source, invert                                                         | 22                                           |
| 0V common                      | 6   |                                                                        | 1, 3, 11, 21, 23, 30, 51 (size 6 and larger) |
| +24V External input            | 1   | Destination, invert                                                    | 2                                            |

**Key:**

|                        |                                                                                                                                                                                                                                                                       |
|------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Destination parameter: | Indicates the parameter which is being controlled by the terminal / function                                                                                                                                                                                          |
| Source parameter:      | Indicates the parameter being output by the terminal                                                                                                                                                                                                                  |
| Mode parameter:        | Analog - indicates the mode of operation of the terminal, i.e. voltage 0-10 V, current 4-20 mA etc. Digital - indicates the mode of operation of the terminal, i.e. positive / negative logic (the Drive Enable terminal is fixed in positive logic), open collector. |

All analog terminal functions can be programmed in menu 7.

All digital terminal functions (including the relay) can be programmed in menu 8.



The control circuits are isolated from the power circuits in the drive by basic insulation (single insulation) only. The installer must ensure that the external control circuits are insulated from human contact by at least one layer of insulation (supplementary insulation) rated for use at the AC supply voltage.



If the control circuits are to be connected to other circuits classified as Safety Extra Low Voltage (SELV) (e.g. to a personal computer), an additional isolating barrier must be included in order to maintain the SELV classification.



If any of the digital inputs (including the drive enable input) are connected in parallel with an inductive load (i.e. contactor or motor brake) then suitable suppression (i.e. diode or varistor) should be used on the coil of the load. If no suppression is used then over voltage spikes can cause damage to the digital inputs and outputs on the drive.



Ensure the logic sense is correct for the control circuit to be used. Incorrect logic sense could cause the motor to be started unexpectedly. Positive logic is the default state for the drive.

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**NOTE**

Any signal cables which are carried inside the motor cable (i.e. motor thermistor, motor brake) will pick up large pulse currents via the cable capacitance. The shield of these signal cables must be connected to ground close to the point of exit of the motor cable, to avoid this noise current spreading through the control system.

**NOTE**

The Safe Torque Off drive enable terminal is a positive logic input only. It is not affected by the setting of *Input Logic Polarity* (08.029).

**NOTE**

The common 0V from analog signals should, wherever possible, not be connected to the same 0V terminal as the common 0V from digital signals. Terminals 3 and 11 should be used for connecting the 0V common of analog signals and terminals 21, 23 and 30 for digital signals. This is to prevent small voltage drops in the terminal connections causing inaccuracies in the analog signals.

**NOTE**

A two wire motor thermistor can be connected to analog input 3 by connecting the thermistor between terminal 8 and any 0V common terminal. It is possible to connect a 4-wire thermistor to analog input 3 as shown below. Pr **07.015** and Pr **07.046** need to be set-up for the thermistor type required.

**Figure 4-5 Connection for PT100, PT1000 and PT2000 thermistors**

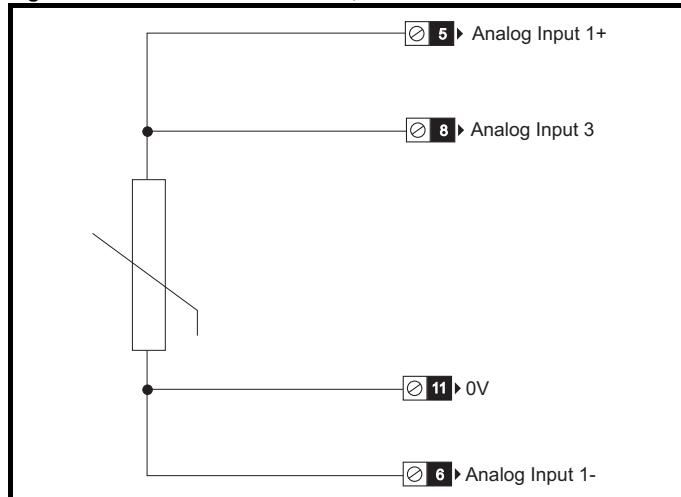
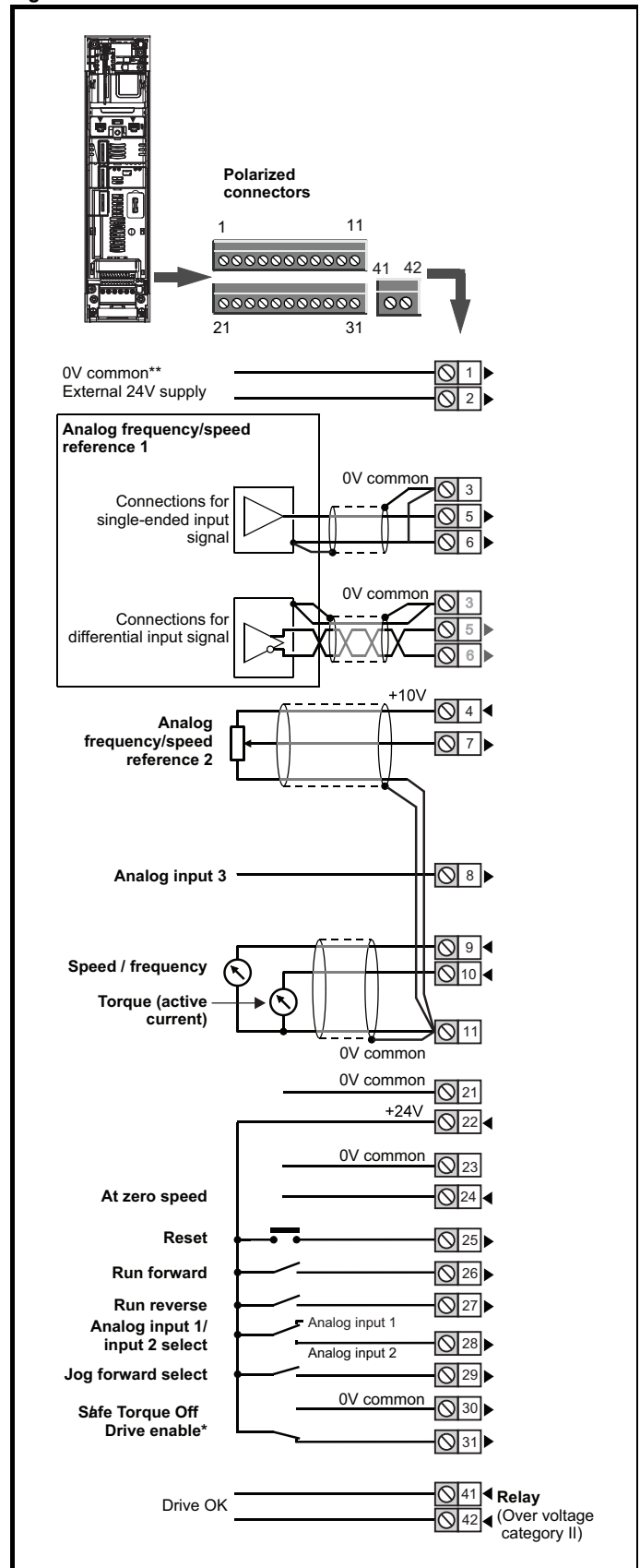


**Figure 4-6 Default terminal functions**



\*The Safe Torque Off / Drive enable terminal is a positive logic input only.

**NOTE**

The 0V terminals on the Safe Torque Off are not isolated from each other and the 0V common.

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 4.3.2 Unidrive M700 / M701 control terminal specification

|                 |                                                   |
|-----------------|---------------------------------------------------|
| <b>1</b>        | <b>0V common</b>                                  |
| <b>Function</b> | <b>Common connection for all external devices</b> |

|                                      |                                                                                    |
|--------------------------------------|------------------------------------------------------------------------------------|
| <b>2</b>                             | <b>+24V external input</b>                                                         |
| <b>Function</b>                      | <b>To supply the control circuit without providing a supply to the power stage</b> |
| Programmability                      | Can be used as digital input when using an external 24 V supply                    |
| Sample / update                      | 2 ms                                                                               |
| Nominal voltage                      | +24.0 Vdc                                                                          |
| Minimum continuous operating voltage | +19.2 Vdc                                                                          |
| Maximum continuous operating voltage | +28.0 Vdc                                                                          |
| Minimum start-up voltage             | 21.6 Vdc                                                                           |
| Recommended power supply             | 40 W 24 Vdc nominal                                                                |
| Recommended fuse                     | 3 A, 50 Vdc                                                                        |

|                 |                                                   |
|-----------------|---------------------------------------------------|
| <b>3</b>        | <b>0V common</b>                                  |
| <b>Function</b> | <b>Common connection for all external devices</b> |

|                        |                                           |
|------------------------|-------------------------------------------|
| <b>4</b>               | <b>+10V user output</b>                   |
| <b>Function</b>        | <b>Supply for external analog devices</b> |
| Voltage                | 10.2 V nominal                            |
| Voltage tolerance      | ±1 %                                      |
| Nominal output current | 10 mA                                     |
| Protection             | Current limit and trip @ 30 mA            |

|                                                                                                                                 |                                                                                                                                                                                                           |
|---------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                                                                                                                                 | <b>Precision reference Analog input 1</b>                                                                                                                                                                 |
| <b>5</b>                                                                                                                        | <b>Non-inverting input</b>                                                                                                                                                                                |
| <b>6</b>                                                                                                                        | <b>Inverting input</b>                                                                                                                                                                                    |
| <b>Default function</b>                                                                                                         | <b>Frequency/speed reference</b>                                                                                                                                                                          |
| Type of input                                                                                                                   | Bipolar differential analog voltage or current, thermistor input                                                                                                                                          |
| Mode controlled by:                                                                                                             | Pr <b>07.007</b>                                                                                                                                                                                          |
| <b>Operating in Voltage mode</b>                                                                                                |                                                                                                                                                                                                           |
| Full scale voltage range                                                                                                        | ±10 V ±2 %                                                                                                                                                                                                |
| Maximum offset                                                                                                                  | ±10 mV                                                                                                                                                                                                    |
| Absolute maximum voltage range                                                                                                  | ±36 V relative to 0V                                                                                                                                                                                      |
| Working common mode voltage range                                                                                               | ±13 V relative to 0V                                                                                                                                                                                      |
| Input resistance                                                                                                                | ≥100 kΩ                                                                                                                                                                                                   |
| Monotonic                                                                                                                       | Yes (including 0V)                                                                                                                                                                                        |
| Dead band                                                                                                                       | None (including 0V)                                                                                                                                                                                       |
| Jumps                                                                                                                           | None (including 0V)                                                                                                                                                                                       |
| Maximum offset                                                                                                                  | 20 mV                                                                                                                                                                                                     |
| Maximum non linearity                                                                                                           | 0.3% of input                                                                                                                                                                                             |
| Maximum gain asymmetry                                                                                                          | 0.5 %                                                                                                                                                                                                     |
| Input filter bandwidth single pole                                                                                              | ~3 kHz                                                                                                                                                                                                    |
| <b>Operating in current mode</b>                                                                                                |                                                                                                                                                                                                           |
| Current ranges                                                                                                                  | 0 to 20 mA ±5 %, 20 to 0 mA ±5 %, 4 to 20 mA ±5 %, 20 to 4 mA ±5 %                                                                                                                                        |
| Maximum offset                                                                                                                  | 250 μA                                                                                                                                                                                                    |
| Absolute maximum voltage (reverse biased)                                                                                       | ±36 V relative to 0V                                                                                                                                                                                      |
| Equivalent input resistance                                                                                                     | ≤300 Ω                                                                                                                                                                                                    |
| Absolute maximum current                                                                                                        | ±30 mA                                                                                                                                                                                                    |
| Operating in thermistor input mode (in conjunction with analog input 3), refer to Pr 07.046 and Figure 4-5 for further details. |                                                                                                                                                                                                           |
| Trip threshold resistance                                                                                                       | User defined in Pr <b>07.048</b>                                                                                                                                                                          |
| Short-circuit detection resistance                                                                                              | 50 Ω ±40 %                                                                                                                                                                                                |
| <b>Common to all modes</b>                                                                                                      |                                                                                                                                                                                                           |
| Resolution                                                                                                                      | 12 bits (11 bits plus sign)                                                                                                                                                                               |
| Sample / update period                                                                                                          | 250 μs with destinations Pr <b>01.036</b> , Pr <b>01.037</b> , Pr <b>03.022</b> or Pr <b>04.008</b> in RFC-A and RFC-S modes. 4 ms for open loop mode and all other destinations in RFC-A or RFC-S modes. |

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| 7                                       | Analog input 2                                                                                                                                                                                   |
|-----------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Default function                        | Frequency / speed reference                                                                                                                                                                      |
| Type of input                           | Bipolar single-ended analog voltage or unipolar current                                                                                                                                          |
| Mode controlled by...                   | Pr <b>07.011</b>                                                                                                                                                                                 |
| Operating in voltage mode               |                                                                                                                                                                                                  |
| Full scale voltage range                | ±10 V ±2 %                                                                                                                                                                                       |
| Maximum offset                          | ±10 mV                                                                                                                                                                                           |
| Absolute maximum voltage range          | ±36 V relative to 0V                                                                                                                                                                             |
| Input resistance                        | ≥100 k Ω                                                                                                                                                                                         |
| Operating in current mode               |                                                                                                                                                                                                  |
| Current ranges                          | 0 to 20 mA ±5 %, 20 to 0 mA ±5 %, 4 to 20 mA ±5 %, 20 to 4 mA ±5 %                                                                                                                               |
| Maximum offset                          | 250 μA                                                                                                                                                                                           |
| Absolute maximum voltage (reverse bias) | ±36 V relative to 0V                                                                                                                                                                             |
| Absolute maximum current                | ±30 mA                                                                                                                                                                                           |
| Equivalent input resistance             | ≤ 300 Ω                                                                                                                                                                                          |
| Common to all modes                     |                                                                                                                                                                                                  |
| Resolution                              | 12 bits (11 bits plus sign)                                                                                                                                                                      |
| Sample / update                         | 250 μs with destinations Pr <b>01.036</b> , Pr <b>01.037</b> or Pr <b>03.022</b> , Pr <b>04.008</b> in RFC-A or RFC-S. 4ms for open loop mode and all other destinations in RFC-A or RFC-S mode. |

| 8                                   | Analog input 3                                           |
|-------------------------------------|----------------------------------------------------------|
| Default function                    | Voltage input                                            |
| Type of input                       | Bipolar single-ended analog voltage, or thermistor input |
| Mode controlled by...               | Pr <b>07.015</b>                                         |
| Operating in Voltage mode (default) |                                                          |
| Voltage range                       | ±10 V ±2 %                                               |
| Maximum offset                      | ±10 mV                                                   |
| Absolute maximum voltage range      | ±36 V relative to 0V                                     |
| Input resistance                    | ≥100 k Ω                                                 |
| Operating in thermistor input mode  |                                                          |
| Supported thermistor types          | Din 44082, KTY 84, PT100, PT 1000, PT 2000, 2.0 mA       |
| Trip threshold resistance           | User defined in Pr <b>07.048</b>                         |
| Reset resistance                    | User defined in Pr <b>07.049</b>                         |
| Short-circuit detection resistance  | 50 Ω ±40 %                                               |
| Common to all modes                 |                                                          |
| Resolution                          | 12 bits (11 bits plus sign)                              |
| Sample / update period              | 4 ms                                                     |

| 9                            | Analog output 1                                                                       |
|------------------------------|---------------------------------------------------------------------------------------|
| 10                           | Analog output 2                                                                       |
| Terminal 9 default function  | OL> Motor FREQUENCY output signal<br>RFC> SPEED output signal                         |
| Terminal 10 default function | Motor active current                                                                  |
| Type of output               | Bipolar single-ended analog voltage                                                   |
| Operating in Voltage mode    |                                                                                       |
| Voltage range                | ±10 V ±5 %                                                                            |
| Maximum offset               | ±120 mV                                                                               |
| Maximum output current       | ±20 mA                                                                                |
| Load resistance              | ≥1 k Ω                                                                                |
| Protection                   | 20 mA max. Short circuit protection                                                   |
| Resolution                   | 10-bit                                                                                |
| Sample / update period       | 250 μs (output will only change at update the rate of the source parameter if slower) |

| 11       | 0V common                                  |
|----------|--------------------------------------------|
| Function | Common connection for all external devices |

| 21       | 0V common                                  |
|----------|--------------------------------------------|
| Function | Common connection for all external devices |

| 22                           | +24 V user output (selectable)                                                                                                                              |
|------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Terminal 22 default function | +24 V user output                                                                                                                                           |
| Programmability              | Can be switched on or off to act as a fourth digital output (positive logic only) by setting the source Pr <b>08.028</b> and source invert Pr <b>08.018</b> |
| Nominal output current       | 100 mA combined with DIO3                                                                                                                                   |
| Maximum output current       | 100 mA<br>200 mA (total including all Digital I/O)                                                                                                          |
| Protection                   | Current limit and trip                                                                                                                                      |
| Sample / update period       | 2 ms when configured as an output (output will only change at the update rate of the source parameter if slower)                                            |

| 23       | 0V common                                  |
|----------|--------------------------------------------|
| Function | Common connection for all external devices |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

|                                        |                                                                                  |
|----------------------------------------|----------------------------------------------------------------------------------|
| <b>24</b>                              | <b>Digital I/O 1</b>                                                             |
| <b>25</b>                              | <b>Digital I/O 2</b>                                                             |
| <b>26</b>                              | <b>Digital I/O 3</b>                                                             |
| <b>Terminal 24 default function</b>    | <b>AT ZERO SPEED output</b>                                                      |
| <b>Terminal 25 default function</b>    | <b>DRIVE RESET input</b>                                                         |
| <b>Terminal 26 default function</b>    | <b>RUN FORWARD input</b>                                                         |
| Type                                   | Positive or negative logic digital inputs, positive logic voltage source outputs |
| Input / output mode controlled by...   | Pr 08.031, Pr 08.032 and Pr 08.033                                               |
| <b>Operating as an input</b>           |                                                                                  |
| Logic mode controlled by...            | Pr 08.029                                                                        |
| Absolute maximum applied voltage range | -3 V to +30 V                                                                    |
| Impedance                              | >2 mA @15 V (IEC 61131-2, type 1, 6.6 k Ω)                                       |
| Input thresholds                       | 10 V ±0.8 V (IEC 61131-2, type 1)                                                |
| <b>Operating as an output</b>          |                                                                                  |
| Nominal maximum output current         | 100 mA (DIO1 & 2 combined)<br>100 mA (DIO3 & 24 V User Output Combined)          |
| Maximum output current                 | 100 mA<br>200 mA (total including all Digital I/O)                               |
| <b>Common to all modes</b>             |                                                                                  |
| Voltage range                          | 0V to +24 V                                                                      |
| Sample / Update period                 | 2 ms (output will only change at the update rate of the source parameter)        |

|                                        |                                                                                                                                                                      |
|----------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>27</b>                              | <b>Digital Input 4</b>                                                                                                                                               |
| <b>28</b>                              | <b>Digital Input 5</b>                                                                                                                                               |
| <b>Terminal 27 default function</b>    | <b>RUN REVERSE input</b>                                                                                                                                             |
| <b>Terminal 28 default function</b>    | <b>Analog INPUT 1 / INPUT 2 select</b>                                                                                                                               |
| Type                                   | Negative or positive logic digital inputs                                                                                                                            |
| Logic mode controlled by...            | Pr 08.029                                                                                                                                                            |
| Voltage range                          | 0V to +24 V                                                                                                                                                          |
| Absolute maximum applied voltage range | -3 V to +30 V                                                                                                                                                        |
| Impedance                              | >2 mA @15 V (IEC 61131-2, type 1, 6.6 k Ω)                                                                                                                           |
| Input thresholds                       | 10 V ±0.8 V (IEC 61131-2, type 1)                                                                                                                                    |
| Sample / Update period                 | 250 μs when configured as an input with destinations Pr 06.035 or Pr 06.036. 600 μs when configured as an input with destination Pr 06.029. 2 ms in all other cases. |

|                                        |                                            |
|----------------------------------------|--------------------------------------------|
| <b>29</b>                              | <b>Digital Input 6</b>                     |
| <b>Terminal 29 default function</b>    | <b>JOG SELECT input</b>                    |
| Type                                   | Negative or positive logic digital inputs  |
| Logic mode controlled by...            | Pr 08.029                                  |
| Voltage range                          | 0V to +24 V                                |
| Absolute maximum applied voltage range | -3 V to +30 V                              |
| Impedance                              | >2 mA @15 V (IEC 61131-2, type 1, 6.6 k Ω) |
| Input thresholds                       | 10 V ±0.8 V (IEC 61131-2, type 1)          |
| Sample / Update period                 | 2 ms                                       |

|                 |                                                   |
|-----------------|---------------------------------------------------|
| <b>30</b>       | <b>0V common</b>                                  |
| <b>Function</b> | <b>Common connection for all external devices</b> |

Refer to section 4.5 *Safe Torque Off (STO)* on page 37 for further information.

|                                                                                                                                                                                                                                                                                                                                                                                                                       |                                                |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------|
| <b>31</b>                                                                                                                                                                                                                                                                                                                                                                                                             | <b>Safe Torque Off function (drive enable)</b> |
| Type                                                                                                                                                                                                                                                                                                                                                                                                                  | Positive logic only digital input              |
| Voltage range                                                                                                                                                                                                                                                                                                                                                                                                         | 0V to +24 V                                    |
| Absolute maximum applied voltage                                                                                                                                                                                                                                                                                                                                                                                      | 30 V                                           |
| Logic Threshold                                                                                                                                                                                                                                                                                                                                                                                                       | 10 V ±5 V                                      |
| Low state maximum voltage for disable to SIL3 and PL e                                                                                                                                                                                                                                                                                                                                                                | 5 V                                            |
| Impedance                                                                                                                                                                                                                                                                                                                                                                                                             | >4 mA @15 V (IEC 61131-2, type 1, 3.3 k Ω)     |
| Low state maximum current for disable to SIL3 and PL e                                                                                                                                                                                                                                                                                                                                                                | 0.5 mA                                         |
| Response time                                                                                                                                                                                                                                                                                                                                                                                                         | Nominal: 8 ms<br>Maximum: 20 ms                |
| The Safe Torque Off function may be used in a safety-related application in preventing the drive from generating torque in the motor to a high level of integrity. The system designer is responsible for ensuring that the complete system is safe and designed correctly according to the relevant safety standards. If the Safe Torque Off function is not required, this terminal is used for enabling the drive. |                                                |

|                                    |                                                                                          |
|------------------------------------|------------------------------------------------------------------------------------------|
| <b>41</b>                          | <b>Relay contacts</b>                                                                    |
| <b>42</b>                          | <b>Relay contacts</b>                                                                    |
| <b>Default function</b>            | <b>Drive OK indicator</b>                                                                |
| Contact voltage rating             | 240 Vac, Installation over-voltage category II                                           |
| Contact maximum current rating     | 2 A AC 240 V<br>4 A DC 30 V resistive load<br>0.5 A DC 30 V inductive load (L/R = 40 ms) |
| Contact minimum recommended rating | 12 V 100 mA                                                                              |
| Contact type                       | Normally open                                                                            |
| Default contact condition          | Closed when power applied and drive OK                                                   |
| Update period                      | 4 ms                                                                                     |

|                                      |                                                        |
|--------------------------------------|--------------------------------------------------------|
| <b>51</b>                            | <b>0V (Common connection for all external devices)</b> |
| <b>52</b>                            | <b>+24 Vdc</b>                                         |
| <b>Size 6</b>                        |                                                        |
| Nominal operating voltage            | 24.0 Vdc                                               |
| Minimum continuous operating voltage | 18.6 Vdc                                               |
| Maximum continuous operating voltage | 28.0 Vdc                                               |
| Minimum startup voltage              | 18.4 Vdc                                               |
| Maximum power supply requirement     | 40 W                                                   |
| Recommended fuse                     | 4 A @ 50 Vdc                                           |
| <b>Size 7 to 11</b>                  |                                                        |
| Nominal operating voltage            | 24.0 Vdc                                               |
| Minimum continuous operating voltage | 19.2 Vdc                                               |
| Maximum continuous operating voltage | 30 Vdc (IEC),<br>26 Vdc (UL)                           |
| Minimum startup voltage              | 21.6 Vdc                                               |
| Maximum power supply requirement     | 60 W                                                   |
| Recommended fuse                     | 4 A @ 50 Vdc                                           |



To prevent the risk of a fire hazard in the event of a fault, a fuse or other over-current protection must be installed in the relay circuit.

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 4.3.3 Unidrive M702 control connections

**Table 4-6** The control connections consist of:

| Function                       | Qty | Control parameters available      | Terminal number |
|--------------------------------|-----|-----------------------------------|-----------------|
| Single ended analog input*     | 1   | Mode, destination                 | 8               |
| Digital input*                 | 2   | Destination, invert, logic select | 7, 8            |
| Digital output                 | 2   | source, invert                    | 4, 5            |
| Relay                          | 1   | Source, invert                    | 41, 42          |
| Drive enable (Safe Torque Off) | 2   |                                   | 11, 13          |
| +24 V User output              | 1   | Source, invert                    | 2               |
| 0V common                      | 5   |                                   | 1, 3, 6, 10, 12 |
| +24 V External input           | 1   | Destination, invert               | 9               |

\* From date code 1710, control terminal 8 on the Unidrive M702 can be a dual-purpose input which can be configured as either a motor thermistor input (Analog Input 3) or a digital input (Digital Input 5).

**Key:**

|                        |                                                                                                                       |
|------------------------|-----------------------------------------------------------------------------------------------------------------------|
| Destination parameter: | Indicates the parameter which is being controlled by the terminal / function                                          |
| Source parameter:      | Indicates the parameter being output by the terminal                                                                  |
| Mode parameter:        | Analog - indicates the mode of operation of the thermistor protection (disabled, temperature, temperature and short). |

All digital terminal functions (including the relay) can be programmed in menu 8.



**WARNING**

The control circuits are isolated from the power circuits in the drive by basic insulation (single insulation) only. The installer must ensure that the external control circuits are insulated from human contact by at least one layer of insulation (supplementary insulation) rated for use at the AC supply voltage.



**WARNING**

If the control circuits are to be connected to other circuits classified as Safety Extra Low Voltage (SELV) (e.g. to a personal computer), an additional isolating barrier must be included in order to maintain the SELV classification.



**CAUTION**

If any of the digital inputs (including the drive enable input) are connected in parallel with an inductive load (i.e. contactor or motor brake) then suitable suppression (i.e. diode or varistor) should be used on the coil of the load. If no suppression is used then over voltage spikes can cause damage to the digital inputs and outputs on the drive.



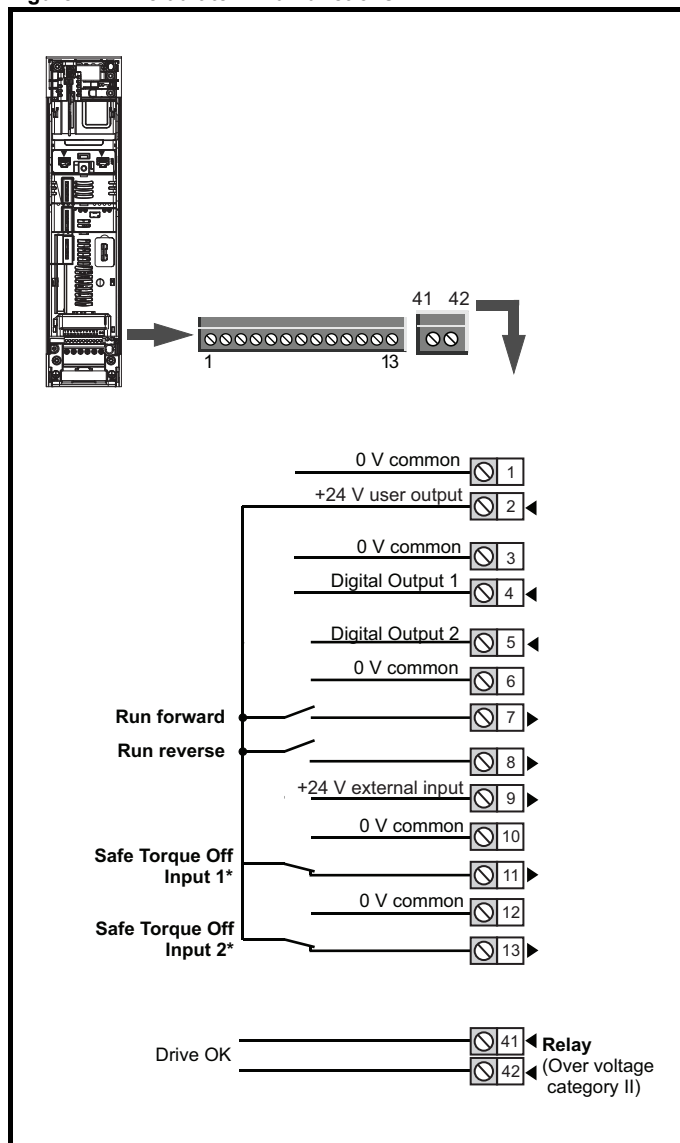
**CAUTION**

Ensure the logic sense is correct for the control circuit to be used. Incorrect logic sense could cause the motor to be started unexpectedly. Positive logic is the default state for the drive.

**NOTE**

Any signal cables which are carried inside the motor cable (i.e. motor thermistor, motor brake) will pick up large pulse currents via the cable capacitance. The shield of these signal cables must be connected to ground close to the point of exit of the motor cable, to avoid this noise current spreading through the control system.

**Figure 4-7** Default terminal functions



\*The Safe Torque Off / Drive enable terminal is a positive logic input only.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 4.3.4 Unidrive M702 control terminal specification

| 1        | 0V common                                  |
|----------|--------------------------------------------|
| Function | Common connection for all external devices |

| 2                           | +24 V user output (selectable)                                                                                                                |
|-----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------|
| Terminal 2 default function | +24 V user output                                                                                                                             |
| Programmability             | Can be switched on or off to act as a fourth digital output (positive logic only) by setting the source Pr 08.028 and source invert Pr 08.018 |
| Nominal output current      | 100 mA                                                                                                                                        |
| Maximum output current      | 100 mA<br>200 mA (total including all Digital I/O)                                                                                            |
| Protection                  | Current limit and trip                                                                                                                        |
| Sample / update period      | 2 ms when configured as an output (output will only change at the update rate of the source parameter if slower)                              |

| 3        | 0V common                                  |
|----------|--------------------------------------------|
| Function | Common connection for all external devices |

| 4                              | Digital Output 1                                                          |
|--------------------------------|---------------------------------------------------------------------------|
| 5                              | Digital Output 2                                                          |
| Terminal 4 default function    | AT ZERO SPEED output                                                      |
| Terminal 5 default function    |                                                                           |
| Type                           | Positive logic voltage source outputs                                     |
| Operating as an output         |                                                                           |
| Nominal maximum output current | 100 mA (DO1 & 2 combined)                                                 |
| Maximum output current         | 100 mA<br>200 mA (total including all Digital I/O)                        |
| Common to all modes            |                                                                           |
| Voltage range                  | 0V to +24 V                                                               |
| Sample / Update period         | 2 ms (output will only change at the update rate of the source parameter) |

| 6        | 0V common                                  |
|----------|--------------------------------------------|
| Function | Common connection for all external devices |

| 7                                      | Digital Input 4                                                                                                                                                                |
|----------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 8                                      | Digital Input 5                                                                                                                                                                |
| Terminal 7 default function            | RUN FORWARD input                                                                                                                                                              |
| Terminal 8 default function            | RUN REVERSE input                                                                                                                                                              |
| Type                                   | Positive logic only digital inputs                                                                                                                                             |
| Logic mode controlled by...            | Pr 08.029                                                                                                                                                                      |
| Voltage range                          | 0V to +24 V                                                                                                                                                                    |
| Absolute maximum applied voltage range | -3 V to +30 V                                                                                                                                                                  |
| Impedance                              | >2 mA @15 V (IEC 61131-2, type 1, 6.6 k $\Omega$ )                                                                                                                             |
| Input thresholds                       | 10 V $\pm$ 0.8 V (IEC 61131-2, type 1)                                                                                                                                         |
| Sample / Update period                 | 250 $\mu$ s when configured as an input with destinations Pr 06.035 or Pr 06.036. 600 $\mu$ s when configured as an input with destination Pr 06.029. 2 ms in all other cases. |

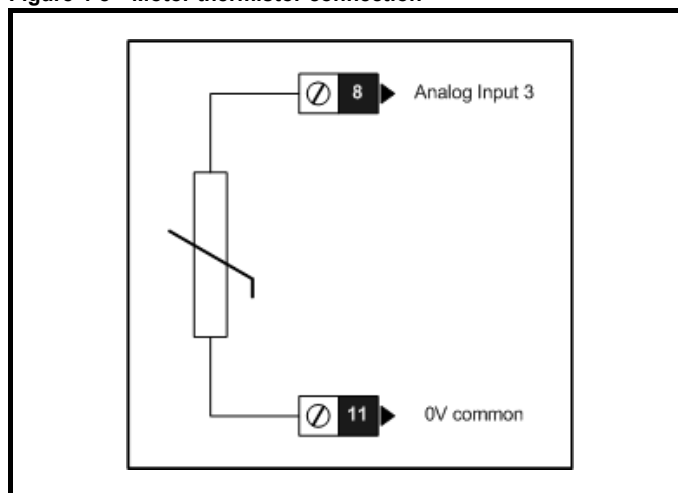
From date code 1710, control terminal 8 on the Unidrive M702 can be a dual purpose input which can be configured as either a motor thermistor input (Analog Input 3) or a digital input (Digital Input 5).

Terminal 8, by default, is set as a digital input (RUN REVERSE) but can be configured to be a motor protection thermistor input by changing *Analog Input 3 Mode* (07.015) from *Disable* (10) to either *Therm Short Cct* (7) or *Thermistor* (8).

| 8                                  | Analog Input 3                                        |
|------------------------------------|-------------------------------------------------------|
| Function                           | Thermistor input                                      |
| Supported thermistor types         | DIN44082, KTY84, PT100 (2W), PT1000 (2W), PT2000 (2W) |
| Trip threshold resistance          | User defined in Pr 07.048                             |
| Reset resistance                   | User defined in Pr 07.049                             |
| Short-circuit detection resistance | 50 $\Omega$ $\pm$ 40 %                                |
| Resolution                         | 12 bits (11 bits plus sign)                           |
| Sample / update period             | 4 ms                                                  |

The thermistor is connected between terminal 8 and any 0V common terminal.

Figure 4-8 Motor thermistor connection



| 9                                    | +24 V external input                                                        |
|--------------------------------------|-----------------------------------------------------------------------------|
| Function                             | To supply the control circuit without providing a supply to the power stage |
| Programmability                      | Can be used as a digital input when using an external 24 Vdc                |
| Sample / Update period               | 2 ms                                                                        |
| Nominal voltage                      | +24.0 Vdc                                                                   |
| Minimum continuous operating voltage | +19.2 Vdc                                                                   |
| Maximum continuous operating voltage | +28.0 Vdc                                                                   |
| Minimum start-up voltage             | 21.6 Vdc                                                                    |
| Recommended power supply             | 40 W 24 Vdc nominal                                                         |
| Recommended fuse                     | 3 A, 50 Vdc                                                                 |

| 10       | 0V common                                  |
|----------|--------------------------------------------|
| Function | Common connection for all external devices |

| 12       | 0V common                                  |
|----------|--------------------------------------------|
| Function | Common connection for all external devices |

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

#### 11 Safe Torque Off function input 1 (drive enable)

#### 13 Safe Torque Off function input 2 (drive enable)

|                                                        |                                                   |
|--------------------------------------------------------|---------------------------------------------------|
| Type                                                   | Positive logic only digital input                 |
| Voltage range                                          | 0V to +24 V                                       |
| Absolute maximum applied voltage                       | 30 V                                              |
| Logic Threshold                                        | 10 V $\pm$ 5 V                                    |
| Low state maximum voltage for disable to SIL3 and PL e | 5 V                                               |
| Impedance                                              | >4 mA @15 V (IEC 61131-2, type 1,3.3 k $\Omega$ ) |
| Low state maximum current for disable to SIL3 and PL e | 0.5 mA                                            |
| Response time                                          | Nominal: 8 ms<br>Maximum: 20 ms                   |

The Safe Torque Off function may be used in a safety-related application in preventing the drive from generating torque in the motor to a high level of integrity. The system designer is responsible for ensuring that the complete system is safe and designed correctly according to the relevant safety standards. If the Safe Torque Off function is not required, these terminals are used for enabling the drive.

Refer to section 4.5 *Safe Torque Off (STO)* on page 37 for further information.

#### 41 Relay contacts

| Default function                   | Drive OK indicator                                                                       |
|------------------------------------|------------------------------------------------------------------------------------------|
| Contact voltage rating             | 240 Vac, Installation over-voltage category II                                           |
| Contact maximum current rating     | 2 A AC 240 V<br>4 A DC 30 V resistive load<br>0.5 A DC 30 V inductive load (L/R = 40 ms) |
| Contact minimum recommended rating | 12 V 100 mA                                                                              |
| Contact type                       | Normally open                                                                            |
| Default contact condition          | Closed when power applied and drive OK                                                   |
| Update period                      | 4 ms                                                                                     |

#### 51 0V (Common connection for all external devices)

#### 52 +24 Vdc

| Size 6                               |                              |
|--------------------------------------|------------------------------|
| Nominal operating voltage            | 24.0 Vdc                     |
| Minimum continuous operating voltage | 18.6 Vdc                     |
| Maximum continuous operating voltage | 28.0 Vdc                     |
| Minimum startup voltage              | 18.4 Vdc                     |
| Maximum power supply requirement     | 40 W                         |
| Recommended fuse                     | 4 A @ 50 Vdc                 |
| Size 7 to 11                         |                              |
| Nominal operating voltage            | 24.0 Vdc                     |
| Minimum continuous operating voltage | 19.2 Vdc                     |
| Maximum continuous operating voltage | 30 Vdc (IEC),<br>26 Vdc (UL) |
| Minimum startup voltage              | 21.6 Vdc                     |
| Maximum power supply requirement     | 60 W                         |
| Recommended fuse                     | 4 A @ 50 Vdc                 |



To prevent the risk of a fire hazard in the event of a fault, a fuse or other over-current protection must be installed in the relay circuit.

**WARNING**

## 4.4 Position feedback connections

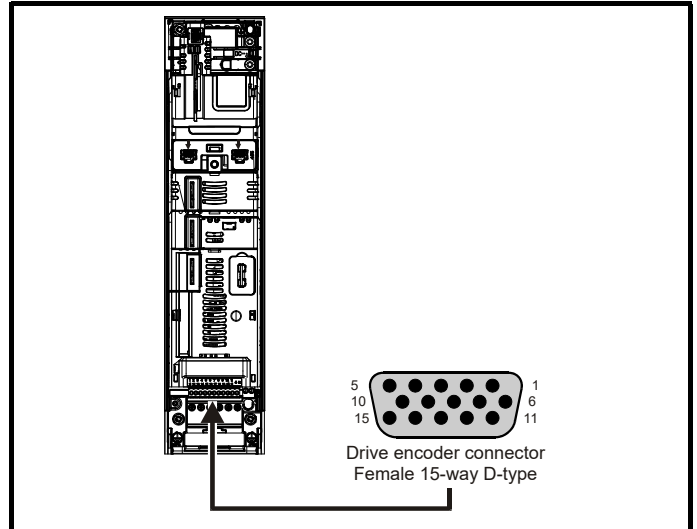
The following functions are provided via the 15-way high density D-type connector on the drive:

- Two position feedback interfaces (P1 and P2).
- One encoder simulation output.
- Two freeze trigger inputs (marker inputs).
- One thermistor input.

The P1 position interface is always available but the availability of the P2 position interface and the encoder simulation output depends on the position feedback device used on the P1 position interface, as shown in Table 4-9.

### 4.4.1 Location of position feedback connector

Figure 4-9 Location of the position feedback



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

#### 4.4.2 Compatible position feedback devices

**Table 4-7 Supported feedback devices on the P1 position interface**

| Encoder type                                                                                                                                             | Pr 3.038 setting      |
|----------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------|
| Quadrature incremental encoders with or without marker pulse                                                                                             | AB (0)                |
| Quadrature incremental encoders with UVW commutation signals for absolute position for permanent magnet motors with or without marker pulse              | AB Servo (3)          |
| Forward / reverse incremental encoders with or without marker pulse                                                                                      | FR (2)                |
| Forward / reverse incremental encoders with UVW commutation signals for absolute position for permanent magnet motors with or without marker pulse       | FR Servo (5)          |
| Frequency and direction incremental encoders with or without marker pulse                                                                                | FD (1)                |
| Frequency and direction incremental encoders with UVW commutation signals for absolute position for permanent magnet motors with or without marker pulse | FD Servo (4)          |
| Sincos incremental encoders                                                                                                                              | SC (6)                |
| Sincos incremental with commutation signals                                                                                                              | SC Servo (12)         |
| Heidenhain sincos encoders with EnDat comms for absolute position                                                                                        | SC EnDat (9)          |
| Stegmann sincos encoders with Hiperface comms for absolute position                                                                                      | SC Hiperface (7)      |
| Sincos encoders with SSI comms for absolute position                                                                                                     | SC SSI (11)           |
| Sincos encoders with BiSS (type C) comms for absolute position                                                                                           | SC BiSS (17)          |
| Sincos incremental with absolute position from single sin and cosine signals                                                                             | SC SC (15)            |
| SSI encoders (Gray code or binary)                                                                                                                       | SSI (10)              |
| EnDat communication only encoders                                                                                                                        | EnDat (8)             |
| BiSS (type C) communication only encoders                                                                                                                | BiSS (13)             |
| Resolver                                                                                                                                                 | Resolver (14)         |
| UVW commutation only encoders*                                                                                                                           | Commutation only (16) |

\* This feedback device provides very low resolution feedback and should not be used for applications requiring a high level of performance

**Table 4-8 Supported feedback devices on the P2 position interface**

| Encoder type                                                              | Pr 3.138 setting |
|---------------------------------------------------------------------------|------------------|
| Quadrature incremental encoders with or without marker pulse              | AB (1)           |
| Frequency and direction incremental encoders with or without marker pulse | FD (2)           |
| Forward / reverse incremental encoders with or without marker pulse       | FR (3)           |
| EnDat communication only encoders                                         | EnDat (4)        |
| SSI encoders (Gray code or binary)                                        | SSI (5)          |
| BiSS communication only encoders                                          | BiSS (6)         |

Table 4-9 shows the possible combinations of position feedback device types connected to the P1 and P2 position interfaces and the availability of the encoder simulation output.

**Table 4-9 Availability of the P2 position feedback interface and the encoder simulation output**

| Functions                                                                 |                                                    |                           |
|---------------------------------------------------------------------------|----------------------------------------------------|---------------------------|
| P1 Position feedback interface                                            | P2 Position feedback interface                     | Encoder Simulation Output |
| AB Servo<br>FD Servo<br>FR Servo<br>SC Servo<br>SC SC<br>Commutation only | None                                               | None                      |
| AB<br>FD<br>FR<br>SC<br>Resolver<br>SC Hiperface                          | AB, FD, FR<br>EnDat, BiSS, SSI                     | None                      |
|                                                                           | None                                               | Full                      |
| SC EnDat<br>SC SSI                                                        | AB, FD, FR<br>(No Z marker pulse input)            | None                      |
|                                                                           | EnDat, BiSS, SSI (with freeze input)               |                           |
|                                                                           | None                                               | No Z marker pulse output  |
| EnDat<br>BiSS<br>SSI                                                      | AB, FD, FR<br>EnDat, BiSS, SSI (with freeze input) | None                      |
|                                                                           | None                                               | Full                      |
|                                                                           | EnDat, BiSS, SSI                                   | No Z marker pulse output  |

The priority of the position feedback interfaces and the encoder simulation output on the 15-way D-type is assigned in the following order from the highest priority to the lowest.

- P1 position interface (highest)
- Encoder simulation output
- P2 position interface (lowest)

For example, if an AB Servo type position feedback device is selected for use on the P1 position interface, then both the encoder simulation output and the P2 position interface will not be available as this device uses all connections of the 15-way D-type connector. Also, if an AB type position feedback device is selected for use on the P1 position interface and Pr **03.085** is set to a valid source for the encoder simulation output, then the P2 position interface will not be available.

Depending on the device type used on the P1 position interface, the encoder simulation output may not be able support a marker pulse output (e.g. SC EnDat or SC SSI device types). Pr **03.086** shows the status of the encoder simulation output indicating whether the output is disabled, no marker pulse is available or full encoder simulation is available.

#### NOTE

When using the P1 and P2 position interfaces and the encoder simulation output together, the P2 position interface uses alternative connections on the 15-way D-type connector. Pr **03.172** shows the status of the P2 position interface and indicates if alternative connections are being used for the P2 position interface.

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 4.4.3 Position feedback connection details

Table 4-10 P1 Position feedback connection details

| P1 Position feedback interface<br>Pr 03.038 | Connections |              |            |              |        |         |     |      |     |      |         |          |    |    |    |
|---------------------------------------------|-------------|--------------|------------|--------------|--------|---------|-----|------|-----|------|---------|----------|----|----|----|
|                                             | 1           | 2            | 3          | 4            | 5      | 6       | 7   | 8    | 9   | 10   | 11      | 12       | 13 | 14 | 15 |
| AB (0)                                      | A           | A\           | B          | B\           | Z      | Z\      |     |      |     |      |         |          | +V | 0V | Th |
| FD (1)                                      | F           | F\           | D          | D\           | Z      | Z\      |     |      |     |      |         |          |    |    |    |
| FR (2)                                      | F           | F\           | R          | R\           | Z      | Z\      |     |      |     |      |         |          |    |    |    |
| AB Servo (3)                                | A           | A\           | B          | B\           | Z      | Z\      | U   | U\   | V   | V\   | W       | W\       |    |    |    |
| FD Servo (4)                                | F           | F\           | D          | D\           | Z      | Z\      | U   | U\   | V   | V\   | W       | W\       |    |    |    |
| FR Servo (5)                                | F           | F\           | R          | R\           | Z      | Z\      | U   | U\   | V   | V\   | W       | W\       |    |    |    |
| SC (6)                                      | A<br>(Cos)  | A\<br>(Cos\) | B<br>(Sin) | B\<br>(Sin\) | Z      | Z\      |     |      |     |      |         |          |    |    |    |
| SC Hiperface (7)                            | Cos         | Cosref       | Sin        | Sinref       | DATA   | DATA\   |     |      |     |      |         |          |    |    |    |
| EnDat (8)                                   | DATA        | DATA\        | CLK        | CLK\         | Freeze | Freeze\ |     |      |     |      |         |          |    |    |    |
| SC EnDat (9)                                | A           | A\           | B          | B\           | DATA   | DATA\   |     |      |     |      | CLK     | CLK\     |    |    |    |
| SSI (10)                                    | DATA        | DATA\        | CLK        | CLK\         | Freeze | Freeze\ |     |      |     |      |         |          |    |    |    |
| SC SSI (11)                                 | A<br>(Cos)  | A\<br>(Cos\) | B<br>(Sin) | B\<br>(Sin\) | DATA   | DATA\   |     |      |     |      | CLK     | CLK\     |    |    |    |
| SC Servo (12)                               | A<br>(Cos)  | A\<br>(Cos\) | B<br>(Sin) | B\<br>(Sin\) | Z      | Z\      | U   | U\   | V   | V\   | W       | W\       |    |    |    |
| BiSS (13)                                   | DATA        | DATA\        | CLK        | CLK\         | Freeze | Freeze\ |     |      |     |      |         |          |    |    |    |
| Resolver (14)                               | Cos H       | Cos L        | Sin H      | Sin L        | Ref H  | Ref L   |     |      |     |      |         |          |    |    |    |
| SC SC (15)                                  | A<br>(Cos)  | A\<br>(Cos\) | B<br>(Sin) | B\<br>(Sin\) | Z      | Z\      | C*1 | C\*1 | D*2 | D\*2 | Freeze2 | Freeze2\ |    |    |    |
| Commutation Only (16)                       |             |              |            |              |        |         | U   | U\   | V   | V\   | W       | W\       |    |    |    |
| SC BiSS (17)                                | A           | A\           | B          | B\           | DATA   | DATA\   |     |      |     |      | CLK     | CLK\     |    |    |    |

\*1 - One cosine wave per revolution

\*2 - One sine wave per revolution

Greyed cells are for P2 position feedback connections or simulated encoder outputs.

#### NOTE

Freeze and Freeze\ on terminals 5 and 6 are for Freeze input 1. Freeze2 and Freeze2\ on terminals 11 and 12 are for Freeze input 2.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Table 4-11 P2 Position feedback and encoder simulation output connection details

| P1 Position feedback interface<br>Pr 03.038                               | P2 Position feedback interface<br>Pr 03.138 | Encoder Simulation Output | Connections |       |         |          |        |         |         |          |
|---------------------------------------------------------------------------|---------------------------------------------|---------------------------|-------------|-------|---------|----------|--------|---------|---------|----------|
|                                                                           |                                             |                           | 5           | 6     | 7       | 8        | 9      | 10      | 11      | 12       |
| AB (0)<br>FD (1)<br>FR (2)<br>SC (6)<br>SC Hiperface (7)<br>Resolver (14) | AB (1)                                      | Disabled* <sup>1</sup>    |             |       | A       | A\       | B      | B\      | Z       | Z\       |
|                                                                           | FD (2)                                      |                           |             |       | F       | F\       | D      | D\      | Z       | Z\       |
|                                                                           | FR (3)                                      |                           |             |       | F       | F\       | R      | R\      | Z       | Z\       |
|                                                                           | EnDat (4)<br>SSI (5)<br>BiSS (6)            |                           |             |       | DATA    | DATA\    | CLK    | CLK\    | Freeze2 | Freeze2\ |
|                                                                           | None (0)                                    | AB                        |             |       | Asim    | Asim\    | Bsim   | Bsim\   | Zsim    | Zsim\    |
|                                                                           |                                             | FD                        |             |       | Fsim    | Fsim\    | Dsim   | Dsim\   | Zsim    | Zsim\    |
|                                                                           |                                             | FR                        |             |       | Fsim    | Fsim\    | Rsim   | Rsim\   | Zsim    | Zsim\    |
|                                                                           |                                             | SSI                       |             |       | DATAsim | DATAsim\ | CLKsim | CLKsim\ |         |          |
| SC EnDat (9)<br>SC SSI (11)                                               | AB (1)                                      | Disabled* <sup>1</sup>    |             |       | A       | A\       | B      | B\      |         |          |
|                                                                           | FD (2)                                      |                           |             |       | F       | F\       | D      | D\      |         |          |
|                                                                           | FR (3)                                      |                           |             |       | F       | F\       | R      | R\      |         |          |
|                                                                           | EnDat (4)<br>SSI (5)<br>BiSS (6)            |                           |             |       | DATA    | DATA\    | CLK    | CLK\    |         |          |
|                                                                           | None (0)                                    | AB                        |             |       | Asim    | Asim\    | Bsim   | Bsim\   |         |          |
|                                                                           |                                             | FD                        |             |       | Fsim    | Fsim\    | Dsim   | Dsim\   |         |          |
|                                                                           |                                             | FR                        |             |       | Fsim    | Fsim\    | Rsim   | Rsim\   |         |          |
|                                                                           |                                             | SSI                       |             |       | DATAsim | DATAsim\ | CLKsim | CLKsim\ |         |          |
| EnDat (8)<br>SSI (10)<br>BiSS (13)                                        | AB (1)                                      | Disabled* <sup>1</sup>    |             |       | A       | A\       | B      | B\      | Z       | Z\       |
|                                                                           | FD (2)                                      |                           |             |       | F       | F\       | D      | D\      | Z       | Z\       |
|                                                                           | FR (3)                                      |                           |             |       | F       | F\       | R      | R\      | Z       | Z\       |
|                                                                           | EnDat (4)<br>SSI (5)<br>BiSS (6)            |                           |             |       | DATA    | DATA\    | CLK    | CLK\    | Freeze2 | Freeze2\ |
|                                                                           | None (0)                                    | AB                        |             |       | Asim    | Asim\    | Bsim   | Bsim\   | Zsim    | Zsim\    |
|                                                                           |                                             | FD                        |             |       | Fsim    | Fsim\    | Dsim   | Dsim\   | Zsim    | Zsim\    |
|                                                                           |                                             | FR                        |             |       | Fsim    | Fsim\    | Rsim   | Rsim\   | Zsim    | Zsim\    |
|                                                                           |                                             | SSI                       |             |       | DATAsim | DATAsim\ | CLKsim | CLKsim\ |         |          |
| EnDat (8)<br>SSI (10)<br>BiSS (13)<br>(with no Freeze inputs)             | EnDat (4)<br>SSI (5)<br>BiSS (6)            | AB                        | DATA        | DATA\ | Asim    | Asim\    | Bsim   | Bsim\   | CLK     | CLK\     |
|                                                                           |                                             | FD                        | DATA        | DATA\ | Fsim    | Fsim\    | Dsim   | Dsim\   | CLK     | CLK\     |
|                                                                           |                                             | FR                        | DATA        | DATA\ | Fsim    | Fsim\    | Rsim   | Rsim\   | CLK     | CLK\     |
|                                                                           |                                             | SSI                       | DATA        | DATA\ | DATAsim | DATAsim\ | CLKsim | CLKsim\ | CLK     | CLK\     |

\*<sup>1</sup> The encoder simulation output is disabled when Pr 03.085 is set to zero.

**NOTE**

The termination resistors are always enabled on the P2 position interface. Wire break detection is not available when using AB, FD or FR position feedback device types on the P2 position interface.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

#### 4.4.4 Position feedback terminal specifications

|                                                                                                                                                                                                                                                                       |                                                                               |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------|
| <b>1</b>                                                                                                                                                                                                                                                              | <b>A,F, Cosref, Data, Cos H</b>                                               |
| <b>2</b>                                                                                                                                                                                                                                                              | <b>Al,F\ Cosref\, Data\, Cos L</b>                                            |
| <b>AB (0), FD (1), FR (2), AB Servo (3), FD Servo(4), FR Servo (5)</b>                                                                                                                                                                                                |                                                                               |
| Type                                                                                                                                                                                                                                                                  | EIA 485 differential receivers                                                |
| Maximum input frequency                                                                                                                                                                                                                                               | 500 kHz                                                                       |
| Line loading                                                                                                                                                                                                                                                          | < 2 unit loads                                                                |
| Line termination components                                                                                                                                                                                                                                           | 120 $\Omega$ (switchable)                                                     |
| Working common mode range                                                                                                                                                                                                                                             | -7 V to +12 V                                                                 |
| <b>SC Hiperface (7), SC EnDat (9), SC SSI (11), SC Servo (12), SC SC (15)</b>                                                                                                                                                                                         |                                                                               |
| Type                                                                                                                                                                                                                                                                  | Differential voltage                                                          |
| Maximum Signal level                                                                                                                                                                                                                                                  | 1.25 V peak to peak (sin with regard to sinref and cos with regard to cosref) |
| Maximum input frequency                                                                                                                                                                                                                                               | See Table 4-12                                                                |
| Maximum applied differential voltage and common mode voltage range                                                                                                                                                                                                    | $\pm 4$ V                                                                     |
| <b>Resolution:</b> The sine wave frequency can be up to 500 kHz but the resolution is reduced at high frequency. Table 4-12 shows the number of bits of interpolated information at different frequencies and with different voltage levels at the drive encoder port |                                                                               |
| <b>EnDat (8), SSI (10), BiSS (13)</b>                                                                                                                                                                                                                                 |                                                                               |
| Type                                                                                                                                                                                                                                                                  | EIA 485 differential receivers                                                |
| Maximum input frequency                                                                                                                                                                                                                                               | 4 MHz                                                                         |
| Line termination components                                                                                                                                                                                                                                           | 120 $\Omega$ (switchable)                                                     |
| Working common mode range                                                                                                                                                                                                                                             | -7 V to +12 V                                                                 |
| <b>Resolver (14)</b>                                                                                                                                                                                                                                                  |                                                                               |
| Type                                                                                                                                                                                                                                                                  | 2 Vrms sinusoidal signal                                                      |
| Operating Frequency                                                                                                                                                                                                                                                   | 6 - 8 kHz                                                                     |
| Input voltage                                                                                                                                                                                                                                                         | 0.6 Vrms                                                                      |
| Minimum impedance                                                                                                                                                                                                                                                     | 85 $\Omega$                                                                   |
| <b>Common to All</b>                                                                                                                                                                                                                                                  |                                                                               |
| Absolute maximum applied voltage relative to 0V                                                                                                                                                                                                                       | -9 V to 14 V                                                                  |

#### NOTE

The position feedback input will accept 5 V TTL differential signals.

|                                                                                                                                                                                                                                                                       |                                                                               |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------|
| <b>3</b>                                                                                                                                                                                                                                                              | <b>B, D, R Sinref, Clock, Sin H</b>                                           |
| <b>4</b>                                                                                                                                                                                                                                                              | <b>Bl, Dl, Rl, Sinrefl, Clockl, Sin L</b>                                     |
| <b>AB (0), FD (1), FR (2), AB Servo (3), FD Servo(4), FR Servo (5)</b>                                                                                                                                                                                                |                                                                               |
| Type                                                                                                                                                                                                                                                                  | EIA 485 differential receivers                                                |
| Maximum input frequency                                                                                                                                                                                                                                               | 500 kHz                                                                       |
| Line loading                                                                                                                                                                                                                                                          | < 2 unit loads                                                                |
| Line termination components                                                                                                                                                                                                                                           | 120 $\Omega$ (switchable)                                                     |
| Working common mode range                                                                                                                                                                                                                                             | -7 V to +12 V                                                                 |
| <b>SC Hiperface (7), SC EnDat (9), SC SSI (11), SC Servo (12), SC SC (15)</b>                                                                                                                                                                                         |                                                                               |
| Type                                                                                                                                                                                                                                                                  | Differential voltage                                                          |
| Maximum Signal level                                                                                                                                                                                                                                                  | 1.25 V peak to peak (sin with regard to sinref and cos with regard to cosref) |
| Maximum input frequency                                                                                                                                                                                                                                               | See Table 4-12                                                                |
| Maximum applied differential voltage and common mode voltage range                                                                                                                                                                                                    | $\pm 4$ V                                                                     |
| <b>Resolution:</b> The sine wave frequency can be up to 500 kHz but the resolution is reduced at high frequency. Table 4-12 shows the number of bits of interpolated information at different frequencies and with different voltage levels at the drive encoder port |                                                                               |
| <b>EnDat (8), SSI (10), BiSS (13)</b>                                                                                                                                                                                                                                 |                                                                               |
| Type                                                                                                                                                                                                                                                                  | EIA 485 differential receivers                                                |
| Maximum input frequency                                                                                                                                                                                                                                               | 4 MHz                                                                         |
| Line termination components                                                                                                                                                                                                                                           | 120 $\Omega$ (switchable)                                                     |
| Working common mode range                                                                                                                                                                                                                                             | -7 V to +12 V                                                                 |
| <b>Resolver (14)</b>                                                                                                                                                                                                                                                  |                                                                               |
| Type                                                                                                                                                                                                                                                                  | 2 Vrms sinusoidal signal                                                      |
| Operating Frequency                                                                                                                                                                                                                                                   | 6 - 8 kHz                                                                     |
| Input voltage                                                                                                                                                                                                                                                         | 0.6 Vrms                                                                      |
| Minimum impedance                                                                                                                                                                                                                                                     | 85 $\Omega$                                                                   |
| <b>Common to All</b>                                                                                                                                                                                                                                                  |                                                                               |
| Absolute maximum applied voltage relative to 0V                                                                                                                                                                                                                       | -9 V to 14 V                                                                  |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

|                                                                                    |                                     |
|------------------------------------------------------------------------------------|-------------------------------------|
| <b>5</b>                                                                           | <b>Z, Data, Freeze, Ref H</b>       |
| <b>6</b>                                                                           | <b>ZI, DataI, FreezeI, Ref L</b>    |
| <b>AB (0), FD (1), FR (2), AB Servo (3), FD Servo(4), FR Servo (5), SC SC (15)</b> |                                     |
| Type                                                                               | EIA 485 differential receivers      |
| Maximum input frequency                                                            | 512 kHz                             |
| Line loading                                                                       | < 2 unit loads                      |
| Line termination components                                                        | 120 Ω (switchable)                  |
| Working common mode range                                                          | -7 V to +12 V                       |
| <b>SC Hiperface (7), SC EnDat (9), SC SSI (11), SC Servo (12)</b>                  |                                     |
| Type                                                                               | EIA 485 differential receivers      |
| Maximum input frequency                                                            | 4 MHz                               |
| Line termination components                                                        | 120 Ω (switchable)                  |
| Working common mode range                                                          | -7 V to +12 V                       |
| <b>EnDat (8), SSI (10), BiSS (13)</b>                                              |                                     |
| Type                                                                               | EIA 485 differential receivers      |
| Maximum input frequency                                                            | 4 MHz                               |
| Line termination components                                                        | 120 Ω (switchable)                  |
| Working common mode range                                                          | -7 V to +12 V                       |
| <b>Resolver (14)</b>                                                               |                                     |
| Type                                                                               | Differential voltage                |
| Nominal voltage                                                                    | 0 – 2 Vrms depending on turns ratio |
| Operating frequency                                                                | 6 - 8 KHz                           |
| Minimum impedance                                                                  | 85 Ω                                |
| <b>Common to All</b>                                                               |                                     |
| Absolute maximum applied voltage relative to 0V                                    | -9 V to 14 V                        |

|                                                                    |                                                                               |
|--------------------------------------------------------------------|-------------------------------------------------------------------------------|
| <b>7</b>                                                           | <b>U, C, Not used, Not used</b>                                               |
| <b>8</b>                                                           | <b>UI, CI, Not used, Not used</b>                                             |
| <b>AB Servo (3), FD Servo(4), FR Servo (5), SC Servo (12)</b>      |                                                                               |
| Type                                                               | EIA 485 differential receivers                                                |
| Maximum input frequency                                            | 512 kHz                                                                       |
| Line loading                                                       | 1 unit load                                                                   |
| Line termination components                                        | 120 Ω (switchable)                                                            |
| Working common mode range                                          | -7 V to +12 V                                                                 |
| <b>SC SC (15)</b>                                                  |                                                                               |
| Type                                                               | Differential voltage                                                          |
| Maximum Signal level                                               | 1.25 V peak to peak (sin with regard to sinref and cos with regard to cosref) |
| Maximum input frequency                                            | See Table 4-12                                                                |
| Maximum applied differential voltage and common mode voltage range | ±4 V                                                                          |
| <b>EnDat (8), SSI (10), BiSS (13)</b>                              |                                                                               |
| Not used                                                           |                                                                               |
| <b>Resolver (14)</b>                                               |                                                                               |
| Not used                                                           |                                                                               |
| <b>Common to All</b>                                               |                                                                               |
| Absolute maximum applied voltage relative to 0V                    | -9 V to 14 V                                                                  |

|                                                                    |                                                                               |
|--------------------------------------------------------------------|-------------------------------------------------------------------------------|
| <b>9</b>                                                           | <b>V, D, Not used, Not used</b>                                               |
| <b>10</b>                                                          | <b>VI, DI, Not used, Not used</b>                                             |
| <b>AB Servo (3), FD Servo(4), FR Servo (5), SC Servo (12)</b>      |                                                                               |
| Type                                                               | EIA 485 differential receivers                                                |
| Maximum input frequency                                            | 512 kHz                                                                       |
| Line loading                                                       | 1 unit load                                                                   |
| Line termination components                                        | 120 Ω (switchable)                                                            |
| Working common mode range                                          | -7 V to +12 V                                                                 |
| <b>SC SC (15)</b>                                                  |                                                                               |
| Type                                                               | Differential voltage                                                          |
| Maximum Signal level                                               | 1.25 V peak to peak (sin with regard to sinref and cos with regard to cosref) |
| Maximum input frequency                                            | See Table 4-12                                                                |
| Maximum applied differential voltage and common mode voltage range | ±4 V                                                                          |
| <b>EnDat (8), SSI (10), BiSS (13)</b>                              |                                                                               |
| Not used                                                           |                                                                               |
| <b>Resolver (14)</b>                                               |                                                                               |
| Not used                                                           |                                                                               |
| <b>Common to All</b>                                               |                                                                               |
| Absolute maximum applied voltage relative to 0V                    | -9 V to 14 V                                                                  |

|                                                                    |                                                                               |
|--------------------------------------------------------------------|-------------------------------------------------------------------------------|
| <b>11</b>                                                          | <b>W, Clock, Not used, Not used</b>                                           |
| <b>12</b>                                                          | <b>WI, ClockI, Not used, Not used</b>                                         |
| <b>AB Servo (3), FD Servo(4), FR Servo (5), SC Servo (12)</b>      |                                                                               |
| Type                                                               | EIA 485 differential receivers                                                |
| Maximum input frequency                                            | 512 kHz                                                                       |
| Line loading                                                       | 1 unit load                                                                   |
| Line termination components                                        | 120 Ω (switchable)                                                            |
| Working common mode range                                          | -7 V to +12 V                                                                 |
| <b>SC EnDat (9), SC SSI (11)</b>                                   |                                                                               |
| Type                                                               | Differential voltage                                                          |
| Maximum Signal level                                               | 1.25 V peak to peak (sin with regard to sinref and cos with regard to cosref) |
| Maximum input frequency                                            | See Table 4-12                                                                |
| Maximum applied differential voltage and common mode voltage range | ±4 V                                                                          |
| <b>EnDat (8), SSI (10), BiSS (13)</b>                              |                                                                               |
| Not used                                                           |                                                                               |
| <b>Resolver (14)</b>                                               |                                                                               |
| Not used                                                           |                                                                               |
| <b>Common to All</b>                                               |                                                                               |
| Absolute maximum applied voltage relative to 0V                    | -9 V to 14 V                                                                  |

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## Common to all Feedback types

| 13                                                                                                                                                                                                                                                                                                                                                         | Feedback device supply                            |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------|
| Supply voltage                                                                                                                                                                                                                                                                                                                                             | 5.15 V $\pm$ 2 %, 8 V $\pm$ 5 % or 15 V $\pm$ 5 % |
| Maximum output current                                                                                                                                                                                                                                                                                                                                     | 300 mA for 5 V and 8 V<br>200 mA for 15 V         |
| The voltage on Terminal 13 is controlled by Pr <b>03.036</b> . The default for this parameter is 5 V (0) but this can be set to 8 V (1) or 15 V (2). Setting the encoder voltage too high for the encoder could result in damage to the feedback device. The termination resistors should be disabled if the outputs from the encoder are higher than 5 V. |                                                   |

| 14 | 0V Common |
|----|-----------|
|----|-----------|

| 15                                                                 | Motor thermistor input |
|--------------------------------------------------------------------|------------------------|
| Thermistor type is selected in <i>P1 Thermistor Type</i> (03.118). |                        |

## Sincos encoder resolution

The sine wave frequency can be up to 500 kHz but the resolution is reduced at high frequency. Table 4-12 shows the number of bits of interpolated information at different frequencies and with different voltage levels at the drive encoder port. The total resolution in bits per revolution is the ELPR plus the number of bits of interpolated information. Although it is possible to obtain 11 bits of interpolation information, the nominal design value is 10 bits.

**Table 4-12 Feedback resolution based on frequency and voltage level**

| Volt/Freq | 1 kHz | 5 kHz | 50 kHz | 100 kHz | 200 kHz | 500 kHz |
|-----------|-------|-------|--------|---------|---------|---------|
| 1.2       | 11    | 11    | 10     | 10      | 9       | 8       |
| 1.0       | 11    | 11    | 10     | 9       | 9       | 7       |
| 0.8       | 10    | 10    | 10     | 9       | 8       | 7       |
| 0.6       | 10    | 10    | 9      | 9       | 8       | 7       |
| 0.4       | 9     | 9     | 9      | 8       | 7       | 6       |

## 4.5 Safe Torque Off (STO)

The *Unidrive M700 / M701* has a single channel STO, whereas the *Unidrive M702* has a dual channel STO.

The Safe Torque Off function provides a means for preventing the drive from generating torque in the motor, with a very high level of integrity. It is suitable for incorporation into a safety system for a machine. It is also suitable for use as a conventional drive enable input.

The safety function is active when the STO input is in the logic-low state as specified in the control terminal specification. The function is defined according to EN 61800-5-2 and IEC 61800-5-2 as follows. (In these standards a drive offering safety-related functions is referred to as a PDS(SR)):

'Power that can cause rotation (or motion in the case of a linear motor) is not applied to the motor. The PDS(SR) will not provide energy to the motor which can generate torque (or force in the case of a linear motor)'

This safety function corresponds to an uncontrolled stop in accordance with stop category 0 of IEC 60204-1.

The Safe Torque Off function makes use of the special property of an inverter drive with an induction motor, which is that torque cannot be generated without the continuous correct active behaviour of the inverter circuit. All credible faults in the inverter power circuit cause a loss of torque generation.

The Safe Torque Off function is fail-safe, so when the Safe Torque Off input is disconnected the drive will not operate the motor, even if a combination of components within the drive has failed. Most component failures are revealed by the drive failing to operate. Safe Torque Off is also independent of the drive firmware. This meets the requirements of the following standards, for the prevention of operation of the motor.

### Machinery Applications

The Safe Torque Off function has been independently assessed by Notified Body, TÜV Rheinland for use as a safety component of a machine:

*Prevention of unintended motor operation: The safety function "Safe Torque Off" can be used in applications up to Cat 4, PL e according to EN ISO 13849-1, SIL 3 according to EN 61800-5-2/ EN 62061/ IEC 61508 and in lift applications according to EN 81-1 and EN81-2.*

| Type examination certificate number | Date of issue | Models           |
|-------------------------------------|---------------|------------------|
| 01.205/5270.01/14                   | 11-11-2014    | M700, M701, M702 |

This certificate is available for download from the TÜV Rheinland website at: <http://www.tuv.com>

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### Safety Parameters as verified by TÜV Rheinland:

According to IEC 61508-1 to 07 / EN 61800-5-2 / EN 62061

| Type                                            | Value                      | Percentage of SIL 3 allowance |
|-------------------------------------------------|----------------------------|-------------------------------|
| Proof test interval                             | 20 years                   |                               |
| High demand or a continuous mode of operation   |                            |                               |
| PFH (1/h)                                       | $4.21 \times 10^{-11}$ 1/h | <1 %                          |
| Low demand mode of operation (not EN 61800-5-2) |                            |                               |
| PFDavg                                          | $3.68 \times 10^{-6}$      | < 1 %                         |

According to EN ISO 13849-1

| Type                       | Value       | Classification |
|----------------------------|-------------|----------------|
| Category                   | 4           |                |
| Performance Level (PL)     | e           |                |
| MTTF <sub>D</sub> (STO1)   | >2500 years | High           |
| MTTF <sub>D</sub> (STO2)   | >2500 years | High           |
| MTTFD (Single channel STO) | >2500 years | High           |
| DC <sub>avg</sub>          | ≥99 %       | High           |
| Mission time               | 20 years    |                |

#### NOTE

Logic levels comply with IEC 61131-2:2007 for type 1 digital inputs rated at 24 V. Maximum level for logic low to achieve SIL3 and PL e 5 V and 0.5 mA.

### Lift (Elevator) Applications

The Safe Torque Off function has been independently assessed for use as a safety component in lift (elevator) applications by Notified Body, TÜV Nord:

*The Unidrive M drives series with Safe Torque Off (STO) function if applied according to the "Conditions of application" fulfil the safety requirements of the standards EN81-1, EN81-2, EN 81-50 and EN60664-1 and are in conformity with all relevant requirements of the Directive 95/16/EC.*

| Certificate of Conformity number | Date of issue | Models           |
|----------------------------------|---------------|------------------|
| 44799 13196202                   | 04-08-2015    | M700, M701, M702 |

The Safe Torque Off function can be used to eliminate electro-mechanical contactors, including special safety contactors, which would otherwise be required for safety applications.

For further information contact the supplier of the drive.

### UL Approval

The Safe Torque Off function has been independently assessed by Underwriters Laboratories (UL). The on-line certification (yellow card) reference is: FSPC.E171230.

### Safety Parameters as verified by UL:

According to IEC 61508-1 to 7

| Type          | Value                                                |
|---------------|------------------------------------------------------|
| Safety Rating | SIL 3                                                |
| SFF           | > 99 %                                               |
| PFH (1/h)     | $4.43 \times 10^{-10}$ 1/h (<1 % of SIL 3 allowance) |
| HFT           | 1                                                    |
| Beta Factor   | 2 %                                                  |
| CFF           | Not applicable                                       |

According to EN ISO 13849-1

| Type                   | Value      |
|------------------------|------------|
| Category               | 4          |
| Performance Level (PL) | e          |
| MTTF <sub>D</sub>      | 2574 years |
| Diagnostic coverage    | High       |
| CCF                    | 65         |

### Two-channel Safe Torque Off

Models M700 and M701 have a single channel STO, whereas the M702 has dual channel STO.

The dual channel STO has two fully independent channels.

Each input meets the requirements of the standards as defined above.

If either or both inputs are set at a logic low state, there are no single faults in the drive which can permit the motor to be driven.

It is not necessary to use both channels to meet the requirements of the standards. The purpose of the two channels is to allow connection to machine safety systems where two channels are required, and to facilitate protection against wiring faults.

For example, if each channel is connected to a safety-related digital output of a safety related controller, computer or PLC, then on detection of a fault in one output the drive can still be disabled safely through the other output.

Under these conditions, there are no single wiring faults which can cause a loss of the safety function, i.e. inadvertent enabling of the drive.

In the event that the two-channel operation is not required, the two inputs can be connected together to form a single Safe Torque Off input.

### One-channel Safe Torque Off (Including Two-channel Safe Torque off with the inputs connected together.)

In a single channel Safe Torque Off application there are no single faults in the drive which can permit the motor to be driven. Therefore it is not necessary to have a second channel to interrupt the power connection, nor a fault detection circuit.

It is important to note that a single short-circuit from the Safe Torque Off input to a DC supply of > 5 V could cause the drive to be enabled.

This might occur through a fault in the wiring. This can be excluded according to EN ISO 13849-2 by the use of protected wiring. The wiring can be protected by either of the following methods:

- By placing the wiring in a segregated cable duct or other enclosure.

or

- By providing the wiring with a grounded (0V of the Drive) shield in a positive-logic grounded control circuit. The shield is provided to avoid a hazard from an electrical fault. It may be grounded by any convenient method; no special EMC precautions are required.

### Note on response time of Safe Torque Off, and use with safety controllers with self-testing outputs:

Safe Torque Off has been designed to have a response time of greater than 1 ms so that it is compatible with safety controllers whose outputs are subject to a dynamic test with a pulse width not exceeding 1 ms.

### Note on the use of servo motors, other permanent-magnet motors, reluctance motors and salient-pole induction motors:

When the drive is disabled through Safe Torque Off, a possible (although highly unlikely) failure mode is for two power devices in the inverter circuit to conduct incorrectly.

|                    |                     |                         |                                |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | <b>Electrical installation</b> | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|--------------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

This fault cannot produce a steady rotating torque in any AC motor. It produces no torque in a conventional induction motor with a cage rotor. If the rotor has permanent magnets and/or saliency, then a transient alignment torque may occur. The motor may briefly try to rotate by up to 180° electrical, for a permanent magnet motor, or 90° electrical, for a salient pole induction motor or reluctance motor. This possible failure mode must be allowed for in the machine design.



**WARNING**

The design of safety-related control systems must only be done by personnel with the required training and experience. The Safe Torque Off function will only ensure the safety of a machine if it is correctly incorporated into a complete safety system. The system must be subject to a risk assessment to confirm that the residual risk of an unsafe event is at an acceptable level for the application.



**WARNING**

Safe Torque Off inhibits the operation of the drive, this includes inhibiting braking. If the drive is required to provide both braking and Safe Torque Off in the same operation (e.g. for emergency stop) then a safety timer relay or similar device must be used to ensure that the drive is disabled a suitable time after braking. The braking function in the drive is provided by an electronic circuit which is not fail-safe. If braking is a safety requirement, it must be supplemented by an independent fail-safe braking mechanism.



**WARNING**

Safe Torque Off does not provide electrical isolation. The supply to the drive must be disconnected by an approved isolation device before gaining access to power connections.



**WARNING**

It is essential to observe the maximum permitted voltage of 5 V for a safe low (disabled) state of Safe Torque Off. The connections to the drive must be arranged so that voltage drops in the 0 V wiring cannot exceed this value under any loading condition. It is strongly recommended that the Safe Torque Off circuit be provided with a dedicated 0 V conductor which should be connected to terminal 30 at the drive.

#### Safe Torque Off over-ride

The drive does not provide any facility to over-ride the Safe Torque Off function, for example for maintenance purposes.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 5 Getting started

This chapter introduces the user interfaces, menu structure and security levels of the drive.

### 5.1 Understanding the display

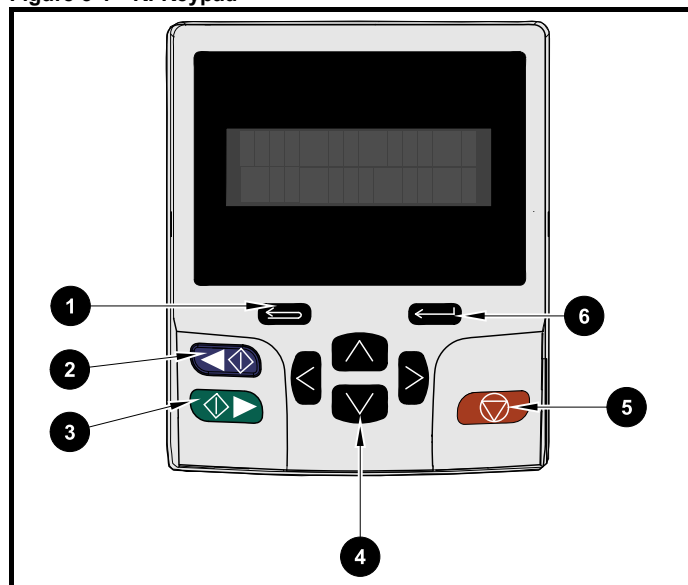
The keypad can only be mounted on the drive.

#### 5.1.1 KI-Keypad

The KI-Keypad display consists of two rows of text. The upper row shows the drive status or the menu and parameter number currently being viewed. The lower row of the display line shows the parameter value or the specific trip type. The last two characters on the first row may display special indications. If more than one of these indications is active then the indications are prioritized as shown in Table 5-2.

When the drive is powered up the lower row will show the power up parameter defined by *Parameter Displayed At Power-Up* (11.022).

Figure 5-1 KI-Keypad



1. Escape button
2. Start reverse (Auxiliary button)
3. Start forward
4. Navigation keys (x4)
5. Stop / Reset (red) button
6. Enter button

#### NOTE

The red stop  button is also used to reset the drive.

The parameter value is correctly displayed in the lower row of the keypad display, see table below.

Table 5-1 Keypad display formats

| Display formats                  | Value                |
|----------------------------------|----------------------|
| IP Address                       | 127.000.000.000      |
| MAC Address                      | 01ABCDEF2345         |
| Time                             | 12:34:56             |
| Date                             | 31-12-11 or 12-31-11 |
| Version number                   | 01.02.02.00          |
| Character                        | ABCD                 |
| 32 bit number with decimal point | 21474836.47          |
| 16 bit binary number             | 0100001011100101     |

Table 5-2 Active action icon

| Active action icon                                                                                                                                                      | Description                                  | Priority                                                                            |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------|-------------------------------------------------------------------------------------|
|                                                                                        | Alarm active                                 |  |
|                                                                                        | Keypad real-time clock battery low           |                                                                                     |
|                                                                                        | Accessing non-volatile media card            |                                                                                     |
|  or  | Drive security active and locked or unlocked |                                                                                     |
|                                                                                        | Motor map 2 active                           |                                                                                     |
|                                                                                        | User program running                         |                                                                                     |
|                                                                                        | Keypad reference active                      |                                                                                     |

### 5.2 Keypad operation

#### 5.2.1 Control buttons

The keypad consists of:

- Navigation Keys - Used to navigate the parameter structure and change parameter values.
- Enter / Mode button - Used to toggle between parameter edit and view mode.
- Escape / Exit button - Used to exit from parameter edit or view mode. In parameter edit mode, if parameter values are edited and the exit button pressed the parameter value will be restored to the value it had on entry to edit mode.
- Start forward button - Use to provide a 'Run' command if keypad mode is selected.
- Start reverse button - Used to control the drive if keypad mode is selected and the reverse button is activated. If *Enable Auxiliary Key* (06.013) = 1, then the keypad reference is toggled between run forward and run reverse each time the button is pressed. If *Enable Auxiliary Key* (06.013) = 2, then the button functions as a run reverse key.
- Stop / Reset button - Used to reset the drive. In keypad mode can be used for 'Stop'.

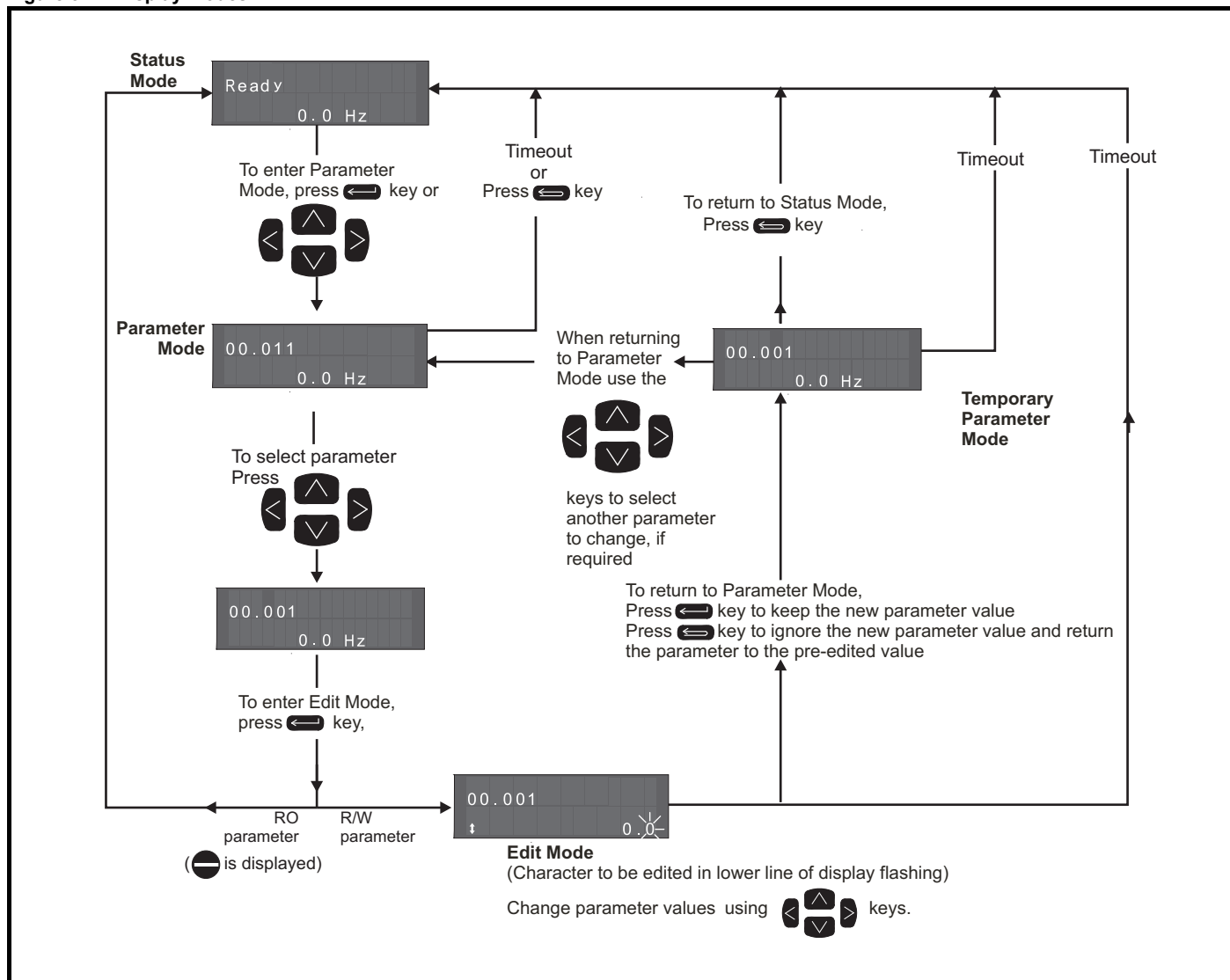
#### NOTE

Low battery voltage is indicated by  low battery symbol on the keypad display.

Figure 5-2 overleaf shows an example on moving between menus and editing parameters.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 5-2 Display modes

**NOTE**

The navigation keys can only be used to move between menus if Pr 00.049 has been set to show 'All Menus'. Refer to section 5.9 *Parameter access level and security* on page 46.

**5.2.2 Quick access mode**

The quick access mode allows direct access to any parameter without scrolling through menus and parameters.

To enter the quick access mode, press and hold the **Enter** button on the keypad while in 'parameter mode'.

Figure 5-3 Quick access mode

**5.2.3 Keypad shortcuts****In 'parameter mode':**

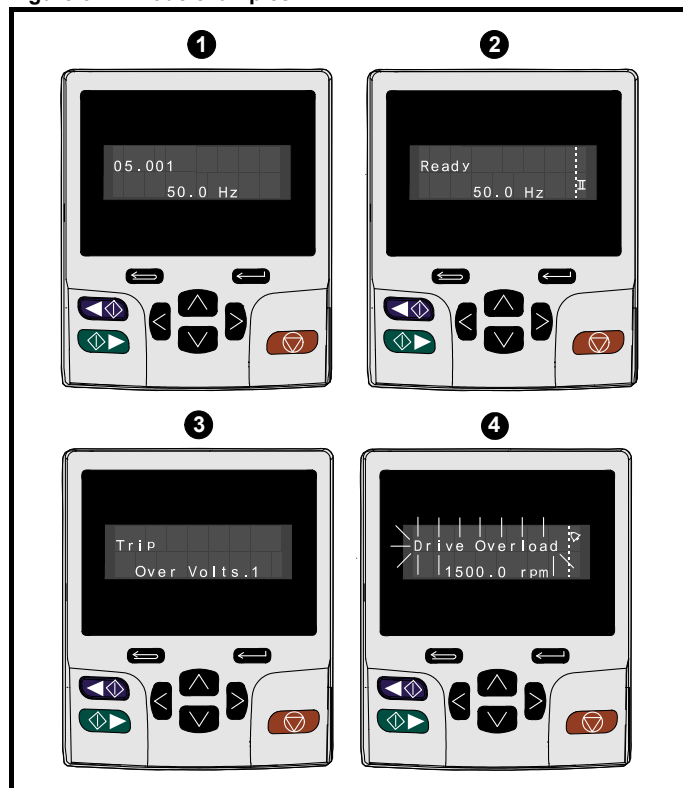
- If the **Up** and **Down** keypad buttons are pressed together, then the keypad display will jump to the start of the parameter menu being viewed, i.e. Pr 05.005 being viewed, when the above buttons pressed together will jump to Pr 05.000.
- If the **Left** and **Right** keypad buttons are pressed together, then the keypad display will jump to the last viewed parameter in Menu 0.

**In 'parameter edit mode':**

- If the **Up** and **Down** keypad buttons are pressed together, then the parameter value of the parameter being edited will be set to 0.
- If the **Left** and **Right** keypad buttons are pressed together, the least significant digit (furthest right) will be selected on the keypad display for editing.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 5-4 Mode examples



**1. Parameter view mode: Read write or Read only**

**2. Status mode: Drive OK status**

If the drive is ok and the parameters are not being edited or viewed, the upper row of the display will show one of the following:

- 'Inhibit', 'Ready' or 'Run'.

**3. Status mode: Trip status**

When the drive is in trip condition, the upper row of the display will indicate that the drive has tripped and the lower row of the display will show the trip code. For further information regarding trip codes, refer to Table 13-4 *Trip indications* on page 247.

**4. Status mode: Alarm status**

During an 'alarm' condition the upper row of the display flashes between the drive status (Inhibit, Ready or Run, depending on what is displayed) and the alarm.



Do not change parameter values without careful consideration; incorrect values may cause damage or a safety hazard.

**NOTE**

When changing the values of parameters, make a note of the new values in case they need to be entered again.

**NOTE**

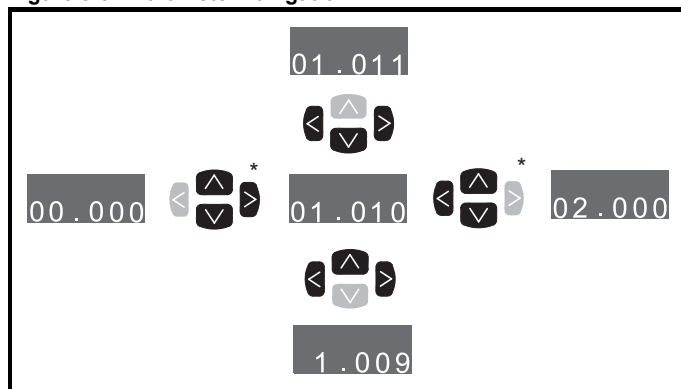
For new parameter-values to apply after the line power supply to the drive is interrupted, new values must be saved. Refer to section 5.7 *Saving parameters* on page 45.

## 5.3 Menu structure

The drive parameter structure consists of menus and parameters.

The drive initially powers up so that only Menu 0 can be viewed. The up and down arrow buttons are used to navigate between parameters and once Pr **00.049** has been set to 'All Menus' the left and right buttons are used to navigate between menus. For further information, refer to section 5.9 *Parameter access level and security* on page 46.

Figure 5-5 Parameter navigation



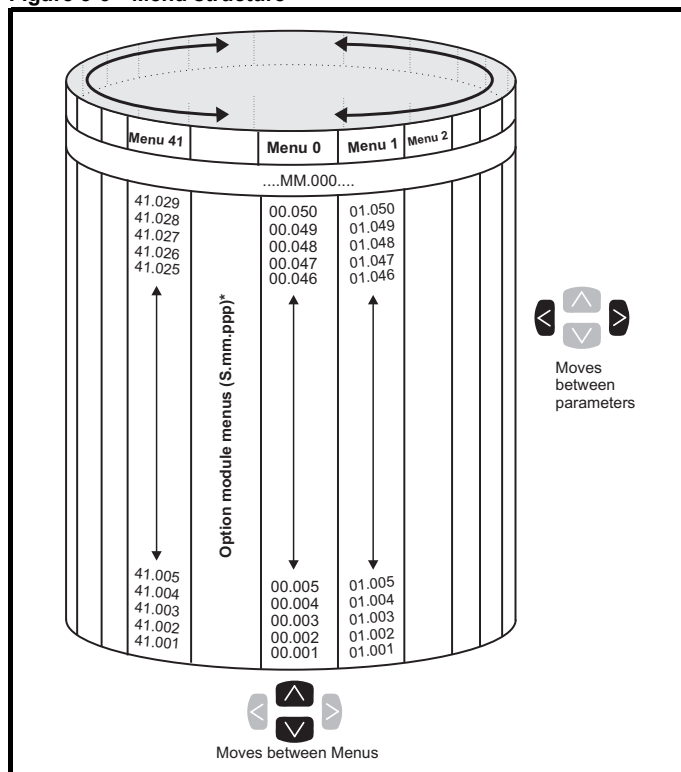
\* Can only be used to move between menus if all menus have been enabled (Pr **00.049**). Refer to section 5.9 *Parameter access level and security* on page 46.

The menus and parameters roll over in both directions.

i.e. if the last parameter is displayed, a further press will cause the display to rollover and show the first parameter.

When changing between menus the drive remembers which parameter was last viewed in a particular menu and thus displays that parameter.

Figure 5-6 Menu structure



\* The option module menus (S.mm.ppp) are only displayed if option modules are installed. Where S signifies the option module slot number and the mm.ppp signifies the menu and the parameter number of the option module's internal menus and parameter.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

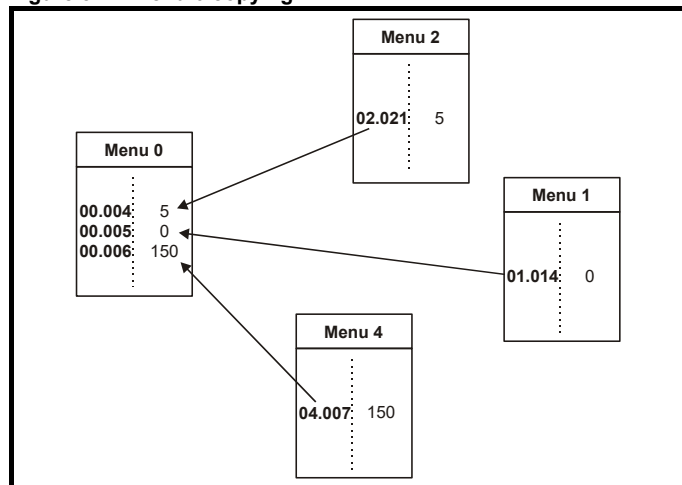
## 5.4 Menu 0

Menu 0 is used to bring together various commonly used parameters for basic easy set up of the drive. The parameters displayed in Menu 0 can be configured in Menu 22.

Appropriate parameters are copied from the advanced menus into Menu 0 and thus exist in both locations.

For further information, refer to Chapter 6 *Basic parameters* on page 49.

**Figure 5-7 Menu 0 copying**



## 5.5 Advanced menus

The advanced menus consist of groups or parameters appropriate to a specific function or feature of the drive. Menus 0 to 41 can be viewed on the KI-Keypad.

The option module menus (S.mm.ppp) are only displayed (except for *Unidrive M700 / M702* 4.mm.ppp) if option modules are installed. Where S signifies the option module slot number and the mm.ppp signifies the menu and parameter number of the option module's internal menus and parameter.

On *Unidrive M700 / M702*, menu 4.00.xxx is the same as menu 24.xxx.

**Table 5-3 Advanced menu descriptions**

| Menu   | Description                                                        |
|--------|--------------------------------------------------------------------|
| 0      | Commonly used basic set up parameters for quick / easy programming |
| 1      | Frequency / Speed reference                                        |
| 2      | Ramps                                                              |
| 3      | Frequency slaving, speed feedback and speed control                |
| 4      | Torque and current control                                         |
| 5      | Motor control                                                      |
| 6      | Sequencer and clock                                                |
| 7      | Analog I/O                                                         |
| 8      | Digital I/O                                                        |
| 9      | Programmable logic, motorized pot, binary sum, timers and scope    |
| 10     | Status and trips                                                   |
| 11     | Drive set-up and identification, serial communications             |
| 12     | Threshold detectors and variable selectors                         |
| 13     | Standard motion control                                            |
| 14     | User PID controller                                                |
| 15     | Option module slot 1 set-up menu                                   |
| 16     | Option module slot 2 set-up menu                                   |
| 17     | Option module slot 3 set-up menu                                   |
| 18     | General option module application menu 1                           |
| 19     | General option module application menu 2                           |
| 20     | General option module application menu 3                           |
| 21     | Second motor parameters                                            |
| 22     | Menu 0 set-up                                                      |
| 23     | Not allocated                                                      |
| 24     | Ethernet module (slot 4) set-up menu*                              |
| 25     | Option module slot 1 application parameters                        |
| 26     | Option module slot 2 application parameters                        |
| 27     | Option module slot 3 application parameters                        |
| 28     | Option module slot 4 application parameters                        |
| 29     | Reserved menu                                                      |
| 30     | Onboard user programming application menu                          |
| 31-41  | Advanced motion controller set-up parameters                       |
| Slot 1 | Slot 1 option menus**                                              |
| Slot 2 | Slot 2 option menus**                                              |
| Slot 3 | Slot 3 option menus**                                              |
| Slot 4 | Slot 4 option menus**                                              |

\* Only displayed on *Unidrive M700 / M702*.

\*\* Only displayed when the option modules are installed.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 5.5.1 KI-Keypad set-up menu

To enter the keypad set-up menu press and hold the escape  button on the keypad from status mode. All the keypad parameters are saved to the keypad non-volatile memory when exiting from the keypad set-up menu.

To exit from the keypad set-up menu press the escape  or  or  button. Below are the keypad set-up parameters.

**Table 5-4 KI-Keypad set-up parameters**

| Parameters |                                | Range                                                                                                       | Type |
|------------|--------------------------------|-------------------------------------------------------------------------------------------------------------|------|
| Keypad.00  | Language*                      | Classic English (0)<br>English (1)<br>German (2)<br>French (3)<br>Italian (4)<br>Spanish (5)<br>Chinese (6) | RW   |
| Keypad.01  | Show Units                     | Off (0), On (1)                                                                                             | RW   |
| Keypad.02  | Backlight Level                | 0 to 100 %                                                                                                  | RW   |
| Keypad.03  | Keypad Date                    | 01.01.10 to 31.12.99                                                                                        | RO   |
| Keypad.04  | Keypad Time                    | 00:00:00 to 23:59:59                                                                                        | RO   |
| Keypad.05  | Show Raw Text Parameter Values | Off (0), On (1)                                                                                             | RW   |
| Keypad.06  | Software Version               | 00.00.00.00 to 99.99.99.99                                                                                  | RO   |
| Keypad. 07 | Language version               | 00.00.00.00 to 99.99.99.99                                                                                  | RO   |
| Keypad. 08 | Font version                   | 0 to 1000                                                                                                   | RO   |
| Keypad. 09 | Show menu names                | Off or on                                                                                                   | RW   |

\* The languages available will depend on the keypad software version.

#### NOTE

It is not possible to access the keypad parameters via any communications channel.

### 5.5.2 Alarm indications

An alarm is an indication given on the display by alternating the alarm string with the drive status string on the upper row and showing the alarm symbol in the last character in the upper row. Alarms strings are not displayed when a parameter is being edited, but the user will still see the alarm character on the upper row.

**Table 5-5 Alarm indications**

| Alarm string          | Description                                                                                                                                                                              |
|-----------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Brake Resistor</b> | Brake resistor overload. <i>Braking Resistor Thermal Accumulator</i> (10.039) in the drive has reached 75.0 % of the value at which the drive will trip.                                 |
| <b>Motor Overload</b> | <i>Motor Protection Accumulator</i> (04.019) in the drive has reached 75.0 % of the value at which the drive will trip and the load on the drive is > 100 %.                             |
| <b>Ind Overload</b>   | Regen inductor overload. <i>Inductor Protection Accumulator</i> (04.019) in the drive has reached 75.0 % of the value at which the drive will trip and the load on the drive is > 100 %. |
| <b>Drive Overload</b> | Drive over temperature. <i>Percentage Of Drive Thermal Trip Level</i> (07.036) in the drive is greater than 90 %.                                                                        |
| <b>Auto Tune</b>      | The autotune procedure has been initialized and an autotune in progress.                                                                                                                 |
| <b>Limit Switch</b>   | Limit switch active. Indicates that a limit switch is active and that is causing the motor to be stopped.                                                                                |

### 5.5.3 Display messages

The following tables indicate the various possible mnemonics which can be displayed by the drive and their meaning.

**Table 5-6 Status indications**

| Upper row string     | Description                                                                                                                                                                                                                                                            | Drive output stage |
|----------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------|
| <b>Inhibit</b>       | The drive is inhibited and cannot be run. The Safe Torque Off signal is not applied to Safe Torque Off terminals or Pr <b>06.015</b> is set to 0. The other conditions that can prevent the drive from enabling are shown as bits in <i>Enable Conditions</i> (06.010) | Disabled           |
| <b>Ready</b>         | The drive is ready to run. The drive enable is active, but the drive inverter is not active because the final drive run is not active                                                                                                                                  | Disabled           |
| <b>Stop</b>          | The drive is stopped / holding zero speed.                                                                                                                                                                                                                             | Enabled            |
| <b>Run</b>           | The drive is active and running                                                                                                                                                                                                                                        | Enabled            |
| <b>Scan</b>          | The drive is enabled in Regen mode and is trying to synchronize to the supply                                                                                                                                                                                          | Enabled            |
| <b>Supply Loss</b>   | Supply loss condition has been detected                                                                                                                                                                                                                                | Enabled            |
| <b>Deceleration</b>  | The motor is being decelerated to zero speed / frequency because the final drive run has been deactivated.                                                                                                                                                             | Enabled            |
| <b>dc injection</b>  | The drive is applying dc injection braking                                                                                                                                                                                                                             | Enabled            |
| <b>Position</b>      | Positioning / position control is active during an orientation stop                                                                                                                                                                                                    | Enabled            |
| <b>Trip</b>          | The drive has tripped and no longer controlling the motor. The trip code appears in the lower display.                                                                                                                                                                 | Disabled           |
| <b>Active</b>        | The Regen unit is enabled and synchronized to the supply                                                                                                                                                                                                               | Enabled            |
| <b>Under Voltage</b> | The drive is in the under voltage state either in low voltage or high voltage mode.                                                                                                                                                                                    | Disabled           |
| <b>Heat</b>          | The motor pre-heat function is active                                                                                                                                                                                                                                  | Enabled            |
| <b>Phasing</b>       | The drive is performing a 'phasing test on enable'                                                                                                                                                                                                                     | Enabled            |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Table 5-7 Option module and NV media card and other status indications at power-up**

| First row string                                                                                                                                                                                                                                                                                                                         | Second row string     | Status                              |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------|-------------------------------------|
| <b>Booting</b>                                                                                                                                                                                                                                                                                                                           | <b>Parameters</b>     | Parameters are being loaded         |
| Drive parameters are being loaded from a NV Media Card                                                                                                                                                                                                                                                                                   |                       |                                     |
| <b>Booting</b>                                                                                                                                                                                                                                                                                                                           | <b>User Program</b>   | User program being loaded           |
| User program is being loaded from a NV Media Card to the drive                                                                                                                                                                                                                                                                           |                       |                                     |
| <b>Booting</b>                                                                                                                                                                                                                                                                                                                           | <b>Option Program</b> | User program being loaded           |
| User program is being loaded from a NV Media Card to the option module in slot X                                                                                                                                                                                                                                                         |                       |                                     |
| <b>Writing To</b>                                                                                                                                                                                                                                                                                                                        | <b>NV Card</b>        | Data being written to NV Media Card |
| Data is being written to a NV Media Card to ensure that its copy of the drive parameters is correct because the drive is in Auto or Boot mode                                                                                                                                                                                            |                       |                                     |
| <b>Waiting For</b>                                                                                                                                                                                                                                                                                                                       | <b>Power System</b>   | Waiting for power stage             |
| The drive is waiting for the processor in the power stage to respond after power-up                                                                                                                                                                                                                                                      |                       |                                     |
| <b>Waiting For</b>                                                                                                                                                                                                                                                                                                                       | <b>Options</b>        | Waiting for an option module        |
| The drive is waiting for the options modules to respond after power-up                                                                                                                                                                                                                                                                   |                       |                                     |
| <b>Uploading From</b>                                                                                                                                                                                                                                                                                                                    | <b>Options</b>        | Loading parameter database          |
| At power-up it may be necessary to update the parameter database held by the drive because an option module has changed or because an applications module has requested changes to the parameter structure. This may involve data transfer between the drive an option modules. During this period 'Uploading From Options' is displayed |                       |                                     |

## 5.6 Changing the operating mode

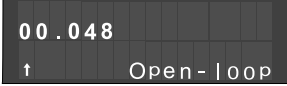
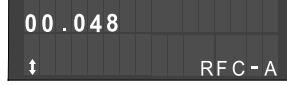
Changing the operating mode returns all parameters to their default value, including the motor parameters. *User security status* (00.049) and *User security code* (00.034) are not affected by this procedure).

### Procedure

Use the following procedure only if a different operating mode is required:

1. Ensure the drive is not enabled, i.e. terminal 31 on *Unidrive M700 / M701* and terminal 11 & 13 on *Unidrive M702* is open or Pr **06.015** is Off (0)
2. Enter either of the following values in Pr **mm.000**, as appropriate:  
1253 (50 Hz AC supply frequency)  
1254 (60 Hz AC supply frequency)

3. Change the setting of Pr **00.048** as follows:

| Pr 00.048 setting                                                                  |   | Operating mode |
|------------------------------------------------------------------------------------|---|----------------|
|  | 1 | Open-loop      |
|  | 2 | RFC-A          |
|  | 3 | RFC-S          |
|  | 4 | Regen          |

The figures in the second column apply when the communications interface is used.

4. Either:

- Press the red  reset button
- Toggle the reset digital input
- Carry out a drive reset through the communications interface by setting Pr **10.038** to 100.

### NOTE

Entering 1253 or 1254 in Pr **mm.000** will only load defaults if the setting of Pr **00.048** has been changed.

## 5.7 Saving parameters

When changing a parameter in Menu 0, the new value is saved when

pressing the  Enter button to return to parameter view mode from parameter edit mode.

If parameters have been changed in the advanced menus, then the change will not be saved automatically. A save function must be carried out.

### Procedure

1. Select 'Save Parameters' in Pr **mm.000** (alternatively enter a value of 1001 in Pr **mm.000**)
2. Either:
  - Press the red  reset button
  - Toggle the reset digital input, or
  - Carry out a drive reset through the communications interface by setting Pr **10.038** to 100

## 5.8 Restoring parameter defaults

Restoring parameter defaults by this method saves the default values in the drives memory. *User security status* (00.049) and *User security code* (00.034) are not affected by this procedure).

### Procedure

1. Ensure the drive is not enabled, i.e. terminal 31 on *Unidrive M700 / M701* and terminal 11 & 13 on *Unidrive M702* is open or Pr **06.015** is Off (0)
2. Select 'Reset 50 Hz Defs' or 'Reset 60 Hz Defs' in Pr **mm.000**. (alternatively, enter 1233 (50 Hz settings) or 1244 (60 Hz settings) in Pr **mm.000**).
3. Either:
  - Press the red  reset button
  - Toggle the reset digital input
  - Carry out a drive reset through the communications interface by setting Pr **10.038** to 100

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 5.9 Parameter access level and security

The parameter access level determines whether the user has access to Menu 0 only or to all the advanced menus (Menus 1 to 41) in addition to Menu 0.

The User Security determines whether the access to the user is read only or read write.

Both the User Security and Parameter Access Level can operate independently of each other as shown in Table 5-8.

**Table 5-8 Parameter access level and security**

| User security status (11.044) | Access level     | User security | Menu 0 status | Advanced menu status |
|-------------------------------|------------------|---------------|---------------|----------------------|
| 0                             | Menu 0           | Open          | RW            | Not visible          |
|                               |                  | Closed        | RO            | Not visible          |
| 1                             | All Menus        | Open          | RW            | RW                   |
|                               |                  | Closed        | RO            | RO                   |
| 2                             | Read-only Menu 0 | Open          | RO            | Not visible          |
|                               |                  | Closed        | RO            | Not visible          |
| 3                             | Read-only        | Open          | RO            | RO                   |
|                               |                  | Closed        | RO            | RO                   |
| 4                             | Status only      | Open          | Not visible   | Not visible          |
|                               |                  | Closed        | Not visible   | Not visible          |
| 5                             | No access        | Open          | Not visible   | Not visible          |
|                               |                  | Closed        | Not visible   | Not visible          |

The default settings of the drive are Parameter Access Level Menu 0 and user Security Open i.e. read / write access to Menu 0 with the advanced menus not visible.

### 5.9.1 User Security Level / Access Level

The drive provides a number of different levels of security that can be set by the user via *User Security Status* (11.044); these are shown below.

| User Security Status (Pr 11.044) | Description                                                                                                                                                                        |
|----------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Menu 0 (0)                       | All writable parameters are available to be edited but only parameters in Menu 0 are visible                                                                                       |
| All menus (1)                    | All parameters are visible and all writable parameters are available to be edited                                                                                                  |
| Read- only Menu 0 (2)            | Access is limited to Menu 0 parameters only. All parameters are read-only                                                                                                          |
| Read-only (3)                    | All parameters are read-only however all menus and parameters are visible                                                                                                          |
| Status only (4)                  | The keypad remains in status mode and no parameters can be viewed or edited                                                                                                        |
| No access (5)                    | The keypad remains in status mode and no parameters can be viewed or edited. Drive parameters cannot be accessed via a comms/ fieldbus interface in the drive or any option module |

### 5.9.2 Changing the User Security Level /Access Level

The security level is determined by the setting of Pr **00.049** or Pr **11.044**. The Security Level can be changed through the keypad even if the User Security Code has been set.

### 5.9.3 User Security Code

The User Security Code, when set, prevents write access to any of the parameters in any menu.

#### Setting User Security Code

Enter a value between 1 and 2147483647 in Pr **00.034** and press the

 button; the security code has now been set to this value. In order

to activate the security, the Security level must be set to desired level in Pr **00.049**. When the drive is reset, the security code will have been

activated and the drive returns to Menu 0 and the  symbol is displayed in the right hand corner of the keypad display. The value of Pr **00.034** will return to 0 in order to hide the security code.

#### Unlocking User Security Code

Select a parameter that need to be edited and press the  button, the upper display will now show 'Security Code'. Use the arrow buttons

to set the security code and press the  button. With the correct security code entered, the display will revert to the parameter selected in edit mode.

If an incorrect security code is entered, the following message 'Incorrect security code' is displayed, then the display will revert to parameter view mode.

#### Disabling User Security

Unlock the previously set security code as detailed above. Set Pr **00.034**

to 0 and press the  button. The User Security has now been disabled, and will not have to be unlocked each time the drive is powered up to allow read / write access to the parameters.

## 5.10 Displaying parameters with non-default values only

By selecting 'Show non-default' in Pr **mm.000** (Alternatively, enter 12000 in Pr **mm.000**), the only parameters that will be visible to the user will be those containing a non-default value. This function does not require a drive reset to become active. In order to deactivate this function, return to Pr **mm.000** and select 'No action' (alternatively enter a value of 0). Please note that this function can be affected by the access level enabled, refer to section 5.9 *Parameter access level and security* on page 46 for further information regarding access level.

## 5.11 Displaying destination parameters only

By selecting 'Destinations' in Pr **mm.000** (Alternatively enter 12001 in Pr **mm.000**), the only parameters that will be visible to the user will be destination parameters. This function does not require a drive reset to become active. In order to deactivate this function, return to Pr **mm.000** and select 'No action' (alternatively enter a value of 0).

Please note that this function can be affected by the access level enabled, refer to section 5.9 *Parameter access level and security* on page 46 for further information regarding access level.

## 5.12 Communications

The *Unidrive M700 / M702* drives offer Ethernet fieldbus communications and the *Unidrive M701* drive offers a 2 wire EIA 485 interface. This enables the drive set-up, operation and monitoring to be carried out with a PC or controller if required.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 5.12.1 Unidrive M700 / M702 - Ethernet communications

The drive offers fieldbus communications via Ethernet, this enables the drive set-up, operation and monitoring to be carried out with a PC or controller. The drive provides two RJ45 connections with an Ethernet switch for easy network creation. The Ethernet option provides support for the following protocols:

- Modbus TCP
- EtherNet/IP or Profinet IO
- Web pages\*
- Email\*\*
- Synchronization with IEEE1588
- RTMoE

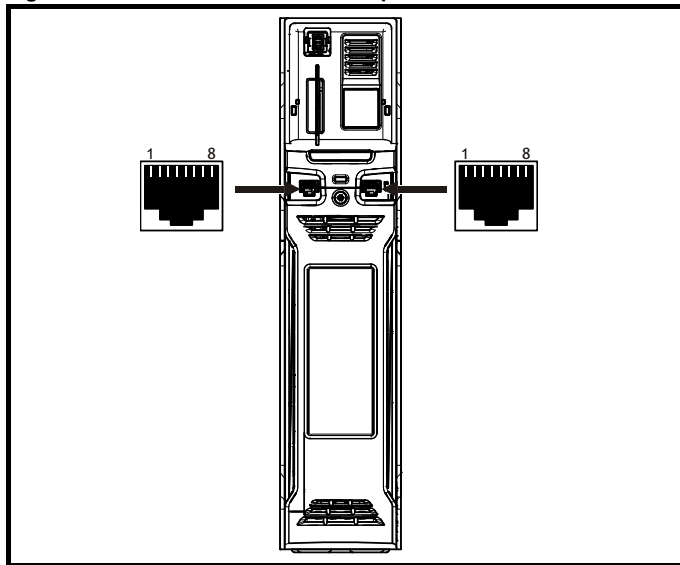
\*Basic Web page functionality only

\*\*Features have not been implemented but will be available soon.

In addition to two RJ45 connectors, each port provides a status LED for diagnostic / information purposes.

| LED status     | Description                                |
|----------------|--------------------------------------------|
| Off            | Ethernet connection not detected           |
| Solid green    | Ethernet connection detected but no data   |
| Flashing green | Ethernet connection detected and data flow |

Figure 5-8 Location of the Ethernet ports



#### NOTE

The shell of the RJ45 connector is isolated from the 0V of the drive control terminals but it is connected to ground.

#### NOTE

Modbus TCP/IP has a maximum number of 4 client connections. Refer to Pr 4.15.006 (Maximum Connections) in the *Parameter Reference Guide*. The default value of Pr 4.15.006 is 2 client connections, but the maximum number of client connections is 10.

#### Recommended cable

It is recommended that a minimum specification of CAT5e is used in new installations. If the existing cabling is used this may limit the maximum data rate depending on the cable ratings. In noisy environments the use of STP cable will offer additional noise immunity.

#### Maximum network lengths

The main restriction imposed on the Ethernet cabling is the length of a single segment of the cable, for Copper - UTP/STP CAT 5 cable type, maximum trunk cable length should be limited to 100 m. If distances greater than this are required it may be possible to extend the network with additional switches.

### Ethernet set-up parameters

This section covers the parameters necessary to establish an Ethernet connection to the drive.

Table 5-9 Key to parameter table coding

|      |                     |      |                     |
|------|---------------------|------|---------------------|
| RW   | Read / Write        | ND   | No default value    |
| RO   | Read only           | NC   | Not copied          |
| Num  | Number parameter    | PT   | Protected parameter |
| Bit  | Bit parameter       | RA   | Rating dependant    |
| Txt  | Text string         | US   | User save           |
| Bin  | Binary parameter    | PS   | Power-down save     |
| FI   | Filtered            | DE   | Destination         |
| IP   | IP Address          | Mac  | Mac Address         |
| Date | Date parameter      | Time | Time parameter      |
| Chr  | Character parameter |      |                     |

|                      |                   |       |  |  |   |         |  |  |    |  |  |
|----------------------|-------------------|-------|--|--|---|---------|--|--|----|--|--|
| 4.00.007<br>{24.007} |                   | Reset |  |  |   |         |  |  |    |  |  |
| RW                   | Bit               |       |  |  |   |         |  |  | US |  |  |
| ⇅                    | Off (0) or On (1) |       |  |  | ⇒ | Off (0) |  |  |    |  |  |

Changes to the Ethernet set-up parameters will not take effect until a *Reset* (4.00.007) has been performed.

|                      |                                       |                   |  |  |  |   |  |  |  |  |    |  |
|----------------------|---------------------------------------|-------------------|--|--|--|---|--|--|--|--|----|--|
| 4.00.010<br>{24.010} |                                       | Active IP Address |  |  |  |   |  |  |  |  |    |  |
| RO                   |                                       | IP                |  |  |  |   |  |  |  |  | US |  |
| ↕                    | 128.000.000.000 to<br>127.255.255.255 |                   |  |  |  | ⇒ |  |  |  |  |    |  |

This parameter displays the Active IP Address. The Active IP Address can also be viewed in Pr 00.037.

|          |                   |             |  |  |  |   |        |  |  |    |  |
|----------|-------------------|-------------|--|--|--|---|--------|--|--|----|--|
| 4.02.005 |                   | DHCP Enable |  |  |  |   |        |  |  |    |  |
| RW       | Bit               |             |  |  |  |   |        |  |  | US |  |
| ↕        | Off (0) or On (1) |             |  |  |  | ⇒ | On (1) |  |  |    |  |

If *DHCP Enable* (4.02.005) is set to On (1), the IP address is acquired from the DHCP server and written to *IP Address* (4.02.006).

#### NOTE

When using manual / static IP address configuration, ensure *Subnet Mask* (4.02.007) and *Default Gateway* (4.02.008) should also be set manually.

#### NOTE

If *Protocol Mode Select* (4.02.018) is set to Profinet (2) and the IP address is assigned to a Profinet Controller, *DHCP Enable* (4.02.005) will be ignored and set to Off (0) on initialisation.

| 4.02.006 |                                       | IP Address |  |  |   |                 |  |    |  |
|----------|---------------------------------------|------------|--|--|---|-----------------|--|----|--|
| RW       | IP                                    |            |  |  |   |                 |  | US |  |
| ↕        | 000.000.000.000 to<br>255.255.255.255 |            |  |  | ⇒ | 192.168.001.100 |  |    |  |

This parameter controls and displays the IP address of the drive. If *DHCP Enable* (4.02.005) is set to On (1) this parameter will become read-only.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| 4.02.007 Subnet Mask |                                    |
|----------------------|------------------------------------|
| RW                   | IP                                 |
| ↑                    | 000.000.000.000 to 255.255.255.255 |
| ⇒                    | 255.255.255.000                    |

This parameter controls and displays the *Subnet Mask* (4.02.007) of the drive.

| 4.02.008 Default Gateway |                                    |
|--------------------------|------------------------------------|
| RW                       | IP                                 |
| ↑                        | 000.000.000.000 to 255.255.255.255 |
| ⇒                        | 192.168.1.254                      |

This parameter controls and displays the *Default Gateway* (4.02.008) of the drive.

### PC Tools support

The discovery protocol feature, which is supported by the Unidrive M PC tools, is able to discover the drives that are connected to a PC, independent of above parameter settings.

## 5.12.2 Unidrive M701 - EIA 485 Serial communications

The EIA 485 option provides two parallel RJ45 connectors allowing easy daisy chaining. The drive only supports Modbus RTU protocol.

The serial communications port of the drive is a RJ45 socket, which is isolated from the power stage and the other control terminals (see section 4.2 *Communication connections* on page 23 for connection and isolation details).

The communications port applies a 2 unit load to the communications network.

### USB/EIA 232 to EIA 485 Communications

An external USB/EIA 232 hardware interface such as a PC cannot be used directly with the 2-wire EIA 485 interface of the drive. Therefore a suitable converter is required.

Suitable USB to EIA 485 and EIA 232 to EIA 485 isolated converters are available from Control Techniques as follows:

- CT USB Comms cable (CT Part No. 4500-0096)
- CT EIA 232 Comms cable (CT Part No. 4500-0087)

#### NOTE

When using the CT EIA 232 Comms cable the available baud rate is limited to 19.2 k baud.

When using one of the above converters or any other suitable converter with the drive, it is recommended that no terminating resistors be connected on the network. It may be necessary to 'link out' the terminating resistor within the converter depending on which type is used. The information on how to link out the terminating resistor will normally be contained in the user information supplied with the converter.

## Serial communications set-up parameters

The following parameters need to be set according to the system requirements.

| Serial communications set-up parameters         |                                                                                                                                                                                                                                                                   |                                                                                                                                                                                                                                                                                                           |
|-------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <i>Serial Mode</i><br>(11.024)<br>{00.035}      | 8 2 NP (0),<br>8 1 NP (1),<br>8 1 EP (2),<br>8 1 OP (3),<br>8 2 NP M (4),<br>8 1 NP M (5),<br>8 1 EP M (6),<br>8 1 OP M (7),<br>7 2 NP (8),<br>7 1 NP (9),<br>7 1 EP (10),<br>7 1 OP (11),<br>7 2 NP M (12),<br>7 1 NP M (13),<br>7 1 EP M (14),<br>7 1 OP M (15) | The drive only supports the Modbus RTU protocol and is always a slave. This parameter defines the supported data formats used by the EIA 485 comms port (if installed) on the drive. This parameter can be changed via the drive keypad, via a option module or via the comms interface itself.           |
| <i>Serial Baud Rate</i><br>(11.025)<br>{00.036} | 300 (0),<br>600 (1),<br>1200 (2),<br>2400 (3),<br>4800 (4),<br>9600 (5),<br>19200 (6),<br>38400 (7),<br>57600(8),<br>76800(9),<br>115200 (10)                                                                                                                     | This parameter can be changed via the drive keypad, via a option module or via the comms interface itself. If it is changed via the comms interface, the response to the command uses the original baud rate. The master should wait at least 20 ms before sending a new message using the new baud rate. |
| <i>Serial Address</i><br>(11.023)<br>{00.037}   | 1 to 247                                                                                                                                                                                                                                                          | This parameter defines the serial address and an addresses between 1 and 247 are permitted.                                                                                                                                                                                                               |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 6 Basic parameters

Menu 0 is used to bring together various commonly used parameters for basic easy set up of the drive. All the parameters in Menu 0 appear in other menus in the drive (denoted by {...}). Menu 22 can be used to configure the parameters in Menu 0.

### 6.1 Parameter ranges and variable minimum / maximums

Some parameters in the drive have a variable range with a variable minimum and a variable maximum value which is dependent on one of the following:

- The settings of other parameters
- The drive rating
- The drive mode
- Combination of any of the above

For more information, refer to section 12.1 *Parameter ranges and Variable minimum/maximums* on page 148

### 6.2 Menu 0: Basic parameters

| Parameter |                                                     |          | Range                                                                                                                                                                               |                                      |       | Default                                                |                                                              |                          | Type |     |    |    |    |    |
|-----------|-----------------------------------------------------|----------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------|-------|--------------------------------------------------------|--------------------------------------------------------------|--------------------------|------|-----|----|----|----|----|
|           |                                                     |          | OL                                                                                                                                                                                  | RFC-A                                | RFC-S | OL                                                     | RFC-A                                                        | RFC-S                    |      |     |    |    |    |    |
| 00.001    | Minimum Reference Clamp                             | {01.007} | VM_NEGATIVE_REF_CLAMP1 Hz / rpm                                                                                                                                                     |                                      |       | 0.0 Hz                                                 | 0.0 rpm                                                      |                          | RW   | Num |    |    |    | US |
| 00.002    | Maximum Reference Clamp                             | {01.006} | VM_POSITIVE_REF_CLAMP1 Hz / rpm                                                                                                                                                     |                                      |       | 50 Hz default:<br>50.0 Hz<br>60 Hz default:<br>60.0 Hz | 50 Hz default:<br>1500.0 rpm<br>60 Hz default:<br>1800.0 rpm | 3000.0 rpm               | RW   | Num |    |    |    | US |
| 00.003    | Acceleration Rate 1                                 | {02.011} | 0.0 to<br>VM_ACCEL_RATE<br>s/100 Hz                                                                                                                                                 | 0.000 to VM_ACCEL_RATE<br>s/1000 rpm |       | 5.0 s/100 Hz                                           | 2.000<br>s/1000 rpm                                          | 0.200<br>s/1000 rpm      | RW   | Num |    |    |    | US |
| 00.004    | Deceleration Rate 1                                 | {02.021} | 0.0 to<br>VM_ACCEL_RATE<br>s/100 Hz                                                                                                                                                 | 0.000 to VM_ACCEL_RATE<br>s/1000 rpm |       | 10.0 s/100 Hz                                          | 2.000<br>s/1000 rpm                                          | 0.200<br>s/1000 rpm      | RW   | Num |    |    |    | US |
| 00.005    | Reference Selector                                  | {01.014} | A1 A2 (0), A1 Preset (1), A2 Preset (2), Preset (3),<br>Keypad (4), Precision (5), Keypad Ref (6)                                                                                   |                                      |       | A1 A2 (0) / Preset (3)***                              |                                                              |                          | RW   | Txt |    |    |    | US |
| 00.006    | Symmetrical Current Limit                           | {04.007} | 0.0 to VM_MOTOR1_CURRENT_LIMIT %                                                                                                                                                    |                                      |       | 165.0 % <sup>1</sup>                                   | 175.0 % <sup>2</sup>                                         |                          | RW   | Num |    | RA |    | US |
| 00.007    | Open-loop Control Mode                              | {05.014} | Ur S (0), Ur (1),<br>Fixed (2),<br>Ur Auto (3), Ur I (4),<br>Square (5)                                                                                                             |                                      |       | Ur I (4)                                               |                                                              |                          | RW   | Txt |    |    |    | US |
|           | Speed Controller Proportional Gain Kp1              | {03.010} |                                                                                                                                                                                     | 0.0000 to 200.000 s/rad              |       |                                                        | 0.0300 s/rad                                                 | 0.0100 s/rad             | RW   | Num |    |    |    | US |
| 00.008    | Low Frequency Voltage Boost                         | {05.015} | 0.0 to 25.0 %                                                                                                                                                                       |                                      |       | 3.0 %                                                  |                                                              |                          | RW   | Num |    |    |    | US |
|           | Speed Controller Integral Gain Ki1                  | {03.011} |                                                                                                                                                                                     | 0.00 to 655.35 s <sup>2</sup> /rad   |       |                                                        | 0.10 s <sup>2</sup> /rad                                     | 1.00 s <sup>2</sup> /rad | RW   | Num |    |    |    | US |
| 00.009    | Dynamic V to F Select                               | {05.013} | Off (0) or On (1)                                                                                                                                                                   |                                      |       | Off (0)                                                |                                                              |                          | RW   | Bit |    |    |    | US |
|           | Speed Controller Differential<br>Feedback Gain Kd 1 | {03.012} |                                                                                                                                                                                     | 0.00000 to 0.65535 1/rad             |       |                                                        | 0.00000 1/rad                                                |                          | RW   | Num |    |    |    | US |
| 00.010    | Motor Rpm                                           | {05.004} | ±180000 rpm                                                                                                                                                                         |                                      |       |                                                        |                                                              |                          | RO   | Bit |    |    |    | US |
|           | Speed Feedback                                      | {03.002} | VM_SPEED rpm                                                                                                                                                                        |                                      | RO    |                                                        |                                                              |                          | Num  | ND  | NC | PT | FI |    |
| 00.011    | Output Frequency                                    | {05.001} | VM_SPEED_FREQ_REF Hz                                                                                                                                                                | ± 2000.0 Hz                          |       |                                                        |                                                              |                          | RO   | Num | ND | NC | PT | FI |
|           | P1 Position                                         | {03.029} | 0 to 65535                                                                                                                                                                          |                                      | RO    |                                                        |                                                              |                          | Num  | ND  | NC | PT | FI |    |
| 00.012    | Current Magnitude                                   | {04.001} | 0.000 to VM_DRIVE_CURRENT_UNIPOLAR A                                                                                                                                                |                                      |       |                                                        |                                                              |                          | RO   | Bit | ND | NC | PT | FI |
| 00.013    | Torque Producing Current                            | {04.002} | VM_DRIVE_CURRENT A                                                                                                                                                                  |                                      |       | RO                                                     | Bit                                                          | ND                       | NC   | PT  | FI |    |    |    |
| 00.014    | Torque Mode Selector                                | {04.011} | 0 or 1                                                                                                                                                                              | 0 to 5                               |       | 0                                                      |                                                              |                          | RW   | Num |    |    |    | US |
| 00.015    | Ramp Mode                                           | {02.004} | Fast (0),<br>Standard (1),<br>Std boost (2)                                                                                                                                         | Fast (0), Standard (1)               |       | Standard (1)                                           |                                                              |                          | RW   | Txt |    |    |    | US |
| 00.016    | Ramp Enable                                         | {02.002} |                                                                                                                                                                                     | Off (0) or On (1)                    |       |                                                        | On (1)                                                       |                          | RW   | Bit |    |    |    | US |
| 00.017    | Digital Input 6 Destination****                     | {08.026} | 00.000 to 59.999                                                                                                                                                                    |                                      |       | 06.031                                                 |                                                              |                          | RW   | Num | DE |    | PT | US |
|           | Current Reference Filter 1 Time Constant            | {04.012} |                                                                                                                                                                                     | 0.0 to 25.0 ms                       |       |                                                        | 0.0 ms                                                       |                          | RW   | Num |    |    |    | US |
| 00.018    | P1 Thermistor Fault Detection                       | {03.123} | None (0), Temperature (1), Temp or Short (2)                                                                                                                                        |                                      |       | None (0)                                               |                                                              |                          | RW   | Txt |    |    |    | US |
| 00.019    | Analog Input 2 Mode****                             | {07.011} | 4-20 mA Low (-4), 20-4 mA Low (-3),<br>4-20 mA Hold (-2), 20-4 mA Hold (-1),<br>0-20 mA (0), 20-0 mA (1), 4-20 mA Trip (2),<br>20-4 mA Trip (3), 4-20 mA (4), 20-4 mA (5), Volt (6) |                                      |       | Volt (6)                                               |                                                              |                          | RW   | Txt |    |    |    | US |
| 00.020    | Analog Input 2 Destination****                      | {07.014} | 00.000 to 59.999                                                                                                                                                                    |                                      |       | 01.037                                                 |                                                              |                          | RW   | Num | DE |    | PT | US |
| 00.021    | Analog Input 3 Mode****                             | {07.015} | M700, M701: Volt (6), Therm Short Cct (7),<br>Thermistor (8), Therm No Trip (9)                                                                                                     |                                      |       | M700, M701: Volt (6)                                   |                                                              |                          | RW   | Txt |    |    |    | US |
|           |                                                     |          | M702: Therm Short Cct (7), Thermistor (8),<br>Therm No Trip (9), Disabled (10)                                                                                                      |                                      |       | M702: Disabled (10)                                    |                                                              |                          |      |     |    |    |    |    |
| 00.022    | Bipolar Reference Enable                            | {01.010} | Off (0) or On (1)                                                                                                                                                                   |                                      |       | Off (0)                                                |                                                              |                          | RW   | Bit |    |    |    | US |
| 00.023    | Jog Reference                                       | {01.005} | 0.0 to 400.0 Hz                                                                                                                                                                     | 0.0 to 4000.0 rpm                    |       | 0.0                                                    |                                                              |                          | RW   | Num |    |    |    | US |
| 00.024    | Preset Reference 1                                  | {01.021} | VM_SPEED_FREQ_REF                                                                                                                                                                   |                                      |       | 0.0                                                    |                                                              |                          | RW   | Num |    |    |    | US |
| 00.025    | Preset Reference 2                                  | {01.022} | VM_SPEED_FREQ_REF                                                                                                                                                                   |                                      |       | 0.0                                                    |                                                              |                          | RW   | Num |    |    |    | US |
| 00.026    | Preset Reference 3                                  | {01.023} | VM_SPEED_FREQ_REF Hz                                                                                                                                                                |                                      |       | 0.0                                                    |                                                              |                          | RW   | Num |    |    |    | US |
|           | Overspeed Threshold                                 | {03.008} |                                                                                                                                                                                     | 0 to 40000 rpm                       |       |                                                        | 0.0                                                          |                          | RW   | Num |    |    |    | US |

| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                      |          | Range                                                                                                                                                                                                                            |                                                                                                                |        | Default                                                                                                                              |                                                                |                    | Type |     |    |    |    |    |
|-----------|--------------------------------------|----------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------|--------|--------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------|--------------------|------|-----|----|----|----|----|
|           |                                      |          | OL                                                                                                                                                                                                                               | RFC-A                                                                                                          | RFC-S  | OL                                                                                                                                   | RFC-A                                                          | RFC-S              |      |     |    |    |    |    |
| 00.027    | Preset Reference 4                   | {01.024} | VM_SPEED_<br>FREQ_REF Hz                                                                                                                                                                                                         |                                                                                                                |        | 0.0                                                                                                                                  |                                                                |                    | RW   | Num |    |    |    | US |
|           | P1 Rotary Lines Per Revolution       | {03.034} |                                                                                                                                                                                                                                  | 1 to 100000                                                                                                    |        |                                                                                                                                      | 1024                                                           | 4096               | RW   | Num |    |    |    | US |
| 00.028    | Enable Auxiliary Key                 | {06.013} | Disabled (0), Forward/Reverse (1), Run Reverse (2)                                                                                                                                                                               |                                                                                                                |        | Disabled (0)                                                                                                                         |                                                                |                    | RW   | Txt |    |    |    | US |
| 00.029    | NV Media Card File Previously Loaded | {11.036} | 0 to 999                                                                                                                                                                                                                         |                                                                                                                |        |                                                                                                                                      |                                                                |                    | RO   | Num |    | NC | PT |    |
| 00.030    | Parameter Cloning                    | {11.042} | None (0), Read (1), Program (2), Auto (3), Boot (4)                                                                                                                                                                              |                                                                                                                |        | None (0)                                                                                                                             |                                                                |                    | RW   | Txt |    | NC |    | US |
| 00.031    | Drive Rated Voltage                  | {11.033} | 200 V (0), 400 V (1), 575 V (2), 690 V (3)                                                                                                                                                                                       |                                                                                                                |        |                                                                                                                                      |                                                                |                    | RO   | Txt | ND | NC | PT |    |
| 00.032    | Maximum Heavy Duty Rating            | {11.032} | 0.000 to 99999.999 A                                                                                                                                                                                                             |                                                                                                                |        |                                                                                                                                      |                                                                |                    | RO   | Num | ND | NC | PT |    |
| 00.033    | Catch A Spinning Motor               | {06.009} | Disable (0),<br>Enable (1),<br>Fwd Only (2),<br>Rev Only (3)                                                                                                                                                                     |                                                                                                                |        | Disable (0)                                                                                                                          |                                                                |                    | RW   | Txt |    |    |    | US |
|           | Rated Speed Optimisation Select      | {05.016} |                                                                                                                                                                                                                                  | Disabled (0),<br>Classic Slow (1),<br>Classic Fast (2),<br>Combined (3),<br>VARs Only (4),<br>Voltage Only (5) |        |                                                                                                                                      | Disabled (0)                                                   |                    | RW   | Txt |    |    |    | US |
| 00.034    | User Security Code                   | {11.030} | 0 to 2 <sup>31</sup> -1                                                                                                                                                                                                          |                                                                                                                |        | 0                                                                                                                                    |                                                                |                    | RW   | Num | ND | NC | PT | US |
| 00.035    | Serial Mode*                         | {11.024} | 8 2 NP (0), 8 1 NP (1), 8 1 EP (2), 8 1 OP (3),<br>8 2 NP M (4), 8 1 NP M (5), 8 1 EP M (6),<br>8 1 OP M (7), 7 2 NP (8), 7 1 NP (9), 7 1 EP (10),<br>7 1 OP (11), 7 2 NP M (12), 7 1 NP M (13),<br>7 1 EP M (14), 7 1 OP M (15) |                                                                                                                |        | 8 2 NP (0)                                                                                                                           |                                                                |                    | RW   | Txt |    |    |    | US |
| 00.036    | Serial Baud Rate*                    | {11.025} | 300 (0), 600 (1), 1200 (2), 2400 (3), 4800 (4),<br>9600 (5), 19200 (6), 38400 (7), 57600 (8),<br>76800 (9), 115200 (10)                                                                                                          |                                                                                                                |        | 19200 (6)                                                                                                                            |                                                                |                    | RW   | Txt |    |    |    | US |
| 00.037    | Serial Address*                      | {11.023} | 1 to 247                                                                                                                                                                                                                         |                                                                                                                |        | 1                                                                                                                                    |                                                                |                    | RW   | Num |    |    |    | US |
|           | Active IP Address**                  | {24.010} | 0.0.0.0 to 255.255.255.255                                                                                                                                                                                                       |                                                                                                                |        |                                                                                                                                      |                                                                |                    | RO   | IP  |    | NC | PT |    |
| 00.038    | Current Controller Kp Gain           | {04.013} | 0 to 30000                                                                                                                                                                                                                       |                                                                                                                |        | 20                                                                                                                                   | 150                                                            |                    | RW   | Num |    |    |    | US |
| 00.039    | Current Controller Ki Gain           | {04.014} | 0 to 30000                                                                                                                                                                                                                       |                                                                                                                |        | 40                                                                                                                                   | 2000                                                           |                    | RW   | Num |    |    |    | US |
| 00.040    | Auto-tune                            | {05.012} | 0 to 2                                                                                                                                                                                                                           | 0 to 5                                                                                                         | 0 to 6 | 0                                                                                                                                    |                                                                |                    | RW   | Num |    | NC |    |    |
| 00.041    | Maximum Switching Frequency          | {05.018} | 2 kHz (0), 3 kHz (1), 4 kHz (2), 6 kHz (3), 8 kHz (4),<br>12 kHz (5), 16 kHz (6)                                                                                                                                                 |                                                                                                                |        | 3 kHz (1)                                                                                                                            |                                                                | 6 kHz (3)          | RW   | Txt |    | RA |    | US |
| 00.042    | Number Of Motor Poles                | {05.011} | Automatic (0) to 480 Poles (240)                                                                                                                                                                                                 |                                                                                                                |        | Automatic (0)                                                                                                                        |                                                                | 6 Poles (3)        | RW   | Num |    |    |    | US |
| 00.043    | Rated Power Factor*****              | {05.010} | 0.000 to 1.000                                                                                                                                                                                                                   |                                                                                                                |        | 0.850                                                                                                                                |                                                                |                    | RW   | Num |    | RA |    | US |
|           | Position Feedback Phase Angle        | {03.025} |                                                                                                                                                                                                                                  |                                                                                                                |        | 0.0 to 359.9 °                                                                                                                       |                                                                | 0.0 °              | RW   | Num | ND |    |    | US |
| 00.044    | Rated Voltage                        | {05.009} | 0 to VM_AC_VOLTAGE_SET V                                                                                                                                                                                                         |                                                                                                                |        | 200 V drive: 230 V<br>50 Hz default 400V drive: 400 V<br>60 Hz default 400V drive: 460 V<br>575 V drive: 575 V<br>690 V drive: 690 V |                                                                |                    | RW   | Num |    | RA |    | US |
| 00.045    | Rated Speed                          | {05.008} | 0 to<br>35940 rpm                                                                                                                                                                                                                | 0.00 to 33000.00 rpm                                                                                           |        | 50 Hz default:<br>1500 rpm<br>60 Hz default:<br>1800rpm                                                                              | 50 Hz default:<br>1450.00 rpm<br>60 Hz default:<br>1750.00 rpm | 3000.00 rpm        | RW   | Num |    |    |    | US |
| 00.046    | Rated Current                        | {05.007} | 0.000 to VM_RATED_CURRENT A                                                                                                                                                                                                      |                                                                                                                |        | Maximum Heavy Duty Rating (11.032)                                                                                                   |                                                                |                    | RW   | Num |    | RA |    | US |
| 00.047    | Rated Frequency                      | {05.006} | 0.0 to 599.0 Hz                                                                                                                                                                                                                  | 0.0 to 550.0 Hz                                                                                                |        | 50Hz: 50.0<br>60Hz: 60.0                                                                                                             |                                                                |                    | RW   | Num |    |    |    | US |
|           | Volts per 1000 rpm                   | {05.033} |                                                                                                                                                                                                                                  |                                                                                                                |        |                                                                                                                                      |                                                                | 98 V /<br>1000 rpm | RW   | Num |    |    |    | US |
| 00.048    | User Drive Mode                      | {11.031} | Open-loop (1), RFC-A (2), RFC-S (3), Regen (4)                                                                                                                                                                                   |                                                                                                                |        | Open-loop (1)                                                                                                                        | RFC-A (2)                                                      | RFC-S (3)          | RW   | Txt | ND | NC | PT |    |
| 00.049    | User Security Status                 | {11.044} | Menu 0 (0), All Menus (1), Read-only Menu 0 (2),<br>Read-only (3), Status Only (4), No Access (5)                                                                                                                                |                                                                                                                |        | Menu 0 (0)                                                                                                                           |                                                                |                    | RW   | Txt | ND |    | PT |    |
| 00.050    | Software Version                     | {11.029} | 0 to 999999999                                                                                                                                                                                                                   |                                                                                                                |        |                                                                                                                                      |                                                                |                    | RO   | Num | ND | NC | PT |    |
| 00.051    | Action On Trip Detection             | {10.037} | 0 to 31                                                                                                                                                                                                                          |                                                                                                                |        | 0                                                                                                                                    |                                                                |                    | RW   | Bin |    |    |    | US |
| 00.052    | Reset Serial Communications*         | {11.020} | Off (0) or On (1)                                                                                                                                                                                                                |                                                                                                                |        | Off (0)                                                                                                                              |                                                                |                    | RW   | Bit | ND | NC |    |    |
| 00.053    | Motor Thermal Time Constant 1        | {04.015} | 1.0 to 3000.0 s                                                                                                                                                                                                                  |                                                                                                                |        | 89.0 s                                                                                                                               |                                                                |                    | RW   | Num |    |    |    | US |

\* Only applicable to Unidrive M701.

\*\* Only applicable to Unidrive M700 / M702.

\*\*\* Only applicable to Unidrive M702.

\*\*\*\* Only applicable to Unidrive M700 / M701.

\*\*\*\*\* Following a rotating autotune Pr 00.043 {05.010} is continuously written by the drive, calculated from the value of Stator Inductance (Pr 05.025). To manually enter a value into Pr 00.043 {05.010}, Pr 05.025 will need to be set to 0. Please refer to the description of Pr 05.010 in the *Parameter Reference Guide* for further details.

1 For size 9 and above the default is 141.9 %.

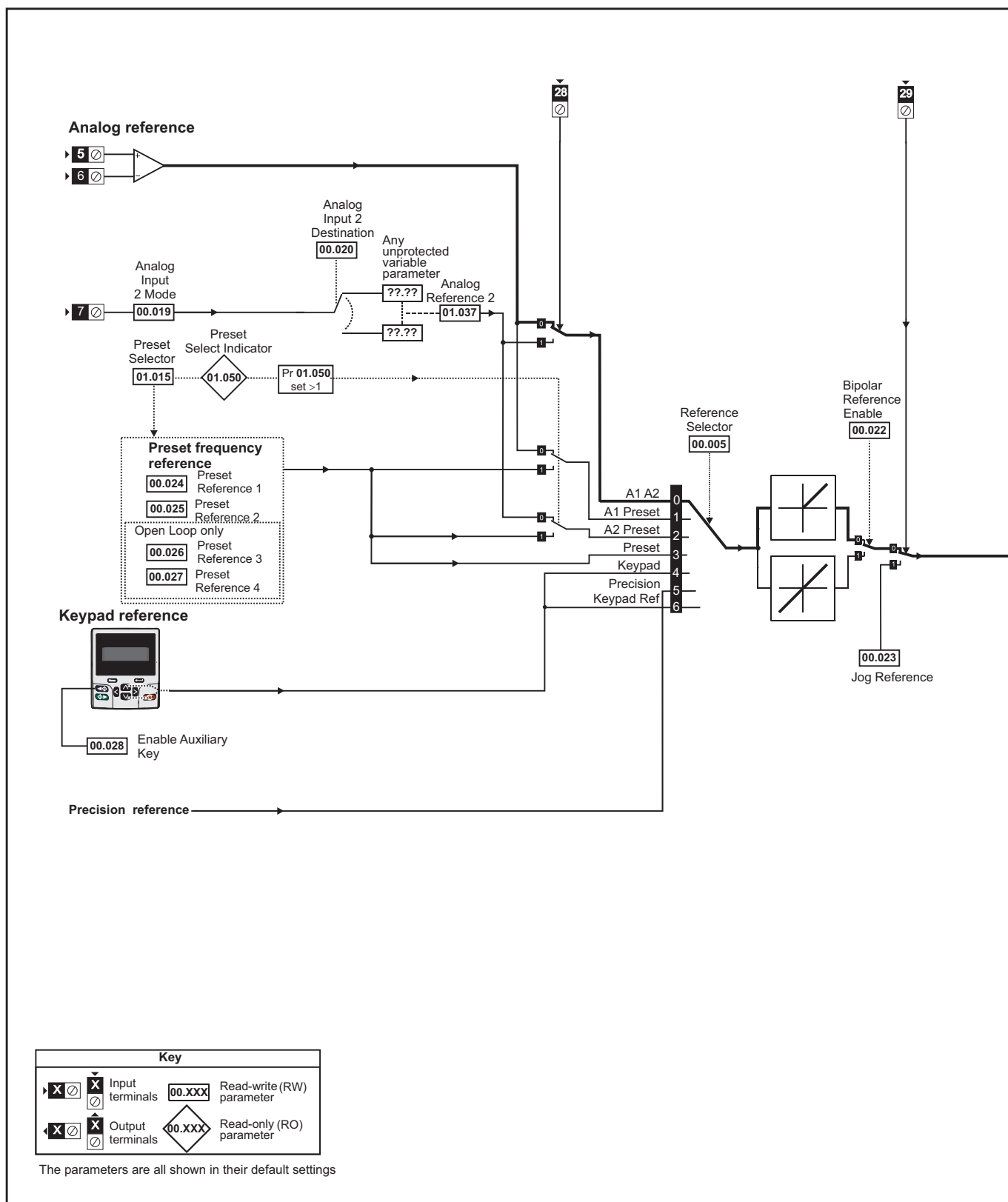
2 For size 9 and above the default is 150.0 %.

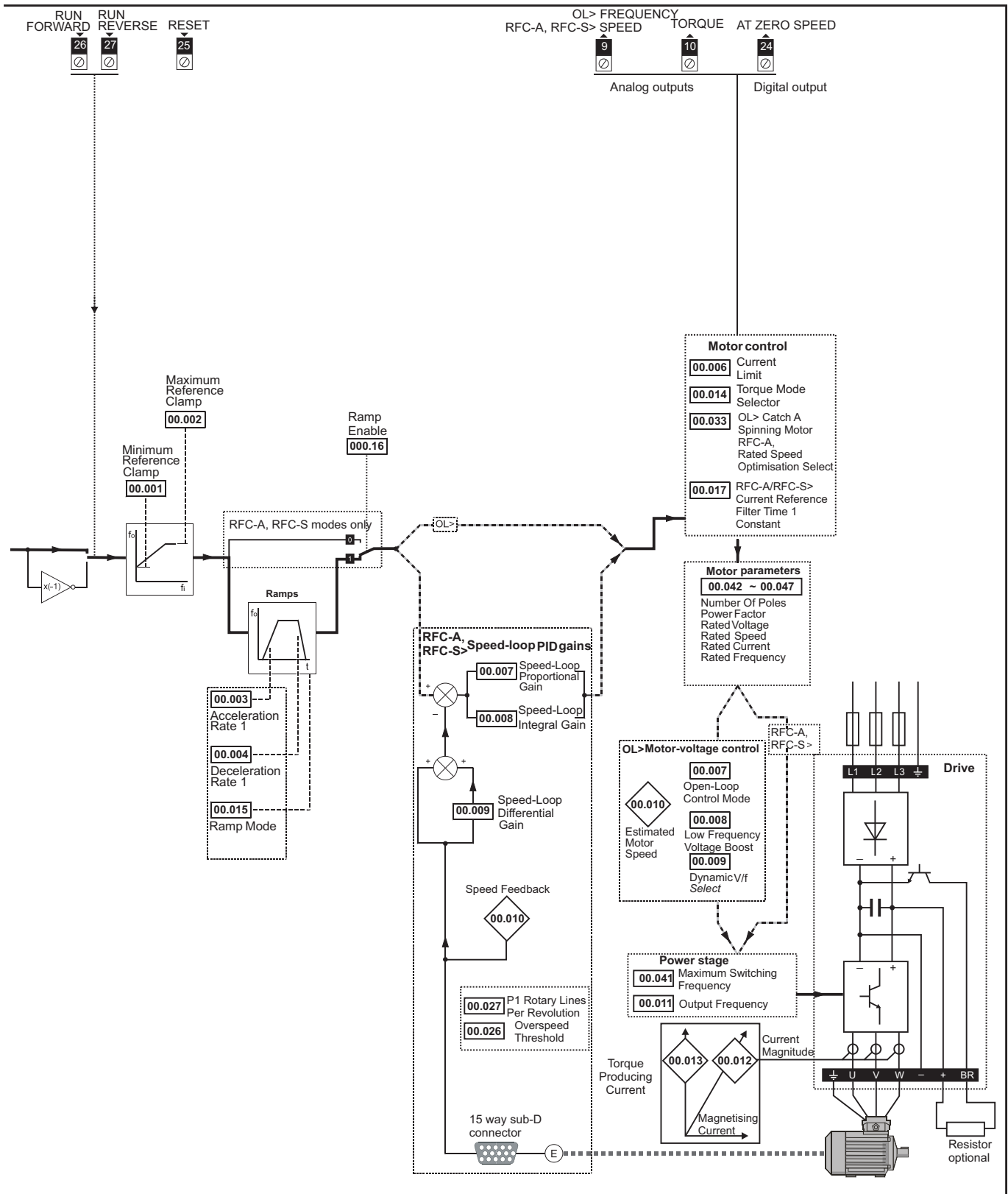
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|-------------|-----|------------------|----|-------------|
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   |     |             |     |                  |    |             |

|                       |                        |                            |                            |                    |                             |                      |              |                        |                            |                |                        |             |                   |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|-----------------------------|----------------------|--------------|------------------------|----------------------------|----------------|------------------------|-------------|-------------------|
| Safety<br>information | Product<br>information | Mechanical<br>installation | Electrical<br>installation | Getting<br>started | <b>Basic<br/>parameters</b> | Running<br>the motor | Optimization | Drive<br>communication | NV Media Card<br>Operation | Onboard<br>PLC | Advanced<br>parameters | Diagnostics | UL<br>information |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|-----------------------------|----------------------|--------------|------------------------|----------------------------|----------------|------------------------|-------------|-------------------|

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

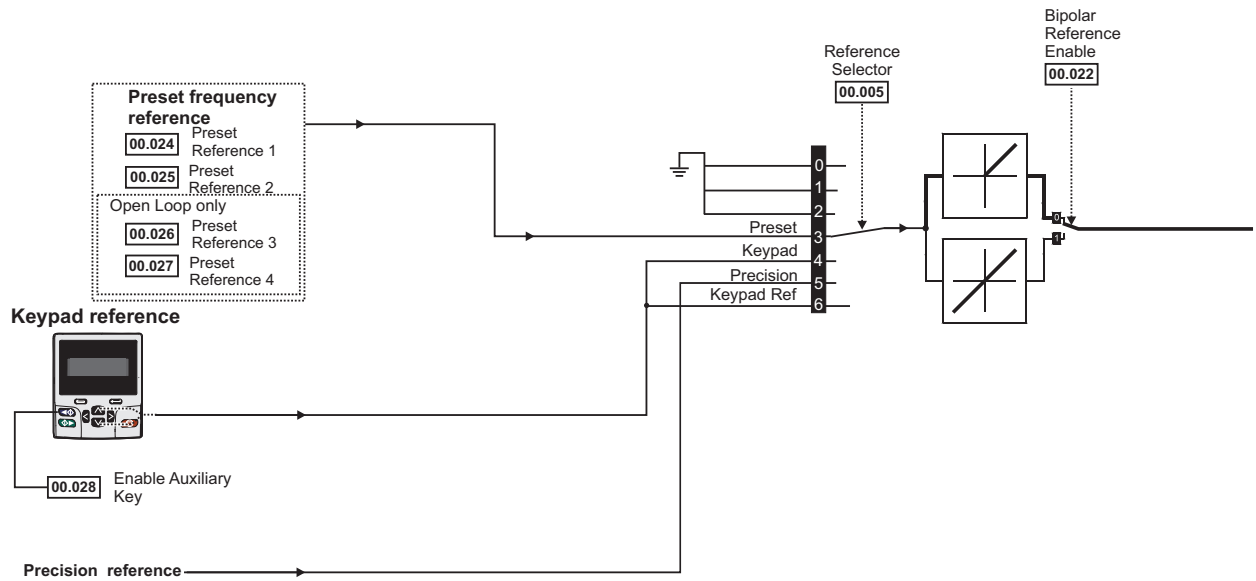
Figure 6-1 Menu 0 logic diagram (Unidrive M700 / 701)





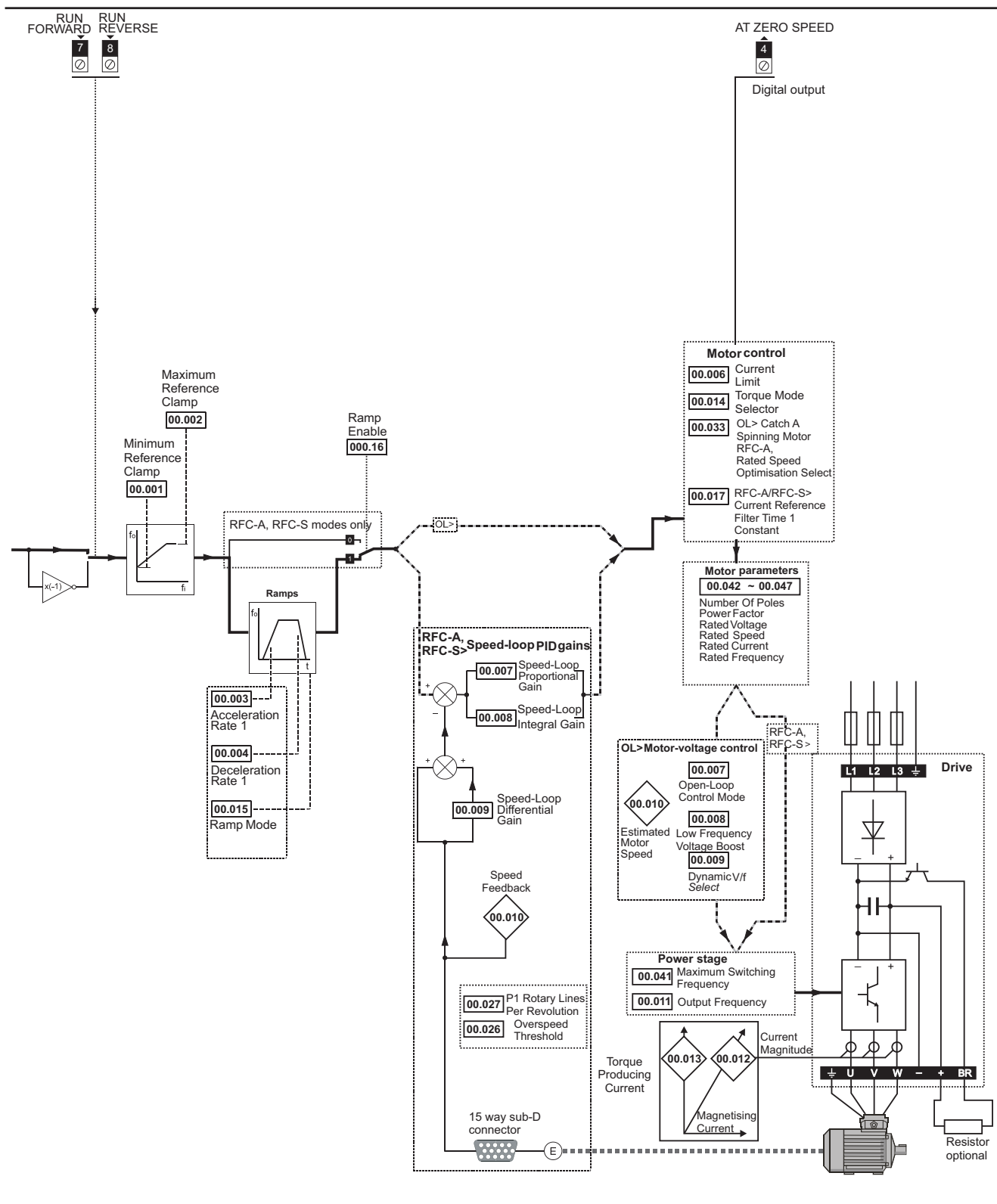
|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 6-2 Menu 0 logic diagram (Unidrive M702)



| Key |  |        |                           |
|-----|--|--------|---------------------------|
|     |  | 00.XXX | Read-write (RW) parameter |
|     |  | 00.XXX | Read-only (RO) parameter  |

The parameters are all shown in their default settings



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 6.3 Parameter descriptions

### 6.3.1 Pr mm.000

Pr mm.000 is available in all menus, commonly used functions are provided as text strings in Pr mm.000 shown in Table 6-1. The functions in Table 6-1 can also be selected by entering the appropriate numeric values (as shown in Table 6-2) in Pr mm.000. For example, enter 4001 in Pr mm.000 to store drive parameters on an NV Media Card.

**Table 6-1 Commonly used functions in xx.000**

| Value | Equivalent value | String             | Action                                                                          |
|-------|------------------|--------------------|---------------------------------------------------------------------------------|
| 0     | 0                | [No Action]        |                                                                                 |
| 1001  | 1                | [Save parameters]  | Save parameters under all conditions                                            |
| 6001  | 2                | [Load file 1]      | Load the drive parameters or user program file from NV Media Card file 001      |
| 4001  | 3                | [Save to file 1]   | Transfer the drive parameters to parameter file 001                             |
| 6002  | 4                | [Load file 2]      | Load the drive parameters or user program file from NV Media Card file 002      |
| 4002  | 5                | [Save to file 2]   | Transfer the drive parameters to parameter file 002                             |
| 6003  | 6                | [Load file 3]      | Load the drive parameters or user program file from NV Media Card file 003      |
| 4003  | 7                | [Save to file 3]   | Transfer the drive parameters to parameter file 003                             |
| 12000 | 8                | [Show non-default] | Displays parameters that are different from defaults                            |
| 12001 | 9                | [Destinations]     | Displays parameters that are set                                                |
| 1233  | 10               | [Reset 50Hz defs]  | Load parameters with standard (50 Hz) defaults                                  |
| 1244  | 11               | [Reset 60Hz defs]  | Load parameters with US (60 Hz) defaults                                        |
| 1070  | 12               | [Reset modules]    | Reset all option modules                                                        |
| 11001 | 13               | [Read enc. NP P1]  | Transfer electronic nameplate motor parameters to the drive from the P1 encoder |
| 11051 | 14               | [Read enc. NP P2]  | Transfer electronic nameplate motor parameters to the drive from the P2 encoder |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Table 6-2 Functions in Pr mm.000**

| Value   | Action                                                                                                                                                                        |
|---------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1000    | Save parameters when <i>Under Voltage Active</i> (Pr <b>10.016</b> ) is not active and <i>Low Under Voltage Threshold Select</i> mode (Pr <b>06.067</b> = Off) is not active. |
| 1001    | Save parameters under all conditions                                                                                                                                          |
| 1070    | Reset all option modules                                                                                                                                                      |
| 1233    | Load standard (50 Hz) defaults                                                                                                                                                |
| 1234    | Load standard (50 Hz) defaults to all menus except option module menus (i.e 15 to 20 and 24 to 28)                                                                            |
| 1244    | Load US (60 Hz) defaults                                                                                                                                                      |
| 1245    | Load US (60 Hz) defaults to all menus except option module menus (i.e 15 to 20 and 24 to 28)                                                                                  |
| 1253    | Change drive mode and load standard (50 Hz) defaults                                                                                                                          |
| 1254    | Change drive mode and load US (60 Hz) defaults                                                                                                                                |
| 1255    | Change drive mode and load standard (50 Hz) defaults except for menus 15 to 20 and 24 to 28                                                                                   |
| 1256    | Change drive mode and load US (60 Hz) defaults except for menus 15 to 20 and 24 to 28                                                                                         |
| 1299    | Reset {Stored HF} trip.                                                                                                                                                       |
| 2001*   | Create a boot file on a non-volatile media card based on the present drive parameters including all Menu 20 parameters                                                        |
| 4yyy*   | NV media card: Transfer the drive parameters to parameter file xxx                                                                                                            |
| 5yyy*   | NV media card: Transfer the onboard user program to onboard user program file xxx                                                                                             |
| 6yyy*   | NV media card: Load the drive parameters from parameter file xxx or the onboard user program from onboard user program file xxx                                               |
| 7yyy*   | NV media card: Erase file xxx                                                                                                                                                 |
| 8yyy*   | NV Media card: Compare the data in the drive with file xxx                                                                                                                    |
| 9555*   | NV media card: Clear the warning suppression flag                                                                                                                             |
| 9666*   | NV media card: Set the warning suppression flag                                                                                                                               |
| 9777*   | NV media card: Clear the read-only flag                                                                                                                                       |
| 9888*   | NV media card: Set the read-only flag                                                                                                                                         |
| 9999*   | NV media card: Erase and format the NV media card                                                                                                                             |
| 59999   | Delete onboard user program                                                                                                                                                   |
| 110S1   | Transfer electronic nameplate data from an encoder connected to the P1 position feedback interface on the drive or option module in slot 'S' into drive parameters.           |
| 110S2   | As 110S1, but for the P2 position feedback interface                                                                                                                          |
| 12000** | Only display parameters that are different from their default value. This action does not require a drive reset.                                                              |
| 12001** | Only display parameters that are used to set-up destinations (i.e. DE format bit is 1). This action does not require a drive reset.                                           |
| 15xxx*  | Transfer the user program in an option module installed in slot 1 to a non-volatile media card file xxx                                                                       |
| 16xxx*  | Transfer the user program in an option module installed in slot 2 to a non-volatile media card file xxx                                                                       |
| 17xxx*  | Transfer the user program in an option module installed in slot 3 to a non-volatile media card file xxx                                                                       |
| 18xxx*  | Transfer the user program from file xxx in a non-volatile media card to an option module installed in slot 1.                                                                 |
| 19xxx*  | Transfer the user program from file xxx in a non-volatile media card to an option module installed in slot 2.                                                                 |
| 20xxx*  | Transfer the user program from file xxx in a non-volatile media card to an option module installed in slot 3.                                                                 |
| 21xxx*  | Transfer the user program in an option module installed in slot 4 to a non-volatile media card file xxx.                                                                      |
| 22xxx*  | Transfer the user program from file xxx in a non-volatile media card to an option module installed in slot 4.                                                                 |

\* See Chapter 10 *NV Media Card Operation* on page 139 for more information on these functions.

\*\* These functions do not require a drive reset to become active. All other functions require a drive reset to initiate the function. Equivalent values and strings are also provided in the table above.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 6.4 Full descriptions

Table 6-3 Key to parameter table coding

| Coding | Attribute                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |
|--------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| RW     | Read/Write: can be written by the user                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
| RO     | Read only: can only be read by the user                                                                                                                                                                                                                                                                                                                                                                                                                                                           |
| Bit    | 1 bit parameter. 'On' or 'Off' on the display                                                                                                                                                                                                                                                                                                                                                                                                                                                     |
| Num    | Number: can be uni-polar or bi-polar                                                                                                                                                                                                                                                                                                                                                                                                                                                              |
| Txt    | Text: the parameter uses text strings instead of numbers.                                                                                                                                                                                                                                                                                                                                                                                                                                         |
| Bin    | Binary parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
| IP     | IP Address parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |
| Mac    | Mac Address parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
| Date   | Date parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
| Time   | Time parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
| Chr    | Character parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
| FI     | Filtered: some parameters which can have rapidly changing values are filtered when displayed on the drive keypad for easy viewing.                                                                                                                                                                                                                                                                                                                                                                |
| DE     | Destination: This parameter selects the destination of an input or logic function.                                                                                                                                                                                                                                                                                                                                                                                                                |
| RA     | Rating dependent: this parameter is likely to have different values and ranges with drives of different voltage and current ratings. Parameters with this attribute will be transferred to the destination drive by non-volatile storage media when the rating of the destination drive is different from the source drive and the file is a parameter file. However, the values will be transferred if only the current rating is different and the file is a difference from default type file. |
| ND     | No default: The parameter is not modified when defaults are loaded                                                                                                                                                                                                                                                                                                                                                                                                                                |
| NC     | Not copied: not transferred to or from non-volatile media during copying.                                                                                                                                                                                                                                                                                                                                                                                                                         |
| PT     | Protected: cannot be used as a destination.                                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| US     | User save: parameter saved in drive EEPROM when the user initiates a parameter save.                                                                                                                                                                                                                                                                                                                                                                                                              |
| PS     | Power-down save: parameter automatically saved in drive EEPROM when the under volts (UV) state occurs.                                                                                                                                                                                                                                                                                                                                                                                            |

### 6.4.1 Parameter x.00

| 00.000<br>{mm.000} |             | Parameter zero |  |  |    |    |    |  |  |
|--------------------|-------------|----------------|--|--|----|----|----|--|--|
| RW                 | Num         |                |  |  | ND | NC | PT |  |  |
| ↕                  | 0 to 65,535 |                |  |  | ⇒  |    |    |  |  |

### 6.4.2 Speed limits

| 00.001 {01.007} |   | Minimum Reference Clamp          |  |  |  |   |         |  |    |
|-----------------|---|----------------------------------|--|--|--|---|---------|--|----|
| RW              |   | Num                              |  |  |  |   |         |  | US |
| OL              | ↕ | VM_NEGATIVE_REF_ CLAMP1 Hz / rpm |  |  |  | ⇒ | 0.0 Hz  |  |    |
| RFC-A           |   |                                  |  |  |  |   | 0.0 rpm |  |    |
| RFC-S           |   |                                  |  |  |  |   |         |  |    |

(When the drive is jogging, [00.001] has no effect.)

#### Open-loop

Set Pr **00.001** at the required minimum output frequency of the drive for both directions of rotation. The drive speed reference is scaled between Pr **00.001** and Pr **00.002**. [00.001] is a nominal value; slip compensation may cause the actual frequency to be higher.

#### RFC-A / RFC-S

Set Pr **00.001** at the required minimum motor speed for both directions of rotation. The drive speed reference is scaled between Pr **00.001** and Pr **00.002**.

| 00.002 {01.006} |   | Maximum Reference Clamp          |  |  |  |  |   |                                                    |  |    |  |
|-----------------|---|----------------------------------|--|--|--|--|---|----------------------------------------------------|--|----|--|
| RW              |   | Num                              |  |  |  |  |   |                                                    |  | US |  |
| OL              | ↕ | VM_POSITIVE_REF_ CLAMP1 Hz / rpm |  |  |  |  | ⇒ | 50Hz default: 50.0 Hz<br>60Hz default: 60.0 Hz     |  |    |  |
| RFC-A           |   |                                  |  |  |  |  |   | 50Hz default:1500.0 rpm<br>60Hz default:1800.0 rpm |  |    |  |
| RFC-S           |   |                                  |  |  |  |  |   | 3000.0 rpm                                         |  |    |  |

(The drive has additional over-speed protection).

#### Open-loop

Set Pr **00.002** at the required maximum output frequency for both directions of rotation. The drive speed reference is scaled between Pr **00.001** and Pr **00.002**. [00.002] is a nominal value; slip compensation may cause the actual frequency to be higher.

#### RFC-A / RFC-S

Set Pr **00.002** at the required maximum motor speed for both directions of rotation. The drive speed reference is scaled between Pr **00.001** and Pr **00.002**.

For operating at high speeds see section 8.6 *High speed operation* on page 109.

### 6.4.3 Ramps, speed reference selection, current limit

| 00.003 {02.011} |   | Acceleration Rate 1                     |  |  |   |                  |  |    |
|-----------------|---|-----------------------------------------|--|--|---|------------------|--|----|
| RW              |   | Num                                     |  |  |   |                  |  | US |
| OL              | ⇕ | 0.0 to VM_ACCEL_RATE<br>s/100 Hz        |  |  | ⇒ | 5.0 s/100 Hz     |  |    |
| RFC-A           |   | 0.000 to<br>VM_ACCEL_RATE<br>s/1000 rpm |  |  |   | 2.000 s/1000 rpm |  |    |
| RFC-S           |   |                                         |  |  |   | 0.200 s/1000 rpm |  |    |

Set Pr **00.003** at the required rate of acceleration.

Note that larger values produce lower acceleration. The rate applies in both directions of rotation.

| 00.004 {02.021} |   | Deceleration Rate 1                     |  |  |  |   |                  |  |    |
|-----------------|---|-----------------------------------------|--|--|--|---|------------------|--|----|
| RW              |   | Num                                     |  |  |  |   |                  |  | US |
| OL              | ↕ | 0.0 to VM_ACCEL_RATE<br>s/100 Hz        |  |  |  | ⇒ | 10.0 s/100 Hz    |  |    |
| RFC-A           |   | 0.000 to<br>VM_ACCEL_RATE<br>s/1000 rpm |  |  |  |   | 2.000 s/1000 rpm |  |    |
| RFC-S           |   |                                         |  |  |  |   | 0.200 s/1000 rpm |  |    |

Set Pr **00.004** at the required rate of deceleration.

Note that larger values produce lower deceleration. The rate applies in both directions of rotation.

| 00.005 {01.014} |   | Reference Selector                                                                                               |  |  |  |  |   |                                            |  |    |  |
|-----------------|---|------------------------------------------------------------------------------------------------------------------|--|--|--|--|---|--------------------------------------------|--|----|--|
| RW              |   | Txt                                                                                                              |  |  |  |  |   |                                            |  | US |  |
| OL              | ↕ | A1 A2 (0)*,<br>A1 Preset (1)*,<br>A2 Preset (2)*,<br>Preset (3), Keypad (4),<br>Precision (5),<br>Keypad Ref (6) |  |  |  |  | ⇒ | M700 / M701: A1 A2 (0)<br>M702: Preset (3) |  |    |  |
| RFC-A           |   |                                                                                                                  |  |  |  |  |   |                                            |  |    |  |
| RFC-S           |   |                                                                                                                  |  |  |  |  |   |                                            |  |    |  |

\* Available on *Unidrive M700 / M701* only.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Use Pr **00.005** to select the required frequency/speed reference as follows:

| Setting        | Description                                                                 |
|----------------|-----------------------------------------------------------------------------|
| A1 A2*         | 0 Analog input 1 OR analog input 2 selectable by digital input, terminal 28 |
| A1 Preset*     | 1 Analog input 1 OR preset frequency/speed                                  |
| A2 Preset*     | 2 Analog input 2 OR preset frequency/speed                                  |
| Preset (3)     | 3 Pre-set frequency/speed                                                   |
| Keypad (4)     | 4 Keypad mode                                                               |
| Precision (5)  | 5 Precision reference                                                       |
| Keypad Ref (6) | 6 Keypad Reference                                                          |

\* Available on Unidrive M700 / M701 only.

| 00.006 {04.007} |   | Symmetrical Current Limit         |  |  |  |   |         |  |    |
|-----------------|---|-----------------------------------|--|--|--|---|---------|--|----|
| RW              |   | Num                               |  |  |  |   |         |  | US |
| OL              | ⇕ | 0.0 to VM_MOTOR1_ CURRENT_LIMIT % |  |  |  | ⇒ | 165.0 % |  |    |
| RFC-A           |   |                                   |  |  |  |   |         |  |    |
| RFC-S           |   |                                   |  |  |  |   | 175.0 % |  |    |

Pr **00.006** limits the maximum output current of the drive (and hence maximum motor torque) to protect the drive and motor from overload.

Set Pr **00.006** at the required maximum torque as a percentage of the rated torque of the motor, as follows:

$$[00.006] = \frac{T_R}{T_{RATED}} \times 100 (\%)$$

Where:

$T_R$  Required maximum torque  
 $T_{RATED}$  Motor rated torque

Alternatively, set Pr **00.006** at the required maximum active (torque-producing) current as a percentage of the rated active current of the motor, as follows:

$$[00.006] = \frac{I_R}{I_{RATED}} \times 100 (\%)$$

Where:

$I_R$  Required maximum active current  
 $I_{RATED}$  Motor rated active current

#### 6.4.4 Voltage boost, (open-loop), Speed-loop PID gains (RFC-A / RFC-S)

| 00.007 {05.014} |   | Open-loop Control Mode (OL)                                          |  |  |  |   |              |  |    |  |
|-----------------|---|----------------------------------------------------------------------|--|--|--|---|--------------|--|----|--|
| 00.007 {03.010} |   | Speed Controller Proportional Gain Kp1 (RFC)                         |  |  |  |   |              |  |    |  |
| RW              |   | Txt / Num                                                            |  |  |  |   |              |  | US |  |
| OL              | ⇅ | Ur S (0), Ur (1),<br>Fixed (2), Ur Auto (3),<br>Ur I (4), Square (5) |  |  |  | ⇒ | Ur I (4)     |  |    |  |
| RFC-A           | ⇅ | 0.0000 to 200.000 s/rad                                              |  |  |  | ⇒ | 0.0300 s/rad |  |    |  |
| RFC-S           |   |                                                                      |  |  |  |   | 0.0100 s/rad |  |    |  |

##### Open-loop

There are six voltage modes available, which fall into two categories, vector control and fixed boost. For further details, refer to Pr **00.007 {05.014} Open Loop Control Mode** on page 96.

##### RFC-A/ RFC-S

Pr **00.007 (03.010)** operates in the feed-forward path of the speed-control loop in the drive. See Figure 12-4 on page 166 for a schematic of the speed controller. For information on setting up the speed controller gains, refer to Chapter 8 *Optimization* on page 95.

| 00.008 {05.015} |   | Low Frequency Voltage Boost (OL)         |  |  |   |                          |  |  |    |
|-----------------|---|------------------------------------------|--|--|---|--------------------------|--|--|----|
| 00.008 {03.011} |   | Speed Controller Integral Gain Ki1 (RFC) |  |  |   |                          |  |  |    |
| RW              |   | Num                                      |  |  |   |                          |  |  | US |
| OL              | ⇅ | 0.0 to 25.0 %                            |  |  | ⇒ | 3.0 %                    |  |  |    |
| RFC-A           | ⇅ | 0.00 to 655.35 s <sup>2</sup> /rad       |  |  | ⇒ | 0.10 s <sup>2</sup> /rad |  |  |    |
| RFC-S           |   |                                          |  |  |   | 1.00 s <sup>2</sup> /rad |  |  |    |

##### Open-loop

When *Open-loop Control Mode* (00.007) is set at **Fd** or **SrE**, set Pr **00.008 (05.015)** at the required value for the motor to run reliably at low speeds.

Excessive values of Pr **00.008** can cause the motor to be overheated.

##### RFC-A/ RFC-S

Pr **00.008 (03.011)** operates in the feed-forward path of the speed-control loop in the drive. See Figure 12-4 on page 166 for a schematic of the speed controller. For information on setting up the speed controller gains, refer to Chapter 8 *Optimization* on page 95.

|                 |   |                                                        |  |  |  |   |               |  |    |  |  |
|-----------------|---|--------------------------------------------------------|--|--|--|---|---------------|--|----|--|--|
| 00.009 {05.013} |   | Dynamic V to F Select (OL)                             |  |  |  |   |               |  |    |  |  |
| 00.009 {03.012} |   | Speed Controller Differential Feedback Gain Kd 1 (RFC) |  |  |  |   |               |  |    |  |  |
| RW              |   | Bit                                                    |  |  |  |   |               |  | US |  |  |
| OL              | ↕ | Off (0) or On (1)                                      |  |  |  | ⇒ | Off (0)       |  |    |  |  |
| RFC-A           | ↕ | 0.00000 to 0.65535 1/rad                               |  |  |  | ⇒ | 0.00000 1/rad |  |    |  |  |
| RFC-S           |   |                                                        |  |  |  |   |               |  |    |  |  |

##### Open-loop

Set Pr **00.009 (05.013)** at 0 when the V/f characteristic applied to the motor is to be fixed. It is then based on the rated voltage and frequency of the motor.

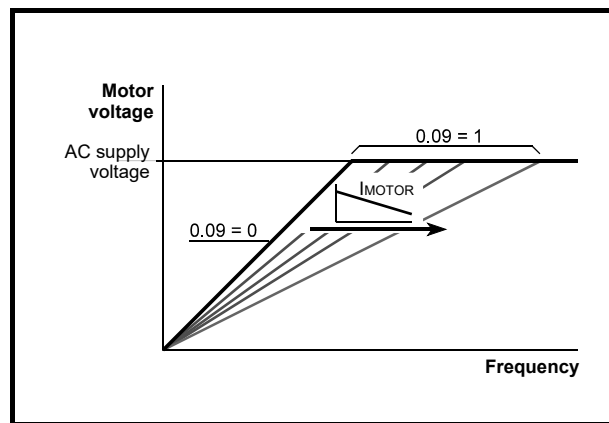
Set Pr **00.009** at 1 when reduced power dissipation is required in the motor when it is lightly loaded. The V/f characteristic is then variable resulting in the motor voltage being proportionally reduced for lower motor currents. Figure 6-3 shows the change in V/f slope when the motor current is reduced.

##### RFC-A / RFC-S

Pr **00.009 (03.012)** operates in the feedback path of the speed-control loop in the drive. See Figure 12-4 *Menu 3 RFC-A, RFC-S logic diagram* on page 166 for a schematic of the speed controller. For information on setting up the speed controller gains, refer to Chapter 8 *Optimization* on page 95.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 6-3 Fixed and variable V/f characteristics



### 6.4.5 Monitoring

| 00.010 {05.004} Motor Rpm |     |             |   |  |  |  |  |    |  |
|---------------------------|-----|-------------|---|--|--|--|--|----|--|
| RO                        | Bit |             |   |  |  |  |  | US |  |
| OL                        | ↕   | ±180000 rpm | ⇒ |  |  |  |  |    |  |

#### Open-loop

Pr **00.010 (05.004)** indicates the value of motor speed that is estimated from the following:

**02.001** Post Ramp Reference

**00.042** Number Of Motor Poles

| 00.010 {03.002} Speed Feedback |     |              |   |  |    |    |    |  |  |
|--------------------------------|-----|--------------|---|--|----|----|----|--|--|
| RO                             | Num | FI           |   |  | ND | NC | PT |  |  |
| RFC-A                          | ↕   | VM_SPEED rpm | ⇒ |  |    |    |    |  |  |
| RFC-S                          |     |              |   |  |    |    |    |  |  |

#### RFC-A / RFC-S

Pr **00.010 (03.002)** indicates the value of motor speed that is obtained from the speed feedback.

| 00.011 {05.001} Output Frequency (OL) |     |                      |   |  |    |    |    |  |  |
|---------------------------------------|-----|----------------------|---|--|----|----|----|--|--|
| 00.011 {03.029} P1 Position (RFC)     |     |                      |   |  |    |    |    |  |  |
| RO                                    | Num | FI                   |   |  | ND | NC | PT |  |  |
| OL                                    | ↕   | VM_SPEED_FREQ_REF Hz | ⇒ |  |    |    |    |  |  |
| RFC-A                                 |     |                      |   |  |    |    |    |  |  |
| RFC-S                                 | ↕   | 0 to 65535           | ⇒ |  |    |    |    |  |  |

#### Open-loop and RFC-A

Pr **00.011** displays the frequency at the drive output.

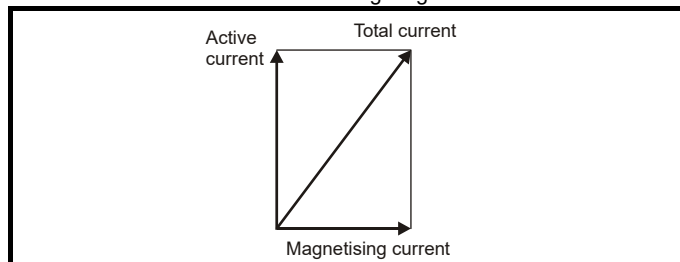
#### RFC-S

Pr **00.011** displays the position of the encoder in mechanical values of 0 to 65,535. There are 65,536 units to one mechanical revolution.

| 00.012 {04.001} Current Magnitude |     |                             |   |  |    |    |    |  |  |
|-----------------------------------|-----|-----------------------------|---|--|----|----|----|--|--|
| RO                                | Bit | FI                          |   |  | ND | NC | PT |  |  |
| OL                                |     | 0.000 to                    |   |  |    |    |    |  |  |
| RFC-A                             | ↕   | VM_DRIVE_CURRENT_UNIPOLAR A | ⇒ |  |    |    |    |  |  |
| RFC-S                             |     |                             |   |  |    |    |    |  |  |

Pr **00.012** displays the rms value of the output current of the drive in each of the three phases. The phase currents consist of an active

component and a reactive component, which can form a resultant current vector as shown in the following diagram.



The active current is the torque producing current and the reactive current is the magnetizing or flux-producing current.

| 00.013 {04.002} Torque Producing Current |     |                    |   |  |    |    |    |  |  |
|------------------------------------------|-----|--------------------|---|--|----|----|----|--|--|
| RO                                       | Bit | FI                 |   |  | ND | NC | PT |  |  |
| OL                                       |     |                    |   |  |    |    |    |  |  |
| RFC-A                                    | ↕   | VM_DRIVE_CURRENT A | ⇒ |  |    |    |    |  |  |
| RFC-S                                    |     |                    |   |  |    |    |    |  |  |

When the motor is being driven below its rated speed, the torque is proportional to **[00.013]**.

### 6.4.6 Jog reference, Ramp mode selector, Stop and torque mode selectors

Pr **00.014** is used to select the required control mode of the drive as follows:

| 00.014 {04.011} Torque Mode Selector |     |        |   |  |  |  |  |    |  |
|--------------------------------------|-----|--------|---|--|--|--|--|----|--|
| RW                                   | Num |        |   |  |  |  |  | US |  |
| OL                                   | ↕   | 0 or 1 | ⇒ |  |  |  |  | 0  |  |
| RFC-A                                | ↕   | 0 to 5 | ⇒ |  |  |  |  | 0  |  |
| RFC-S                                |     |        |   |  |  |  |  |    |  |

| Setting | Open-Loop         | RFC-A/S                                           |
|---------|-------------------|---------------------------------------------------|
| 0       | Frequency control | Speed control                                     |
| 1       | Torque control    | Torque control                                    |
| 2       |                   | Torque control with speed override                |
| 3       |                   | Coiler/uncoiler mode                              |
| 4       |                   | Speed control with torque feed-forward            |
| 5       |                   | Bi-directional torque control with speed override |

| 00.015 {02.004} Ramp Mode Select |     |                                       |   |  |  |  |  |              |  |
|----------------------------------|-----|---------------------------------------|---|--|--|--|--|--------------|--|
| RW                               | Txt |                                       |   |  |  |  |  | US           |  |
| OL                               | ↕   | Fast (0), Standard (1), Std boost (2) | ⇒ |  |  |  |  | Standard (1) |  |
| RFC-A                            | ↕   | Fast (0), Standard (1)                | ⇒ |  |  |  |  | Standard (1) |  |
| RFC-S                            |     |                                       |   |  |  |  |  |              |  |

Pr **00.015** sets the ramp mode of the drive as shown below:

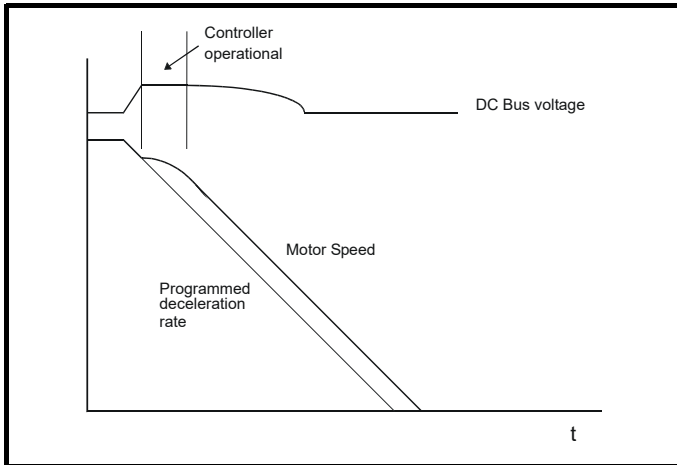
#### 0: Fast ramp

Fast ramp is used where the deceleration follows the programmed deceleration rate subject to current limits. This mode must be used if a braking resistor is connected to the drive.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 1: Standard ramp

Standard ramp is used. During deceleration, if the voltage rises to the standard ramp level (Pr **02.008**) it causes a controller to operate, the output of which changes the demanded load current in the motor. As the controller regulates the link voltage, the motor deceleration increases as the speed approaches zero speed. When the motor deceleration rate reaches the programmed deceleration rate the controller ceases to operate and the drive continues to decelerate at the programmed rate. If the standard ramp voltage (Pr **02.008**) is set lower than the nominal DC bus level the drive will not decelerate the motor, but it will coast to rest. The output of the ramp controller (when active) is a current demand that is fed to the frequency changing current controller (Open-loop modes) or the torque producing current controller (RFC-A or RFC-S modes). The gain of these controllers can be modified with Pr **00.038** and Pr **00.039**.



## 2: Standard ramp with motor voltage boost

This mode is the same as normal standard ramp mode except that the motor voltage is boosted by 20 %. This increases the losses in the motor, dissipating some of the mechanical energy as heat giving faster deceleration.

| 00.016 {02.002} Ramp Enable |     |                   |  |  |  |  |  |   |        |
|-----------------------------|-----|-------------------|--|--|--|--|--|---|--------|
| RW                          | Bit |                   |  |  |  |  |  |   | US     |
| OL                          | ↕   |                   |  |  |  |  |  |   |        |
| RFC-A                       | ↕   |                   |  |  |  |  |  |   |        |
| RFC-S                       | ↕   | Off (0) or On (1) |  |  |  |  |  | ⇒ | On (1) |

Setting Pr **00.016** to 0 allows the user to disable the ramps. This is generally used when the drive is required to closely follow a speed reference which already contains acceleration and deceleration ramps.

| 00.017 {08.026} Digital Input 6 Destination* |     |                  |    |  |  |   |        |    |  |
|----------------------------------------------|-----|------------------|----|--|--|---|--------|----|--|
| RW                                           | Num |                  | DE |  |  |   | PT     | US |  |
| OL                                           | ↕   | 00.000 to 59.999 |    |  |  | ⇒ | 06.031 |    |  |

\* Not applicable to *Unidrive M702*.

### Open-loop

Pr **00.017** sets the destination of digital input T29.

| 00.017 {04.012} Current Reference Filter Time Constant |     |                |  |  |  |  |  |   |        |
|--------------------------------------------------------|-----|----------------|--|--|--|--|--|---|--------|
| RW                                                     | Num |                |  |  |  |  |  |   | US     |
| RFC-A                                                  | ↕   | 0.0 to 25.0 ms |  |  |  |  |  | ⇒ | 0.0 ms |
| RFC-S                                                  | ↕   |                |  |  |  |  |  | ⇒ |        |

## RFC-A / RFC-S

A first order filter, with a time constant defined by Pr **00.017**, is provided on the current demand to reduce acoustic noise and vibration produced as a result of position feedback quantisation noise. The filter introduces a lag in the speed loop, and so the speed loop gains may need to be reduced to maintain stability as the filter time constant is increased.

| 00.018 {03.123} P1 Thermistor Fault Detection |     |                           |  |  |  |  |  |   |                 |
|-----------------------------------------------|-----|---------------------------|--|--|--|--|--|---|-----------------|
| RW                                            | Txt |                           |  |  |  |  |  |   |                 |
| OL                                            |     | None (0)                  |  |  |  |  |  | ⇒ | Temperature (1) |
| RFC-A                                         | ↕   | Temperature (1)           |  |  |  |  |  | ⇒ | Temperature (1) |
| RFC-S                                         | ↕   | Temperature and short (2) |  |  |  |  |  | ⇒ |                 |

Defines the fault detection for the P1 thermistor input:

| P1 Thermistor Fault Detection (03.123) | Fault detection                              |
|----------------------------------------|----------------------------------------------|
| 0: None                                | No detection active                          |
| 1: Temperature                         | Over temperature detection                   |
| 2: Temp and short                      | Over temperature and short circuit detection |

If over temperature detection is enabled a *Thermistor.001* trip is initiated if *P1 Thermistor Feedback* (03.119) is above the level defined by *P1 Thermistor Trip Threshold* (03.120). The trip cannot be reset until *P1 Thermistor Feedback* (03.119) is below *P1 Thermistor Reset Threshold* (03.121).

If short circuit detection is enabled then a *Th Short Circuit.001* is initiated if *P1 Thermistor Feedback* (03.119) is below 50 Ohms.

| 00.019 {07.011} Analog Input 2 Mode* |     |                                                                                                                                                                            |  |  |  |  |  |   |          |
|--------------------------------------|-----|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|--|--|--|--|---|----------|
| RW                                   | Num |                                                                                                                                                                            |  |  |  |  |  |   | US       |
| OL                                   |     | 4-20 mA Low (-4), 20-4 mA Low (-3), 4-20 mA Hold (-2), 20-4 mA Hold (-1), 0-20 mA (0), 20-0 mA (1), 4-20 mA Trip (2), 20-4 mA Trip (3), 4-20 mA (4), 20-4 mA (5), Volt (6) |  |  |  |  |  | ⇒ | Volt (6) |
| RFC-A                                | ↕   |                                                                                                                                                                            |  |  |  |  |  | ⇒ |          |
| RFC-S                                | ↕   |                                                                                                                                                                            |  |  |  |  |  | ⇒ |          |

\* Not applicable to *Unidrive M702*.

In modes 2 and 3 a current loop loss trip is generated if the current falls below 3 mA.

In modes -4, -3, 2 and 3 the analog input level goes to 0.0 % if the input current falls below 3 mA.

In modes -2 and -1 the analog input remains at the value it had in the previous sample before the current fell below 3mA.

| Pr Value | Pr string    | Comments                                          |
|----------|--------------|---------------------------------------------------|
| -4       | 4-20 mA Low  | 4-20 mA low value on current loss (1)             |
| -3       | 20-4 mA Low  | 20-4 mA low value on current loss (1)             |
| -2       | 4-20 mA Hold | 4-20 mA hold at level before loss on current loss |
| -1       | 20-4 mA Hold | 20-4 mA hold at level before loss on current loss |
| 0        | 0-20 mA      |                                                   |
| 1        | 20-0 mA      |                                                   |
| 2        | 4-20 mA Trip | 4-20 mA trip on current loss                      |
| 3        | 20-4 mA Trip | 20-4 mA trip on current loss                      |
| 4        | 4-20 mA      |                                                   |
| 5        | 20-4 mA      |                                                   |
| 6        | Volt         |                                                   |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| 00.020 {07.014} |   | Analog Input 2 Destination* |  |    |  |   |        |    |    |  |
|-----------------|---|-----------------------------|--|----|--|---|--------|----|----|--|
| RW              |   | Num                         |  | DE |  |   |        | PT | US |  |
| OL              | ⇕ | 00.000 to 59.999            |  |    |  | ⇒ | 01.037 |    |    |  |
| RFC-A           |   |                             |  |    |  |   |        |    |    |  |
| RFC-S           |   |                             |  |    |  |   |        |    |    |  |

\* Not applicable to *Unidrive M702*.

Pr **00.020** sets the destination of analog input 2.

| 00.021 {07.015} |   | Analog Input 3 Mode*                                             |  |  |  |  |   |          |  |    |  |  |
|-----------------|---|------------------------------------------------------------------|--|--|--|--|---|----------|--|----|--|--|
| RW              |   | Txt                                                              |  |  |  |  |   |          |  | US |  |  |
| OL              | ⇕ | Volt (6), Therm Short Cct (7), Thermistor (8), Therm No Trip (9) |  |  |  |  | ⇒ | Volt (6) |  |    |  |  |
| RFC-A           |   |                                                                  |  |  |  |  |   |          |  |    |  |  |
| RFC-S           |   |                                                                  |  |  |  |  |   |          |  |    |  |  |

\* Not applicable to *Unidrive M702*.

| Pr value | Pr string       | Comments                                                   |
|----------|-----------------|------------------------------------------------------------|
| 6        | Volt            |                                                            |
| 7        | Therm Short Cct | Temperature measurement input with short circuit detection |
| 8        | Thermistor      | Temperature measurement without short circuit detection    |
| 9        | Therm No Trip   | Temperature measurement input with no trips                |

| 00.022 {01.010} |   | Bipolar Reference Enable |  |  |  |  |   |         |  |    |  |
|-----------------|---|--------------------------|--|--|--|--|---|---------|--|----|--|
| RW              |   | Bit                      |  |  |  |  |   |         |  | US |  |
| OL              | ⇕ | OFF (0) or On (1)        |  |  |  |  | ⇒ | OFF (0) |  |    |  |
| RFC-A           |   |                          |  |  |  |  |   |         |  |    |  |
| RFC-S           |   |                          |  |  |  |  |   |         |  |    |  |

Pr **00.022** determines whether the reference is uni-polar or bi-polar as follows:

| Pr 00.022 | Function                           |                                                                                     |
|-----------|------------------------------------|-------------------------------------------------------------------------------------|
| 0         | Unipolar speed/frequency reference |  |
| 1         | Bipolar speed/frequency reference  |  |

| 00.023 {01.005} |   | Jog Reference     |  |  |  |   |     |  |    |
|-----------------|---|-------------------|--|--|--|---|-----|--|----|
| RW              |   | Num               |  |  |  |   |     |  | US |
| OL              | ↕ | 0.0 to 400.0 Hz   |  |  |  | ⇒ | 0.0 |  |    |
| RFC-A           | ↕ | 0.0 to 4000.0 rpm |  |  |  | ⇒ | 0.0 |  |    |
| RFC-S           |   |                   |  |  |  |   |     |  |    |

Enter the required value of jog frequency/speed.

The frequency/speed limits affect the drive when jogging as follows:

| Frequency-limit parameter                | Limit applies |
|------------------------------------------|---------------|
| Pr <b>00.001</b> Minimum reference clamp | No            |
| Pr <b>00.002</b> Maximum reference clamp | Yes           |

| 00.024 {01.021} |   | Preset Reference 1 |  |  |  |   |     |  |    |
|-----------------|---|--------------------|--|--|--|---|-----|--|----|
| RW              |   | Num                |  |  |  |   |     |  | US |
| OL              | ↕ | VM_SPEED_FREQ_REF  |  |  |  | ⇒ | 0.0 |  |    |
| RFC-A           |   |                    |  |  |  |   |     |  |    |
| RFC-S           |   |                    |  |  |  |   |     |  |    |

| 00.025 {01.022} |   | Preset Reference 2 |  |  |  |   |     |  |    |
|-----------------|---|--------------------|--|--|--|---|-----|--|----|
| RW              |   | Num                |  |  |  |   |     |  | US |
| OL              | ↕ | VM_SPEED_FREQ_REF  |  |  |  | ⇒ | 0.0 |  |    |
| RFC-A           |   |                    |  |  |  |   |     |  |    |
| RFC-S           |   |                    |  |  |  |   |     |  |    |

| 00.026 {01.023} |   | Preset Reference 3 (OL)   |  |  |  |   |     |  |  |    |  |
|-----------------|---|---------------------------|--|--|--|---|-----|--|--|----|--|
| 00.026 {03.008} |   | Overspeed Threshold (RFC) |  |  |  |   |     |  |  |    |  |
| RW              |   | Num                       |  |  |  |   |     |  |  | US |  |
| OL              | ↕ | VM_SPEED_FREQ_REF Hz      |  |  |  | ⇒ | 0.0 |  |  |    |  |
| RFC-A           |   | 0 to 40000 rpm            |  |  |  |   |     |  |  |    |  |
| RFC-S           | ↕ |                           |  |  |  |   |     |  |  |    |  |

#### Open-loop

If the preset reference has been selected (see Pr **00.005**), the speed at which the motor runs is determined by these parameters.

#### RFC-A / RFC-S

If the speed feedback (Pr **00.010**) exceeds this level in either direction, an overspeed trip is produced. If this parameter is set to zero, the overspeed threshold is automatically set to 120 % x SPEED\_FREQ\_MAX.

| 00.027 {01.024} Preset Reference 4 (OL)              |     |                      |  |  |  |   |      |    |  |
|------------------------------------------------------|-----|----------------------|--|--|--|---|------|----|--|
| 00.027 {03.034} P1 Rotary Lines Per Revolution (RFC) |     |                      |  |  |  |   |      |    |  |
| RW                                                   | Num |                      |  |  |  |   |      | US |  |
| OL                                                   | ⇕   | VM_SPEED_FREQ_REF Hz |  |  |  | ⇒ | 0.0  |    |  |
| RFC-A                                                | ⇕   | 1 to 100000          |  |  |  | ⇒ | 1024 |    |  |
| RFC-S                                                |     |                      |  |  |  |   | 4096 |    |  |

#### Open-loop

Refer to Pr **00.024** to Pr **00.026**.

#### RFC-A / RFC-S

Enter in Pr **00.027** the number of lines per revolution of the drive encoder.

| 00.028 {06.013} Enable Auxiliary Key |   |                                                          |  |  |  |   |              |  |    |
|--------------------------------------|---|----------------------------------------------------------|--|--|--|---|--------------|--|----|
| RW                                   |   | Txt                                                      |  |  |  |   |              |  | US |
| OL                                   |   | Disabled (0),<br>Forward/Reverse (1),<br>Run Reverse (2) |  |  |  | ⇒ | Disabled (0) |  |    |
| RFC-A                                | ⇕ |                                                          |  |  |  |   |              |  |    |
| RFC-S                                |   |                                                          |  |  |  |   |              |  |    |

When a keypad is installed, this parameter enables the forward/reverse key.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| 00.029 {11.036} NV Media Card File Previously Loaded |     |          |  |  |  |    |    |  |  |
|------------------------------------------------------|-----|----------|--|--|--|----|----|--|--|
| RO                                                   | Num |          |  |  |  | NC | PT |  |  |
| OL                                                   |     |          |  |  |  |    |    |  |  |
| RFC-A                                                | ⇅   | 0 to 999 |  |  |  | ⇒  |    |  |  |
| RFC-S                                                |     |          |  |  |  |    |    |  |  |

This parameter shows the number of the data block last transferred from a NV Media Card to the drive.

| 00.030 {11.42} Parameter Cloning |     |                                                     |  |  |  |    |  |          |  |
|----------------------------------|-----|-----------------------------------------------------|--|--|--|----|--|----------|--|
| RW                               | Txt |                                                     |  |  |  | NC |  | US*      |  |
| OL                               |     |                                                     |  |  |  |    |  |          |  |
| RFC-A                            | ⇅   | None (0), Read (1), Program (2), Auto (3), Boot (4) |  |  |  | ⇒  |  | None (0) |  |
| RFC-S                            |     |                                                     |  |  |  |    |  |          |  |

\* Only a value of 3 or 4 in this parameter is saved.

#### NOTE

If Pr **00.030** is equal to 1 or 2 this value is not transferred to the EEPROM or the drive. If Pr **00.030** is set to a 3 or 4 the value is transferred.

| Pr String | Pr value | Comment                                          |
|-----------|----------|--------------------------------------------------|
| None      | 0        | Inactive                                         |
| Read      | 1        | Read parameter set from the NV Media Card        |
| Program   | 2        | Programming a parameter set to the NV Media Card |
| Auto      | 3        | Auto save                                        |
| Boot      | 4        | Boot mode                                        |

For further information, please refer to Chapter 10 NV Media Card Operation on page 139.

| 00.031 {11.033} Drive Rated Voltage |     |                                            |  |  |  |    |    |    |  |
|-------------------------------------|-----|--------------------------------------------|--|--|--|----|----|----|--|
| RO                                  | Txt |                                            |  |  |  | ND | NC | PT |  |
| OL                                  |     |                                            |  |  |  |    |    |    |  |
| RFC-A                               | ⇅   | 200 V (0), 400 V (1), 575 V (2), 690 V (3) |  |  |  | ⇒  |    |    |  |
| RFC-S                               |     |                                            |  |  |  |    |    |    |  |

Pr **00.031** indicates the voltage rating of the drive.

| 00.032 {11.032} Maximum Heavy Duty Rating |     |                      |  |  |  |    |    |    |  |
|-------------------------------------------|-----|----------------------|--|--|--|----|----|----|--|
| RO                                        | Num |                      |  |  |  | ND | NC | PT |  |
| OL                                        |     |                      |  |  |  |    |    |    |  |
| RFC-A                                     | ⇅   | 0.000 to 99999.999 A |  |  |  | ⇒  |    |    |  |
| RFC-S                                     |     |                      |  |  |  |    |    |    |  |

Pr **00.032** indicates the maximum continuous Heavy Duty current rating.

| 00.033 {06.009} Catch A Spinning Motor (OL)             |     |                                                                                                 |  |  |  |   |  |              |  |
|---------------------------------------------------------|-----|-------------------------------------------------------------------------------------------------|--|--|--|---|--|--------------|--|
| 00.033 {05.016} Rated Speed Optimisation Select (RFC-A) |     |                                                                                                 |  |  |  |   |  |              |  |
| RW                                                      | Txt |                                                                                                 |  |  |  |   |  | US           |  |
| OL                                                      | ⇅   | Disable (0), Enable (1), Fwd Only (2), Rev Only (3)                                             |  |  |  | ⇒ |  | Disable (0)  |  |
| RFC-A                                                   | ⇅   | Disabled (0), Classic Slow (1), Classic Fast (2), Combined (3), VARs Only (4), Voltage Only (5) |  |  |  | ⇒ |  | Disabled (0) |  |

#### Open-loop

When the drive is enabled with Pr **00.033** = 0, the output frequency starts at zero and ramps to the required reference. When the drive is enabled when Pr **00.033** has a non-zero value, the drive performs a start-up test to determine the motor speed and then sets the initial output frequency to the synchronous frequency of the motor. Restrictions may be placed on the frequencies detected by the drive as follows:

| Pr 00.033 | Pr string | Function                         |
|-----------|-----------|----------------------------------|
| 0         | Disable   | Disabled                         |
| 1         | Enable    | Detect all frequencies           |
| 2         | Fwd only  | Detect positive frequencies only |
| 3         | Rev only  | Detect negative frequencies only |

#### RFC-A

The *Rated Frequency* (00.047) and *Rated Speed* (00.045) are used to define the rated slip of the motor. The rated slip is used in sensorless mode (*Sensorless Mode Active* (03.078) = 1) to correct the motor speed with load. When this mode is active *Rated Speed Optimisation Select* (00.033) has no effect.

If sensorless mode is not active (*Sensorless Mode Active* (03.078) = 0) the rated slip is used in the motor control algorithm and an incorrect value of slip can have a significant effect on the motor performance. If *Rated Speed Optimisation Select* (00.033) = 0 then the adaptive control system is disabled. However, if *Rated Speed Optimisation Select* (00.033) is set to a non-zero value the drive can automatically adjust the *Rated Speed* (00.045) to give the correct value of rated slip. *Rated Speed* (00.045) is not saved at power-down, and so when the drive is powered-down and up again it will return to the last value saved by the user. The rate of convergence and the accuracy of the adaptive controller reduces at low output frequency and low load. The minimum frequency is defined as a percentage of *Rated Frequency* (00.047) by *Rated Speed Optimisation Minimum Frequency* (05.019). The minimum load is defined as a percentage of rated load by *Rated Speed Optimisation Minimum Load* (05.020). The adaptive controller is enabled when a motoring or regenerative load rises above *Rated Speed Optimisation Minimum Load* (05.020) + 5 %, and is disabled again when it falls below *Rated Speed Optimisation Minimum Load* (05.020). For best optimisation results the correct values of *Stator Resistance* (05.017), *Transient Inductance* (05.024), *Stator Inductance* (05.025), *Saturation Breakpoint 1* (05.029), *Saturation Breakpoint 2* (05.062), *Saturation Breakpoint 3* (05.030) and *Saturation Breakpoint 4* (05.063) should be used.

| 00.034 {11.030} User security code |     |                         |  |  |  |    |    |    |    |
|------------------------------------|-----|-------------------------|--|--|--|----|----|----|----|
| RW                                 | Num |                         |  |  |  | ND | NC | PT | US |
| OL                                 |     |                         |  |  |  |    |    |    |    |
| RFC-A                              | ⇅   | 0 to 2 <sup>31</sup> -1 |  |  |  | ⇒  |    | 0  |    |
| RFC-S                              |     |                         |  |  |  |    |    |    |    |

If any number other than 0 is programmed into this parameter, user security is applied so that no parameters except Pr **00.049** can be adjusted with the keypad. When this parameter is read via a keypad it appears as zero. For further details refer to section 5.9.3 *User Security Code* on page 46.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| 00.035 {11.024} Serial Mode* |                                                                                                                                                                                                                                                       |   |  |  |  |  |   |            |    |
|------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---|--|--|--|--|---|------------|----|
| RW                           | Txt                                                                                                                                                                                                                                                   |   |  |  |  |  |   |            | US |
| OL                           | 8 2 NP (0), 8 1 NP (1),<br>8 1 EP (2), 8 1 OP (3),<br>8 2 NP M (4),<br>8 1 NP M (5),<br>8 1 EP M (6),<br>8 1 OP M (7), 7 2 NP (8),<br>7 1 NP (9), 7 1 EP (10),<br>7 1 OP (11),<br>7 2 NP M (12),<br>7 1 NP M (13),<br>7 1 EP M (14),<br>7 1 OP M (15) | ⇕ |  |  |  |  | ⇒ | 8 2 NP (0) |    |
| RFC-A                        |                                                                                                                                                                                                                                                       |   |  |  |  |  |   |            |    |
| RFC-S                        |                                                                                                                                                                                                                                                       |   |  |  |  |  |   |            |    |

\* Only applicable to *Unidrive M701*.

This parameter defines the communications protocol used by the EIA485 comms port on the drive. This parameter can be changed via the drive keypad, via a Solutions Module or via the comms interface itself. If it is changed via the comms interface, the response to the command uses the original protocol. The master should wait at least 20 ms before send a new message using the new protocol. (Note: ANSI uses 7 data bits, 1 stop bit and even parity; Modbus RTU uses 8 data bits, 2 stops bits and no parity).

| Pr Value | Pr String |
|----------|-----------|
| 0        | 8 2 NP    |
| 1        | 8 1 NP    |
| 2        | 8 1 EP    |
| 3        | 8 1 OP    |
| 4        | 8 2 NP M  |
| 5        | 8 1 NP M  |
| 6        | 8 1 EP M  |
| 7        | 8 1 OP M  |
| 8        | 7 2 NP    |
| 9        | 7 1 NP    |
| 10       | 7 1 EP    |
| 11       | 7 1 OP    |
| 12       | 7 2 NP M  |
| 13       | 7 1 NP M  |
| 14       | 7 1 EP M  |
| 15       | 7 1 OP M  |

The core drive always uses the Modbus rtu protocol and is always a slave. *Serial Mode* (00.035) defines the data format used by the serial comms interface. The bits in the value of *Serial Mode* (00.035) define the data format as follows. Bit 3 is always 0 in the core product as 8 data bits are required for Modbus rtu. The parameter value can be extended in derivative products which provide alternative communications protocols if required.

| Bits   | 3                                               | 2                                             | 1 and 0                                                                                                                                      |
|--------|-------------------------------------------------|-----------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------|
| Format | Number of data bits<br>0 = 8 bits<br>1 = 7 bits | Register mode<br>0 = Standard<br>1 = Modified | Stop bits and Parity<br>0 = 2 stop bits, no parity<br>1 = 1 stop bit, no parity<br>2 = 1 stop bit, even parity<br>3 = 1 stop bit, odd parity |

Bit 2 selects either standard or modified register mode. The menu and parameter numbers are derived for each mode as given in the following table. Standard mode is compatible with Unidrive SP. Modified mode is provided to allow register numbers up to 255 to be addressed. If any menus with numbers above 63 should contain more than 99 parameters, then these parameters cannot be accessed via Modbus rtu.

| Register mode | Register address                                 |
|---------------|--------------------------------------------------|
| Standard      | (mm x 100) + ppp - 1 where mm ≤ 162 and ppp ≤ 99 |
| Modified      | (mm x 256) + ppp - 1 where mm ≤ 63 and ppp ≤ 255 |

Changing the parameters does not immediately change the serial communications settings. See *Reset Serial Communications* (11.020) for more details.

| 00.036 {11.025} Serial Baud Rate* |                                                                                                                               |   |  |  |  |  |   |           |    |
|-----------------------------------|-------------------------------------------------------------------------------------------------------------------------------|---|--|--|--|--|---|-----------|----|
| RW                                | Txt                                                                                                                           |   |  |  |  |  |   |           | US |
| OL                                | 300 (0), 600 (1), 1200 (2),<br>2400 (3), 4800 (4),<br>9600 (5), 19200 (6),<br>38400 (7), 57600 (8),<br>76800 (9), 115200 (10) | ⇕ |  |  |  |  | ⇒ | 19200 (6) |    |
| RFC-A                             |                                                                                                                               |   |  |  |  |  |   |           |    |
| RFC-S                             |                                                                                                                               |   |  |  |  |  |   |           |    |

\* Only applicable to *Unidrive M701*.

This parameter can be changed via the drive keypad, via a Solutions Module or via the comms interface itself. If it is changed via the comms interface, the response to the command uses the original baud rate. The master should wait at least 20 ms before send a new message using the new baud rate.

| 00.037 {11.023} Serial Address* |     |          |  |  |  |  |   |   |    |
|---------------------------------|-----|----------|--|--|--|--|---|---|----|
| RW                              | Num |          |  |  |  |  |   |   | US |
| OL                              |     |          |  |  |  |  |   |   |    |
| RFC-A                           | ⇕   | 1 to 247 |  |  |  |  | ⇒ | 1 |    |
| RFC-S                           |     |          |  |  |  |  |   |   |    |

\* Only applicable to *Unidrive M701*.

Used to define the unique address for the drive for the serial interface. The drive is always a slave address 0 is used to globally address all slaves, and so this address should not be set in this parameter

| 00.037 {24.010} Active IP Address* |    |                               |  |  |  |  |    |    |  |
|------------------------------------|----|-------------------------------|--|--|--|--|----|----|--|
| RO                                 | IP |                               |  |  |  |  | NC | PT |  |
| OL                                 |    |                               |  |  |  |  |    |    |  |
| RFC-A                              | ⇕  | 0.0.0.0 to<br>255.255.255.255 |  |  |  |  |    |    |  |
| RFC-S                              |    |                               |  |  |  |  |    |    |  |

\* Only applicable to *Unidrive M700* and *Unidrive M702*.

| 00.038 {04.013} Current Controller Kp Gain |     |            |  |  |  |  |   |     |    |
|--------------------------------------------|-----|------------|--|--|--|--|---|-----|----|
| RW                                         | Num |            |  |  |  |  |   |     | US |
| OL                                         |     |            |  |  |  |  |   | 20  |    |
| RFC-A                                      | ⇕   | 0 to 30000 |  |  |  |  | ⇒ | 150 |    |
| RFC-S                                      |     |            |  |  |  |  |   |     |    |

| 00.039 {04.014} Current Controller Ki Gain |     |            |  |  |  |  |   |      |    |
|--------------------------------------------|-----|------------|--|--|--|--|---|------|----|
| RW                                         | Num |            |  |  |  |  |   |      | US |
| OL                                         | ⇕   |            |  |  |  |  | ⇒ | 40   |    |
| RFC-A                                      | ⇕   | 0 to 30000 |  |  |  |  | ⇒ | 2000 |    |
| RFC-S                                      |     |            |  |  |  |  |   |      |    |

These parameters control the proportional and integral gains of the current controller used in the open loop drive. The current controller either provides current limits or closed loop torque control by modifying the drive output frequency. The control loop is also used in its torque mode during line power supply loss, or when the controlled mode standard ramp is active and the drive is decelerating, to regulate the flow of current into the drive.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| 00.040<br>{05.012} |     | Auto-tune |  |  |  |   |    |  |  |  |  |
|--------------------|-----|-----------|--|--|--|---|----|--|--|--|--|
| RW                 | Num |           |  |  |  |   | NC |  |  |  |  |
| OL                 | ↕   | 0 to 2    |  |  |  | ⇒ | 0  |  |  |  |  |
| RFC-A              | ↕   | 0 to 5    |  |  |  | ⇒ |    |  |  |  |  |
| RFC-S              | ↕   | 0 to 6    |  |  |  | ⇒ |    |  |  |  |  |

### Open-Loop

There are two autotune tests available in open loop mode, a stationary and a rotating test. A rotating autotune should be used whenever possible so the measured value of power factor of the motor is used by the drive.

- A stationary autotune can be used when the motor is loaded and it is not possible to remove the load from the motor shaft. The stationary test measures the *Stator Resistance* (05.017), *Transient Inductance* (05.024), *Maximum Deadtime Compensation* (05.059) and *Current At Maximum Deadtime Compensation* (05.060) which are required for good performance in vector control modes (see *Open Loop Control Mode* (00.007), later in this table). The stationary autotune does not measure the power factor of the motor so the value on the motor nameplate must be entered into Pr **00.043**. To perform a Stationary autotune, set Pr **00.040** to 1, and provide the drive with both an enable signal (terminal 31 on *Unidrive M700 / M701* and terminal 11 and 13 on *Unidrive M702*) and a run signal (terminal 26 or 27 on *Unidrive M700 / M701* and terminal 7 or 8 on *Unidrive M702*).
- A rotating autotune should only be used if the motor is unloaded. A rotating autotune first performs a stationary autotune, as above, then a rotating test is performed in which the motor is accelerated with currently selected ramps up to a frequency of *Rated Frequency* (05.006) x 2/3, and the frequency is maintained at that level for 4 seconds. *Stator Inductance* (05.025) is measured and this value is used in conjunction with other motor parameters to calculate *Rated Power Factor* (00.043). To perform a Rotating autotune, set Pr **00.040** to 2, and provide the drive with both an enable signal (terminal 31 on *Unidrive M700 / M701* and terminal 11 & 13 on *Unidrive M702*) and a run signal (terminal 26 or 27 on *Unidrive M700 / M701* and terminal 7 or 8 on *Unidrive M702*).

Following the completion of an autotune test the drive will go into the inhibit state. The drive must be placed into a controlled disable condition before the drive can be made to run at the required reference. The drive can be put in to a controlled disable condition by removing the Safe Torque Off signal from terminal 31 on *Unidrive M700 / M701* and terminal 11 & 13 on *Unidrive M702*, setting the *Drive Enable* (06.015) to OFF (0) or disabling the drive via the *Control Word* (06.042) and *Control Word Enable* (06.043).

### RFC-A

There are four autotune tests available in RFC-A mode, a stationary test, a rotating test, two mechanical load measurement tests. A stationary autotune will give moderate performance whereas a rotating autotune will give improved performance as it measures the actual values of the motor parameters required by the drive. A mechanical load measurement test should be performed separately to a stationary or rotating autotune.

#### NOTE

It is highly recommended that a rotating autotune is performed (Pr **00.040** set to 2).

- A stationary autotune can be used when the motor is loaded and it is not possible to remove the load from the motor shaft. The stationary autotune measures the *Stator Resistance* (05.017) and *Transient Inductance* (05.024) of the motor. These are used to calculate the current loop gains, and at the end of the test the values in Pr **00.038** and Pr **00.039** are updated. A stationary autotune does not measure the power factor of the motor so the value on the motor nameplate

must be entered into Pr **00.043**. To perform a Stationary autotune, set Pr **00.040** to 1, and provide the drive with both an enable signal (terminal 31 on *Unidrive M700 / M701* and terminal 11 & 13 on *Unidrive M702*) and a run signal (terminal 26 or 27 on *Unidrive M700 / M701* and terminal 7 or 8 on *Unidrive M702*).

- A rotating autotune should only be used if the motor is unloaded. A rotating autotune first performs a stationary autotune, a rotating test is then performed which the motor is accelerated with currently selected ramps up to a frequency of *Rated Frequency* (00.047) x 2/3, and the frequency is maintained at the level for up to 40 s. During the rotating autotune the *Stator Inductance* (05.025), and the motor saturation breakpoints (Pr **05.029**, Pr **05.030**, Pr **06.062** and Pr **05.063**) are modified by the drive. The *Motor Rated Power Factor* (00.043) is also modified by the *Stator Inductance* (05.025). The No-Load motor core losses are measured and written to *No-Load Core Loss* (04.045). To perform a Rotating autotune, set Pr **00.040** to 2, and provide the drive with both an enable signal (terminal 31 on *Unidrive M700 / M701* and terminal 11 and 13 on *Unidrive M702*) and a run signal (terminal 26 or 27 on *Unidrive M700 / M701* and terminal 7 or 8 on *Unidrive M702*).

Following the completion of an autotune test the drive will go into the inhibit state. The drive must be placed into a controlled disable condition before the drive can be made to run at the required reference. The drive can be put in to a controlled disable condition by removing the Safe Torque Off signal from terminal 31 on *Unidrive M700 / M701* and terminal 11 and 13 on *Unidrive M702*, setting the *Drive Enable* (06.015) to OFF (0) or disabling the drive via the control word (Pr **06.042** & Pr **06.043**).

### RFC-S

There are five autotune tests available in RFC-S mode, a stationary autotune, a rotating autotune, two mechanical load measurement tests and a locked rotor test to measure load dependent parameters.

#### Stationary Autotune

The stationary autotune can be used when the motor is loaded and it is not possible uncouple the load from motor shaft. This test can be used to measure all the necessary parameters for basic control. During the stationary autotune, a test is performed to locate the flux axis of the motor. However this test may not be able to calculate such an accurate value for the *Position Feedback Phase Angle* (00.043) as compared to rotating autotune. A stationary test is performed to measure *Stator Resistance* (05.017), *Ld* (05.024), *Maximum Deadtime Compensation* (05.059), *Current At Maximum Deadtime Compensation* (05.060), *No Load Lq* (05.072). If *Enable Stator Compensation* (05.049) = 1 then *Stator Base Temperature* (05.048) is made equal to *Stator Temperature* (05.046). The *Stator Resistance* (05.017) and the *Ld* (05.024) are then used to set up *Current controller Kp Gain* (00.038) and *Current Controller Ki Gain* (00.039). If sensorless mode is not selected then *Position Feedback Phase Angle* (00.043) is set up for the position from the position feedback interface selected with *Motor Control Feedback Select* (03.026). To perform a Stationary autotune, set Pr **00.040** to 1, and provide the drive with both an enable signal (terminal 31 on *Unidrive M700 / M701* and terminal 11 & 13 on *Unidrive M702*) and a run signal (terminal 26 or 27 on *Unidrive M700 / M701* and terminal 7 or 8 on *Unidrive M702*).

#### Rotating Autotune

The rotating autotune must be performed on unloaded motor. This test can be used to measure all the necessary parameters for the basic control and parameters for cancelling the effects of the cogging torque.

During the rotating autotune, *Rated Current* (00.046) is applied and the motor is rotated by 2 electrical revolutions (i.e. up to 2 mechanical revolutions) in the required direction. If sensorless mode is not selected then the *Position Feedback Phase Angle* (00.043) is set-up for the position from the position feedback interface selected with *Motor Control Feedback Select* (03.026). A stationary test is then performed to measure *Stator Resistance* (05.017), *Ld* (05.024), *Maximum Deadtime Compensation* (05.059), *Current At Maximum Deadtime Compensation* (05.060) and *No Load Lq* (05.072). *Stator Resistance* (05.017) and *Ld*

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

(00.024) are used to set up *Current Controller Kp Gain* (00.038) and *Current Controller Ki Gain* (00.039). This is only done once during the test, and so the user can make further adjustments to the current controller gains if required. To perform a Rotating autotune, set Pr **00.040** to 2, and provide the drive with both an enable signal (terminal 31 on *Unidrive M700 / M701* and terminal 11 and 13 on *Unidrive M702*) and a run signal (terminal 26 or 27 on *Unidrive M700 / M701* and terminal 7 or 8 on *Unidrive M702*).

| 00.041 {05.018} |     | Maximum Switching Frequency                                                            |  |  |  |    |           |  |  |  |  |  |  |
|-----------------|-----|----------------------------------------------------------------------------------------|--|--|--|----|-----------|--|--|--|--|--|--|
| RW              | Txt |                                                                                        |  |  |  | RA | NC        |  |  |  |  |  |  |
| OL              |     | 2 kHz (0), 3 kHz (1),<br>4 kHz (2), 6 kHz (3),<br>8 kHz (4), 12 kHz (5),<br>16 kHz (6) |  |  |  |    | 3 kHz (1) |  |  |  |  |  |  |
| RFC-A           | ↕   |                                                                                        |  |  |  |    |           |  |  |  |  |  |  |
| RFC-S           |     |                                                                                        |  |  |  |    |           |  |  |  |  |  |  |
|                 |     |                                                                                        |  |  |  |    | 6 kHz (3) |  |  |  |  |  |  |

This parameter defines the required switching frequency. The drive may automatically reduce the actual switching frequency (without changing this parameter) if the power stage becomes too hot. A thermal model of the IGBT junction temperature is used based on the heatsink temperature and an instantaneous temperature drop using the drive output current and switching frequency. The estimated IGBT junction temperature is displayed in Pr **07.034**. If the temperature exceeds 135 °C the switching frequency is reduced if this is possible (i.e >3 kHz). Reducing the switching frequency reduces the drive losses and the junction temperature displayed in Pr **07.034** also reduces. If the load condition persists the junction temperature may continue to rise again above 145 °C and the drive cannot reduce the switching frequency further the drive will initiate an 'OHT Inverter' trip. Every second the drive will attempt to restore the switching frequency to the level set in Pr **00.041**.

The full range of switching frequencies is not available on all ratings of Unidrive M. See section 8.5 *Switching frequency* on page 109, for the maximum available switching frequency for each drive rating.

## 6.4.7 Motor parameters

| 00.042 {05.011} |     | Number Of Motor Poles               |  |  |  |  |               |  |  |  |  |    |  |
|-----------------|-----|-------------------------------------|--|--|--|--|---------------|--|--|--|--|----|--|
| RW              | Num |                                     |  |  |  |  |               |  |  |  |  | US |  |
| OL              |     | Automatic (0) to<br>480 Poles (240) |  |  |  |  | Automatic (0) |  |  |  |  |    |  |
| RFC-A           | ↕   |                                     |  |  |  |  |               |  |  |  |  |    |  |
| RFC-S           |     |                                     |  |  |  |  |               |  |  |  |  |    |  |
|                 |     |                                     |  |  |  |  | 6 Poles (3)   |  |  |  |  |    |  |

### Open-loop

This parameter is used in the calculation of motor speed, and in applying the correct slip compensation. When Automatic (0) is selected, the number of motor poles is automatically calculated from the *Rated Frequency* (00.047) and the *Rated Speed* rpm (00.045). The number of poles = 120 \* rated frequency / rpm rounded to the nearest even number.

### RFC-A

This parameter must be set correctly for the vector control algorithms to operate correctly. When Automatic (0) is selected, the number of motor poles is automatically calculated from the *Rated Frequency* (00.047) and the *Rated Speed* (00.045) rpm. The number of poles = 120 \* rated frequency / rpm rounded to the nearest even number.

### RFC-S

This parameter must be set correctly for the vector control algorithms to operate correctly. When Automatic (0) is selected the number of poles is set to 6.

| 00.043 {05.010} |     | Rated Power Factor (OL)             |  |  |  |  |       |  |  |  |  |    |  |
|-----------------|-----|-------------------------------------|--|--|--|--|-------|--|--|--|--|----|--|
| 00.043 {03.025} |     | Position Feedback Phase Angle (RFC) |  |  |  |  |       |  |  |  |  |    |  |
| RW              | Num |                                     |  |  |  |  |       |  |  |  |  | US |  |
| OL              | ↕   | 0.000 to 1.000                      |  |  |  |  | 0.850 |  |  |  |  |    |  |
| RFC-A           | ↕   | 0.000 to 1.000                      |  |  |  |  | 0.850 |  |  |  |  |    |  |
| RFC-S           | ↕   | 0.0 to 359.9 °                      |  |  |  |  | 0.0 ° |  |  |  |  |    |  |

The power factor is the true power factor of the motor, i.e. the angle between the motor voltage and current.

### Open-loop

The power factor is used in conjunction with the motor rated current (Pr **00.046**) to calculate the rated active current and magnetizing current of the motor. The rated active current is used extensively to control the drive, and the magnetizing current is used in vector mode Rs compensation. It is important that this parameter is set up correctly.

This parameter is obtained by the drive during a rotational autotune. If a stationary autotune is carried out, then the nameplate value should be entered in Pr **00.043**.

### RFC-A

If the stator inductance (Pr **05.025**) contains a non-zero value, the power factor used by the drive is continuously calculated and used in the vector control algorithms (this will not update Pr **00.043**).

If the stator inductance is set to zero (Pr **05.025**) then the power factor written in Pr **00.043** is used in conjunction with the motor rated current and other motor parameters to calculate the rated active and magnetizing currents which are used in the vector control algorithm.

This parameter is obtained by the drive during a rotational autotune. If a stationary autotune is carried out, then the nameplate value should be entered in Pr **00.043**.

### RFC-S

The phase angle between the rotor flux in a servo motor and the encoder position is required for the motor to operate correctly. If the phase angle is known it can be set in this parameter by the user. Alternatively the drive can automatically measure the phase angle by performing a phasing test (see autotune in RFC-S mode Pr **00.040**). When the test is complete the new value is written to this parameter. The encoder phase angle can be modified at any time and becomes effective immediately. This parameter has a factory default value of 0.0 °, but is not affected when defaults are loaded by the user.

| 00.044 {05.009} |     | Rated Voltage                 |  |  |  |  |                                                                             |  |  |  |  |    |  |
|-----------------|-----|-------------------------------|--|--|--|--|-----------------------------------------------------------------------------|--|--|--|--|----|--|
| RW              | Num |                               |  |  |  |  |                                                                             |  |  |  |  | US |  |
| OL              |     | 0 to<br>VM_AC_VOLTAGE_<br>SET |  |  |  |  | 200 V drive: 230 V                                                          |  |  |  |  |    |  |
| RFC-A           | ↕   |                               |  |  |  |  | 50Hz default 400 V drive: 400 V                                             |  |  |  |  |    |  |
| RFC-S           |     |                               |  |  |  |  | 60Hz default 400 V drive: 460 V<br>575 V drive: 575 V<br>690 V drive: 690 V |  |  |  |  |    |  |

Enter the value from the rating plate of the motor.

| 00.045 {05.008} |     | Rated Speed          |  |  |  |  |                                                          |  |  |  |  |    |  |
|-----------------|-----|----------------------|--|--|--|--|----------------------------------------------------------|--|--|--|--|----|--|
| RW              | Num |                      |  |  |  |  |                                                          |  |  |  |  | US |  |
| OL              | ↕   | 0 to 35940 rpm       |  |  |  |  | 50 Hz default: 1500 rpm<br>60 Hz default: 1800 rpm       |  |  |  |  |    |  |
| RFC-A           | ↕   | 0.00 to 33000.00 rpm |  |  |  |  | 50 Hz default: 1450.00 rpm<br>60 Hz default: 1750.00 rpm |  |  |  |  |    |  |
| RFC-S           | ↕   |                      |  |  |  |  | 3000.00 rpm                                              |  |  |  |  |    |  |

### Open-loop

This is the speed at which the motor would rotate when supplied with its base frequency at rated voltage, under rated load conditions (= synchronous speed - slip speed). Entering the correct value into this parameter allows the drive to increase the output frequency as a

|                    |                     |                         |                         |                 |                         |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|-------------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | <b>Basic parameters</b> | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|-------------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

function of load in order to compensate for this speed drop.

Slip compensation is disabled if Pr **00.045** is set to 0 or to synchronous speed, or if Pr **05.027** is set to 0.

If slip compensation is required this parameter should be set to the value from the rating plate of the motor, which should give the correct rpm for a hot machine. Sometimes it will be necessary to adjust this when the drive is commissioned because the nameplate value may be inaccurate. Slip compensation will operate correctly both below base speed and within the field weakening region. Slip compensation is normally used to correct for the motor speed to prevent speed variation with load. The rated load rpm can be set higher than synchronous speed to deliberately introduce speed droop. This can be useful to aid load sharing with mechanically coupled motors.

#### RFC-A

Rated speed is used with motor rated frequency to determine the full load slip of the motor which is used by the vector control algorithm. Incorrect setting of this parameter can result in the following:

- Reduced efficiency of motor operation
- Reduction of maximum torque available from the motor
- Failure to reach maximum speed
- Over-current trips
- Reduced transient performance
- Inaccurate control of absolute torque in torque control modes

The nameplate value is normally the value for a hot machine, however, some adjustment may be required when the drive is commissioned if the nameplate value is inaccurate.

The rated speed rpm can be optimized by the drive (For further information, refer to section 8.1.2 *RFC-A mode* on page 98).

#### RFC-S

*Rated Speed* (00.045) is used as follows:

1. Operation without position feedback, i.e. Sensorless Mode Active (03.078) = 1.
2. Where the motor operates above this speed and flux weakening is active.
3. In the motor thermal model.

The units for *Rated Speed* (00.045) are always rpm even if a linear motor is used and *Linear Speed Select* (01.055) = 1.

| 00.046 {05.007} Rated Current |     |                           |  |  |  |                                    |  |    |  |
|-------------------------------|-----|---------------------------|--|--|--|------------------------------------|--|----|--|
| RW                            | Num |                           |  |  |  | RA                                 |  | US |  |
| OL                            | ↕   | 0.000 to VM_RATED_CURRENT |  |  |  | Maximum Heavy Duty Rating (00.032) |  |    |  |
| RFC-A                         | ↕   |                           |  |  |  |                                    |  |    |  |
| RFC-S                         | ↕   |                           |  |  |  |                                    |  |    |  |

Enter the name-plate value for the motor rated current.

| 00.047<br>{05.006} |   | Rated Frequency |  |  |  |   |                                                  |  |  |    |  |
|--------------------|---|-----------------|--|--|--|---|--------------------------------------------------|--|--|----|--|
| RW                 |   | Num             |  |  |  |   |                                                  |  |  | US |  |
| OL                 | ↕ | 0.0 to 599.0 Hz |  |  |  | ⇒ | 50 Hz default: 50.0 Hz<br>60 Hz default: 60.0 Hz |  |  |    |  |
| RFC-A              | ↕ | 0.0 to 550.0 Hz |  |  |  |   |                                                  |  |  |    |  |
| RFC-S              | ↕ |                 |  |  |  |   |                                                  |  |  |    |  |

#### Open-loop and RFC-A

Enter the value from the rating plate of the motor.

### 6.4.8 Operating-mode selection

| 00.048 {11.031} User Drive Mode |     |                                                |  |  |  |    |               |    |  |
|---------------------------------|-----|------------------------------------------------|--|--|--|----|---------------|----|--|
| RW                              | Txt |                                                |  |  |  | ND | NC            | PT |  |
| OL                              | ↕   | Open-loop (1), RFC-A (2), RFC-S (3), Regen (4) |  |  |  | ⇒  | Open-loop (1) |    |  |
| RFC-A                           |     |                                                |  |  |  | ⇒  | RFC-A (2)     |    |  |
| RFC-S                           |     |                                                |  |  |  | ⇒  | RFC-S (3)     |    |  |
| Regen                           |     |                                                |  |  |  | ⇒  | Regen (4)     |    |  |

The settings for Pr **00.048** are as follows:

| Setting | Operating mode |
|---------|----------------|
| 1       | Open-loop      |
| 2       | RFC-A          |
| 3       | RFC-S          |
| 4       | Regen          |

This parameter defines the drive operating mode. Pr **mm.000** must be set to '1253' (European defaults) or '1254' (USA defaults) before this parameter can be changed. When the drive is reset to implement any change in this parameter, the default settings of all parameters will be set according to the drive operating mode selected and saved in memory.

### 6.4.9 Status information

| 00.049 {11.044} User Security Status |   |                                                                                                            |  |  |  |   |            |    |    |  |  |
|--------------------------------------|---|------------------------------------------------------------------------------------------------------------|--|--|--|---|------------|----|----|--|--|
| RW                                   |   | Txt                                                                                                        |  |  |  |   |            | ND | PT |  |  |
| OL                                   | ↕ | Menu 0 (0), All Menus (1),<br>Read-only Menu 0 (2),<br>Read-only (3),<br>Status Only (4),<br>No Access (5) |  |  |  | ⇒ | Menu 0 (0) |    |    |  |  |
| RFC-A                                |   |                                                                                                            |  |  |  |   |            |    |    |  |  |
| RFC-S                                |   |                                                                                                            |  |  |  |   |            |    |    |  |  |

This parameter controls access via the drive keypad as follows:

| Security level       | Description                                                                                                                                                                          |
|----------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 0 (Menu 0)           | All writable parameters are available to be edited but only parameters in Menu 0 are visible.                                                                                        |
| 1 (All Menus)        | All writable parameters are visible and available to be edited.                                                                                                                      |
| 2 (Read-only Menu 0) | All parameters are read-only. Access is limited to Menu 0 parameters only.                                                                                                           |
| 3 (Read-only)        | All parameters are read-only however all menus and parameters are visible.                                                                                                           |
| 4 (Status Only)      | The keypad remains in status mode and no parameters can be viewed or edited.                                                                                                         |
| 5 (No Access)        | The keypad remains in status mode and no parameters can be viewed or edited. Drive parameters cannot be accessed via a comms / fieldbus interface in the drive or any option module. |

The keypad can adjust this parameter even when user security is set.

| 00.050 {11.029} Software Version |   |                |  |  |  |    |    |    |  |  |
|----------------------------------|---|----------------|--|--|--|----|----|----|--|--|
| RO                               |   | Num            |  |  |  | ND | NC | PT |  |  |
| OL                               | ↕ | 0 to 999999999 |  |  |  | ⇒  |    |    |  |  |
| RFC-A                            |   |                |  |  |  |    |    |    |  |  |
| RFC-S                            |   |                |  |  |  |    |    |    |  |  |

The parameter displays the software version of the drive.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| 00.051 {10.037} Action On Trip Detection |     |         |  |  |  |   |   |    |  |
|------------------------------------------|-----|---------|--|--|--|---|---|----|--|
| RW                                       | Bin |         |  |  |  |   |   | US |  |
| OL                                       |     |         |  |  |  |   |   |    |  |
| RFC-A                                    | ⇕   | 0 to 31 |  |  |  | ⇒ | 0 |    |  |
| RFC-S                                    |     |         |  |  |  |   |   |    |  |

Each bit in this parameter has the following functions:

| Bit | Function                                        |
|-----|-------------------------------------------------|
| 0   | Stop on non-important trips                     |
| 1   | Disable braking resistor overload detection     |
| 2   | Disable phase loss stop                         |
| 3   | Disable braking resistor temperature monitoring |
| 4   | Disable parameter freeze on trip                |

#### Example

Pr **00.051** = 8 (1000<sub>binary</sub>) Th Brake Res trip is disabled

Pr **00.051** = 12 (1100<sub>binary</sub>) Th Brake Res and phase loss trip is disabled

#### Stop on non-important trips

If bit 0 is set to one the drive will attempt to stop before tripping if any of the following trip conditions are detected: I/O Overload, An Input 1 Loss, An Input 2 Loss or Keypad Mode.

#### Disable braking resistor overload detection

For details of braking resistor overload detection mode see Pr **10.030**.

#### Disable phase loss trip

Normally the drive will stop when the input phase loss condition is detected. If this bit is set to 1 the drive will continue to run and will only trip when the drive is brought to a stop by the user.

#### Disable braking resistor temperature monitoring

Size 3, 4 and 5 drives have an internal user install braking resistor with a thermistor to detect overheating of the resistor. As default bit 3 of Pr **00.051** is set to zero, and so if the braking resistor and its thermistor is not installed the drive will produce a trip (Th Brake Res) because the thermistor appears to be open-circuit. This trip can be disabled so that the drive can run by setting bit 3 of Pr **00.051** to one. If the resistor is installed then no trip is produced unless the thermistor fails, and so bit 3 of Pr **00.051** can be left at zero. This feature only applies to size 3, 4 and 5 drives. For example if Pr **00.051** = 8, then Th Brake Res trip will be disabled.

#### Disable parameter freeze on trip

If this bit is 0 then the parameters listed below are frozen on trip until the

trip is cleared. If this bit is 1 then this feature is disabled.

| Open-loop mode                     |  | RFC-A and RFC-S modes              |  |
|------------------------------------|--|------------------------------------|--|
| Reference Selected (01.001)        |  | Reference Selected (01.001)        |  |
| Pre-skip Filter Reference (01.002) |  | Pre-skip Filter Reference (01.002) |  |
| Pre-ramp Reference (01.003)        |  | Pre-ramp Reference (01.003)        |  |
| Post Ramp Reference (02.001)       |  | Post Ramp Reference (02.001)       |  |
| Frequency Slaving Demand (03.001)  |  | Final Speed Reference (03.001)     |  |
|                                    |  | Speed Feedback (00.010)            |  |
|                                    |  | Speed Error (03.003)               |  |
|                                    |  | Speed Controller Output (03.004)   |  |
| Current Magnitude (00.012)         |  | Current Magnitude (00.012)         |  |
| Torque Producing Current (00.013)  |  | Torque Producing Current (00.013)  |  |
| Magnetising Current (04.017)       |  | Magnetising Current (04.017)       |  |
| Output Frequency (00.011)          |  | Output Frequency (00.011)          |  |
| Output Voltage (05.002)            |  | Output Voltage (05.002)            |  |
| Output Power (05.003)              |  | Output Power (05.003)              |  |
| D.c. Bus Voltage (05.005)          |  | D.c. Bus Voltage (05.005)          |  |
| Analog Input 1 (07.001)*           |  | Analog Input 1 (07.001)*           |  |
| Analog Input 2 (07.002)*           |  | Analog Input 2 (07.002)*           |  |
| Analog Input 3 (07.003)*           |  | Analog Input 3 (07.003)*           |  |

\*Not applicable to Unidrive M702

| 00.052 {11.020} Reset Serial Communications* |     |                   |  |  |  |    |         |  |  |
|----------------------------------------------|-----|-------------------|--|--|--|----|---------|--|--|
| RW                                           | Bit |                   |  |  |  | ND | NC      |  |  |
| OL                                           |     |                   |  |  |  |    |         |  |  |
| RFC-A                                        | ⇕   | Off (0) or On (1) |  |  |  | ⇒  | Off (0) |  |  |
| RFC-S                                        |     |                   |  |  |  |    |         |  |  |

\* Only applicable to Unidrive M701.

When *Serial Address* (00.037), *Serial Mode* (00.035), *Serial Baud Rate* (00.036), *Minimum Comms Transmit Delay* (11.026) or *Silent Period* (11.027) are modified the changes do not have an immediate effect on the serial communications system. The new values are used after the next power-up or if *Reset Serial Communications* (00.052) is set to one. *Reset Serial Communications* (00.052) is automatically cleared to zero after the communications system is updated.

| 00.053 {04.015} Motor Thermal Time Constant |     |                 |  |  |  |   |        |    |  |
|---------------------------------------------|-----|-----------------|--|--|--|---|--------|----|--|
| RW                                          | Num |                 |  |  |  |   |        | US |  |
| OL                                          |     |                 |  |  |  |   |        |    |  |
| RFC-A                                       | ⇕   | 1.0 to 3000.0 s |  |  |  | ⇒ | 89.0 s |    |  |
| RFC-S                                       |     |                 |  |  |  |   |        |    |  |

Pr **00.053** is the motor thermal time constant of the motor, and is used (along with the motor rated current Pr **00.046**, and total motor current Pr **00.012**) in the thermal model of the motor in applying thermal protection to the motor.

For further details, refer to section 8.4 *Motor thermal protection* on page 108.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 7 Running the motor

This chapter takes the new user through all the essential steps to running a motor for the first time, in each of the possible operating modes.

For information on tuning the drive for the best performance, see *Chapter 8 Optimization* on page 95.



Ensure that no damage or safety hazard could arise from the motor starting unexpectedly.



The values of the motor parameters affect the protection of the motor. The default values in the drive should not be relied upon. It is essential that the correct value is entered in Pr **00.046 Rated Current**. This affects the thermal protection of the motor.



If the drive is started using the keypad it will run to the speed defined by the keypad reference (Pr **01.017**). This may not be acceptable depending on the application. The user must check in Pr **01.017** and ensure that the keypad reference has been set to 0.



If the intended maximum speed affects the safety of the machinery, additional independent over-speed protection must be used.

### 7.1 Quick start connections

#### 7.1.1 Basic requirements

This section shows the basic connections which must be made for the drive to run in the required mode. For minimal parameter settings to run in each mode please see the relevant part of section 7.3 *Quick start commissioning / start-up* on page 78.

**Table 7-1 Minimum control connection requirements for each control mode**

| Drive control method | Requirements                                                          |
|----------------------|-----------------------------------------------------------------------|
| Terminal mode        | Drive enable<br>Speed / Torque reference<br>Run forward / Run reverse |
| Keypad mode          | Drive enable                                                          |
| Communications link  | Drive enable<br>Communications link                                   |

**Table 7-2 Minimum control connection requirements for each mode of operation**

| Operating mode                                  | Requirements                                            |
|-------------------------------------------------|---------------------------------------------------------|
| Open loop mode                                  | Induction motor                                         |
| RFC – A mode (with speed feedback)              | Induction motor with speed feedback                     |
| RFC - S mode (with speed and position feedback) | Permanent magnet motor with speed and position feedback |

#### Speed feedback

Suitable devices are:

- Incremental encoder (A, B or F, D with or without Z)
- Incremental encoder with forward and reverse outputs (F, R with or without Z)
- SINCOS encoder (with, or without Stegmann Hiperface, EnDat or SSI communications protocols)
- EnDat absolute encoder
- Resolver

#### Speed and position feedback

Suitable devices are:

- Incremental encoder (A, B or F, D with or without Z) with commutation signals (U, V, W)
- Incremental encoder with forward and reverse outputs (F, R with or without Z) and commutation outputs (U, V, W)
- SINCOS encoder (with Stegmann Hiperface, EnDat or SSI communications protocols)
- EnDat absolute encoder
- Resolver

### 7.2 Changing the operating mode

Changing the operating mode returns all parameters to their default value, including the motor parameters. *User Security Status* (Pr **00.049**) and *User Security Code* (Pr **00.034**) are not affected by this procedure).

#### Procedure

Use the following procedure only if a different operating mode is required:

- Enter either of the following values in Pr **mm.000**, as appropriate:  
1253 (50 Hz AC supply frequency)  
1254 (60 Hz AC supply frequency)
- Change the setting of Pr **00.048** as follows:

| Pr 00.048 setting     |   | Operating mode |
|-----------------------|---|----------------|
| 00.048<br>↑ Open-loop | 1 | Open-loop      |
| 00.048<br>↑ RFC-A     | 2 | RFC-A          |
| 00.048<br>↑ RFC-S     | 3 | RFC-S          |
| 00.048<br>↑ Regen     | 4 | Regen          |

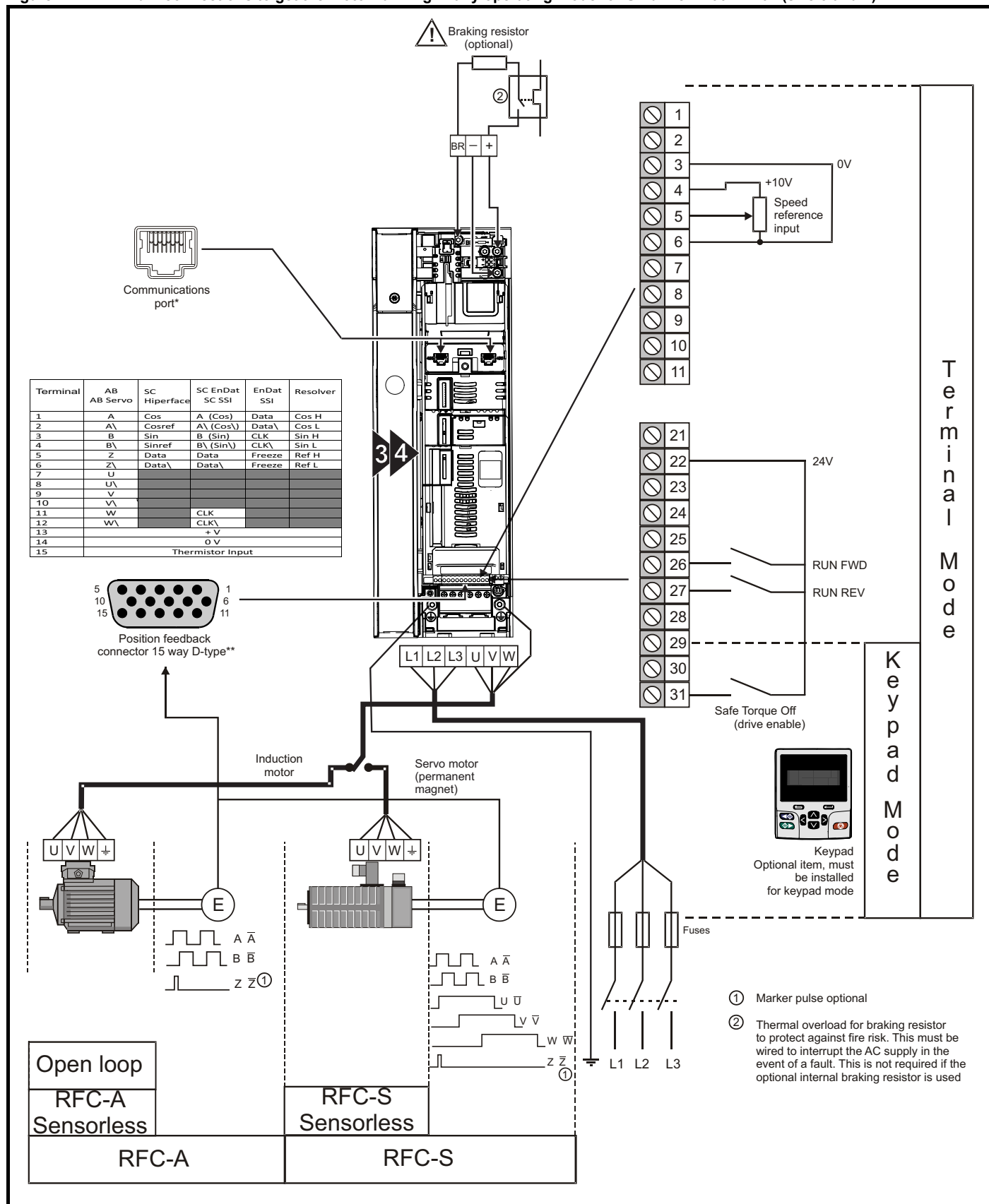
The figures in the second column apply when the communications interface is used.

3. Either:

- Press the red  reset button
- Toggle the reset digital input
- Carry out a drive reset through the communications interface by setting Pr **10.038** to 100 (ensure that Pr **mm.000** returns to 0).

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Figure 7-1 Minimum connections to get the motor running in any operating mode for Unidrive M700 / M701 (size 3 and 4)**

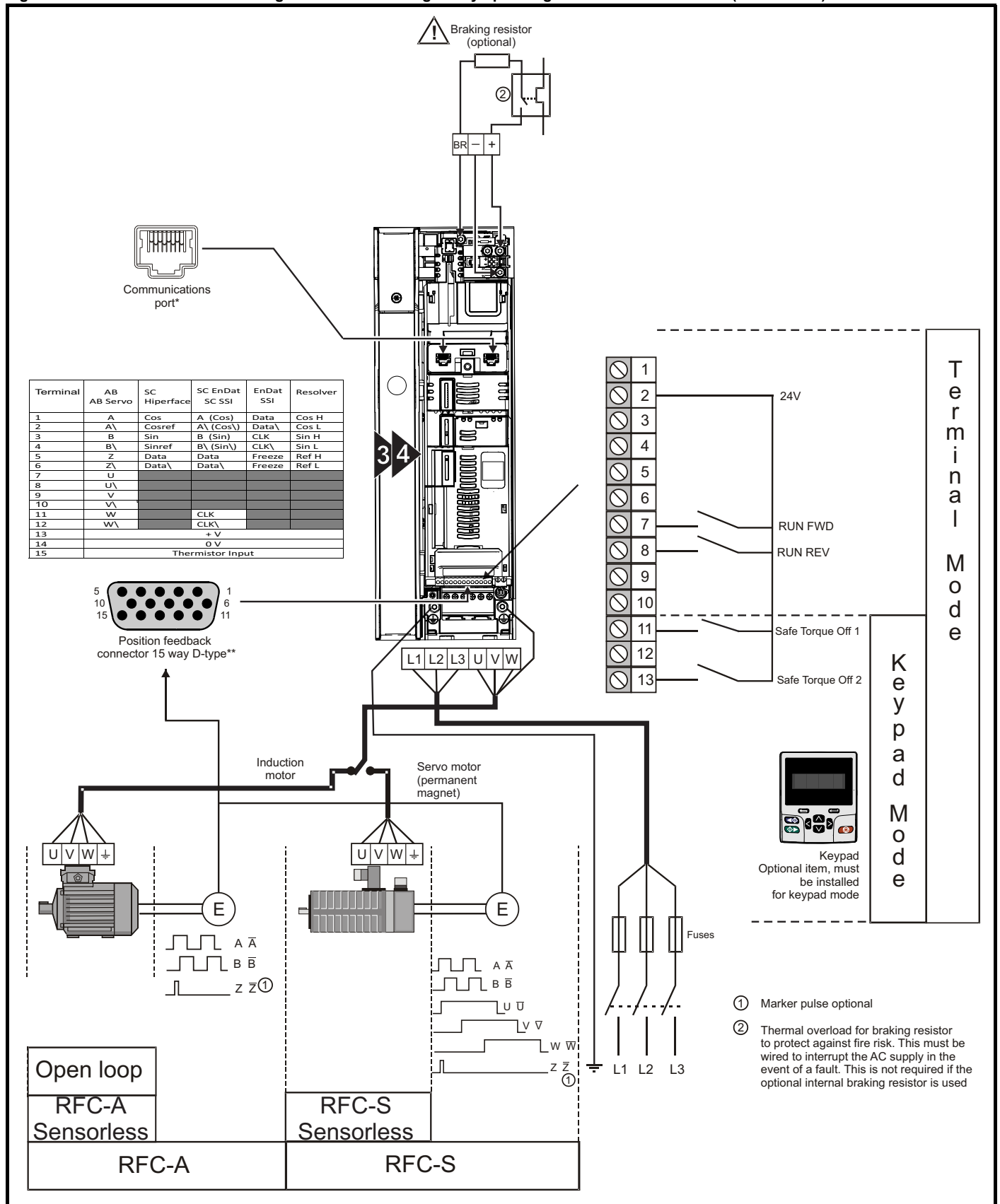


\* Ethernet fieldbus communication ports on *Unidrive M700* and EIA 485 serial communication ports on *Unidrive M701*.

\*\* Position feedback port.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 7-2 Minimum connections to get the motor running in any operating mode for Unidrive M702 (size 3 and 4)

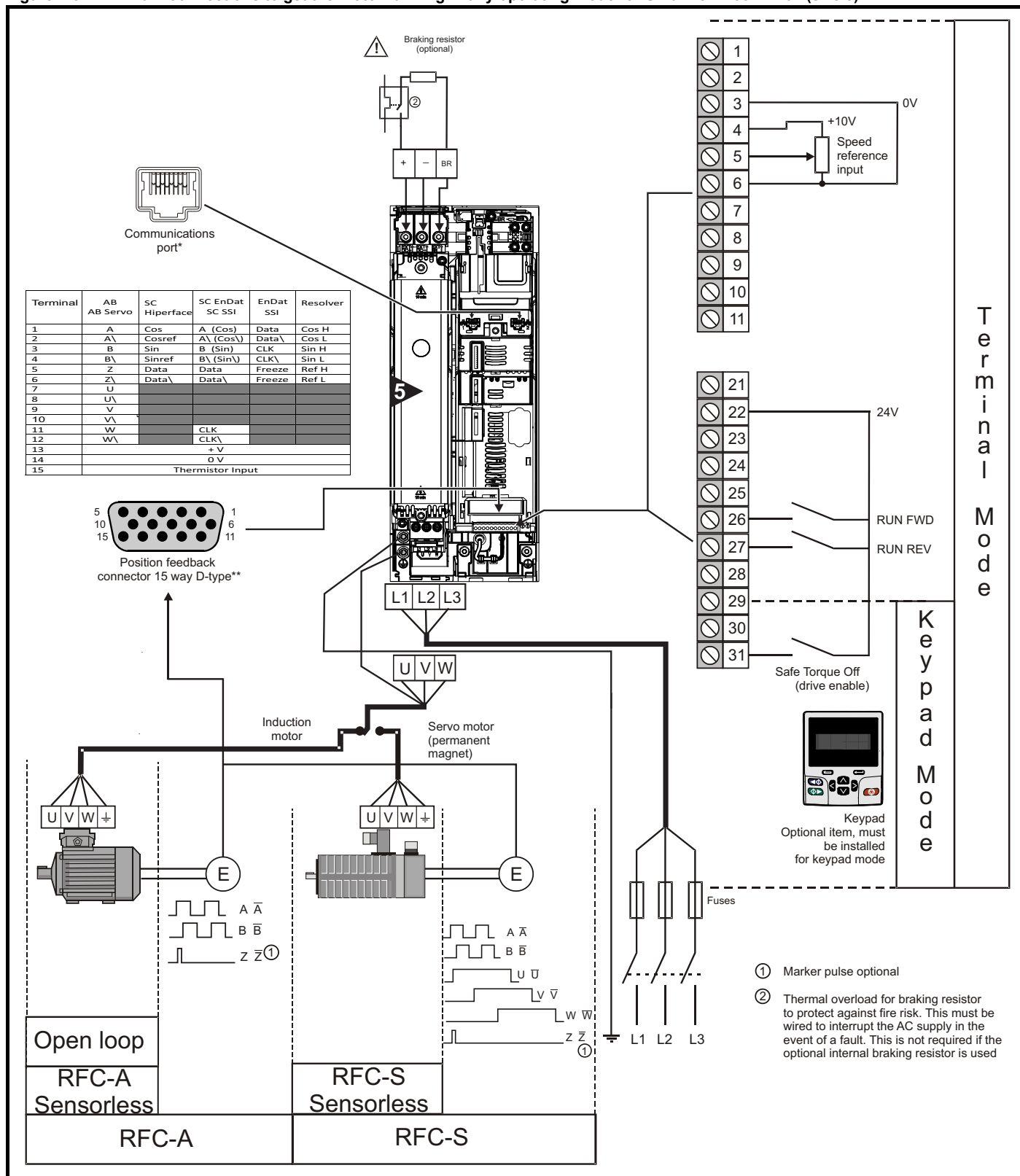


\* Ethernet fieldbus communication ports.

\*\* Position feedback port.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 7-3 Minimum connections to get the motor running in any operating mode for Unidrive M700 / M701 (size 5)

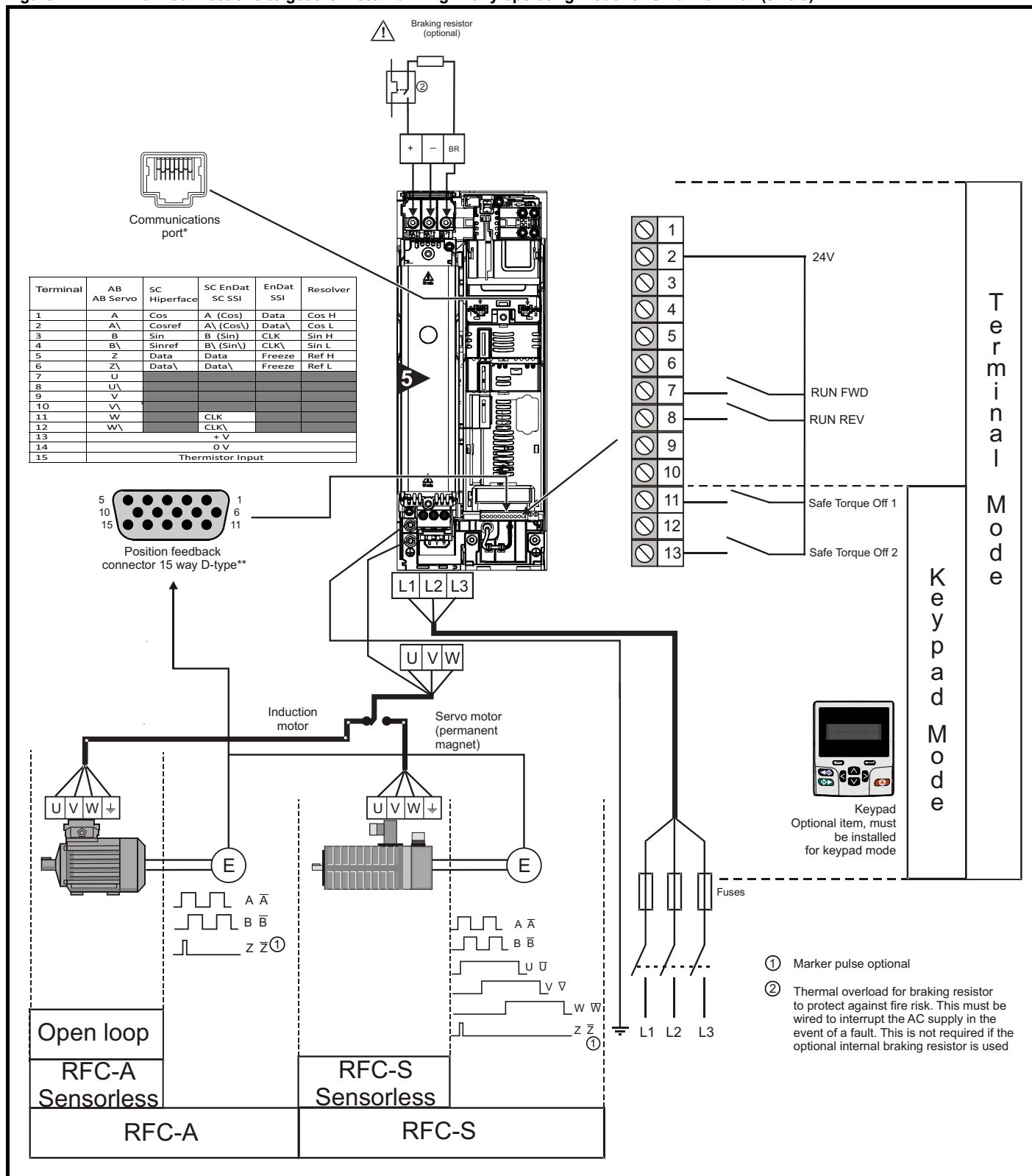


\* Ethernet fieldbus communication ports on *Unidrive M700* and EIA 485 serial communication ports on *Unidrive M701*.

\*\* Position feedback port.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 7-4 Minimum connections to get the motor running in any operating mode for Unidrive M702 (size 5)

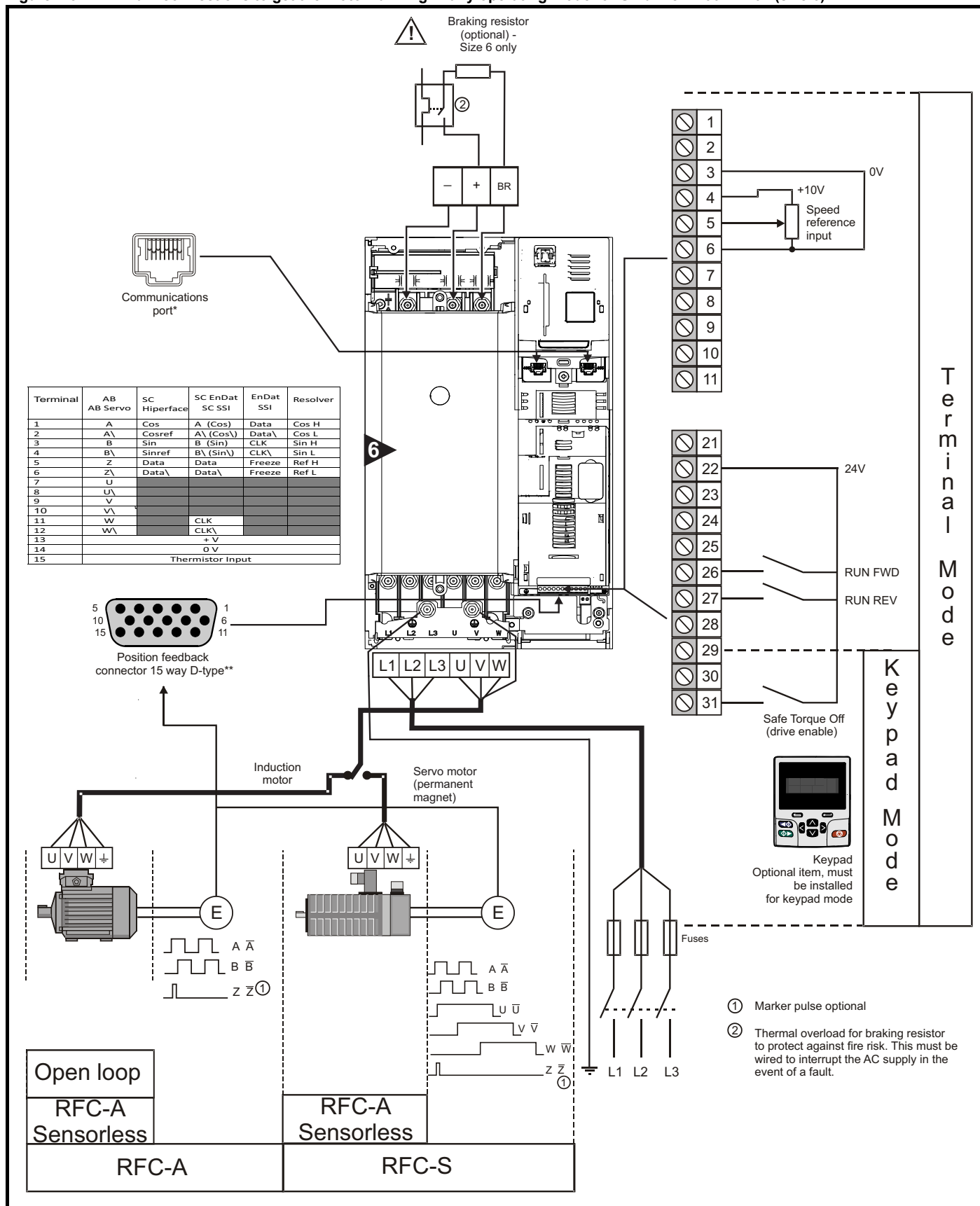


\* Ethernet fieldbus communication ports.

\*\* Position feedback port.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 7-5 Minimum connections to get the motor running in any operating mode for Unidrive M700 / M701 (size 6)

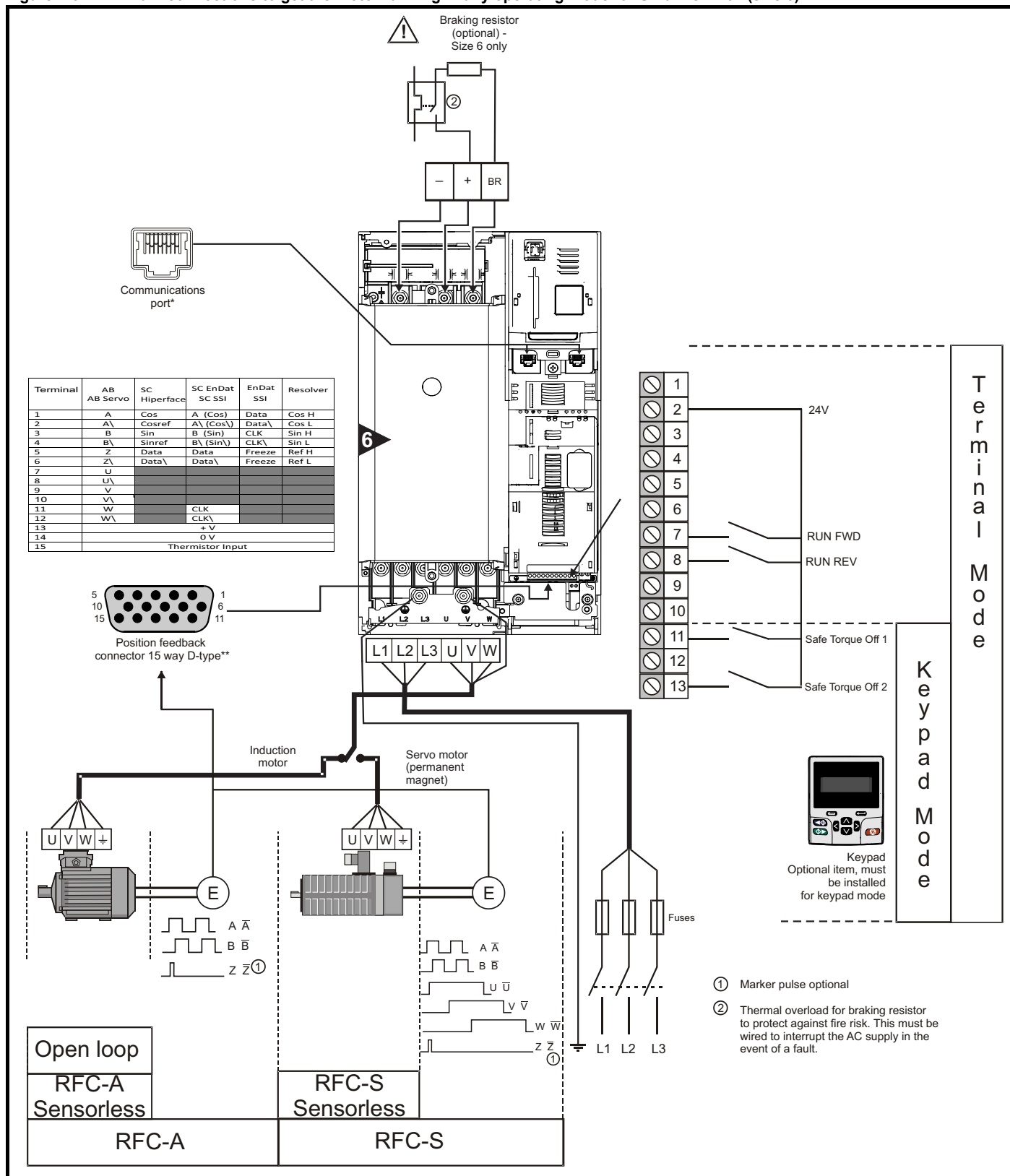


\* Ethernet fieldbus communication ports on *Unidrive M700* and EIA 485 serial communication ports on *Unidrive M701*.

\*\* Position feedback port.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 7-6 Minimum connections to get the motor running in any operating mode for Unidrive M702 (size 6)

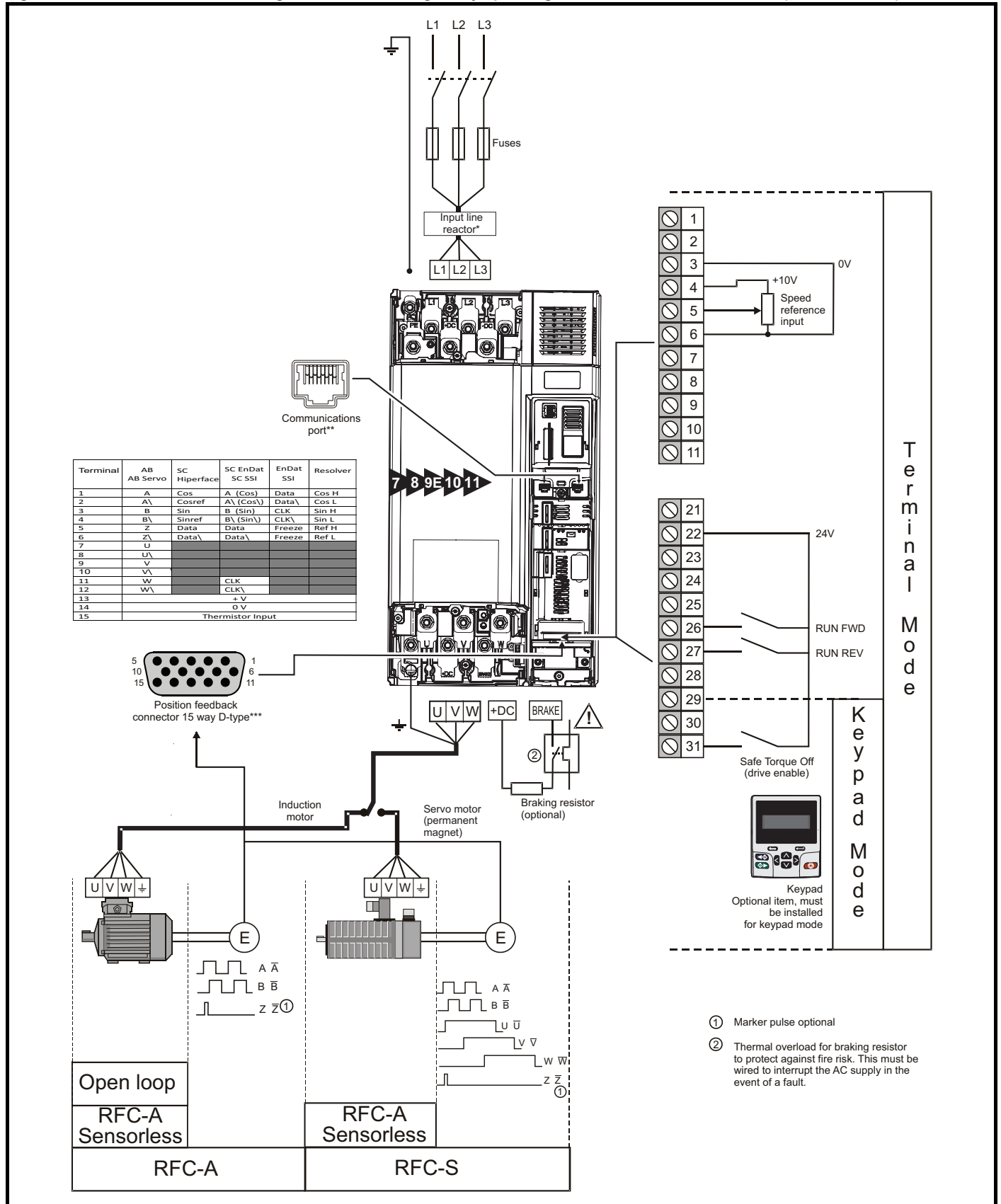


\* Ethernet fieldbus communication ports.

\*\* Position feedback port.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Figure 7-7 Minimum connections to get the motor running in any operating mode for Unidrive M700 / M701 (size 7 onwards)**



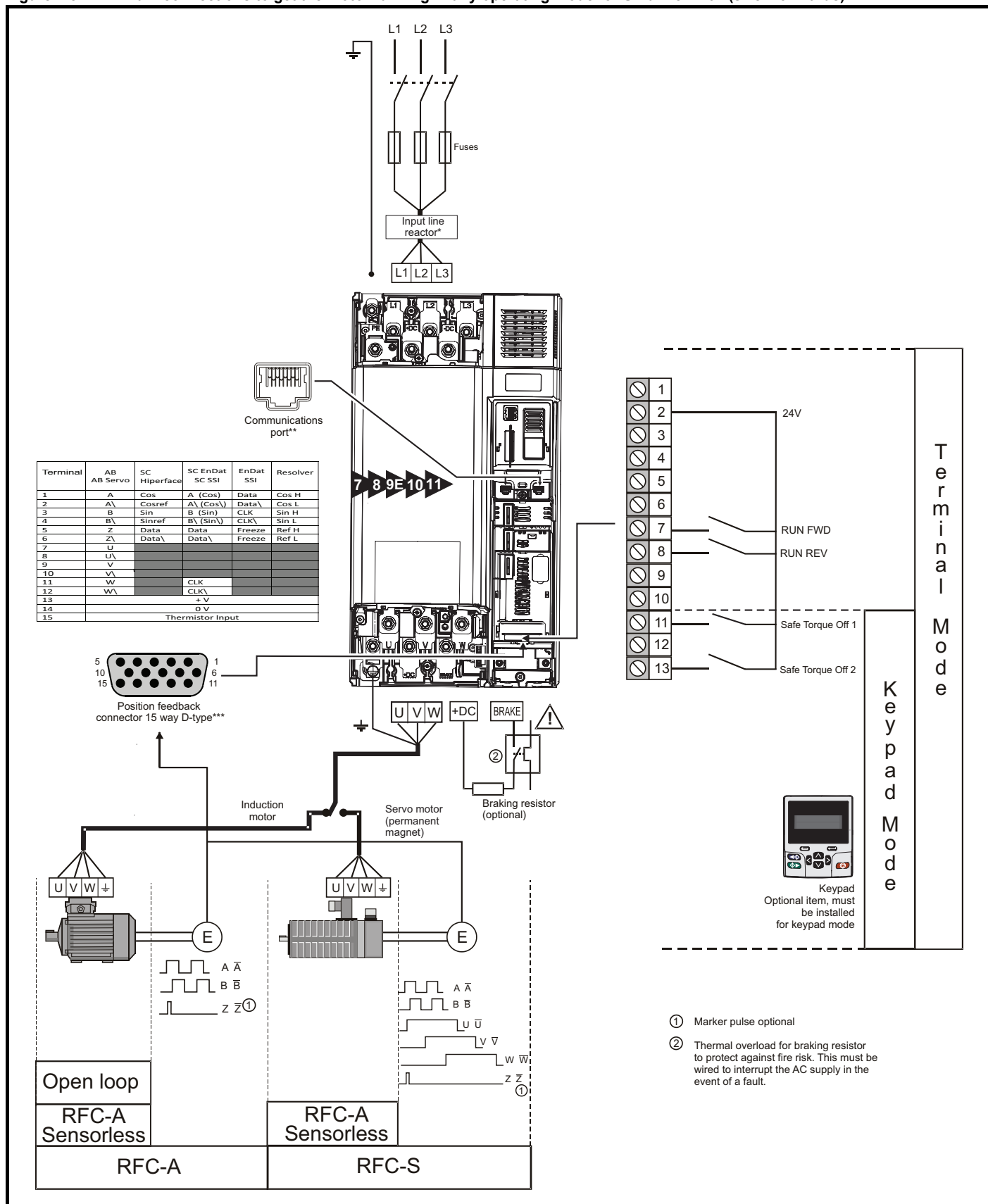
\* Required for size 9E, 10 and 11.

\*\* Ethernet fieldbus communication ports on *Unidrive M700* and EIA 485 serial communication ports on *Unidrive M701*.

\*\*\* Position feedback port.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 7-8 Minimum connections to get the motor running in any operating mode for Unidrive M702 (size 7 onwards)



\* Required for size 9E, 10 and 11.

\*\* Ethernet fieldbus communication ports.

\*\*\* Position feedback port.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 7.3 Quick start commissioning / start-up

### 7.3.1 Open loop

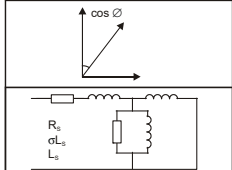
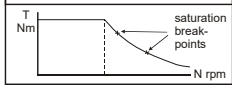
| Action                                | Detail                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |  |
|---------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|
| Before power-up                       | Ensure: <ul style="list-style-type: none"> <li>The drive enable signal is not given (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702).</li> <li>Run signal is not given</li> <li>Motor is connected</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |  |
| Power-up the drive                    | Verify that Open Loop mode is displayed as the drive powers up. If the mode is incorrect see section 5.6 <i>Changing the operating mode</i> on page 45.<br>Ensure: <ul style="list-style-type: none"> <li>Drive displays 'Inhibit'</li> </ul> If the drive trips, see section 13 <i>Diagnostics</i> on page 245.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |  |
| Enter motor nameplate details         | Enter: <ul style="list-style-type: none"> <li>Motor rated frequency in Pr <b>00.047</b> (Hz)</li> <li>Motor rated current in Pr <b>00.046</b> (A)</li> <li>Motor rated speed in Pr <b>00.045</b> (rpm)</li> <li>Motor rated voltage in Pr <b>00.044</b> (V) - check if <math>\Delta</math> or <math>\Delta</math> connection</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |  |
| Set maximum frequency                 | Enter: <ul style="list-style-type: none"> <li>Maximum frequency in Pr <b>00.002</b> (Hz)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |  |
| Set acceleration / deceleration rates | Enter: <ul style="list-style-type: none"> <li>Acceleration rate in Pr <b>00.003</b> (s/100 Hz)</li> <li>Deceleration rate in Pr <b>00.004</b> (s/100 Hz) (If braking resistor installed, set Pr <b>00.015</b> = Fast. Also ensure Pr <b>10.030</b> and Pr <b>10.031</b> and Pr <b>10.061</b> are set correctly, otherwise premature 'Brake R Too Hot' trips may be seen).</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |  |
| Motor thermistor set-up               | The motor thermistor connection is made through the drive encoder port (terminal 15). The thermistor type is selected in <i>P1 Thermistor Type</i> (03.118). On Unidrive M700 / M701, the motor thermistor can be selected in Pr <b>07.015</b> . Refer to Pr <b>07.015</b> for further information.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |  |
| Autotune                              | <p>The drive is able to perform either a stationary or a rotating autotune. The motor must be at a standstill before an autotune is enabled. A rotating autotune should be used whenever possible so the measured value of power factor of the motor is used by the drive.</p> <div style="border: 1px solid black; padding: 5px; margin-bottom: 10px;"> <p><b>WARNING</b> A rotating autotune will cause the motor to accelerate up to <math>2/3</math> base speed in the direction selected regardless of the reference provided. Once complete the motor will coast to a stop. The enable signal must be removed before the drive can be made to run at the required reference.<br/>The drive can be stopped at any time by removing the run signal or removing the drive enable.</p> </div> <ul style="list-style-type: none"> <li>A stationary autotune can be used when the motor is loaded and it is not possible to uncouple the load from the motor shaft. A stationary autotune measures the stator resistance and the transient inductance in the motor. These are required for good performance in vector control modes. A stationary autotune does not measure the power factor of the motor so the value on the motor nameplate must be entered into Pr <b>00.043</b>.</li> <li>A rotating autotune should only be used if the motor is uncoupled. A rotating autotune first performs a stationary autotune before rotating the motor at <math>2/3</math> base speed in the direction selected. The rotating autotune measures the power factor of the motor.</li> </ul> <p>To perform an autotune:</p> <ul style="list-style-type: none"> <li>Set Pr <b>00.040</b> = 1 for a stationary autotune or set Pr <b>00.040</b> = 2 for a rotating autotune</li> <li>Close the Drive Enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702). The drive will display 'Ready'.</li> <li>Close the run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702). The upper row of the display will flash 'Auto Tune' while the drive is performing the autotune.</li> <li>Wait for the drive to display 'Ready' or 'Inhibit' and for the motor to come to a standstill.</li> </ul> <p>If the drive trips, see Chapter 13 <i>Diagnostics</i> on page 245.</p> <ul style="list-style-type: none"> <li>Remove the drive enable and run signal from the drive.</li> </ul> |  |
| Save parameters                       | Select 'Save Parameters' in Pr <b>mm.000</b> (alternatively enter a value of 1001 in Pr <b>mm.000</b> ) and press the red  reset button or toggle the reset digital input.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |  |
| Run                                   | Drive is now ready to run                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |  |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 7.3.2 RFC - A mode (with position feedback)

#### Induction motor with position feedback

For simplicity only an incremental quadrature encoder will be considered here. For information on setting up one of the other supported speed feedback devices, refer to section 7.3.5 *RFC-Sensorless* on page 83.

| Action                                | Detail                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                                                                                                                                                                |
|---------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Before power-up                       | Ensure: <ul style="list-style-type: none"> <li>The drive enable signal is not given (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702).</li> <li>Run signal is not given</li> <li>Motor and feedback device are connected</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                                |
| Power-up the drive                    | Verify that RFC-A mode is displayed as the drive powers up. If the mode is incorrect see section 5.6 <i>Changing the operating mode</i> on page 45.<br>Ensure: <ul style="list-style-type: none"> <li>Drive displays 'Inhibit'</li> </ul> If the drive trips, see Chapter 13 <i>Diagnostics</i> on page 245.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                                                                                                                                                                |
| Set motor feedback parameters         | <b>Incremental encoder basic set-up</b><br>Enter: <ul style="list-style-type: none"> <li>Drive encoder type in Pr <b>03.038</b> = AB (0): Quadrature encoder</li> <li>Encoder power supply in Pr <b>03.036</b> = 5 V (0), 8 V (1) or 15 V (2).</li> </ul> <b>NOTE</b> If output voltage from the encoder is >5 V, then the termination resistors must be disabled Pr <b>03.039</b> to 0.<br><br> Setting the encoder voltage supply too high for the encoder could result in damage to the feedback device.<br><br><b>CAUTION</b> <ul style="list-style-type: none"> <li>Drive encoder Lines Per Revolution (LPR) in Pr <b>03.034</b> (set according to encoder)</li> <li>Drive encoder termination resistor setting in Pr <b>03.039</b>: <ul style="list-style-type: none"> <li>0 = A-A\, B-B\, Z-Z\ termination resistors disabled</li> <li>1 = A-A\, B-B\, termination resistors enabled, Z-Z\ termination resistors disabled</li> <li>2 = A-A\, B-B\, Z-Z\ termination resistors enabled</li> </ul> </li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                                                                                                                                                                |
| Enter motor nameplate details         | <ul style="list-style-type: none"> <li>Motor rated frequency in Pr <b>00.047</b> (Hz)</li> <li>Motor rated current in Pr <b>00.046</b> (A)</li> <li>Motor rated speed in Pr <b>00.045</b> (rpm)</li> <li>Motor rated voltage in Pr <b>00.044</b> (V) - check if <math>\Delta</math> or <math>\text{Y}</math> connection</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                                                                                                                                                |
| Set maximum speed                     | Enter: Maximum speed in Pr <b>00.002</b> (rpm)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                |
| Set acceleration / deceleration rates | Enter: <ul style="list-style-type: none"> <li>Acceleration rate in Pr <b>00.003</b> (s/1000 rpm)</li> <li>Deceleration rate in Pr <b>00.004</b> (s/1000 rpm) (If braking resistor installed, set Pr <b>00.015</b> = Fast. Also ensure Pr <b>10.030</b>, Pr <b>10.031</b> and Pr <b>10.061</b> are set correctly, otherwise premature 'Brake R Too Hot' trips may be seen).</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                                                                                                                                |
| Motor thermistor set-up               | The motor thermistor connection is made through the drive encoder port (terminal 15). The thermistor type is selected in P1 <i>Thermistor Type</i> (03.118). On Unidrive M700 / M701, the motor thermistor can be selected in Pr <b>07.015</b> . Refer to Pr <b>07.015</b> for further information.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                |
| Autotune                              | <p>The drive is able to perform either a stationary or a rotating autotune. The motor must be at a standstill before an autotune is enabled. A stationary autotune will give moderate performance whereas a rotating autotune will give improved performance as it measures the actual values of the motor parameters required by the drive.</p>  A rotating autotune will cause the motor to accelerate up to $2/3$ base speed in the direction selected regardless of the reference provided. Once complete the motor will coast to a stop. The enable signal must be removed before the drive can be made to run at the required reference. The drive can be stopped at any time by removing the run signal or removing the drive enable.<br><br><ul style="list-style-type: none"> <li>A stationary autotune can be used when the motor is loaded and it is not possible to uncouple the load from the motor shaft. The stationary autotune measures the stator resistance and transient inductance of the motor. These are used to calculate the current loop gains, and at the end of the test the values in Pr <b>00.038</b> and Pr <b>00.039</b> are updated. A stationary autotune does not measure the power factor of the motor so the value on the motor nameplate must be entered into Pr <b>00.043</b>.</li> <li>A rotating autotune should only be used if the motor is uncoupled. A rotating autotune first performs a stationary autotune before rotating the motor at <math>2/3</math> base speed in the direction selected. The rotating autotune measures the stator inductance of the motor and calculates the power factor.</li> </ul> <p>To perform an autotune:</p> <ul style="list-style-type: none"> <li>Set Pr <b>00.040</b> = 1 for a stationary autotune or set Pr <b>00.040</b> = 2 for a rotating autotune</li> <li>Close the drive enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702). The drive will display 'Ready'.</li> <li>Close the run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702). The upper row of the display will flash 'Auto Tune' while the drive is performing the autotune.</li> <li>Wait for the drive to display 'Ready' or 'Inhibit' and for the motor to come to a standstill. If the drive trips, see Chapter 13 <i>Diagnostics</i> on page 245.</li> <li>Remove the drive enable and run signal from the drive.</li> </ul> | <br> |
| Save parameters                       | Select 'Save Parameters' in Pr <b>mm.000</b> (alternatively enter a value of 1001 in Pr <b>mm.000</b> ) and press red                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                                                                                                                                |
| Run                                   | Drive is now ready to run                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                                                                                                                |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 7.3.3 RFC-A mode (Sensorless control) Induction motor with sensorless control

| Action                                                                     | Detail                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |  |
|----------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|
| Before power-up                                                            | Ensure: <ul style="list-style-type: none"> <li>The drive enable signal is not given (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702).</li> <li>Run signal is not given</li> <li>Motor is connected</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |  |
| Power-up the drive                                                         | Verify that RFC-A mode is displayed as the drive powers up. If the mode is incorrect see section 5.6 <i>Changing the operating mode</i> on page 45.<br>Ensure: <ul style="list-style-type: none"> <li>Drive displays 'Inhibit'</li> </ul> If the drive trips, see Chapter 13 <i>Diagnostics</i> on page 245.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |  |
| Select RFC-A (Sensorless control) mode and disable encoder wire-break trip | <ul style="list-style-type: none"> <li>Set Pr <b>03.024</b> = 1 or 3 to select RFC-A Sensorless mode</li> <li>Set Pr <b>03.040</b> = 0000 to disable the wire break</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |  |
| Enter motor nameplate details                                              | Enter: <ul style="list-style-type: none"> <li>Motor rated frequency in Pr <b>00.047</b> (Hz)</li> <li>Motor rated current in Pr <b>00.046</b> (A)</li> <li>Motor rated speed in Pr <b>00.045</b> (rpm)</li> <li>Motor rated voltage in Pr <b>00.044</b> (V) - check if <math>\Delta</math> or <math>\text{Y}</math> connection</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |  |
| Set maximum speed                                                          | Enter: <ul style="list-style-type: none"> <li>Maximum speed in Pr <b>00.002</b> (rpm)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |  |
| Set acceleration / deceleration rates                                      | Enter: <ul style="list-style-type: none"> <li>Acceleration rate in Pr <b>00.003</b> (s/1000rpm)</li> <li>Deceleration rate in Pr <b>00.004</b> (s/1000rpm) (If braking resistor installed, set Pr <b>00.015</b> = Fast. Also ensure Pr <b>10.030</b>, Pr <b>10.031</b> and Pr <b>10.061</b> are set correctly, otherwise premature 'Brake R Too Hot' trips may be seen).</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |  |
| Motor thermistor set-up                                                    | The motor thermistor connection is made through the drive encoder port (terminal 15). The thermistor type is selected in <i>P1 Thermistor Type</i> (03.118). On Unidrive M700 / M701, the motor thermistor can be selected in Pr <b>07.015</b> . Refer to Pr <b>07.015</b> for further information.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |  |
| Select or deselect catch a spinning motor mode                             | If catch a spinning motor mode is not required then set Pr <b>06.009</b> to 0.<br>If catch a spinning motor mode is required then leave Pr <b>06.009</b> at the default of 1, but depending on the size of the motor the value in Pr <b>05.040</b> may need to be adjusted.<br>Pr <b>05.040</b> defines a scaling function used by the algorithm that detects the speed of the motor. The default value of Pr <b>05.040</b> is 1 which is suitable for small motors (<4 kW). For larger motors the value in Pr <b>05.040</b> will need to be increased. Approximate values of Pr <b>05.040</b> for different motor sizes are as follows, 2 for 11 kW, 3 for 55 kW and 5 for 150 kW. If the value of Pr <b>05.040</b> is too large the motor may accelerate from standstill when the drive is enabled. If the value of this parameter is too small the drive will detect the motor speed as zero even if the motor is spinning.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |  |
| Autotune                                                                   | <p>The drive is able to perform either a stationary or a rotating autotune. The motor must be at a standstill before an autotune is enabled. A stationary autotune will give moderate performance whereas a rotating autotune will give improved performance as it measures the actual values of the motor parameters required by the drive.</p> <p><b>NOTE</b> It is highly recommended that a rotating autotune is performed (Pr <b>00.040</b> set to 2).</p> <p><b>WARNING</b> A rotating autotune will cause the motor to accelerate up to <math>2/3</math> base speed in the direction selected regardless of the reference provided. Once complete the motor will coast to a stop. The enable signal must be removed before the drive can be made to run at the required reference. The drive can be stopped at any time by removing the run signal or removing the drive enable.</p> <ul style="list-style-type: none"> <li>A stationary autotune can be used when the motor is loaded and it is not possible to uncouple the load from the motor shaft. The stationary autotune measures the stator resistance and transient inductance of the motor. These are used to calculate the current loop gains, and at the end of the test the values in Pr <b>00.038</b> and Pr <b>00.039</b> are updated. A stationary autotune does not measure the power factor of the motor so the value on the motor nameplate must be entered into Pr <b>00.043</b>.</li> <li>A rotating autotune should only be used if the motor is uncoupled. A rotating autotune first performs a stationary autotune before rotating the motor at <math>2/3</math> base speed in the direction selected. The rotating autotune measures the stator inductance of the motor and calculates the power factor.</li> </ul> <p>To perform an autotune:</p> <ul style="list-style-type: none"> <li>Set Pr <b>00.040</b> = 1 for a stationary autotune or set Pr <b>00.040</b> = 2 for a rotating autotune</li> <li>Close the drive enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702). The drive will display 'Ready' or 'Inhibit'.</li> <li>Close the run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702). The upper row of the display will flash 'Auto Tune' while the drive is performing the autotune.</li> <li>Wait for the drive to display 'Ready' or 'Inhibit' and for the motor to come to a standstill.</li> </ul> <p>If the drive trips, see Chapter 13 <i>Diagnostics</i> on page 245.</p> <ul style="list-style-type: none"> <li>Remove the drive enable and run signal from the drive.</li> </ul> |  |

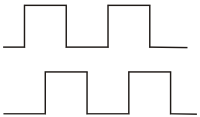
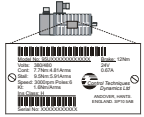
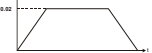
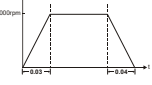
|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Action          | Detail                                                                                                                                                                                                                                                  |
|-----------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Save parameters | Select 'Save Parameters' in Pr <b>MM.000</b> (alternatively enter a value of 1001 in Pr <b>MM.000</b> ) and press red  reset button or toggle the reset digital input. |
| Run             | Drive is now ready to run                                                                                                                                            |

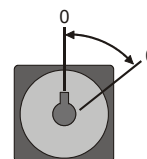
### 7.3.4 RFC-S mode (with position feedback)

#### Permanent magnet motor with position feedback

For simplicity only an incremental quadrature encoder with commutation outputs will be considered here. For information on setting up one of the other supported speed feedback devices, refer to section 7.3.5 *RFC-Sensorless* on page 83.

| Action                                | Detail                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
|---------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Before power-up                       | Ensure: <ul style="list-style-type: none"> <li>The drive enable signal is not given (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702).</li> <li>Run signal is not given</li> <li>Motor and feedback device are connected</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |
| Power-up the drive                    | Verify that RFC-S mode is displayed as the drive powers up. If the mode is incorrect see section 5.6 <i>Changing the operating mode</i> on page 45.<br>Ensure: <ul style="list-style-type: none"> <li>Drive displays 'inhibit'</li> </ul> If the drive trips, see Chapter 13 <i>Diagnostics</i> on page 245.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
| Set motor feedback parameters         | <b>Incremental encoder basic set-up</b><br>Enter: <ul style="list-style-type: none"> <li>Drive encoder type in Pr <b>03.038</b> = AB Servo (3): Quadrature encoder with commutation outputs</li> <li>Encoder power supply in Pr <b>03.036</b> = 5 V (0), 8 V (1) or 15 V (2).</li> </ul> <b>NOTE</b><br>If output voltage from the encoder is >5 V, then the termination resistors must be disabled Pr <b>03.039</b> to 0. <div style="border: 1px solid black; padding: 5px; margin: 10px 0;">  Setting the encoder voltage supply too high for the encoder could result in damage to the feedback device. </div>  <ul style="list-style-type: none"> <li>Drive encoder Pulses Per Revolution in Pr <b>03.034</b> (set according to encoder)</li> <li>Drive encoder termination resistor setting in Pr <b>03.039</b>: <ul style="list-style-type: none"> <li>0 = A-A\, B-B\, Z-Z\ termination resistors disabled</li> <li>1 = A-A\, B-B\, termination resistors enabled, Z-Z\ termination resistors disabled</li> <li>2 = A-A\, B-B\, Z-Z\ termination resistors enabled</li> </ul> </li> </ul> |
| Enter motor nameplate details         | Enter: <ul style="list-style-type: none"> <li>Motor rated current in Pr <b>00.046</b> (A)</li> </ul> Ensure that this equal to or less than the Heavy Duty rating of the drive otherwise 'Motor Too Hot' trips may occur during the autotune. <ul style="list-style-type: none"> <li>Number of poles in Pr <b>00.042</b></li> <li>Motor rated voltage in Pr <b>00.044</b> (V)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |
| Set maximum speed                     | Enter: <ul style="list-style-type: none"> <li>Maximum speed in Pr <b>00.002</b> (rpm)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |
| Set acceleration / deceleration rates | Enter: <ul style="list-style-type: none"> <li>Acceleration rate in Pr <b>00.003</b> (s/1000 rpm)</li> <li>Deceleration rate in Pr <b>00.004</b> (s/1000 rpm) (If braking resistor installed, set Pr <b>00.015</b> = Fast. Also ensure Pr <b>10.030</b>, Pr <b>10.031</b> and Pr <b>10.061</b> are set correctly, otherwise premature 'Brake R Too Hot' trips may be seen).</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |
| Motor thermistor set-up               | The motor thermistor connection is made through the drive encoder port (terminal 15). The thermistor type is selected in <i>P1 Thermistor Type</i> (03.118). On Unidrive M700 / M701, the motor thermistor can be selected in Pr <b>07.015</b> . Refer to Pr <b>07.015</b> for further information.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |

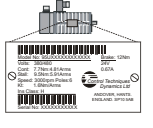
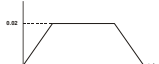
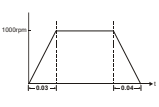
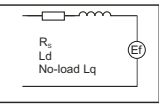
| Safety information | Product information                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Action             | Detail                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
| Autotune           | <p>The drive is able to perform either a stationary or a rotating autotune. The motor must be at a standstill before an autotune is enabled. A stationary autotune will give moderate performance whereas a rotating autotune will give improved performance as it measures the actual values of the motor parameters required by the drive. The drive is able to perform a stationary, rotating, mechanical load measurement or locked rotor test autotune. The motor must be at a standstill before an autotune is enabled. It is suggested that a rotating auto tune is used for accurate measurement for position feedback phase angle.</p> <ul style="list-style-type: none"> <li>A stationary autotune can be used when the motor is loaded and it is not possible to uncouple the load from the motor shaft. A stationary autotune is performed to locate the flux axis of the motor. The stationary autotune measures the stator resistance, inductance in flux axis, maximum deadtime compensation, inductance in torque axis with no load on the motor and current at maximum deadtime compensation of the motor. These are used to calculate the current loop gains, and at the end of the test the values in Pr <b>00.038</b> and Pr <b>00.039</b> are updated. If Sensorless mode is not selected then <i>Position Feedback Phase Angle</i> (00.043) is set-up for the selected position feedback.</li> <li>A rotating autotune should only be used if the motor is uncoupled. The rotating autotune will rotate the motor by up to 2 mechanical revolutions in the direction selected, regardless of the reference provided to obtain the position feedback phase angle. A stationary autotune is then performed to obtain stator resistance, inductance in flux axis, maximum deadtime compensation, inductance in torque axis with no load on the motor and current at maximum deadtime compensation of the motor. From the above obtained parameters the current loop gains are calculated, and at the end of the test the values in Pr <b>00.038</b> and Pr <b>00.039</b> are updated.</li> </ul> <div style="border: 1px solid black; padding: 5px; margin-top: 10px;">  <p>The rotating autotune will rotate the motor by up to 2 mechanical revolutions in the direction selected, regardless of the reference provided. After a short delay, the motor is further rotated through a electrical revolution. The enable signal must be removed before the drive can be made to run at the required reference. The drive can be stopped at any time by removing the run signal or removing the drive enable.</p> </div> <p>To perform an autotune:</p> <ul style="list-style-type: none"> <li>Set Pr <b>00.040</b> = 1 for a stationary autotune, Pr <b>00.040</b> = 2 for a rotating autotune.</li> <li>Close the run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).</li> <li>Close the drive enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702). The upper row of the display will flash 'Auto Tune' while the drive is performing the test.</li> <li>Wait for the drive to display 'Ready' or 'Inhibit' and for the motor to come to a standstill.</li> </ul> <p>If the drive trips it cannot be reset until the drive enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 &amp; 13 on Unidrive M702) has been removed. See section 13 <i>Diagnostics</i> on page 245.</p> <ul style="list-style-type: none"> <li>Remove the drive enabled and run signal from the drive.</li> </ul> |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
| Save parameters    | <p>Select 'Save Parameters' in Pr <b>MM.000</b> (alternatively enter a value of 1001 in Pr <b>MM.000</b>) and press red </p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
| Run                | <p>Drive is now ready to run</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 7.3.5 RFC-Sensorless

#### Permanent magnet motor without position feedback

| Action                                | Detail                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                                                                                       |
|---------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------|
| Before power-up                       | Ensure: <ul style="list-style-type: none"> <li>The drive enable signal is not given (terminal 31 on Unidrive M700/M701 and terminal 11 &amp; 13 on Unidrive M702).</li> <li>Run signal is not given</li> <li>Motor is connected</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |    |
| Power-up the drive                    | Verify that RFC-S mode is displayed as the drive powers up. If the mode is incorrect see section 5.6 <i>Changing the operating mode</i> on page 45, otherwise restore parameter defaults (see section 5.8 <i>Restoring parameter defaults</i> on page 45).<br>Ensure: <ul style="list-style-type: none"> <li>Drive displays 'inhibit'</li> </ul> If the drive trips, see Chapter 13 <i>Diagnostics</i> on page 245.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |    |
| Enter motor nameplate details         | Enter: <ul style="list-style-type: none"> <li>Motor rated current in Pr <b>00.046</b> (A)<br/>Ensure that this equal to or less than the Heavy Duty rating of the drive otherwise 'Motor Too Hot' trips may occur during the autotune.</li> <li>Number of poles in Pr <b>00.042</b></li> <li>Motor rated voltage in Pr <b>00.044</b> (V)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |    |
| Set maximum speed                     | Enter: <ul style="list-style-type: none"> <li>Maximum speed in Pr <b>00.002</b> (rpm)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |    |
| Set acceleration / deceleration rates | Enter: <ul style="list-style-type: none"> <li>Acceleration rate in Pr <b>00.003</b> (s/1000 rpm). It is recommended that the ramp rates are increased from the default value of 0.200 s/1000 rpm.</li> <li>Deceleration rate in Pr <b>00.004</b> (s/1000 rpm) (If braking resistor installed, set Pr <b>00.015</b> = Fast. Also ensure Pr <b>10.030</b>, Pr <b>10.031</b> and Pr <b>10.061</b> are set correctly, otherwise premature 'Brake R Too Hot' trips may be seen).</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |    |
| Set stop mode                         | Enter: <ul style="list-style-type: none"> <li>Set Stop Mode to Ramp in Pr <b>06.001</b></li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                                                                       |
| Set hold zero speed                   | Enter: <ul style="list-style-type: none"> <li>Set Hold Zero Speed to Off (0) in Pr <b>06.008</b>.</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                       |
| Autotune                              | The drive is able to perform a stationary autotune. The motor must be at a standstill before an autotune is enabled. A stationary autotune will give moderate performance. <ul style="list-style-type: none"> <li>A stationary autotune is performed to locate the flux axis of the motor. The stationary autotune measures the stator resistance, inductance in flux axis, inductance in torque axis with no load on the motor and values relating to deadtime compensation from the drive. Measured values are used to calculate the current loop gains, and at the end of the test the values in Pr <b>00.038</b> and Pr <b>00.039</b> are updated.</li> </ul> To perform an autotune: <ul style="list-style-type: none"> <li>Set Pr <b>00.040</b> = 1 or 2 for a stationary autotune. (Both perform the same tests).</li> <li>Close the run signal (terminal 26 or 27 on Unidrive M700/M701 and terminal 7 or 8 on Unidrive M702).</li> <li>Close the drive enable signal (terminal 31 on Unidrive M700/M701 and terminal 11 &amp; 13 on Unidrive M702). The upper row of the display will flash 'Auto Tune' while the drive is performing the test.</li> <li>Wait for the drive to display 'Ready' or 'Inhibit' and for the motor to come to a standstill.</li> </ul> If the drive trips it cannot be reset until the drive enable signal (terminal 31) has been removed. See Chapter 13 <i>Diagnostics</i> on page 245. <ul style="list-style-type: none"> <li>Remove the drive enabled and run signal from the drive.</li> </ul> |  |
| Check Saliency                        | In sensorless mode, when the motor speed is below Pr <b>00.045</b> / 10, a special low speed algorithm must be used to control the motor. There are two modes available, with the mode chosen based on the saliency of the motor.<br>The ratio No-load L <sub>q</sub> (Pr <b>00.056</b> ) / L <sub>d</sub> (Pr <b>05.024</b> ) provides a measure of the saliency. If this value is > 1.1, then Injection (0) mode may be used. Current (2) mode may be used (but with limitations). If this value is < 1.1, then Current (2) mode must be used (this is the default of Pr <b>05.064</b> ).                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |                                                                                       |
| Save parameters                       | Select 'Save Parameters' in Pr <b>mm.000</b> (alternatively enter a value of 1001 in Pr <b>mm.000</b> ) and press red                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                                                                       |
| Run                                   | Drive is now ready to run                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |  |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 7.4 Setting up a feedback device

### 7.4.1 P1 position interface

This section shows the parameter settings which must be made to use each of the compatible feedback device types with P1 position interface on the drive. For more information on the parameters listed here please refer to the *Parameter Reference Guide*.

**Table 7-3 Parameters required for feedback device set-up on the P1 position interface**

| Parameter                               | AB, FD, FR,<br>AB Servo, FD Servo,<br>FR Servo, SC,<br>SC Servo | SC<br>Hiperface | SC<br>EnDat | EnDat | SC SSI | SSI | SC BiSS | BiSS | Resolver |
|-----------------------------------------|-----------------------------------------------------------------|-----------------|-------------|-------|--------|-----|---------|------|----------|
| P1 Marker Mode (03.031)                 | ✓                                                               |                 |             |       |        |     |         |      |          |
| P1 Rotary Turns Bits (03.033)           |                                                                 | •               | •           | •     | ✓      | ✓   | ✓       | ✓    |          |
| P1 Rotary Lines Per Revolution (03.034) | ✓                                                               | •               | •           |       | ✓      |     | ✓       |      |          |
| P1 Comms Bits (03.035)                  |                                                                 | •               | •           | •     | ✓      | ✓   | ✓       | ✓    |          |
| P1 Supply Voltage (03.036)*             | ✓                                                               | ✓               | ✓           | ✓     | ✓      | ✓   | ✓       | ✓    |          |
| P1 Comms Baud Rate (03.037)             |                                                                 |                 | ✓           | ✓     | ✓      | ✓   | ✓       | ✓    |          |
| P1 Device Type (03.038)                 | ✓                                                               | ✓               | ✓           | ✓     | ✓      | ✓   | ✓       | ✓    | ✓        |
| P1 Auto-configuration Select (03.041)   |                                                                 | ✓               | ✓           | ✓     |        |     |         |      |          |
| P1 SSI Binary Mode (03.048)             |                                                                 |                 |             |       | ✓      | ✓   | ✓       | ✓    |          |
| P1 Resolver Poles (03.065)              |                                                                 |                 |             |       |        |     |         |      | ✓        |
| P1 Resolver Excitation (03.066)         |                                                                 |                 |             |       |        |     |         |      | ✓        |
| P1 Additional Configuration (03.074)    |                                                                 |                 |             |       |        |     | ✓       | ✓    |          |

✓ Information required to be entered by the user.

- Parameter can be set-up automatically by the drive through auto-configuration parameter. Must be set by the user if auto-configuration is disabled (i.e. Pr **03.041** = Disabled (0)).

\* Pr **03.036**: If the output voltage from the encoder is >5 V, then termination resistors must be disabled by setting Pr **03.039** to 0.

Table 7-3 shows a summary of the parameters required to set-up each feedback device. More detailed information follows.

### 7.4.2 P1 position interface: Detailed feedback device commissioning / start-up information

| Standard quadrature encoder with or without commutation signals (A, B, Z or A, B, Z, U, V, W), or Sincos encoder with or without UVW commutation signals |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
|----------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|---|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|-------------|---|---|---|---|---|---|---|---|--------------------------------------------------------------------------|---|---|---|---|-------------------------------------------------------|---|---|---|---|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---|---|---|---|-------------------------------------------------------------------------------------------------------------------------------|
| Device Type (03.038)                                                                                                                                     | <b>AB</b> (0) for a quadrature encoder without commutation signals *<br><b>AB Servo</b> (3) for a quadrature encoder with commutation signals<br><b>SC</b> (6) for a Sincos encoder without commutation signals *<br><b>SC Servo</b> (12) for a Sincos encoder with commutation signals                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Supply Voltage (03.036)                                                                                                                                  | <b>5 V</b> (0), <b>8 V</b> (1) or <b>15 V</b> (2)<br><div>NOTE</div> If output voltage from the encoder is >5 V, then the termination resistors must be disabled. Set Pr <b>03.039</b> to 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Rotary Line Per Revolution (03.034)                                                                                                                      | Set to the number of lines or sine waves per revolution of the encoder.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Termination Select (03.039)<br>(AB or AB Servo only)                                                                                                     | <b>0</b> = A, B, Z termination resistors disabled<br><b>1</b> = A, B termination resistors enabled and Z termination resistors disabled<br><b>2</b> = A, B, Z termination resistors enabled                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Marker Mode (03.031)                                                                                                                                     | <table><thead><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr></thead><tbody><tr><td>x</td><td>x</td><td>x</td><td>1</td><td>No action is taken unless marker flag is zero before marker event occurs</td></tr><tr><td>x</td><td>x</td><td>1</td><td>x</td><td>Pr <b>03.028</b> and Pr <b>03.058</b> are set to zero</td></tr><tr><td>x</td><td>1</td><td>x</td><td>x</td><td>Pr <b>03.028</b>, Pr <b>03.029</b>, Pr <b>03.030</b> and the related part of Pr <b>03.058</b> are not reset. Pr <b>03.058</b> is transferred to Pr <b>03.059</b> and Pr <b>03.032</b> is set to 1.</td></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Undefined state region range is reduced from -30 mV to 30 mV. The marker pulse is only recognized if the pulse is 10 μs wide.</td></tr></tbody></table> | Bit |   |                                                                                                                                                                                                      |  | Description | 3 | 2 | 1 | 0 | x | x | x | 1 | No action is taken unless marker flag is zero before marker event occurs | x | x | 1 | x | Pr <b>03.028</b> and Pr <b>03.058</b> are set to zero | x | 1 | x | x | Pr <b>03.028</b> , Pr <b>03.029</b> , Pr <b>03.030</b> and the related part of Pr <b>03.058</b> are not reset. Pr <b>03.058</b> is transferred to Pr <b>03.059</b> and Pr <b>03.032</b> is set to 1. | 1 | x | x | x | Undefined state region range is reduced from -30 mV to 30 mV. The marker pulse is only recognized if the pulse is 10 μs wide. |
| Bit                                                                                                                                                      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |     |   | Description                                                                                                                                                                                          |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| 3                                                                                                                                                        | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 1   | 0 |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| x                                                                                                                                                        | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | 1 | No action is taken unless marker flag is zero before marker event occurs                                                                                                                             |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| x                                                                                                                                                        | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 1   | x | Pr <b>03.028</b> and Pr <b>03.058</b> are set to zero                                                                                                                                                |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| x                                                                                                                                                        | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | x | Pr <b>03.028</b> , Pr <b>03.029</b> , Pr <b>03.030</b> and the related part of Pr <b>03.058</b> are not reset. Pr <b>03.058</b> is transferred to Pr <b>03.059</b> and Pr <b>03.032</b> is set to 1. |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| 1                                                                                                                                                        | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | x | Undefined state region range is reduced from -30 mV to 30 mV. The marker pulse is only recognized if the pulse is 10 μs wide.                                                                        |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Error Detection Level (03.040)                                                                                                                           | <table><thead><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr></thead><tbody><tr><td>x</td><td>x</td><td>x</td><td>1</td><td>Enable wire break detection</td></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Disable trips <i>Encoder 1 to Encoder 6</i></td></tr></tbody></table>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | Bit |   |                                                                                                                                                                                                      |  | Description | 3 | 2 | 1 | 0 | x | x | x | 1 | Enable wire break detection                                              | 1 | x | x | x | Disable trips <i>Encoder 1 to Encoder 6</i>           |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Bit                                                                                                                                                      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |     |   | Description                                                                                                                                                                                          |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| 3                                                                                                                                                        | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 1   | 0 |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| x                                                                                                                                                        | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | 1 | Enable wire break detection                                                                                                                                                                          |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| 1                                                                                                                                                        | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | x | Disable trips <i>Encoder 1 to Encoder 6</i>                                                                                                                                                          |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |

\* These settings should only be used in RFC-A mode. If used in RFC-S mode a phase offset test must be performed after every power up.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### Incremental encoder with Frequency and Direction (F and D) or Forward and Reverse (CW and CCW) signals with or without commutation signals.

| Device Type (03.038)                | <b>FD</b> (1) for frequency and direction signals without commutation signals*<br><b>FR</b> (3) for forward and reverse signals without commutation signals*<br><b>FD Servo</b> (4) for frequency and direction signals with commutation signals<br><b>FR Servo</b> (5) for forward and reverse signals with commutation signals                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
|-------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|---|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|-------------|---|---|---|---|---|---|---|---|--------------------------------------------------------------------------|---|---|---|---|-------------------------------------------------------|---|---|---|---|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---|---|---|---|-------------------------------------------------------------------------------------------------------------------------------|
| Supply Voltage (03.036)             | <b>5 V</b> (0), <b>8 V</b> (1) or <b>15 V</b> (2)<br><b>NOTE</b><br>If output voltage from the encoder is >5 V, then the termination resistors must be disabled. Set Pr <b>03.039</b> to 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Rotary Line Per Revolution (03.034) | Set to the number of pulses per revolution of the encoder divided by 2.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Termination Select (03.039)         | 0 = F or CW, D or CCW, Z termination resistors disabled<br>1 = F or CW, D or CCW termination resistors enabled and Z termination resistors disabled<br>2 = For CW, D or CCW, Z termination resistors enabled                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |     |   |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Marker Mode (03.031)                | <table><thead><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr></thead><tbody><tr><td>x</td><td>x</td><td>x</td><td>1</td><td>No action is taken unless marker flag is zero before marker event occurs</td></tr><tr><td>x</td><td>x</td><td>1</td><td>x</td><td>Pr <b>03.028</b> and Pr <b>03.058</b> are set to zero</td></tr><tr><td>x</td><td>1</td><td>x</td><td>x</td><td>Pr <b>03.028</b>, Pr <b>03.029</b>, Pr <b>03.030</b> and the related part of Pr <b>03.058</b> are not reset. Pr <b>03.058</b> is transferred to Pr <b>03.059</b> and Pr <b>03.032</b> is set to 1.</td></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Undefined state region range is reduced from -30 mV to 30 mV. The marker pulse is only recognized if the pulse is 10 μs wide.</td></tr></tbody></table> | Bit |   |                                                                                                                                                                                                      |  | Description | 3 | 2 | 1 | 0 | x | x | x | 1 | No action is taken unless marker flag is zero before marker event occurs | x | x | 1 | x | Pr <b>03.028</b> and Pr <b>03.058</b> are set to zero | x | 1 | x | x | Pr <b>03.028</b> , Pr <b>03.029</b> , Pr <b>03.030</b> and the related part of Pr <b>03.058</b> are not reset. Pr <b>03.058</b> is transferred to Pr <b>03.059</b> and Pr <b>03.032</b> is set to 1. | 1 | x | x | x | Undefined state region range is reduced from -30 mV to 30 mV. The marker pulse is only recognized if the pulse is 10 μs wide. |
| Bit                                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |     |   | Description                                                                                                                                                                                          |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| 3                                   | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 1   | 0 |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| x                                   | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | 1 | No action is taken unless marker flag is zero before marker event occurs                                                                                                                             |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| x                                   | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 1   | x | Pr <b>03.028</b> and Pr <b>03.058</b> are set to zero                                                                                                                                                |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| x                                   | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | x | Pr <b>03.028</b> , Pr <b>03.029</b> , Pr <b>03.030</b> and the related part of Pr <b>03.058</b> are not reset. Pr <b>03.058</b> is transferred to Pr <b>03.059</b> and Pr <b>03.032</b> is set to 1. |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| 1                                   | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | x | Undefined state region range is reduced from -30 mV to 30 mV. The marker pulse is only recognized if the pulse is 10 μs wide.                                                                        |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Error Detection Level (03.040)      | <table><thead><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr></thead><tbody><tr><td>x</td><td>x</td><td>x</td><td>1</td><td>Enable wire break detection</td></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Disable trips <i>Encoder 1 to Encoder 7</i></td></tr></tbody></table>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | Bit |   |                                                                                                                                                                                                      |  | Description | 3 | 2 | 1 | 0 | x | x | x | 1 | Enable wire break detection                                              | 1 | x | x | x | Disable trips <i>Encoder 1 to Encoder 7</i>           |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| Bit                                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |     |   | Description                                                                                                                                                                                          |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| 3                                   | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 1   | 0 |                                                                                                                                                                                                      |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| x                                   | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | 1 | Enable wire break detection                                                                                                                                                                          |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |
| 1                                   | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | x | Disable trips <i>Encoder 1 to Encoder 7</i>                                                                                                                                                          |  |             |   |   |   |   |   |   |   |   |                                                                          |   |   |   |   |                                                       |   |   |   |   |                                                                                                                                                                                                      |   |   |   |   |                                                                                                                               |

\* These settings should only be used in RFC-A mode. If used in RFC-S mode a phase offset test must be performed after every power up.

### Absolute Sincos encoder with Hiperface or EnDat serial communication, or Absolute EnDat communication only encoder

| Device Type (03.038)               | SC Hiperface (7) for a Sincos encoder with Hiperface serial communications<br>EnDat (8) for an EnDat communications only encoder<br>SC EnDat (9) for a Sincos encoder with EnDat serial communications                                                                                                                                                                                                                                                                                                              |     |   |                                      |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |
|------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|---|--------------------------------------|--|-------------|---|---|---|---|---|---|---|---|-----------------------------|---|---|---|---|------------------------------|---|---|---|---|--------------------------------------|
| Supply Voltage (03.036)            | 5 V (0), 8 V (1) or 15 V (2)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |     |   |                                      |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |
| Auto-configuration Select (03.041) | Auto-configuration is enabled at default and automatically sets up the following parameters.<br>Rotary Turns Bits (03.033)<br>Rotary Lines Per Revolutions (03.034)<br>Comms Bits (03.035)<br>These parameters can be entered manually when Pr 03.041 is set to Disabled (0).                                                                                                                                                                                                                                       |     |   |                                      |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |
| Comms Baud Rate (03.037)           | 100 k, 200 k, 300 k, 400 k, 500 k, 1 M, 1.5 M, 2 M, 4 M                                                                                                                                                                                                                                                                                                                                                                                                                                                             |     |   |                                      |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |
| Error Detection Level (03.040)     | <table><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr><tr><td>x</td><td>x</td><td>x</td><td>1</td><td>Enable wire break detection</td></tr><tr><td>x</td><td>x</td><td>1</td><td>x</td><td>Enable phase error detection</td></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Disable trips Encoder 1 to Encoder 6</td></tr></table> <p>So for example, to enable the wire break and phase error detection, set Pr <b>03.040</b> to 0011.</p> | Bit |   |                                      |  | Description | 3 | 2 | 1 | 0 | x | x | x | 1 | Enable wire break detection | x | x | 1 | x | Enable phase error detection | 1 | x | x | x | Disable trips Encoder 1 to Encoder 6 |
| Bit                                |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |     |   | Description                          |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |
| 3                                  | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 1   | 0 |                                      |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |
| x                                  | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | 1 | Enable wire break detection          |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |
| x                                  | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 1   | x | Enable phase error detection         |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |
| 1                                  | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | x   | x | Disable trips Encoder 1 to Encoder 6 |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                      |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
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| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Absolute SSI communications only encoder, or Absolute Sincos encoder with SSI communications**

| Device Type (03.038)                | SSI (10) for a SSI communications only encoder<br>SC SSI (11) for a Sincos encoder with SSI serial communications                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
|-------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|---|---------------------------------------------|--|-------------|---|---|---|---|---|---|---|---|-----------------------------|---|---|---|---|------------------------------|---|---|---|---|-------------------------------------------|---|---|---|---|---------------------------------------------|
| Supply Voltage (03.036)             | 5 V (0), 8 V (1) or 15 V (2)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| Rotary Line Per Revolution (03.034) | Set the number of sine waves per revolution of the encoder                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| SSI Binary Mode (03.048)            | Off = Gray Code<br>On = Binary Mode                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| Rotary Turns Bits (03.033)          | Set to the number of turns bits for the encoder (this is normally 12 bits for a SSI encoder)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| Comms Bits (03.035)                 | Total number of bits of position information (this is usually 25 bits for a SSI encoder)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| Comms Baud Rate (03.037)            | 100 k, 200 k, 300 k, 400 k, 500 k, 1 M, 1.5 M, 2 M, 4 M                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| Error Detection Level (03.040)      | <table><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr><tr><td>x</td><td>x</td><td>x</td><td>1</td><td>Enable wire break detection</td></tr><tr><td>x</td><td>x</td><td>1</td><td>x</td><td>Enable phase error detection</td></tr><tr><td>x</td><td>1</td><td>x</td><td>x</td><td>Enable SSI power supply alarm bit monitor</td></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Disable trips <i>Encoder 1 to Encoder 6</i></td></tr></table> <p>So for example, to enable the wire break and phase error detection, set Pr <b>03.040</b> to 0011.</p> | Bit |   |                                             |  | Description | 3 | 2 | 1 | 0 | x | x | x | 1 | Enable wire break detection | x | x | 1 | x | Enable phase error detection | x | 1 | x | x | Enable SSI power supply alarm bit monitor | 1 | x | x | x | Disable trips <i>Encoder 1 to Encoder 6</i> |
| Bit                                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |     |   | Description                                 |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| 3                                   | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | 1   | 0 |                                             |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| x                                   | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | x   | 1 | Enable wire break detection                 |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| x                                   | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | 1   | x | Enable phase error detection                |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| x                                   | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | x   | x | Enable SSI power supply alarm bit monitor   |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |
| 1                                   | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | x   | x | Disable trips <i>Encoder 1 to Encoder 6</i> |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                              |   |   |   |   |                                           |   |   |   |   |                                             |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
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| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
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**BiSS or SC BiSS setup**

|                                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
|-----------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------|-------------------------|---------------------|----------|-----|----------------|----------------------|-------------------------|---------------------|------|-----|-----|
| P1 Device Type (03.038)                 | BiSS (13) for a BiSS communications only encoder<br>SC BiSS (17) for Sincos encoder with BiSS communications                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| Supply Voltage (03.036)                 | 5 V (0), 8 V (1) or 15 V (2)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P1 Rotary Turns Bits (03.033)           | Set to the number of turns bits for the encoder.<br>Some BiSS encoders include zero padding either before or after the turns information (see P1 Additional Configuration (03.074) below). P1 Rotary Turns Bits (03.033) should include the actual turns bits and the additional padding.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P1 Rotary Lines Per Revolution (03.034) | SC BiSS only<br>Set to the number sine waves per revolution for the encoder.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P1 Comms Bits (03.035)                  | Set to the Total number of bits of position information in the comms message from the encoder excluding the warning and error bits. It is always assumed there is one warning bit and one error bit. The length of the position information includes any zero padding that is included by the encoder.<br><table><tr><td>Turns<br/>Padding</td><td>Turns</td><td>Position<br/>Padding</td><td>Position</td><td>/E</td><td>/W</td><td>CRC</td></tr></table> <p style="text-align: center;">← P1 Comms Bits (03.035) →</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Turns<br>Padding     | Turns                   | Position<br>Padding | Position | /E  | /W             | CRC                  |                         |                     |      |     |     |
| Turns<br>Padding                        | Turns                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | Position<br>Padding  | Position                | /E                  | /W       | CRC |                |                      |                         |                     |      |     |     |
| Comms Baud Rate (03.037)                | BiSS only<br>Set the baud required baud rate. 2Mbaud or 4Mbaud is likely to be required.<br>Any baud rate that is within the range specified for the encoder may be used. The line delay is measured during initialisation, and is used to compensate this delay during communications with the encoder. Therefore there is no timing based restriction on the length of the cable between the position feedback interface and the encoder. However, care should be taken to ensure that the wiring arrangement and the type of cable used are suitable for the selected baud rate and the distance between the position interface and the encoder. See P1 Low Speed Update Rate Active (03.063) in the Parameter Reference Guide for more details on timing restrictions related to the drive sample times.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P1 Calculation Time (03.060)            | The calculation time ( $t_{cal}$ ) may be longer than the default given in parameter 03.060. This time is referred to as $t_{busy}$ in the BiSS specification and is the time from the first rising edge of the MA signal to the rising edge of the start bit. It may be necessary to check this time with a scope if the encoder does not communicate and the data is not available from the encoder datasheet.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P1 Additional Configuration (03.074)    | The CRC polynomial and rotary turns and position padding need to be configured in this parameter. This information should be available on the encoder datasheet.<br>P1 Additional Configuration (03.074) provides configuration information, not covered by the other set-up parameters, for the position feedback device connected to the P1 position feedback interface and is specific to the type of device being used.<br>This parameter is split into 3 fields as shown below. <table><tr><td>Decimal Digits</td><td>9-6</td><td>5-3</td><td>2-0</td></tr><tr><td></td><td>CRC polynomial</td><td>Rotary Turns Padding</td><td>Rotary Position Padding</td></tr><tr><td>Commonly used value</td><td>0067</td><td>000</td><td>000</td></tr></table> <p><b>CRC polynomial</b></p> <p>The CRC polynomial is a bit representation of the terms of a polynomial used to generate the CRC applied to the position and the additional data transferred to/from the encoder via the BiSS communications channel. The standard value is 0067 which in hexadecimal is 0x0043, or in binary form is 0000 0000 0100 0011. The bits that are set to one show which terms exist in the polynomial. The standard value has bits 6, 1 and 0 set to one and gives the polynomial normally used with BiSS encoders which is <math>X^6+X^1+1</math>. If the encoder uses a different polynomial then this can be selected with the four digits (9-6). The maximum value is 511 (0x01FF), and so a polynomial up to degree 10 can be set up.</p> <p><b>Rotary Turns Padding and Rotary Position Padding</b></p> <p>The turns, and position within a turn, provided by a rotary encoder may not completely fill the number of bits provided. The unfilled bits will be padded with zeros. The total number of bits provided for the turns including zero padding is given by P1 Rotary Turns Bits (03.033). The zero padding is given by decimal digits 5 to 3 of P1 Additional Configuration (03.074). Digits 4 and 3 give the number of bits and digit 5 specifies whether the padding is on the left (0) or on the right (1). For example a value of 104 would specify 4 padding bits on the right of the turns data. The default value of 000 specifies no padding. If the padding value is outside the range +/-16 then an Encoder 14 is initiated. The total number of bits provided for position within a turn is given by:</p> <p style="text-align: center;">P1 Comms Bits (03.035) - P1 Rotary Turns Bits (03.033).</p> <p>The zero padding is given by decimal digits 2 to 0 of P1 Additional Configuration (03.074) in the same manner as is used for the turns padding. It is not possible to specify zero padding for linear encoders.</p> | Decimal Digits       | 9-6                     | 5-3                 | 2-0      |     | CRC polynomial | Rotary Turns Padding | Rotary Position Padding | Commonly used value | 0067 | 000 | 000 |
| Decimal Digits                          | 9-6                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | 5-3                  | 2-0                     |                     |          |     |                |                      |                         |                     |      |     |     |
|                                         | CRC polynomial                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Rotary Turns Padding | Rotary Position Padding |                     |          |     |                |                      |                         |                     |      |     |     |
| Commonly used value                     | 0067                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | 000                  | 000                     |                     |          |     |                |                      |                         |                     |      |     |     |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**UVW commutation signal only encoders\***

|                                       |                                                                          |
|---------------------------------------|--------------------------------------------------------------------------|
| <i>Device Type (03.038)</i>           | Commutation Only (16) for a quadrature encoder with commutation signals* |
| <i>Supply Voltage (03.036)</i>        | <b>5 V</b> (0), <b>8 V</b> (1) or <b>15 V</b> (2)                        |
| <i>Error Detection Level (03.040)</i> | Set to zero to disable wire break detection                              |

\* This feedback device provides very low resolution feedback and should not be used for applications requiring a high level of performance.

Due to the low resolution of UVW communication only encoders, it is recommended that the *P1 Feedback Filter* (03.042) is set to its maximum value. A value of 1 ms to 2 ms may also be required in the *Current Reference Filter* (00.017) and it is also recommended that the speed loop gains are set to a low value to obtain stable operation.

**Resolver**

| <i>Device Type (03.038)</i>           | Resolver (14)                                                                                                                                                                                                                                                                                                                                                                                                                                                              |     |   |                                                    |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                                                    |
|---------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|---|----------------------------------------------------|--|-------------|---|---|---|---|---|---|---|---|-----------------------------|---|---|---|---|----------------------------------------------------|
| <i>Resolver Poles (03.065)</i>        | Set number of Resolver poles<br>2 poles (1) to 20 poles (10)                                                                                                                                                                                                                                                                                                                                                                                                               |     |   |                                                    |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                                                    |
| <i>Resolver Excitation (03.066)</i>   | Set Resolver excitation voltage and frequency<br>6kHz 3V (0), 8kHz 3V (1), 6kHz 2V (2), 8kHz 2V (3)                                                                                                                                                                                                                                                                                                                                                                        |     |   |                                                    |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                                                    |
| <i>Error Detection Level (03.040)</i> | <table border="1"><thead><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr></thead><tbody><tr><td>x</td><td>x</td><td>x</td><td>1</td><td>Enable wire break detection</td></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Disable trips <i>Encoder 1</i> to <i>Encoder 6</i></td></tr></tbody></table> <p>So for example, to enable the wire break error detection, set Pr <b>03.040</b> to 0001.</p> | Bit |   |                                                    |  | Description | 3 | 2 | 1 | 0 | x | x | x | 1 | Enable wire break detection | 1 | x | x | x | Disable trips <i>Encoder 1</i> to <i>Encoder 6</i> |
| Bit                                   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |     |   | Description                                        |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                                                    |
| 3                                     | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | 1   | 0 |                                                    |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                                                    |
| x                                     | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | x   | 1 | Enable wire break detection                        |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                                                    |
| 1                                     | x                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | x   | x | Disable trips <i>Encoder 1</i> to <i>Encoder 6</i> |  |             |   |   |   |   |   |   |   |   |                             |   |   |   |   |                                                    |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 7.4.3 P2 position interface

This section shows the parameter settings which must be made to use each of the compatible feedback device types with the P2 position interface on the drive. For more information on the parameters listed here please refer to the *Parameter Reference Guide*. If the position feedback device connected to the P2 position interface is required to be used for motor control feedback then Pr **03.026** will need to be set to P2 Drive (1).

**Table 7-4 Parameters required for feedback device set-up on the P2 position interface**

| Parameter                               | AB, FD, FR | EnDat | SSI | BISS |
|-----------------------------------------|------------|-------|-----|------|
| P2 Marker Mode (03.131)                 | ✓          |       |     |      |
| P2 Rotary Turns Bits (03.133)           |            | ●     | ●   | ✓    |
| P2 Rotary Lines Per Revolution (03.134) | ✓          |       |     |      |
| P2 Comms Bits (03.135)                  |            | ●     | ●   | ✓    |
| P2 Comms Baud Rate (03.137)             |            | ✓     | ✓   | ✓    |
| P2 Device Type (03.138)                 | ✓          | ✓     | ✓   | ✓    |
| P2 Auto-configuration Select (03.141)   |            | ✓     |     |      |
| P2 Additional Configuration (03.174)    |            |       |     | ✓    |

✓ Information required to be entered by the user.

- Parameter can be set-up automatically by the drive through auto-configuration. Parameter must be set by the user if auto-configuration is disabled (i.e. Pr **03.141** = Disabled (0)).

The P2 position interface does not have its own independent power supply output. Therefore, any position feedback device connected to the P2 position interface must either share the P1 power supply output on pin 13 of the 15-way D-type, or be supplied from an external source.

#### NOTE

The termination resistors are always enabled on the P2 position interface. Wire break detection is not available when using AB, FD or FR position feedback device types on the P2 position interface.

Table 7-4 shows a summary of the parameters required to set-up each feedback device. More detailed information follows.

#### Standard quadrature encoder (A, B, Z)

| Device Type (03.138)                | AB (1) for a quadrature encoder                                                                                                        |   |   |                                                                                                                                                                                                      |     |  |  |  |             |   |   |   |   |
|-------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------|---|---|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|--|--|--|-------------|---|---|---|---|
| Rotary Line Per Revolution (03.134) | Set to the number of lines per revolution of the encoder                                                                               |   |   |                                                                                                                                                                                                      |     |  |  |  |             |   |   |   |   |
| Marker Mode (03.131)                | <table> <tr> <th colspan="4">Bit</th><th rowspan="2">Description</th></tr> <tr> <th>3</th><th>2</th><th>1</th><th>0</th></tr> </table> |   |   |                                                                                                                                                                                                      | Bit |  |  |  | Description | 3 | 2 | 1 | 0 |
| Bit                                 |                                                                                                                                        |   |   | Description                                                                                                                                                                                          |     |  |  |  |             |   |   |   |   |
| 3                                   | 2                                                                                                                                      | 1 | 0 |                                                                                                                                                                                                      |     |  |  |  |             |   |   |   |   |
| x                                   | x                                                                                                                                      | x | 1 | No action is taken unless marker flag is zero before marker event occurs                                                                                                                             |     |  |  |  |             |   |   |   |   |
| x                                   | x                                                                                                                                      | 1 | x | Pr <b>03.128</b> and Pr <b>03.158</b> are set to zero                                                                                                                                                |     |  |  |  |             |   |   |   |   |
| x                                   | 1                                                                                                                                      | x | x | Pr <b>03.128</b> , Pr <b>03.129</b> , Pr <b>03.130</b> and the related part of Pr <b>03.158</b> are not reset. Pr <b>03.158</b> is transferred to Pr <b>03.159</b> and Pr <b>03.132</b> is set to 1. |     |  |  |  |             |   |   |   |   |
| 1                                   | x                                                                                                                                      | x | x | This Bit in has no effect.                                                                                                                                                                           |     |  |  |  |             |   |   |   |   |

#### Incremental encoder with Frequency and Direction (F and D), or Forward and Reverse (CW and CCW) signals

| Device Type (03.138)                | FD (2) for frequency and direction signals without commutation signals<br>FR (3) for forward and reverse signals without commutation signals |   |   |                                                                                                                                                                                                      |     |  |  |  |             |   |   |   |   |
|-------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------|---|---|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|--|--|--|-------------|---|---|---|---|
| Rotary Line Per Revolution (03.134) | Set to the number of pulses per revolution of the encoder divided by 2                                                                       |   |   |                                                                                                                                                                                                      |     |  |  |  |             |   |   |   |   |
| Marker Mode (03.131)                | <table> <tr> <th colspan="4">Bit</th><th rowspan="2">Description</th></tr> <tr> <th>3</th><th>2</th><th>1</th><th>0</th></tr> </table>       |   |   |                                                                                                                                                                                                      | Bit |  |  |  | Description | 3 | 2 | 1 | 0 |
| Bit                                 |                                                                                                                                              |   |   | Description                                                                                                                                                                                          |     |  |  |  |             |   |   |   |   |
| 3                                   | 2                                                                                                                                            | 1 | 0 |                                                                                                                                                                                                      |     |  |  |  |             |   |   |   |   |
| x                                   | x                                                                                                                                            | x | 1 | No action is taken unless marker flag is zero before marker event occurs                                                                                                                             |     |  |  |  |             |   |   |   |   |
| x                                   | x                                                                                                                                            | 1 | x | Pr <b>03.128</b> and Pr <b>03.158</b> are set to zero                                                                                                                                                |     |  |  |  |             |   |   |   |   |
| x                                   | 1                                                                                                                                            | x | x | Pr <b>03.128</b> , Pr <b>03.129</b> , Pr <b>03.130</b> and the related part of Pr <b>03.158</b> are not reset. Pr <b>03.158</b> is transferred to Pr <b>03.159</b> and Pr <b>03.132</b> is set to 1. |     |  |  |  |             |   |   |   |   |
| 1                                   | x                                                                                                                                            | x | x | This Bit in has no effect.                                                                                                                                                                           |     |  |  |  |             |   |   |   |   |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Absolute EnDat communication only encoder**

| <i>Device Type (03.138)</i>               | <b>EnDat (4)</b> for an EnDat communications only encoder                                                                                                                                                                                                 |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                                             |
|-------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|---|---------------------------------------------|--|-------------|---|---|---|---|---|---|---|---|---------------------------------------------|
| <i>Auto-configuration Select (03.141)</i> | Auto-configuration is enabled at default and automatically sets up the following parameters:<br><i>Rotary Turns Bits (03.133)</i><br><i>Comms Bits (03.135)</i><br>These parameters can be entered manually when Pr <b>03.141</b> is set to Disabled (0). |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                                             |
| <i>Comms Baud Rate (03.137)</i>           | 100 k, 200 k, 300 k, 400 k, 500 k, 1 M, 1.5 M, 2 M, 4 M                                                                                                                                                                                                   |     |   |                                             |  |             |   |   |   |   |   |   |   |   |                                             |
| <i>Error Detection Level (03.140)</i>     | <table><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Disable trips <i>Encoder 4 to Encoder 6</i></td></tr></table>                    | Bit |   |                                             |  | Description | 3 | 2 | 1 | 0 | 1 | x | x | x | Disable trips <i>Encoder 4 to Encoder 6</i> |
| Bit                                       |                                                                                                                                                                                                                                                           |     |   | Description                                 |  |             |   |   |   |   |   |   |   |   |                                             |
| 3                                         | 2                                                                                                                                                                                                                                                         | 1   | 0 |                                             |  |             |   |   |   |   |   |   |   |   |                                             |
| 1                                         | x                                                                                                                                                                                                                                                         | x   | x | Disable trips <i>Encoder 4 to Encoder 6</i> |  |             |   |   |   |   |   |   |   |   |                                             |

**Absolute SSI communications only encoder**

| Device Type (03.138)           | SSI (5) for a SSI communications only encoder                                                                                                                                                                                                                                                                                      |     |   |                                           |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |
|--------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|---|-------------------------------------------|--|-------------|---|---|---|---|---|---|---|---|-------------------------------------------|---|---|---|---|--------------------------------------|
| SSI Binary Mode (03.148)       | Off (0) = Gray Code<br>On (1) = Binary Mode                                                                                                                                                                                                                                                                                        |     |   |                                           |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |
| Rotary Turns Bits (03.133)     | Set to the number of turns bits for the encoder (this is usually 12 bits for a multi-turn SSI encoder)                                                                                                                                                                                                                             |     |   |                                           |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |
| Comms Bits (03.135)            | Total number of bits of position information for the encoder (this is usually 25 bits for a multi-turn SSI encoder)                                                                                                                                                                                                                |     |   |                                           |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |
| Comms Baud Rate (03.137)       | 100 k, 200 k, 300 k, 400 k, 500 k, 1 M, 1.5 M, 2 M, 4 M                                                                                                                                                                                                                                                                            |     |   |                                           |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |
| Error Detection Level (03.140) | <table><tr><th colspan="4">Bit</th><th rowspan="2">Description</th></tr><tr><th>3</th><th>2</th><th>1</th><th>0</th></tr><tr><td>x</td><td>1</td><td>x</td><td>x</td><td>Enable SSI power supply alarm bit monitor</td></tr><tr><td>1</td><td>x</td><td>x</td><td>x</td><td>Disable trips Encoder 4 to Encoder 6</td></tr></table> | Bit |   |                                           |  | Description | 3 | 2 | 1 | 0 | x | 1 | x | x | Enable SSI power supply alarm bit monitor | 1 | x | x | x | Disable trips Encoder 4 to Encoder 6 |
| Bit                            |                                                                                                                                                                                                                                                                                                                                    |     |   | Description                               |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |
| 3                              | 2                                                                                                                                                                                                                                                                                                                                  | 1   | 0 |                                           |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |
| x                              | 1                                                                                                                                                                                                                                                                                                                                  | x   | x | Enable SSI power supply alarm bit monitor |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |
| 1                              | x                                                                                                                                                                                                                                                                                                                                  | x   | x | Disable trips Encoder 4 to Encoder 6      |  |             |   |   |   |   |   |   |   |   |                                           |   |   |   |   |                                      |

| P2 Device Type (03.138)              | BiSS (6) for a BiSS communications only encoder                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
|--------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------|-------------------------|---------------------|----------|-----|----------------|----------------------|-------------------------|---------------------|------|-----|-----|
| Supply Voltage (03.036)              | 5 V (0), 8 V (1) or 15 V (2)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P2 Rotary Turns Bits (03.133)        | Set to the number of turns bits for the encoder.<br>Some BiSS encoders include zero padding either before or after the turns information (see <i>P2 Additional Configuration</i> (03.174) below). <i>P2 Rotary Turns Bits</i> (03.133) should include the actual turns bits and the additional padding.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P2 Comms Bits (03.135)               | Set to the Total number of bits of position information in the comms message from the encoder excluding the warning and error bits. It is always assumed there is one warning bit and one error bit. The length of the position information includes any zero padding that is included by the encoder.<br><br><table border="1" style="margin: 10px auto; width: 80%;"> <tr> <td style="width: 15%;">Turns<br/>Padding</td><td style="width: 35%;">Turns</td><td style="width: 15%;">Position<br/>Padding</td><td style="width: 25%;">Position</td><td style="width: 5%;">/E</td><td style="width: 5%;">/W</td><td style="width: 5%;">CRC</td></tr> </table> <p style="text-align: center;">← P2 Comms Bits (03.135) →</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | Turns<br>Padding     | Turns                   | Position<br>Padding | Position | /E  | /W             | CRC                  |                         |                     |      |     |     |
| Turns<br>Padding                     | Turns                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Position<br>Padding  | Position                | /E                  | /W       | CRC |                |                      |                         |                     |      |     |     |
| P2 Comms Baud Rate (03.137)          | <i>BiSS only</i><br>Set the baud required baud rate. 2Mbaud or 4Mbaud is likely to be required.<br>Any baud rate that is within the range specified for the encoder may be used. The line delay is measured during initialisation, and used to compensate this delay during communications with the encoder.<br>Therefore there is no timing based restriction on the length of the cable between the position feedback interface and the encoder. However, care should be taken to ensure that the wiring arrangement and the type of cable used are suitable for the selected baud rate and the distance between the position interface and the encoder. See <i>P2 Low Speed Update Rate Active</i> (03.163) in the <i>Parameter Reference Guide</i> for more details on timing restrictions related to the drive sample times.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P2 Calculation Time (03.160)         | The calculation time ( $t_{cal}$ ) may be longer than the default given in parameter 03.160. This time is referred to as $t_{busy}$ in the BiSS specification and is the time from the first rising edge of the MA signal to the rising edge of the start bit. It may be necessary to check this time with a scope if the encoder does not communicate and the data is not available from the encoder datasheet.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |                      |                         |                     |          |     |                |                      |                         |                     |      |     |     |
| P2 Additional Configuration (03.174) | The CRC polynomial and rotary turns and position padding need to be configured in this parameter. This information should be available on the encoder datasheet.<br><br><i>P2 Additional Configuration</i> (03.174) provides configuration information, not covered by the other set-up parameters, for the position feedback device connected to the P2 position feedback interface and is specific to the type of device being used.<br><br>This parameter is split into 3 fields as shown below.<br><br><table border="1" style="margin: 10px auto; width: 80%;"> <tr> <th>Decimal Digits</th><th>9-6</th><th>5-3</th><th>2-0</th></tr> <tr> <td></td><td>CRC polynomial</td><td>Rotary Turns Padding</td><td>Rotary Position Padding</td></tr> <tr> <td>Commonly used value</td><td>0067</td><td>000</td><td>000</td></tr> </table> <p><b>CRC polynomial</b></p> <p>The CRC polynomial is a bit representation of the terms of a polynomial used to generate the CRC applied to the position and the additional data transferred to/from the encoder via the BiSS communications channel. The standard value is 0067 which in hexadecimal is 0x0043, or in binary form is 0000 0000 0100 0011. The bits that are set to one show which terms exist in the polynomial. The standard value has bits 6, 1 and 0 set to one and gives the polynomial normally used with BiSS encoders which is <math>X^6 + X^1 + 1</math>. If the encoder uses a different polynomial then this can be selected with the four digits (9-6). The maximum value is 511 (0x01FF), and so a polynomial up to degree 10 can be set up.</p> <p><b>Rotary Turns Padding and Rotary Position Padding</b></p> <p>The turns, and position within a turn, provided by a rotary encoder may not completely fill the number of bits provided. The unfilled bits will be padded with zeros. The total number of bits provided for the turns including zero padding is given by <i>P2 Rotary Turns Bits</i> (03.133). The zero padding is given by decimal digits 5 to 3 of <i>P2 Additional Configuration</i> (03.174). Digits 4 and 3 give the number of bits and digit 5 specifies whether the padding is on the left (0) or on the right (1). For example a value of 104 would specify 4 padding bits on the right of the turns data. The default value of 000 specifies no padding. If the padding value is outside the range +/-16 then an <i>Encoder 14</i> is initiated. The total number of bits provided for position within a turn is given by:</p> <p style="text-align: center;"><i>P2 Comms Bits</i> (03.135) – <i>P2 Rotary Turns Bits</i> (03.133).</p> <p>The zero padding is given by decimal digits 2 to 0 of <i>P2 Additional Configuration</i> (03.174) in the same manner as is used for the turns padding. It is not possible to specify zero padding for linear encoders.</p> | Decimal Digits       | 9-6                     | 5-3                 | 2-0      |     | CRC polynomial | Rotary Turns Padding | Rotary Position Padding | Commonly used value | 0067 | 000 | 000 |
| Decimal Digits                       | 9-6                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    | 5-3                  | 2-0                     |                     |          |     |                |                      |                         |                     |      |     |     |
|                                      | CRC polynomial                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | Rotary Turns Padding | Rotary Position Padding |                     |          |     |                |                      |                         |                     |      |     |     |
| Commonly used value                  | 0067                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 000                  | 000                     |                     |          |     |                |                      |                         |                     |      |     |     |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 7.5 Encoder Simulation Output Set-up

The drive supports four modes of encoder simulation output.

- Hardware mode - Incremental signals (AB, FD, FR)
- Software mode - Incremental signals (AB, FD, FR)
- Software mode - Ratio
- Software mode - Absolute SSI data

The availability of the encoder simulation output on the 15-way D-type on the drive is dependent on the type of feedback device connected to the P1 position interface. See Table 4-9 on page 32 for more information on the availability of the encoder simulation output. The status of the encoder simulation output can be seen in *Encoder Simulation Status* (03.086) as follows:

- None (0) The encoder simulation output is not enabled or is not available
- Full (1) Full encoder simulation with marker output is available
- No Marker (2) Encoder simulation without marker output is available

This section shows the parameter settings which must be made to use the encoder simulation output on the drive. For more information on the parameters listed here please refer to the Parameter Reference Guide.

### 7.5.1 Hardware mode - Incremental signals (AB, FD, or FR)

Hardware mode provides incremental signals derived via hardware from the P1 position feedback interface on the drive, with negligible delay. The supported incremental output signals are AB, FD and FR. Hardware mode only produces an output when the input device connected to the P1 position interface is AB, FD, FR, SC, SC Hiperface, SC EnDat or SC SSI type devices. It should be noted that with a SINCOS source device the output is based on the zero crossings of the sine wave inputs and does not include interpolation.

| Hardware mode set-up                                    |                                                                                                                                                                                                                                                                                  |
|---------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <i>Encoder Simulation Source</i> (03.085)               | This parameter must be set to <b>03.029</b> to select the P1 position interface as the source.                                                                                                                                                                                   |
| <i>Encoder Simulation Mode</i> (03.088)                 | Set to a value of <b>Hardware (0)</b>                                                                                                                                                                                                                                            |
| <i>Encoder Simulation Hardware Divider</i> (03.089)     | This parameter defines the divider ratio between the device connected to the P1 position feedback interface and the output.<br><b>0</b> = 1/1<br><b>1</b> = 1/2<br><b>2</b> = 1/4<br><b>3</b> = 1/8<br><b>4</b> = 1/16<br><b>5</b> = 1/32<br><b>6</b> = 1/64<br><b>7</b> = 1/128 |
| <i>Encoder Simulation Hardware Marker Lock</i> (03.090) | <b>0</b> = The marker output is derived directly from the marker input<br><b>1</b> = The incremental output signals are adjusted on each marker event so that the A and B are high with an AB type output, or F is high with an FD or FR type output                             |
| <i>Encoder Simulation Output Mode</i> (03.098)          | <b>AB/Gray</b> (0) for a AB quadrature output signals<br><b>FD/Binary</b> (1) for Frequency and Direction output signals<br><b>FR/Binary</b> (2) for Forward and Reverse output signals                                                                                          |

### 7.5.2 Software mode - Incremental signals (AB, FD, or FR)

In software mode the encoder simulation output is derived via software from the selected source with a minimum delay of 250  $\mu$ s which may be extended with *Encoder Simulation Sample Period* (03.087). For incremental output signals, the resolution of the output can be defined by either selecting the required output lines per revolution or by an output ratio.

#### Lines per revolution

The output resolution of the encoder simulation output is defined by *Encoder Simulation Output Lines Per Revolution* (03.092).

| AB quadrature output signals, software mode setup – Lines per revolution |                                                                                                                                                                                                                                                                                                                                     |
|--------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <i>Encoder Simulation Source</i> (03.085)                                | Set to the parameter number of the position source<br>Pr <b>03.029</b> to use the P1 position interface on the drive as the source.<br>Pr <b>03.129</b> to use the P2 position interface on the drive as the source.<br>This parameter can be set to any other valid position reference generated by the drive or an option module. |
| <i>Encoder Simulation Mode</i> (03.088)                                  | Set to a value of <b>Lines Per Rev (1)</b>                                                                                                                                                                                                                                                                                          |
| <i>Encoder Simulation Output Lines Per Revolution</i> (03.092)           | Set to the required output lines per revolution. The maximum output lines per revolution are 16384.                                                                                                                                                                                                                                 |
| <i>Encoder Simulation Output Mode</i> (03.098)                           | <b>AB/Gray</b> (0) for a AB quadrature output signals                                                                                                                                                                                                                                                                               |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### Frequency and Direction or Forward and Reverse output signals, software mode setup – Lines per revolution

|                                                                |                                                                                                                                                                                                                                                                                                                                     |
|----------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <i>Encoder Simulation Source (03.085)</i>                      | Set to the parameter number of the position source<br>Pr <b>03.029</b> to use the P1 position interface on the drive as the source.<br>Pr <b>03.129</b> to use the P2 position interface on the drive as the source.<br>This parameter can be set to any other valid position reference generated by the drive or an option module. |
| <i>Encoder Simulation Mode (03.088)</i>                        | Set to a value of <b>Lines Per Rev (1)</b>                                                                                                                                                                                                                                                                                          |
| <i>Encoder Simulation Output Lines Per Revolution (03.092)</i> | Set to the required output pulse per revolution divided by 2. For example if 2000 pulses per revolution is required, set this parameter to 1000.                                                                                                                                                                                    |
| <i>Encoder Simulation Output Mode (03.098)</i>                 | <b>FD/Binary</b> (1) for Frequency and Direction output signals<br><b>FR/Binary</b> (2) for Forward and Reverse output signals                                                                                                                                                                                                      |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## Ratio

In ratio mode the resolution of the input source is based on a 16 bit position feedback device (i.e. equivalent to an AB quadrature encoder with a resolution of 16384 lines per revolution). The output resolution of the encoder simulation output is defined by the ratio of *Encoder Simulation Numerator* (03.093) and *Encoder Simulation Denominator* (03.094).

### AB quadrature output signals, software mode setup – Ratio

#### Frequency and Direction or Forward and Reverse output signals, software mode setup

|                                                                                                    |                                                                                                                                                                                                                                                                                                                                     |
|----------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <i>Encoder Simulation Source</i> (03.085)                                                          | Set to the parameter number of the position source<br>Pr <b>03.029</b> to use the P1 position interface on the drive as the source.<br>Pr <b>03.129</b> to use the P2 position interface on the drive as the source.<br>This parameter can be set to any other valid position reference generated by the drive or an option module. |
| <i>Encoder Simulation Mode</i> (03.088)                                                            | Set to a value of <b>Ratio (2)</b>                                                                                                                                                                                                                                                                                                  |
| <i>Encoder Simulation Numerator</i> (03.093) and<br><i>Encoder Simulation Denominator</i> (03.094) | Set these two parameters to give the required output ratio.                                                                                                                                                                                                                                                                         |
| <i>Encoder Simulation Output Mode</i> (03.098)                                                     | <b>AB/Gray</b> (0) for a AB quadrature output signals<br><b>FD/Binary</b> (1) for Frequency and Direction output signals<br><b>FR/Binary</b> (2) for Forward and Reverse output signals                                                                                                                                             |

## Software mode - Absolute SSI data

In software mode the encoder simulation output is derived via software from the selected source with a minimum delay of 250  $\mu$ s which may be extended with *Encoder Simulation Sample Period* (03.087). In SSI output mode drive will simulate an SSI encoder, where the number of bits and the format of the position message can be adjusted.

### Absolute SSI data, software mode setup

|                                                   |                                                                                                                                                                                                                                                                                                                                     |
|---------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <i>Encoder Simulation Source</i> (03.085)         | Set to the parameter number of the position source<br>Pr <b>03.029</b> to use the P1 position interface on the drive as the source.<br>Pr <b>03.129</b> to use the P2 position interface on the drive as the source.<br>This parameter can be set to any other valid position reference generated by the drive or an option module. |
| <i>Encoder Simulation Mode</i> (03.088)           | Set to a value of <b>SSI (3)</b>                                                                                                                                                                                                                                                                                                    |
| <i>Encoder Simulation SSI Turns Bits</i> (03.096) | Set to the number of bits representing the number of turns in the position message.                                                                                                                                                                                                                                                 |
| <i>Encoder Simulation SSI Comms Bits</i> (03.097) | Set to the number bits in the whole position message.                                                                                                                                                                                                                                                                               |
| <i>Encoder Simulation Output Mode</i> (03.098)    | <b>AB/Gray</b> (0) for position data in Gray code format<br><b>FD/Binary</b> (1) or <b>FR/Binary</b> (2) for position data in binary format                                                                                                                                                                                         |

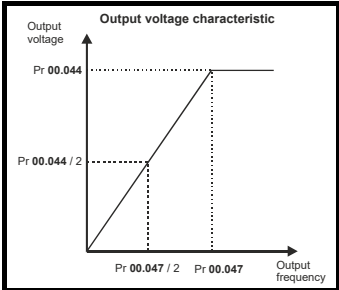
|                    |                     |                         |                         |                 |                  |                   |                     |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|---------------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | <b>Optimization</b> | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
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## 8 Optimization

This chapter takes the user through methods of optimizing the drive set-up and maximize the performance. The auto-tuning features of the drive simplify the optimization tasks.

### 8.1 Motor map parameters

#### 8.1.1 Open loop motor control

|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                                                    |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------|
| <b>Pr 00.046 {05.007} Rated Current</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | <b>Defines the maximum continuous motor current</b>                |
| <ul style="list-style-type: none"> <li>The rated current parameter must be set to the maximum continuous current of the motor. (See section 8.2 <i>Maximum motor rated current</i> on page 108, for information about setting this parameter higher than the maximum Heavy Duty current rating). The motor rated current is used in the following:</li> <li>Current limits (see section 8.3 <i>Current limits</i> on page 108, for more information)</li> <li>Motor thermal overload protection (see section 8.4 <i>Motor thermal protection</i> on page 108, for more information)</li> <li>Vector mode voltage control (see <i>Open Loop Control Mode</i> (00.007), later in this table)</li> <li>Slip compensation (see <i>Enable Slip Compensation</i> (05.027), later in this table)</li> <li>Dynamic V/F control</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                                                                    |
| <b>Pr 00.044 {05.009} Rated Voltage</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | <b>Defines the voltage applied to the motor at rated frequency</b> |
| <b>Pr 00.047 {05.006} Rated Frequency</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | <b>Defines the frequency at which rated voltage is applied</b>     |
| <p>The <i>Rated Voltage</i> (00.044) and the <i>Rated Frequency</i> (00.047) are used to define the voltage to frequency characteristic applied to the motor (see <i>Open Loop Control Mode</i> (00.007), later in this table). The <i>Rated Frequency</i> (00.047) is also used in conjunction with the motor rated speed to calculate the rated slip for slip compensation (see <i>Rated Speed</i> (00.045), later in this table).</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                    |
| <b>Pr 00.045 {05.008} Rated Speed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | <b>Defines the full load rated speed of the motor</b>              |
| <b>Pr 00.042 {05.011} Number Of Motor Poles</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    | <b>Defines the number of motor poles</b>                           |
| <p>The motor rated speed and the number of poles are used with the motor rated frequency to calculate the rated slip of induction machines in Hz.</p> $\text{Rated slip (Hz)} = \text{Motor rated frequency} - (\text{Number of pole pairs} \times [\text{Motor rated speed} / 60]) = 00.047 = \left( \frac{00.042}{2} \times \frac{00.045}{60} \right)$ <p>If <b>Pr 00.045</b> is set to 0 or to synchronous speed, slip compensation is disabled. If slip compensation is required this parameter should be set to the nameplate value, which should give the correct rpm for a hot machine. Sometimes it will be necessary to adjust this when the drive is commissioned because the nameplate value may be inaccurate. Slip compensation will operate correctly both below base speed and within the field-weakening region. Slip compensation is normally used to correct for the motor speed to prevent speed variation with load. The rated load rpm can be set higher than synchronous speed to deliberately introduce speed droop. This can be useful to aid load sharing with mechanically coupled motors.</p> <p><b>Pr 00.042</b> is also used in the calculation of the motor speed display by the drive for a given output frequency. When <b>Pr 00.042</b> is set to 'Automatic', the number of motor poles is automatically calculated from the rated frequency <b>Pr 00.047</b>, and the motor rated speed <b>Pr 00.045</b>.</p> $\text{Number of poles} = 120 \times (\text{Rated Frequency} (00.047) / \text{Rated Speed} (00.045)) \text{ rounded to the nearest even number.}$ |                                                                    |
| <b>Pr 00.043 {05.010} Rated Power Factor</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | <b>Defines the angle between the motor voltage and current</b>     |
| <p>The power factor is the true power factor of the motor, i.e. the angle between the motor voltage and current. The power factor is used in conjunction with the <i>Rated Current</i> (00.046), to calculate the rated active current and magnetising current of the motor. The rated active current is used extensively to control the drive, and the magnetising current is used in vector mode stator resistance compensation. It is important that this parameter is set up correctly. The drive can measure the motor rated power factor by performing a rotating autotune (see Autotune (Pr 00.040), overleaf).</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                    |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## Pr 00.040 {05.012} Autotune

There are two autotune tests available in open loop mode, a stationary and a rotating test. A rotating autotune should be used whenever possible so the measured value of power factor of the motor is used by the drive.

- A stationary autotune can be used when the motor is loaded and it is not possible to remove the load from the motor shaft. The stationary test measures the *Stator Resistance* (05.017), *Transient Inductance* (05.024), *Maximum Deadtime Compensation* (05.059) and *Current At Maximum Deadtime Compensation* (05.060) which are required for good performance in vector control modes (see *Open Loop Control Mode* (00.007), later in this table). The stationary autotune does not measure the power factor of the motor so the value on the motor nameplate must be entered into Pr **00.043**. To perform a Stationary autotune, set Pr **00.040** to 1, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).
- A rotating autotune should only be used if the motor is unloaded. A rotating autotune first performs a stationary autotune, as above, then a rotating test is performed in which the motor is accelerated with currently selected ramps up to a frequency of *Rated Frequency* (05.006) x 2/3, and the frequency is maintained at that level for 4 seconds. *Stator Inductance* (05.025) is measured and this value is used in conjunction with other motor parameters to calculate *Rated Power Factor* (05.010). To perform a Rotating autotune, set Pr **00.040** to 2, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).

Following the completion of an autotune test the drive will go into the inhibit state. The drive must be placed into a controlled disable condition before the drive can be made to run at the required reference. The drive can be put in to a controlled disable condition by removing the Safe Torque Off signal from terminal 31 on *Unidrive M700 / M701* and terminal 11 & 13 on *Unidrive M702*, setting the *Drive Enable* (06.015) to OFF (0) or disabling the drive via the *Control Word* (06.042) and *Control Word Enable* (06.043).

## Pr 00.007 {05.014} Open Loop Control Mode

There are several voltage modes available which fall into two categories, vector control and fixed boost.

### Vector control

Vector control mode provides the motor with a linear voltage characteristic from 0 Hz to motor *Rated Frequency* (00.047), and then a constant voltage above motor rated frequency. When the drive operates between motor rated frequency/50 and motor rated frequency/4, full vector based stator resistance compensation is applied. When the drive operates between motor rated frequency/4 and motor rated frequency/2 the stator resistance compensation is gradually reduced to zero as the frequency increases. For the vector modes to operate correctly the *Rated Power Factor* (00.043), *Stator Resistance* (05.017) are all required to be set up accurately. The drive can be made to measure these by performing an autotune (see Pr 00.040 *Autotune*). The drive can also be made to measure the stator resistance automatically every time the drive is enabled or the first time the drive is enabled after it is powered up, by selecting one of the vector control voltage modes.

(0) **Ur S** = The stator resistance is measured and the parameter for the selected motor map is over-written each time the drive is made to run. This test can only be done with a stationary motor where the flux has decayed to zero. Therefore this mode should only be used if the motor is guaranteed to be stationary each time the drive is made to run. To prevent the test from being done before the flux has decayed there is a period of 1 second after the drive has been in the ready state during which the test is not done if the drive is made to run again. In this case, previously measured values are used. Ur S mode ensures that the drive compensates for any change in motor parameters due to changes in temperature. The new value of stator resistance is not automatically saved to the drive's EEPROM.

(1) **Ur** = The stator resistance is not measured. The user can enter the motor and cabling resistance into the *Stator Resistance* (05.017). However this will not include resistance effects within the drive inverter. Therefore if this mode is to be used, it is best to use an autotune test initially to measure the stator resistance.

(3) **Ur\_Auto** = The stator resistance is measured once, the first time the drive is made to run. After the test has been completed successfully the *Open Loop Control Mode* (00.007) is changed to Ur mode. The *Stator Resistance* (05.017) parameter is written to, and along with the *Open Loop Control Mode* (00.007), are saved in the drive's EEPROM. If the test fails, the voltage mode changes to Ur mode but *Stator Resistance* (05.017) is not updated.

(4) **Ur I** = The stator resistance is measured when the drive is first made to run after each power-up. This test can only be done with a stationary motor. Therefore this mode should only be used if the motor is guaranteed to be stationary the first time the drive is made to run after each power-up. The new value of stator resistance is not automatically saved to the drive's EEPROM.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
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## Pr 00.007 {05.014} Open Loop Control Mode (cont)

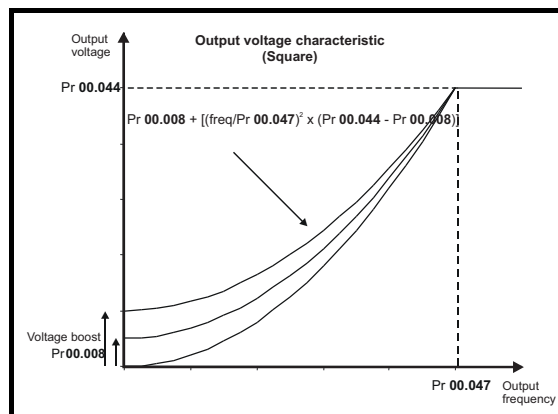
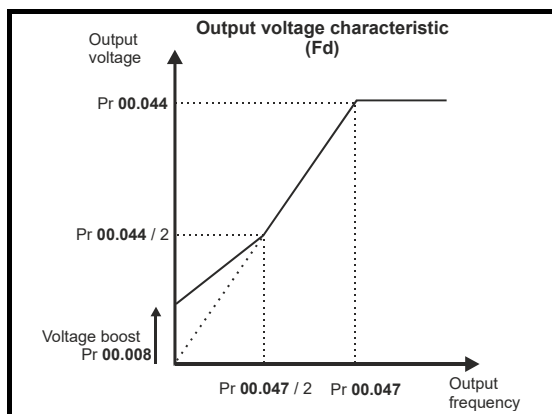
### Fixed boost

The stator resistance is not used in the control of the motor, instead a fixed characteristic with low frequency voltage boost as defined by parameter Pr 00.008, is used. Fixed boost mode should be used when the drive is controlling multiple motors. There are two settings of fixed boost available:

(2) **Fixed** = This mode provides the motor with a linear voltage characteristic from 0 Hz to *Rated Frequency* (00.047), and then a constant voltage above rated frequency.

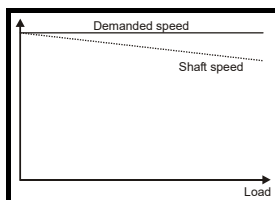
(5) **Square** = This mode provides the motor with a square law voltage characteristic from 0 Hz to *Rated Frequency* (00.047), and then a constant voltage above rated frequency. This mode is suitable for variable torque applications like fans and pumps where the load is proportional to the square of the speed of the motor shaft. This mode should not be used if a high starting torque is required.

For both these modes, at low frequencies (from 0Hz to  $\frac{1}{2} \times$  Pr 00.047) a voltage boost is applied defined by Pr 00.008 as shown below:



## Pr 05.027 Enable Slip Compensation

When a motor, being controlled in open loop mode, has load applied a characteristic of the motor is that the output speed droops in proportion to the load applied as shown:



In order to prevent the speed droop shown above slip compensation should be enabled. To enable slip compensation Pr 05.027 must be set to a 1 (this is the default setting), and the motor rated speed must be entered in Pr 00.045 (Pr 05.008).

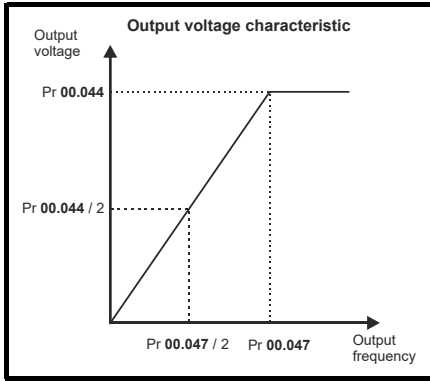
The motor rated speed parameter should be set to the synchronous speed of the motor minus the slip speed. This is normally displayed on the motor nameplate, i.e. for a typical 18.5 kW, 50 Hz, 4 pole motor, the motor rated speed would be approximately 1465 rpm. The synchronous speed for a 50 Hz, 4 pole motor is 1500 rpm, so therefore the slip speed would be 35 rpm. If the synchronous speed is entered in Pr 00.045, slip compensation will be disabled. If too small a value is entered in Pr 00.045, the motor will run faster than the demanded frequency. The synchronous speeds for 50 Hz motors with different numbers of poles are as follows:

2 pole = 3000 rpm, 4 pole = 1500 rpm, 6 pole = 1000 rpm, 8 pole = 750 rpm

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## 8.1.2 RFC-A mode

### Induction motor with Position feedback

|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                    |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------|
| <b>Pr 00.046 {05.007} Motor Rated Current</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | <b>Defines the maximum motor continuous current</b>                |
| <p>The motor rated current parameter must be set to the maximum continuous current of the motor. (See section 8.2 <i>Maximum motor rated current</i> on page 108, for information about setting this parameter higher than the maximum Heavy Duty current rating.) The motor rated current is used in the following:</p> <ul style="list-style-type: none"> <li>Current limits (see section 8.3 <i>Current limits</i> on page 108, for more information).</li> <li>Motor thermal overload protection (see section 8.4 <i>Motor thermal protection</i> on page 108, for more information)</li> <li>Vector control algorithm</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                                    |
| <b>Pr 00.044 {05.009} Rated Voltage</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | <b>Defines the voltage applied to the motor at rated frequency</b> |
| <b>Pr 00.047 {05.006} Rated Frequency</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | <b>Defines the frequency at which rated voltage is applied</b>     |
| <p>The <i>Rated Voltage</i> (00.044) and the <i>Rated Frequency</i> (00.047) are used to define the voltage to frequency characteristic applied to the motor (see <i>Open Loop Control Mode</i> (00.007), later in this table). The motor rated frequency is also used in conjunction with the motor rated speed to calculate the rated slip for slip compensation (see motor <i>Rated Speed</i> (00.045), later in this table).</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                    |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                                    |
| <b>Pr 00.045 {05.008} Rated Speed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | <b>Defines the full load rated speed of the motor</b>              |
| <b>Pr 00.042 {05.011} Number Of Motor Poles</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | <b>Defines the number of motor poles</b>                           |
| <p>The motor rated speed and motor rated frequency are used to determine the full load slip of the motor which is used by the vector control algorithm. Incorrect setting of this parameter has the following effects:</p> <ul style="list-style-type: none"> <li>Reduced efficiency of motor operation</li> <li>Reduction of maximum torque available from the motor</li> <li>Reduced transient performance</li> <li>Inaccurate control of absolute torque in torque control modes</li> </ul> <p>The nameplate value is normally the value for a hot motor; however, some adjustment may be required when the drive is commissioned if the nameplate value is inaccurate. Either a fixed value can be entered in this parameter or an optimization system may be used to automatically adjust this parameter (see <i>Rated Speed Optimisation Select</i> (00.033), later in this table).</p> <p>When Pr <b>00.042</b> is set to 'Automatic', the number of motor poles is automatically calculated from the motor <i>Rated Frequency</i> (00.047), and the motor <i>Rated Speed</i> (00.045).</p> <p>Number of poles = <math>120 \times (\text{Motor Rated Frequency (00.047)} / \text{Motor Rated Speed (00.045)})</math> rounded to the nearest even number.</p> |                                                                    |
| <b>Pr 00.043 {5.10} Rated Power Factor</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | <b>Defines the angle between the motor voltage and current</b>     |
| <p>The power factor is the true power factor of the motor, i.e. the angle between the motor voltage and current. If the <i>Stator Inductance</i> (05.025) is set to zero then the power factor is used in conjunction with the motor <i>Rated Current</i> (00.046) and other motor parameters to calculate the rated active and magnetising currents of the motor, which are used in the vector control algorithm. If the stator inductance has a non-zero value this parameter is not used by the drive, but is continuously written with a calculated value of power factor. The stator inductance can be measured by the drive by performing a rotating autotune (see <i>Autotune</i> (Pr 00.040), later in this table).</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                    |

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## Pr 00.040 (05.012) Autotune

There are four autotune tests available in RFC-A mode, a stationary autotune, a rotating autotune, two mechanical load measurement tests. A stationary autotune will give moderate performance whereas a rotating autotune will give improved performance as it measures the actual values of the motor parameters required by the drive. A mechanical load measurement test should be performed separately to a stationary or rotating autotune.

### NOTE

It is highly recommended that a rotating autotune is performed (Pr **00.040** set to 2).

- A stationary autotune can be used when the motor is loaded and it is not possible to remove the load from the motor shaft. The stationary autotune measures the *Stator Resistance* (05.017) and *Transient Inductance* (05.024) of the motor. These are used to calculate the current loop gains, and at the end of the test the values in Pr **00.038** and Pr **00.039** are updated. A stationary autotune does not measure the power factor of the motor so the value on the motor nameplate must be entered into Pr **00.043**. To perform a Stationary autotune, set Pr **00.040** to 1, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).
- A rotating autotune should only be used if the motor is unloaded. A rotating autotune first performs a stationary autotune, a rotating test is then performed which the motor is accelerated with currently selected ramps up to a frequency of *Rated Frequency* (00.047) x 2/3, and the frequency is maintained at the level for up to 40 s. During the rotating autotune the *Stator Inductance* (05.025), and the motor saturation breakpoints (Pr **05.029**, Pr **05.030**, Pr **06.062** and Pr **05.063**) are modified by the drive. The *Motor Rated Power Factor* (00.043) is also modified by the *Stator Inductance* (05.025). The No-Load motor core losses are measured and written to *No-Load Core Losses* (04.045). To perform a Rotating autotune, set Pr **00.040** to 2, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).
- Mechanical load measurement test using signal injection.

This test measures the mechanical characteristic of the motor and load by rotating the motor at the speed defined by the present speed reference and injecting a series of speed test signals. This test should only be used provided all the basic control parameters have been set-up correctly and the speed controller parameters should be set to conservative levels, such as the default values, so that the motor is stable when it runs. The test measures the motor and load inertia, which can be used in automatic set-up of the speed controller gains and in producing a torque feed-forward term. If *Mechanical Load Test Level* (05.021) is left at its default value of zero then the peak level of the injection signal will be 1 % of the maximum speed reference subject to a maximum of 500 rpm. If a different test level is required then *Mechanical Load Test Level* (05.021) should be set to a non-zero value to define the level as a percentage of the maximum speed reference, again subject to a maximum of 500 rpm. The user defined speed reference which defines the speed of the motor should be set to a level higher than the test level, but not high enough for flux weakening to become active. In some cases however, it is possible to perform the test at zero speed provided the motor is free to move, but it may be necessary to increase the test signal from the default value. The test will give the correct results when there is a static load applied to the motor and in the presence of mechanical damping. This test should be used if possible, however for sensorless mode, or if the speed controller cannot be set up for stable operation an alternative test is provided (*Autotune* (00.040) = 4) where a series of torque levels are applied to accelerate and decelerate the motor to measure the inertia.

1. A rotating test is performed in which the motor is accelerated with the currently selected ramps up to the currently selected speed reference, and this speed is maintained for the duration of the test. The *Motor And Load Inertia* (03.018) is set-up.

To perform this autotune test, set Pr **00.040** to 3 and provide the drive with both an enable signal (on terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).

- Mechanical load measurement test using applied torque.*

Auto-tune test 3 should normally be used for mechanical load measurement, but under some circumstances this test may be used as an alternative. This test will not give such accurate results as test 3 if the motor rated speed is not set to the correct value for the motor. Also this test is likely to give incorrect results if standard ramp mode is active. A series of progressively larger torque levels are applied to the motor (20 %, 40 % ... 100 % of rated torque) to accelerate the motor up to 3/4 x *Rated Speed* (00.045) to determine the inertia from the acceleration/deceleration time. The test attempts to reach the required speed within 5 s, but if this fails the next torque level is used. When 100 % torque is used the test allows 60 s for the required speed to be reached, but if this is unsuccessful, an *Autotune 1* trip is initiated. To reduce the time taken for the test it is possible to define the level of torque to be used for the test by setting *Mechanical Load Test Level* (05.021) to a non-zero value. When the test level is defined the test is only carried out at the defined test level and 60 s is allowed for the motor to reach the required speed. It should be noted that if the maximum speed allows for flux weakening then it may not be possible to achieve the required torque level to accelerate the motor fast enough. If this is the case, the maximum speed reference should be reduced.

1. The motor is accelerated in the required direction up to 3/4 of the maximum speed reference and then decelerated to zero speed.
2. The test is repeated with progressively higher torques until the required speed is reached.
3. *Motor And Load Inertia* (03.018) and *Inertia Times 1000* (04.033) are set up.

To perform this autotune test, set Pr **00.040** to 4 and provide the drive with both an enable signal (on terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).

Following the completion of an autotune test the drive will go into the inhibit state. The drive must be placed into a controlled disable condition before the drive can be made to run at the required reference. The drive can be put in to a controlled disable condition by removing the Safe Torque Off signal from terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702, setting the *Drive Enable* (06.015) to Off (0) or disabling the drive via the control word (Pr **06.042** & Pr **06.043**).

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### Pr 00.033 {05.016} *Rated Speed Optimisation Select*

The *Rated Frequency* (00.047) and *Rated Speed* (00.045) are used to define the rated slip of the motor. The rated slip is used in sensorless mode (*Sensorless Mode Active* (03.078) = 1) to correct the motor speed with load. When this mode is active *Rated Speed Optimisation Select* (00.033) has no effect.

If sensorless mode is not active (*Sensorless Mode Active* (03.078) = 0) the rated slip is used in the motor control algorithm and an incorrect value of slip can have a significant effect on the motor performance. If *Rated Speed Optimisation Select* (00.033) = 0 then the adaptive control system is disabled. However, if *Rated Speed Optimisation Select* (00.033) is set to a non-zero value the drive can automatically adjust the *Rated Speed* (00.045) to give the correct value of rated slip. *Rated Speed* (00.045) is not saved at power-down, and so when the drive is powered-down and up again it will return to the last value saved by the user. The rate of convergence and the accuracy of the adaptive controller reduces at low output frequency and low load. The minimum frequency is defined as a percentage of *Rated Frequency* (00.047) by *Rated Speed Optimisation Minimum Frequency* (05.019). The minimum load is defined as a percentage of rated load by *Rated Speed Optimisation Minimum Load* (05.020). The adaptive controller is enabled when a motoring or regenerative load rises above *Rated Speed Optimisation Minimum Load* (05.020) + 5%, and is disabled again when it falls below *Rated Speed Optimisation Minimum Load* (05.020). For best optimisation results the correct values of *Stator Resistance* (05.017), *Transient Inductance* (05.024), *Stator Inductance* (05.025), *Saturation Breakpoint 1* (05.029), *Saturation Breakpoint 2* (05.062), *Saturation Breakpoint 3* (05.030) and *Saturation Breakpoint 4* (05.063) should be used.

### Pr 00.038 {04.013} / Pr 00.039 {04.014} *Current Loop Gains*

The current loop gains proportional (Kp) and integral (Ki) gains control the response of the current loop to a change in current (torque) demand. The default values give satisfactory operation with most motors. However, for optimal performance in dynamic applications it may be necessary to change the gains to improve the performance. The *Current Controller Kp Gain* (00.038) is the most critical value in controlling the performance. The values for the current loop gains can be calculated by performing a stationary or rotating autotune (see *Autotune* Pr 00.040, earlier in this table) the drive measures the *Stator Resistance* (05.017) and *Transient Inductance* (05.024) of the motor and calculates the current loop gains.

This will give a step response with minimum overshoot after a step change of current reference. The proportional gain can be increased by a factor of 1.5 giving a similar increase in bandwidth; however, this gives a step response with approximately 12.5 % overshoot. The equation for the integral gain gives a conservative value. In some applications where it is necessary for the reference frame used by the drive to dynamically follow the flux very closely (i.e. high speed Sensorless RFC-A induction motor applications) the integral gain may need to have a significantly higher value.

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### Speed Loop Gains (Pr 00.007 {03.010}, Pr 00.008 {03.011}, Pr 00.009 {03.012})

The speed loop gains control the response of the speed controller to a change in speed demand. The speed controller includes proportional (Kp) and integral (Ki) feed forward terms, and a differential (Kd) feedback term. The drive holds two sets of these gains and either set may be selected for use by the speed controller with Pr 03.016. If Pr 03.016 = 0, gains Kp1, Ki1 and Kd1 (Pr 00.007 to Pr 00.009) are used, and if Pr 03.016 = 1, gains Kp2, Ki2 and Kd2 (Pr 03.013 to Pr 03.015) are used. Pr 03.016 may be changed when the drive is enabled or disabled. If the load is predominantly a constant inertia and constant torque, the drive can calculate the required Kp and Ki gains to give a required compliance angle or bandwidth dependant on the setting of Pr 03.017.

#### Speed Controller Proportional Gain (Kp), Pr 00.007 {03.010} and Pr 03.013

If the proportional gain has a value and the integral gain is set to zero the controller will only have a proportional term, and there must be a speed error to produce a torque reference. Therefore as the motor load increases there will be a difference between the reference and actual speeds. This effect, called regulation, depends on the level of the proportional gain, the higher the gain the smaller the speed error for a given load. If the proportional gain is too high either the acoustic noise produced by speed feedback quantization becomes unacceptable, or the stability limit is reached.

#### Speed Controller Integral Gain (Ki), Pr 00.008 {03.011} and Pr 03.014

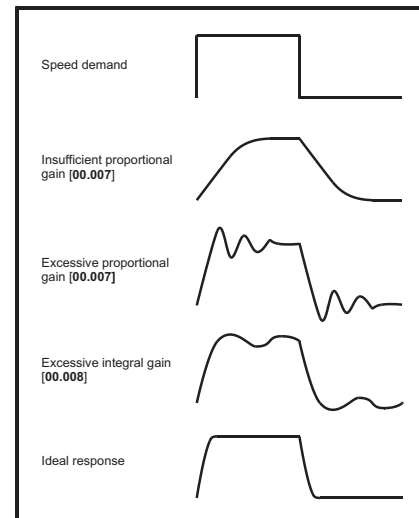
The integral gain is provided to prevent speed regulation. The error is accumulated over a period of time and used to produce the necessary torque demand without any speed error. Increasing the integral gain reduces the time taken for the speed to reach the correct level and increases the stiffness of the system, i.e. it reduces the positional displacement produced by applying a load torque to the motor. Unfortunately increasing the integral gain also reduces the system damping giving overshoot after a transient. For a given integral gain the damping can be improved by increasing the proportional gain. A compromise must be reached where the system response, stiffness and damping are all adequate for the application. For RFC-A Sensorless mode, it is unlikely that the integral gain can be increased much above 0.50.

#### Differential Gain (Kd), Pr 00.009 {03.012} and Pr 03.015

The differential gain is provided in the feedback of the speed controller to give additional damping. The differential term is implemented in a way that does not introduce excessive noise normally associated with this type of function. Increasing the differential term reduces the overshoot produced by under-damping, however, for most applications the proportional and integral gains alone are sufficient.

There are six methods of tuning the speed loop gains dependant on the setting of Pr 03.017:

1. Pr 03.017 = 0, User set-up.  
This involves the connecting of an oscilloscope to analog output 1 to monitor the speed feedback.  
Give the drive a step change in speed reference and monitor the response of the drive on the oscilloscope.  
The proportional gain (Kp) should be set up initially. The value should be increased up to the point where the speed overshoots and then reduced slightly.  
The integral gain (Ki) should then be increased up to the point where the speed becomes unstable and then reduced slightly.  
It may now be possible to increase the proportional gain to a higher value and the process should be repeated until the system response matches the ideal response as shown.  
The diagram shows the effect of incorrect P and I gain settings as well as the ideal response.
2. Pr 03.017 = 1, Bandwidth set-up  
If bandwidth based set-up is required, the drive can calculate Kp and Ki if the following parameters are set up correctly:  
Pr 03.020 - Required bandwidth,  
Pr 03.021 - Required damping factor,  
Pr 03.018 - Motor and load inertia.  
The drive can be made to measure the motor and load inertia by performing a mechanical load measurement autotune (see Autotune Pr 00.040, earlier in this table).
3. Pr 03.017 = 2, Compliance angle set-up  
If compliance angle based set-up is required, the drive can calculate Kp and Ki if the following parameters are set up correctly:  
Pr 03.019 - Required compliance angle,  
Pr 03.021 - Required damping factor,  
Pr 03.018 - Motor and load inertia  
The drive can be made to measure the motor and load inertia by performing a mechanical load measurement autotune (see Autotune Pr 00.040, earlier in this table).
4. Pr 03.017 = 3, Kp gains times 16  
If Speed Controller Set-up Method (03.017) = 3 the selected proportional gain used by the drive is multiplied by 16.



#### Pr 03.017 = 4 - 6

If Speed Controller Set-up Method (03.017) is set to a value from 4 to 6 the Speed Controller Proportional Gain Kp1 (03.010) and Speed Controller Integral Gain Ki1 (03.011) are automatically set up to give the bandwidths given in the table below and a damping factor of unity. These settings give low, standard or high performance.

| Speed Controller Set-up Method (03.017) | Performance | Bandwidth |
|-----------------------------------------|-------------|-----------|
| 4                                       | Low         | 5 Hz      |
| 5                                       | Standard    | 25 Hz     |
| 6                                       | High        | 100 Hz    |

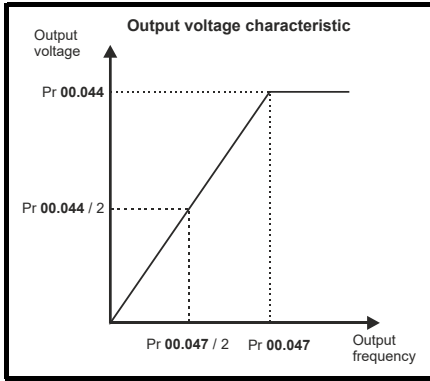
#### 6. Pr 03.017 = 7

If Speed Controller Set-up Method (03.017) = 7 then Speed Controller Proportional Gain Kp1 (03.010), Speed Controller Integral Gain Ki1 (03.011) and Speed Controller Differential Feedback Gain Kd1 (03.012) are set up to give a closed-loop speed controller response that approximates to a first order system with a transfer function of  $1 / (s\tau + 1)$ , where  $\tau = 1/\omega_{bw}$  and  $\omega_{bw} = 2\pi \times \text{Bandwidth}$  (03.020). In this case the damping factor is meaningless, and Damping Factor (03.021) and Compliance Angle (03.019) have no effect.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
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### 8.1.3 RFC-A Sensorless mode

#### Induction motor without position feedback

|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                    |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------|
| <b>Pr 00.046 {05.007} Motor Rated Current</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | <b>Defines the maximum motor continuous current</b>                |
| <p>The motor rated current parameter must be set to the maximum continuous current of the motor. (See section 8.2 <i>Maximum motor rated current</i> on page 108, for information about setting this parameter higher than the maximum Heavy Duty current rating.) The motor rated current is used in the following:</p> <ul style="list-style-type: none"> <li>Current limits (see section 8.3 <i>Current limits</i> on page 108, for more information).</li> <li>Motor thermal overload protection (see section 8.4 <i>Motor thermal protection</i> on page 108, for more information)</li> <li>Vector control algorithm</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                                    |
| <b>Pr 00.044 {05.009} Rated Voltage</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | <b>Defines the voltage applied to the motor at rated frequency</b> |
| <b>Pr 00.047 {05.006} Rated Frequency</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | <b>Defines the frequency at which rated voltage is applied</b>     |
| <p>The <i>Rated Voltage</i> (00.044) and the <i>Rated Frequency</i> (00.047) are used to define the voltage to frequency characteristic applied to the motor (see <i>Open Loop Control Mode</i> (00.007), later in this table). The motor rated frequency is also used in conjunction with the motor rated speed to calculate the rated slip for slip compensation (see motor <i>Rated Speed</i> (00.045), later in this table).</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                    |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                                    |
| <b>Pr 00.045 {05.008} Rated Speed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | <b>Defines the full load rated speed of the motor</b>              |
| <b>Pr 00.042 {05.011} Number Of Motor Poles</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | <b>Defines the number of motor poles</b>                           |
| <p>The motor rated speed and motor rated frequency are used to determine the full load slip of the motor which is used by the vector control algorithm. Incorrect setting of this parameter has the following effects:</p> <ul style="list-style-type: none"> <li>Reduced efficiency of motor operation</li> <li>Reduction of maximum torque available from the motor</li> <li>Reduced transient performance</li> <li>Inaccurate control of absolute torque in torque control modes</li> </ul> <p>The nameplate value is normally the value for a hot motor; however, some adjustment may be required when the drive is commissioned if the nameplate value is inaccurate. Either a fixed value can be entered in this parameter or an optimization system may be used to automatically adjust this parameter (see <i>Rated Speed Optimization Select</i> (05.016), later in this table).</p> <p>When Pr <b>00.042</b> is set to 'Automatic', the number of motor poles is automatically calculated from the motor <i>Rated Frequency</i> (00.047), and the motor <i>Rated Speed</i> (00.045).</p> <p>Number of poles = <math>120 \times (\text{Motor Rated Frequency (00.047)} / \text{Motor Rated Speed (00.045)})</math> rounded to the nearest even number.</p> |                                                                    |
| <b>Pr 00.043 {5.010} Rated Power Factor</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | <b>Defines the angle between the motor voltage and current</b>     |
| <p>The power factor is the true power factor of the motor, i.e. the angle between the motor voltage and current. If the <i>Stator Inductance</i> (05.025) is set to zero then the power factor is used in conjunction with the motor <i>Rated Current</i> (00.046) and other motor parameters to calculate the rated active and magnetising currents of the motor, which are used in the vector control algorithm. If the stator inductance has a non-zero value this parameter is not used by the drive, but is continuously written with a calculated value of power factor. The stator inductance can be measured by the drive by performing a rotating autotune (see <i>Autotune</i> (Pr 00.040), later in this table).</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                    |

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| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
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## Pr 00.040 {05.012} Autotune

There are three autotune tests available in RFC-A mode, a stationary test, a rotating test and a mechanical load measurement test. A stationary autotune will give moderate performance whereas a rotating autotune will give improved performance as it measures the actual values of the motor parameters required by the drive. A mechanical load measurement test should be performed separately to a stationary or rotating autotune.

It is highly recommended that a rotating autotune is performed (Pr 00.040 set to 2).

- A stationary autotune can be used when the motor is loaded and it is not possible to remove the load from the motor shaft. The stationary autotune measures the *Stator Resistance* (05.017) and *Transient Inductance* (05.024) of the motor. These are used to calculate the current loop gains, and at the end of the test the values in Pr 00.038 and Pr 00.039 are updated. *Maximum Deadtime Compensation* (05.059) and *Current At Maximum Deadtime Compensation* (05.060) for the drive are also measured. Additionally, if *Enable Stator Compensation* (05.049) = 1, then *Stator Base Temperature* (05.048) is made equal to *Stator Temperature* (05.046). A stationary autotune does not measure the power factor of the motor so the value on the motor nameplate must be entered into Pr 00.043. To perform a stationary autotune, set Pr 00.040 to 1, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).
- A rotating autotune should only be used if the motor is unloaded. A rotating autotune first performs a stationary autotune, a rotating test is then performed in which the motor is accelerated with currently selected ramps up to a frequency of *Rated Frequency* (00.047) x 2/3, and the frequency is maintained at the level for up to 40 s. During the rotating autotune the *Stator Inductance* (05.025), and the motor saturation breakpoints (Pr 05.029, Pr 05.030, Pr 06.062 and Pr 05.063) are modified by the drive. The power factor is also modified for user information only, but is not used after this point as the stator inductance is used in the vector control algorithm instead. To perform a Rotating autotune, set Pr 00.040 to 2, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).
- The mechanical load measurement test can measure the total inertia of the load and the motor. This is used to set the speed loop gains (see Speed loop gains) and to provide torque feed-forwards when required during acceleration.

**Applied torque (sensorless mode)** This test may give inaccurate results, if the motor rated speed is not set to the correct value for the motor, or if standard ramp mode is active. During the mechanical load measurement test a series of progressively larger torque levels are applied to the motor (20 %, 40 % ... 100 % of rated torque) to accelerate the motor up to  $\frac{3}{4} \times \text{Rated Speed}$  (00.045) to determine the inertia from the acceleration/deceleration time. The test attempts to reach the required speed within 5 s, but if this fails the next torque level is used. When 100 % torque is used the test allows 60 s for the required speed to be reached, but if this is unsuccessful an Autotune 1 trip is initiated. To reduce the time taken for the test it is possible to define the level of torque to be used for the test by setting *Mechanical Load Test Level* (05.021) to a non-zero value. When the test level is defined the test is only carried out at the defined test level and 60 s is allowed for the motor to reach the required speed. It should be noted that if the maximum speed allows for flux weakening then it may not be possible to achieve the required torque level to accelerate the motor quickly enough. If this is the case, the maximum speed reference should be reduced. To perform a mechanical load measurement autotune, set Pr 00.040 to 4, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).

Following the completion of an autotune test the drive will go into the inhibit state. The drive must be placed into a controlled disable condition before the drive can be made to run at the required reference. The drive can be put in to a controlled disable condition by removing the Safe Torque Off signal from terminal 31, setting the *Drive Enable* (06.015) to OFF (0) or disabling the drive via the control word (Pr 06.042 & Pr 06.043).

## Pr 00.038 {04.013} / Pr 00.039 {04.014} Current Loop Gains

The current loop gains proportional (Kp) and integral (Ki) gains control the response of the current loop to a change in current (torque) demand. The default values give satisfactory operation with most motors. However, for optimal performance in dynamic applications it may be necessary to change the gains to improve the performance. The *Current Controller Kp Gain* (00.038) is the most critical value in controlling the performance. The values for the current loop gains can be calculated by performing a stationary or rotating autotune (see *Autotune* Pr 00.040, earlier in this table) the drive measures the *Stator Resistance* (05.017) and *Transient Inductance* (05.024) of the motor and calculates the current loop gains.

This will give a step response with minimum overshoot after a step change of current reference. The proportional gain can be increased by a factor of 1.5 giving a similar increase in bandwidth; however, this gives a step response with approximately 12.5 % overshoot. The equation for the integral gain gives a conservative value. In some applications where it is necessary for the reference frame used by the drive to dynamically follow the flux very closely (i.e. high speed Sensorless RFC-A induction motor applications) the integral gain may need to have a significantly higher value.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
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| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
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## Speed Loop Gains (Pr 00.007 {03.010}, Pr 00.008 {03.011}, Pr 00.009 {03.012})

The speed loop gains control the response of the speed controller to a change in speed demand. The speed controller includes proportional (Kp) and integral (Ki) feed forward terms, and a differential (Kd) feedback term. The drive holds two sets of these gains and either set may be selected for use by the speed controller with Pr 03.016. If Pr 03.016 = 0, gains Kp1, Ki1 and Kd1 (Pr 00.007 to Pr 00.009) are used, and if Pr 03.016 = 1, gains Kp2, Ki2 and Kd2 (Pr 03.013 to Pr 03.015) are used. Pr 03.016 may be changed when the drive is enabled or disabled. If the load is predominantly a constant inertia and constant torque, the drive can calculate the required Kp and Ki gains to give a required compliance angle or bandwidth dependant on the setting of Pr 03.017.

### Speed Controller Proportional Gain (Kp), Pr 00.007 {03.010} and Pr 03.013

If the proportional gain has a value and the integral gain is set to zero the controller will only have a proportional term, and there must be a speed error to produce a torque reference. Therefore as the motor load increases there will be a difference between the reference and actual speeds. This effect, called regulation, depends on the level of the proportional gain, the higher the gain the smaller the speed error for a given load. If the proportional gain is too high either the acoustic noise produced by speed feedback quantization becomes unacceptable, or the stability limit is reached.

### Speed Controller Integral Gain (Ki), Pr 00.008 {03.011} and Pr 03.014

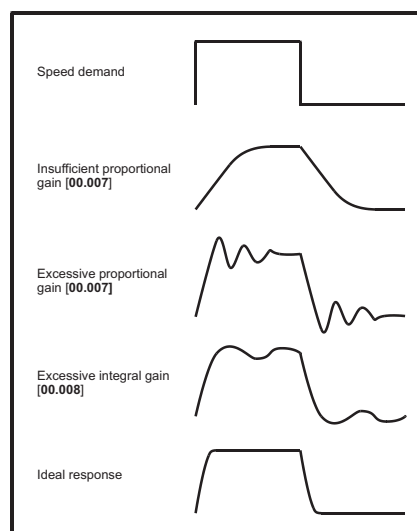
The integral gain is provided to prevent speed regulation. The error is accumulated over a period of time and used to produce the necessary torque demand without any speed error. Increasing the integral gain reduces the time taken for the speed to reach the correct level and increases the stiffness of the system, i.e. it reduces the positional displacement produced by applying a load torque to the motor. Unfortunately increasing the integral gain also reduces the system damping giving overshoot after a transient. For a given integral gain the damping can be improved by increasing the proportional gain. A compromise must be reached where the system response, stiffness and damping are all adequate for the application. For RFC-A Sensorless mode, it is unlikely that the integral gain can be increased much above 0.50.

### Differential Gain (Kd), Pr 00.009 {03.012} and Pr 03.015

The differential gain is provided in the feedback of the speed controller to give additional damping. The differential term is implemented in a way that does not introduce excessive noise normally associated with this type of function. Increasing the differential term reduces the overshoot produced by under-damping, however, for most applications the proportional and integral gains alone are sufficient.

There are six methods of tuning the speed loop gains dependant on the setting of Pr 03.017:

1. Pr 03.017 = 0, User set-up.  
This involves the connecting of an oscilloscope to analog output 1 to monitor the speed feedback.  
Give the drive a step change in speed reference and monitor the response of the drive on the oscilloscope.  
The proportional gain (Kp) should be set up initially. The value should be increased up to the point where the speed overshoots and then reduced slightly.  
The integral gain (Ki) should then be increased up to the point where the speed becomes unstable and then reduced slightly.  
It may now be possible to increase the proportional gain to a higher value and the process should be repeated until the system response matches the ideal response as shown.  
The diagram shows the effect of incorrect P and I gain settings as well as the ideal response.
2. Pr 03.017 = 1, Bandwidth set-up  
If bandwidth based set-up is required, the drive can calculate Kp and Ki if the following parameters are set up correctly:  
Pr 03.020 - Required bandwidth,  
Pr 03.021 - Required damping factor,  
Pr 03.018 - Motor and load inertia.  
The drive can be made to measure the motor and load inertia by performing a mechanical load measurement autotune (see Autotune Pr 00.040, earlier in this table).
3. Pr 03.017 = 2, Compliance angle set-up  
If compliance angle based set-up is required, the drive can calculate Kp and Ki if the following parameters are set up correctly:  
Pr 03.019 - Required compliance angle,  
Pr 03.021 - Required damping factor,  
Pr 03.018 - Motor and load inertia  
The drive can be made to measure the motor and load inertia by performing a mechanical load measurement autotune (see Autotune Pr 00.040, earlier in this table).
4. Pr 03.017 = 3, Kp gains times 16  
If Speed Controller Set-up Method (03.017) = 3 the selected proportional gain used by the drive is multiplied by 16.



### 5. Pr 03.017 = 4 - 6

If Speed Controller Set-up Method (03.017) is set to a value from 4 to 6 the Speed Controller Proportional Gain Kp1 (03.010) and Speed Controller Integral Gain Ki1 (03.011) are automatically set up to give the bandwidths given in the table below and a damping factor of unity. These settings give low, standard or high performance.

| Pr 03.017 | Performance | Bandwidth |
|-----------|-------------|-----------|
| 4         | Low         | 5 Hz      |
| 5         | Standard    | 25 Hz     |
| 6         | High        | 100 Hz    |

### 6. Pr 03.017 = 7

If Speed Controller Set-up Method (03.017) = 7 then Speed Controller Proportional Gain Kp1 (03.010), Speed Controller Integral Gain Ki1 (03.011) and Speed Controller Differential Feedback Gain Kd1 (03.012) are set up to give a closed-loop speed controller response that approximates to a first order system with a transfer function of  $1 / (s\tau + 1)$ , where  $\tau = 1/\omega_{bw}$  and  $\omega_{bw} = 2\pi \times \text{Bandwidth}$  (03.020). In this case the damping factor is meaningless, and Damping Factor (03.021) and Compliance Angle (03.019) have no effect.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
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## 8.1.4 RFC-S mode

### Permanent magnet motor with Position feedback

#### Pr 00.046 {05.007} Rated Current

Defines the maximum motor continuous current

The motor rated current parameter must be set to the maximum continuous current of the motor. The motor rated current is used in the following:

- Current limits (see section 8.3 *Current limits* on page 108, for more information)
- Motor thermal overload protection (see section 8.4 *Motor thermal protection* on page 108, for more information)

#### Pr 00.042 {05.011} Number Of Motor Poles

Defines the number of motor poles

The number of motor poles parameter defines the number of electrical revolutions in one whole mechanical revolution of the motor. This parameter must be set correctly for the control algorithms to operate correctly. When Pr **00.042** is set to "Automatic" the number of poles is 6.

#### Pr 00.040 {05.012} Autotune

There are four autotune tests available in RFC-S mode, a stationary autotune, a rotating autotune, mechanical load measurement tests to measure load dependent parameters.

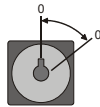
##### • Stationary Autotune

The stationary autotune can be used when the motor is loaded and it is not possible uncouple the load from motor shaft. This test can be used to measure all the necessary parameters for basic control. During the stationary autotune, a test is performed to locate the flux axis of the motor. However this test may not be able to calculate such an accurate value for the *Position Feedback Phase Angle* (00.043) as compared to rotating autotune. A stationary test is performed to measure *Stator Resistance* (05.017), *Ld* (05.024), *Maximum Deadtime Compensation* (05.059), *Current At Maximum Deadtime Compensation* (05.060), *No Load Lq* (05.072). If *Enable Stator Compensation* (05.049) = 1 then *Stator Base Temperature* (05.048) is made equal to *Stator Temperature* (05.046). The *Stator Resistance* (05.017) and the *Ld* (05.024) are then used to set up *Current controller Kp Gain* (00.038) and *Current Controller Ki Gain* (00.039). If sensorless mode is not selected then *Position Feedback Phase Angle* (00.043) is set up for the position from the position feedback interface selected with *Motor Control Feedback Select* (03.026). To perform a Stationary autotune, set Pr **00.040** to 1, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).

##### • Rotating Autotune

The rotating autotune must be performed on unloaded motor. This test can be used to measure all the necessary parameters for the basic control and parameters for cancelling the effects of the cogging torque.

During the rotating autotune, *Rated Current* (00.046) is applied and the motor is rotated by 2 electrical revolutions (i.e. up to 2 mechanical revolutions) in the required direction. If sensorless mode is not selected then the *Position Feedback Phase Angle* (00.043) is set-up for the position from the position feedback interface selected with *Motor Control Feedback Select* (03.026). A stationary test is then performed to measure *Stator Resistance* (05.017), *Ld* (05.024), *Maximum Deadtime Compensation* (05.059), *Current At Maximum Deadtime Compensation* (05.060) and *No Load Lq* (05.072). *Stator Resistance* (05.017) and *Ld* (05.024) are used to set up *Current Controller Kp Gain* (00.038) and *Current Controller Ki Gain* (00.039). This is only done once during the test, and so the user can make further adjustments to the current controller gains if required. To perform a Rotating autotune, set Pr **00.040** to 2, and provide the drive with both an enable signal (terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).



##### • Mechanical load measurement test using signal injection

The mechanical load measurement test using signal injection, measures the mechanical characteristic of the motor and load by rotating the motor at the speed defined by the present speed reference and injecting a series of speed test signals. This test should only be used provided all the basic control parameters (including *Torque Per Amp* (05.032)) have been set-up correctly and the speed controller parameters should be set to conservative levels, such as the default values, so that the motor is stable when it runs. The test measures the motor and load inertia, which can be used in automatic set-up of the speed controller gains and in producing a torque feed-forward term. If *Mechanical Load Test Level* (05.021) is left at its default value of zero then the peak level of the injection signal will be 1 % of the maximum speed reference subject to a maximum of 500 rpm. If a different test level is required then *Mechanical Load Test Level* (05.021) should be set to a non-zero value to define the level as a percentage of the maximum speed reference, again subject to a maximum of 500 rpm. The user defined speed reference which defines the speed of the motor should be set to a level higher than the test level, but not high enough for flux weakening to become active. In some cases, however it is possible to perform the test at zero speed provided the motor is free to move, but it may be necessary to increase the test signal from the default value. The test will give the correct results when there is a static load applied to the motor and in the presence of mechanical damping. This test should be used if possible, however for sensorless mode, or if the speed controller cannot be set up for stable operation an alternative test is provided (*Autotune* (00.040) = 4) where a series of torque levels are applied to accelerate and decelerate the motor to measure the inertia.

1. A rotating test is performed in which the motor is accelerated with the currently selected ramps up to the currently selected speed reference, and this speed is maintained for the duration of the test. *Motor And Load Inertia* (03.018) and *Inertia Times 1000* (04.033) are set up.

To perform this autotune test, set Pr **00.040** to 3 and provide the drive with both an enable signal (on terminal 31 on Unidrive M700 / M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700 / M701 and terminal 7 or 8 on Unidrive M702).

##### • Mechanical load measurement using applied torque

Auto-tune test 3 should normally be used for mechanical load measurement, but under some circumstances this test may be used as an alternative. This test is likely to give incorrect results if standard ramp mode is active. A series of progressively larger torque levels are applied to the motor (20 %, 40 % ... 100 % of rated torque) to accelerate the motor up to  $\frac{3}{4} \times \text{Rated Speed}$  (00.045) to determine the inertia from the acceleration/deceleration time. The test attempts to reach the required speed within 5s, but if this fails the next torque level is used. When 100 % torque is used the test allows 60 s for the required speed to be reached, but if this is unsuccessful, a trip is initiated. To reduce the time taken for the test it is possible to define the level of torque to be used for the test by setting *Mechanical Load Test Level* (05.021) to a non-zero value. When the test level is defined the test is only carried out at the defined test level and 60 s is allowed for the motor to reach the required speed. It should be noted that if the maximum speed allows for flux weakening then it may not be possible to achieve the required torque level to accelerate the motor fast enough. If this is the case, the maximum speed reference should be reduced.

1. The motor is accelerated in the required direction up to  $\frac{3}{4}$  of the maximum speed reference and then decelerated to zero speed.
2. The test is repeated with progressively higher torques until the required speed is reached.
3. *Motor And Load Inertia* (03.018) and *Inertia Times 1000* (04.033) are set up. To perform this autotune test, set Pr 00.040 to 4 and provide the drive with both an enable signal (on terminal 31 on Unidrive M700/M701 and terminal 11 & 13 on Unidrive M702) and a run signal (terminal 26 or 27 on Unidrive M700/M701 and terminal 7 or 8 on Unidrive M702).

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| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
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### Pr 00.038 {04.013} / Pr 00.039 {04.014} *Current Loop Gains*

The current loop gains proportional (Kp) and integral (Ki) gains control the response of the current loop to a change in current (torque) demand. The default values give satisfactory operation with most motors. However, for optimal performance in dynamic applications it may be necessary to change the gains to improve the performance. The proportional gain (Pr 00.038) is the most critical value in controlling the performance. The values for the current loop gains can be calculated by performing a stationary or rotating autotune (see *Autotune* Pr 00.040, earlier in this table) the drive measures the *Stator Resistance* (05.017) and *Transient Inductance* (05.024) of the motor and calculates the current loop gains.

This will give a step response with minimum overshoot after a step change of current reference. The proportional gain can be increased by a factor of 1.5 giving a similar increase in bandwidth; however, this gives a step response with approximately 12.5 % overshoot. The equation for the integral gain gives a conservative value. In some applications where it is necessary for the reference frame used by the drive to dynamically follow the flux very closely (i.e. high speed Sensorless RFC-A induction motor applications) the integral gain may need to have a significantly higher value.

### Speed loop gains (Pr 00.007 {03.010}, Pr 00.008 {03.011}, Pr 00.009 {03.012})

The speed loop gains control the response of the speed controller to a change in speed demand. The speed controller includes proportional (Kp) and integral (Ki) feed forward terms, and a differential (Kd) feedback term. The drive holds two sets of these gains and either set may be selected for use by the speed controller with Pr 03.016. If Pr 03.016 = 0, gains Kp1, Ki1 and Kd1 (Pr 00.007 to Pr 00.009) are used, and if Pr 03.016 = 1, gains Kp2, Ki2 and Kd2 (Pr 03.013 to Pr 03.015) are used. Pr 03.016 may be changed when the drive is enabled or disabled. If the load is predominantly a constant inertia and constant torque, the drive can calculate the required Kp and Ki gains to give a required compliance angle or bandwidth dependant on the setting of Pr 03.017.

#### *Speed Controller Proportional Gain (Kp), Pr 00.007 {03.010} and Pr 03.013*

If the proportional gain has a value and the integral gain is set to zero the controller will only have a proportional term, and there must be a speed error to produce a torque reference. Therefore as the motor load increases there will be a difference between the reference and actual speeds. This effect, called regulation, depends on the level of the proportional gain, the higher the gain the smaller the speed error for a given load. If the proportional gain is too high either the acoustic noise produced by speed feedback quantization becomes unacceptable, or the stability limit is reached.

#### *Speed Controller Integral Gain (Ki), Pr 00.008 {03.011} and Pr 03.014*

The integral gain is provided to prevent speed regulation. The error is accumulated over a period of time and used to produce the necessary torque demand without any speed error. Increasing the integral gain reduces the time taken for the speed to reach the correct level and increases the stiffness of the system, i.e. it reduces the positional displacement produced by applying a load torque to the motor. Unfortunately increasing the integral gain also reduces the system damping giving overshoot after a transient. For a given integral gain the damping can be improved by increasing the proportional gain. A compromise must be reached where the system response, stiffness and damping are all adequate for the application.

#### *Differential Gain (Kd), Pr 00.009 {03.012} and Pr 03.015*

The differential gain is provided in the feedback of the speed controller to give additional damping. The differential term is implemented in a way that does not introduce excessive noise normally associated with this type of function. Increasing the differential term reduces the overshoot produced by under-damping, however, for most applications the proportional and integral gains alone are sufficient.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### Speed loop gains (cont) (Pr 00.007 {03.010}, Pr 00.008 {03.011}, Pr 00.009 {03.012})

There are three methods of tuning the speed loop gains dependant on the setting of Pr 03.017:

1. Pr 03.017 = 0, User set-up.

This involves the connecting of an oscilloscope to analog output 1 to monitor the speed feedback.

Give the drive a step change in speed reference and monitor the response of the drive on the oscilloscope.

The proportional gain (Kp) should be set up initially. The value should be increased up to the point where the speed overshoots and then reduced slightly.

The integral gain (Ki) should then be increased up to the point where the speed becomes unstable and then reduced slightly.

It may now be possible to increase the proportional gain to a higher value and the process should be repeated until the system response matches the ideal response as shown.

The diagram shows the effect of incorrect P and I gain settings as well as the ideal response.

2. Pr 03.017 = 1, Bandwidth set-up

If bandwidth based set-up is required, the drive can calculate Kp and Ki if the following parameters are set up correctly:

Pr 03.020 - Required bandwidth,

Pr 03.021 - Required damping factor,

Pr 03.018 - Motor and load inertia.

The drive can be made to measure the motor and load inertia by performing a mechanical load measurement autotune (see *Autotune* Pr 00.040, earlier in this table).

3. Pr 03.017 = 2, Compliance angle set-up

If compliance angle based set-up is required, the drive can calculate Kp and Ki if the following parameters are set up correctly:

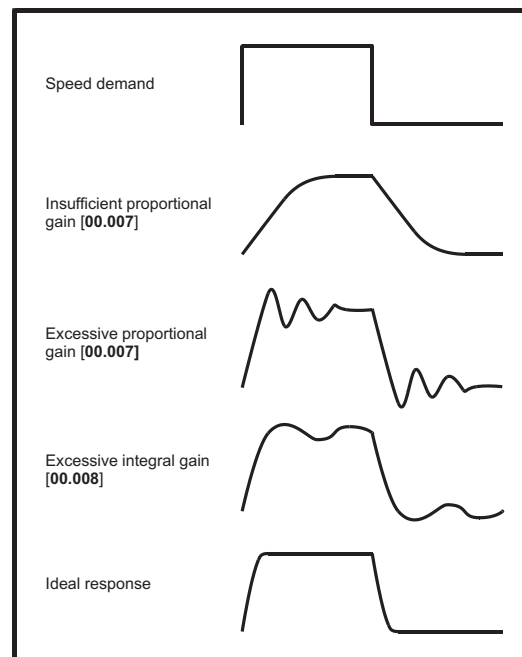
Pr 03.019 - Required compliance angle,

Pr 03.021 - Required damping factor,

Pr 03.018 - Motor and load inertia. The drive can be made to measure the motor and load inertia by performing a mechanical load autotune (see *Autotune* Pr 00.040, earlier in this table).

4. Pr 03.017 = 3, Kp gains times 16

If *Speed Controller Set-up Method* (03.017) = 3 the selected proportional gain used by the drive is multiplied by 16.



5. Pr 03.017 = 4 - 6

If *Speed Controller Set-up Method* (03.017) is set to a value from 4 to 6 the *Speed Controller Proportional Gain Kp1* (03.010) and *Speed Controller Integral Gain Ki1* (03.011) are automatically set up to give the bandwidths given in the table below and a damping factor of unity. These settings give low, standard or high performance.

| Speed Controller Set-up Method (03.017) | Performance | Bandwidth |
|-----------------------------------------|-------------|-----------|
| 4                                       | Low         | 5 Hz      |
| 5                                       | Standard    | 25 Hz     |
| 6                                       | High        | 100 Hz    |

6. Pr 03.017 = 7

If *Speed Controller Set-up Method* (03.017) = 7 then *Speed Controller Proportional Gain Kp1* (03.010), *Speed Controller Integral Gain Ki1* (03.011) and *Speed Controller Differential Feedback Gain Kd1* (03.012) are set up to give a closed-loop speed controller response that approximates to a first order system with a transfer function of  $1 / (s\tau + 1)$ , where  $\tau = 1/\omega_{bw}$  and  $\omega_{bw} = 2\pi \times \text{Bandwidth}$  (03.020). In this case the damping factor is meaningless, and *Damping Factor* (03.021) and *Compliance Angle* (03.019) have no effect.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 8.2 Maximum motor rated current

The maximum motor rated current allowed by the drive is greater than the *Maximum Heavy Duty Current Rating* (00.032). The ratio between the Normal Duty rating and the *Maximum Heavy Duty Current Rating* (00.032) varies between drive sizes. The values for the Normal and Heavy Duty rating can be found in the *Power Installation Guide*. If the motor *Rated Current* (00.046) is set above the *Maximum Heavy Duty Current Rating* (00.032), the current limits and the motor thermal protection scheme are modified (see section 8.3 *Current limits* on page 108 and section 8.4 *Motor thermal protection* on page 108 for more information).

## 8.3 Current limits

The default setting for the current limit parameters is:

- 165 % (141.9 % for frame 9 and above) x motor rated torque producing current for open loop mode
- 175 % (150 % for frame 9 and above) x motor rated torque producing current for RFC-A and RFC-S modes

There are three parameters which control the current limits:

- Motoring current limit: power flowing from the drive to the motor
- Regen current limit: power flowing from the motor to the drive
- Symmetrical current limit: current limit for both motoring and regen operation

The lowest of either the motoring and regen current limit, or the symmetrical current limit applies.

The maximum setting of these parameters depends on the values of motor rated current, drive rated current and the power factor.

Increasing the motor rated current (Pr **00.046/05.007**) above the Heavy Duty rating (default value), will automatically reduce the current limits in Pr **04.005** to Pr **04.007**. If the motor rated current is then set to or below the Heavy Duty rating, the current limits will be left at their reduced values.

The drive can be oversized to permit a higher current limit setting to provide higher accelerating torque as required up to a maximum of 1000 %.

## 8.4 Motor thermal protection

A dual time constant thermal model is provided to estimate the motor temperature as a percentage of its maximum allowed temperature.

The motor thermal protection is modelled using losses in the motor. The losses in the motor are calculated as a percentage value, so that under these conditions the *Motor Protection Accumulator* (04.019) would eventually reach 100 %.

$$\text{Percentage losses} = 100 \% \times [\text{Load related losses} + \text{Iron losses}]$$

Where:

$$\text{Load related losses} = (1 - K_{fe}) \times [(I / (K_1 \times I_{\text{Rated}}))]^2$$

$$\text{Iron losses} = K_{fe} \times (w / w_{\text{Rated}})^{1.6}$$

Where:

$I$  = *Current Magnitude* (00.012)

$I_{\text{Rated}}$  = *Rated Current* (00.046)

$K_{fe}$  = *Rated Iron Losses As Percentage Of Losses* (04.039) / 100 %

The *Motor Protection Accumulator* (04.019) is given by:

$$\text{Pr } 04.019 = \text{Percentage Losses} \times [(1 - K_2) (1 - e^{-t/\tau_1}) + K_2 (1 - e^{-t/\tau_2})]$$

Where:

$T$  = *Motor Protection Accumulator* (04.019)

$K_2$  = *Motor Thermal Time Constant 2 Scaling* (04.038) / 100 %

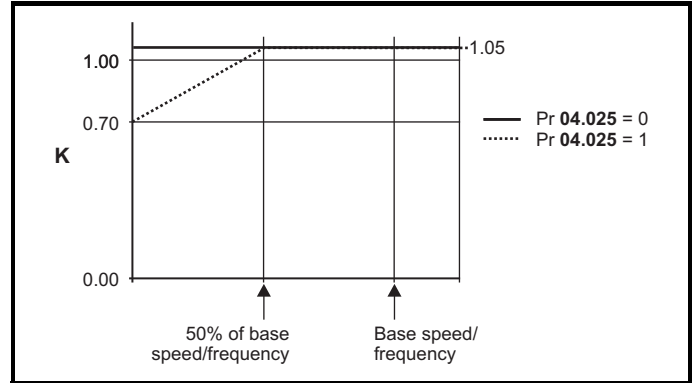
$\tau_1$  = *Motor Thermal Time Constant 1* (00.053)

$\tau_2$  = *Motor Thermal Time Constant 2* (04.037)

$K_1$  = Varies, see below

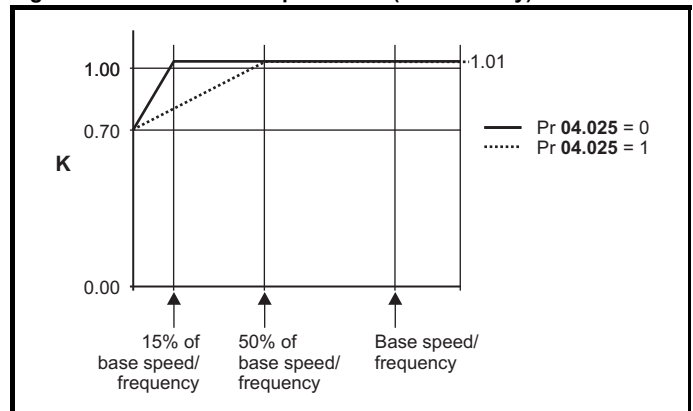
If *Rated Current* (00.046) ≤ *Maximum Heavy Duty Current* (00.032)

Figure 8-1 Motor thermal protection (Heavy Duty)



If Pr **04.025** is 0 the characteristic is for a motor which can operate at rated current over the whole speed range. Induction motors with this type of characteristic normally have forced cooling. If Pr **04.025** is 1 the characteristic is intended for motors where the cooling effect of motor fan reduces with reduced motor speed below 50 % of base speed/frequency. The maximum value for K1 is 1.05, so that above the knee of the characteristics the motor can operate continuously up to 105 % current.

Figure 8-2 Motor thermal protection (Normal Duty)



Both settings of Pr **04.025** are intended for motors where the cooling effect of the motor fan reduces with reduced motor speed, but with different speeds below which the cooling effect is reduced. If Pr **04.025** is 0 the characteristic is intended for motors where the cooling effect reduces with motor speed below 15 % of base speed/frequency. If Pr **04.025** is 1 the characteristic is intended for motors where the cooling effect reduces with motor speed below 50 % of base speed/frequency. The maximum value for K1 is 1.01, so that above the knee of the characteristics the motor can operate continuously up to 101 % current.

When the estimated temperature in Pr **04.019** reaches 100 % the drive takes some action depending on the setting of Pr **04.016**. If Pr **04.016** is 0, the drive trips when Pr **04.019** reaches 100 %. If Pr **04.016** is 1, the current limit is reduced to  $(K - 0.05) \times 100 \%$  when Pr **04.019** reaches 100 %.

The current limit is set back to the user defined level when Pr **04.019** falls below 95 %. The thermal model temperature accumulator accumulates the temperature of the motor while the drive remains powered-up. By default, the accumulator is set to the power down value at power-up. If the rated current defined by Pr **00.046** is altered, the accumulator is reset to zero.

The default setting of the thermal time constant (Pr **00.053**) is 89 s which is equivalent to an overload of 150 % for 60 s from cold.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 8.5 Switching frequency

The default switching frequency is 3 kHz (6 kHz in RFC-S mode), however this can be increased up to a maximum of 16 kHz by Pr **00.041** (dependent on drive size). The available switching frequencies are shown below.

**Table 8-1 Available switching frequencies**

| Drive size | Model                | 2 kHz | 3 kHz | 4 kHz | 6 kHz | 8 kHz | 12 kHz | 16 kHz |
|------------|----------------------|-------|-------|-------|-------|-------|--------|--------|
| 3          | All                  |       |       |       |       |       |        |        |
| 4          |                      |       |       |       |       |       |        |        |
| 5          |                      |       |       |       |       |       |        |        |
| 6          |                      | ✓     | ✓     | ✓     | ✓     | ✓     | ✓      | ✓      |
| 7          |                      |       |       |       |       |       |        |        |
| 8          |                      |       |       |       |       |       |        |        |
| 9E         |                      |       |       |       |       |       |        |        |
| 10         | 10202830 to 10203000 |       |       |       |       |       |        |        |
|            | 10501520 to 10501900 | ✓     | ✓     | ✓     | ✓     | ✓     | ✓      | ✓      |
|            | 10601500 to 10601780 |       |       |       |       |       |        |        |
|            | 10402700 to 10403200 | ✓     | ✓     | ✓     | ✓     |       |        |        |
| 11         | 400 V                | ✓     | ✓     | ✓     | ✓     | ✓     |        |        |
| 11         | 575 and 690 V        | ✓     | ✓     | ✓     |       |       |        |        |

If switching frequency is increased from 3 kHz the following apply:

- Increased heat loss in the drive, which means that derating to the output current must be applied.  
See the derating tables for switching frequency and ambient temperature in the *Power Installation Guide*.
- Reduced heating of the motor - due to improved output waveform quality.
- Reduced acoustic noise generated by the motor.
- Increased sample rate on the speed and current controllers. A trade off must be made between motor heating, drive heating and the demands of the application with respect to the sample time required.

**Table 8-1 Sample rates for various control tasks at each switching frequency**

| Level      | 3, 6, 12 kHz                                      | 2, 4, 8, 16 kHz                                                         | Open loop                        | RFC-A RFC-S                |
|------------|---------------------------------------------------|-------------------------------------------------------------------------|----------------------------------|----------------------------|
| Level 1    | 3 kHz - 167 μs<br>6 kHz - 83 μs<br>12 kHz - 83 μs | 2 kHz - 250 μs<br>4 kHz - 125 μs<br>8 kHz - 62.5 μs<br>16 kHz - 62.5 μs | Peak limit                       | Current controllers        |
| Level 2    | 250 μs                                            | 2 kHz - 500 μs<br>4 kHz - 250 μs<br>8 kHz - 250 μs<br>16 kHz - 250 μs   | Current limit and ramps          | Speed controller and ramps |
| Level 3    | 1 ms                                              |                                                                         | Voltage controller               |                            |
| Level 4    | 4 ms                                              |                                                                         | Time critical user interface     |                            |
| Background |                                                   |                                                                         | Non-time critical user interface |                            |

## 8.6 High speed operation

### 8.6.1 Encoder feedback limits

The maximum encoder frequency should be prevented from exceeding 500 kHz. In RFC-A and RFC-S modes the maximum speed that can be entered in to the speed reference clamps (Pr **00.002** and Pr **00.001**) can be limited by the drive. This is defined by the following (subject to an absolute maximum of 33,000 rpm):

$$\begin{aligned} \text{Maximum speed limit (rpm)} &= \frac{500 \text{ kHz} \times 60}{\text{ELPR}} \\ &= \frac{3.0 \times 10^7}{\text{ELPR}} \end{aligned}$$

Where:

ELPR is the equivalent encoder lines per revolution and is the number of lines that would be produced by a quadrature encoder.

- Quadrature encoder ELPR = number of lines per revolution
- F and D encoder ELPR = number of lines per revolution / 2
- SINCOS encoder ELPR = number of sine waves per revolution

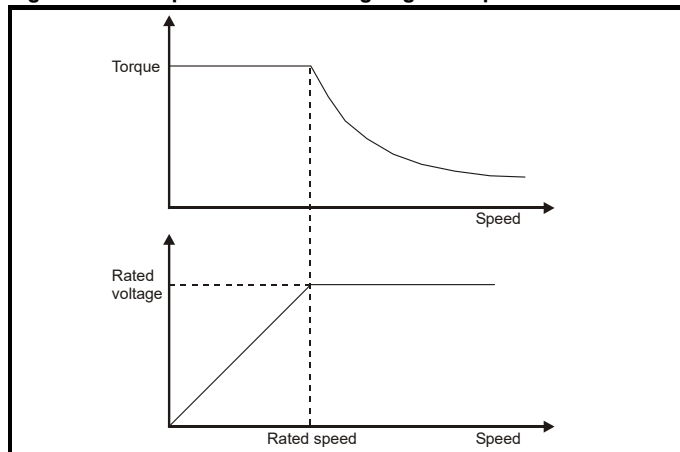
This maximum speed limit is defined by the device selected with the speed feedback selector (Pr **03.026**), and the ELPR set for the position feedback device. In RFC-A mode it is possible to disable this limit via Pr **03.024**, so that the drive can be switched between operation with and without feedback when the speed becomes too high for the feedback device.

### 8.6.2 Field weakening (constant power) operation

(Open loop and RFC-A mode only)

The drive can be used to run an induction machine above synchronous speed into the constant power region. The speed continues to increase and the available shaft torque reduces. The characteristics below show the torque and output voltage characteristics as the speed is increased above the rated value.

**Figure 8-3 Torque and rated voltage against speed**



Care must be taken to ensure the torque available above base speed is sufficient for the application to run satisfactorily. The saturation breakpoint parameters (Pr **05.029**, Pr **05.030**, Pr **05.062** and Pr **05.063**) found during the autotune in RFC-A mode ensure the magnetizing current is reduced in the correct proportion for the specific motor. (In open loop mode the magnetizing current is not actively controlled).

### 8.6.3 Permanent magnet motor high speed operation

High speed servo mode is enabled by setting Pr **05.022** = 1. Care must be taken when using this mode with permanent magnet motor to avoid damaging the drive. The voltage produced by the permanent magnet motor magnets is proportional to speed. For high speed operation the drive must apply currents to the motor to counter-act the flux produced by the magnets. It is possible to operate the motor at very high speeds

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
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that would give a very high motor terminal voltage, but this voltage is prevented by the action of the drive.

If however, the drive is disabled (or tripped) when the motor voltages would be higher than the rating of the drive without the currents to counter-act the flux from the magnets, it is possible to damage the drive. If high speed mode is enabled the motor speed must be limited to the levels given in the table below unless an additional hardware protection system is used to limit the voltages applied to the drive output terminals to a safe level.

The additional low order harmonics cause increased losses and heating in the motor.

| Drive voltage rating | Maximum motor speed (rpm)                  | Maximum safe line to line voltage at the motor terminals (V rms) |
|----------------------|--------------------------------------------|------------------------------------------------------------------|
| 200                  | $400 \times 1000 / (K_e \times \sqrt{2})$  | $400 / \sqrt{2}$                                                 |
| 400                  | $800 \times 1000 / (K_e \times \sqrt{2})$  | $800 / \sqrt{2}$                                                 |
| 575                  | $955 \times 1000 / (K_e \times \sqrt{2})$  | $955 / \sqrt{2}$                                                 |
| 690                  | $1145 \times 1000 / (K_e \times \sqrt{2})$ | $1145 / \sqrt{2}$                                                |

$K_e$  is the ratio between r.m.s. line to line voltage produced by the motor and the speed in V/1000 rpm. Care must also be taken not to de-magnetize the motor. The motor manufacturer should always be consulted before using this mode.

By default, high speed operation is disabled (Pr 05.022 = 0).

It is also possible to enable high speed operation and allow the drive to automatically limit the motor speed to the levels specified in the table and generate an *Overspeed.1* trip if the level is exceeded (Pr 05.022 = -1).

### 8.6.4 Switching frequency

With a default switching frequency of 3 kHz the maximum output frequency should be limited to 250 Hz. Ideally a minimum ratio of 12:1 should be maintained between the switching frequency and the output frequency. This ensures the number of switchings per cycle is sufficient to ensure the output waveform quality is maintained at a minimum level. If this is not possible, quasi-square switching should be enabled (Pr 05.020 = 1). The output waveform will be quasi square above base speed ensuring a symmetrical output waveform, which results in a better quality output than would otherwise result.

### 8.6.5 Maximum speed / frequency

In all operating modes (Open loop, RFC-A and RFC-S) the maximum output frequency is limited to 550 Hz. However, in RFC-S mode the speed is also limited by the voltage constant ( $K_e$ ) of the motor.  $K_e$  is a specific constant for the servo motor being used. It can normally be found on the motor data sheet in V/k rpm (volts per 1,000 rpm).

### 8.6.6 Quasi-Square wave (open-loop only)

The maximum output voltage level of the drive is normally limited to an equivalent of the drive input voltage minus voltage drops within the drive (the drive will also retain a few percent of the voltage in order to maintain current control). If the motor rated voltage is set at the same level as the supply voltage, some pulse deletion will occur as the drive output voltage approaches the rated voltage level. If Pr 05.020 (Quasi-square wave enable) is set to 1 the modulator will allow over modulation, so that as the output frequency increases beyond the rated frequency the voltage continues to increase above the rated voltage. The modulation depth will increase beyond unity; first producing trapezoidal and then quasi-square waveforms.

This can be used for example:

- To obtain high output frequencies with a low switching frequency which would not be possible with space vector modulation limited to unity modulation depth,

or

- In order to maintain a higher output voltage with a low supply voltage.

The disadvantage is that the machine current will be distorted as the modulation depth increases above unity, and will contain a significant amount of low order odd harmonics of the fundamental output frequency.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 9 Drive communication

This section details the communication protocols supported on the drives.

The drive is supplied with either an Ethernet interface (Unidrive M700 / M702), or an EIA 485 serial communication interface (Unidrive M701).

For more information on the parameters associated with each interface and the connection details please refer to section 5.12 *Communications* on page 46.

### 9.1 CT Modbus RTU specification (Unidrive M701)

This section describes the adaptation of the MODBUS RTU protocol offered on Control Techniques' products. The portable software class which implements this protocol is also defined.

MODBUS RTU is a master slave system with half-duplex message exchange. The Control Techniques (CT) implementation supports the core function codes to read and write registers. A scheme to map between MODBUS registers and CT parameters is defined. The CT implementation also defines a 32 bit extension to the standard 16 bit register data format.

#### 9.1.1 MODBUS RTU

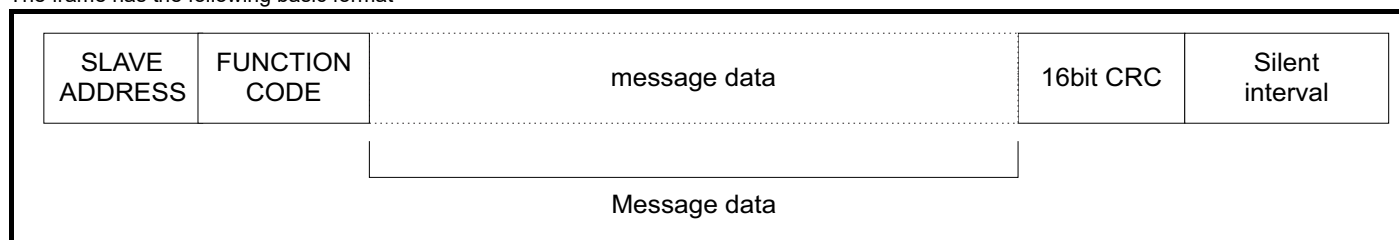
##### Physical layer

| Attribute                                      | Description                                                                                                       |
|------------------------------------------------|-------------------------------------------------------------------------------------------------------------------|
| Normal physical layer for multi-drop operation | EIA 485 2 wire                                                                                                    |
| Bit stream                                     | Standard UART asynchronous symbols with Non Return to Zero (NRZ)                                                  |
| Symbol                                         | Each symbol consists of:-<br>1 start bit<br>8 data bits (transmitted least significant bit first)<br>2 stop bits* |
| Baud rates                                     | 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 76800, 115200                                              |

\* The drive will accept a packet with 1 or 2 stop bits but will always transmit 2 stop bits

##### RTU framing

The frame has the following basic format

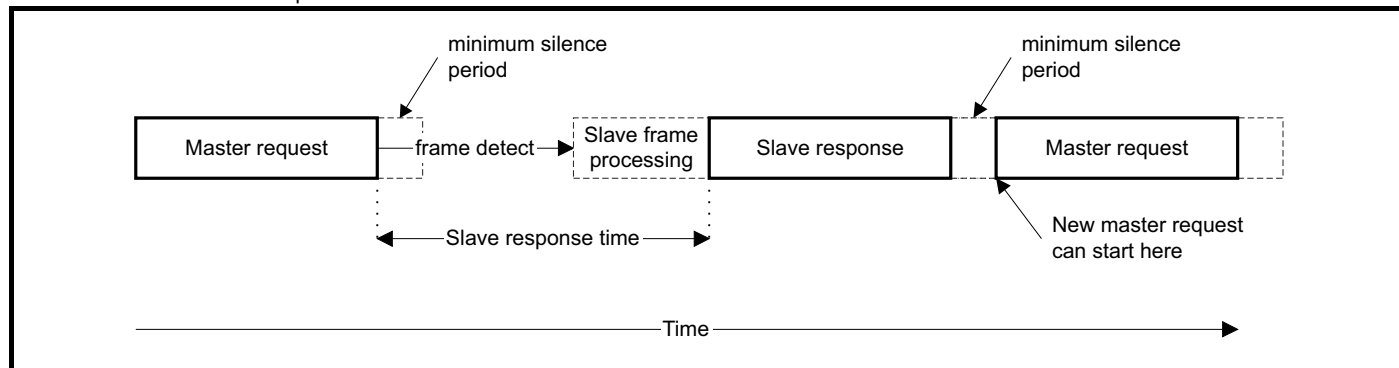


The frame is terminated with a minimum silent period of 3.5 character times (for example, at 19200 baud the minimum silent period is 2 ms). Nodes use the terminating silence period to detect the end of frame and begin frame processing. All frames must therefore be transmitted as a continuous stream without any gaps greater or equal to the silence period. If an erroneous gap is inserted then receiving nodes may start frame processing early in which case the CRC will fail and the frame will be discarded.

MODBUS RTU is a master slave system. All master requests, except broadcast requests, will lead to a response from an individual slave. The slave will respond (i.e. start transmitting the response) within the quoted maximum slave response time (this time is quoted in the data sheet for all Nidec Industrial Automation's products). The minimum slave response time is also quoted but will never be less than the minimum silent period defined by 3.5 character times.

If the master request was a broadcast request then the master may transmit a new request once the maximum slave response time has expired.

The master must implement a message time out to handle transmission errors. This time out period must be set to the maximum slave response time + transmission time for the response.



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 9.1.2 Slave address

The first byte of the frame is the slave node address. Valid slave node addresses are 1 through 247 decimal. In the master request this byte indicates the target slave node; in the slave response this byte indicates the address of the slave sending the response.

#### Global addressing

Address zero addresses all slave nodes on the network. Slave nodes suppress the response messages for broadcast requests.

### 9.1.3 MODBUS registers

The MODBUS register address range is 16 bit (65536 registers) which at the protocol level is represented by indexes 0 through 65535.

#### PLC registers

Modicon PLCs typically define 4 register 'files' each containing 65536 registers. Traditionally, the registers are referenced 1 through 65536 rather than 0 through 65535. The register address is therefore decremented on the master device before passing to the protocol.

| File type | Description                 |
|-----------|-----------------------------|
| 1         | Read only bits ("coil")     |
| 2         | Read / write bits ("coil")  |
| 3         | Read only 16bit register    |
| 4         | Read / write 16bit register |

The register file type code is NOT transmitted by MODBUS and all register files can be considered to map onto a single register address space. However, specific function codes are defined in MODBUS to support access to the "coil" registers.

All standard drive parameters are mapped to register file '4' and the coil function codes are not required.

#### CT parameter mapping

The Modbus register address is 16 bits in size, of which the upper two bits are used for data type selection leaving 14 bits to represent the parameter address, taking into account the slave increments the address value by 1, this results in a theoretical maximum parameter address of 163.84 (limited to 162.99 in software) when the default standard addressing mode (see *Serial Mode* (11.024)) is used.

To access a parameter number above 99 in any drive menu then the modified addressing mode must be used (see *Serial Mode* (11.024)), this will allow access to parameter numbers up to 255 but also limit the maximum menu number to 63.

The Modbus slave device increments the register address by 1 before processing the command, this effectively prevents access to parameter Pr 00.000 in the drive or option module.

The table below shows how the start register address is calculated for both addressing modes.

| Parameter | Addressing mode | Protocol register  |          |         |          |
|-----------|-----------------|--------------------|----------|---------|----------|
| 0.mm.ppp  | Standard        | mm x 100 + ppp - 1 |          |         |          |
|           | Modified        | mm x 256 + ppp - 1 |          |         |          |
| Examples  |                 |                    |          |         |          |
|           |                 | 16-bit             |          | 32-bit  |          |
|           |                 | Decimal            | Hex (0x) | Decimal | Hex (0x) |
| 0.01.021  | Standard        | 120                | 00 78    | 16504   | 40 78    |
|           | Modified        | 276                | 01 14    | 16660   | 41 14    |
| 0.01.000  | Standard        | 99                 | 00 63    | 16483   | 40 63    |
|           | Modified        | 255                | 00 FF    | 16639   | 40 FF    |
| 0.03.161  | Standard        | N/A                | N/A      | N/A     | N/A      |
|           | Modified        | 928                | 03 A0    | 17312   | 43 A0    |

#### Data types

The MODBUS protocol specification defines registers as 16 bit signed integers. All CT devices support this data size.

Refer to the section 9.1.7 *Extended data types* on page 114 for detail on accessing 32 bit register data.

### 9.1.4 Data consistency

All CT devices support a minimum data consistency of one parameter (16 bit or 32 bit data). Some devices support consistency for a complete multiple register transaction.

#### 9.1.5 Data encoding

MODBUS RTU uses a 'big-endian' representation for addresses and data items (except the CRC, which is 'little-endian'). This means that when a numerical quantity larger than a single byte is transmitted, the MOST significant byte is sent first. So for example

16 - bits    0x1234            would be    0x12   0x34

32 - bits    0x12345678       would be    0x12   0x34   0x56   0x78

### 9.1.6 Function codes

The function code determines the context and format of the message data. Bit 7 of the function code is used in the slave response to indicate an exception.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

The following function codes are supported:

| Code | Description                              |
|------|------------------------------------------|
| 3    | Read multiple 16 bit registers           |
| 6    | Write single register                    |
| 16   | Write multiple 16 bit registers          |
| 23   | Read and write multiple 16 bit registers |

### FC03 Read multiple

Read a contiguous array of registers. The slave imposes an upper limit on the number of registers, which can be read. If this is exceeded the slave will issue an exception code 2.

**Table 9-1 Master request**

| Byte | Description                                               |
|------|-----------------------------------------------------------|
| 0    | Slave destination node address 1 through 247, 0 is global |
| 1    | Function code 0x03                                        |
| 2    | Start register address MSB                                |
| 3    | Start register address LSB                                |
| 4    | Number of 16 bit registers MSB                            |
| 5    | Number of 16 bit registers LSB                            |
| 6    | CRC LSB                                                   |
| 7    | CRC MSB                                                   |

**Table 9-2 Slave response**

| Byte         | Description                                      |
|--------------|--------------------------------------------------|
| 0            | Slave source node address                        |
| 1            | Function code 0x03                               |
| 2            | Length of register data in read block (in bytes) |
| 3            | Register data 0 MSB                              |
| 4            | Register data 0 LSB                              |
| 3+byte count | CRC LSB                                          |
| 4+byte count | CRC MSB                                          |

### FC06 Write single register

Writes a value to a single 16 bit register. The normal response is an echo of the request, returned after the register contents have been written. The register address can correspond to a 32 bit parameter but only 16 bits of data can be sent.

**Table 9-3 Master request**

| Byte | Description                                   |
|------|-----------------------------------------------|
| 0    | Slave node address 1 through 247, 0 is global |
| 1    | Function code 0x06                            |
| 2    | Register address MSB                          |
| 3    | Register address LSB                          |
| 4    | Register data MSB                             |
| 5    | Register data LSB                             |
| 6    | CRC LSB                                       |
| 7    | CRC MSB                                       |

**Table 9-4 Slave response**

| Byte | Description               |
|------|---------------------------|
| 0    | Slave source node address |
| 1    | Function code 0x06        |
| 2    | Register address MSB      |
| 3    | Register address LSB      |
| 4    | Register data MSB         |
| 5    | Register data LSB         |
| 6    | CRC LSB                   |
| 7    | CRC MSB                   |

### FC16 Write multiple

Writes a contiguous array of registers. The slave imposes an upper limit on the number of registers which can be written. If this is exceeded the slave will discard the request and the master will time out.

**Table 9-5 Master request**

| Byte         | Description                                   |
|--------------|-----------------------------------------------|
| 0            | Slave node address 1 through 247, 0 is global |
| 1            | Function code 0x10                            |
| 2            | Start register address MSB                    |
| 3            | Start register address LSB                    |
| 4            | Number of 16 bit registers MSB                |
| 5            | Number of 16 bit registers LSB                |
| 6            | Length of register data to write (in bytes)   |
| 7            | Register data 0 MSB                           |
| 8            | Register data 0 LSB                           |
| 7+byte count | CRC LSB                                       |
| 8+byte count | CRC MSB                                       |

**Table 9-6 Slave response**

| Byte | Description                            |
|------|----------------------------------------|
| 0    | Slave source node address              |
| 1    | Function code 0x10                     |
| 2    | Start register address MSB             |
| 3    | Start register address LSB             |
| 4    | Number of 16 bit registers written MSB |
| 5    | Number of 16 bit registers written LSB |
| 6    | CRC LSB                                |
| 7    | CRC MSB                                |

### FC23 Read/Write multiple

Writes and reads two contiguous arrays of registers. The slave imposes an upper limit on the number of registers which can be written. If this is exceeded the slave will discard the request and the master will time out.

**Table 9-7 Master request**

| Byte          | Description                                   |
|---------------|-----------------------------------------------|
| 0             | Slave node address 1 through 247, 0 is global |
| 1             | Function code 0x17                            |
| 2             | Start register address to read MSB            |
| 3             | Start register address to read LSB            |
| 4             | Number of 16 bit registers to read MSB        |
| 5             | Number of 16 bit registers to read LSB        |
| 6             | Start register address to write MSB           |
| 7             | Start register address to write LSB           |
| 8             | Number of 16 bit registers to write MSB       |
| 9             | Number of 16 bit registers to write LSB       |
| 10            | Length of register data to write (in bytes)   |
| 11            | Register data 0 MSB                           |
| 12            | Register data 0 LSB                           |
| 11+byte count | CRC LSB                                       |
| 12+byte count | CRC MSB                                       |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Table 9-8 Slave response**

| Byte         | Description                                      |
|--------------|--------------------------------------------------|
| 0            | Slave source node address                        |
| 1            | Function code 0x17                               |
| 2            | Length of register data in read block (in bytes) |
| 3            | Register data 0 MSB                              |
| 4            | Register data 0 LSB                              |
| 3+byte count | CRC LSB                                          |
| 4+byte count | CRC MSB                                          |

### 9.1.7 Extended data types

Standard MODBUS registers are 16bit and the standard mapping maps a single #X.Y parameter to a single MODBUS register. To support 32 bit data types (integer and float) the MODBUS multiple read and write services are used to transfer a contiguous array of 16bit registers.

Slave devices typically contain a mixed set of 16 bit and 32 bit registers. To permit the master to select the desired 16 bit or 32 bit access the top two bits of the register address are used to indicate the selected data type.

#### NOTE

The selection is applied for the whole block access.

|                |                |                                  |
|----------------|----------------|----------------------------------|
| bit 15<br>TYP1 | bit 14<br>TYP0 | bits 0 - 13                      |
| Type select    |                | Parameter address<br>X x 100+Y-1 |

The 2 bit type field selects the data type according to the table below:

| Type field bits 15-14 | Selected data type | Comments                                        |
|-----------------------|--------------------|-------------------------------------------------|
| 00                    | INT16              | backward compatible                             |
| 01                    | INT32              |                                                 |
| 10                    | Float32            | IEEE754 standard<br>Not supported on all slaves |
| 11                    | Reserved           |                                                 |

If a 32 bit data type is selected then the slave uses two consecutive 16 bit MODBUS registers (in 'big endian'). The master must also set the correct 'number of 16 bit registers'.

Example, read Pr **20.021** through Pr **20.024** as 32 bit parameters using FC03 from node 8:

**Table 9-9 Master request**

| Byte | Value   | Description                                                                          |
|------|---------|--------------------------------------------------------------------------------------|
| 0    | 0x08    | Slave destination node address                                                       |
| 1    | 0x03    | FC03 multiple read                                                                   |
| 2    | 0x47    | Start register address Pr <b>20.021</b>                                              |
| 3    | 0xE4    | (16384 + 2021 - 1) = 18404 = 0x47E4                                                  |
| 4    | 0x00    | Number of 16bit registers to read                                                    |
| 5    | 0x08    | Pr <b>20.021</b> through Pr <b>20.024</b> is 4x32 bit registers = 8x16 bit registers |
| 6    | CRC LSB |                                                                                      |
| 7    | CRC MSB |                                                                                      |

**Table 9-10 Slave response**

| Byte  | Value   | Description                                            |
|-------|---------|--------------------------------------------------------|
| 0     | 0x08    | Slave destination node address                         |
| 1     | 0x03    | FC03 multiple read                                     |
| 2     | 0x10    | Length of data (bytes) = 4x32 bit registers = 16 bytes |
| 3-6   |         | Pr <b>20.021</b> data                                  |
| 7-10  |         | Pr <b>20.022</b> data                                  |
| 11-14 |         | Pr <b>20.023</b> data                                  |
| 15-18 |         | Pr <b>20.024</b> data                                  |
| 19    | CRC LSB |                                                        |
| 20    | CRC MSB |                                                        |

### Reads when actual parameter type is different from selected

The slave will send the least significant word of a 32 bit parameter if that parameter is read as part of a 16 bit access.

The slave will sign extend the least significant word if a 16 bit parameter is accessed as a 32 bit parameter. The number of 16 bit registers must be even during a 32 bit access.

Example, If Pr **01.028** is a 32 bit parameter with a value of 0x12345678, Pr **01.029** is a signed 16 bit parameter with a value of 0xABCD, and Pr **01.030** is a signed 16 bit parameter with a value of 0x0123.

| Read                                 | Start register address | Number of 16 bit registers | Response               | Comments                                                                                  |
|--------------------------------------|------------------------|----------------------------|------------------------|-------------------------------------------------------------------------------------------|
| Pr <b>01.028</b>                     | 127                    | 1                          | 0x5678                 | Standard 16 bit access to a 32 bit register will return low 16 bit word of truncated data |
| Pr <b>01.028</b>                     | 16511*                 | 2                          | 0x12345678             | Full 32 bit access                                                                        |
| Pr <b>01.028</b>                     | 16511*                 | 1                          | Exception 2            | Number of words must be even for 32 bit access                                            |
| Pr <b>01.029</b>                     | 128                    | 1                          | 0xABCD                 | Standard 16 bit access to a 32 bit register will return low 16 bit word of data           |
| Pr <b>01.029</b>                     | 16512*                 | 2                          | 0xFFFFABCD             | 32 bit access to a 16 bit register will return 32 bit sign extended data                  |
| Pr <b>01.030</b>                     | 16513*                 | 2                          | 0x00000123             | 32 bit access to a 16 bit register will return 32 bit sign extended data                  |
| Pr <b>01.028</b> to Pr <b>01.029</b> | 127                    | 2                          | 0x5678, 0xABCD         | Standard 16 bit access to a 32 bit register will return low 16 bit word of truncated data |
| Pr <b>01.028</b> to Pr <b>01.029</b> | 16511*                 | 4                          | 0x12345678, 0xFFFFABCD | Full 32 bit access                                                                        |

\* Bit 14 is set to allow 32 bit access.

### Writes when actual parameter type is different from selected

The slave will allow writing a 32 bit value to a 16 bit parameter as long as the 32 bit value is within the normal range of the 16 bit parameter.

The slave will allow a 16 bit write to a 32 bit parameter. The slave will sign extend the written value, therefore the effective range of this type of write will be -32768 to +32767.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Examples, if Pr **01.028** has a range of  $\pm 100000$ , and Pr **01.029** has a range of  $\pm 10000$ .

| Write            | Start register address | Number of 16bit registers | Data       | Comments                                                              |
|------------------|------------------------|---------------------------|------------|-----------------------------------------------------------------------|
| Pr <b>01.028</b> | 127                    | 1                         | 0x1234     | Standard 16 bit write to a 32bit register. Value written = 0x00001234 |
| Pr <b>01.028</b> | 127                    | 1                         | 0xABCD     | Standard 16 bit write to a 32bit register. Value written = 0xFFFFABCD |
| Pr <b>01.028</b> | 16511                  | 2                         | 0x00001234 | Value written = 0x00001234                                            |
| Pr <b>01.029</b> | 128                    | 1                         | 0x0123     | Value written = 0x0123                                                |
| Pr <b>01.029</b> | 16512                  | 2                         | 0x00000123 | Value written = 0x00000123                                            |

\* Bit 14 is set to allow 32 bit access

### 9.1.8 Exceptions

The slave will respond with an exception response if an error is detected in the master request. If a message is corrupted and the frame is not received or the CRC fails then the slave will not issue an exception. In this case the master device will time out. If a write multiple (FC16 or FC23) request exceeds the slave maximum buffer size then the slave will discard the message. No exception will be transmitted in this case and the master will time out.

#### Exception message format

The slave exception message has the following format.

| Byte | Description                           |
|------|---------------------------------------|
| 0    | Slave source node address             |
| 1    | Original function code with bit 7 set |
| 2    | Exception code                        |
| 3    | CRC LSB                               |
| 4    | CRC MSB                               |

#### Exception codes

The following exception codes are supported.

| Code | Description                                                          |
|------|----------------------------------------------------------------------|
| 1    | Function code not supported                                          |
| 2    | Register address out of range, or request to read too many registers |

#### Parameter over range during block write FC16

The slave processes the write block in the order the data is received. If a write fails due to an out of range value then the write block is terminated. However, the slave does not raise an exception response, rather the error condition is signalled to the master by the number of successful writes field in the response.

#### Parameter over range during block read/write FC23

There will be no indication that there has been a value out of range during a FC23 access.

### 9.1.9 CRC

The CRC is a 16 bit cyclic redundancy check using the standard CRC-16 polynomial  $x^{16} + x^{15} + x^2 + 1$ . The 16 bit CRC is appended to the message and transmitted LSB first.

The CRC is calculated on ALL the bytes in the frame.

### 9.1.10 Device compatibility parameters

All devices have the following compatibility parameters defined:

| Parameter                        | Description                                                                                                                                                                                                       |
|----------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Device ID                        | Unique device identification code                                                                                                                                                                                 |
| Minimum slave response time      | The minimum delay between the end of a message from the master and the time at which the master is ready to receive a response from the slave. Refer to Pr <b>11.029</b> ( <i>Minimum Comms Transmit Delay</i> ). |
| Maximum slave response time      | When global addressing, the master must wait for this time before issuing a new message. In a network of devices, the slowest time must be used.                                                                  |
| Maximum baud rate                |                                                                                                                                                                                                                   |
| 32 bit float data type supported | If this data type is not supported then an over range error will be raised if this data type is used.                                                                                                             |
| Maximum buffer size              | Determines the maximum block size.                                                                                                                                                                                |

## 9.2 Ethernet communication (Unidrive M700 / M702)

This section describes the adaptation of the Ethernet interface offered on the Unidrive M700 and M702 drives. The portable software class which implements this protocol is also defined.

### 9.2.1 Features

The following list gives an overview of the functionality available:

- Dual RJ45 connectivity with support for shielded twisted pair.
- 100 Mbs Ethernet with auto-negotiation.
- Full and half duplex operation with auto-negotiation.
- Auto crossover detection.
- TCP/IP.
- Modbus TCP/IP.
- EtherNet/IP or Profinet IO.
- Switch or Gateway mode.
- VLAN tagging.
- SyPTPro.
- Unidrive M Connect.
- Machine Control Studio.
- Static IP configuration or DHCP client.
- Non-cyclic data transfer with user program.
- Up to 3 transmit and 3 receive cyclic links (easy mode).
- IEEE1588 Precision Time Protocol synchronization.
- RTMoE (Real Time Motion over Ethernet).

### 9.2.2 Backup/auxiliary supply

Some drives provide a method of powering up the control circuits (and therefore any option module installed) if the AC supply is removed, this allows Ethernet communication to continue operating when the main AC supply is switched off.

### 9.2.3 Network design considerations

Ethernet is an open system allowing many different vendors to design and supply equipment. When designing an industrial network you must carefully consider the topology and data traffic on the network to avoid potential problems.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

To avoid bandwidth issues it is recommended that the control network is logically separate from any other network. Where possible a physically separate network should be used. If this is not possible, the use of managed network devices should be considered to prevent unnecessary traffic such as broadcasts reaching the control network.

**NOTE** The use of un-switched hubs is not supported.

## 9.2.4 Addressing

The addressing system used on Ethernet uses two essential numbers for making connection, these are the IP address and the subnet mask. The address allows a specific device to be located and the subnet mask defines how many bits represent the subnet part of the address and how many bits represent the node address (see section 9.2.7 *Generating the complete address* on page 116). Generally devices on different subnets can only communicate by using a gateway (typically a router or firewall).

## 9.2.5 Where do IP addresses come from?

Every address on a network must be unique. If you do not connect your network to any other networks the assignment of IP addresses is not critical (although using a standard system is recommended), as you have full control of the addresses used. The issue of addressing becomes important when connecting multiple networks together or connecting to the Internet where there is a strong possibility of duplication of addresses if a scheme is not followed.

## 9.2.6 Addressing etiquette

The following list details some points that should be considered when selecting addresses:

- **Reserve address space:** Ensure you have enough reserve address space on your chosen addressing scheme to allow for future expansion.
- **Uniqueness:** Ensure your addresses are unique, every device on a subnet must have a unique address.
- **Avoid reserved addresses:** For example the address 127.0.0.1 is reserved as the loop back address.
- **Broadcast and system addresses:** The highest and lowest host address on a subnet are reserved addresses.
- **Use a system:** Have a scheme for assigning your addresses, for example typically servers may have a low IP address and routers a high IP address. It is not necessary to allocate consecutive IP addresses so it is possible to reserve ranges for specific uses such as servers, work stations or routers.

## 9.2.7 Generating the complete address

A complete IP address consists of an IP address and a subnet mask, these two numbers are required to allow communication on Ethernet using TCP/IP.

### The IP address

The IP address is made up from four 8 bit decimal numbers (*octets*) and is written as follows:

w.x.y.z for example 192.168.0.1

### The subnet mask

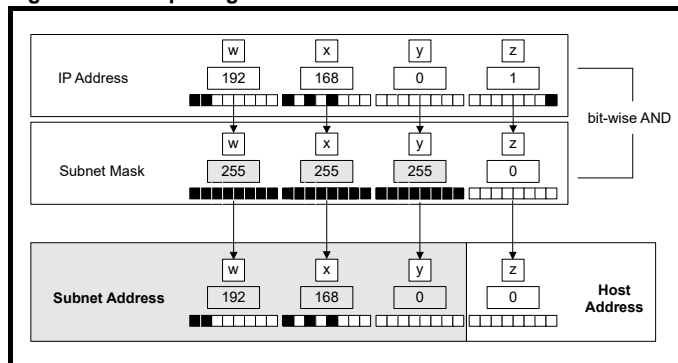
The subnet mask defines what part of the address constitutes the subnet within the IP address and what part of the address constitutes the host address. The subnet mask is bit-wise ANDed with the address to give the subnet to which the host belongs. A typical subnet mask would be 255.255.255.0, this may alternatively be written as '/24' as in the example below, showing an IP address of 192.168.0.1 with a subnet mask of 255.255.255.0. This alternative notation indicates the number of bits representing the subnet part of the address, starting from the most significant bit.

Alternative subnet mask notation: 192.168.0.1 /24

## Completing the address

To determine which part of the address constitutes the network address and which part constitutes the node address, the IP address is bit-wise ANDed with the subnet mask. Figure 9-1 shows how the IP address and subnet mask are used to determine the subnet address and the host address.

Figure 9-1 Completing the address



## 9.2.8 DHCP considerations

### Using fixed IP addressing

Using fixed IP addresses (*manually configured*) means that if a module fails, the IP address can be restored to a replacement module without the need to reconfigure the DHCP server. Using fixed addresses also prevents the DHCP server from changing the address. When using fixed IP addresses, it is vital that the IP address is reserved on the DHCP server to prevent duplicate addressing.

**NOTE** If using manual IP address configuration please note that the IP address subnet mask and the default gateway must also be set manually.

**NOTE** In Profinet mode, Pr 4.02.004 (*DHCP Enable*) will be forced off on initialisation.

## 9.2.9 Basic principles of routing

Routing is required to get TCP/IP packets from one subnet to another. In an IP network, nodes from one subnet cannot communicate directly with nodes on a different subnet. To allow nodes to communicate, a router (or similar device) is required to allow the two subnets to exchange data. This means that any node wishing to communicate with a node that is not on its own subnet, must know the address of a router that is on its own subnet. This is sometimes called a gateway or default gateway.

## 9.3 CT Modbus TCP/IP specification (Unidrive M700 / M702)

### Modbus TCP/IP

Modbus TCP/IP is one of the most widely supported industrial Ethernet based protocols offering the functionality and simplicity of the Modbus protocol, with the flexibility of Ethernet. Table 9-11 shows the supported Modbus function codes.

Modbus TCP/IP uses the standard Modbus RTU Protocol Data Unit (PDU) but without the CRC bytes and encapsulates it within a Modbus TCP/IP Application Data Unit (ADU) for transmission. This means that the Modbus PDU is the same for both standard (RTU) and Ethernet based transmission.

Table 9-11 Supported Modbus function codes

| Code | Description                               |
|------|-------------------------------------------|
| 3    | Read multiple 16 bit registers.           |
| 6    | Write single 16 bit register.             |
| 16   | Write multiple 16 bit registers.          |
| 23   | Read and write multiple 16 bit registers. |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 9.3.1 Data structure

Communication between devices is based upon Modbus Application Data Units (ADUs), the ADU consists of 2 parts, the Modbus Application Protocol (MBAP) header and the Modbus Protocol Data Unit (PDU).

Figure 9-2 Modbus Data Structure

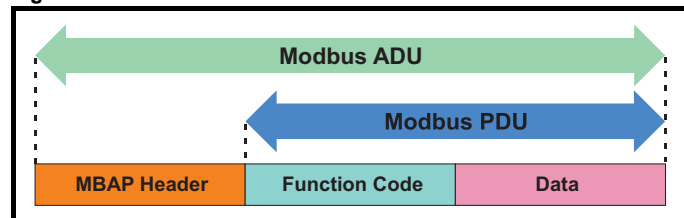


Table 9-12 MBAP Header

| Field                  | Length (Bytes) | Description                                         |
|------------------------|----------------|-----------------------------------------------------|
| Transaction Identifier | 2              | Uniquely identifies the transaction (0 to 65535)    |
| Protocol Identifier    | 2              | Identifies the protocol (0 = Modbus)                |
| Length                 | 2              | Number of following bytes in the message            |
| Unit Identifier        | 1              | Uniquely identifies the destination node (0 to 255) |

The unit identifier within the MBAP header is used to identify whether the destination node is the host drive or an option module (not available on the onboard Ethernet interface with firmware versions prior to V01.02.01.10).

Table 9-13 MBAP Unit Identifier

| Unit Identifier | Destination               |
|-----------------|---------------------------|
| 0 or 255        | Drive                     |
| 1               | Slot 1                    |
| 2               | Slot 2                    |
| 3               | Slot 3                    |
| 4               | Slot 4 (onboard Ethernet) |
| 254             | Self                      |

### 9.3.2 Data access

Data access using Modbus TCP/IP takes the form of a request for data by the master, followed by a response from the slave indicating success or failure. If no response is received this indicates that the message has not been received or the message is invalid or the node is unable to reply.

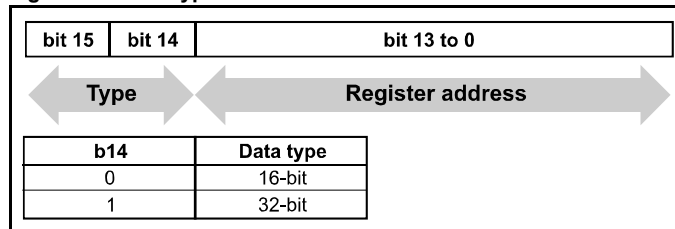
Each drive or option module parameter is internally mapped to a single 16-bit Modbus register, all Modbus function codes access 16-bit registers only. To access a 32-bit parameter, two contiguous Modbus registers must be specified in the request and the 32-bit data access scheme must be used.

### 9.3.3 32-bit data access

Standard Modbus registers are 16 bits in size and reference a single drive/option module parameter. To access a 32-bit data value the multiple read/write services must be used to transfer a contiguous array of 16-bit registers. To instruct the client to select either 16-bit or 32-bit access bit 14 of the register address is used.

**NOTE** Bit b15 of the register address is reserved for future use.

Figure 9-3 Data type selection



If 32-bit data type is selected then this effectively adds 16384 (0x4000) to the start register address.

e.g. For drive parameter Pr **01.021** in standard addressing mode, the start register value is 16384 + 120 = 16504 (0x4078)

### 9.3.4 Supported Modbus function codes

The following table details the supported Modbus function codes.

Table 9-14 Supported Modbus function codes

| Function Code |          | Description                              |
|---------------|----------|------------------------------------------|
| Decimal       | Hex (0x) |                                          |
| 3             | 03       | Read multiple 16-bit registers           |
| 6             | 06       | Write single 16-bit register             |
| 16            | 10       | Write multiple 16-bit registers          |
| 23            | 17       | Read and write multiple 16-bit registers |

### 9.3.5 Register addressing

The Modbus register address is 16 bits in size, of which the upper two bits are used for data type selection leaving 14 bits to represent the parameter address, taking into account the slave increments the address value by 1, this results in a theoretical maximum parameter address of 163.84 (limited to 162.99 in software) when the default standard addressing mode (see *Modbus Register Addressing Mode (S.15.013)*) is used.

To access a parameter number above 99 then the modified addressing mode must be used (see *Modbus Register Addressing Mode (S.15.013)*), this will allow access to parameter numbers up to 255 but also limit the maximum menu number to 63.

**NOTE** A reset is not required to activate the change, the addressing mode is effectively made active immediately on changing.

The Modbus slave device increments the register address by 1 before processing the command, this effectively prevents access to parameter Pr **00.000** in the drive or option module.

The Table 9-15 shows how the start register address is calculated for both addressing modes.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Table 9-15 Start register addressing**

| CT<br>Parameter | Addressing<br>mode | Protocol register  |          |         |          |
|-----------------|--------------------|--------------------|----------|---------|----------|
| s.mm.ppp        | Standard           | mm * 100 + ppp - 1 |          |         |          |
|                 | Modified           | mm * 256 + ppp - 1 |          |         |          |
| Examples        |                    |                    |          |         |          |
|                 |                    | 16-bit             |          | 32-bit  |          |
|                 |                    | Decimal            | Hex (0x) | Decimal | Hex (0x) |
| 0.01.021        | Standard           | 120                | 00 78    | 16504   | 40 78    |
|                 | Modified           | 276                | 01 14    | 16660   | 41 14    |
| 0.01.000        | Standard           | 99                 | 00 63    | 16483   | 40 63    |
|                 | Modified           | 255                | 00 FF    | 16639   | 40 FF    |
| 3.70.001        | Standard           | 7000               | 1B 58    | 23384   | 5B 58    |
|                 | Modified           | N/A                | N/A      | N/A     | N/A      |
| 0.03.161        | Standard           | N/A                | N/A      | N/A     | N/A      |
|                 | Modified           | 928                | 03 A0    | 17312   | 43 A0    |

**9.3.6 FC03 – Read multiple registers**

This function code allows a contiguous array of registers to be read. The maximum number of registers that can be read is 120, this allows up to 120 16-bit parameters or 60 32-bit parameters to be read in a single transaction. If this is exceeded the server will issue an exception response code 2.

**Master request data**

| Byte | Description                      |
|------|----------------------------------|
| 7    | Function code 0x03               |
| 8    | Start register address (MSB)     |
| 9    | Start register address (LSB)     |
| 10   | Number of 16-bit registers (MSB) |
| 11   | Number of 16-bit registers (LSB) |

**Slave response data**

| Byte | Description                          |
|------|--------------------------------------|
| 7    | Function code 0x03                   |
| 8    | Length of data in read block (Bytes) |
| 9    | Register data (MSB)                  |
| 10   | Register data (LSB)                  |

The normal response includes the function code, number of data bytes in the read block followed by the register data (unless an exception occurs).

If 32-bit parameter addressing is used, then for each parameter read:

- Two 16-bit registers must be used in the request
- The register data in the response will contain 4 bytes of data

**Example**

To read drive parameters **0.20.021** to **0.20.023** (transaction ID = 42) with 32-bit data access and standard addressing:

**Master request data**

| Byte  | Hex value | Description                 |
|-------|-----------|-----------------------------|
| 0-1   | 00 2A     | Transaction ID (42)         |
| 2-3   | 00 00     | Protocol ID (0=TCP/IP)      |
| 4-5   | 00 06     | Length (Bytes=6)            |
| 6     | FF        | Unit identifier (FF= Drive) |
| 7     | 03        | Function code (3)           |
| 8-9   | 47 E4     | Start register (20.20)      |
| 10-11 | 00 06     | Number of registers (6)     |

**Slave response data**

| Byte  | Hex value | Description                 |
|-------|-----------|-----------------------------|
| 0-1   | 00 2A     | Transaction ID (42)         |
| 2-3   | 00 00     | Protocol ID (0=TCP/IP)      |
| 4-5   | 00 0F     | Length (Bytes=15)           |
| 6     | FF        | Unit identifier (FF= Drive) |
| 7     | 03        | Function code (3)           |
| 8     | 0C        | Data length (Bytes=12)      |
| 9-12  | ?         | Pr <b>0.20.021</b> data     |
| 13-16 | ?         | Pr <b>0.20.022</b> data     |
| 17-20 | ?         | Pr <b>0.20.023</b> data     |

**9.3.7 FC06 – Write single register**

This function code writes a single 16-bit value to a register. The normal response is an echo of the request (unless an exception occurs) returned after the parameter has been written.

The register address can be a 32-bit parameter address but only the lower 16 bits of the value will be written.

**Master request data**

| Byte | Description                  |
|------|------------------------------|
| 7    | Function code 0x06           |
| 8    | Start register address (MSB) |
| 9    | Start register address (LSB) |
| 10   | Register data (MSB)          |
| 11   | Register data (LSB)          |

**Slave response data**

| Byte | Description                  |
|------|------------------------------|
| 7    | Function code 0x06           |
| 8    | Start register address (MSB) |
| 9    | Start register address (LSB) |
| 10   | Register data (MSB)          |
| 11   | Register data (LSB)          |

**Example**

To write the value 12345 to drive parameter **0.20.001** (transaction ID = 42) using standard addressing:

**Master request data**

| Byte  | Hex value | Description                      |
|-------|-----------|----------------------------------|
| 0-1   | 00 2A     | Transaction ID (42)              |
| 2-3   | 00 00     | Protocol ID (0=TCP/IP)           |
| 4-5   | 00 06     | Length (Bytes=6)                 |
| 6     | FF        | Unit identifier (FF= Drive)      |
| 7     | 06        | Function code (06)               |
| 8-9   | 07 D0     | Start register ( <b>20.000</b> ) |
| 10-11 | 30 39     | Register data (12345)            |

**Slave response data**

| Byte  | Hex value | Description                      |
|-------|-----------|----------------------------------|
| 0-1   | 00 2A     | Transaction ID (42)              |
| 2-3   | 00 00     | Protocol ID (0=TCP/IP)           |
| 4-5   | 00 06     | Length (Bytes=6)                 |
| 6     | FF        | Unit identifier (FF= Drive)      |
| 7     | 06        | Function code (6)                |
| 8-9   | 07 D0     | Start register ( <b>20.000</b> ) |
| 10-11 | 30 39     | Register data (12345)            |

**9.3.8 FC16 – Write multiple registers**

This function code allows a contiguous series of registers to be written. The maximum number of registers that can be written is 120, this allows up to 120 16-bit parameters or 60 32-bit parameters to be read in a single transaction. If this is exceeded the server will issue an exception response code 2. The normal response includes the function code, start register address and number of 16-bit registers written (unless an exception occurs), returned after the parameters have been written.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

If 32-bit parameter addressing is used, then for each parameter written:

- Two 16-bit registers must be used in the request
- Four bytes must be specified in the request
- The number of registers written in the response will be twice the number of parameters written

#### Master request data

| Byte | Description                              |
|------|------------------------------------------|
| 7    | Function code 0x10                       |
| 8    | Start register address (MSB)             |
| 9    | Start register address (LSB)             |
| 10   | Number of 16-bit registers (MSB)         |
| 11   | Number of 16-bit registers (LSB)         |
| 12   | Length of register data to write (Bytes) |
| 13   | Register data (MSB)                      |
| 14   | Register data (LSB)                      |

#### Slave response data

| Byte | Description                              |
|------|------------------------------------------|
| 7    | Function code 0x10                       |
| 8    | Start register address (MSB)             |
| 9    | Start register address (LSB)             |
| 10   | Number of 16-bit registers written (MSB) |
| 11   | Number of 16-bit registers written (LSB) |

#### Master request data Slave response data

| Byte | Description                              |
|------|------------------------------------------|
| 7    | Function code 0x17                       |
| 8    | Start read register address (MSB)        |
| 9    | Start read register address (LSB)        |
| 10   | Number of registers to read (MSB)        |
| 11   | Number of registers to read (LSB)        |
| 12   | Start write register address (MSB)       |
| 13   | Start write register address (LSB)       |
| 14   | Number of registers to write (MSB)       |
| 15   | Number of registers to write (LSB)       |
| 16   | Length of register data to write (Bytes) |
| 17   | Register data 0 (MSB)                    |
| 18   | Register data 0 (LSB)                    |

| Byte | Description                          |
|------|--------------------------------------|
| 7    | Function code 0x17                   |
| 8    | Length of data in read block (Bytes) |
| 9    | Register data (MSB)                  |
| 10   | Register data (LSB)                  |

#### Example

To write the value 12345 to drive parameters **0.20.021** through **0.20.023** (Transaction ID=42) using standard 32-bit addressing:

#### Master request data

| Byte  | Hex value   | Description                      |
|-------|-------------|----------------------------------|
| 0-1   | 00 2A       | Transaction ID (42)              |
| 2-3   | 00 00       | Protocol ID (0=TCP/IP)           |
| 4-5   | 00 13       | Length (Bytes=19)                |
| 6     | FF          | Unit identifier (FF= Drive)      |
| 7     | 10          | Function code (16)               |
| 8-9   | 47 E4       | Start register ( <b>20.020</b> ) |
| 10-11 | 00 06       | Number of registers (6)          |
| 12    | 0C          | Register data length (Bytes)     |
| 13-16 | 00 00 30 39 | Register data 0                  |
| 17-20 | 00 00 30 39 | Register data 1                  |
| 21-24 | 00 00 30 39 | Register data 2                  |

#### Slave response data

| Byte  | Hex value | Description                      |
|-------|-----------|----------------------------------|
| 0-1   | 00 2A     | Transaction ID (42)              |
| 2-3   | 00 00     | Protocol ID (0=TCP/IP)           |
| 4-5   | 00 06     | Length (Bytes=6)                 |
| 6     | FF        | Unit identifier (FF= Drive)      |
| 7     | 10        | Function code (16)               |
| 8-9   | 47 E4     | Start register ( <b>20.020</b> ) |
| 10-11 | 00 06     | Registers written (6)            |

The normal response includes the function code, number of data bytes in the read block followed by the register data (unless an exception occurs).

If 32-bit parameter addressing is used:

- For each parameter read or written, two 16-bit registers must be used in the request
- For each parameter written, four bytes must be specified in the request
- For each parameter read, four bytes of data will be used in the response

### 9.3.9 FC23 - Read/Write multiple registers

This function code allows a contiguous series of registers to be written and another contiguous series of registers to be read. The maximum number of registers that can be read is 120 and similarly the maximum number of registers that can be written is 120, this allows up to 120 16-bit parameters or 60 32-bit parameters to be read and / or written in a single transaction. If this is exceeded the server will issue an exception response code 2.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Example**

To write the value 12345 to drive parameters **0.20.021** through **0.20.023** and read the values of parameters **0.20.024** through **0.20.026**

(Transaction ID=42) using standard addressing:

**Master request data**

| Byte  | Hex value      | Description                                 |
|-------|----------------|---------------------------------------------|
| 0-1   | 00 2A          | Transaction ID (42)                         |
| 2-3   | 00 00          | Protocol ID (0=TCP/IP)                      |
| 4-5   | 00 17          | Length (Bytes=6)                            |
| 6     | FF             | Unit identifier (FF= Drive)                 |
| 7     | 17             | Function code (23)                          |
| 8-9   | 47 E7          | Start read register ( <b>20.023</b> )       |
| 10-11 | 00 06          | Number of read registers (6)                |
| 12-13 | 47 E4          | Start write register ( <b>20.020</b> )      |
| 14-15 | 00 06          | Number of write registers (6)               |
| 16    | 0C             | Length of register data to write (Bytes=12) |
| 17-20 | 00 00<br>30 39 | Register data 0 (12345)                     |
| 21-24 | 00 00<br>30 39 | Register data 1 (12345)                     |
| 25-28 | 00 00<br>30 39 | Register data 2 (12345)                     |

**Slave response data**

| Byte  | Hex value      | Description                         |
|-------|----------------|-------------------------------------|
| 0-1   | 00 2A          | Transaction ID (42)                 |
| 2-3   | 00 00          | Protocol ID (0=TCP/IP)              |
| 4-5   | 00 0F          | Length (Bytes=15)                   |
| 6     | FF             | Unit identifier (FF= Drive)         |
| 7     | 17             | Function code (23)                  |
| 8     | 0C             | Length of data (Bytes=12)           |
| 9-12  | ?? ??<br>?? ?? | Register data 0 (Pr <b>20.024</b> ) |
| 13-16 | ?? ??<br>?? ?? | Register data 1 (Pr <b>20.025</b> ) |
| 17-20 | ?? ??<br>?? ?? | Register data 2 (Pr <b>20.026</b> ) |

**9.3.10 Modbus Exception Response Message**

If the master request is rejected then an exception response message will be returned.

**Exception Response Message**

| Byte | Hex value | Description                                                                         |
|------|-----------|-------------------------------------------------------------------------------------|
| 0-1  | ?? ??     | Transaction ID (defined by Modbus Master)                                           |
| 2-3  | 00 00     | Protocol ID                                                                         |
| 4-5  | 00 03     | Number of data bytes to follow                                                      |
| 6    | ??        | Unit identifier                                                                     |
| 7    | ??        | Function code (request FC with bit b7 set to 1)                                     |
| 8    | ??        | Exception code<br>01 = Function code not supported<br>02 = Invalid register address |

The master request function code will be returned but with bit b7 set (e.g. function code 0x03 will be returned as 0x83).

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 9.4 RTMoE (Real Time Motion over Ethernet) (Unidrive M700 / M702)

This is a communication protocol developed to provide Ethernet synchronisation and data transfer between Control Techniques drives.

RTMoE provides:

- Drive synchronization using the Precision Time Protocol (PTP) otherwise known as IEEE1588 V2  
Each PTP device has a tuneable clock running. Following an arbitration process the devices select a master and tune their clocks until they are synchronized to that master. This process may take several seconds to complete.
- Data transfer
  - Cyclic data (synchronous and non-synchronous) is sent using the User Datagram Protocol (UDP)
  - Non-cyclic data is sent using the Transmission Control Protocol (TCP)
- Cycle time down to 250  $\mu$ s (Using Machine Control Studio)
- Jitter less than 1  $\mu$ s

RTMoE can be configured in two ways:

- Via Machine Control Studio using the Advanced link editor or
- Via parameters using the Easy Mode menus (10 and 11)

The full capabilities of RTMoE are available only when using Machine Control Studio.

Table 9-16 shows the comparison between Easy Mode and Machine Control Studio support levels.

**Table 9-16 RTMoE Support levels**

| Capability                                     | Support Level                |                                           |
|------------------------------------------------|------------------------------|-------------------------------------------|
|                                                | Easy Mode                    | Machine Control Studio <sup>(1) (3)</sup> |
| Non-cyclic communication                       | No                           | Yes                                       |
| Total number of transmit cyclic links          | 3                            | 11                                        |
| Total number of receive cyclic links           | 3                            | 11                                        |
| Max transmit synchronous links                 | 1                            | 1                                         |
| Max receive synchronous links                  | 1                            | 1                                         |
| Max length of non-synchronous link             | 10 x 32-bit                  | 10 x 32-bit <sup>(2)</sup>                |
| Max length of synchronous link                 | 3 x 32-bit                   | 3 x 32-bit                                |
| Minimum transmission period (non-synchronised) | 1 ms                         | 1 ms                                      |
| Maximum transmission period (non-synchronised) | 100 ms                       | 100 ms <sup>(3)</sup>                     |
| Minimum transmission period (Synchronised)     | 1 ms                         | 250 $\mu$ s                               |
| Maximum transmission period (Synchronised)     | 8 ms                         | 8 ms                                      |
| Synchronised with onboard program              | Yes (when cycle time = 4 ms) | Yes (when cycle time = 4 ms)              |
| Max parameter accesses per second              | 6000                         | 6000                                      |
| Max messages per second ( <b>S.02.004</b> )    | 8000                         | 8000                                      |

<sup>(1)</sup> MCi2x0 firmware version V01.08.04.06 and later.

<sup>(2)</sup> Maximum number of parameter in a non-synchronous links between two MCi210 modules (V01.08.04.06 and later) is 20.

<sup>(3)</sup> Currently the Ethernet interface only supports cyclic links using Easy Mode (Menu 10), cyclic links using Machine Control Studio will be available in a future release of the Ethernet interface firmware.

**NOTE** The number of cyclic links is limited to a maximum of 2 when accessing the option module internal parameters (e.g. the PLC register menus 7x).

### 9.4.1 RTMoE Message rate capability

When designing a network, the message loading for each device should be checked to ensure the number of messages do not exceed the maximum recommended value.

Consider the following example where a Unidrive M700 is communicating with three other devices over Ethernet using Modbus TCP/IP (10 parameters read every 100 ms), EtherNet/IP (5 parameters read every 10 ms and 5 parameters written every 10 ms) and RTMoE (2 parameters written every 500  $\mu$ s).

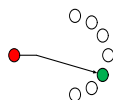
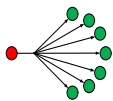
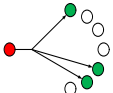
| Protocol           | Number of Parameters | Rate        | Parameters accessed / second | Message rate / second |
|--------------------|----------------------|-------------|------------------------------|-----------------------|
| Modbus TCP/IP      | 10 x read            | 100 ms      | 100                          | 10                    |
| EtherNet/IP        | 5 x read             | 10 ms       | 500                          | 100                   |
|                    | 5 x write            | 10 ms       | 500                          | 100                   |
| RTMoE              | 2 x write            | 500 $\mu$ s | 4000                         | 2000                  |
| Total              |                      |             | 5100                         | 2210                  |
| Maximum supported  |                      |             | 6000                         | 8000                  |
| Within capability? |                      |             | ✓                            | ✓                     |

### 9.4.2 RTMoE Message type

From the system design, it should be known how many drives will be used and what data needs to be sent where. There are two fundamental ways of sharing data:

- Cyclic data – use cyclic links for important information relating to the dynamic behavior of the machine (e.g. control word, speed reference, etc.)
- Non-cyclic data – used for non time-critical information (e.g. drive setup data) A user program must be used to control the transfer of non-cyclic messages. (see *Non cyclic enable* (**S.02.035**) and *Non cyclic base parameter* (**S.02.036**))

Each cyclic message can be one of three types:

- Unicast – used if data needs to go from one device to another  

- Broadcast – used if data needs to go from one device to all other devices  

- Multicast – used if data needs to go from one device to a subset of the other devices  


By choosing the most appropriate transmission type an efficient and reliable network can be designed.

For example:

- Three drives must use an ELS (Electronic Line Shaft) to follow a Smart Drive. In this case a **multicast** message should be used to transmit the reference position from the Smart Drive.
- Three drives need to return general status information to the Smart Drive. In this case, each drive should send a **unicast** message to the Smart Drive.
- The Smart Drive needs to command all other drives to stop/start. The Smart Drive should use a broadcast message to transmit the command to all the other drives.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**NOTE** Broadcast messages should be used with care, bottlenecks in the network can be easily created by using broadcast messages, this will reduce the performance of the network and, in extreme situations, seriously impair the system operation.

### 9.4.3 Checking for bottlenecks

There are three main reasons why a bottleneck occurs:

1. A drive is receiving more Ethernet messages than it can handle (8000 frames per second).
2. A drive is being asked to access more parameters than it can handle (6000 parameters per second).
3. A segment of the network has reached its bandwidth limit.  
For a full duplex 100Mbit/sec Ethernet network, assuming all Ethernet messages are the maximum 1500 bytes in length, the bandwidth is 8000 frames/sec in each direction.

**NOTE**

- It is unrealistic to assume that all messages will be full frames
- In reality the maximum number of frames/sec will be higher
- A more detailed frame analysis may be performed if necessary but the values stated can be used to quickly determine whether bottlenecks could be a problem

### 9.4.4 RTMoE Message synchronization

Cyclic messages can be synchronized or non-synchronized.

Only one synchronized cyclic link in each direction (one transmit and one receive) is possible so these should only be used for high precision applications where the motion of multiple drives must be closely coupled (e.g. printing applications). All other messages should be sent using a non-synchronized cyclic link.

Synchronized cyclic data links utilise the IEEE1588 clock time distributed across the network. The IEEE1588 clock can synchronize the drive's control loops to within a 1 µs accuracy, Pr **0.11.002 Option Synchronisation Active** displays the active option slot providing synchronization. With synchronized control loops the Ethernet interface can be used to transfer drive parameters containing motion information, including those from the AMC.

With normal Ethernet there are a number of variables that can impact upon the performance of the network. These include:

- Delays through switches - Ethernet is a switched network and messages are typically copied completely into a switch before being forwarded on. *This is fundamental to modern Ethernet and cannot be influenced by system design.*
- Message length – the longer a message, the longer it will take to transmit and copy into a switch before forwarding it on. For a synchronous cyclic link frame this delay is 12 µs, for a full Ethernet frame it is 120 µs.  
Message length can be controlled, but to maximise compatibility with other Ethernet traffic, it is sensible to allow for full frame Ethernet messages where possible.
- Length of daisy chain - A daisy chain with Ethernet is really a chain of three port switches.  
This can be controlled through physical network design e.g. using a tree structure to limit the length of daisy chains.

The above delays (Latency) are managed in software, in conjunction with PTP, to ensure that all device use synchronous data at the same time, but the length of the daisy chain must be controlled by careful network design.

### 9.4.5 General guidelines for synchronous cyclic data

The following guidelines provide a simple way of specifying a network supporting synchronous cyclic data that offers accurate synchronization and guaranteed determinism, whilst maintaining compatibility with standard Ethernet traffic.

- Limit daisy chains to 10 drives
- Where more than 10 drives are used, create a tree structure using a switch
- Any Ethernet switches must support IEEE1588 V2
- Segregate the network using VLANs and gateways
- Assign one device to be the synchronization master for each segregated network

### 9.4.6 Segregating the network

If synchronous cyclic links are used, for best reliability it is sensible to segregate the network. This means:

- Assign one (or more) drive(s) to be a gateway, which ensures messages entering the segregated section are stripped of any existing prioritisation information. (See *Gateway Mode (S.02.025)*)
- Ensure that **VLAN** (Virtual Local Area Network) is enabled on all devices so that synchronous data can be prioritized as it is passed between switches. (See *VLAN Enable (S.02.030)*)
- Use multiple Master Clock Domains. (See *Master Clock Domain (S.11.002)*)

### 9.4.7 Synchronization master

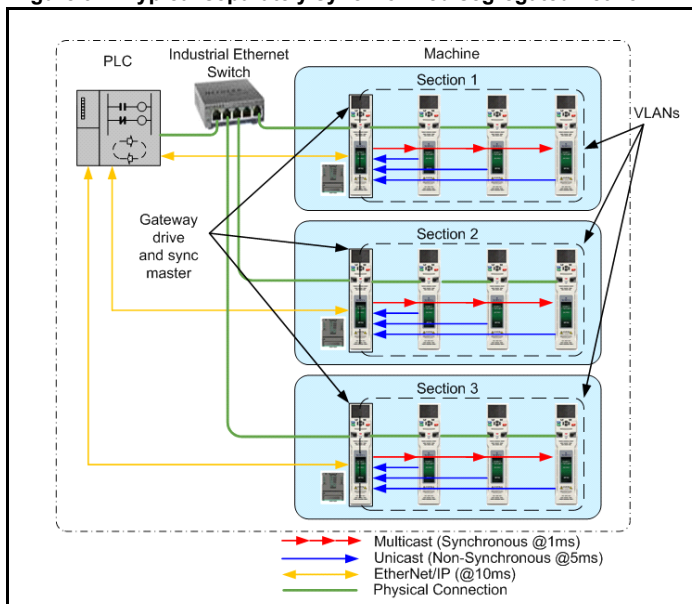
If a synchronous cyclic link is used then one device must be a synchronous master, if this is an existing 3<sup>rd</sup> party device then, to minimize the initialization time, all other devices/drives on the network should not be allowed to become the synchronous master. To disable the drive from becoming the synchronous master then set the value in *Preferred Sync Master (S.11.001)* to 0, this ensures the drive does not become the synchronous master.

If there is no existing synchronous master then a suitable drive should be chosen (see *Preferred Sync Master (S.11.001)*), in choosing which drive to be the synchronous master, the physical position of the drives and network layout should be considered so as to minimize the number of switches each message has to pass through.

A typical segregated network using VLANs and gateways consisting of three separate sections of a machine controlled by one master PLC is shown in the following diagram.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 9-4 Typical separately synchronized segregated network



**NOTE** Configuring a single drive to act as both gateway and synchronization master will increase the message loading on that drive, in some situations this may result in a reduction of the network performance. In these situations, separate drives should be used for the gateway and synchronization master.

**NOTE** For the gateway mode to operate correctly, the standard Ethernet network must be connected to port 1 on the drive and the real-time Ethernet to port 2 as shown in Figure 9-4.

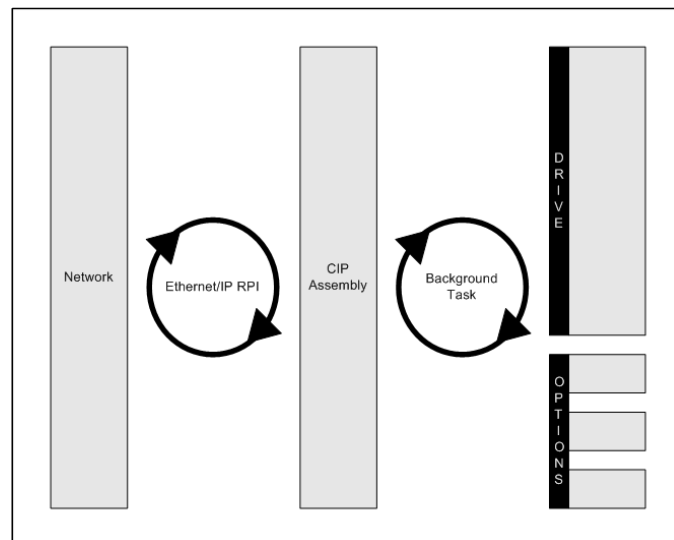
#### 9.4.8 VLANs

To guarantee the timing of synchronous links VLANs must be enabled using *VLAN Enable (S.02.030)*. VLANs include a priority field that is applied to all messages. This field is used to apply a higher priority to synchronous cyclic data than other non-deterministic traffic.

#### 9.4.9 Parameter Update Rate

Parameters are exchanged over the network. The value exchanged over the network must be exchanged with the drive or option parameter. The rate of data exchange differs for synchronous and non-synchronous cyclic links as well as for drive and option destinations.

The diagram below depicts the update cycles used within the Ethernet interface. Cyclic link mappings being exchanged with the drive will be updated at the background task rate. This rate (*Background cycles per second (S.09.008)*) varies with the load on the Ethernet interface; EtherNet/IP data exchange also takes place in the background task.



#### 9.5 EtherNet/IP specification (Unidrive M700 / M702)

The Ethernet interface supports the EtherNet/IP protocol and conforms to the EtherNet/IP adaptation of the Common Industrial Protocol (CIP) Specification. This is the same upper-layer protocol and object model as used in DeviceNet.

The Ethernet interface module will operate as a slave device and the following functionality is supported:

- Variable length input assembly object (instance 100) with consistency for up to 32 parameters
- Variable length output assembly object (instance 101) with consistency for up to 32 parameters
- User selectable RPI timeout action
- Identity object (class 0x01)
- Motor data object (class 0x28)
- Control supervisor object (class 0x29)
- AC/DC Drive object (class 0x2A)
- Control Techniques objects (classes 0x64 to 0x69)
- Explicit (non-cyclic) access to parameters

##### 9.5.1 Requested Packet Interval (RPI) timeout

This timeout is defined by the EtherNet/IP protocol and is configured in the PLC master. If enabled, the Ethernet interface will monitor the data traffic once the cyclic data has been established, and if data is not received within the specified time, it will perform the requested action as defined by Pr S.20.011 *RPI timeout action*. This indicates that the interface has detected that the cyclic data communication has been interrupted.

**NOTE** The RPI timeout action will only occur on a loss of cyclic data message, i.e. after cyclic data has been established and subsequently lost. No action will be taken if no cyclic data has been detected.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 9.5.2 Read consistency

Under normal conditions, cyclic data is sampled and transmitted at the Requested Packet Interval (RPI). However, if an option module was in the process of modifying the mapped parameters while these parameters were being sampled, then the data transmitted across the network may not be consistent across the entire assembly object. If read consistency is enabled (**S.20.026 In Consistency Enable**) and a trigger parameter specified in *In Consistency Trigger Param* (**S.20.027**) then data will only be sampled and transmitted when the trigger parameter *In Consistency Trigger Param* (**S.20.027**) contains a non-zero value. This trigger parameter will then be set to zero after the data has been sampled.

It is therefore possible, by controlling the trigger parameters, that a user program in the drive or option module can ensure that the values in the cyclic data parameters are not sampled until all values are updated.

Whether consistency is enabled or not, data will always be consistent for an individual parameter, i.e. all 4 bytes of a 32-bit value will be consistent.

### 9.5.3 Write consistency

Under normal conditions, cyclic data is sampled and written at the Requested Packet Interval (RPI). However, if an option module was in the process of reading the mapped parameters while these parameters were being written, then the data obtained may not be consistent across the entire assembly object. If write consistency is enabled (*Out Consistency Enable* (**S.20.028**)) and a trigger parameter specified in *Out Consistency Trigger Param* (**S.20.029**) then new data will only be written to the drive (or option module) when the trigger parameter *Out Consistency Trigger Param* (**S.20.029**) contains a value of zero. This trigger parameter will then be set to one after the data has been written.

It is therefore possible, by controlling the trigger parameters, that a user program in the drive or option module can ensure that the values in the cyclic data parameters are not sampled until all values are updated.

Whether consistency is enabled or not, data will always be consistent for an individual parameter, i.e. all 4 bytes of a 32-bit value will be consistent.

#### Example

In this example, Pr **0.18.031** is set as the input trigger and Pr **0.18.032** is set as the output trigger. The EtherNet/IP master is configured to check the values of Pr **0.20.011** and Pr **0.20.012** are equal and write the same value to Pr **0.20.021**. The SI-Applications Plus module is configured to generate a ramp value between -32768 and 32767 to write to Pr **0.20.011** and Pr **0.20.012** when the value of Pr **0.20.021** is equal to the ramp value.

With the input and output consistency enabled, parameters Pr **0.20.011** and Pr **0.20.012** will be sampled and transmitted to the EtherNet/IP master when the input trigger parameter Pr **0.18.031** is a non-zero value, Pr **0.20.021** will be written to when the output trigger parameter Pr **0.18.032** is a value of zero.

The parameter changes required are:

|                                               |             |
|-----------------------------------------------|-------------|
| <b>S.20.020</b> Input assembly object size    | = 8 (bytes) |
| <b>S.20.021</b> Output assembly object size   | = 4 (bytes) |
| <b>S.20.026</b> In Consistency Enable         | = On        |
| <b>S.20.027</b> In Consistency Trigger Param  | = 0.18.031  |
| <b>S.20.028</b> Out Consistency Enable        | = On        |
| <b>S.20.029</b> Out Consistency Trigger Param | = 0.18.032  |
| <b>S.21.001</b> Input mapping parameter 1     | = 0.20.011  |
| <b>S.21.002</b> Input mapping parameter 2     | = 0.20.012  |
| <b>S.22.001</b> Output mapping parameter 1    | = 0.20.021  |

The user program in the SI-Applications Plus module may be written as follows (some changes may be necessary to account for bus cycle times and parameter update rates):

```
Initial{
    // Initialise variables
    NewValue% = 0
    #86.03 = 0 // Set digital output0 off
    #86.04 = 0 // Set digital output1 off
    #20.011 = 0 // Set input parameter 1 to 0
    #20.012 = 0 // Set input parameter 2 to 0
    #20.021 = 0 // Set output parameter 1 to 0
    REINIT // Initialise configuration
} //Initial

Background{
top:

IF #18.32 = 1 THEN
    // Output trigger set
    // Check first sum value against NewValue
    IF #20.021 = NewValue% THEN
        // OK increment values by 1
        NewValue% = NewValue% + 1
        IF NewValue% > 32767 THEN NewValue = -32768
        #20.011 = NewValue%
        #20.012 = NewValue%

        // Set input trigger – Read input parameters and
        // transmit to master
        #18.031 = 1

        // Delay for PLC to get inputs - depends on cycle
        // time and parameter access time
        DO WHILE #18.031 = 1
            // Dummy command
            NewValue% = NewValue%
        LOOP

        // Reset output trigger
        #18.032 = 0

        // Delay for outputs to be written - depends on
        // parameter access time
        DO WHILE #18.032 = 0
            // Dummy command
            NewValue% = NewValue%
        LOOP

    ELSE
        // ERROR - set DOP0 ON
        #86.03 = 1
    ENDIF
ENDIF

goto top: // main background loop
} //Background
```

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 9.5.4 Non-cyclic (explicit) data transfer

Non-cyclic or explicit messaging is used to read and write parameters non-cyclically by means of assembly objects. All of the AC Drives profile attributes can be accessed using explicit messaging.

The *Control Techniques* objects provide access to all drive and slot parameters using the following format.

| Object            | CT Group                       | CT This Slot | CT Slot 1  | CT Slot 2  | CT Slot 3  | CT Slot 4  |
|-------------------|--------------------------------|--------------|------------|------------|------------|------------|
| <b>Class code</b> | 100 (0x64)                     | 101 (0x65)   | 102 (0x66) | 103 (0x67) | 104 (0x68) | 105 (0x69) |
| <b>Instance</b>   | Menu                           |              |            |            |            |            |
| <b>Attribute</b>  | Parameter                      |              |            |            |            |            |
| <b>Read code</b>  | 14 (0x0E) Get_Attribute_Single |              |            |            |            |            |
| <b>Write code</b> | 16 (0x10) Set_Attribute_Single |              |            |            |            |            |

**NOTE** An instance value of 0 is not a valid value in this context, therefore an instance value of 200 (0xC8) should be used to access menu 0 parameters. For more information on the *Control Techniques* object see section 9.5.21 *Control Techniques objects* on page 134.

### 9.5.5 Cyclic (implicit or polled) data transfer

Cyclic data is a method of data transfer that must be setup during network configuration, but is transmitted automatically at the determined rate once configuration is complete.

EtherNet/IP transfers cyclic data using assembly objects, “cyclic data” is sometimes referred to as “Polled data” or “implicit data”.

The terms “input” and “output” refer to data from the perspective of the PLC, an “output” assembly object transfers data from the PLC to the drive, an “input” assembly object transfers data from the drive to the PLC.

**NOTE** Some PLCs provide the option of transmitting a configuration assembly object. The Ethernet interface does not use a configuration object; if one is required by the PLC then instance 1 should be specified with a length of 0 bytes.

### 9.5.6 Configuring EtherNet/IP cyclic parameters

In order to use cyclic data over EtherNet/IP, the EtherNet/IP interface must be configured to map the required parameter data to the assembly object.

For drive parameter access, object 100 (0x64) is used for reading parameters and object 101 (0x65) is used for writing parameters. The pre-defined assembly objects as listed in Table 9-17 *Supported drive assembly objects* can also be configured as cyclic data.

### 9.5.7 Assembly objects

An assembly object is an object which contains a group of attributes to control or monitor the drive operation. These attributes can be members of EtherNet/IP objects or drive parameters. The Ethernet interface supports a series of standard assembly objects and two *Control Techniques* objects (100 and 101) to access the drive parameters (see Table 9-17 *Supported drive assembly objects* on page 125).

**NOTE** Conformance with the pre-defined assembly objects specification can only be guaranteed if the speed reference configuration of the drive has not been changed from the default settings. For information on setting default values, refer to the appropriate drive user guide.

Table 9-17 Supported drive assembly objects

| Assembly object name | Class   |          | Length (Bytes) | Type   | Default Mappings |              |
|----------------------|---------|----------|----------------|--------|------------------|--------------|
|                      | Decimal | Hex (0x) |                |        | Bytes 0 to 3     | Bytes 4 to 7 |
| PrimaryI             | 100     | 64       | 4 to 80        | Input  | 0.10.040         | 0.02.001     |
| BscSpdCtrlI          | 70      | 46       | 4              | Input  |                  |              |
| ExtSpdCtrlI          | 71      | 47       | 4              | Input  |                  |              |
| SpdTrqCtrlI          | 72      | 48       | 6              | Input  |                  |              |
| ExtSpdTrqCtrlI       | 73      | 49       | 6              | Input  |                  |              |
| PrimaryO             | 101     | 65       | 4 to 80        | Output | 0.06.042         | 0.01.021     |
| BscSpdCtrlO          | 20      | 14       | 4              | Output |                  |              |
| ExtSpdCtrlO          | 21      | 15       | 4              | Output |                  |              |
| SpdTrqCtrlO          | 22      | 16       | 6              | Output |                  |              |
| ExtSpdTrqCtrlO       | 23      | 17       | 6              | Output |                  |              |

### 9.5.8 Basic speed control

#### Output assembly object 0x14 (20<sub>10</sub>)

The PLC or scanner must be configured for 4 output bytes (or 2 output words) if this assembly object is to be used.

Table 9-18 Basic speed control

| Data word | Function                             |
|-----------|--------------------------------------|
| Word 0    | Basic control word.                  |
| Word 1    | Speed reference ( <i>SpeedRef</i> ). |

#### Basic control word

The basic control word consists of 2 bytes (16 bits), with only 2 bits of the low byte being used as shown below.

| b15 | b14 | b13 | b12 | b11 | b10      | b9 | b8     |
|-----|-----|-----|-----|-----|----------|----|--------|
|     |     |     |     |     |          |    |        |
| b7  | b6  | b5  | b4  | b3  | b2       | b1 | b0     |
|     |     |     |     |     | FaultRst |    | RunFwd |

The individual bit functions are described as follows:

| Name     | Control Word | Description                                                                |
|----------|--------------|----------------------------------------------------------------------------|
| RunFwd   | b0           | Set this bit to command the drive to run in the forward direction.         |
| FaultRst | b2           | A 0 to 1 transition will reset the drive if the drive was in a trip state. |

**NOTE** For the drive to run at the speed specified in Word 1, Pr 0.06.043 must be ON and bit 0, bit 7 and bit 8 of the drive control word (Pr 0.06.042) must all be set to 1 and the external hardware enable signal must be present.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

The individual bit functions for the drive control word are shown in Table 9-19 below.

**Table 9-19 Drive control word bit functions**

| Bit | Function                | Equivalent parameter |
|-----|-------------------------|----------------------|
| 0   | Drive enable            | Pr <b>0.06.015</b>   |
| 1   | Run forward             | Pr <b>0.06.030</b>   |
| 2   | Jog forward             | Pr <b>0.06.031</b>   |
| 3   | Run reverse             | Pr <b>0.06.032</b>   |
| 4   | Forward/reverse         | Pr <b>0.06.033</b>   |
| 5   | Run                     | Pr <b>0.06.034</b>   |
| 6   | Not stop                | Pr <b>0.06.039</b>   |
| 7   | Auto/manual             | N/A                  |
| 8   | Analog/preset reference | Pr <b>0.01.042</b>   |
| 9   | Jog reverse             | Pr <b>0.06.037</b>   |
| 10  | Reserved                | N/A                  |
| 11  | Reserved                | N/A                  |
| 12  | Trip drive              | N/A                  |
| 13  | Reset drive             | Pr <b>0.10.033</b>   |
| 14  | Keypad watchdog         | N/A                  |

### Speed reference (*SpeedRef*)

The speed reference word utilises 2 bytes (16 bits) as shown below.

| b15                  | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
|----------------------|-----|-----|-----|-----|-----|----|----|
| SpeedRef (high byte) |     |     |     |     |     |    |    |
| b7                   | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| SpeedRef (low byte)  |     |     |     |     |     |    |    |

For more information on the setting of the speed reference see Table 9-40 *AC/DC Drive object attributes* on page 133.

## 9.5.9 Extended speed control

### Output assembly object 0x15 (21<sub>10</sub>)

The PLC or scanner must be configured for 4 output bytes (or 2 output words) if this assembly object is to be used.

**Table 9-20 Extended speed control**

| Data word | Function                             |
|-----------|--------------------------------------|
| Word 0    | Extended control word.               |
| Word 1    | Speed reference ( <i>SpeedRef</i> ). |

### Extended control word

The extended control word consists of 2 bytes (16 bits), with only the low byte used as shown.

| b15 | b14    | b13     | b12 | b11 | b10      | b9     | b8     |
|-----|--------|---------|-----|-----|----------|--------|--------|
|     |        |         |     |     |          |        |        |
| b7  | b6     | b5      | b4  | b3  | b2       | b1     | b0     |
|     | NetRef | NetCtrl |     |     | FaultRst | RunRev | RunFwd |

The individual bit functions are described as follows:

| Name     | Control Word | Description                                                                                                              |
|----------|--------------|--------------------------------------------------------------------------------------------------------------------------|
| RunFwd   | b0           | Set this bit to command the drive to run in the forward direction.                                                       |
| RunRev   | b1           | Set this bit to command the drive to run in the reverse direction.                                                       |
| FaultRst | b2           | A 0 to 1 transition will reset the drive if the drive was in a trip state.                                               |
| NetCtrl  | b5           | Used in conjunction with Pr <b>0.06.043</b> to enable the drive control word bits b0-b6 and bit 9 (Pr <b>0.06.042</b> ). |
| NetRef   | b6           | Set this bit to command the drive to use the remote speed reference value specified in Word 1.                           |

**NOTE** For the drive to run at the speed specified in Word 1, Pr **0.06.043** must be *ON* and bit 0, bit 7 and bit 8 of the drive control word (Pr **0.06.042**) must all be set to 1 and the external hardware enable signal must be present.

**NOTE** For information on the drive control word see Table 9-19 *Drive control word bit functions* on page 126.

**NOTE** Conformance with the pre-defined assembly objects specification can only be guaranteed if the speed reference configuration of the drive has not been changed from the default settings. For information on setting default values, refer to the appropriate drive user guide.

### Speed reference (*SpeedRef*)

The speed reference word utilises 2 bytes (16 bits) as shown below.

| b15                  | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
|----------------------|-----|-----|-----|-----|-----|----|----|
| SpeedRef (high byte) |     |     |     |     |     |    |    |
| b7                   | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| SpeedRef (low byte)  |     |     |     |     |     |    |    |

For more information on the setting of the speed reference see Table 9-40 *AC/DC Drive object attributes* on page 133.

## 9.5.10 Basic speed and torque control

### Output assembly object 0x16 (22<sub>10</sub>)

The PLC or scanner must be configured for 6 output bytes (or 3 output words) if this assembly object is to be used.

**Table 9-21 Basic speed and torque control**

| Data Word | Function                               |
|-----------|----------------------------------------|
| Word 0    | Basic control word.                    |
| Word 1    | Speed reference ( <i>SpeedRef</i> ).   |
| Word 2    | Torque reference ( <i>TorqueRef</i> ). |

### Basic control word

The basic control word consists of 2 bytes (16 bits), with only 2 bits of the low byte being used as shown below.

| b15 | b14 | b13 | b12 | b11 | b10      | b9 | b8     |
|-----|-----|-----|-----|-----|----------|----|--------|
|     |     |     |     |     |          |    |        |
| b7  | b6  | b5  | b4  | b3  | b2       | b1 | b0     |
|     |     |     |     |     | FaultRst |    | RunFwd |

The individual bit functions are described as follows:

| Name     | Control Word | Description                                                                |
|----------|--------------|----------------------------------------------------------------------------|
| RunFwd   | b0           | Set this bit to command the drive to run in the forward direction.         |
| FaultRst | b2           | A 0 to 1 transition will reset the drive if the drive was in a trip state. |

**NOTE** For the drive to run at the speed specified in Word 1, Pr **0.06.043** must be *ON* and bit 0, bit 7 and bit 8 of the drive control word (Pr **0.06.043**) must all be set to 1.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**NOTE** For information on the drive control word see Table 9-19  
Drive control word bit functions on page 126.

### Speed reference (*SpeedRef*)

The speed reference word utilises 2 bytes (16 bits) as shown below.

|                      |     |     |     |     |     |    |    |
|----------------------|-----|-----|-----|-----|-----|----|----|
| b15                  | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
| SpeedRef (high byte) |     |     |     |     |     |    |    |
| b7                   | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| SpeedRef (low byte)  |     |     |     |     |     |    |    |

For more information on the setting of the speed reference see Table 9-40 AC/DC Drive object attributes on page 133.

### Torque reference (*TorqueRef*)

The torque reference word utilises 2 bytes (16 bits) as shown below.

|                       |     |     |     |     |     |    |    |
|-----------------------|-----|-----|-----|-----|-----|----|----|
| b15                   | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
| TorqueRef (high byte) |     |     |     |     |     |    |    |
| b7                    | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| TorqueRef (low byte)  |     |     |     |     |     |    |    |

For more information on the setting of the torque reference see Table 9-40 AC/DC Drive object attributes on page 133.

## 9.5.11 Extended speed and torque control

### Output assembly object 0x17 (23<sub>10</sub>)

The PLC or scanner must be configured for 6 output bytes (or 3 output words) if this assembly object is to be used.

**Table 9-22 Extended speed and torque control**

| Data word | Function                               |
|-----------|----------------------------------------|
| Word 0    | Extended control word.                 |
| Word 1    | Speed reference ( <i>SpeedRef</i> ).   |
| Word 2    | Torque reference ( <i>TorqueRef</i> ). |

### Extended control word

The extended control word consists of 2 bytes (16 bits), with only 5 bits of the low byte used as shown below.

|     |        |         |     |     |          |        |        |
|-----|--------|---------|-----|-----|----------|--------|--------|
| b15 | b14    | b13     | b12 | b11 | b10      | b9     | b8     |
|     |        |         |     |     |          |        |        |
| b7  | b6     | b5      | b4  | b3  | b2       | b1     | b0     |
|     | NetRef | NetCtrl |     |     | FaultRst | RunRev | RunFwd |

The individual bit functions are described as follows:

| Name     | Control Word | Description                                                                                           |
|----------|--------------|-------------------------------------------------------------------------------------------------------|
| RunFwd   | b0           | Set this bit to command the drive to run in the forward direction.                                    |
| RunRev   | b1           | Set this bit to command the drive to run in the reverse direction.                                    |
| FaultRst | b2           | A 0 to 1 transition will reset the drive if the drive was in a trip state.                            |
| NetCtrl  | b5           | Used in conjunction with Pr 06.043 to enable the drive control word bits b0-b6 and bit 9 (Pr 06.042). |
| NetRef   | b6           | Set this bit to command the drive to use the remote speed reference value specified in Word 1.        |

**NOTE** For the drive to run at the speed specified in Word 1, Pr 06.043 must be ON and bit 0, bit 7 and bit 8 of the drive control word (Pr 06.042) must all be set to 1 and the external hardware enable signal must be present.

**NOTE** For information on the drive control word see Table 9-19 Drive control word bit functions on page 126.

### Speed reference (*SpeedRef*)

The speed reference word utilises 2 bytes (16 bits) as shown below.

|                      |     |     |     |     |     |    |    |
|----------------------|-----|-----|-----|-----|-----|----|----|
| b15                  | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
| SpeedRef (high byte) |     |     |     |     |     |    |    |
| b7                   | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| SpeedRef (low byte)  |     |     |     |     |     |    |    |

For more information on the setting of the speed reference see Table 9-40 AC/DC Drive object attributes on page 133.

### Torque reference (*TorqueRef*)

The torque reference word utilises 2 bytes (16 bits) as shown below.

|                       |     |     |     |     |     |    |    |
|-----------------------|-----|-----|-----|-----|-----|----|----|
| b15                   | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
| TorqueRef (high byte) |     |     |     |     |     |    |    |
| b7                    | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| TorqueRef (low byte)  |     |     |     |     |     |    |    |

For more information on the setting of the torque reference see Table 9-40 AC/DC Drive object attributes on page 133.

## 9.5.12 Basic speed feedback

### Input assembly object 0x46 (70<sub>10</sub>)

The PLC or scanner must be configured for 4 input bytes (or 2 input words) if this assembly object is to be used.

**Table 9-23 Basic speed feedback**

| Data word | Function                               |
|-----------|----------------------------------------|
| Word 0    | Basic status word.                     |
| Word 1    | Speed feedback ( <i>SpeedActual</i> ). |

### Basic status word

The basic status word consists of 2 bytes (16 bits), with only 2 bits of the low byte used as shown below.

|     |     |     |     |     |                 |    |         |
|-----|-----|-----|-----|-----|-----------------|----|---------|
| b15 | b14 | b13 | b12 | b11 | b10             | b9 | b8      |
|     |     |     |     |     |                 |    |         |
| b7  | b6  | b5  | b4  | b3  | b2              | b1 | b0      |
|     |     |     |     |     | Running 1 (Fwd) |    | Faulted |

The individual bit functions are described as follows:

| Bit | Name           | Description                                                                   |
|-----|----------------|-------------------------------------------------------------------------------|
| b0  | Faulted        | Indicates whether the drive is OK or tripped (0=OK, 1=Tripped).               |
| b2  | Running1 (Fwd) | Indicates if the drive is running in the forward direction (0=False, 1=True). |

### Speed feedback (*SpeedActual*)

The speed feedback word utilises 2 bytes (16 bits) as shown below.

|                         |     |     |     |     |     |    |    |
|-------------------------|-----|-----|-----|-----|-----|----|----|
| b15                     | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
| SpeedActual (high byte) |     |     |     |     |     |    |    |
| b7                      | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| SpeedActual (low byte)  |     |     |     |     |     |    |    |

For more information on the speed feedback see Table 9-40 AC/DC Drive object attributes on page 133.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 9.5.13 Extended speed feedback

#### Input assembly object 0x47 (71<sub>10</sub>)

The PLC or scanner must be configured for 4 input bytes (or 2 input words) if this assembly object is to be used.

**Table 9-24 Extended speed feedback**

| Data word | Function                               |
|-----------|----------------------------------------|
| Word 0    | Extended status word.                  |
| Word 1    | Speed feedback ( <i>SpeedActual</i> ). |

#### Extended status word

The extended status word consists of 2 bytes (16 bits), with the bits having functions as shown below.

| b15          | b14         | b13          | b12   | b11            | b10            | b9      | b8      |
|--------------|-------------|--------------|-------|----------------|----------------|---------|---------|
| DriveState   |             |              |       |                |                |         |         |
| b7           | b6          | b5           | b4    | b3             | b2             | b1      | b0      |
| At Reference | RefFrom Net | CtrlFrom Net | Ready | Running2 (Rev) | Running1 (Fwd) | Warning | Faulted |

The DriveState byte returns a code to indicate the operating state of the drive as shown in Table 9-25 following.

**Table 9-25 DriveState codes**

| Code | b15 - b8 | State           | Description                                                          |
|------|----------|-----------------|----------------------------------------------------------------------|
| 1    | 00000001 | Startup         | This state is skipped over on CT drives.                             |
| 2    | 00000010 | Not_Ready       | Inhibit.                                                             |
| 3    | 00000011 | Ready           | Ready.                                                               |
| 4    | 00000100 | Enabled         | Run or Stop.                                                         |
| 5    | 00000101 | Stopping        | Deceleration or Injection.                                           |
| 6    | 00000110 | Fault_Stop      | AC_UU (this will only occur if Mains Loss is enabled).               |
| 7    | 00000111 | Faulted         | Tripped.                                                             |
| 0    | 00000000 | Vendor Specific | All other DriveType states, e.g. Scan, Orienting, Regen Active, etc. |

The individual bits of the low byte of the extended status word are described below.

#### Extended status word (low byte)

| Name           | Bit | Description                                                                                                                                               |
|----------------|-----|-----------------------------------------------------------------------------------------------------------------------------------------------------------|
| Faulted        | b0  | Indicates whether the drive is OK or tripped.<br>0=OK (Pr 0.10.001=1).<br>1=Tripped (Pr 0.10.001=0).                                                      |
| Warning        | b1  | Indicates if one of the drive alarms is active.                                                                                                           |
| Running1 (Fwd) | b2  | Indicates if the drive is running in the forward direction.<br>0=False, 1=True.                                                                           |
| Running2 (Rev) | b3  | Indicates if the drive is running in the reverse direction.<br>0=False, 1=True.                                                                           |
| Ready          | b4  | The 'Ready' bit is set depending on which state the drive is in.<br>Ready = True.<br>Enabled = True.<br>Stopping = True.<br>All others = False.           |
| CtrlFromNet    | b5  | Indicates if the drive is being controlled from the 'Drive Control Word'.<br>0=False, 1=True.                                                             |
| RefFromNet     | b6  | Indicates if the speed reference is derived from Pr 0.01.021.<br>0=False (Pr 0.01.050<>1 OR Pr 0.01.049<>3).<br>1=True (Pr 0.01.050=1 AND Pr 0.01.049=3). |
| AtReference    | b7  | Indicates if the drive speed has reached the set reference.<br>0=False (Pr 0.10.006=0).<br>1=True (Pr 0.10.006=1).                                        |

### Speed feedback (*SpeedActual*)

The speed feedback word utilises 2 bytes (16 bits) as shown below.

| b15                     | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
|-------------------------|-----|-----|-----|-----|-----|----|----|
| SpeedActual (high byte) |     |     |     |     |     |    |    |
| b7                      | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| SpeedActual (low byte)  |     |     |     |     |     |    |    |

For more information on the speed feedback see Table 9-40 AC/DC Drive object attributes on page 133.

### 9.5.14 Basic speed and torque feedback

#### Input assembly object 0x48 (72<sub>10</sub>)

The PLC or scanner must be configured for 6 input bytes (or 3 input words) if this assembly object is to be used.

**Table 9-26 Basic speed and torque feedback**

| Data word | Function                                 |
|-----------|------------------------------------------|
| Word 0    | Basic status word.                       |
| Word 1    | Speed feedback ( <i>SpeedActual</i> ).   |
| Word 2    | Torque feedback ( <i>TorqueActual</i> ). |

#### Basic status word

The basic status word consists of 2 bytes (16 bits), with only the low byte used as shown below.

| b15 | b14 | b13 | b12 | b11 | b10            | b9 | b8      |
|-----|-----|-----|-----|-----|----------------|----|---------|
|     |     |     |     |     |                |    |         |
| b7  | b6  | b5  | b4  | b3  | b2             | b1 | b0      |
|     |     |     |     |     | Running1 (Fwd) |    | Faulted |

The individual bit functions are described as follows:

| Bit | Name           | Description                                                                      |
|-----|----------------|----------------------------------------------------------------------------------|
| b0  | Faulted        | Indicates whether the drive is OK or tripped<br>(0=OK, 1=Tripped).               |
| b2  | Running1 (Fwd) | Indicates if the drive is running in the forward direction<br>(0=False, 1=True). |

### Speed feedback (*SpeedActual*)

The speed feedback word utilises 2 bytes (16 bits) as shown below.

| b15                     | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
|-------------------------|-----|-----|-----|-----|-----|----|----|
| SpeedActual (high byte) |     |     |     |     |     |    |    |
| b7                      | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| SpeedActual (low byte)  |     |     |     |     |     |    |    |

For more information on the speed feedback see Table 9-40 AC/DC Drive object attributes on page 133.

### Torque feedback (*TorqueActual*)

The torque feedback word utilises 2 bytes (16 bits) as shown below.

| b15                      | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
|--------------------------|-----|-----|-----|-----|-----|----|----|
| TorqueActual (high byte) |     |     |     |     |     |    |    |
| b7                       | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| TorqueActual (low byte)  |     |     |     |     |     |    |    |

For more information on the torque feedback see Table 9-40 AC/DC Drive object attributes on page 133.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 9.5.15 Extended speed and torque feedback

### Input assembly object 0x49 (73<sub>10</sub>)

The PLC or scanner must be configured for 6 input bytes (or 3 input words) if this assembly object is to be used.

**Table 9-27 Basic speed and torque feedback**

| Data word | Function                                 |
|-----------|------------------------------------------|
| Word 0    | Extended status word.                    |
| Word 1    | Speed feedback ( <i>SpeedActual</i> ).   |
| Word 2    | Torque feedback ( <i>TorqueActual</i> ). |

#### Extended status word

The extended status word consists of 2 bytes (16 bits), with the bits having functions as shown below.

| b15          | b14         | b13          | b12   | b11            | b10            | b9      | b8      |
|--------------|-------------|--------------|-------|----------------|----------------|---------|---------|
| DriveState   |             |              |       |                |                |         |         |
| b7           | b6          | b5           | b4    | b3             | b2             | b1      | b0      |
| At Reference | RefFrom Net | CtrlFrom Net | Ready | Running2 (Rev) | Running1 (Fwd) | Warning | Faulted |

The DriveState byte returns a code to indicate the operating state of the drive as shown in Table 9-28.

**Table 9-28 DriveState codes**

| Code | b15 - b8 | State           | Description                                                          |
|------|----------|-----------------|----------------------------------------------------------------------|
| 1    | 00000001 | Startup         | This state is skipped over on CT drives.                             |
| 2    | 00000010 | Not_Ready       | Inhibit.                                                             |
| 3    | 00000011 | Ready           | Ready.                                                               |
| 4    | 00000100 | Enabled         | Run or Stop.                                                         |
| 5    | 00000101 | Stopping        | Deceleration or Injection.                                           |
| 6    | 00000110 | Fault_Stop      | AC_UU (this will only occur if Mains Loss is enabled).               |
| 7    | 00000111 | Faulted         | Tripped.                                                             |
| 0    | 00000000 | Vendor Specific | All other DriveType states, e.g. Scan, Orienting, Regen Active, etc. |

The individual bits of the low byte of the extended status word are described in Table 9-29 *Extended status word (low byte)* on page 129.

**Table 9-29 Extended status word (low byte)**

| Name           | Bit | Description                                                                                                                                               |
|----------------|-----|-----------------------------------------------------------------------------------------------------------------------------------------------------------|
| Faulted        | b0  | Indicates whether the drive is OK or tripped.<br>0=OK (Pr 0.10.001=1).<br>1=Tripped (Pr 0.10.001=0).                                                      |
| Warning        | b1  | Indicates if one of the drive alarms is active.                                                                                                           |
| Running1 (Fwd) | b2  | Indicates if the drive is running in the forward direction.<br>0=False, 1=True.                                                                           |
| Running2 (Rev) | b3  | Indicates if the drive is running in the reverse direction.<br>0=False, 1=True.                                                                           |
| Ready          | b4  | The 'Ready' bit is set depending on which state the drive is in.<br>Ready = True.<br>Enabled = True.<br>Stopping = True.<br>All others = False.           |
| CtrlFromNet    | b5  | Indicates if the drive is being controlled from the 'Drive Control Word'.<br>0=False, 1=True.                                                             |
| RefFromNet     | b6  | Indicates if the speed reference is derived from Pr 0.01.021.<br>0=False (Pr 0.01.050<>1 OR Pr 0.01.049<>3).<br>1=True (Pr 0.01.050=1 AND Pr 0.01.049=3). |
| AtReference    | b7  | Indicates if the drive speed has reached the set reference.<br>0=False (Pr 0.10.006=0).<br>1=True (Pr 0.10.006=1).                                        |

### Speed feedback (*SpeedActual*)

The speed feedback word utilises 2 bytes (16 bits) as shown below.

| b15                    | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
|------------------------|-----|-----|-----|-----|-----|----|----|
| SpeedActual(high byte) |     |     |     |     |     |    |    |
| b7                     | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| SpeedActual (low byte) |     |     |     |     |     |    |    |

For more information on the speed feedback see Table 9-40 *AC/DC Drive object attributes* on page 133.

### Torque feedback (*TorqueActual*)

The torque feedback word utilises 2 bytes (16 bits) as shown below.

| b15                      | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
|--------------------------|-----|-----|-----|-----|-----|----|----|
| TorqueActual (high byte) |     |     |     |     |     |    |    |
| b7                       | b6  | b5  | b4  | b3  | b2  | b1 | b0 |
| TorqueActual (low byte)  |     |     |     |     |     |    |    |

For more information on the torque feedback see Table 9-40 *AC/DC Drive object attributes* on page 133.

## 9.5.16 Object Model

The Object Model has the following object classes present.

**Table 9-30 Supported Objects**

| Object Class       | Class Code |          | Number of Instances | Effect                                                        |
|--------------------|------------|----------|---------------------|---------------------------------------------------------------|
|                    | Decimal    | Hex (0x) |                     |                                                               |
| Identity           | 1          | 01       | 1                   | Provides device specific information.                         |
| Assembly           | 4          | 04       | 16                  | Defines the I/O data format (parameter mapping).              |
| Motor Data         | 40         | 28       | 2                   | Defines the motor data.                                       |
| Control Supervisor | 41         | 29       | 1                   | Provides drive control and monitoring information.            |
| AC/DC Drive        | 42         | 2A       | 1                   | Provides drive configuration and running state information.   |
| CT Group           | 100        | 64       | <No. of menus>      | Provides access to drive parameters.                          |
| CT This Slot       | 101        | 65       | <No. of menus>      | Provides access to the local option module parameters.        |
| CT Slot 1          | 102        | 66       | <No. of menus>      | Provides access to the option module parameters in slot 1.    |
| CT Slot 2          | 103        | 67       | <No. of menus>      | Provides access to the option module parameters in slot 2.    |
| CT Slot 3          | 104        | 68       | <No. of menus>      | Provides access to the option module parameters in slot 3.    |
| CT Slot 4          | 105        | 69       | <No. of menus>      | Provides access to the onboard Ethernet interface parameters. |

## 9.5.17 Identity object

**Class:** 0x01 (1<sub>10</sub>)

The identity object provides identification of and general information about the device.

**Table 9-31 Identity object**

| Attribute | Access | Name         | Data Type    |
|-----------|--------|--------------|--------------|
| 1         | Get    | VendorID     | UINT         |
| 2         | Get    | DeviceType   | UINT         |
| 3         | Get    | ProductCode  | UINT         |
| 4         | Get    | Revision     | USINT        |
| 6         | Get    | SerialNumber | UDINT        |
| 7         | Get    | ProductName  | SHORT_STRING |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## Vendor ID

|           |          |           |                            |
|-----------|----------|-----------|----------------------------|
| Name:     | VendorID |           |                            |
| Class     | 0x01     | Default   | 0x101 (257 <sub>10</sub> ) |
| Instance  | 0x01     | Data Type | UINT                       |
| Attribute | 0x01     | Access    | Get                        |

Returns the vendor ID code 0x101 (257<sub>10</sub>) for *Control Techniques*.

## Device type

|           |            |           |      |
|-----------|------------|-----------|------|
| Name:     | DeviceType |           |      |
| Class     | 0x01       | Default   | 0x02 |
| Instance  | 0x01       | Data Type | UINT |
| Attribute | 0x02       | Access    | Get  |

Returns the device type code. The following codes are used:

| Device Type code | Drive type |
|------------------|------------|
| 0x02             | AC Drive   |

## Product code

|           |              |           |           |
|-----------|--------------|-----------|-----------|
| Name:     | Product Code |           |           |
| Class     | 0x01         | Default   | See below |
| Instance  | 0x01         | Data Type | UINT      |
| Attribute | 0x03         | Access    | Get       |

Returns a 16 bit value to identify the drive type and drive mode and also links a node to the installed EDS files. The product code is calculated as shown in Table 9-32 *Product code bit allocation* below.

**Table 9-32 Product code bit allocation**

| b15        | b14 | b13 | b12 | b11              | b10 | b9 | b8 | b7         | b6 | b5 | b4 | b3       | b2 | b1 | b0 |
|------------|-----|-----|-----|------------------|-----|----|----|------------|----|----|----|----------|----|----|----|
| Drive Type |     |     |     | Drive Derivative |     |    |    | Drive Mode |    |    |    | CIP code |    |    |    |

### Drive Type (b15 to b11)

The drive type is defined as follows:

| Value | Drive Type |
|-------|------------|
| 2     | Unidrive M |

### Drive Derivative (b10 to b6)

The drive derivative as shown in Pr **0.11.028**.

For more information on the drive derivative codes please refer to the relevant drive documentation.

### Drive Mode (b5 to b3)

The drive operating mode is defined as follows:

| Value | Operating Mode |
|-------|----------------|
| 0     | Open-loop      |
| 1     | RFC-A          |
| 2     | RFC-S          |
| 3     | Regen          |

### CIP code (b2 to b0)

The CIP (Common Industrial Protocol) interface code is defined as follows:

| Value | Interface ID | Description                    |
|-------|--------------|--------------------------------|
| 0     | 430          | Unidrive M700 onboard Ethernet |
| 1     | 447          | SI-DeviceNet                   |
| 2     | 310          | MCi210                         |
| 3     | 433          | SI-Ethernet                    |

## Revision

|           |          |           |                |
|-----------|----------|-----------|----------------|
| Name:     | Revision |           |                |
| Class     | 0x01     | Default   | N/A            |
| Instance  | 0x01     | Data Type | ARRAY of USINT |
| Attribute | 0x04     | Access    | Get            |

Returns 2 bytes to indicate the major and minor revision numbers of the Ethernet interface firmware version.

The Ethernet interface firmware version (**MM.002**) consists of four 2-digit decimal numbers with the following significance:

[Major].[Minor].[Bugfix].[Build].

The revision code returns the major and minor revisions of the Ethernet interface firmware version in two unsigned bytes, the major revision being returned first followed by the minor revision.

**Table 9-33 Revision specification**

| b7                                        | b6                                              | b5 | b4 | b3 | b2 | b1 | b0 |
|-------------------------------------------|-------------------------------------------------|----|----|----|----|----|----|
| Major revision ( <b>MM.002</b> / 1000000) |                                                 |    |    |    |    |    |    |
| R                                         | Minor revision ( <b>MM.002</b> / 10000) Mod 100 |    |    |    |    |    |    |

Where "Mod 100" refers to the fractional value of the result from **MM.002**/10000, (the value after the decimal point).

e.g. For a value of 12345678 in Pr **MM.002** (12.34.56.78 on the keypad display), the major revision is 12 and the minor revision is 34.

The returned data will consist of 2 unsigned bytes, the first byte will be the major revision value 12 (0x0C) and the second byte will be the minor revision value 34 (0x22).

### Major revision

| b7                         | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
|----------------------------|----|----|----|----|----|----|----|
| 0                          | 0  | 0  | 0  | 1  | 1  | 0  | 0  |
| Major revision = 12 (0x0C) |    |    |    |    |    |    |    |

### Minor revision

| b6                         | b5 | b4 | b3 | b2 | b1 | b0 |
|----------------------------|----|----|----|----|----|----|
| 0                          | 1  | 0  | 0  | 0  | 1  | 0  |
| Minor revision = 34 (0x22) |    |    |    |    |    |    |

## Serial Number

|           |              |           |       |
|-----------|--------------|-----------|-------|
| Name:     | SerialNumber |           |       |
| Class     | 0x01         | Default   | N/A   |
| Instance  | 0x01         | Data Type | UDINT |
| Attribute | 0x06         | Access    | Get   |

Returns the lower 4 bytes (32 bits) of the Ethernet interface serial number.

The Ethernet interface serial number is contained within two adjacent parameters, Pr **MM.004 Serial Number LS** displays the least 8 significant decimal digits and Pr **MM.005 Serial Number MS** displays the most 8 significant decimal digits.

For example, if the serial number of the onboard Ethernet interface is 123456789 then Pr **MM.005 Serial Number MS** will display 1 and Pr **MM.004 Serial Number LS** will display 23456789.

The Ethernet interface serial number is set during manufacture and cannot be changed.

## Product Name

|           |             |           |                  |
|-----------|-------------|-----------|------------------|
| Name:     | ProductName |           |                  |
| Class     | 0x01        | Default   | Onboard Ethernet |
|           |             |           | SI-Ethernet      |
| Instance  | 0x01        | Data Type | SHORT_STRING     |
| Attribute | 0x07        | Access    | Get              |

Returns the product name as a short string of ASCII Bytes. The first byte specifies the number of following bytes that constitute the product name.

## 9.5.18 Motor data object

**Class:** 0x28 (40<sub>10</sub>)

There are 2 instances of the Motor data object. Instance 1 will represent menu 5 motor information (motor 1) and instance 2 will represent menu 21 motor information (motor 2). The instance being used by the other dependant objects will be determined by Pr **0.11.045**, to use the second motor map objects (instance 2), Pr **0.11.045** should be set to *Motor 2*. Pr **0.11.045** is polled in the background task, so the user should be

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

aware that during motor map changeover, the RPM speed reference may not be accurate. The available attributes and associated functions for the AC motor data object are shown in Table 9-34 *AC Motor data object attributes* below.

**Table 9-34 AC Motor data object attributes**

| AC Motor Instance Attributes |               |         | Drive Parameter                         |                                         |
|------------------------------|---------------|---------|-----------------------------------------|-----------------------------------------|
| Attribute ID                 | Name          | Access  | Instance 1                              | Instance 2                              |
| 0x03 (3 <sub>10</sub> )      | MotorType (*) | Get/Set | None                                    | None                                    |
| 0x06 (6 <sub>10</sub> )      | RatedCurrent  | Get/Set | Pr 0.05.007<br>(scaled to 100 mA units) | Pr 0.21.007<br>(scaled to 100 mA units) |
| 0x07 (7 <sub>10</sub> )      | RatedVoltage  | Get/Set | Pr 0.05.009                             | Pr 0.21.009                             |
| 0x09 (9 <sub>10</sub> )      | RatedFreq     | Get/Set | Pr 0.05.006<br>(scaled to Hz)           | Pr 0.21.006<br>(scaled to Hz)           |
| 0x0F (15 <sub>10</sub> )     | BaseSpeed     | Get/Set | Pr 0.05.008<br>(scaled to rpm units)    | Pr 0.21.008<br>(scaled to rpm units)    |
| 0x64 (100 <sub>10</sub> )    | Motor2Select  | Get     | Pr 0.21.015                             | Pr 0.21.015                             |
|                              |               | Set     | Pr 0.11.045                             | Pr 0.11.045                             |

(\* The MotorType attribute has no effect on drive operation, it is only used to provide information to the user as shown in Table 9-35 *Supported motor types* below).

**Table 9-35 Supported motor types**

| Value | Motor Type                              |
|-------|-----------------------------------------|
| 6     | Wound rotor induction motor             |
| 7     | Squirrel cage induction motor (default) |
| 9     | Sinusoidal PM BL motor                  |
| 10    | Trapezoidal PM BL motor                 |

**NOTE** In Open loop mode, only values 6 and 7 will be supported.

### Motor type

|                  |            |                  |         |
|------------------|------------|------------------|---------|
| <b>Name:</b>     | MotorType1 |                  |         |
| <b>Class</b>     | 0x28       | <b>Default</b>   | 7       |
| <b>Instance</b>  | 0x01       | <b>Data Type</b> | USINT   |
| <b>Attribute</b> | 0x03       | <b>Access</b>    | Get/Set |

Returns or sets the motor type to be used by the drive for instance 1.

|                  |            |                  |         |
|------------------|------------|------------------|---------|
| <b>Name:</b>     | MotorType2 |                  |         |
| <b>Class</b>     | 0x28       | <b>Default</b>   | 7       |
| <b>Instance</b>  | 0x02       | <b>Data Type</b> | USINT   |
| <b>Attribute</b> | 0x03       | <b>Access</b>    | Get/Set |

Returns or sets the motor type to be used by the drive for instance 2.

### Rated current

|                  |               |                  |                  |
|------------------|---------------|------------------|------------------|
| <b>Name:</b>     | RatedCurrent1 |                  |                  |
| <b>Class</b>     | 0x28          | <b>Default</b>   | Pr 0.05.007 / 10 |
| <b>Instance</b>  | 0x01          | <b>Data Type</b> | USINT            |
| <b>Attribute</b> | 0x06          | <b>Access</b>    | Get/Set          |

Returns or sets the rated motor current in Amps for instance 1. This attribute is linked to Pr 0.05.007.

Set Pr 0.05.007 = RatedCurrent1 \* 10.  
Get RatedCurrent1 = Pr 0.05.007 / 10.

|                  |               |                  |                  |
|------------------|---------------|------------------|------------------|
| <b>Name:</b>     | RatedCurrent2 |                  |                  |
| <b>Class</b>     | 0x28          | <b>Default</b>   | Pr 0.21.007 / 10 |
| <b>Instance</b>  | 0x02          | <b>Data Type</b> | USINT            |
| <b>Attribute</b> | 0x06          | <b>Access</b>    | Get/Set          |

Returns or sets the rated motor current in Amps for instance 2. This attribute is linked to Pr 0.21.007.

Set Pr 0.21.007 = RatedCurrent2 \* 10.

Get RatedCurrent2 = Pr 0.21.007 / 10.

### Rated voltage

|                  |               |                  |             |
|------------------|---------------|------------------|-------------|
| <b>Name:</b>     | RatedVoltage1 |                  |             |
| <b>Class</b>     | 0x28          | <b>Default</b>   | Pr 0.05.009 |
| <b>Instance</b>  | 0x01          | <b>Data Type</b> | USINT       |
| <b>Attribute</b> | 0x07          | <b>Access</b>    | Get/Set     |

Returns or sets the rated motor voltage in Volts for instance 1. This attribute is linked to Pr 0.05.009.

|                  |               |                  |             |
|------------------|---------------|------------------|-------------|
| <b>Name:</b>     | RatedVoltage2 |                  |             |
| <b>Class</b>     | 0x28          | <b>Default</b>   | Pr 0.21.009 |
| <b>Instance</b>  | 0x02          | <b>Data Type</b> | USINT       |
| <b>Attribute</b> | 0x07          | <b>Access</b>    | Get/Set     |

Returns or sets the rated motor voltage in Volts for instance 2. This attribute is linked to Pr 0.21.009.

### Rated frequency

|                  |            |                  |                  |
|------------------|------------|------------------|------------------|
| <b>Name:</b>     | RatedFreq1 |                  |                  |
| <b>Class</b>     | 0x28       | <b>Default</b>   | Pr 0.05.006 / 10 |
| <b>Instance</b>  | 0x01       | <b>Data Type</b> | USINT            |
| <b>Attribute</b> | 0x09       | <b>Access</b>    | Get/Set          |

Returns or sets the rated motor frequency in Hertz for instance 1. This attribute is linked to Pr 0.05.006.

Set Pr 0.05.006 = RatedFreq1 \* 10.  
Get RatedFreq1 = Pr 0.05.006 / 10.

|                  |            |                  |                  |
|------------------|------------|------------------|------------------|
| <b>Name:</b>     | RatedFreq2 |                  |                  |
| <b>Class</b>     | 0x28       | <b>Default</b>   | Pr 0.21.006 / 10 |
| <b>Instance</b>  | 0x02       | <b>Data Type</b> | USINT            |
| <b>Attribute</b> | 0x09       | <b>Access</b>    | Get/Set          |

Returns or sets the rated motor frequency in Hertz for instance 2. This attribute is linked to Pr 21.006.

Set Pr 0.21.006 = RatedFreq2 \* 10.  
Get RatedFreq2 = Pr 0.21.006 / 10.

### Base speed

|                  |            |                  |             |
|------------------|------------|------------------|-------------|
| <b>Name:</b>     | BaseSpeed1 |                  |             |
| <b>Class</b>     | 0x28       | <b>Default</b>   | Pr 0.05.008 |
| <b>Instance</b>  | 0x01       | <b>Data Type</b> | USINT       |
| <b>Attribute</b> | 0x0F       | <b>Access</b>    | Get/Set     |

Returns or sets the base speed of the motor in RPM for instance 1. This attribute is linked to Pr 0.05.008.

|                  |            |                  |             |
|------------------|------------|------------------|-------------|
| <b>Name:</b>     | BaseSpeed2 |                  |             |
| <b>Class</b>     | 0x28       | <b>Default</b>   | Pr 0.21.008 |
| <b>Instance</b>  | 0x02       | <b>Data Type</b> | USINT       |
| <b>Attribute</b> | 0x0F       | <b>Access</b>    | Get/Set     |

Returns or sets the base speed of the motor in RPM for instance 2. This attribute is linked to Pr 0.21.008.

### Motor2Select

|                  |              |                  |         |
|------------------|--------------|------------------|---------|
| <b>Name:</b>     | Motor2Select |                  |         |
| <b>Class</b>     | 0x28         | <b>Default</b>   |         |
| <b>Instance</b>  | 0x01         | <b>Data Type</b> | USINT   |
| <b>Attribute</b> | 0x64         | <b>Access</b>    | Get/Set |

Selects between Motor 1 and Motor 2. This attribute is linked to Pr 0.11.045. When this bit is set to 1, Motor 2 will be active.

**NOTE** Any change in this attribute will be implemented when the drive is disabled.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

### 9.5.19 Control Supervisor object

**Class:** 0x29 (41<sub>10</sub>)

The Control Supervisor object provides access to various attributes which control or monitor the drive running state. The available attributes and their associated functions are shown in Table 9-36 following.

**Table 9-36 Control Supervisor object attribute**

| Attribute ID |          | Access  | Name        | Parameter dependence                                                  |
|--------------|----------|---------|-------------|-----------------------------------------------------------------------|
| Decimal      | Hex (0x) |         |             |                                                                       |
| 3            | 03       | Get/Set | RunFwd      | 0.06.042 bit1                                                         |
| 4            | 04       | Get/Set | RunRev      | 0.06.042 bit3                                                         |
| 5            | 05       | Get/Set | NetCtrl     | 0.06.042 bit7                                                         |
| 6            | 06       | Get     | State       | See Table 9-37 Control Supervisor state attributes on page 132        |
| 7            | 07       | Get     | RunningFwd  | 1 (0.10.040 AND 0x2002) = 0x0002<br>0 (0.10.040 AND 0x2002) <> 0x0002 |
| 8            | 08       | Get     | RunningRev  | 1 (0.10.040 AND 0x2002) = 0x2002<br>0 (0.10.040 AND 0x2002) <> 0x2002 |
| 9            | 09       | Get     | Ready       | See Table 9-37 Control Supervisor state attributes on page 132        |
| 10           | 0A       | Get     | Faulted     | Inverse of 0.10.001                                                   |
| 11           | 0B       | Get     | Warning     | 0.10.019                                                              |
| 12           | 0C       | Get/Set | FaultRst    | Sets 0.10.038 to 100 on a 0 to 1 transition                           |
| 13           | 0D       | Get     | FaultCode   | See Table 9-37 Control Supervisor state attributes on page 132        |
| 15           | 0F       | Get     | CtrlFromNet | 0.06.042 bit7 AND 0.06.043                                            |
| 102          | 66       | Get/Set | DriveEnable | 0.06.042 bit0                                                         |

#### RunFwd

| Name:     | RunFwd |           |         |
|-----------|--------|-----------|---------|
| Class     | 0x29   | Default   | N/A     |
| Instance  | 0x01   | Data Type | USINT   |
| Attribute | 0x03   | Access    | Get/Set |

Set to 1 to run the drive in the forward direction.

Get/Set Pr 0.06.042 (bit 1).

#### RunRev

| Name:     | RunRev |           |         |
|-----------|--------|-----------|---------|
| Class     | 0x29   | Default   | N/A     |
| Instance  | 0x01   | Data Type | USINT   |
| Attribute | 0x04   | Access    | Get/Set |

Set to 1 to run the drive in the reverse direction.

Get/Set Pr 0.06.042 (bit 3).

#### NetCtrl

| Name:     | NetCtrl |           |         |
|-----------|---------|-----------|---------|
| Class     | 0x29    | Default   | N/A     |
| Instance  | 0x01    | Data Type | USINT   |
| Attribute | 0x05    | Access    | Get/Set |

Switches between terminal and fieldbus control.

Get/Set Pr 0.06.042 (bit 7)

0 = Terminal control.

1 = Fieldbus control.

### State

| Name:     | State |           |       |
|-----------|-------|-----------|-------|
| Class     | 0x29  | Default   | N/A   |
| Instance  | 0x01  | Data Type | USINT |
| Attribute | 0x06  | Access    | Get   |

This returns a code to indicate the current running state of the drive as shown in Table 9-37 following.

**Table 9-37 Control Supervisor state attributes**

| Code | State           | Parameter Dependence              | Description                          |
|------|-----------------|-----------------------------------|--------------------------------------|
| 1    | Startup         | N/A                               | This state is skipped over           |
| 2    | Not_Ready       | 0.10.101 = 0                      | Inhibit                              |
| 3    | Ready           | 0.10.101 = 1                      | Ready                                |
| 4    | Enabled         | 0.10.101 = 2 OR 0.10.101 = 4      | Stop or Run                          |
| 5    | Stopping        | 0.10.101 = 6 OR 0.10.101 = 7      | Decelerating or DC injection braking |
| 6    | Fault_Stop      | 0.10.101 = 5                      | AC supply loss                       |
| 7    | Faulted         | 0.10.101 = 9                      | Tripped                              |
| 0    | Vendor Specific | 0.10.101 = All other drive states | See parameter reference guide        |

#### RunningFwd

| Name:     | RunningFwd |           |       |
|-----------|------------|-----------|-------|
| Class     | 0x29       | Default   | N/A   |
| Instance  | 0x01       | Data Type | USINT |
| Attribute | 0x07       | Access    | Get   |

Indicates that the drive is running in the forward direction.

This attribute will be set to 1 when Pr 0.10.014 = 0 and Pr 0.10.002 = 1.

#### RunningRev

| Name:     | RunningRev |           |       |
|-----------|------------|-----------|-------|
| Class     | 0x29       | Default   | N/A   |
| Instance  | 0x01       | Data Type | USINT |
| Attribute | 0x08       | Access    | Get   |

Indicates that the drive is running in the reverse direction.

This attribute will be set to 1 when Pr 0.10.014 = 0 and Pr 0.10.002 = 1.

#### Ready

| Name:     | Ready |           |       |
|-----------|-------|-----------|-------|
| Class     | 0x29  | Default   | N/A   |
| Instance  | 0x01  | Data Type | USINT |
| Attribute | 0x09  | Access    | Get   |

The Ready attribute will be set in accordance with the state as shown in Table 9-38.

**Table 9-38 Control Supervisor Ready attributes**

| Code       | State    | Ready state |
|------------|----------|-------------|
| 3          | Ready    | True        |
| 4          | Enabled  | True        |
| 5          | Stopping | True        |
| All others |          | False       |

#### Faulted

| Name:     | Faulted |           |       |
|-----------|---------|-----------|-------|
| Class     | 0x29    | Default   | N/A   |
| Instance  | 0x01    | Data Type | USINT |
| Attribute | 0x0A    | Access    | Get   |

Indicates that the drive is tripped, i.e. not OK (inverse of Pr 0.10.001).

Get 1 = Pr 0.10.001 = 0.

Get 0 = Pr 0.10.001 = 1.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## Warning

|           |         |           |       |
|-----------|---------|-----------|-------|
| Name:     | Warning |           |       |
| Class     | 0x29    | Default   | N/A   |
| Instance  | 0x01    | Data Type | USINT |
| Attribute | 0x0B    | Access    | Get   |

Indicates that one of the drive alarms is active.

Get Pr **0.10.019**.

## FaultRst

|           |          |           |         |
|-----------|----------|-----------|---------|
| Name:     | FaultRst |           |         |
| Class     | 0x29     | Default   | N/A     |
| Instance  | 0x01     | Data Type | USINT   |
| Attribute | 0x0C     | Access    | Get/Set |

Resets the drive from a tripped condition.

Sets Pr **0.10.038** to 100 on a 0 to 1 transition.

## FaultCode

|           |           |           |       |
|-----------|-----------|-----------|-------|
| Name:     | FaultCode |           |       |
| Class     | 0x29      | Default   | N/A   |
| Instance  | 0x01      | Data Type | USINT |
| Attribute | 0x0D      | Access    | Get   |

The fault code attribute will return the ODVA fault code as follows:

If the drive is not OK, the drive fault code is obtained from Pr **0.10.020**, if the drive fault code is listed in Table 9-39, then the ODVA fault code as shown in Table 9-39 below will be returned.

If the drive fault code is not listed in Table 9-39 then the Ethernet interface will return the ODVA code as follows:

ODVA Fault Code = 0x1000 + drive fault code.

**Table 9-39 Control Supervisor fault code attributes**

| Drive Fault Code | ODVA Fault Code | Drive Fault Code | ODVA Fault Code |
|------------------|-----------------|------------------|-----------------|
| 1                | 0x3220          | 20               | 0x2310          |
| 2                | 0x3210          | 21               | 0x4300          |
| 3                | 0x2300          | 26               | 0x5112          |
| 4                | 0x7112          | 32               | 0x3130          |
| 6                | 0x9000          |                  |                 |

## CtrlFromNet

|           |             |           |       |
|-----------|-------------|-----------|-------|
| Name:     | CtrlFromNet |           |       |
| Class     | 0x29        | Default   | N/A   |
| Instance  | 0x01        | Data Type | USINT |
| Attribute | 0x0F        | Access    | Get   |

Indicates whether the drive is operating under fieldbus or terminal control.

This attribute will be set to 1 if Pr **0.06.042** (bit 7) = 1 and Pr **0.06.043** = 1 (fieldbus).

## DriveEnable

|           |             |           |         |
|-----------|-------------|-----------|---------|
| Name:     | DriveEnable |           |         |
| Class     | 0x29        | Default   | N/A     |
| Instance  | 0x01        | Data Type | USINT   |
| Attribute | 0x66        | Access    | Get/Set |

Enables the drive. This puts the drive into the "Ready" state, allowing the **RunFwd** and **RunRev** attributes to control the drive. **RunFwd** and **RunRev** will have no effect if **DriveEnable** is not set to 1.

Get/Set Pr **0.06.042** bit 0.

**NOTE** The external hardware enable signal must also be present before the drive will enter the Ready state.

## 9.5.20 AC/DC Drive object

Class: **0x2A (42<sub>10</sub>)**

The AC/DC Drive object provides information on the drive running state and supports the following attributes:

**Table 9-40 AC/DC Drive object attributes**

| Attribute ID             | Name         | Access  | Parameter dependence                                                           |
|--------------------------|--------------|---------|--------------------------------------------------------------------------------|
| 0x03 (3 <sub>10</sub> )  | AtReference  | Get     | Pr <b>0.10.006</b>                                                             |
| 0x04 (4 <sub>10</sub> )  | NetRef       | Get/Set | Pr <b>0.06.042</b> (bit 8)                                                     |
| 0x06 (6 <sub>10</sub> )  | DriveMode    | Get/Set | (See Table 9-41 on page 134)                                                   |
| 0x07 (7 <sub>10</sub> )  | SpeedActual  | Get     | RFC-A or RFC-S Pr <b>0.03.002</b>                                              |
|                          |              |         | Open Loop Pr <b>0.05.004</b>                                                   |
| 0x08 (8 <sub>10</sub> )  | SpeedRef     | Get/Set | RFC-A or RFC-S Pr <b>0.01.021</b> (scaled to 0 decimal places)                 |
|                          |              | Get     | Open Loop Pr <b>0.01.021</b> * 60 / <i>NofPP</i> (scaled to 0 decimal places)  |
|                          |              | Set     | Pr <b>0.01.021</b> = SpeedRef * <i>NofPP</i> / 60 (scaled to 0 decimal places) |
| 0x0B (11 <sub>10</sub> ) | TorqueActual | Get     | Pr <b>0.04.020</b> (scaled to 1 decimal place)                                 |
| 0x0C (12 <sub>10</sub> ) | TorqueRef    | Get/Set | Pr <b>0.04.008</b> (scaled to 1 decimal place)                                 |
| 0x1D (29 <sub>10</sub> ) | RefFromNet   | Get     | 1 Pr <b>0.01.049</b> =3 AND Pr <b>0.01.050</b> =1                              |
|                          |              |         | 0 Pr <b>0.01.049</b> <>3 OR Pr <b>0.01.050</b> <>1                             |

**NOTE** *NofPP* = Number of Pole Pairs.

## AtReference

|           |             |           |       |
|-----------|-------------|-----------|-------|
| Name:     | AtReference |           |       |
| Class     | 0x2A        | Default   | N/A   |
| Instance  | 0x01        | Data Type | USINT |
| Attribute | 0x03        | Access    | Get   |

Indicates that the drive is running at the requested speed.

Get Pr **0.10.006**

0 = Drive not running at requested speed.

1 = Drive running at requested speed.

## NetRef

|           |        |           |         |
|-----------|--------|-----------|---------|
| Name:     | NetRef |           |         |
| Class     | 0x2A   | Default   | N/A     |
| Instance  | 0x01   | Data Type | USINT   |
| Attribute | 0x04   | Access    | Get/Set |

Selects the source of the speed reference.

Get/Set Pr **0.06.042** bit 8

0 = analog speed reference.

1 = digital speed reference.

**NOTE** The NetRef can only be changed between local and remote when the drive is configured in speed control mode. If a change is requested when in torque mode then a 'Device State Conflict' error code 0x10 will be returned.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## DriveMode

|                  |                  |                  |         |
|------------------|------------------|------------------|---------|
| <b>Name:</b>     | <b>DriveMode</b> |                  |         |
| <b>Class</b>     | 0x2A             | <b>Default</b>   | N/A     |
| <b>Instance</b>  | 0x01             | <b>Data Type</b> | USINT   |
| <b>Attribute</b> | 0x06             | <b>Access</b>    | Get/Set |

DriveMode does not allow the operating mode of the drive to be changed. Pr **0.04.011** will be written to as shown in Table 9-41 below, provided that the drive is already in the correct operating mode.

**Table 9-41 AC/DC Drive object DriveMode attribute (Get)**

| Access | DriveMode |                   | Actual Drive Mode | Torque Mode (0.4.011)                                                                                                          |
|--------|-----------|-------------------|-------------------|--------------------------------------------------------------------------------------------------------------------------------|
|        | Value     | Mode              |                   |                                                                                                                                |
| Get    | 1         | Open Loop Speed   | Open-loop         | Speed control mode (0)                                                                                                         |
|        | 2         | Closed Loop Speed | RFC-A             |                                                                                                                                |
|        |           |                   | RFC-S             |                                                                                                                                |
|        | 3         | Torque Control    | Open-loop         | Torque control (3)                                                                                                             |
|        |           |                   | RFC-A             |                                                                                                                                |
|        |           |                   | RFC-S             |                                                                                                                                |
|        | 0         | User Defined      | Regen             | Don't care                                                                                                                     |
|        |           |                   | Don't care        | Torque control with speed override (2)<br>or<br>Coiler / uncoiler mode (3)<br>or<br>Speed control with torque feed-forward (4) |

**Table 9-42 AC/DC Drive object DriveMode attribute (Set)**

| Access | DriveMode |                   | Actual Drive Mode           | Action                                       |
|--------|-----------|-------------------|-----------------------------|----------------------------------------------|
|        | Value     | Mode              |                             |                                              |
| Set    | 0         | User Defined      | Don't care                  | Return Invalid Attribute Value (0x09)        |
|        | 1         | Open Loop Speed   | Open-loop                   | Pr <b>0.04.011</b> = Speed control mode (0)  |
|        |           |                   | RFC-A or RFC-S or Regen     | Return 'Drive state conflict' error (0x10)   |
|        |           |                   |                             |                                              |
|        | 2         | Closed Loop Speed | RFC-A or RFC-S              | Pr <b>0.04.011</b> = Speed control mode (0)  |
|        |           |                   | Open-loop or Regen          | Return 'Drive state conflict' error (0x10)   |
|        | 3         | Torque Control    | Open-loop or RFC-A or RFC-S | Pr <b>0.04.011</b> = Torque control mode (1) |
|        |           |                   | Regen                       | Return 'Drive state conflict' error (0x10)   |

**NOTE** Pr **0.11.031** will never be changed by setting the DriveMode attribute. An error (0x10) will be generated if the requested DriveMode value does not correspond to the current DriveType operating mode.

## SpeedActual

|                  |                    |                  |       |
|------------------|--------------------|------------------|-------|
| <b>Name:</b>     | <b>SpeedActual</b> |                  |       |
| <b>Class</b>     | 0x2A               | <b>Default</b>   | N/A   |
| <b>Instance</b>  | 0x01               | <b>Data Type</b> | USINT |
| <b>Attribute</b> | 0x07               | <b>Access</b>    | Get   |

Returns the actual speed of the motor in RPM. The source of the motor speed depends on the operating mode of the drive.

Get Pr **0.05.004** (Open Loop).

Get Pr **0.03.002** (RFC-A or RFC-S).

## SpeedRef

|                  |                 |                  |         |
|------------------|-----------------|------------------|---------|
| <b>Name:</b>     | <b>SpeedRef</b> |                  |         |
| <b>Class</b>     | 0x2A            | <b>Default</b>   | N/A     |
| <b>Instance</b>  | 0x01            | <b>Data Type</b> | USINT   |
| <b>Attribute</b> | 0x08            | <b>Access</b>    | Get/Set |

Sets or returns the speed reference in RPM.

### RFC-A or RFC-S

Get/Set SpeedRef = Pr **0.01.021** (Scaled to 0 decimal places).

### Open loop

Get SpeedRef = (Pr **0.01.021** \* 60) / Pole Pairs (Scaled to 0 decimal places).

Set Pr **0.01.021** = (SpeedRef \* Pole Pairs) / 60 (Scaled to 0 decimal places).

## TorqueActual

|                  |                     |                  |       |
|------------------|---------------------|------------------|-------|
| <b>Name:</b>     | <b>TorqueActual</b> |                  |       |
| <b>Class</b>     | 0x2A                | <b>Default</b>   | N/A   |
| <b>Instance</b>  | 0x01                | <b>Data Type</b> | USINT |
| <b>Attribute</b> | 0x0B                | <b>Access</b>    | Get   |

Returns the actual load on the motor as a percentage of the rated motor load. This attribute has 1 decimal place precision, a value of 1000 represents 100.0 % load.

Get Pr **0.04.020** (Scaled to 1 decimal place).

## TorqueRef

|                  |                  |                  |         |
|------------------|------------------|------------------|---------|
| <b>Name:</b>     | <b>TorqueRef</b> |                  |         |
| <b>Class</b>     | 0x2A             | <b>Default</b>   | N/A     |
| <b>Instance</b>  | 0x01             | <b>Data Type</b> | USINT   |
| <b>Attribute</b> | 0x0C             | <b>Access</b>    | Get/Set |

Sets the load (torque) reference as % of rated motor load (torque). This attribute has 1 decimal place precision, so a value of 1000 represents 100.0 % load.

Set Pr **0.04.008** = TorqueRef / 10 (Scaled to 1 decimal place).

Get TorqueRef = Pr **0.04.008** \* 10 (Scaled to 1 decimal place).

## RefFromNet

|                  |                   |                  |       |
|------------------|-------------------|------------------|-------|
| <b>Name:</b>     | <b>RefFromNet</b> |                  |       |
| <b>Class</b>     | 0x2A              | <b>Default</b>   |       |
| <b>Instance</b>  | 0x01              | <b>Data Type</b> | USINT |
| <b>Attribute</b> | 0x1D              | <b>Access</b>    | Get   |

Indicates the source of the speed reference.

TRUE if Pr **0.01.049** = 3 and Pr **0.01.050** = 1.

FALSE otherwise.

## 9.5.21 Control Techniques objects

The Control Techniques objects (classes 0x64 to 0x69) allow access to all drive and option module parameters. The class instance number is used to reference the drive or option module menu number (except menu 0) and the class attribute number references the parameter within that menu.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

For example, the drive parameter *Percentage Load (0.04.020)* would be accessed as class 0x64, instance 0x04 and attribute 0x14.

An instance value of 0 is invalid therefore to allow access to menu 0 parameters, the instance value 200 (0xC8) must be used.

The number of instances and therefore the number of menus for each class depends on the destination device. If the drive is the destination then the number of menus will depend on the drive operating mode. If the destination is one of the option slots (or onboard Ethernet interface) then the number of menus depends on the type of option module fitted (or the onboard Ethernet interface).

Six individual classes are provided, the following table shows the classes used when accessing the drive or option module parameters.

**Table 9-43 Control Techniques object classes**

| Class Code |          | Name         | Description                                                    |
|------------|----------|--------------|----------------------------------------------------------------|
| Dec        | Hex (0x) |              |                                                                |
| 100        | 64       | CT Group     | Provides access to all drive parameters                        |
| 101        | 65       | CT This Slot | Provides access to the connected Ethernet interface parameters |
| 102        | 66       | CT Slot 1    | Provides access to the option module in slot 1 parameters      |
| 103        | 67       | CT Slot 2    | Provides access to the option module in slot 2 parameters      |
| 104        | 68       | CT Slot 3    | Provides access to the option module in slot 3 parameters      |
| 105        | 69       | CT Slot 4    | Provides access to the onboard Ethernet interface parameters   |

## 9.6 Profinet IO specification (Unidrive M700 / M702)

### 9.6.1 What is PROFINET?

PROFINET is an Ethernet based industrial network protocol adapting Ethernet hardware and protocols to the real time needs of industrial automation. Profinet enables distributed IO control from a PLC.

### 9.6.2 Features / Specification

- Dual 100 BASE-TX RJ45 connectors with support for shielded twisted pair, full-duplex 100 M bps connectivity with auto crossover correction
- Both RJ45 ports operate in full duplex mode as a network switch
- PROFINET Real Time class RT\_Class\_1 and conformance class A
- Cycle times from 1 ms to 512 ms specified during configuration
- Automatic device replacement using the LLDP protocols
- LED indication of network port activity
- Up to 64 cyclic IO module slots (maximum 32 inputs and 32 outputs configured by network configuration tool and GSDML file)
- Identification and Maintenance functions I&M0 to I&M4 supported

**NOTE** When referring to the cyclic data, the terms input and output are with respect to the PROFINET IO controller (PLC).

**NOTE** The terms 'network controller' and 'PLC' are mutually used in this manual to refer to the PROFINET network controller. This is generally a PLC with a PROFINET interface and possibly a programming interface to connect to the programming device or PC. However this interface is not necessary, as the PROFINET interface can be used to program the PLC.

### 9.6.3 GSDML Files

A GSDML (General Station Description Markup Language) file is required to describe the drive interface to a PROFINET controller or PLC. This is an XML file, the structure of which is specified by the PROFIBUS INTERNATIONAL organization ([www.profibus.org](http://www.profibus.org)).

The GSDML file is used in conjunction with the network configuration software to configure the Profinet interface for cyclic data exchange. Many commonly used drive parameters are available as direct mapping 'modules' to be added to the cyclic data 'slots'.

Non-specific 'Flexible modules' are also provided so that the user can allocate a parameter within the drive (or option module), that is not directly available as a specific 'module'. These options will be available from a drop-down selection list within the 'Parameters' tab of the 'module' properties.

The GSDML file can be downloaded from the main Control Techniques company website ([www.controltechniques.com](http://www.controltechniques.com)), providing you are registered or, alternatively, requested from your local Drive Centre or supplier.

**NOTE** For further information regarding the use of the GSDML file please refer to the PLC documentation

### 9.6.4 Network topology

The Ethernet interface has two Ethernet ports with integrated switches to allow the use of line networks. However, when using line networks, a break in the connection (for example when replacing a device) will cause all devices downstream from the failure to also stop communicating with the controller.

Other Ethernet network topologies can be used but care must be taken to ensure that the system still operates within the constraints specified by the designer.

Generally a star or tree network structure using switches gives improved availability in the event of a device failure or replacement.

|                    |                     |                         |                         |                 |                  |                   |              |                            |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|----------------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | <b>Drive communication</b> | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|----------------------------|-------------------------|-------------|---------------------|-------------|----------------|

Although the Profinet protocol does support all major topologies, line networks are normally used for practical or financial reasons, other topologies (e.g. star) may not be suitable for real time communications due to their inherent use of switches or other network equipment.

Any network devices used, such as switches, must be capable of real time communication. Standard office grade equipment is not normally suitable and should not be used in an industrial environment.

**NOTE** For the device replacement feature to work, the physical network topology must be configured in the controller. For further information please refer to the controller or network configuration software documentation.

### 9.6.5 Configuring the PROFINET IO communications

No module parameters need to be configured by the user in order to achieve PROFINET cyclic communications. All the necessary configuration is undertaken by the network controller or PLC during the start-up sequence, and after the network configuration is programmed into the network controller or PLC.

It must be noted that when configuring the cyclic data modules, if a module is configured but the associated drive parameter does not actually exist in the drive, then the PLC will not start up correctly and will indicate a configuration fault.

Parameters of slot option module menus can also be configured for cyclic data communication via correctly configured 'Flexible Modules'. The source of the associated parameter can be set to drive or any possible slot within the 'Flexible Module' parameter properties.

### 9.6.6 Setting the Profinet device name

Each Profinet device must have its own unique device name assigned during network configuration. Device names are used by the controller to communicate with the device for real time messages and alarms. Without a device name the device will not enter data exchange with the controller.

The actual device name is not important to the Profinet system itself, however, a suitable name should be chosen so that it is easily recognised on the network and identifies the location and function of the device.

A typical device name may contain up to four labels, each label is separated by a dot (.) and may be up to 63 characters in length.

The following rules must be observed when choosing the device name:

- Maximum length of 127 characters
- Characters must be lower case letters, numbers, dashes (-) or dots (.)
- The device name must start with a letter and end with either a letter or number
- The device name must not be in the format n.n.n.n (where n is a number from 0 to 999)
- The device name must not begin with the character sequence 'port-xyz' (where x, y and z are numbers from 0 to 9).

A typical example of a device name may be:

**motor-1.conveyor-2.line-3.ct-4**

The default device name is specified in the GSDML file under the section 'DNS\_CompatibleName'.

### 9.6.7 Profinet transmission cycle (send cycle)

The Profinet transmission cycle is the time required to update all the devices on the Profinet network, the duration of the transmission cycle is determined by the Profinet device with the slowest update rate.

The transmission cycle can be split into a number of phases, where each phase contains one or more devices with similar update rates, the duration of each phase will be equal to the fastest update rate.

#### Base clock

The base clock is the minimum time unit used and is equal to 31.25 µs.

### Send clock factor

The send clock factor determines the duration of each phase and is the number of base clock periods within each phase.

The following table illustrates the relationship between the supported send clock values and the phase duration.

| Send Clock Factor | Phase Duration (ms) |
|-------------------|---------------------|
| 32                | 1                   |
| 64                | 2                   |
| 128               | 4                   |

### Phase duration

The duration (or length) of each phase is determined by the formula:

$$\text{Phase duration} = \text{Send clock factor} \times \text{Base clock.}$$

### Reduction ratio

The reduction ratio acts as a multiplier of the minimum update time (or phase duration) and is determined for each device by the formula:

$$\text{Reduction ratio} = \text{Device update time} / \text{Phase duration}$$

### Number of phases

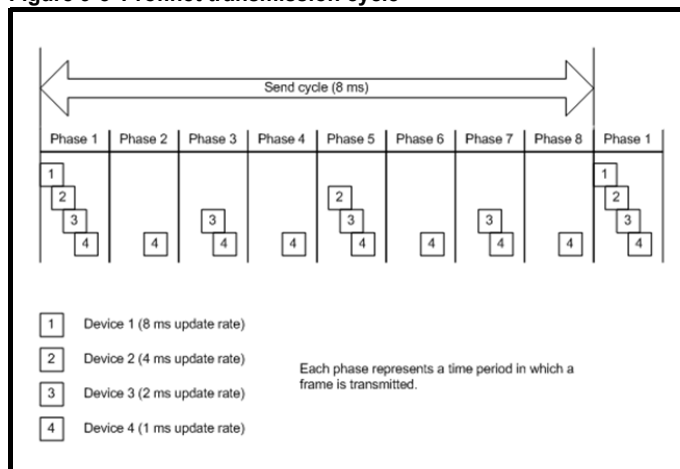
The number of phases is determined by the formula:

$$\text{Number of phases} = \text{Send cycle} / \text{fastest update rate.}$$

### Example:

In the following example, a system uses four devices, device 1 has an update rate of 8 ms, device 2 has an update rate of 4 ms, device 3 has an update rate of 2 ms and device 4 has an update rate of 1 ms.

**Figure 9-5 Profinet transmission cycle**



The Profinet transmission cycle is effectively the slowest update rate (8 ms in this example), and the phase duration is effectively the quickest update rate (1 ms in this example).

$$\begin{aligned} \text{Phase duration} &= \text{Send clock factor} \times \text{Base clock} \\ &= 32 \times 31.25 \mu\text{s} = 1 \text{ ms} \end{aligned}$$

$$\text{Reduction ratio} = \text{Device update time} / \text{Phase duration}$$

$$\text{Reduction ratio}_{(\text{device1})} = 8 \text{ ms} / 1 \text{ ms} = 8$$

$$\text{Reduction ratio}_{(\text{device2})} = 4 \text{ ms} / 1 \text{ ms} = 4$$

$$\text{Reduction ratio}_{(\text{device3})} = 2 \text{ ms} / 1 \text{ ms} = 2$$

$$\text{Reduction ratio}_{(\text{device4})} = 1 \text{ ms} / 1 \text{ ms} = 1$$

$$\begin{aligned} \text{Number of phases} &= \text{Send cycle} / \text{fastest update rate} \\ &= 8 \text{ ms} / 1 \text{ ms} = 8 \end{aligned}$$

### 9.6.8 Update rates

In contrast to some other fieldbus networks, Profinet devices can be configured with different update rates, these rates are specified in the device GSDML file. The Profinet interface on the M700 and M702 supports update rates of 1, 2, 4, 8, 16, 32, 64, 128, 256 and 512 ms.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

It is recommended that to avoid the possibility of overloading any sections of the Profinet network, the slowest update rate necessary is used.

The update rate can be configured in one of three ways:

- **Automatic** – the update rate selected is the time calculated by the I/O system that can be reliably achieved, based on the configuration.
- **Fixed update time** – the update rate is selected by the user from a list of supported rates specified in the GSDML file
- **Fixed factor** – the update rate is selected by the user from a list of supported rates specified in the GSDML file

**NOTE** This information only applies to the Siemens I/O configuration system (TIA Portal/SIMATIC STEP7), other I/O configuration systems may provide different configuration options.

### 9.6.9 Link Layer Discovery Protocol (LLDP)

LLDP is a manufacturer independent layer 2 protocol defined in accordance with the IEEE802.1AB standard.

During start-up and at regular intervals, LLDP messages are used to transfer device information between neighbouring devices. This information includes the device name and connection port numbers. LLDP messages use a special multicast destination MAC address that the IEEE802.1D compliant bridges and switches should not forward.

If all devices in a network support LLDP messages then an accurate network topology view can be presented in the I/O system configuration / diagnostic tool.

### 9.6.10 Discovery and Configuration Protocol (DCP)

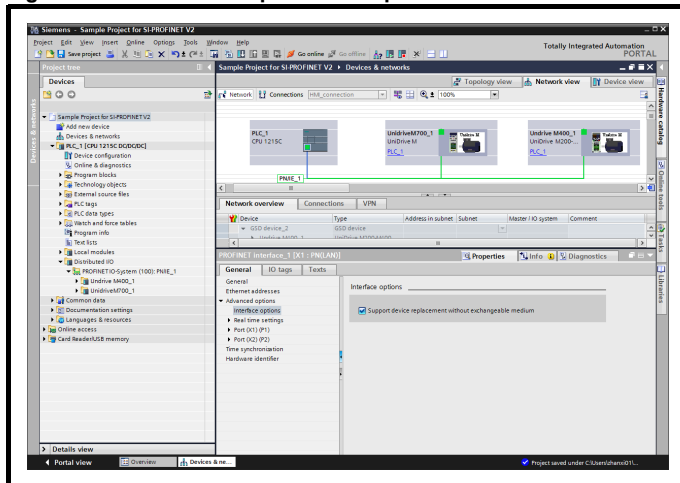
The Discovery and Configuration Protocol is used in the event of a device replacement to automatically configure the new device. All the necessary configuration is done by an appropriate neighbouring device when the new device is detected.

In order to use the network discovery and configuration protocol, the PLC must be correctly configured and programmed with the physical network topology, the following information is intended as a guide only, for more specific information (in particular for other types of PLC's), then please consult the PLC documentation.

**NOTE** Although the Siemens PLC is mentioned in this manual, Control Techniques does not recommend or endorse any particular PLC or controller manufacturer.

The following information relates to the Siemens S7-1215C PLC. The PLC must be configured to support device replacement, this is an option in the properties of the PROFINET port. In the device configuration screen of the TIA PORTAL application, open the properties of the PLC PROFINET port, click 'Interface options' under 'Advanced options' as shown in Figure 9-6. Ensure the option 'Support device replacement without exchangeable medium' is selected.

Figure 9-6 PLC device replacement option



The network topology must now be configured. From the hardware configuration screen, select the port, right click it and select 'PROFINET IO Topology...', the topology editor will be displayed, select the 'Graphic view' tab and using 'drag and drop', connect the relevant device ports together to match the physical network wiring. The program must then be compiled and downloaded to the PLC in the normal manner. Once the PLC has been configured, if a device is replaced then the new device will be automatically configured with the original device's properties, including the device name and IP address.

**NOTE** For the discovery protocol to work, the replacement device must not have a device name programmed, i.e. it must be blank or unused. If a device name exists in the module and that name is different to the device name set in the network configuration then the PLC will indicate a configuration error and will not enter data exchange with it.

### 9.6.11 Identification and Maintenance (I&M)

Identification and Maintenance (I&M) functions can be used to read and change various information about devices, such as manufacturer, ordering information, serial number, etc. This information can be used to assist the user in tracking the drive's life cycle through commissioning/start-up, parameterization, diagnosis, repair, etc. The Ethernet interface supports I&M0 to I&M4 inclusively; I&M0 is mandatory for all PROFINET devices, I&M1 to I&M4 are optional. Each I&M function returns specific information about the device and is explained in the following tables.

#### I&M0

Table 9-44 I&M0 Description

| Attribute             | Value (Read only)                           |
|-----------------------|---------------------------------------------|
| Manufacturer ID       | 0x0160                                      |
| Order ID              | SI-PROFINET                                 |
| Serial number         | (Pr S.00.005 x 1,000,000,000 + Pr S.00.004) |
| Hardware revision     | (Pr S.00.003)                               |
| Software revision     | (Pr S.00.002)                               |
| Revision counter      | (Pr S.24.006)                               |
| Profile ID            | (as read)                                   |
| Profile specific type | (as read)                                   |
| I&M version           | (as read)                                   |
| I&M supported         | (as read)                                   |

**Manufacturer ID:** 2-byte unsigned hexadecimal number assigned by the PROFIBUS business office and specified in the GSDML file. For Control Techniques this value is 0x0160.

**Order ID:** 20-byte string to identify the device. This value is specified in the GSDML file. For the Ethernet interface this value is 'SI-PROFINET'.

**Serial number:** 16 character string indicating the module serial number. This value is read from Pr S.00.004 and Pr S.00.005 of the Ethernet interface.

**Hardware revision:** 2-byte unsigned hexadecimal number indicating the hardware revision of the Ethernet interface. This value is read from Pr S.00.003 of the Ethernet interface.

**Software revision:** 4-byte value consisting of a single character 'V' and 3 unsigned 8-bit decimal numbers indicating the software revision of the Ethernet interface. This value is taken from Pr S.00.002 of the Ethernet interface.

**Revision counter:** 2-byte unsigned decimal number. This value will increment by one for each of the following conditions:

- > Drive parameter save
- > Drive parameter default
- > Drive mode change

Will wrap back to 1 after a value of 65535.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

**Profile ID:** 2-byte unsigned hexadecimal number indicating the application profile.

Devices not following any particular profile use the generic profile value 0xF600.

**Profile specific type:** 2-byte unsigned hexadecimal number indicating the application profile specific type. This value is not applicable to devices using the generic profile and in these instances this value will be zero.

**I&M version:** 2 unsigned 8-bit numbers indicating the version of the implemented I&M functions.

**I&M supported:** 2-byte unsigned number indicating the availability of the implemented I&M functions as shown in Table 9-45.

**Table 9-45 Supported I&M bit descriptions**

| Bit     | Value | Description          |
|---------|-------|----------------------|
| 0       |       | Profile specific I&M |
| 1       | 0     | I&M1 Not supported   |
|         | 1     | I&M1 Supported       |
| 2       | 0     | I&M2 Not supported   |
|         | 1     | I&M2 Supported       |
| 3       | 0     | I&M3 Not supported   |
|         | 1     | I&M3 Supported       |
| 4       | 0     | I&M4 Not supported   |
|         | 1     | I&M4 Supported       |
| 5 to 15 |       | Reserved             |

#### I&M1

**Table 9-46 I&M1 Description**

| Attribute                 | Value (Read/Write) |
|---------------------------|--------------------|
| Drive function (32 bytes) | (User defined)     |
| Drive location (22 bytes) | (User defined)     |

**Drive function:** 32-byte string indicating the drive function.

**Drive location:** 22-byte string indicating the drive location.

#### I&M2

**Table 9-47 I&M2 Description**

| Attribute         | Value (Read/Write) |
|-------------------|--------------------|
| Installation date | (User defined)     |

**Installation date:** 16-byte string indicating the installation or commissioning date of the device. The installation date is in the format DD/MM/YYYY.

#### I&M3

**Table 9-48 I&M3 Description**

| Attribute             | Value (Read/Write) |
|-----------------------|--------------------|
| Descriptor (54 bytes) | (User defined)     |

**Descriptor:** 54-byte string used to store additional information on the location, function or maintenance status of the device.

#### I&M4

**Table 9-49 I&M4 Description**

| Attribute            | Value (Read/Write) |
|----------------------|--------------------|
| Signature (54 bytes) | (User defined)     |

**Signature:** 54-byte octet string used to allow parameterization tools to store a security code as a reference for a particular parameterization session and audit trail tools to retrieve the code for integrity checks.

#### NOTE

All unused bytes of the I&M functions will be set to 0x20 (space).

|                    |                     |                         |                         |                 |                  |                   |              |                     |                                |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|--------------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | <b>NV Media Card Operation</b> | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|--------------------------------|-------------|---------------------|-------------|----------------|

# 10 NV Media Card Operation

## 10.1 Introduction

The Non-Volatile Media Card feature enables simple configuration of parameters, parameter back-up, storing / reading PLC programs and drive copying using a SMARTCARD or SD card storing / reading PLC programs. The drive offers backward compatibility for a Unidrive SP SMARTCARD and supports NV Media Cards formatted with either FAT16 or FAT32 file system.

The NV Media Card can be used for:

- Parameter copying between drives
- Saving drive parameter sets
- Saving an onboard user program

The NV Media Card is located at the top of the module under the drive display (if installed) on the left-hand side.

Ensure the NV Media Card is inserted with the contacts facing the left-hand side of the drive.

The drive only communicates with the NV Media Card when commanded to read or write, meaning the card may be "hot swapped".

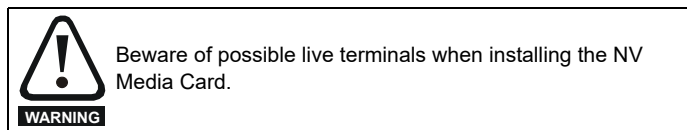
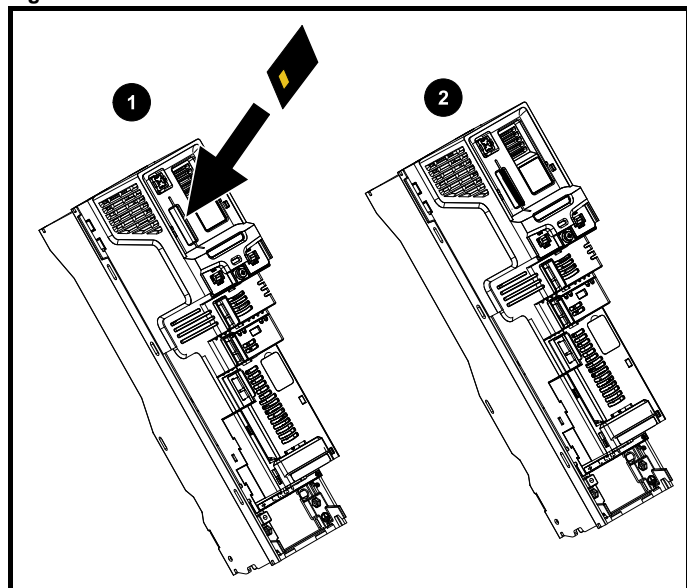


Figure 10-1 Installation of the NV Media Card



1. Installing the NV Media Card
2. NV Media Card installed

| NV Media Card                              | Part number    |
|--------------------------------------------|----------------|
| SD Card Adaptor (memory card not included) | 82400000016400 |
| 8 kB SMARTCARD                             | 2214-4246-03   |
| 64 kB SMARTCARD                            | 2214-1006-03   |

## 10.2 NV Media Card support

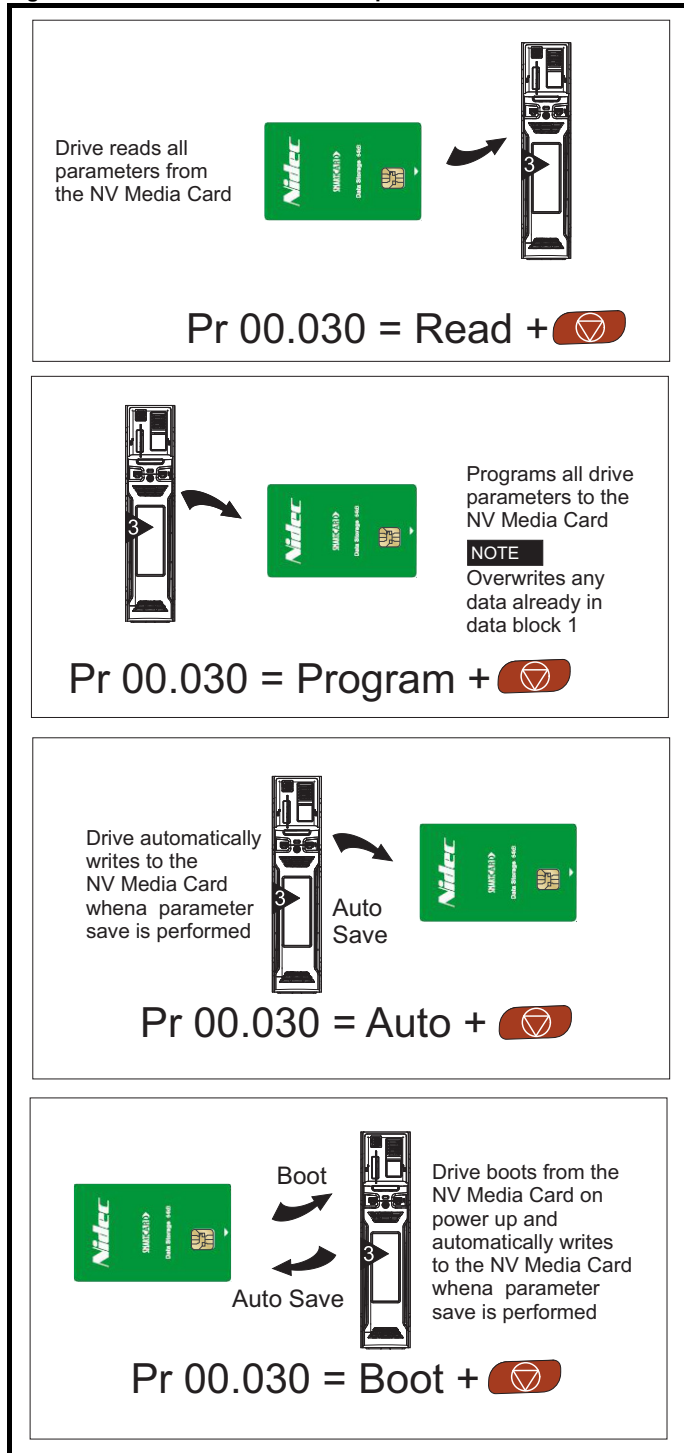
The NV Media Card can be used to store drive parameter sets and / or PLC programs set from the Unidrive M in data blocks 001 to 499 on the card.

The Unidrive M is compatible with a Unidrive SP SMARTCARD and is able to read and translate the Unidrive SP parameter set into a compatible parameter set for Unidrive M. This is only possible if the Unidrive SP parameter set was transferred to the SMARTCARD using

the difference from defaults transfer method (i.e. 4yyy transfer). The Unidrive M is not able to read any other type of Unidrive SP data block on the card. Although it is possible to transfer difference from default data blocks from a Unidrive SP into the Unidrive M, the following should be noted:

1. If a parameter from the source drive does not exist in the target drive then no data is transferred for that parameter.
2. If the data for the parameter in the target drive is out of range then the data is limited to the range of the target parameter.
3. If the target drive has a different rating to the source drive then the normal rules for this type of transfer apply.

Figure 10-2 Basic NV Media Card operation



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

The whole card may be protected from writing or erasing by setting the read-only flag as detailed section 10.3.9 9888 / 9777 - *Setting and clearing the NV Media Card read only flag* on page 141.

The card should not be removed during data transfer, as the drive will produce a trip. If this occurs then either the transfer should be reattempted or in the case of a card to drive transfer, default parameters should be loaded.

## 10.3 Transferring data

Data transfer, erasing and protecting the information is performed by entering a code in Pr **mm.000** and then resetting the drive as shown in Table 10-1.

**Table 10-1 SMARTCARD and SD card codes**

| Code | Operation                                                                                                                                                                                                                                                                  | SMARTCARD | SD card |
|------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|---------|
| 2001 | Transfer the drive parameters to parameter file 001 and sets the block as bootable. This will include the parameters from attached option modules.                                                                                                                         | ✓         | ✓       |
| 4yyy | Transfer the drive parameters to parameter file yyy. This will include the parameters from attached option modules.                                                                                                                                                        | ✓         | ✓       |
| 5yyy | Transfer the onboard user program to onboard user program file yyy.                                                                                                                                                                                                        | ✓         | ✓       |
| 6yyy | Load the drive parameters from parameter file yyy or the onboard user program from onboard user program file yyy.                                                                                                                                                          | ✓         | ✓       |
| 7yyy | Erase file yyy.                                                                                                                                                                                                                                                            | ✓         | ✓       |
| 8yyy | Compare the data in the drive with file yyy. If the files are the same then Pr <b>mm.000</b> ( <b>mm.000</b> ) is simply reset to 0 when the compare is complete. If the files are different a 'Card Compare' trip is initiated. All other NV media card trips also apply. | ✓         | ✓       |
| 9555 | Clear the warning suppression flag                                                                                                                                                                                                                                         | ✓         | ✓       |
| 9666 | Set the warning suppression flag                                                                                                                                                                                                                                           | ✓         | ✓       |
| 9777 | Clear the read-only flag                                                                                                                                                                                                                                                   | ✓         | ✓       |
| 9888 | Set the read-only flag                                                                                                                                                                                                                                                     | ✓         | ✓       |
| 9999 | Erase and format the NV media card                                                                                                                                                                                                                                         | ✓         |         |

Where yyy indicates the block number 001 to 999.

### NOTE

If the read only flag is set then only codes 6yyy or 9777 are effective.

### 10.3.1 Writing to the NV Media Card

#### 4yyy - Writes defaults differences to the NV Media Card

The data block only contains the parameter differences from the last time default settings were loaded.

All parameters except those with the NC (Not copied) coding bit set are transferred to the NV Media Card. In addition to these parameters all menu 20 parameters (except Pr **20.000**), can be transferred to the NV Media Card.

#### Writing a parameter set to the NV Media Card (Pr 00.030 = Program (2))

Setting Pr **00.030** to Program (2) and resetting the drive will save the parameters to the NV Media Card, i.e. this is equivalent to writing 4001 to Pr **mm.000**. All NV Media Card trips apply except 'Card Change'. If the data block already exists it is automatically overwritten. When the action is complete this parameter is automatically reset to None (0).

### 10.3.2 Reading from the NV Media Card

#### 6yyy - Reading from NV Media Card

When the data is transferred back to the drive, using 6yyy in Pr **mm.000**, it is transferred to the drive RAM and the EEPROM. A parameter save is not required to retain the data after-power down. Set up data for any option modules installed stored on the card are transferred to the drive. If the option modules installed are different between source and destination drives, the menus for the option module slots where the option module categories are different are not updated from the card and will contain their default values after the copying action. The drive will produce a 'Card Option' trip if the option module installed to the source and the destination drives are different or are in different slots. If the data is being transferred to the drive with different voltage or current rating a 'Card Rating' trip will occur.

The following drive rating dependant parameters (RA coding bit set) will not be transferred to the destination drive by a NV Media Card when the

voltage rating of the destination drive is different from the source drive and the file is a parameter file.

However, drive rating dependent parameters will be transferred if only the current rating is different. If drive rating dependant parameters are not transferred to the destination drive they will contain their default values.

Pr **02.008** *Standard Ramp Voltage*

Pr **04.005** to Pr **04.007** and Pr **21.027** to Pr **21.029** *Motoring Current Limits*

Pr **04.024**, *User Current Maximum Scaling*

Pr **05.007**, Pr **21.007** *Rated Current*

Pr **05.009**, Pr **21.009** *Rated Voltage*

Pr **05.010**, Pr **21.010** *Rated Power Factor*

Pr **05.017**, Pr **21.012** *Stator Resistance*

Pr **05.018** *Maximum Switching Frequency*

Pr **05.024**, Pr **21.014** *Transient Inductance*

Pr **05.025**, Pr **21.024** *Stator Inductance*

Pr **06.006** *Injection Braking Level*

Pr **06.048** *Supply Loss Detection Level*

Pr **06.065** *Standard Under Voltage Threshold*

Pr **06.066** *Low Under Voltage Threshold*

Pr **06.073** *Braking IGBT Lower Threshold*

Pr **06.074** *Braking IGBT Upper Threshold*

Pr **06.075** *Low Voltage Braking IGBT Threshold*

#### Reading a parameter set from the NV Media Card (Pr 00.030 = Read (1))

Setting Pr **00.030** to Read (1) and resetting the drive will transfer the parameters from the card into the drive parameter set and the drive EEPROM, i.e. this is equivalent to writing 6001 to Pr **mm.000**.

All NV Media Card trips apply. Once the parameters are successfully copied this parameter is automatically reset to None (0). Parameters are saved to the drive EEPROM after this action is complete.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                                |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|--------------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | <b>NV Media Card Operation</b> | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|--------------------------------|-------------|---------------------|-------------|----------------|

### 10.3.3 Auto saving parameter changes (Pr 00.030 = Auto (3))

This setting causes the drive to automatically save any changes made to menu 0 parameters on the drive to the NV Media Card. The latest menu 0 parameter set in the drive is therefore always backed up on the NV Media Card. Changing Pr **00.030** to Auto (3) and resetting the drive will immediately save the complete parameter set from the drive to the card, i.e. all parameters except parameters with the NC coding bit set. Once the whole parameter set is stored only the individual modified menu 0 parameter setting is updated.

Advanced parameter changes are only saved to the NV Media Card when Pr **mm.000** is set to 'Save Parameters' or a 1001 and the drive reset.

All NV Media Card trips apply, except 'Card Change'. If the data block already contains information it is automatically overwritten.

If the card is removed when Pr **00.030** is set to 3 Pr **00.030** is then automatically set to None (0).

When a new NV Media Card is installed Pr **00.030** must be set back to Auto (3) by the user and the drive reset so the complete parameter set is rewritten to the new NV Media Card if auto mode is still required.

When Pr **00.030** is set to Auto (3) and the parameters in the drive are saved, the NV Media Card is also updated, and therefore the NV Media Card becomes a copy of the drives stored configuration.

At power up, if Pr **00.030** is set to Auto (3), the drive will save the complete parameter set to the NV Media Card. The drive will display 'Card Write' during this operation. This is done to ensure that if a user puts a new NV Media Card in during power down the new NV Media Card will have the correct data.

#### NOTE

When Pr **00.030** is set to Auto (3) the setting of Pr **00.030** itself is saved to the drive EEPROM but not the NV Media Card.

### 10.3.4 Booting up from the NV Media Card on every power up (Pr 00.030 = Boot (4))

When Pr **00.030** is set to Boot (4) the drive operates the same as Auto mode except when the drive is powered-up. The parameters on the NV Media Card will be automatically transferred to the drive at power up if the following are true:

- A card is inserted in the drive
- Parameter data block 1 exists on the card
- The data in block 1 is type 1 to 4 (as defined in Pr **11.038**)
- Pr **00.030** on the card set to Boot (4)

The drive will display 'Booting Parameters' during this operation. If the drive mode is different from that on the card, the drive gives a 'Card Drive Mode' trip and the data is not transferred.

If 'Boot' mode is stored on the copying NV Media Card this makes the copying NV Media Card the master device. This provides a very fast and efficient way of re-programming a number of drives.

#### NOTE

'Boot' mode is saved to the card, but when the card is read, the value of Pr **00.030** is not transferred to the drive.

### 10.3.5 Booting up from the NV Media Card on every power up (Pr mm.000 = 2001)

It is possible to create a bootable parameter data block by setting Pr **mm.000** to 2001 and initiating a drive reset. This data block is created in one operation and is not updated when further parameter changes are made.

Setting Pr **mm.000** to 2001 will overwrite the data block 1 on the card if it already exists.

### 10.3.6 8yyy - Comparing the drive full parameter set with the NV Media Card values

Setting 8yyy in Pr **mm.000**, will compare the NV Media Card file with the data in the drive. If the compare is successful Pr **mm.000** is simply set to 0. If the compare fails a 'Card Compare' trip is initiated.

### 10.3.7 7yyy / 9999 - Erasing data from the NV Media Card values

Data can be erased from the NV Media Card either one block at a time or all blocks in one go.

- Setting 7yyy in Pr **mm.000** will erase NV Media Card data block yyy
- Setting 9999 in Pr **mm.000** will erase all data blocks on a SMARTCARD, but not on a SD Card.

### 10.3.8 9666 / 9555 - Setting and clearing the NV Media Card warning suppression flag

If the option modules installed to the source and destination drive are different or are in different slots the drive will produce a 'Card Option' trip. If the data is being transferred to a drive of a different voltage or current rating a 'Card Rating' trip will occur. It is possible to suppress these trips by setting the warning suppression flag. If this flag is set the drive will not trip if the option module(s) or drive ratings are different between the source and destination drives. The options module or rating dependent parameters will not be transferred.

- Setting 9666 in Pr **mm.000** will set the warning suppression flag
- Setting 9555 in Pr **mm.000** will clear the warning suppression flag

### 10.3.9 9888 / 9777 - Setting and clearing the NV Media Card read only flag

The NV Media Card may be protected from writing or erasing by setting the read only flag. If an attempt is made to write or erase a data block when the read only flag is set, a 'Card Read Only' trip is initiated. When the read only flag is set only codes 6yyy or 9777 are effective.

- Setting 9888 in Pr **mm.000** will set the read only flag
- Setting 9777 in Pr **mm.000** will clear the read only flag

## 10.4 Data block header information

Each data block stored on a NV Media Card has header information detailing the following:

- NV Media Card File Number (11.037)
- NV Media Card File Type (11.038)
- NV Media Card File Version (11.039)
- NV Media Card File Checksum (11.040)

The header information for each data block which has been used can be viewed in Pr **11.038** to Pr **11.040** by increasing or decreasing the data block number set in Pr **11.037**. If there is no data on the card Pr **11.037** can only have a value of 0.

## 10.5 NV Media Card parameters

Table 10-2 Key to parameter table coding

|     |                  |    |                     |
|-----|------------------|----|---------------------|
| RW  | Read / Write     | ND | No default value    |
| RO  | Read only        | NC | Not copied          |
| Num | Number parameter | PT | Protected parameter |
| Bit | Bit parameter    | RA | Rating dependant    |
| Txt | Text string      | US | User save           |
| Bin | Binary parameter | PS | Power-down save     |
| FI  | Filtered         | DE | Destination         |

| 11.036 {00.029} |     | NV Media Card File Previously Loaded |  |  |    |    |  |
|-----------------|-----|--------------------------------------|--|--|----|----|--|
| RO              | Num |                                      |  |  | NC | PT |  |
| OL              |     |                                      |  |  |    |    |  |
| RFC-A           | ↕   | 0 to 999                             |  |  | ⇒  | 0  |  |
| RFC-S           |     |                                      |  |  |    |    |  |

This parameter shows the number of the data block last transferred from a NV Media Card to the drive. If defaults are subsequently reloaded this parameter is set to 0.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| 11.037 |   | NV Media Card File Number |  |  |  |  |   |   |  |  |  |  |  |
|--------|---|---------------------------|--|--|--|--|---|---|--|--|--|--|--|
| RW     |   | Num                       |  |  |  |  |   |   |  |  |  |  |  |
| OL     | ⇕ | 0 to 999                  |  |  |  |  | ⇒ | 0 |  |  |  |  |  |
| RFC-A  |   |                           |  |  |  |  |   |   |  |  |  |  |  |
| RFC-S  |   |                           |  |  |  |  |   |   |  |  |  |  |  |

This parameter should have the data block number which the user would like the information displayed in Pr 11.038, Pr 11.039 and Pr 11.040.

| 11.038 |   | NV Media Card File Type                                                                          |  |  |  |    |    |    |  |  |  |
|--------|---|--------------------------------------------------------------------------------------------------|--|--|--|----|----|----|--|--|--|
| RO     |   | Txt                                                                                              |  |  |  | ND | NC | PT |  |  |  |
| OL     | ⇕ | None (0), Open-loop (1),<br>RFC-A (2), RFC-S (3),<br>Regen (4), User Prog (5),<br>Option App (6) |  |  |  | ⇒  |    |    |  |  |  |
| RFC-A  |   |                                                                                                  |  |  |  |    |    |    |  |  |  |
| RFC-S  |   |                                                                                                  |  |  |  |    |    |    |  |  |  |

Displays the type/mode of the data block selected with Pr 11.037.

| Pr 11.038 | String     | Type / mode                    |
|-----------|------------|--------------------------------|
| 0         | None       | No file selected               |
| 1         | Open-loop  | Open-loop mode parameter file  |
| 2         | RFC-A      | RFC-A mode parameter file      |
| 3         | RFC-S      | RFC-S mode parameter file      |
| 4         | Regen      | Regen mode parameter file      |
| 5         | User Prog  | Onboard user program file      |
| 6         | Option App | Option module application file |

| 11.039 |   | NV Media Card File Version |  |  |  |    |    |    |  |  |  |
|--------|---|----------------------------|--|--|--|----|----|----|--|--|--|
| RO     |   | Num                        |  |  |  | ND | NC | PT |  |  |  |
| OL     | ⇕ | 0 to 9999                  |  |  |  | ⇒  |    |    |  |  |  |
| RFC-A  |   |                            |  |  |  |    |    |    |  |  |  |
| RFC-S  |   |                            |  |  |  |    |    |    |  |  |  |

Displays the version number of the file selected in Pr 11.037.

| 11.040 |     | NV Media Card File Checksum  |  |  |  |    |    |    |  |  |  |
|--------|-----|------------------------------|--|--|--|----|----|----|--|--|--|
| RO     | Num |                              |  |  |  | ND | NC | PT |  |  |  |
| OL     | ⇕   | -2147483648 to<br>2147483647 |  |  |  | ⇒  |    |    |  |  |  |
| RFC-A  |     |                              |  |  |  |    |    |    |  |  |  |
| RFC-S  |     |                              |  |  |  |    |    |    |  |  |  |

Displays the checksum of the data block selected in Pr 11.037.

| 11.042 {00.030} |   | Parameter Cloning                                         |  |  |  |  |   |          |  |     |  |
|-----------------|---|-----------------------------------------------------------|--|--|--|--|---|----------|--|-----|--|
| RW              |   | Txt                                                       |  |  |  |  |   | NC       |  | US* |  |
| OL              | ⇕ | None (0), Read (1),<br>Program (2), Auto (3),<br>Boot (4) |  |  |  |  | ⇒ | None (0) |  |     |  |
| RFC-A           |   |                                                           |  |  |  |  |   |          |  |     |  |
| RFC-S           |   |                                                           |  |  |  |  |   |          |  |     |  |

\* Only a value of 3 or 4 in this parameter is saved.

#### NOTE

If Pr 11.042 is equal to 1 or 2, this value is not transferred to the drive or saved to the EEPROM. If Pr 11.042 is set to 3 or 4 the value is saved to the EEPROM

None (0) = Inactive

Read (1) = Read parameter set from the NV Media Card

Program (2) = Program a parameter set to the NV Media Card

Auto (3) = Auto save

Boot (4) = Boot mode

| 11.072 |   | NV Media Card Create Special File |  |  |  |  |    |   |  |  |  |
|--------|---|-----------------------------------|--|--|--|--|----|---|--|--|--|
| RW     |   | Num                               |  |  |  |  | NC |   |  |  |  |
| OL     | ⇕ | 0 to 1                            |  |  |  |  | ⇒  | 0 |  |  |  |
| RFC-A  |   |                                   |  |  |  |  |    |   |  |  |  |
| RFC-S  |   |                                   |  |  |  |  |    |   |  |  |  |

If *NV Media Card Create Special File* (11.072) = 1 when a parameter file is transferred to an NV media card the file is created as a macro file. *NV Media Card Create Special File* (11.072) is reset to 0 after the file is created or the transfer fails.

| 11.073 |   | NV Media Card Type                          |  |  |  |    |    |    |  |  |  |
|--------|---|---------------------------------------------|--|--|--|----|----|----|--|--|--|
| RO     |   | Txt                                         |  |  |  | ND | NC | PT |  |  |  |
| OL     | ⇕ | None (0),<br>SMART Card (1),<br>SD Card (2) |  |  |  | ⇒  |    |    |  |  |  |
| RFC-A  |   |                                             |  |  |  |    |    |    |  |  |  |
| RFC-S  |   |                                             |  |  |  |    |    |    |  |  |  |

This will display the type of media card inserted; it will contain one of the following values:

"None" (0) - No NV Media Card has been inserted.

"SMART Card" (1) - A SMARTCARD has been inserted.

"SD Card" (2) - A FAT formatted SD card has been inserted.

| 11.075 |   | NV Media Card Read-only Flag |  |  |  |    |    |    |  |  |  |
|--------|---|------------------------------|--|--|--|----|----|----|--|--|--|
| RO     |   | Bit                          |  |  |  | ND | NC | PT |  |  |  |
| OL     | ⇕ | Off (0) or On (1)            |  |  |  | ⇒  |    |    |  |  |  |
| RFC-A  |   |                              |  |  |  |    |    |    |  |  |  |
| RFC-S  |   |                              |  |  |  |    |    |    |  |  |  |

*NV Media Card Read-only Flag* (11.075) shows the state of the read-only flag for the currently installed card.

| 11.076 |   | NV Media Card Warning Suppression Flag |  |  |  |    |    |    |  |  |  |
|--------|---|----------------------------------------|--|--|--|----|----|----|--|--|--|
| RO     |   | Bit                                    |  |  |  | ND | NC | PT |  |  |  |
| OL     | ⇕ | Off (0) or On (1)                      |  |  |  | ⇒  |    |    |  |  |  |
| RFC-A  |   |                                        |  |  |  |    |    |    |  |  |  |
| RFC-S  |   |                                        |  |  |  |    |    |    |  |  |  |

*NV Media Card Warning Suppression Flag* (11.076) shows the state of the warning flag for the currently installed card.

| 11.077 |   | NV Media Card File Required Version |  |  |  |    |    |    |  |  |  |
|--------|---|-------------------------------------|--|--|--|----|----|----|--|--|--|
| RW     |   | Num                                 |  |  |  | ND | NC | PT |  |  |  |
| OL     | ⇕ | 0 to 9999                           |  |  |  | ⇒  |    |    |  |  |  |
| RFC-A  |   |                                     |  |  |  |    |    |    |  |  |  |
| RFC-S  |   |                                     |  |  |  |    |    |    |  |  |  |

The value of *NV Media Card File Required Version* (11.077) is used as the version number for a file when it is created on an NV Media Card. *NV Media Card File Required Version* (11.077) is reset to 0 when the file is created or the transfer fails.

## 10.6 NV Media Card trips

After an attempt to read, write or erase data from a NV Media Card a trip is initiated if there has been a problem with the command.

See Chapter 13 *Diagnostics* on page 245 for more information on NV Media Card trips.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |                    |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|--------------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | <b>Onboard PLC</b> | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|--------------------|---------------------|-------------|----------------|

# 11 Onboard PLC

## 11.1 Onboard PLC and Machine Control Studio

The drive has the ability to store and execute a 16 kB Onboard PLC user program without the need for additional hardware in the form of an option module.

Machine Control Studio is an IEC61131-3 development environment designed for use with Unidrive M and compatible application modules. Machine Control Studio is based on CODESYS from 3S-Smart Software Solutions.

All of the programming languages defined in the IEC standard IEC 61131-3 are supported in the Machine Control Studio development environment.

- ST (Structured text)
- LD (Ladder diagram)
- FBD (Function block diagram)
- IL (Instruction list)
- SFC (Sequential function chart)
- CFC (Continuous Function Chart). CFC is an extension to the standard IEC programming languages

Machine Control Studio provides a complete environment for the development of user programs. Programs can be created, compiled and downloaded to a Unidrive M for execution, via the communications port on the front of the drive. The run-time operation of the compiled program on the target can also be monitored using Machine Control Studio and facilities are provided to interact with the program on the target by setting new values for target variables and parameters.

The Onboard PLC and Machine Control Studio form the first level of functionality in a range of programmable options for Unidrive M.

Machine Control Studio can be downloaded from [www.controltechniques.com](http://www.controltechniques.com).

See the Machine Control Studio help file for more information regarding using Machine Control Studio, creating user programs and downloading user programs to the drive.

## 11.2 Benefits

The combination of the Onboard PLC and Machine Control Studio, means that the drive can replace nano and some micro PLCs in many applications

Machine Control Studio benefits from access to the standard CODESYS function and function block libraries as well as those from third parties. Functions and function blocks available as standard in Machine Control Studio include, but not limited to, the following:

- Arithmetic blocks
- Comparison blocks
- Timers
- Counters
- Multiplexers
- Latches
- Bit manipulation

Typical applications for the Onboard PLC include:

- Ancillary pumps
- Fans and control valves
- Interlocking logic
- Sequences routines
- Custom control words.

## 11.3 Features

The Unidrive M Onboard PLC user program has the following features:

### 11.3.1 Tasks

The Onboard PLC allows use of two tasks.

- **Clock:** A high priority real time task. The clock task interval can be set from 4 ms to 262 s in multiples of 4 ms. The parameter *Onboard User Program: Clock Task Time Used* (11.051) shows the percentage of the available time used by clock task. A read or write of a drive parameter by the user program takes a finite period of time. It is possible to select up to 10 parameters as fast access parameter which reduced the amount of time it takes for the user program to read from or write to a drive parameter. This is useful when using a clock task with a fast update rate as selecting a parameter for fast access reduces the amount of the clock task resource required to access parameters.
- **Freewheeling:** A non-real time background task. The freewheeling task is scheduled for a short period once every 64 ms. The time for which the task is scheduled will vary depending on the loading of the drive's processor. When scheduled, several scans of the user program may be performed. Some scans may execute in microseconds. However, when the main drive functions are scheduled there will be a pause in the execution of the program causing some scans to take many milliseconds. The parameter *Onboard User Program: Freewheeling Tasks Per Second* (11.050) shows the number of times the freewheeling task has started per second.

### 11.3.2 Variables

The Onboard PLC supports the use of variables with the data types of Boolean, integer (8 bit, 16 bit and 32 bit, signed and unsigned), floating point (64 bit only), strings and time.

### 11.3.3 Custom menu

Machine Control Studio can construct a custom drive menu to reside in menu 30 on the drive. The following properties of each parameter can be defined using Machine Control Studio:

- Parameter name
- Number of decimal places
- The units for the parameter to be display on the keypad.
- The minimum, maximum and default values
- Memory handling (i.e. power down save, user save or volatile)
- Data type. The drive provides a limited set of 1 bit, 8 bit, 16 bit and 32 bit integer parameters to create the customer menu.

Parameters in this customer menu can be accessed by the user program and will appear on the keypad.

### 11.3.4 Limitations

The Onboard PLC user program has the following limitations:

- The flash memory allocated to the Onboard PLC is 16 kB which includes the user program and its header which results in a maximum user program size of about 12 kB
- The Onboard PLC is provided with 2 kB of RAM.
- The drive is rated for 100 program downloads. This limitation is imposed by the flash memory used to store the program within the drive.
- There is only one real-time task with a minimum period of 4 ms.
- The freewheeling background task runs at a low priority. The drive is prioritized to perform the clock task and its major functions first, e.g. motor control, and will use any remaining processing time to execute the freewheeling task as a background activity. As the drive's processor becomes more heavily loaded, less time is spent executing the freewheeling task.
- Breakpoints, single stepping and online program changes are not possible.
- The Graphing tool is not supported.
- The variable data types REAL (32 bit floating point), LWORD (64 bit integer) and WSTRING (Unicode string), and retained variables are not supported.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |                    |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|--------------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | <b>Onboard PLC</b> | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|--------------------|---------------------|-------------|----------------|

## 11.4 Onboard PLC parameters

The following parameters are associated with the Onboard PLC user program.

| 11.047 Onboard User Program: Enable |                     |  |  |   |         |  |
|-------------------------------------|---------------------|--|--|---|---------|--|
| RW                                  | Txt                 |  |  |   | US      |  |
| ↕                                   | Stop (0) or Run (1) |  |  | ⇒ | Run (1) |  |

This parameter stops and starts the user program.

### 0 - Stop the User Program

The onboard user program is stopped. If it is restarted by setting *Onboard User Program: Enable* (11.047) to a non-zero value the background task starts from the beginning.

### 1 - Run the User Program

The user program will execute.

| 11.048 Onboard User Program: Status |                           |  |    |    |  |  |
|-------------------------------------|---------------------------|--|----|----|--|--|
| RO                                  | Txt                       |  | NC | PT |  |  |
| ↕                                   | -2147483648 to 2147483647 |  |    | ⇒  |  |  |

This parameter is read-only and indicates the status of the user program in the drive. The user program writes the value to this parameter.

0: Stopped

1: Running

2: Exception

3: No user program present

| 11.049 Onboard User Program: Programming Events |            |  |    |    |    |  |
|-------------------------------------------------|------------|--|----|----|----|--|
| RO                                              | Uni        |  | NC | PT | PS |  |
| ↕                                               | 0 to 65535 |  |    | ⇒  |    |  |

This parameter holds the number of times an Onboard PLC user program download has taken place and is 0 on dispatch from the factory. The drive is rated for one hundred program downloads. This parameter is not altered when defaults are loaded.

| 11.050 Onboard User Program: Freewheeling Tasks Per Second |            |  |    |    |  |  |
|------------------------------------------------------------|------------|--|----|----|--|--|
| RO                                                         | Uni        |  | NC | PT |  |  |
| ↕                                                          | 0 to 65535 |  |    | ⇒  |  |  |

This parameter shows the number of times the freewheeling task has started per second.

| 11.051 Onboard User Program: Clock Task Time Used |                |  |    |    |  |  |
|---------------------------------------------------|----------------|--|----|----|--|--|
| RO                                                |                |  | NC | PT |  |  |
| ↕                                                 | 0.0 to 100.0 % |  |    | ⇒  |  |  |

This parameter shows the percentage of the available time used by the user program clock task.

| 11.055 Onboard User Program: Clock Task Scheduled Interval |                |  |    |    |  |  |
|------------------------------------------------------------|----------------|--|----|----|--|--|
| RO                                                         |                |  | NC | PT |  |  |
| ↕                                                          | 0 to 262128 ms |  |    | ⇒  |  |  |

This parameter shows the interval at which the clock task is scheduled to run at in ms.

## 11.5 Onboard PLC trips

If the drive detects an error in the user program it will initiate a User Program trip. The sub-trip number for the User Program trip details the reason for the error. See Chapter 13 *Diagnostics* on page 245 for more information on the User Program trip.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                            |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|----------------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | <b>Advanced parameters</b> | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|----------------------------|-------------|----------------|

## 12 Advanced parameters

This is a quick reference to all parameters in the drive showing units, ranges limits etc, with block diagrams to illustrate their function. Full descriptions of the parameters can be found in the *Parameter Reference Guide*.



**These advanced parameters are listed for reference purposes only. The lists in this chapter do not include sufficient information for adjusting these parameters. Incorrect adjustment can affect the safety of the system, and damage the drive and or external equipment. Before attempting to adjust any of these parameters, refer to the *Parameter Reference Guide*.**

**Table 12-1 Menu descriptions**

| Menu   | Description                                                        |
|--------|--------------------------------------------------------------------|
| 0      | Commonly used basic set up parameters for quick / easy programming |
| 1      | Frequency / Speed reference                                        |
| 2      | Ramps                                                              |
| 3      | Frequency slaving, speed feedback and speed control                |
| 4      | Torque and current control                                         |
| 5      | Motor control                                                      |
| 6      | Sequencer and clock                                                |
| 7      | Analog I/O / Temperature monitoring                                |
| 8      | Digital I/O                                                        |
| 9      | Programmable logic, motorized pot, binary sum, timers and scope    |
| 10     | Status and trips                                                   |
| 11     | Drive set-up and identification, serial communications             |
| 12     | Threshold detectors and variable selectors                         |
| 13     | Standard motion control                                            |
| 14     | User PID controller                                                |
| 15     | Option module slot 1 set-up menu                                   |
| 16     | Option module slot 2 set-up menu                                   |
| 17     | Option module slot 3 set-up menu                                   |
| 18     | General option module application menu 1                           |
| 19     | General option module application menu 2                           |
| 20     | General option module application menu 3                           |
| 21     | Second motor parameters                                            |
| 22     | Menu 0 set-up                                                      |
| 23     | Not allocated                                                      |
| 24     | Ethernet module (slot 4) set-up menu*                              |
| 25     | Option module slot 1 application parameters                        |
| 26     | Option module slot 2 application parameters                        |
| 27     | Option module slot 3 application parameters                        |
| 28     | Option module slot 4 application parameters                        |
| 29     | Reserved menu                                                      |
| 30     | Onboard user programming application menu                          |
| 31-41  | Advanced motion controller setup parameters                        |
| Slot 1 | Slot 1 option menus**                                              |
| Slot 2 | Slot 2 option menus**                                              |
| Slot 3 | Slot 3 option menus**                                              |
| Slot 4 | Slot 4 option menus**                                              |

\* Only displayed on *Unidrive M700 / M702*.

\*\* Only displayed when the option modules are installed.

### Operation mode abbreviations:

**Open-loop:** Sensorless control for induction motors

**RFC-A:** Asynchronous Rotor Flux Control for induction motors

**RFC-S:** Synchronous Rotor Flux Control for synchronous motors including permanent magnet motors.

### Default abbreviations:

Standard default value (50 Hz AC supply frequency)

USA default value (60 Hz AC supply frequency)

### NOTE

Parameter numbers shown in brackets {...} are the equivalent Menu 0 parameters. Some Menu 0 parameters appear twice since their function depends on the operating mode.

The Range - RFC-A / S column applies to both RFC-A and RFC-S. For some parameters, this column applies to only one of these modes, this is indicated accordingly in the Default columns.

In some cases, the function or range of a parameter is affected by the setting of another parameter. The information in the lists relates to the default condition of any parameters affected in this way.

**Table 12-2 Key to parameter table coding**

| Coding      | Attribute                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |
|-------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>RW</b>   | Read/Write: can be written by the user                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
| <b>RO</b>   | Read only: can only be read by the user                                                                                                                                                                                                                                                                                                                                                                                                                                                           |
| <b>Bit</b>  | 1 bit parameter. 'On' or 'Off' on the display                                                                                                                                                                                                                                                                                                                                                                                                                                                     |
| <b>Num</b>  | Number: can be uni-polar or bi-polar                                                                                                                                                                                                                                                                                                                                                                                                                                                              |
| <b>Txt</b>  | Text: the parameter uses text strings instead of numbers.                                                                                                                                                                                                                                                                                                                                                                                                                                         |
| <b>Bin</b>  | Binary parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
| <b>IP</b>   | IP Address parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |
| <b>Mac</b>  | Mac Address parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
| <b>Date</b> | Date parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
| <b>Time</b> | Time parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
| <b>Chr</b>  | Character parameter                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
| <b>FI</b>   | Filtered: some parameters which can have rapidly changing values are filtered when displayed on the drive keypad for easy viewing.                                                                                                                                                                                                                                                                                                                                                                |
| <b>DE</b>   | Destination: This parameter selects the destination of an input or logic function.                                                                                                                                                                                                                                                                                                                                                                                                                |
| <b>RA</b>   | Rating dependent: this parameter is likely to have different values and ranges with drives of different voltage and current ratings. Parameters with this attribute will be transferred to the destination drive by non-volatile storage media when the rating of the destination drive is different from the source drive and the file is a parameter file. However, the values will be transferred if only the current rating is different and the file is a difference from default type file. |
| <b>ND</b>   | No default: The parameter is not modified when defaults are loaded                                                                                                                                                                                                                                                                                                                                                                                                                                |
| <b>NC</b>   | Not copied: not transferred to or from non-volatile media during copying.                                                                                                                                                                                                                                                                                                                                                                                                                         |
| <b>PT</b>   | Protected: cannot be used as a destination.                                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| <b>US</b>   | User save: parameter saved in drive EEPROM when the user initiates a parameter save.                                                                                                                                                                                                                                                                                                                                                                                                              |
| <b>PS</b>   | Power-down save: parameter automatically saved in drive EEPROM when the under volts (UV) state occurs.                                                                                                                                                                                                                                                                                                                                                                                            |

| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Table 12-3 Feature look-up table

| Feature                                | Related parameters (Pr) |                  |        |         |                  |        |        |        |        |                  |        |        |        |
|----------------------------------------|-------------------------|------------------|--------|---------|------------------|--------|--------|--------|--------|------------------|--------|--------|--------|
| Acceleration rates                     | 02.010                  | 02.011 to 02.019 |        | 02.032  | 02.033           | 02.034 | 02.002 |        |        |                  |        |        |        |
| Analog speed reference 1               | 01.036                  | 07.010           | 07.001 | 07.007  | 07.008           | 07.009 | 07.025 | 07.026 | 07.030 |                  |        |        |        |
| Analog speed reference 2               | 01.037                  | 07.014           | 01.041 | 07.002  | 07.011           | 07.012 | 07.013 | 07.029 | 07.031 |                  |        |        |        |
| Analog I/O                             | Menu 7                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Analog input 1                         | 07.001                  | 07.007           | 07.008 | 07.009  | 07.010           | 07.025 | 07.026 | 07.030 |        |                  |        |        |        |
| Analog input 2                         | 07.002                  | 07.011           | 07.012 | 07.013  | 07.014           | 07.029 | 07.031 |        |        |                  |        |        |        |
| Analog input 3                         | 07.003                  | 07.015           | 07.016 | 07.017  | 07.018           | 07.032 |        |        |        |                  |        |        |        |
| Analog output 1                        | 07.019                  | 07.020           |        |         |                  |        |        |        |        |                  |        |        |        |
| Analog output 2                        | 07.022                  | 07.023           |        |         |                  |        |        |        |        |                  |        |        |        |
| Application menu                       | Menu 18                 | Menu 19          |        | Menu 20 |                  |        |        |        |        |                  |        |        |        |
| At speed indicator bit                 | 03.006                  | 03.007           | 03.009 | 10.006  | 10.005           | 10.007 |        |        |        |                  |        |        |        |
| Auto reset                             | 10.034                  | 10.035           | 10.036 | 10.001  |                  |        |        |        |        |                  |        |        |        |
| Autotune                               | 05.010                  | 05.012           | 05.017 | 05.024  | 05.025           | 05.029 | 05.030 | 05.059 | 05.060 | 05.062           |        |        |        |
| Binary sum                             | 09.029                  | 09.030           | 09.031 | 09.032  | 09.033           | 09.034 |        |        |        |                  |        |        |        |
| Bipolar speed                          | 01.010                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Brake control                          | 12.040 to 12.055        |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Braking                                | 10.011                  | 10.010           | 10.030 | 10.031  | 06.001           | 02.004 | 02.002 | 10.012 | 10.039 | 10.040           | 10.061 |        |        |
| Catch a spinning motor                 | 06.009                  | 05.040           |        |         |                  |        |        |        |        |                  |        |        |        |
| Coast to stop                          | 06.001                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Comms                                  | 11.023 to 11.027        |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Copying                                | 11.042                  | 11.036 to 11.040 |        |         |                  |        |        |        |        |                  |        |        |        |
| Cost - per kWh electricity             | 06.016                  | 06.017           | 06.024 | 06.025  | 06.026           | 06.027 | 06.028 |        |        |                  |        |        |        |
| Current controller                     | 04.013                  | 04.014           |        |         |                  |        |        |        |        |                  |        |        |        |
| Current feedback                       | 04.001                  | 04.002           | 04.017 | 04.004  | 04.012           | 04.020 | 04.023 | 04.024 | 04.026 | 10.008           | 10.009 | 10.017 |        |
| Current limits                         | 04.005                  | 04.006           | 04.007 | 04.018  | 04.015           | 04.019 | 04.016 | 05.007 | 05.010 | 10.008           | 10.009 | 10.017 |        |
| DC bus voltage                         | 05.005                  | 02.008           |        |         |                  |        |        |        |        |                  |        |        |        |
| DC injection braking                   | 06.006                  | 06.007           | 06.001 |         |                  |        |        |        |        |                  |        |        |        |
| Deceleration rates                     | 02.020                  | 02.021 to 02.029 |        | 02.004  | 02.035 to 02.037 |        | 02.002 | 02.008 | 06.001 | 10.030           | 10.031 | 10.039 | 02.009 |
| Defaults                               | 11.043                  | 11.046           |        |         |                  |        |        |        |        |                  |        |        |        |
| Digital I/O                            | Menu 8                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Digital I/O read word                  | 08.020                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Digital I/O 1 T24                      | 08.001                  | 08.011           | 08.021 | 08.031  |                  |        |        |        |        |                  |        |        |        |
| Digital I/O 2 T25                      | 08.002                  | 08.012           | 08.022 | 08.032  |                  |        |        |        |        |                  |        |        |        |
| Digital I/O 3 T26                      | 08.003                  | 08.013           | 08.023 | 08.033  |                  |        |        |        |        |                  |        |        |        |
| Digital input 4 T27                    | 08.004                  | 08.014           | 08.024 |         |                  |        |        |        |        |                  |        |        |        |
| Digital input 5 T28                    | 08.005                  | 08.015           | 08.025 |         |                  |        |        |        |        |                  |        |        |        |
| Digital input 6 T29                    | 08.006                  | 08.016           | 08.026 |         |                  |        |        |        |        |                  |        |        |        |
| Digital lock                           | 13.010                  | 13.001 to 13.009 |        |         | 13.011           | 13.012 | 13.016 | 03.022 | 03.023 | 13.019 to 13.023 |        |        |        |
| Digital output T22                     | 08.008                  | 08.018           | 08.028 |         |                  |        |        |        |        |                  |        |        |        |
| Direction                              | 10.013                  | 06.030           | 06.031 | 01.003  | 10.014           | 02.001 | 03.002 | 08.003 | 08.004 | 10.040           |        |        |        |
| Drive active                           | 10.002                  | 10.040           |        |         |                  |        |        |        |        |                  |        |        |        |
| Drive derivative                       | 11.028                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Drive OK                               | 10.001                  | 08.027           | 08.007 | 08.017  | 10.036           | 10.040 |        |        |        |                  |        |        |        |
| Dynamic performance                    | 05.026                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Dynamic V/F                            | 05.013                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Enable                                 | 06.015                  | 08.009           | 08.040 |         |                  |        |        |        |        |                  |        |        |        |
| Encoder reference                      | 03.043                  | 03.044           | 03.045 | 03.046  |                  |        |        |        |        |                  |        |        |        |
| Encoder set-up                         | 03.033                  | 03.034 to 03.042 |        |         | 03.047           | 03.048 |        |        |        |                  |        |        |        |
| External trip                          | 10.032                  | 08.010           | 08.007 |         |                  |        |        |        |        |                  |        |        |        |
| Fan speed                              | 06.045                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Fast disable                           | 06.029                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| Field weakening - induction motor      | 05.029                  | 05.030           | 01.006 | 05.028  | 05.062           | 05.063 |        |        |        |                  |        |        |        |
| Field weakening - servo                | 05.022                  | 01.006           | 05.009 |         |                  |        |        |        |        |                  |        |        |        |
| Filter change                          | 06.019                  | 06.018           | 06.021 | 06.022  | 06.023           |        |        |        |        |                  |        |        |        |
| Frequency reference selection          | 01.014                  | 01.015           |        |         |                  |        |        |        |        |                  |        |        |        |
| Frequency slaving                      | 03.001                  | 03.013           | 03.014 | 03.015  | 03.016           | 03.017 |        |        |        |                  |        |        |        |
| Hard speed reference                   | 03.022                  | 03.023           |        |         |                  |        |        |        |        |                  |        |        |        |
| Heavy duty rating                      | 05.007                  | 11.032           |        |         |                  |        |        |        |        |                  |        |        |        |
| High stability space vector modulation | 05.019                  |                  |        |         |                  |        |        |        |        |                  |        |        |        |
| I/O sequencer                          | 06.030                  | 06.031           | 06.032 | 06.033  | 06.034           | 06.042 | 06.043 | 06.041 |        |                  |        |        |        |
| Inertia compensation                   | 02.038                  | 05.012           | 04.022 | 03.018  |                  |        |        |        |        |                  |        |        |        |

| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Feature                          | Related parameters (Pr) |                  |        |         |        |        |        |                  |        |        |        |  |  |
|----------------------------------|-------------------------|------------------|--------|---------|--------|--------|--------|------------------|--------|--------|--------|--|--|
| Jog reference                    | 01.005                  | 02.019           | 02.029 |         |        |        |        |                  |        |        |        |  |  |
| Keypad reference                 | 01.017                  | 01.014           | 01.043 | 01.051  | 06.012 | 06.013 |        |                  |        |        |        |  |  |
| Kt                               | 05.032                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Limit switches                   | 06.035                  | 06.036           |        |         |        |        |        |                  |        |        |        |  |  |
| Line power supply loss           | 06.003                  | 10.015           | 10.016 | 05.005  | 06.048 |        |        |                  |        |        |        |  |  |
| Local position reference         | 13.020 to 13.023        |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Logic function 1                 | 09.001                  | 09.004           | 09.005 | 09.006  | 09.007 | 09.008 | 09.009 | 09.010           |        |        |        |  |  |
| Logic function 2                 | 09.002                  | 09.014           | 09.015 | 09.016  | 09.017 | 09.018 | 09.019 | 09.020           |        |        |        |  |  |
| Low voltage supply               | 06.044                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Marker pulse                     | 03.032                  | 03.031           |        |         |        |        |        |                  |        |        |        |  |  |
| Maximum speed                    | 01.006                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Menu 0 set-up                    | 11.018 to 11.022        |                  |        | Menu 22 |        |        |        |                  |        |        |        |  |  |
| Minimum speed                    | 01.007                  | 10.004           |        |         |        |        |        |                  |        |        |        |  |  |
| Modules - number of              | 11.035                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Motor map                        | 05.006                  | 05.007           | 05.008 | 05.009  | 05.010 | 05.011 |        |                  |        |        |        |  |  |
| Motor map 2                      | Menu 21                 |                  | 11.45  |         |        |        |        |                  |        |        |        |  |  |
| Motorized potentiometer          | 09.021                  | 09.022           | 09.023 | 09.024  | 09.025 | 09.026 | 09.027 | 09.028           |        |        |        |  |  |
| Offset speed reference           | 01.004                  | 01.038           | 01.009 |         |        |        |        |                  |        |        |        |  |  |
| Onboard PLC                      | 11.047 to 11.051        |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Open loop vector mode            | 05.014                  | 05.017           |        |         |        |        |        |                  |        |        |        |  |  |
| Operating mode                   | 00.048                  | 11.031           | 03.024 | 05.014  |        |        |        |                  |        |        |        |  |  |
| Orientation                      | 13.010                  | 13.013 to 13.015 |        |         |        |        |        |                  |        |        |        |  |  |
| Output                           | 05.001                  | 05.002           | 05.003 | 05.004  |        |        |        |                  |        |        |        |  |  |
| Overspeed threshold              | 03.008                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Phase angle                      | 03.025                  | 05.012           |        |         |        |        |        |                  |        |        |        |  |  |
| PID controller                   | Menu 14                 |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Position feedback - drive        | 03.028                  | 03.029           | 03.030 | 03.050  |        |        |        |                  |        |        |        |  |  |
| Positive logic                   | 08.029                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Power up parameter               | 11.022                  | 11.021           |        |         |        |        |        |                  |        |        |        |  |  |
| Precision reference              | 01.018                  | 01.019           | 01.020 | 01.044  |        |        |        |                  |        |        |        |  |  |
| Preset speeds                    | 01.015                  | 01.021 to 01.028 |        |         | 01.016 | 01.014 | 01.042 | 01.045 to 01.048 |        |        | 01.050 |  |  |
| Programmable logic               | Menu 9                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Quasi square operation           | 05.020                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Ramp (accel / decel) mode        | 02.004                  | 02.008           | 06.001 | 02.002  | 02.003 | 10.030 | 10.031 | 10.039           |        |        |        |  |  |
| Rated speed autotune             | 05.016                  | 05.008           |        |         |        |        |        |                  |        |        |        |  |  |
| Regenerating                     | 10.010                  | 10.011           | 10.030 | 10.031  | 06.001 | 02.004 | 02.002 | 10.012           | 10.039 | 10.040 |        |  |  |
| Relative jog                     | 13.017 to 13.019        |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Relay output                     | 08.007                  | 08.017           | 08.027 |         |        |        |        |                  |        |        |        |  |  |
| Reset                            | 10.033                  | 08.002           | 08.022 | 10.034  | 10.035 | 10.036 | 10.001 | 10.038           |        |        |        |  |  |
| RFC mode (encoder less CLV mode) | 03.024                  | 03.042           | 04.012 |         |        |        |        |                  |        |        |        |  |  |
| S ramp                           | 02.006                  | 02.007           |        |         |        |        |        |                  |        |        |        |  |  |
| Sample rates                     | 05.018                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Safe Torque Off input            | 08.009                  | 08.040           |        |         |        |        |        |                  |        |        |        |  |  |
| Security code                    | 11.030                  | 11.044           |        |         |        |        |        |                  |        |        |        |  |  |
| Serial comms                     | 11.023 to 11.027        |                  |        | 11.020  |        |        |        |                  |        |        |        |  |  |
| Skip speeds                      | 01.029                  | 01.030           | 01.031 | 01.032  | 01.033 | 01.034 | 01.035 |                  |        |        |        |  |  |
| Slip compensation                | 05.027                  | 05.008           |        |         |        |        |        |                  |        |        |        |  |  |
| NV media card                    | 11.036 to 11.040        |                  |        | 11.042  |        |        |        |                  |        |        |        |  |  |
| Firmware version                 | 11.029                  | 11.034           | 11.062 |         |        |        |        |                  |        |        |        |  |  |
| Speed controller                 | 03.010 to 03.017        |                  |        | 03.019  | 03.020 | 03.021 |        |                  |        |        |        |  |  |
| Speed feedback                   | 03.002                  | 03.003           | 03.004 |         |        |        |        |                  |        |        |        |  |  |
| Speed feedback - drive           | 03.026                  | 03.027           | 03.028 | 03.029  | 03.030 | 03.031 | 03.042 |                  |        |        |        |  |  |
| Speed feed forward               | 01.039                  | 01.040           |        |         |        |        |        |                  |        |        |        |  |  |
| Speed reference selection        | 01.014                  | 01.015           | 01.049 | 01.050  | 01.001 |        |        |                  |        |        |        |  |  |
| Status word                      | 10.040                  |                  |        |         |        |        |        |                  |        |        |        |  |  |
| Supply                           | 06.044                  | 05.005           |        |         |        |        |        |                  |        |        |        |  |  |
| Switching frequency              | 05.018                  | 05.035           | 07.034 | 07.035  |        |        |        |                  |        |        |        |  |  |
| Thermal protection - drive       | 05.018                  | 05.035           | 07.004 | 07.005  | 07.006 | 07.034 | 07.035 | 07.036           | 10.018 |        |        |  |  |
| Thermal protection - motor       | 04.015                  | 05.007           | 04.019 | 04.016  | 04.025 | 07.015 |        |                  |        |        |        |  |  |
| Thermistor input                 | 07.003                  | 07.015           | 07.046 | 07.047  | 07.048 | 07.049 | 07.050 |                  |        |        |        |  |  |
| Threshold detector 1             | 12.001                  | 12.003 to 12.007 |        |         |        |        |        |                  |        |        |        |  |  |
| Threshold detector 2             | 12.002                  | 12.023 to 12.027 |        |         |        |        |        |                  |        |        |        |  |  |
| Time - filter change             | 06.019                  | 06.018           | 06.021 | 06.022  | 06.023 |        |        |                  |        |        |        |  |  |
| Time - powered up log            | 06.019                  | 06.020           |        |         |        |        |        |                  |        |        |        |  |  |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Feature                  | Related parameters (Pr) |        |                  |        |        |  |                  |  |  |  |  |  |  |
|--------------------------|-------------------------|--------|------------------|--------|--------|--|------------------|--|--|--|--|--|--|
| Time - run log           | 06.019                  |        |                  |        |        |  |                  |  |  |  |  |  |  |
| Torque                   | 04.003                  | 04.026 | 05.032           |        |        |  |                  |  |  |  |  |  |  |
| Torque mode              | 04.008                  | 04.011 | 04.009           | 04.010 |        |  |                  |  |  |  |  |  |  |
| Trip detection           | 10.037                  | 10.038 | 10.020 to 10.029 |        |        |  |                  |  |  |  |  |  |  |
| Trip log                 | 10.020 to 10.029        |        | 10.041 to 10.060 |        |        |  | 10.070 to 10.079 |  |  |  |  |  |  |
| Under voltage            | 05.005                  | 10.016 | 10.015           |        |        |  |                  |  |  |  |  |  |  |
| V/F mode                 | 05.015                  | 05.014 |                  |        |        |  |                  |  |  |  |  |  |  |
| Variable selector 1      | 12.008 to 12.016        |        |                  |        |        |  |                  |  |  |  |  |  |  |
| Variable selector 2      | 12.028 to 12.036        |        |                  |        |        |  |                  |  |  |  |  |  |  |
| Voltage controller       | 05.031                  |        |                  |        |        |  |                  |  |  |  |  |  |  |
| Voltage mode             | 05.014                  | 05.017 |                  | 05.015 |        |  |                  |  |  |  |  |  |  |
| Voltage rating           | 11.033                  | 05.009 | 05.005           |        |        |  |                  |  |  |  |  |  |  |
| Voltage supply           | 06.044                  |        | 05.005           |        |        |  |                  |  |  |  |  |  |  |
| Warning                  | 10.019                  | 10.012 | 10.017           | 10.018 | 10.040 |  |                  |  |  |  |  |  |  |
| Zero speed indicator bit | 03.005                  | 10.003 |                  |        |        |  |                  |  |  |  |  |  |  |

## 12.1 Parameter ranges and Variable minimum/maximums

Some parameters in the drive have a variable range with a variable minimum and a variable maximum value which is dependent on one of the following:

- The settings of other parameters
- The drive rating
- The drive mode
- Combination of any of the above

The tables below give the definition of variable minimum/maximum and the maximum range of these.

| VM_AC_VOLTAGE  |                                                                                                | Range applied to parameters showing AC voltage |
|----------------|------------------------------------------------------------------------------------------------|------------------------------------------------|
| Units          | V                                                                                              |                                                |
| Range of [MIN] | 0                                                                                              |                                                |
| Range of [MAX] | 0 to 930                                                                                       |                                                |
| Definition     | VM_AC_VOLTAGE[MAX] is drive voltage rating dependent. See Table 12-4<br>VM_AC_VOLTAGE[MIN] = 0 |                                                |

| VM_AC_VOLTAGE_SET |                                                                                                | Range applied to the AC voltage set-up parameters |
|-------------------|------------------------------------------------------------------------------------------------|---------------------------------------------------|
| Units             | V                                                                                              |                                                   |
| Range of [MIN]    | 0                                                                                              |                                                   |
| Range of [MAX]    | 0 to 690                                                                                       |                                                   |
| Definition        | VM_AC_VOLTAGE[MAX] is drive voltage rating dependent. See Table 12-4<br>VM_AC_VOLTAGE[MIN] = 0 |                                                   |

| VM_ACCEL_RATE  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Maximum applied to the ramp rate parameters |
|----------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------|
| Units          | s / 100 Hz, s / 1000 rpm, s / 1000 mm/s                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                                             |
| Range of [MIN] | Open-loop: 0.0<br>RFC-A, RFC-S: 0.000                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                             |
| Range of [MAX] | Open-loop: 0.0 to 3200.0<br>RFC-A, RFC-S: 0.000 to 3200.000                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                             |
| Definition     | <p>Open-loop mode</p> <p>If <i>Ramp Rate Units</i> (02.039) = 0:<br/>VM_ACCEL_RATE[MAX] = 3200.0</p> <p>If <i>Ramp Rate Units</i> (02.039) = 1:<br/>VM_ACCEL_RATE[MAX] = 3200.0 x Pr <b>01.006</b> / 100.0</p> <p>VM_ACCEL_RATE[MIN] = 0.0</p> <p>RFC-A, RFC-S modes</p> <p>If <i>Ramp Rate Units</i> (02.039) = 0:<br/>VM_ACCEL_RATE[MAX] = 3200.000</p> <p>If <i>Ramp Rate Units</i> (02.039) = 1:<br/>VM_ACCEL_RATE[MAX] = 3200.000 x Pr <b>01.006</b> / 1000.0</p> <p>VM_ACCEL_RATE[MIN] = 0.000</p> <p>If the second motor map is selected (Pr <b>11.045</b> = 1) Pr <b>21.001</b> is used instead of Pr <b>01.006</b>.</p> |                                             |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| VM_AMC_JERK_UNIPOLAR |                                                                                                                        | Range applied to the parameters showing the AMC jerk |
|----------------------|------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------|
| Units                | User units / ms / ms / ms                                                                                              |                                                      |
| Range of [MIN]       | 0                                                                                                                      |                                                      |
| Range of [MAX]       | 107374.1823                                                                                                            |                                                      |
| Definition           | VM_AMC_JERK_UNIPOLAR[MAX] = 107374.1823 / <i>AMC Auto Resolution Scaling</i> (31.016)<br>VM_AMC_JERK_UNIPOLAR[MIN] = 0 |                                                      |

| VM_AMC_POSITION              |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | Range applied to the parameters showing the AMC position |                              |     |     |                      |                                                          |                                         |                      |                                                           |   |
|------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------|------------------------------|-----|-----|----------------------|----------------------------------------------------------|-----------------------------------------|----------------------|-----------------------------------------------------------|---|
| Unit                         | User units                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                          |                              |     |     |                      |                                                          |                                         |                      |                                                           |   |
| Range of [MIN]               | -2147483648                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                                          |                              |     |     |                      |                                                          |                                         |                      |                                                           |   |
| Range of [MAX]               | 2147483647                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                          |                              |     |     |                      |                                                          |                                         |                      |                                                           |   |
| Definition                   | VM_AMC_POSITION is modified by <i>AMC Auto Resolution Scaling</i> (31.016) and <i>AMC Roll Over Limit</i> (31.010). See the table below. <table border="1"> <thead> <tr> <th>AMC Roll Over Limit (31.010)</th><th>= 0</th><th>&gt; 0</th></tr> </thead> <tbody> <tr> <td>VM_AMC_POSITION[MAX]</td><td>2147483647 / <i>AMC Auto Resolution Scaling</i> (31.016)</td><td><i>AMC Roll Over Limit</i> (31.010) - 1</td></tr> <tr> <td>VM_AMC_POSITION[MIN]</td><td>-2147483648 / <i>AMC Auto Resolution Scaling</i> (31.016)</td><td>0</td></tr> </tbody> </table> |                                                          | AMC Roll Over Limit (31.010) | = 0 | > 0 | VM_AMC_POSITION[MAX] | 2147483647 / <i>AMC Auto Resolution Scaling</i> (31.016) | <i>AMC Roll Over Limit</i> (31.010) - 1 | VM_AMC_POSITION[MIN] | -2147483648 / <i>AMC Auto Resolution Scaling</i> (31.016) | 0 |
| AMC Roll Over Limit (31.010) | = 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | > 0                                                      |                              |     |     |                      |                                                          |                                         |                      |                                                           |   |
| VM_AMC_POSITION[MAX]         | 2147483647 / <i>AMC Auto Resolution Scaling</i> (31.016)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | <i>AMC Roll Over Limit</i> (31.010) - 1                  |                              |     |     |                      |                                                          |                                         |                      |                                                           |   |
| VM_AMC_POSITION[MIN]         | -2147483648 / <i>AMC Auto Resolution Scaling</i> (31.016)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | 0                                                        |                              |     |     |                      |                                                          |                                         |                      |                                                           |   |

| VM_AMC_POSITION_CAM          |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Range applied to the parameters showing the AMC cam position |                              |     |     |                          |                                                          |                                         |                          |                                                           |                                           |
|------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------|------------------------------|-----|-----|--------------------------|----------------------------------------------------------|-----------------------------------------|--------------------------|-----------------------------------------------------------|-------------------------------------------|
| Unit                         | User units                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                              |                              |     |     |                          |                                                          |                                         |                          |                                                           |                                           |
| Range of [MIN]               | -1073741824                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |                                                              |                              |     |     |                          |                                                          |                                         |                          |                                                           |                                           |
| Range of [MAX]               | 1073741823                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                              |                              |     |     |                          |                                                          |                                         |                          |                                                           |                                           |
| Definition                   | VM_AMC_POSITION_CAM is modified by <i>AMC Auto Resolution Scaling</i> (31.016) and <i>AMC Roll Over Limit</i> (31.010). See the table below. <table border="1"> <thead> <tr> <th>AMC Roll Over Limit (31.010)</th><th>= 0</th><th>&gt; 0</th></tr> </thead> <tbody> <tr> <td>VM_AMC_POSITION_CAM[MAX]</td><td>1073741823 / <i>AMC Auto Resolution Scaling</i> (31.016)</td><td><i>AMC Roll Over Limit</i> (31.010) - 1</td></tr> <tr> <td>VM_AMC_POSITION_CAM[MIN]</td><td>-1073741824 / <i>AMC Auto Resolution Scaling</i> (31.016)</td><td>-<i>AMC Roll Over Limit</i> (31.010) + 1</td></tr> </tbody> </table> |                                                              | AMC Roll Over Limit (31.010) | = 0 | > 0 | VM_AMC_POSITION_CAM[MAX] | 1073741823 / <i>AMC Auto Resolution Scaling</i> (31.016) | <i>AMC Roll Over Limit</i> (31.010) - 1 | VM_AMC_POSITION_CAM[MIN] | -1073741824 / <i>AMC Auto Resolution Scaling</i> (31.016) | - <i>AMC Roll Over Limit</i> (31.010) + 1 |
| AMC Roll Over Limit (31.010) | = 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | > 0                                                          |                              |     |     |                          |                                                          |                                         |                          |                                                           |                                           |
| VM_AMC_POSITION_CAM[MAX]     | 1073741823 / <i>AMC Auto Resolution Scaling</i> (31.016)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | <i>AMC Roll Over Limit</i> (31.010) - 1                      |                              |     |     |                          |                                                          |                                         |                          |                                                           |                                           |
| VM_AMC_POSITION_CAM[MIN]     | -1073741824 / <i>AMC Auto Resolution Scaling</i> (31.016)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | - <i>AMC Roll Over Limit</i> (31.010) + 1                    |                              |     |     |                          |                                                          |                                         |                          |                                                           |                                           |

| VM_AMC_POSITION_CAM_UNIPOLAR      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | Unipolar version of VM_AMC_POSITION_CAM |                              |     |     |                                   |                                                          |                                         |                                   |   |   |
|-----------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------|------------------------------|-----|-----|-----------------------------------|----------------------------------------------------------|-----------------------------------------|-----------------------------------|---|---|
| Unit                              | User units                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                         |                              |     |     |                                   |                                                          |                                         |                                   |   |   |
| Range of [MIN]                    | 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |                                         |                              |     |     |                                   |                                                          |                                         |                                   |   |   |
| Range of [MAX]                    | 1073741823                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                         |                              |     |     |                                   |                                                          |                                         |                                   |   |   |
| Definition                        | VM_AMC_POSITION_CAM_UNIPOLAR is modified by <i>AMC Auto Resolution Scaling</i> (31.016) and <i>AMC Roll Over Limit</i> (31.010). See the table below. <table border="1"> <thead> <tr> <th>AMC Roll Over Limit (31.010)</th><th>= 0</th><th>&gt; 0</th></tr> </thead> <tbody> <tr> <td>VM_AMC_POSITION_CAM_UNIPOLAR[MAX]</td><td>1073741823 / <i>AMC Auto Resolution Scaling</i> (31.016)</td><td><i>AMC Roll Over Limit</i> (31.010) - 1</td></tr> <tr> <td>VM_AMC_POSITION_CAM_UNIPOLAR[MIN]</td><td>0</td><td>0</td></tr> </tbody> </table> |                                         | AMC Roll Over Limit (31.010) | = 0 | > 0 | VM_AMC_POSITION_CAM_UNIPOLAR[MAX] | 1073741823 / <i>AMC Auto Resolution Scaling</i> (31.016) | <i>AMC Roll Over Limit</i> (31.010) - 1 | VM_AMC_POSITION_CAM_UNIPOLAR[MIN] | 0 | 0 |
| AMC Roll Over Limit (31.010)      | = 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | > 0                                     |                              |     |     |                                   |                                                          |                                         |                                   |   |   |
| VM_AMC_POSITION_CAM_UNIPOLAR[MAX] | 1073741823 / <i>AMC Auto Resolution Scaling</i> (31.016)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | <i>AMC Roll Over Limit</i> (31.010) - 1 |                              |     |     |                                   |                                                          |                                         |                                   |   |   |
| VM_AMC_POSITION_CAM_UNIPOLAR[MIN] | 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | 0                                       |                              |     |     |                                   |                                                          |                                         |                                   |   |   |

| VM_AMC_POSITION_REF |                                                                                                                                                                               | Range applied to the AMC position reference               |                                         |                                                           |
|---------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------|-----------------------------------------|-----------------------------------------------------------|
| Unit                | User units                                                                                                                                                                    |                                                           |                                         |                                                           |
| Range of [MIN]      | -2147483648                                                                                                                                                                   |                                                           |                                         |                                                           |
| Range of [MAX]      | 2147483647                                                                                                                                                                    |                                                           |                                         |                                                           |
| Definition          | VM_AMC_POSITION_REF is modified by <i>AMC Auto Resolution Scaling</i> (31.016), <i>AMC Roll Over Limit</i> (31.010) and <i>AMC Rotary Mode</i> (34.005). See the table below. |                                                           |                                         |                                                           |
|                     | AMC Roll Over Limit (31.010)                                                                                                                                                  | = 0                                                       | > 0                                     | > 0                                                       |
|                     | AMC Rotary Mode (34.005)                                                                                                                                                      | Not active                                                | < 4                                     | = 4                                                       |
|                     | VM_AMC_POSITION_REF[MAX]                                                                                                                                                      | 2147483647 / <i>AMC Auto Resolution Scaling</i> (31.016)  | <i>AMC Roll Over Limit</i> (31.010) - 1 | 1073741823 / <i>AMC Auto Resolution Scaling</i> (31.016)  |
|                     | VM_AMC_POSITION_REF[MIN]                                                                                                                                                      | -2147483648 / <i>AMC Auto Resolution Scaling</i> (31.016) | 0                                       | -1073741824 / <i>AMC Auto Resolution Scaling</i> (31.016) |
|                     |                                                                                                                                                                               |                                                           |                                         |                                                           |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| VM_AMC_POSITION_UNIPOLAR |                                                                                                                                                   | Unipolar version of VM_AMC_POSITION                      |                                         |
|--------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------|-----------------------------------------|
| Unit                     | User units                                                                                                                                        |                                                          |                                         |
| Range of [MIN]           | 0                                                                                                                                                 |                                                          |                                         |
| Range of [MAX]           | 2147483647                                                                                                                                        |                                                          |                                         |
| Definition               | VM_AMC_POSITION_UNIPOLAR is modified by <i>AMC Auto Resolution Scaling</i> (31.016) and <i>AMC Roll Over Limit</i> (31.010). See the table below. |                                                          |                                         |
|                          | AMC Roll Over Limit (31.010)                                                                                                                      | = 0                                                      | > 0                                     |
|                          | VM_AMC_POSITION_UNIPOLAR[MAX]                                                                                                                     | 2147483647 / <i>AMC Auto Resolution Scaling</i> (31.016) | <i>AMC Roll Over Limit</i> (31.010) - 1 |
|                          | VM_AMC_POSITION_UNIPOLAR[MIN]                                                                                                                     | 0                                                        | 0                                       |

| VM_AMC_RATE    |                                                                                       | Range applied to the parameters showing the AMC acceleration |
|----------------|---------------------------------------------------------------------------------------|--------------------------------------------------------------|
| Unit           | User units / ms / ms                                                                  |                                                              |
| Range of [MIN] | 1073742.824                                                                           |                                                              |
| Range of [MAX] | 1073741.823                                                                           |                                                              |
| Definition     | VM_AMC_RATE_UNIPOLAR[MAX] = 1073741.823 / <i>AMC Auto Resolution Scaling</i> (31.016) |                                                              |
|                | VM_AMC_RATE_UNIPOLAR[MIN] = 1073741.824 / <i>AMC Auto Resolution Scaling</i> (31.016) |                                                              |

| VM_AMC_RATE_UNIPOLAR |                                                                                       | Unipolar version of VM_AMC_RATE |
|----------------------|---------------------------------------------------------------------------------------|---------------------------------|
| Unit                 | User units / ms / ms                                                                  |                                 |
| Range of [MIN]       | 0                                                                                     |                                 |
| Range of [MAX]       | 1073741.823                                                                           |                                 |
| Definition           | VM_AMC_RATE_UNIPOLAR[MAX] = 1073741.823 / <i>AMC Auto Resolution Scaling</i> (31.016) |                                 |
|                      | VM_AMC_RATE_UNIPOLAR[MIN] = 0                                                         |                                 |

| VM_AMC_ROLLOVER |                                                                                 | Maximum applied to the AMC Rollover parameter |
|-----------------|---------------------------------------------------------------------------------|-----------------------------------------------|
| Unit            | User units / ms / ms                                                            |                                               |
| Range of [MIN]  | 0                                                                               |                                               |
| Range of [MAX]  | 1073741823                                                                      |                                               |
| Definition      | VM_AMC_ROLLOVER[MAX] = 1073741823 / <i>AMC Auto Resolution Scaling</i> (31.016) |                                               |
|                 | VM_AMC_ROLLOVER[MIN] = 0                                                        |                                               |

| VM_AMC_SPEED   |                                                                                | Range applied to the parameters showing the AMC speed |
|----------------|--------------------------------------------------------------------------------|-------------------------------------------------------|
| Unit           | User units / ms / ms                                                           |                                                       |
| Range of [MIN] | -21474836.48                                                                   |                                                       |
| Range of [MAX] | 21474836.47                                                                    |                                                       |
| Definition     | VM_AMC_SPEED[MAX] = 21474836.47 / <i>AMC Auto Resolution Scaling</i> (31.016)  |                                                       |
|                | VM_AMC_SPEED[MIN] = -21474836.48 / <i>AMC Auto Resolution Scaling</i> (31.016) |                                                       |

| VM_AMC_SPEED_UNIPOLAR |                                                                                    | Unipolar version of VM_AMC_SPEED |
|-----------------------|------------------------------------------------------------------------------------|----------------------------------|
| Unit                  | User units / ms                                                                    |                                  |
| Range of [MIN]        | 0                                                                                  |                                  |
| Range of [MAX]        | 21474836.47                                                                        |                                  |
| Definition            | VM_SPEED_UNIPOLAR[MAX] = 21474836.47 / <i>AMC Auto Resolution Scaling</i> (31.016) |                                  |
|                       | VM_SPEED_UNIPOLAR[MIN] = 0                                                         |                                  |

| VM_DC_VOLTAGE  |                                                                                                                                                                        | Range applied to parameters showing DC voltage |
|----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------|
| Units          | V                                                                                                                                                                      |                                                |
| Range of [MIN] | 0                                                                                                                                                                      |                                                |
| Range of [MAX] | 0 to 1190                                                                                                                                                              |                                                |
| Definition     | VM_DC_VOLTAGE[MAX] is the full scale d.c. link voltage feedback (over voltage trip level) for the drive. This level is drive voltage rating dependent. See Table 12-4. |                                                |
|                | VM_DC_VOLTAGE[MIN] = 0                                                                                                                                                 |                                                |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| VM_DC_VOLTAGE_SET |                                                                                                         | Range applied to DC voltage reference parameters |
|-------------------|---------------------------------------------------------------------------------------------------------|--------------------------------------------------|
| Units             | V                                                                                                       |                                                  |
| Range of [MIN]    | 0                                                                                                       |                                                  |
| Range of [MAX]    | 0 to 1150                                                                                               |                                                  |
| Definition        | VM_DC_VOLTAGE_SET[MAX] is drive voltage rating dependent. See Table 12-4.<br>VM_DC_VOLTAGE_SET[MIN] = 0 |                                                  |

| VM_DRIVE_CURRENT |                                                                                                                                                                                                         | Range applied to parameters showing current in A |
|------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------|
| Units            | A                                                                                                                                                                                                       |                                                  |
| Range of [MIN]   | -99999.999 to 0.000                                                                                                                                                                                     |                                                  |
| Range of [MAX]   | 0.000 to 99999.999                                                                                                                                                                                      |                                                  |
| Definition       | VM_DRIVE_CURRENT[MAX] is equivalent to the full scale (over current trip level) for the drive and is given by <i>Full Scale Current Kc</i> (11.061).<br>VM_DRIVE_CURRENT[MIN] = - VM_DRIVE_CURRENT[MAX] |                                                  |

| VM_DRIVE_CURRENT_UNIPOLAR |                                                                                                  | Unipolar version of VM_DRIVE_CURRENT |
|---------------------------|--------------------------------------------------------------------------------------------------|--------------------------------------|
| Units                     | A                                                                                                |                                      |
| Range of [MIN]            | 0.000                                                                                            |                                      |
| Range of [MAX]            | 0.000 to 99999.999                                                                               |                                      |
| Definition                | VM_DRIVE_CURRENT_UNIPOLAR[MAX] = VM_DRIVE_CURRENT[MAX]<br>VM_DRIVE_CURRENT_UNIPOLAR[MIN] = 0.000 |                                      |

| VM_HIGH_DC_VOLTAGE |                                                                                                                                                                                                                                           | Range applied to parameters showing high DC voltage |
|--------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------|
| Units              | V                                                                                                                                                                                                                                         |                                                     |
| Range of [MIN]     | 0                                                                                                                                                                                                                                         |                                                     |
| Range of [MAX]     | 0 to 1500                                                                                                                                                                                                                                 |                                                     |
| Definition         | VM_HIGH_DC_VOLTAGE[MAX] is the full scale d.c. link voltage feedback for the high d.c. link voltage measurement which can measure the voltage if it goes above the normal full scale value. See Table 12-4<br>VM_HIGH_DC_VOLTAGE[MIN] = 0 |                                                     |

| VM_LOW_UNDER_VOLTS |                                                                                                                                                                                                                                              | Range applied to the low under-voltage threshold |
|--------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------|
| Units              | V                                                                                                                                                                                                                                            |                                                  |
| Range of [MIN]     | 24                                                                                                                                                                                                                                           |                                                  |
| Range of [MAX]     | 24 to 1150                                                                                                                                                                                                                                   |                                                  |
| Definition         | If <i>Back-up Mode Enable</i> (06.068) = 0:<br>VM_LOW_UNDER_VOLTS[MAX] = VM_STD_UNDER_VOLTS[MIN]<br>If <i>Back-up Mode Enable</i> (06.068) = 1:<br>VM_LOW_UNDER_VOLTS[MAX] = VM_STD_UNDER_VOLTS[MIN] / 1.1.<br>VM_LOW_UNDER_VOLTS[MIN] = 24. |                                                  |

| VM_MIN_SWITCHING_FREQUENCY |                                                                                                                                                                                            | Range applied to the minimum switching frequency parameter |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------|
| Units                      | User units                                                                                                                                                                                 |                                                            |
| Range of [MIN]             | 0                                                                                                                                                                                          |                                                            |
| Range of [MAX]             | 0 to 6                                                                                                                                                                                     |                                                            |
| Definition                 | VM_MIN_SWITCHING_FREQUENCY[MAX] = <i>Maximum Switching Frequency</i> (05.018)<br>VM_MIN_SWITCHING_FREQUENCY[MIN] = 0 for motor control modes, or 1 for Regen mode (subject to the maximum) |                                                            |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| VM_MOTOR1_CURRENT_LIMIT<br>VM_MOTOR2_CURRENT_LIMIT |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | Range applied to current limit parameters |
|----------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------|
| Units                                              | %                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                           |
| Range of [MIN]                                     | 0.0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                           |
| Range of [MAX]                                     | 0.0 to 1000.0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                           |
| Definition                                         | <p>VM_MOTOR1_CURRENT_LIMIT[MIN] = 0.0</p> <p><b>Open-loop</b><br/> <math>VM\_MOTOR1\_CURRENT\_LIMIT[MAX] = (I_{Tlimit} / I_{Trated}) \times 100 \%</math><br/> Where:<br/> <math>I_{Tlimit} = I_{MaxRef} \times \cos(\sin^{-1}(I_{Mrated} / I_{MaxRef}))</math><br/> <math>I_{Mrated} = Pr\ 05.007 \sin \phi</math><br/> <math>I_{Trated} = Pr\ 05.007 \times \cos \phi</math><br/> <math>\cos \phi = Pr\ 05.010</math><br/> <math>I_{MaxRef}</math> is 0.7 x Pr 11.061 when the motor rated current set in Pr 05.007 is less than or equal to Pr 11.032 (i.e. Heavy duty), otherwise it is the lower of 0.7 x Pr 11.061 or 1.1 x Pr 11.060 (i.e. Normal duty).</p> <p><b>RFC-A</b><br/> <math>VM\_MOTOR1\_CURRENT\_LIMIT[MAX] = (I_{Tlimit} / I_{Trated}) \times 100 \%</math><br/> Where:<br/> <math>I_{Tlimit} = I_{MaxRef} \times \cos(\sin^{-1}(I_{Mrated} / I_{MaxRef}))</math><br/> <math>I_{Mrated} = Pr\ 05.007 \times \sin \phi_1</math><br/> <math>I_{Trated} = Pr\ 05.007 \times \cos \phi_1</math><br/> <math>\phi_1 = \cos^{-1}(Pr\ 05.010) + \phi_2</math>. <math>\phi_1</math> is calculated during an autotune. See the variable minimum / maximum calculations in the <i>Parameter Reference Guide</i> for more information regarding <math>\phi_2</math>.<br/> <math>I_{MaxRef}</math> is 0.9 x Pr 11.061 when the motor rated current set in Pr 05.007 is less than or equal to Pr 11.032 (i.e. Heavy duty), otherwise it is the lower of 0.9 x Pr 11.061 or 1.1 x Pr 11.060 (i.e. Normal duty).</p> <p><b>RFC-S and Regen</b><br/> <math>VM\_MOTOR1\_CURRENT\_LIMIT[MAX] = (I_{MaxRef} / Pr\ 05.007) \times 100 \%</math><br/> Where:<br/> <math>I_{MaxRef}</math> is 0.9 x Pr 11.061 when the motor rated current set in Pr 05.007 is less than or equal to Pr 11.032 (i.e. Heavy duty), otherwise it is the lower of 0.9 x Pr 11.061 or 1.1 x Pr 11.060 (i.e. Normal duty).</p> <p>For VM_MOTOR2_CURRENT_LIMIT[MAX] use Pr 21.007 instead of Pr 05.007 and Pr 21.010 instead of Pr 05.010.</p> |                                           |

| VM_NEGATIVE_REF_CLAMP1<br>VM_NEGATIVE_REF_CLAMP2                                                                     |                                                                                                                                                                                                                                                                                                                                                                                                                | Limits applied to the negative frequency or speed clamp |                              |                                                 |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |
|----------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------|------------------------------|-------------------------------------------------|------------------------------------------|-----------------------------|-----------------------------|---|---|-----|------------------|---|---|-----|-----|---|---|------------------------------|-----|
| Units                                                                                                                | Open-loop: Hz<br>RFC-A, RFC-S: rpm or mm/s                                                                                                                                                                                                                                                                                                                                                                     |                                                         |                              |                                                 |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |
| Range of [MIN]                                                                                                       | Open-loop: -599.0 to 0.0<br>RFC-A, RFC-S: -50000.0 to 0.0                                                                                                                                                                                                                                                                                                                                                      |                                                         |                              |                                                 |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |
| Range of [MAX]                                                                                                       | Open-loop: 0.0 to 599.0<br>RFC-A, RFC-S: 0.0 to 50000.0                                                                                                                                                                                                                                                                                                                                                        |                                                         |                              |                                                 |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |
| Definition                                                                                                           | <table><tr><th><i>Negative Reference Clamp Enable (01.008)</i></th><th><i>Bipolar Reference Enable (01.010)</i></th><th>VM_NEGATIVE_REF_CLAMP1[MIN]</th><th>VM_NEGATIVE_REF_CLAMP1[MAX]</th></tr><tr><td>0</td><td>0</td><td>0.0</td><td>Pr <b>01.006</b></td></tr><tr><td>0</td><td>1</td><td>0.0</td><td>0.0</td></tr><tr><td>1</td><td>X</td><td>-VM_POSITIVE_REF_CLAMP1[MAX]</td><td>0.0</td></tr></table> |                                                         |                              | <i>Negative Reference Clamp Enable (01.008)</i> | <i>Bipolar Reference Enable (01.010)</i> | VM_NEGATIVE_REF_CLAMP1[MIN] | VM_NEGATIVE_REF_CLAMP1[MAX] | 0 | 0 | 0.0 | Pr <b>01.006</b> | 0 | 1 | 0.0 | 0.0 | 1 | X | -VM_POSITIVE_REF_CLAMP1[MAX] | 0.0 |
|                                                                                                                      | <i>Negative Reference Clamp Enable (01.008)</i>                                                                                                                                                                                                                                                                                                                                                                | <i>Bipolar Reference Enable (01.010)</i>                | VM_NEGATIVE_REF_CLAMP1[MIN]  | VM_NEGATIVE_REF_CLAMP1[MAX]                     |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |
|                                                                                                                      | 0                                                                                                                                                                                                                                                                                                                                                                                                              | 0                                                       | 0.0                          | Pr <b>01.006</b>                                |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |
|                                                                                                                      | 0                                                                                                                                                                                                                                                                                                                                                                                                              | 1                                                       | 0.0                          | 0.0                                             |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |
|                                                                                                                      | 1                                                                                                                                                                                                                                                                                                                                                                                                              | X                                                       | -VM_POSITIVE_REF_CLAMP1[MAX] | 0.0                                             |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |
| VM_NEGATIVE_REF_CLAMP2 is defined in the same way except that Pr <b>21.001</b> is used instead of Pr <b>01.006</b> . |                                                                                                                                                                                                                                                                                                                                                                                                                |                                                         |                              |                                                 |                                          |                             |                             |   |   |     |                  |   |   |     |     |   |   |                              |     |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| VM_POSITIVE_REF_CLAMP1<br>VM_POSITIVE_REF_CLAMP2                                                                                                                                   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Limits applied to the positive frequency or speed reference clamp                                |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------|-----------------|-----------------------------|-----------------|----------------------------------------------------------------------------------------------|-------------------------------|--------------------------------------------------------------------------------------------------|------------------------------------------------|--------------------------------------------------------------------------------------------|----------|-----------------------------------------------|------------------|---------------------|
| Units                                                                                                                                                                              | Open-loop: Hz<br>RFC-A, RFC-S: rpm or mm/s                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
| Range of [MIN]                                                                                                                                                                     | Open-loop: 0.0<br>RFC-A, RFC-S: 0.0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
| Range of [MAX]                                                                                                                                                                     | Open-loop: 599.0<br>RFC-A, RFC-S: 0.0 to 550 x 60 / Motor pole pairs                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
| Definition                                                                                                                                                                         | VM_POSITIVE_REF_CLAMP1[MAX] defines the range of the positive reference clamp, <i>Maximum Reference Clamp</i> (01.006), which in turn limit the references. In RFC-A and RFC-S modes a limit is applied so that the position feedback does not exceed the speed where the drive can no longer interpret the feedback signal correctly as given in the table below. The limit is based on the position feedback device selected with <i>Motor Control Feedback Select</i> (03.026). It is possible to disable this limit if the <i>RFC Feedback Mode</i> (03.024) $\geq 1$ (i.e. VM_POSITIVE_REF_CLAMP1 = 50000.0), so that the motor can be operated at a speed above the level where the drive can interpret the feedback in sensorless mode. It should be noted that the position feedback device itself may have a maximum speed limit that is lower than those given in the table. Care should be taken not to exceed a speed that would cause damage to the position feedback device. |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
|                                                                                                                                                                                    | <table><tr><th>Feedback device</th><th>VM_POSITIVE_REF_CLAMP1[MAX]</th></tr><tr><td>AB,<br/>AB Servo</td><td>(500 kHz x 60 / rotary lines per revolution) rpm<br/>(500 kHz x linear line pitch in mm) mm/s</td></tr><tr><td>FD, FR,<br/>FD Servo, FR Servo</td><td>(500 kHz x 60 / rotary lines per revolution)/2 rpm<br/>(500 kHz x linear line pitch in mm)/2 mm/s</td></tr><tr><td>SC,<br/>SC Hiper, SC EnDat,<br/>SC SSI, SC Servo</td><td>(500 kHz x 60 / sine waves per revolution) rpm<br/>(500 kHz x linear line pitch in mm) mm/s</td></tr><tr><td>Resolver</td><td>30000 rpm<br/>(250 Hz x pole pitch in mm) mm/s</td></tr><tr><td>Any other device</td><td>50000.0 rpm or mm/s</td></tr></table>                                                                                                                                                                                                                                                                                |                                                                                                  | Feedback device | VM_POSITIVE_REF_CLAMP1[MAX] | AB,<br>AB Servo | (500 kHz x 60 / rotary lines per revolution) rpm<br>(500 kHz x linear line pitch in mm) mm/s | FD, FR,<br>FD Servo, FR Servo | (500 kHz x 60 / rotary lines per revolution)/2 rpm<br>(500 kHz x linear line pitch in mm)/2 mm/s | SC,<br>SC Hiper, SC EnDat,<br>SC SSI, SC Servo | (500 kHz x 60 / sine waves per revolution) rpm<br>(500 kHz x linear line pitch in mm) mm/s | Resolver | 30000 rpm<br>(250 Hz x pole pitch in mm) mm/s | Any other device | 50000.0 rpm or mm/s |
|                                                                                                                                                                                    | Feedback device                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | VM_POSITIVE_REF_CLAMP1[MAX]                                                                      |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
|                                                                                                                                                                                    | AB,<br>AB Servo                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | (500 kHz x 60 / rotary lines per revolution) rpm<br>(500 kHz x linear line pitch in mm) mm/s     |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
|                                                                                                                                                                                    | FD, FR,<br>FD Servo, FR Servo                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | (500 kHz x 60 / rotary lines per revolution)/2 rpm<br>(500 kHz x linear line pitch in mm)/2 mm/s |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
|                                                                                                                                                                                    | SC,<br>SC Hiper, SC EnDat,<br>SC SSI, SC Servo                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | (500 kHz x 60 / sine waves per revolution) rpm<br>(500 kHz x linear line pitch in mm) mm/s       |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
|                                                                                                                                                                                    | Resolver                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 30000 rpm<br>(250 Hz x pole pitch in mm) mm/s                                                    |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
|                                                                                                                                                                                    | Any other device                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | 50000.0 rpm or mm/s                                                                              |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
| In open-loop mode VM_POSITIVE_REF_CLAMP1[MAX] is fixed at 599.0 Hz                                                                                                                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
| In RFC mode a limit is applied to the speed reference of 550 x 60 / Motor pole pairs. Therefore, with a 4 pole motor the limit for VM_POSITIVE_REF_CLAMP1[MAX] will be 16,500 rpm. |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
| VM_POSITIVE_REF_CLAMP1[MIN] = 0.0                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
| VM_POSITIVE_REF_CLAMP2 is defined in the same way as VM_POSITIVE_REF_CLAMP1 except                                                                                                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |
| VM_POSITIVE_REF_CLAMP2[MAX] defines the range of the positive reference clamp, <i>M2 Maximum Reference Clamp</i> (21.001), which in turn limits the references.                    |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                  |                 |                             |                 |                                                                                              |                               |                                                                                                  |                                                |                                                                                            |          |                                               |                  |                     |

| VM_POWER       |                                                                                                                                                                                                        | Range applied to parameters that either set or display power |
|----------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------|
| Units          | kW                                                                                                                                                                                                     |                                                              |
| Range of [MIN] | -99999.999 to 0.000                                                                                                                                                                                    |                                                              |
| Range of [MAX] | 0.000 to 99999.999                                                                                                                                                                                     |                                                              |
| Definition     | VM_POWER[MAX] is rating dependent and is chosen to allow for the maximum power that can be output by the drive with maximum a.c. output voltage, at maximum controlled current and unity power factor. |                                                              |
|                | $VM\_POWER[MAX] = \sqrt{3} \times VM\_AC\_VOLTAGE[MAX] \times VM\_DRIVE\_CURRENT[MAX] / 1000$                                                                                                          |                                                              |
|                | VM_POWER[MIN] = -VM_POWER[MAX]                                                                                                                                                                         |                                                              |

| VM_RATED_CURRENT |                                                                                                                                                   | Range applied to rated current parameters |
|------------------|---------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------|
| Units            | A                                                                                                                                                 |                                           |
| Range of [MIN]   | 0.000                                                                                                                                             |                                           |
| Range of [MAX]   | 0.000 to 99999.999                                                                                                                                |                                           |
| Definition       | VM_RATED_CURRENT [MAX] = <i>Maximum Rated Current</i> (11.060) and is dependent on the drive rating. This is the Normal Duty rating of the drive. |                                           |
|                  | VM_RATED_CURRENT [MIN] = 0.000                                                                                                                    |                                           |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| VM_REGEN_REACTIVE |                                                                                                                                                                                                                                       | Range applied to the reactive current reference in Regen mode |
|-------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------|
| Units             | %                                                                                                                                                                                                                                     |                                                               |
| Range of [MIN]    | -1000.0 to 0.0                                                                                                                                                                                                                        |                                                               |
| Range of [MAX]    | 0.0 to 1000.0                                                                                                                                                                                                                         |                                                               |
| Definition        | <p>VM_REGEN_REACTIVE[MAX] Applies a limit to the reactive current reference in Regen mode so that the total current reference does not exceed its maximum allowed level.</p> <p>VM_REGEN_REACTIVE[MIN] = - VM_REGEN_REACTIVE[MAX]</p> |                                                               |

| VM_SPEED       |                                                                                                                                                                                                                                                                                         | Range applied to parameters showing speed |
|----------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------|
| Units          | Open-loop, RFC-A, RFC-S: rpm or mm/s                                                                                                                                                                                                                                                    |                                           |
| Range of [MIN] | Open-loop, RFC-A, RFC-S: -50000.0 to 0.0                                                                                                                                                                                                                                                |                                           |
| Range of [MAX] | Open-loop, RFC-A, RFC-S: 0.0 to 50000.0                                                                                                                                                                                                                                                 |                                           |
| Definition     | <p>This variable minimum/maximum defines the range of speed monitoring parameters. To allow headroom for overshoot the range is set to twice the range of the speed references.</p> <p>VM_SPEED[MAX] = 2 x VM_SPEED_FREQ_REF[MAX]</p> <p>VM_SPEED[MIN] = 2 x VM_SPEED_FREQ_REF[MIN]</p> |                                           |

| VM_SPEED_FREQ_KEYPAD_REF                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | Range applied to the keypad reference                                                                                                                |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |
|------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------|-----------------------------------|------------------------------|---|---|------------------------------------------------------------------------------------------------------------------------------------------------------|---|---|-------------------------|---|---|-----|---|---|-------------------------|
| Units                                    | Open-loop: Hz<br>RFC-A, RFC-S: rpm or mm/s                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                                                                                                                                      |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |
| Range of [MIN]                           | Open-loop: -599.0 to 599.0<br>RFC-A, RFC-S: -(550 x 60 / Motor pole pairs) to (550 x 60 / Motor pole pairs)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                      |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |
| Range of [MAX]                           | Open-loop: 0.0 to 599.0<br>RFC-A, RFC-S: 0.0 to 550 x 60 / Motor pole pairs                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                      |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |
| Definition                               | <p>This variable maximum is applied to <i>Keypad Control Mode Reference</i> (01.017). The maximum applied to these parameters is the same as other frequency reference parameters.</p> <p>VM_SPEED_FREQ_USER_REFS [MAX] = VM_SPEED_FREQ_REF[MAX]</p> <p>However the minimum is dependent on <i>Negative Reference Clamp Enable</i> (01.008) and <i>Bipolar Reference Enable</i> (01.010).</p> <table border="1"> <thead> <tr> <th>Negative Reference Clamp Enable (01.008)</th><th>Bipolar Reference Enable (01.010)</th><th>VM_SPEED_FREQ_USER_REFS[MIN]</th></tr> </thead> <tbody> <tr> <td>0</td><td>0</td><td>If <i>Select Motor 2 Parameters</i> (11.045) = 0<br/><i>Minimum Reference Clamp</i> (01.007), otherwise<br/><i>M2 Minimum Reference Clamp</i> (21.002)</td></tr> <tr> <td>0</td><td>1</td><td>-VM_SPEED_FREQ_REF[MAX]</td></tr> <tr> <td>1</td><td>0</td><td>0.0</td></tr> <tr> <td>1</td><td>1</td><td>-VM_SPEED_FREQ_REF[MAX]</td></tr> </tbody> </table> |                                                                                                                                                      | Negative Reference Clamp Enable (01.008) | Bipolar Reference Enable (01.010) | VM_SPEED_FREQ_USER_REFS[MIN] | 0 | 0 | If <i>Select Motor 2 Parameters</i> (11.045) = 0<br><i>Minimum Reference Clamp</i> (01.007), otherwise<br><i>M2 Minimum Reference Clamp</i> (21.002) | 0 | 1 | -VM_SPEED_FREQ_REF[MAX] | 1 | 0 | 0.0 | 1 | 1 | -VM_SPEED_FREQ_REF[MAX] |
| Negative Reference Clamp Enable (01.008) | Bipolar Reference Enable (01.010)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | VM_SPEED_FREQ_USER_REFS[MIN]                                                                                                                         |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |
| 0                                        | 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | If <i>Select Motor 2 Parameters</i> (11.045) = 0<br><i>Minimum Reference Clamp</i> (01.007), otherwise<br><i>M2 Minimum Reference Clamp</i> (21.002) |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |
| 0                                        | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | -VM_SPEED_FREQ_REF[MAX]                                                                                                                              |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |
| 1                                        | 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | 0.0                                                                                                                                                  |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |
| 1                                        | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | -VM_SPEED_FREQ_REF[MAX]                                                                                                                              |                                          |                                   |                              |   |   |                                                                                                                                                      |   |   |                         |   |   |     |   |   |                         |

| VM_SPEED_FREQ_REF |                                                                                                                                                                                                                                                                                                                                                                                                                                   | Range applied to the frequency or speed reference parameters |
|-------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------|
| Units             | Open-loop: Hz<br>RFC-A, RFC-S: rpm or mm/s                                                                                                                                                                                                                                                                                                                                                                                        |                                                              |
| Range of [MIN]    | Open-loop: -599.0 to 0.0<br>RFC-A, RFC-S: -(550 x 60 / Motor pole pairs to 0.0)                                                                                                                                                                                                                                                                                                                                                   |                                                              |
| Range of [MAX]    | Open-loop: 0.0 to 599.0<br>RFC-A, RFC-S: 0.0 to 550 x 60 / Motor pole pairs                                                                                                                                                                                                                                                                                                                                                       |                                                              |
| Definition        | <p>If Pr <b>01.008</b> = 0: VM_SPEED_FREQ_REF[MAX] = Pr <b>01.006</b></p> <p>If Pr <b>01.008</b> = 1: VM_SPEED_FREQ_REF[MAX] = Pr <b>01.006</b> or  Pr <b>01.007</b> , whichever is larger.</p> <p>If the second motor map is selected (Pr <b>11.045</b> = 1) Pr <b>21.001</b> is used instead of Pr <b>01.006</b> and Pr <b>21.002</b> instead of Pr <b>01.007</b>.</p> <p>VM_SPEED_FREQ_REF[MIN] = -VM_SPEED_FREQ_REF[MAX].</p> |                                                              |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| VM_SPEED_FREQ_REF_UNIPOLAR |                                                                                                   | Unipolar version of VM_SPEED_FREQ_REF |
|----------------------------|---------------------------------------------------------------------------------------------------|---------------------------------------|
| Units                      | Open-loop: Hz<br>RFC-A, RFC-S: rpm or mm/s                                                        |                                       |
| Range of [MIN]             | Open-loop: 0.0<br>RFC-A, RFC-S: 0.0                                                               |                                       |
| Range of [MAX]             | Open-loop: 0.0 to 599.0<br>RFC-A, RFC-S: 0.0 to 550 x 60 / Motor pole pairs                       |                                       |
| Definition                 | VM_SPEED_FREQ_REF_UNIPOLAR[MAX] = VM_SPEED_FREQ_REF[MAX]<br>VM_SPEED_FREQ_REF_UNIPOLAR[MIN] = 0.0 |                                       |

| VM_SPEED_FREQ_USER_REFS                                                                     |                                                                                                             | Range applied to Analog reference parameters |
|---------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------|----------------------------------------------|
| Units                                                                                       | Open-loop: Hz<br>RFC-A, RFC-S: rpm or mm/s                                                                  |                                              |
| Range of [MIN]                                                                              | Open-loop: -599.00 to 599.00<br>RFC-A, RFC-S: -(550 x 60 / Motor pole pairs) to 550 x 60 / Motor pole pairs |                                              |
| Range of [MAX]                                                                              | Open-loop: 0.00 to 599.00<br>RFC-A, RFC-S: 0.0 to 550 x 60 / Motor pole pairs                               |                                              |
| Definition                                                                                  | VM_SPEED_FREQ_USER_REFS = VM_SPEED_FREQ_REF[MAX]                                                            |                                              |
|                                                                                             | <b>Negative Reference Clamp Enable (01.008)</b>                                                             | <b>Bipolar Reference Enable (01.010)</b>     |
|                                                                                             | 0                                                                                                           | 0                                            |
|                                                                                             | 0                                                                                                           | 1                                            |
|                                                                                             | 1                                                                                                           | 0                                            |
|                                                                                             | 1                                                                                                           | 1                                            |
| VM_SPEED_FREQ_USER_REFS [MIN]                                                               |                                                                                                             |                                              |
| Pr 01.007                                                                                   |                                                                                                             |                                              |
| -VM_SPEED_FREQ_REF[MAX]                                                                     |                                                                                                             |                                              |
| 0.0                                                                                         |                                                                                                             |                                              |
| -VM_SPEED_FREQ_REF[MAX]                                                                     |                                                                                                             |                                              |
| If the second motor map is selected (Pr 11.045 = 1) Pr 21.002 is used instead of Pr 01.007. |                                                                                                             |                                              |

| VM_STD_UNDER_VOLTS |                                                                                                                          | Range applied to the standard under-voltage threshold |
|--------------------|--------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------|
| Units              | V                                                                                                                        |                                                       |
| Range of [MIN]     | 0 to 1150                                                                                                                |                                                       |
| Range of [MAX]     | 0 to 1150                                                                                                                |                                                       |
| Definition         | VM_STD_UNDER_VOLTS[MAX] = VM_DC_VOLTAGE_SET / 1.1<br>VM_STD_UNDER_VOLTS[MIN] is voltage rating dependent. See Table 12-4 |                                                       |

| VM_SUPPLY_LOSS_LEVEL |                                                                                                                                   | Range applied to the supply loss threshold |
|----------------------|-----------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------|
| Units                | V                                                                                                                                 |                                            |
| Range of [MIN]       | 0 to 1150                                                                                                                         |                                            |
| Range of [MAX]       | 0 to 1150                                                                                                                         |                                            |
| Definition           | VM_SUPPLY_LOSS_LEVEL[MAX] = VM_DC_VOLTAGE_SET[MAX]<br>VM_SUPPLY_LOSS_LEVEL[MIN] is drive voltage rating dependent. See Table 12-4 |                                            |

| VM_SWITCHING_FREQUENCY |                                                                                                                                                              | Range applied to the maximum switching frequency parameters |
|------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------|
| Units                  | User units                                                                                                                                                   |                                                             |
| Range of [MIN]         | 0                                                                                                                                                            |                                                             |
| Range of [MAX]         | 0 to 6                                                                                                                                                       |                                                             |
| Definition             | VM_SWITCHING_FREQUENCY[MAX] = Power stage dependent<br>VM_SWITCHING_FREQUENCY[MIN] = 0 for motor control modes, or 1 for Regen mode (subject to the maximum) |                                                             |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| VM_TORQUE_CURRENT |                                                  | Range applied to torque and torque producing current parameters (where this is used in Regen mode it refers to the active current) |                              |
|-------------------|--------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------|------------------------------|
| Units             | %                                                |                                                                                                                                    |                              |
| Range of [MIN]    | -1000.0 to 0.0                                   |                                                                                                                                    |                              |
| Range of [MAX]    | 0.0 to 1000.0                                    |                                                                                                                                    |                              |
| Definition        | Select Motor 2 Parameters (11.045)               |                                                                                                                                    | VM_TORQUE_CURRENT [MAX]      |
|                   | 0                                                |                                                                                                                                    | VM_MOTOR1_CURRENT_LIMIT[MAX] |
|                   | 1                                                |                                                                                                                                    | VM_MOTOR2_CURRENT_LIMIT[MAX] |
|                   | VM_TORQUE_CURRENT[MIN] = -VM_TORQUE_CURRENT[MAX] |                                                                                                                                    |                              |
|                   |                                                  |                                                                                                                                    |                              |

| VM_TORQUE_CURRENT_UNIPOLAR |                                                          | Unipolar version of VM_TORQUE_CURRENT |
|----------------------------|----------------------------------------------------------|---------------------------------------|
| Units                      | %                                                        |                                       |
| Range of [MIN]             | 0.0                                                      |                                       |
| Range of [MAX]             | 0.0 to 1000.0                                            |                                       |
| Definition                 | VM_TORQUE_CURRENT_UNIPOLAR[MAX] = VM_TORQUE_CURRENT[MAX] |                                       |
|                            | VM_TORQUE_CURRENT_UNIPOLAR[MIN] = 0.0                    |                                       |

| VM_USER_CURRENT |                                                                                                                                                                                                                                                                                                                                                                                                | Range applied to torque reference and percentage load parameters with one decimal place |
|-----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------|
| Units           | %                                                                                                                                                                                                                                                                                                                                                                                              |                                                                                         |
| Range of [MIN]  | -1000.0 to 0.0                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                         |
| Range of [MAX]  | 0.0 to 1000.0                                                                                                                                                                                                                                                                                                                                                                                  |                                                                                         |
| Definition      | VM_USER_CURRENT[MAX] = <i>User Current Maximum Scaling</i> (04.024)                                                                                                                                                                                                                                                                                                                            |                                                                                         |
|                 | VM_USER_CURRENT[MIN] = -VM_USER_CURRENT[MAX]                                                                                                                                                                                                                                                                                                                                                   |                                                                                         |
|                 | <i>User Current Maximum Scaling</i> (04.024) defines the variable maximum/minimums VM_USER_CURRENT and VM_USER_CURRENT_HIGH_RES which are applied to <i>Percentage Load</i> (04.020), <i>Torque Reference</i> (04.008) and <i>Torque Offset</i> (04.009). This is useful when routing these parameters to an analog output as it allows the full scale output value to be defined by the user. |                                                                                         |
|                 | The maximum value (VM_TORQUE_CURRENT_UNIPOLAR [MAX]) varies between drive sizes with default parameters loaded. For some drive sizes the default value may be reduced below the value given by the parameter range limiting.                                                                                                                                                                   |                                                                                         |

| VM_USER_CURRENT_HIGH_RES |                                                                                                                                                                                                                                                                                                                                                                                                | Range applied to torque reference and percentage load parameters with two decimal places |
|--------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------|
| Units                    | %                                                                                                                                                                                                                                                                                                                                                                                              |                                                                                          |
| Range of [MIN]           | -1000.00 to 0.00                                                                                                                                                                                                                                                                                                                                                                               |                                                                                          |
| Range of [MAX]           | 0.00 to 1000.00                                                                                                                                                                                                                                                                                                                                                                                |                                                                                          |
| Definition               | VM_USER_CURRENT_HIGH_RES[MAX] = <i>User Current Maximum Scaling</i> (04.024) with an additional decimal place                                                                                                                                                                                                                                                                                  |                                                                                          |
|                          | VM_USER_CURRENT_HIGH_RES[MIN] = -VM_USER_CURRENT_HIGH_RES[MAX]                                                                                                                                                                                                                                                                                                                                 |                                                                                          |
|                          | <i>User Current Maximum Scaling</i> (04.024) defines the variable maximum/minimums VM_USER_CURRENT and VM_USER_CURRENT_HIGH_RES which are applied to <i>Percentage Load</i> (04.020), <i>Torque Reference</i> (04.008) and <i>Torque Offset</i> (04.009). This is useful when routing these parameters to an analog output as it allows the full scale output value to be defined by the user. |                                                                                          |
|                          | The maximum value (VM_TORQUE_CURRENT_UNIPOLAR [MAX]) varies between drive sizes with default parameters loaded. For some drive sizes the default value may be reduced below the value given by the parameter range limiting.                                                                                                                                                                   |                                                                                          |

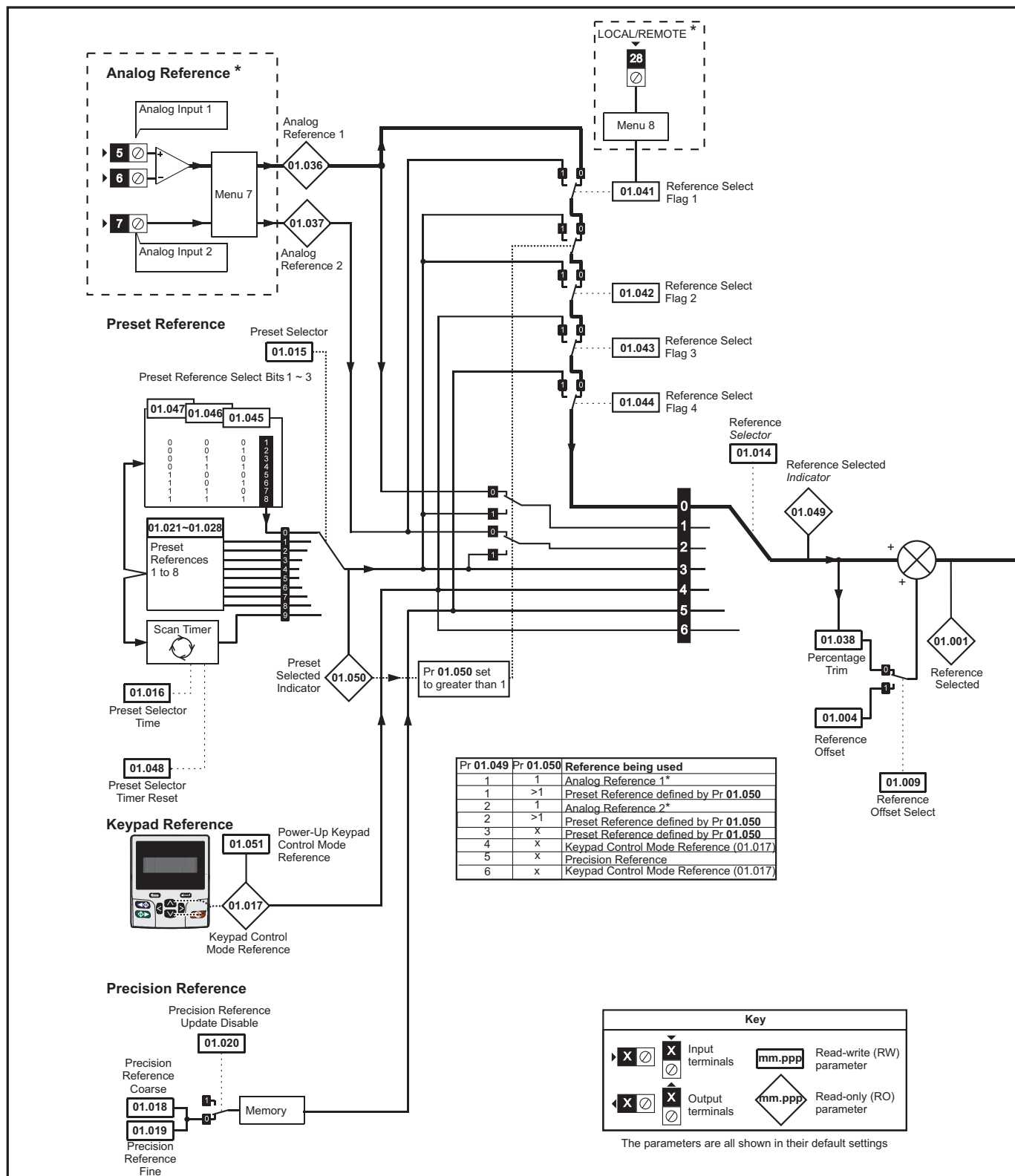
Table 12-4 Voltage ratings dependant values

| Variable min/max          | Voltage level (V) |       |       |       |
|---------------------------|-------------------|-------|-------|-------|
|                           | 200 V             | 400 V | 575 V | 690 V |
| VM_DC_VOLTAGE_SET[MAX]    | 400               | 800   | 955   | 1150  |
| VM_DC_VOLTAGE[MAX]        | 415               | 830   | 990   | 1190  |
| VM_AC_VOLTAGE_SET[MAX]    | 265               | 530   | 635   | 765   |
| VM_AC_VOLTAGE[MAX]        | 325               | 650   | 780   | 930   |
| VM_STD_UNDER_VOLTS[MIN]   | 175               | 330   | 435   | 435   |
| VM_SUPPLY_LOSS_LEVEL[MIN] | 205               | 410   | 540   | 540   |
| VM_HIGH_DC_VOLTAGE[MAX]   | 1500              | 1500  | 1500  | 1500  |

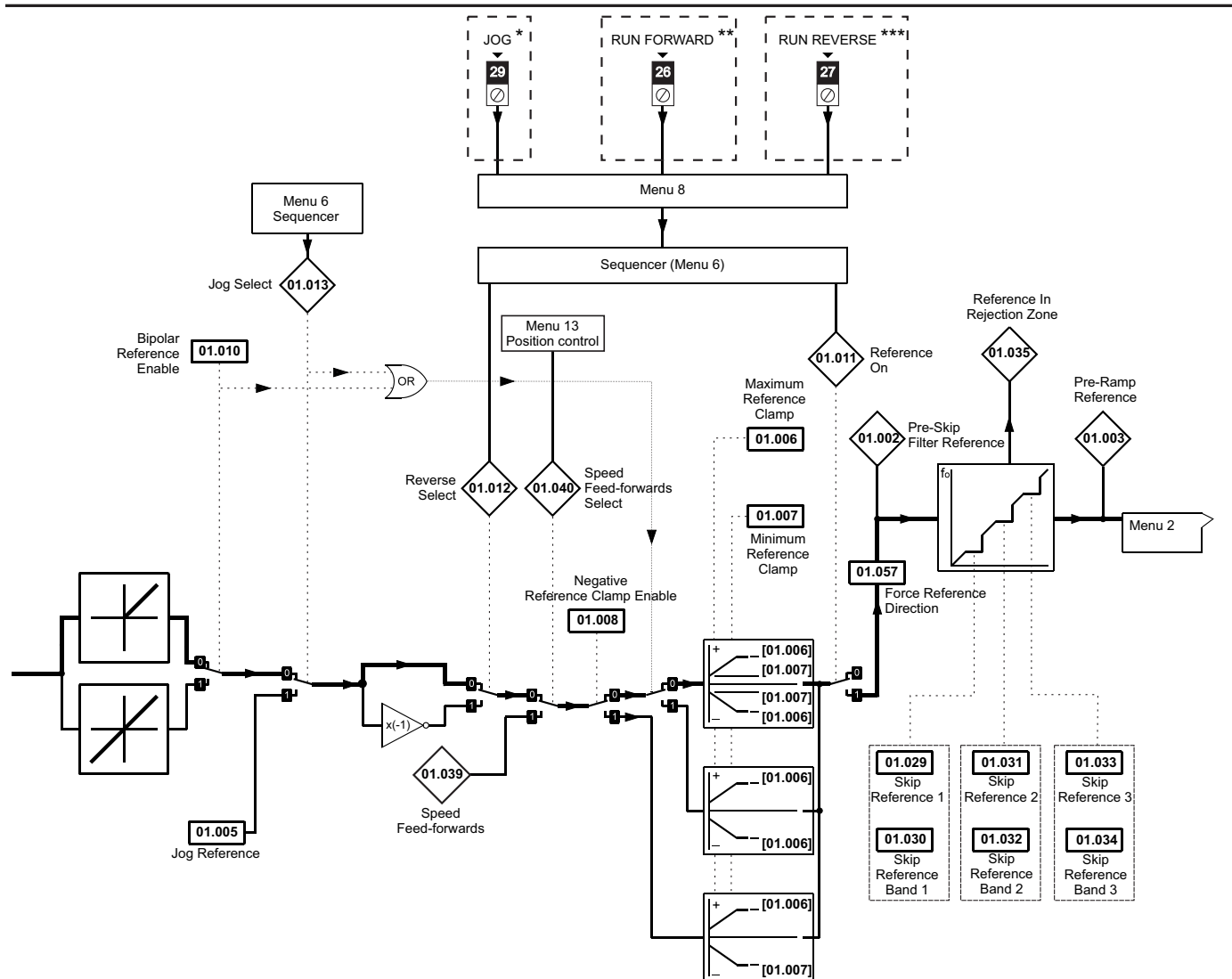
|                       |                        |                            |                            |                    |                     |                      |              |                        |                            |                |                                |             |                   |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|---------------------|----------------------|--------------|------------------------|----------------------------|----------------|--------------------------------|-------------|-------------------|
| Safety<br>information | Product<br>information | Mechanical<br>installation | Electrical<br>installation | Getting<br>started | Basic<br>parameters | Running<br>the motor | Optimization | Drive<br>communication | NV Media Card<br>Operation | Onboard<br>PLC | <b>Advanced<br/>parameters</b> | Diagnostics | UL<br>information |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|---------------------|----------------------|--------------|------------------------|----------------------------|----------------|--------------------------------|-------------|-------------------|

## 12.2 Menu 1: Frequency / speed reference

Figure 12-1 Menu 1 logic diagram



\* Not available on Unidrive M702.



\*\*\* Terminal 8 on *Unidrive M702*.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                        | Range(⚡)                                                                                              |                             | Default(⇄)                 |                              |        | Type |     |    |    |    |    |
|-----------|----------------------------------------|-------------------------------------------------------------------------------------------------------|-----------------------------|----------------------------|------------------------------|--------|------|-----|----|----|----|----|
|           |                                        | OL                                                                                                    | RFC-A / S                   | OL                         | RFC-A                        | RFC-S  |      |     |    |    |    |    |
| 01.001    | Reference Selected                     | VM_SPEED_FREQ_REF Hz                                                                                  | VM_SPEED_FREQ_REF rpm       |                            |                              |        | RO   | Num | ND | NC | PT |    |
| 01.002    | Pre-Skip Filter Reference              | VM_SPEED_FREQ_REF Hz                                                                                  | VM_SPEED_FREQ_REF rpm       |                            |                              |        | RO   | Num | ND | NC | PT |    |
| 01.003    | Pre-Ramp Reference                     | VM_SPEED_FREQ_REF Hz                                                                                  | VM_SPEED_FREQ_REF rpm       |                            |                              |        | RO   | Num | ND | NC | PT |    |
| 01.004    | Reference Offset                       | VM_SPEED_FREQ_REF Hz                                                                                  | VM_SPEED_FREQ_REF rpm       |                            | 0.0                          |        | RW   | Num |    |    |    | US |
| 01.005    | Jog Reference                          | 0.0 to 400.0 Hz                                                                                       | 0.0 to 4000.0 rpm           |                            | 0.0                          |        | RW   | Num |    |    |    | US |
| 01.006    | Maximum Reference Clamp                | VM_POSITIVE_REF_CLAMP1 Hz                                                                             | VM_POSITIVE_REF_CLAMP1 rpm  | 50 Hz: 50.0<br>60 Hz: 60.0 | 50Hz: 1500.0<br>60Hz: 1800.0 | 3000.0 | RW   | Num |    |    |    | US |
| 01.007    | Minimum Reference Clamp                | VM_NEGATIVE_REF_CLAMP1 Hz                                                                             | VM_NEGATIVE_REF_CLAMP1 rpm  |                            | 0.0                          |        | RW   | Num |    |    |    | US |
| 01.008    | Negative Reference Clamp Enable        | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    |    |    | US |
| 01.009    | Reference Offset Select                | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    |    |    | US |
| 01.010    | Bipolar Reference Enable               | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    |    |    | US |
| 01.011    | Reference On                           | Off (0) or On (1)                                                                                     |                             |                            |                              |        | RO   | Bit | ND | NC | PT |    |
| 01.012    | Reverse Select                         | Off (0) or On (1)                                                                                     |                             |                            |                              |        | RO   | Bit | ND | NC | PT |    |
| 01.013    | Jog Select                             | Off (0) or On (1)                                                                                     |                             |                            |                              |        | RO   | Bit | ND | NC | PT |    |
| 01.014    | Reference Selector                     | A1 A2 (0)*, A1 Preset (1)*, A2 Preset (2)*<br>Preset (3), Keypad (4), Precision (5)<br>Keypad Ref (6) |                             | A1 A2 (0)**                |                              |        | RW   | Txt |    |    |    | US |
| 01.015    | Preset Selector                        | 0 to 9                                                                                                |                             | 0                          |                              |        | RW   | Num |    |    |    | US |
| 01.016    | Preset Selector Time                   | 0.0 to 400.0 s                                                                                        |                             | 10.0 s                     |                              |        | RW   | Num |    |    |    | US |
| 01.017    | Keypad Control Mode Reference          | VM_SPEED_FREQ_KEYPAD_REF                                                                              |                             | 0.0                        |                              |        | RO   | Num |    | NC | PT | PS |
| 01.018    | Precision Reference Coarse             | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.019    | Precision Reference Fine               | 0.000 to 0.099 Hz                                                                                     | 0.000 to 0.099 rpm          | 0.000                      |                              |        | RW   | Num |    |    |    | US |
| 01.020    | Precision Reference Update Disable     | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.021    | Preset Reference 1                     | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.022    | Preset Reference 2                     | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.023    | Preset Reference 3                     | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.024    | Preset Reference 4                     | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.025    | Preset Reference 5                     | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.026    | Preset Reference 6                     | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.027    | Preset Reference 7                     | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.028    | Preset Reference 8                     | VM_SPEED_FREQ_REF                                                                                     |                             | 0.0                        |                              |        | RW   | Num |    |    |    | US |
| 01.029    | Skip Reference 1                       | 0.0 to 599.0 Hz                                                                                       | 0 to 33, 000 rpm            | 0.0                        | 0                            |        | RW   | Num |    |    |    | US |
| 01.030    | Skip Reference Band 1                  | 0.0 to 25.0 Hz                                                                                        | 0 to 250 rpm                | 0.0                        | 0                            |        | RW   | Num |    |    |    | US |
| 01.031    | Skip Reference 2                       | 0.0 to 599.0 Hz                                                                                       | 0 to 33, 000 rpm            | 0.0                        | 0                            |        | RW   | Num |    |    |    | US |
| 01.032    | Skip Reference Band 2                  | 0.0 to 25.0 Hz                                                                                        | 0 to 250 rpm                | 0.0                        | 0                            |        | RW   | Num |    |    |    | US |
| 01.033    | Skip Reference 3                       | 0.0 to 599.0 Hz                                                                                       | 0 to 33, 000 rpm            | 0.0                        | 0                            |        | RW   | Num |    |    |    | US |
| 01.034    | Skip Reference Band 3                  | 0.0 to 25.0 Hz                                                                                        | 0 to 250 rpm                | 0.0                        | 0                            |        | RW   | Num |    |    |    | US |
| 01.035    | Reference In Rejection Zone            | Off (0) or On (1)                                                                                     |                             |                            |                              |        | RO   | Bit | ND | NC | PT |    |
| 01.036    | Analog Reference 1                     | VM_SPEED_FREQ_USER_REFS Hz                                                                            | VM_SPEED_FREQ_USER_REFS rpm | 0.0                        |                              |        | RO   | Num |    | NC |    |    |
| 01.037    | Analog Reference 2                     |                                                                                                       |                             | 0.0                        |                              |        | RO   | Num |    | NC |    |    |
| 01.038    | Percentage Trim                        | ±100.00 %                                                                                             |                             | 0.00 %                     |                              |        | RW   | Num |    | NC |    |    |
| 01.039    | Speed Feed-forwards                    | VM_SPEED_FREQ_REF                                                                                     |                             |                            |                              |        | RO   | Num | ND | NC | PT |    |
| 01.040    | Speed Feed-forwards Select             | Off (0) or On (1)                                                                                     |                             |                            |                              |        | RO   | Bit | ND | NC | PT |    |
| 01.041    | Reference Select Flag 1                | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.042    | Reference Select Flag 2                | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.043    | Reference Select Flag 3                | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.044    | Reference Select Flag 4                | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.045    | Preset Select Flag 1                   | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.046    | Preset Select Flag 2                   | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.047    | Preset Select Flag 3                   | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.048    | Preset Selector Timer Reset            | Off (0) or On (1)                                                                                     |                             | Off (0)                    |                              |        | RW   | Bit |    | NC |    |    |
| 01.049    | Reference Selected Indicator           | 1 to 6                                                                                                |                             |                            |                              |        | RO   | Num | ND | NC | PT |    |
| 01.050    | Preset Selected Indicator              | 1 to 8                                                                                                |                             |                            |                              |        | RO   | Num | ND | NC | PT |    |
| 01.051    | Power-up Keypad Control Mode Reference | Reset (0), Last (1), Preset (2)                                                                       |                             | Reset (0)                  |                              |        | RW   | Txt |    |    |    | US |
| 01.052    | Hand/Off/Auto Operating Mode           | 0 to 3                                                                                                |                             | 0                          |                              |        | RW   | Num |    |    |    | US |
| 01.055    | Linear Speed Select                    |                                                                                                       |                             | Off (0)                    |                              |        | RW   | Bit |    |    |    | US |
| 01.056    | Linear Speed Selected                  |                                                                                                       |                             | Off (0) or On (1)          |                              |        | RO   | Bit | ND | NC | PT |    |
| 01.057    | Force Reference Direction              | None (0), Forward (1), Reverse (2)                                                                    |                             | None (0)                   |                              |        | RW   | Txt |    |    |    |    |

\* Not available on Unidrive M702.

\*\* Preset (3) on Unidrive M702.

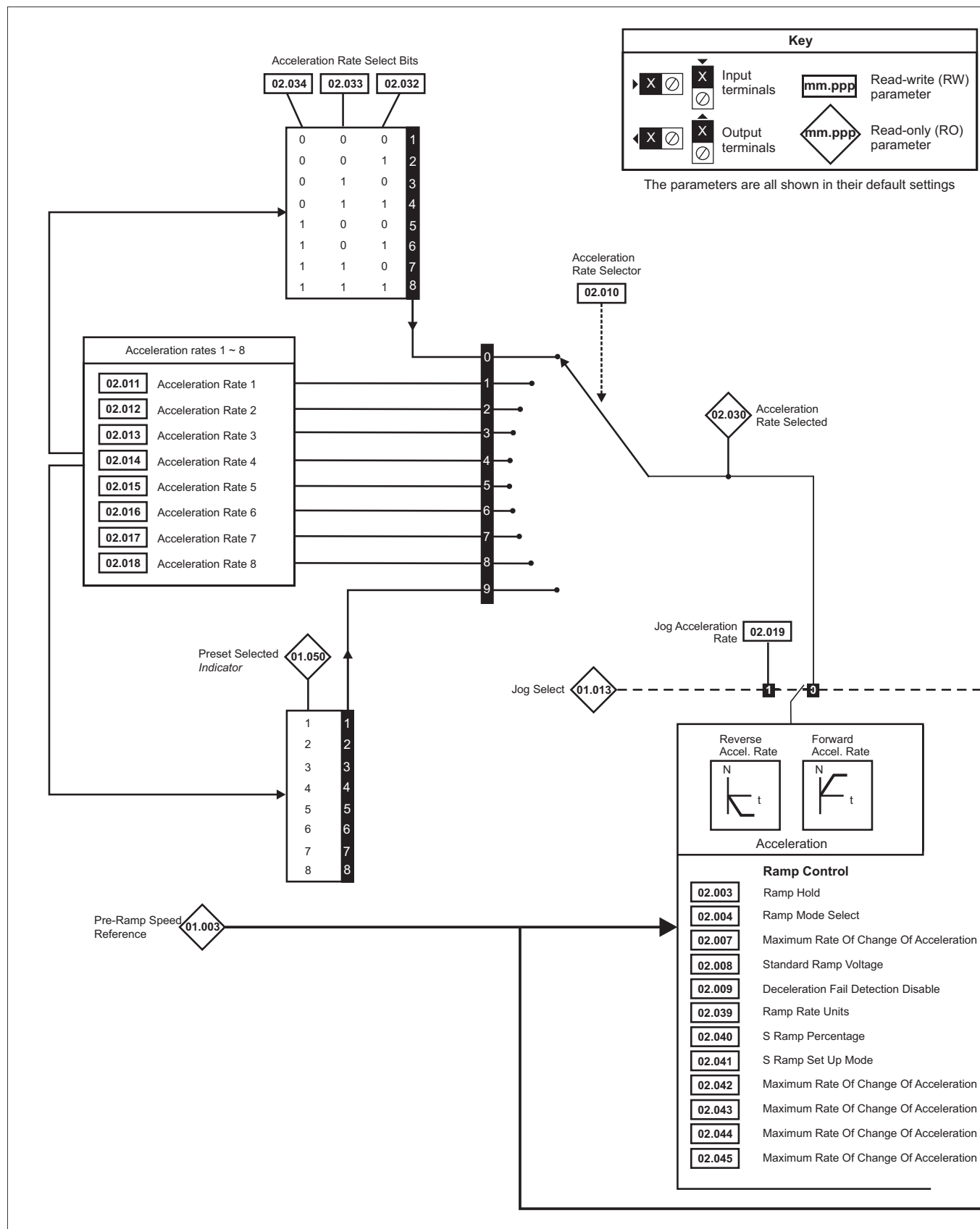
|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

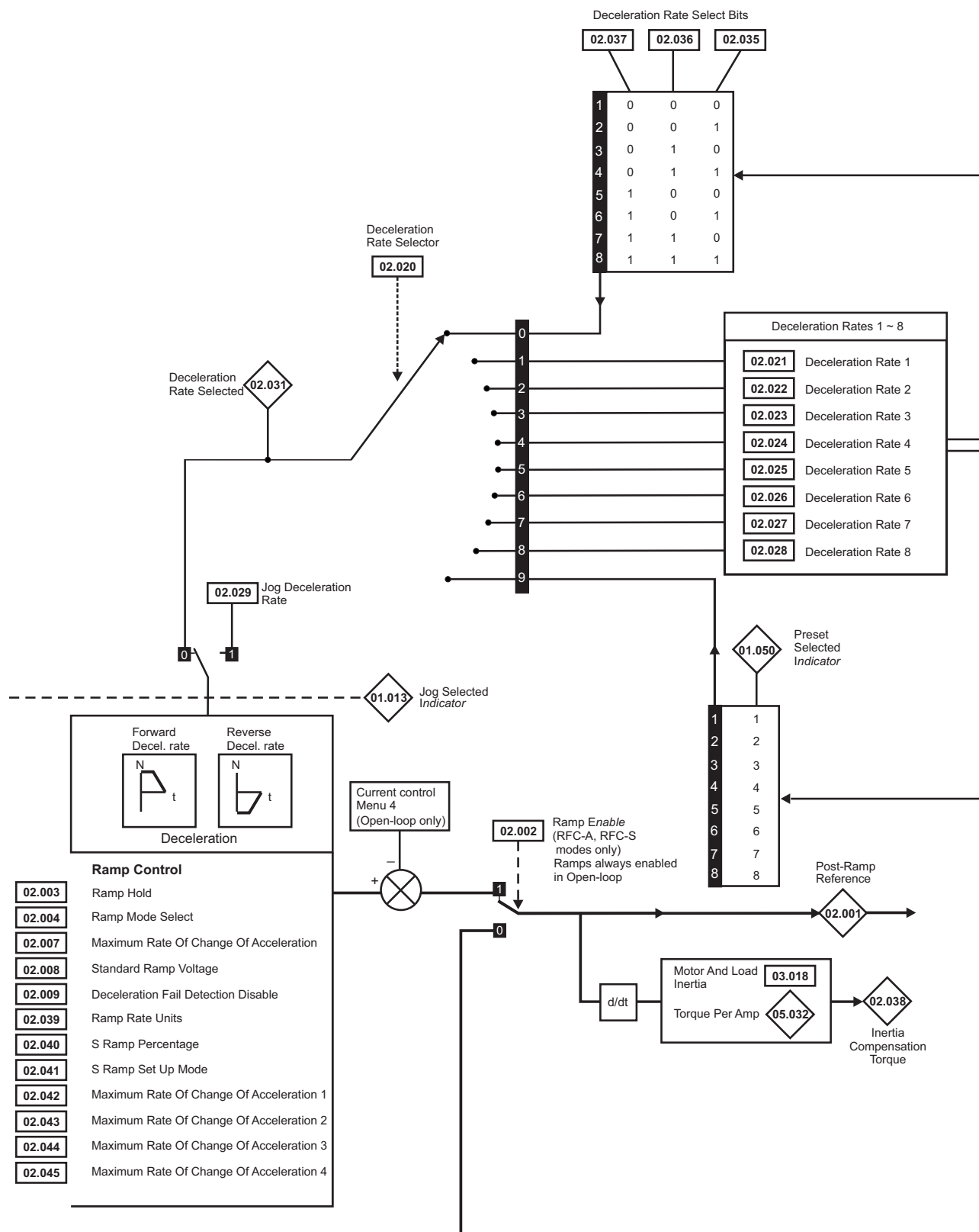
|                       |                        |                            |                            |                    |                     |                      |              |                        |                            |                |                                |             |                   |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|---------------------|----------------------|--------------|------------------------|----------------------------|----------------|--------------------------------|-------------|-------------------|
| Safety<br>information | Product<br>information | Mechanical<br>installation | Electrical<br>installation | Getting<br>started | Basic<br>parameters | Running<br>the motor | Optimization | Drive<br>communication | NV Media Card<br>Operation | Onboard<br>PLC | <b>Advanced<br/>parameters</b> | Diagnostics | UL<br>information |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|---------------------|----------------------|--------------|------------------------|----------------------------|----------------|--------------------------------|-------------|-------------------|

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 12.3 Menu 2: Ramps

Figure 12-2 Menu 2 logic diagram



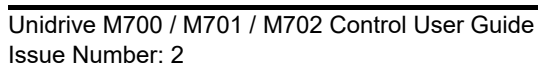


| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                          | Range(↕)                              |                                             | Default(↔)                                                                                                                  |              |         | Type |     |    |    |    |    |
|-----------|------------------------------------------|---------------------------------------|---------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------|--------------|---------|------|-----|----|----|----|----|
|           |                                          | OL                                    | RFC-A / S                                   | OL                                                                                                                          | RFC-A        | RFC-S   |      |     |    |    |    |    |
| 02.001    | Post Ramp Reference                      | VM_SPEED_FREQ_REF Hz                  | VM_SPEED_FREQ_REF rpm                       |                                                                                                                             |              |         | RO   | Num | ND | NC | PT |    |
| 02.002    | Ramp Enable                              |                                       | Off (0) or On (1)                           |                                                                                                                             | On (1)       |         | RW   | Bit |    |    |    | US |
| 02.003    | Ramp Hold                                |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    |    |    | US |
| 02.004    | Ramp Mode                                | Fast (0), Standard (1), Std boost (2) | Fast (0), Standard (1)                      |                                                                                                                             | Standard (1) |         | RW   | Txt |    |    |    | US |
| 02.005    | Disable Ramp Output                      |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    |    |    | US |
| 02.006    | S Ramp Enable                            |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    |    |    | US |
| 02.007    | Maximum Rate Of Change Of Acceleration   | 0.0 to 300.0 s <sup>2</sup> /100 Hz   | 0.000 to 100.000 s <sup>2</sup> /1000 rpm   | 3.1                                                                                                                         | 1.500        | 0.030   | RW   | Num |    |    |    | US |
| 02.008    | Standard Ramp Voltage                    | 0 to VM_DC_VOLTAGE_SET V              |                                             | 200 V drive: 375 V<br>50 Hz - 400 V drive: 750 V<br>60 Hz - 400 V drive: 775 V<br>575 V drive: 895 V<br>690 V drive: 1075 V |              |         | RW   | Num |    | RA |    | US |
| 02.009    | Deceleration Fail Detection Disable      |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    |    |    | US |
| 02.010    | Acceleration Rate Selector               |                                       | 0 to 9                                      |                                                                                                                             | 0            |         | RW   | Num |    |    |    | US |
| 02.011    | Acceleration Rate 1                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 5.0 s                                                                                                                       | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.012    | Acceleration Rate 2                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 5.0 s                                                                                                                       | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.013    | Acceleration Rate 3                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 5.0 s                                                                                                                       | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.014    | Acceleration Rate 4                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 5.0 s                                                                                                                       | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.015    | Acceleration Rate 5                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 5.0 s                                                                                                                       | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.016    | Acceleration Rate 6                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 5.0 s                                                                                                                       | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.017    | Acceleration Rate 7                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 5.0 s                                                                                                                       | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.018    | Acceleration Rate 8                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 5.0 s                                                                                                                       | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.019    | Jog Acceleration Rate                    | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 0.2 s                                                                                                                       | 0.000 s      |         | RW   | Num |    |    |    | US |
| 02.020    | Deceleration Rate Selector               |                                       | 0 to 9                                      |                                                                                                                             | 0            |         | RW   | Num |    |    |    | US |
| 02.021    | Deceleration Rate 1                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 10.0 s                                                                                                                      | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.022    | Deceleration Rate 2                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 10.0 s                                                                                                                      | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.023    | Deceleration Rate 3                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 10.0 s                                                                                                                      | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.024    | Deceleration Rate 4                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 10.0 s                                                                                                                      | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.025    | Deceleration Rate 5                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 10.0 s                                                                                                                      | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.026    | Deceleration Rate 6                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 10.0 s                                                                                                                      | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.027    | Deceleration Rate 7                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 10.0 s                                                                                                                      | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.028    | Deceleration Rate 8                      | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 10.0 s                                                                                                                      | 2.000 s      | 0.200 s | RW   | Num |    |    |    | US |
| 02.029    | Jog Deceleration Rate                    | 0.0 to VM_ACCEL_RATE s/100 Hz         | 0.000 to VM_ACCEL_RATE s/1000 rpm           | 0.2 s                                                                                                                       | 0.000 s      |         | RW   | Num |    |    |    | US |
| 02.030    | Acceleration Rate Selected               |                                       | 0 to 8                                      |                                                                                                                             |              |         | RO   | Num | ND | NC | PT |    |
| 02.031    | Deceleration Rate Selected               |                                       | 0 to 8                                      |                                                                                                                             |              |         | RO   | Num | ND | NC | PT |    |
| 02.032    | Acceleration Rate Select Bit 0           |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    | NC |    |    |
| 02.033    | Acceleration Rate Select Bit 1           |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    | NC |    |    |
| 02.034    | Acceleration Rate Select Bit 2           |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    | NC |    |    |
| 02.035    | Deceleration Rate Select Bit 0           |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    | NC |    |    |
| 02.036    | Deceleration Rate Select Bit 1           |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    | NC |    |    |
| 02.037    | Deceleration Rate Select Bit 2           |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    | NC |    |    |
| 02.038    | Inertia Compensation Torque              |                                       | ±1000.0 %                                   |                                                                                                                             |              |         | RO   | Num | ND | NC | PT |    |
| 02.039    | Ramp Rate Units                          |                                       | Off (0) or On (1)                           |                                                                                                                             | Off (0)      |         | RW   | Bit |    |    |    | US |
| 02.040    | S Ramp Percentage                        |                                       | 0.0 to 50.0 %                               |                                                                                                                             | 0.0 %        |         | RW   |     |    |    |    | US |
| 02.041    | S Ramp Set-up Mode                       |                                       | Single (0), Percentage (1), Independent (2) |                                                                                                                             | Single (0)   |         | RW   | Txt |    |    |    | US |
| 02.042    | Maximum Rate Of Change Of Acceleration 1 | 0.0 to 300.0                          | 0.000 to 100.000                            | 0.0                                                                                                                         | 0.000        |         | RW   | Num |    |    |    | US |
| 02.043    | Maximum Rate Of Change Of Acceleration 2 | 0.0 to 300.0                          | 0.000 to 100.000                            | 0.0                                                                                                                         | 0.000        |         | RW   | Num |    |    |    | US |
| 02.044    | Maximum Rate Of Change Of Acceleration 3 | 0.0 to 300.0                          | 0.000 to 100.000                            | 0.0                                                                                                                         | 0.000        |         | RW   | Num |    |    |    | US |
| 02.045    | Maximum Rate Of Change Of Acceleration 4 | 0.0 to 300.0                          | 0.000 to 100.000                            | 0.0                                                                                                                         | 0.000        |         | RW   | Num |    |    |    | US |

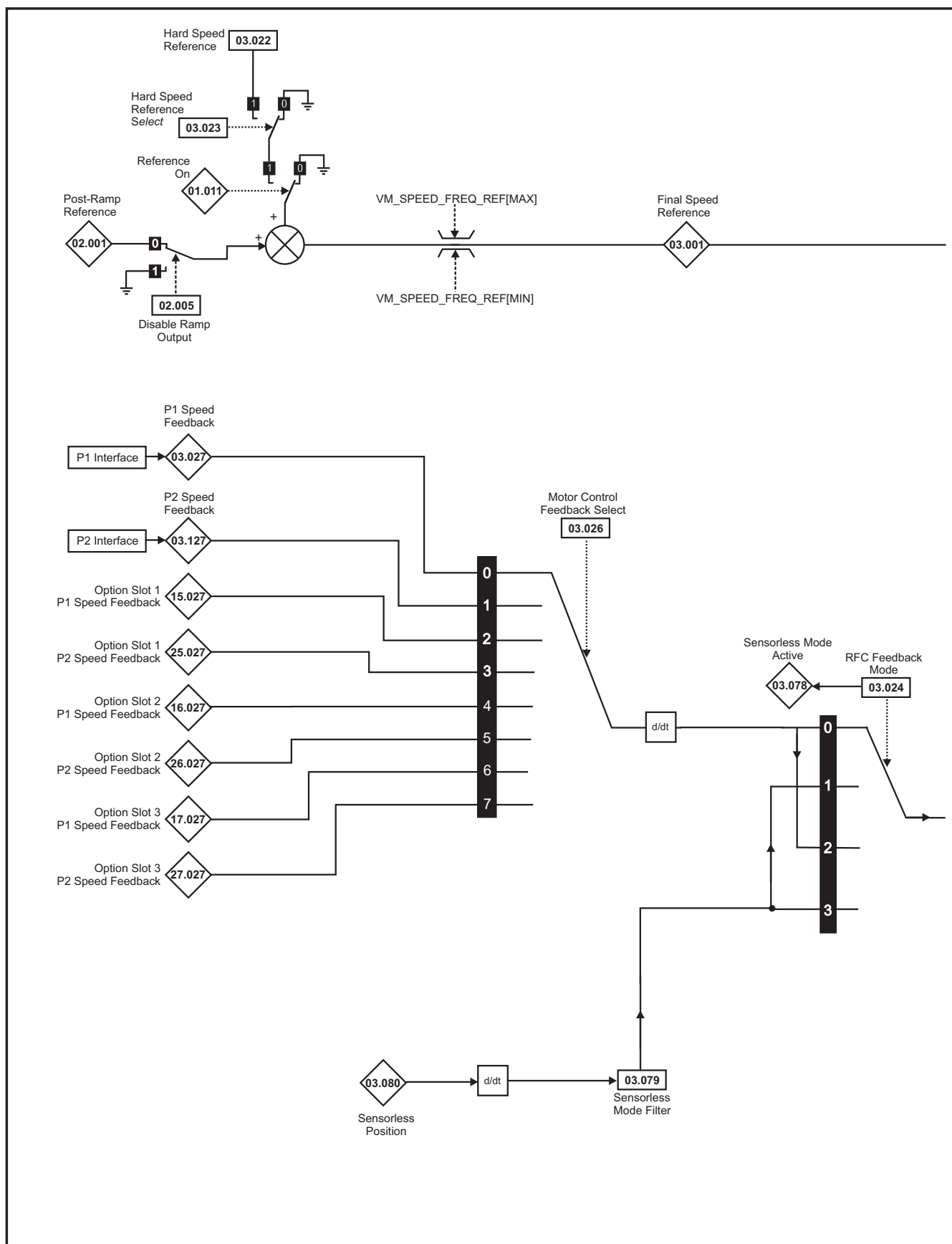
|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

**Figure 12-3 Menu 3 Open-loop logic diagram**

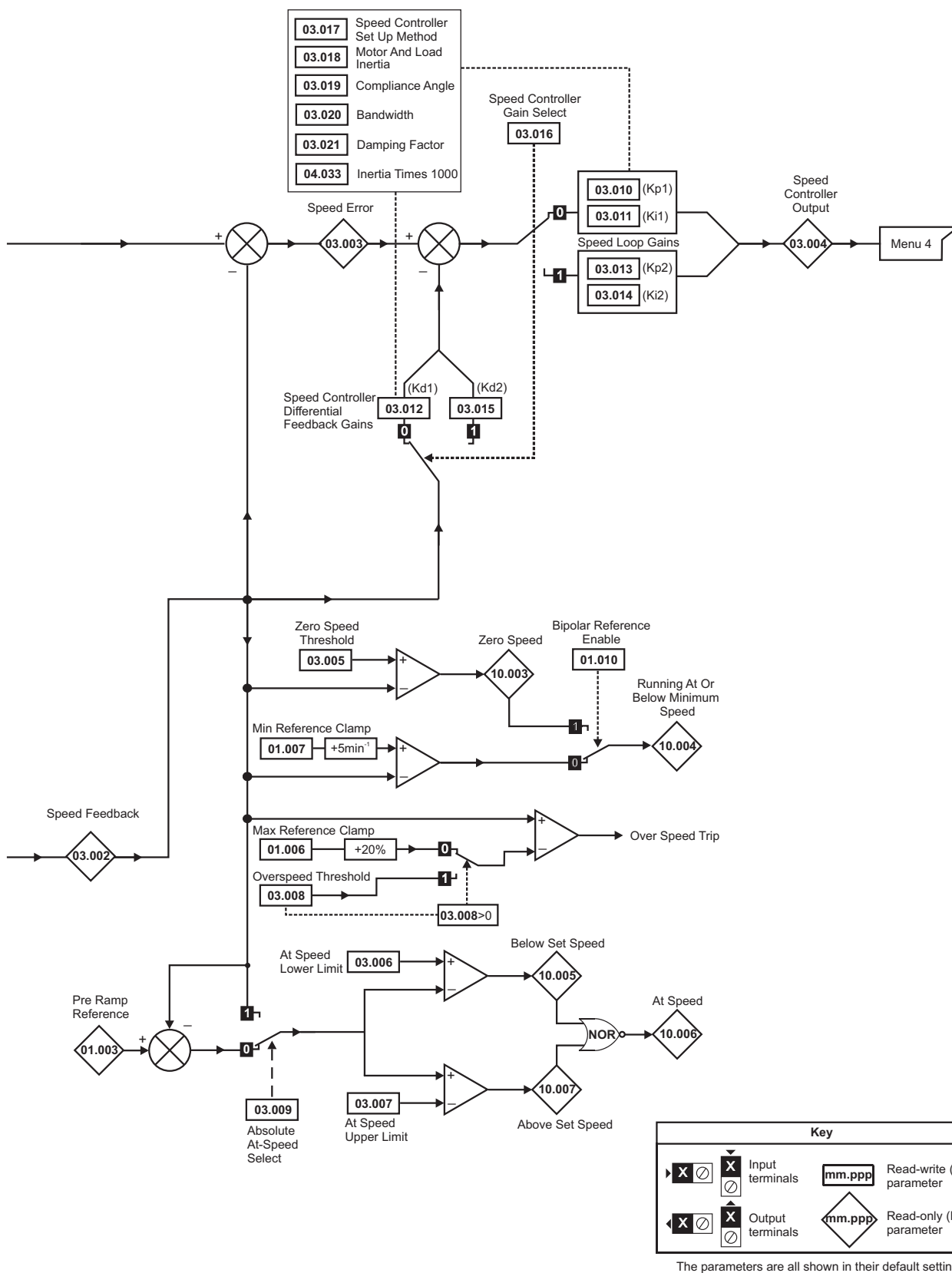


|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-4 Menu 3 RFC-A, RFC-S logic diagram

**NOTE**

\* Automatic change over if the relevant 'bit' of *Position Feedback Initialized* (03.076) is 0.



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-5 P1 Interface

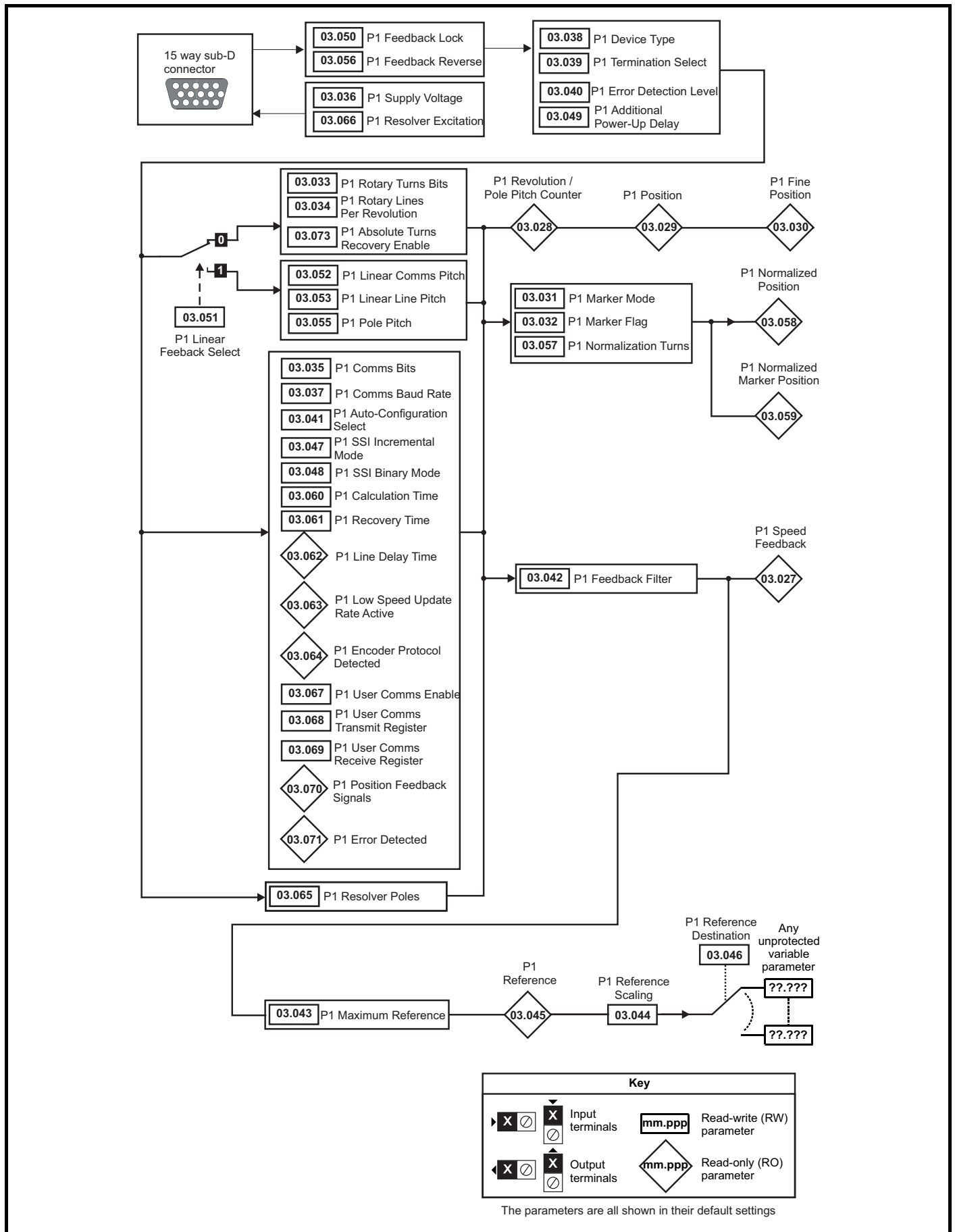
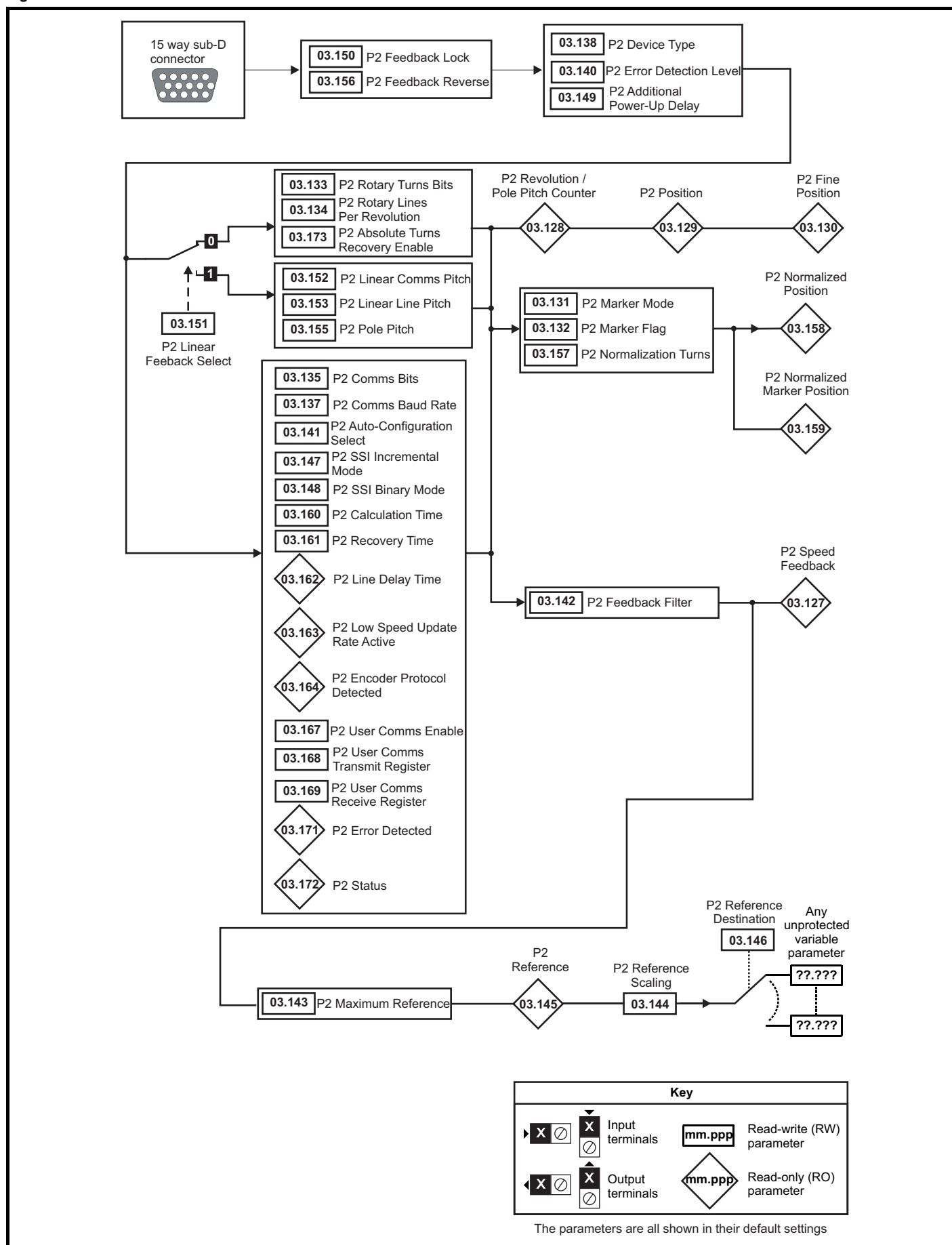


**Figure 12-6 P2 Interface**

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-7 Freeze system logic

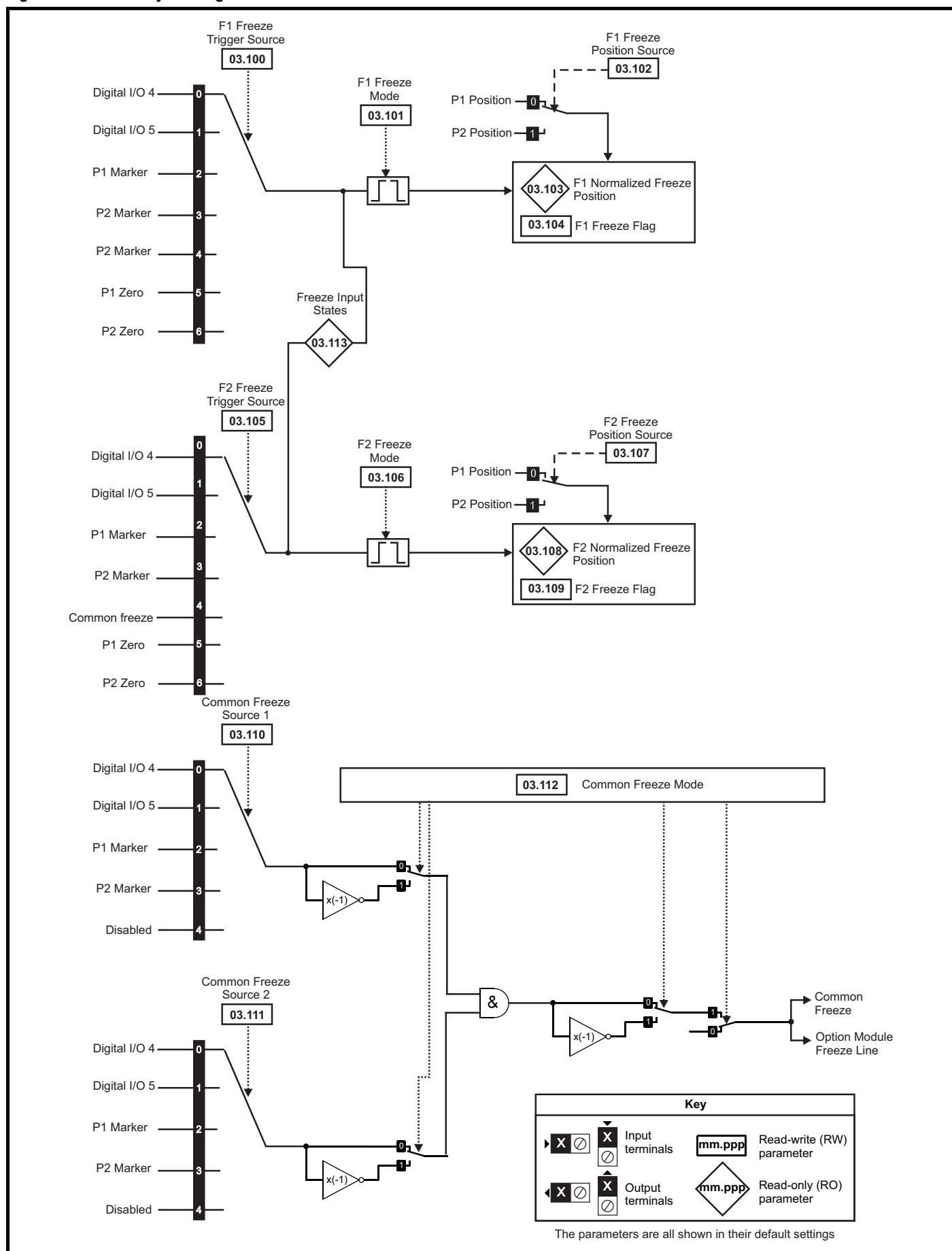


Figure 12-8 P1 Position feedback interface thermistor input

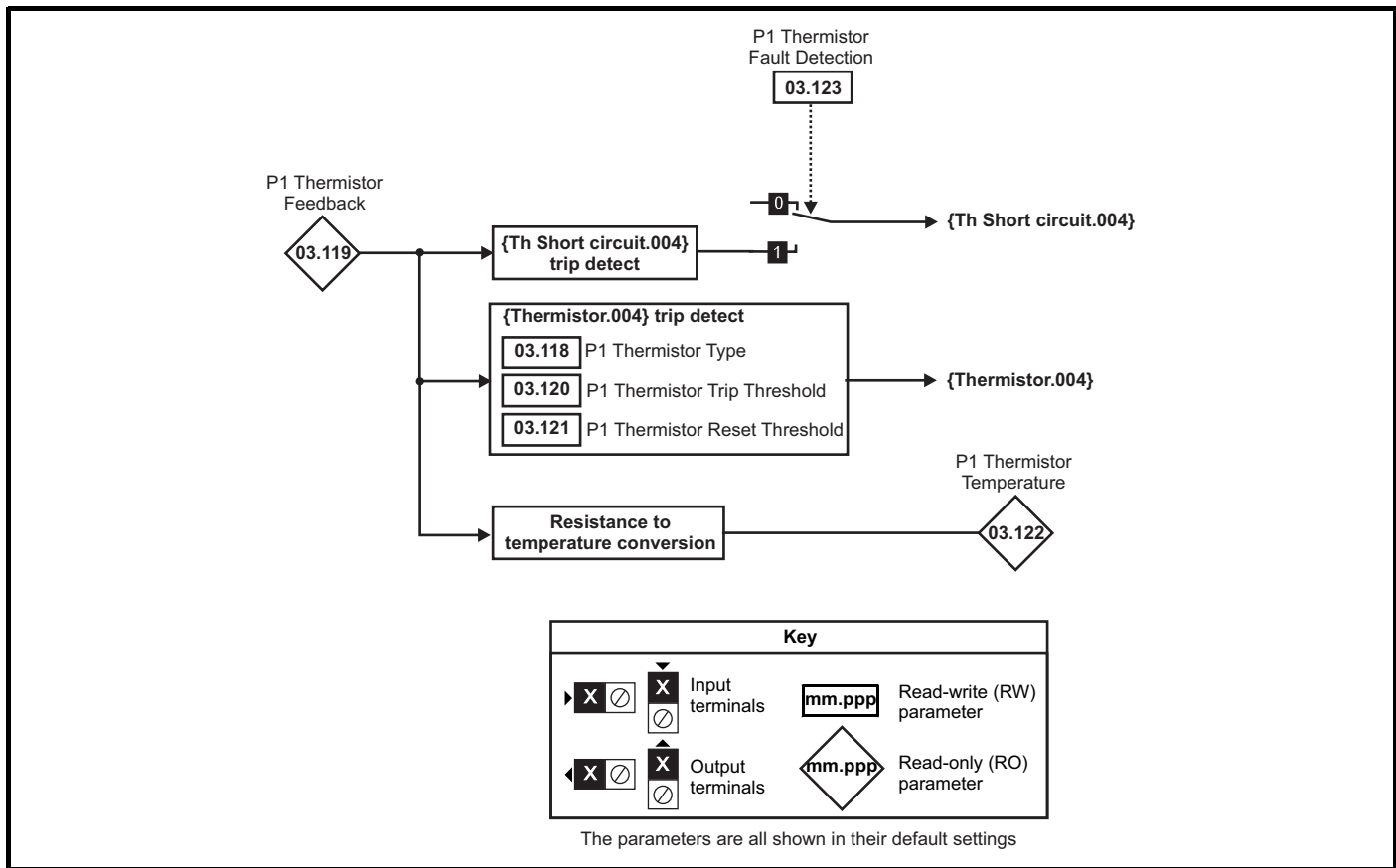
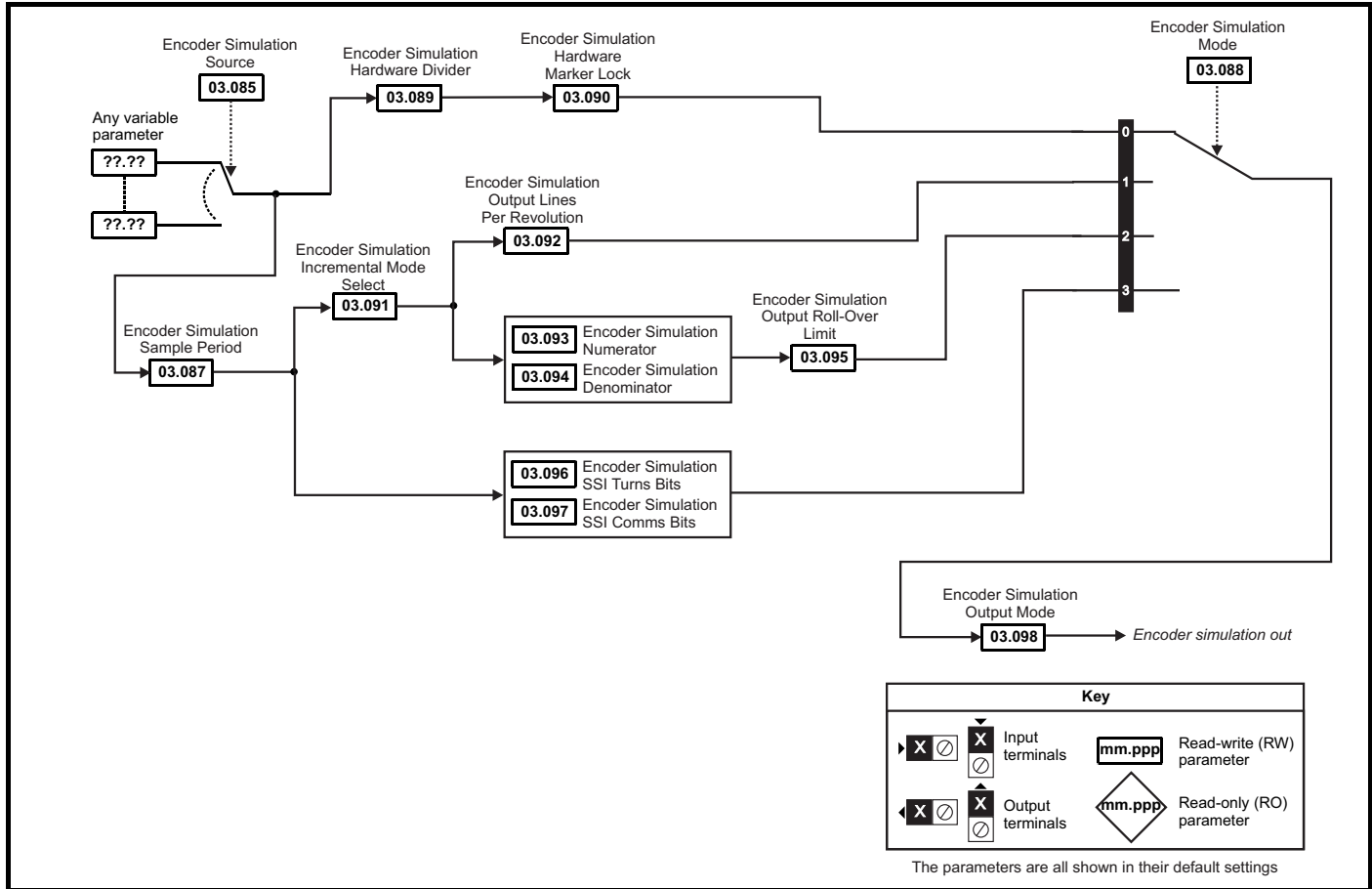


Figure 12-9 Encoder simulation



| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                                      | Range                                                                                                                                                                                                                                                                                                                               |                                                                                                                                                                      |                | Default     |                          |                          | Type |     |    |    |    |    |
|-----------|------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------|-------------|--------------------------|--------------------------|------|-----|----|----|----|----|
|           |                                                      | OL                                                                                                                                                                                                                                                                                                                                  | RFC-A                                                                                                                                                                | RFC-S          | OL          | RFC-A                    | RFC-S                    |      |     |    |    |    |    |
| 03.001    | Open-loop> Frequency Slaving Demand                  | ±1000.0 Hz                                                                                                                                                                                                                                                                                                                          |                                                                                                                                                                      |                |             |                          |                          | RO   | Num | ND | NC | PT | FI |
|           | RFC> Final Speed Reference                           |                                                                                                                                                                                                                                                                                                                                     | VM_SPEED                                                                                                                                                             |                |             |                          |                          | RO   | Num | ND | NC | PT | FI |
| 03.002    | Speed Feedback                                       |                                                                                                                                                                                                                                                                                                                                     | VM_SPEED                                                                                                                                                             |                |             |                          |                          | RO   | Num | ND | NC | PT | FI |
| 03.003    | Speed Error                                          |                                                                                                                                                                                                                                                                                                                                     | VM_SPEED                                                                                                                                                             |                |             |                          |                          | RO   | Num | ND | NC | PT | FI |
| 03.004    | Speed Controller Output                              |                                                                                                                                                                                                                                                                                                                                     | VM_TORQUE_CURRENT %                                                                                                                                                  |                |             |                          |                          | RO   | Num | ND | NC | PT | FI |
| 03.005    | Zero Speed Threshold                                 | 0.0 to 20.0 Hz                                                                                                                                                                                                                                                                                                                      | 0 to 200 rpm                                                                                                                                                         |                | 1.0 Hz      | 5 rpm                    |                          | RW   | Num |    |    |    | US |
| 03.006    | At Speed Lower Limit                                 | 0.0 to 599.0 Hz                                                                                                                                                                                                                                                                                                                     | 0 to 33,000 rpm                                                                                                                                                      |                | 1.0 Hz      | 5 rpm                    |                          | RW   | Num |    |    |    | US |
| 03.007    | At Speed Upper Limit                                 | 0.0 to 599.0 Hz                                                                                                                                                                                                                                                                                                                     | 0 to 33,000 rpm                                                                                                                                                      |                | 1.0 Hz      | 5 rpm                    |                          | RW   | Num |    |    |    | US |
| 03.008    | Over Speed Threshold                                 | 0.0 to 599.0 Hz                                                                                                                                                                                                                                                                                                                     | 0 to 33,000 rpm                                                                                                                                                      |                | 0.0 Hz      | 0 rpm                    |                          | RW   | Num |    |    |    | US |
| 03.009    | Absolute At Speed Select                             | Off (0) or On (1)                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                                      |                | Off (0)     |                          |                          | RW   | Bit |    |    |    | US |
| 03.010    | Speed Controller Proportional Gain Kp1               |                                                                                                                                                                                                                                                                                                                                     | 0.0000 to 200.0000 s/rad                                                                                                                                             |                |             | 0.0300 s/rad             | 0.0100 s/rad             | RW   | Num |    |    |    | US |
| 03.011    | Speed Controller Integral Gain Ki1                   |                                                                                                                                                                                                                                                                                                                                     | 0.00 to 655.35 s <sup>2</sup> /rad                                                                                                                                   |                |             | 0.10 s <sup>2</sup> /rad | 1.00 s <sup>2</sup> /rad | RW   | Num |    |    |    | US |
| 03.012    | Speed Controller Differential Feedback Gain Kd1      |                                                                                                                                                                                                                                                                                                                                     | 0.00000 to 0.65535 1/rad                                                                                                                                             |                |             | 0.00000 1/rad            |                          | RW   | Num |    |    |    | US |
| 03.013    | Open-loop> Enable Frequency Slaving                  | Off (0) or On (1)                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                                      |                | Off (0)     |                          |                          | RW   | Bit |    |    |    | US |
|           | RFC> Speed Controller Proportional Gain Kp2          |                                                                                                                                                                                                                                                                                                                                     | 0.0000 to 200.0000 s/rad                                                                                                                                             |                |             | 0.0300 s/rad             | 0.0100 s/rad             | RW   | Num |    |    |    | US |
| 03.014    | Open-loop> Slaving Ratio Numerator                   | 0.000 to 1.000                                                                                                                                                                                                                                                                                                                      |                                                                                                                                                                      |                | 1.000       |                          |                          | RW   | Num |    |    |    | US |
|           | RFC> Speed Controller Integral Gain Ki2              |                                                                                                                                                                                                                                                                                                                                     | 0.00 to 655.35 s <sup>2</sup> /rad                                                                                                                                   |                |             | 0.10 s <sup>2</sup> /rad | 1.00 s <sup>2</sup> /rad | RW   | Num |    |    |    | US |
| 03.015    | Open-loop> Slaving Ratio Denominator                 | 0.001 to 1.000                                                                                                                                                                                                                                                                                                                      |                                                                                                                                                                      |                | 1.000       |                          |                          | RW   | Num |    |    |    | US |
|           | RFC> Speed Controller Differential Feedback Gain Kd2 |                                                                                                                                                                                                                                                                                                                                     | 0.00000 to 0.65535 1/rad                                                                                                                                             |                |             | 0.00000 1/rad            |                          | RW   | Num |    |    |    | US |
| 03.016    | Open-loop> Reference Frame Angle                     | 0 to 65535                                                                                                                                                                                                                                                                                                                          |                                                                                                                                                                      |                |             |                          |                          | RO   | Num | ND | NC | PT |    |
|           | RFC> Speed Controller Gain Select                    |                                                                                                                                                                                                                                                                                                                                     | Off (0) or On (1)                                                                                                                                                    |                |             | Off (0)                  |                          | RW   | Bit |    |    |    | US |
| 03.017    | Speed Controller Set-up Method                       |                                                                                                                                                                                                                                                                                                                                     | Disabled (0), Bandwidth (1),<br>Comp Angle (2),<br>Kp Gain Times 16 (3),<br>Low Performance (4),<br>Std Performance (5),<br>High Performance (6),<br>First Order (7) |                |             | Disabled (0)             |                          | RW   | Txt |    |    |    | US |
| 03.018    | Motor And Load Inertia                               |                                                                                                                                                                                                                                                                                                                                     | 0.00000 to 1000.00000 kgm <sup>2</sup>                                                                                                                               |                |             | 0.00000 kgm <sup>2</sup> |                          | RW   | Num |    |    |    | US |
| 03.019    | Compliance Angle                                     |                                                                                                                                                                                                                                                                                                                                     | 0.0 to 360.0 °                                                                                                                                                       |                |             | 4.0 °                    |                          | RW   | Num |    |    |    | US |
| 03.020    | Bandwidth                                            |                                                                                                                                                                                                                                                                                                                                     | 5 to 1000 Hz                                                                                                                                                         |                |             | 10 Hz                    |                          | RW   | Num |    |    |    | US |
| 03.021    | Damping Factor                                       |                                                                                                                                                                                                                                                                                                                                     | 0.0 to 10.0                                                                                                                                                          |                |             | 1.0                      |                          | RW   | Num |    |    |    | US |
| 03.022    | Hard Speed Reference                                 |                                                                                                                                                                                                                                                                                                                                     | VM_SPEED_FREQ_REF                                                                                                                                                    |                |             | 0.0                      |                          | RW   | Num |    |    |    | US |
| 03.023    | Hard Speed Reference Select                          |                                                                                                                                                                                                                                                                                                                                     | Off (0) or On (1)                                                                                                                                                    |                |             | Off (0)                  |                          | RW   | Bit |    |    |    | US |
| 03.024    | RFC Feedback Mode                                    |                                                                                                                                                                                                                                                                                                                                     | Feedback (0), Sensorless (1),<br>Feedback NoMax (2),<br>Sensorless NoMax (3)                                                                                         |                |             | Feedback (0)             |                          | RW   | Txt |    |    |    | US |
| 03.025    | Position Feedback Phase Angle                        |                                                                                                                                                                                                                                                                                                                                     |                                                                                                                                                                      | 0.0 to 359.9 ° |             |                          | 0.0 °                    | RW   | Num | ND |    |    | US |
| 03.026    | Motor Control Feedback Select                        |                                                                                                                                                                                                                                                                                                                                     | P1 Drive (0), P2 Drive (1),<br>P1 Slot 1 (2), P2 Slot 1 (3),<br>P1 Slot 2 (4), P2 Slot 2 (5),<br>P1 Slot 3 (6), P2 Slot 3 (7)                                        |                |             | P1 Drive (0)             |                          | RW   | Txt |    |    |    | US |
| 03.027    | P1 Speed Feedback                                    | VM_SPEED                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                      |                |             |                          |                          | RO   | Num | ND | NC | PT | FI |
| 03.028    | P1 Revolution/Pole Pitch Counter                     | 0 to 65535                                                                                                                                                                                                                                                                                                                          |                                                                                                                                                                      |                |             |                          |                          | RO   | Num | ND | NC | PT | PS |
| 03.029    | P1 Position                                          | 0 to 65535                                                                                                                                                                                                                                                                                                                          |                                                                                                                                                                      |                |             |                          |                          | RO   | Num | ND | NC | PT | PS |
| 03.030    | P1 Fine Position                                     | 0 to 65535                                                                                                                                                                                                                                                                                                                          |                                                                                                                                                                      |                |             |                          |                          | RO   | Num | ND | NC | PT |    |
| 03.031    | P1 Marker Mode                                       | 0000 to 1111                                                                                                                                                                                                                                                                                                                        |                                                                                                                                                                      |                | 0100        |                          |                          | RW   | Bin |    |    |    | US |
| 03.032    | P1 Marker Flag                                       | Off (0) or On (1)                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                                      |                | Off (0)     |                          |                          | RW   | Bit |    | NC |    |    |
| 03.033    | P1 Rotary Turns Bits                                 | 0 to 16                                                                                                                                                                                                                                                                                                                             |                                                                                                                                                                      |                | 16          |                          |                          | RW   | Num |    |    |    | US |
| 03.034    | P1 Rotary Lines Per Revolution                       | 1 to 100000                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                      |                | 1024        |                          | 4096                     | RW   | Num |    |    |    | US |
| 03.035    | P1 Comms Bits                                        | 0 to 48                                                                                                                                                                                                                                                                                                                             |                                                                                                                                                                      |                | 0           |                          |                          | RW   | Num |    |    |    | US |
| 03.036    | P1 Supply Voltage                                    | 5V (0), 8V (1), 15V (2)                                                                                                                                                                                                                                                                                                             |                                                                                                                                                                      |                | 5V (0)      |                          |                          | RW   | Txt |    |    |    | US |
| 03.037    | P1 Comms Baud Rate                                   | 100k (0), 200k (1), 300k (2), 400k (3), 500k (4),<br>1M (5), 1.5M (6), 2M (7), 4M (8)                                                                                                                                                                                                                                               |                                                                                                                                                                      |                | 300k (2)    |                          |                          | RW   | Txt |    |    |    | US |
| 03.038    | P1 Device Type                                       | AB (0), FD (1), FR (2), AB Servo (3), FD Servo (4),<br>FR Servo (5), SC (6), SC Hiperface (7), EnDat (8),<br>SC EnDat (9), SSI (10), SC SSI (11), SC Servo (12),<br>BiSS (13), Resolver (14), SC SC (15), Commutation<br>Only (16), SC BiSS (17), Option Slot 1 (18), Option<br>Slot 2 (19), Option Slot 3 (20), Option Slot 4 (21) |                                                                                                                                                                      |                | AB (0)      |                          | AB Servo (3)             | RW   | Txt |    |    |    | US |
| 03.039    | P1 Termination Select                                | 0 to 2                                                                                                                                                                                                                                                                                                                              |                                                                                                                                                                      |                | 1           |                          |                          | RW   | Num |    |    |    | US |
| 03.040    | P1 Error Detection Level                             | 00000000 to 11111111                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                      |                | 00000000    | 00000001                 |                          | RW   | Bin |    |    |    | US |
| 03.041    | P1 Auto-configuration Select                         | Disabled (0) or Enabled (1)                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                      |                | Enabled (1) |                          |                          | RW   | Txt |    |    |    | US |

| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
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| Parameter |                                                | Range                                                                                                                      |                                         |       | Default             |              |          | Type |     |    |    |    |    |
|-----------|------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------|-----------------------------------------|-------|---------------------|--------------|----------|------|-----|----|----|----|----|
|           |                                                | OL                                                                                                                         | RFC-A                                   | RFC-S | OL                  | RFC-A        | RFC-S    |      |     |    |    |    |    |
| 03.042    | P1 Feedback Filter                             | Disabled (0), 1 (1), 2 (2), 4 (3), 8 (4), 16 (5) ms                                                                        |                                         |       | Disabled (0)        |              |          | RW   | Txt |    |    |    | US |
| 03.043    | P1 Maximum Reference                           | 0 to 35,940 rpm                                                                                                            | 0 to 33,000 rpm                         |       | 1500 rpm            |              | 3000 rpm | RW   | Txt |    |    |    | US |
| 03.044    | P1 Reference Scaling                           | 0.000 to 4.000                                                                                                             |                                         |       | 1.000               |              |          | RW   | Num |    |    |    | US |
| 03.045    | P1 Reference                                   | ±100.0 %                                                                                                                   |                                         |       |                     |              |          | RO   | Num | ND | NC | PT | FI |
| 03.046    | P1 Reference destination                       | 0.000 to 59.999                                                                                                            |                                         |       | 0.000               |              |          | RW   | Num | DE |    | PT | US |
| 03.047    | P1 SSI Incremental Mode                        | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    |    |    | US |
| 03.048    | P1 SSI Binary Mode                             | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    |    |    | US |
| 03.049    | P1 Additional Power-up Delay                   | 0.0 to 25.0 s                                                                                                              |                                         |       | 0.0 s               |              |          | RW   | Num |    |    |    | US |
| 03.050    | P1 Feedback Lock                               | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    |    |    | US |
| 03.051    | P1 Linear Feedback Select                      | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    |    |    | US |
| 03.052    | P1 Linear Comms Pitch                          | 0.001 to 100.000                                                                                                           |                                         |       | 0.001               |              |          | RW   | Num |    |    |    | US |
| 03.053    | P1 Linear Line Pitch                           | 0.001 to 100.000                                                                                                           |                                         |       | 0.001               |              |          | RW   | Num |    |    |    | US |
| 03.054    | P1 Linear Comms And Line Pitch Units           | millimetres (0) or micrometres (1)                                                                                         |                                         |       | millimetres (0)     |              |          | RW   | Txt |    |    |    | US |
| 03.055    | P1 Pole Pitch                                  | 0.01 to 1000.00 mm                                                                                                         |                                         |       | 10.00 mm            |              |          | RW   | Num |    |    |    | US |
| 03.056    | P1 Feedback Reverse                            | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    |    |    | US |
| 03.057    | P1 Normalization Turns                         | 0 to 16                                                                                                                    |                                         |       | 16                  |              |          | RW   | Num |    |    |    | US |
| 03.058    | P1 Normalized Position                         | -2147483648 to 2147483647                                                                                                  |                                         |       |                     |              |          | RO   | Num | ND | NC | PT |    |
| 03.059    | P1 Normalized Marker Position                  | -2147483648 to 2147483647                                                                                                  |                                         |       |                     |              |          | RO   | Num | ND | NC | PT |    |
| 03.060    | P1 Calculation Time                            | 0 to 20 µs                                                                                                                 |                                         |       | 5 µs                |              |          | RW   | Num |    |    |    | US |
| 03.061    | P1 Recovery Time                               | 5 to 100 µs                                                                                                                |                                         |       | 30 µs               |              |          | RW   | Num |    |    |    | US |
| 03.062    | P1 Line Delay Time                             | 0 to 5000 ns                                                                                                               |                                         |       |                     |              |          | RO   | Num | ND | NC | PT | US |
| 03.063    | P1 Low Speed Update Rate Active                | Off (0) or On (1)                                                                                                          |                                         |       |                     |              |          | RO   | Bit | ND | NC | PT |    |
| 03.064    | P1 Encoder Protocol Detected                   | None (0), Hiperface (1), EnDat 2.1 (2), EnDat 2.2 (3), BiSS (4)                                                            |                                         |       |                     |              |          | RO   | Txt | ND | NC | PT |    |
| 03.065    | P1 Resolver Poles                              | 2 Poles (1) to 20 Poles (10)                                                                                               |                                         |       | 2 Poles (1)         |              |          | RW   |     |    |    |    | US |
| 03.066    | P1 Resolver Excitation                         | 6kHz 3V (0), 8kHz 3V (1), 6kHz 2V (2), 8kHz 2V (3), 6kHz 3V Fast (4), 8kHz 3V Fast (5), 6kHz 2V Fast (6), 8kHz 2V Fast (7) |                                         |       | 6kHz 3V (0)         |              |          | RW   | Txt |    |    |    | US |
| 03.067    | P1 User Comms Enable                           | 0 to 1                                                                                                                     |                                         |       | 0                   |              |          | RW   | Num |    | NC | PT |    |
| 03.068    | P1 User Comms Transmit Register                | 0 to 65535                                                                                                                 |                                         |       | 0                   |              |          | RW   | Num |    | NC | PT |    |
| 03.069    | P1 User Comms Receive Register                 | 0 to 65535                                                                                                                 |                                         |       | 0                   |              |          | RW   | Num |    | NC | PT |    |
| 03.070    | P1 Position Feedback Signals                   | 000000 to 111111                                                                                                           |                                         |       |                     |              |          | RO   | Bin | ND | NC | PT |    |
| 03.071    | P1 Error Detected                              | Off (0) or On (1)                                                                                                          |                                         |       |                     |              |          | RO   | Bit | ND | NC | PT |    |
| 03.073    | P1 Absolute Turns Recovery Enable              | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    |    |    | US |
| 03.074    | P1 Additional Configuration                    | 0 to 511116116                                                                                                             |                                         |       | 0                   |              |          | RW   | Num |    |    |    | US |
| 03.075    | Initialise Position Feedback                   | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    | NC |    |    |
| 03.076    | Position Feedback Initialized                  | 0000000000 to 1111111111                                                                                                   |                                         |       | 0000000000          |              |          | RO   | Bin |    | NC | PT |    |
| 03.078    | Sensorless Mode Active                         |                                                                                                                            | Off (0) or On (1)                       |       |                     |              |          | RO   | Bit | ND | NC | PT |    |
| 03.079    | Sensorless Mode Filter                         |                                                                                                                            | 4 (0), 8 (1), 16 (2), 32 (3), 64 (4) ms |       |                     | 4 ms         | 64 ms    | RW   | Txt |    |    |    | US |
| 03.080    | Sensorless Position                            |                                                                                                                            | -2147483648 to 2147483647               |       |                     |              |          | RO   | Num | ND | NC | PT |    |
| 03.083    | Full Motor Object Nameplate Transfer           | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    |    |    | US |
| 03.085    | Encoder Simulation Source                      | 0.000 to 59.999                                                                                                            |                                         |       | 3.016               | 0.000        |          | RW   | Num |    |    | PT | US |
| 03.086    | Encoder Simulation Status                      | None (0), Full (1), No Marker Pulse (2)                                                                                    |                                         |       |                     |              |          | RO   | Txt | ND | NC | PT |    |
| 03.087    | Encoder Simulation Sample Period               | 0.25 (0), 1 (1), 4, (2), 16 (3) ms                                                                                         |                                         |       | 4 (2) ms            | 0.25 (0) ms  |          | RW   | Txt |    |    |    | US |
| 03.088    | Encoder Simulation Mode                        | Hardware (0), Lines Per Rev (1), Ratio (2), SSI (3)                                                                        |                                         |       | Lines Per Rev (1)   | Hardware (0) |          | RW   | Txt |    |    |    | US |
| 03.089    | Encoder Simulation Hardware Divider            | 0 to 7                                                                                                                     |                                         |       | 0                   |              |          | RW   | Num |    |    |    | US |
| 03.090    | Encoder Simulation Hardware Marker Lock        | Off (0) or On (1)                                                                                                          |                                         |       | Off (0)             |              |          | RW   | Bit |    |    |    | US |
| 03.091    | Encoder Simulation Incremental Mode Select     | Off (0) or On (1)                                                                                                          |                                         |       | On (1)              | Off (0)      |          | RW   | Bit |    |    |    | US |
| 03.092    | Encoder Simulation Output Lines Per Revolution | 1 to 16384                                                                                                                 |                                         |       | 1024                | 4096         |          | RW   | Num |    |    |    | US |
| 03.093    | Encoder Simulation Numerator                   | 1 to 65536                                                                                                                 |                                         |       | 65536               |              |          | RW   | Num |    |    |    | US |
| 03.094    | Encoder Simulation Denominator                 | 1 to 65536                                                                                                                 |                                         |       | 65536               |              |          | RW   | Num |    |    |    | US |
| 03.095    | Encoder Simulation Output Roll-over Limit      | 1 to 65535                                                                                                                 |                                         |       | 65535               |              |          | RW   | Num |    |    |    | US |
| 03.096    | Encoder Simulation SSI Turns Bits              | 0 to 16                                                                                                                    |                                         |       | 16                  |              |          | RW   | Num |    |    |    | US |
| 03.097    | Encoder Simulation SSI Comms Bits              | 2 to 48                                                                                                                    |                                         |       | 33                  |              |          | RW   | Num |    |    |    | US |
| 03.098    | Encoder Simulation Output Mode                 | AB/Gray (0), FD/Binary (1), FR/Binary (2)                                                                                  |                                         |       | AB/Gray (0)         |              |          | RW   | Txt |    |    |    | US |
| 03.100    | F1 Freeze Trigger Source                       | Digital Input 4 (0), Digital Input 5 (1), P1 Marker (2), P2 Marker (3), Common (4), P1 Zero (5), P2 Zero (6)               |                                         |       | Digital Input 4 (0) |              |          | RW   | Txt |    |    |    | US |
| 03.101    | F1 Freeze Mode                                 | Rising 1st (0), Falling 1st (1), Rising all (2), Falling all (3)                                                           |                                         |       | Rising 1st (0)      |              |          | RW   | Txt |    |    |    | US |

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| Parameter |                                      | Range                                                                                                        |                 |       | Default             |       |          | Type |     |    |    |    |    |    |
|-----------|--------------------------------------|--------------------------------------------------------------------------------------------------------------|-----------------|-------|---------------------|-------|----------|------|-----|----|----|----|----|----|
|           |                                      | OL                                                                                                           | RFC-A           | RFC-S | OL                  | RFC-A | RFC-S    |      |     |    |    |    |    |    |
| 03.102    | F1 Freeze Position Source            | P1 (0), P2 (1), Time (2)                                                                                     |                 |       | P1 (0)              |       |          | RW   | Txt |    |    |    |    | US |
| 03.103    | F1 Normalized Freeze Position        | -2147483648 to 2147483647                                                                                    |                 |       |                     |       |          | RO   | Num | ND | NC | PT |    |    |
| 03.104    | F1 Freeze Flag                       | Off (0) or On (1)                                                                                            |                 |       | Off (0)             |       |          | RW   | Bit | ND | NC | PT |    |    |
| 03.105    | F2 Freeze Trigger Source             | Digital Input 4 (0), Digital Input 5 (1), P1 Marker (2), P2 Marker (3), Common (4), P1 Zero (5), P2 Zero (6) |                 |       | Digital Input 4 (0) |       |          | RW   | Txt |    |    |    |    | US |
| 03.106    | F2 Freeze Mode                       | Rising 1st (0), Falling 1st (1), Rising all (2), Falling all (3)                                             |                 |       | Rising 1st (0)      |       |          | RW   | Txt |    |    |    |    | US |
| 03.107    | F2 Freeze Position Source            | P1 (0), P2 (1), Time (2)                                                                                     |                 |       | P1 (0)              |       |          | RW   | Txt |    |    |    |    | US |
| 03.108    | F2 Normalized Freeze Position        | -2147483648 to 2147483647                                                                                    |                 |       |                     |       |          | RO   | Num | ND | NC | PT |    |    |
| 03.109    | F2 Freeze Flag                       | Off (0) or On (1)                                                                                            |                 |       | Off (0)             |       |          | RW   | Bit | ND | NC | PT |    |    |
| 03.110    | Common Freeze Source 1               | Digital Input 4 (0), Digital Input 5 (1), P1 Marker (2), P2 Marker (3), Disabled (4)                         |                 |       | Digital Input 4 (0) |       |          | RW   | Txt |    |    |    |    | US |
| 03.111    | Common Freeze Source 2               | Digital Input 4 (0), Digital Input 5 (1), P1 Marker (2), P2 Marker (3), Disabled (4)                         |                 |       | Digital Input 4 (0) |       |          | RW   | Txt |    |    |    |    | US |
| 03.112    | Common Freeze Mode                   | 0000 to 1111                                                                                                 |                 |       | 0000                |       |          | RW   | Bin |    |    |    |    | US |
| 03.113    | Freeze Input States                  | 00 to 11                                                                                                     |                 |       |                     |       |          | RO   | Bin | ND | NC | PT |    |    |
| 03.118    | P1 Thermistor Type                   | DIN44082 (0), KTY84 (1), 0.8mA (2), Encoder (3)                                                              |                 |       | DIN44082 (0)        |       |          | RW   | Txt |    |    |    |    | US |
| 03.119    | P1 Thermistor Feedback               | 0 to 5000 Ω                                                                                                  |                 |       |                     |       |          | RO   | Num | ND | NC | PT |    |    |
| 03.120    | P1 Thermistor Trip Threshold         | 0 to 5000 Ω                                                                                                  |                 |       | 3300 Ω              |       |          | RW   | Num |    |    |    |    | US |
| 03.121    | P1 Thermistor Reset Threshold        | 0 to 5000 Ω                                                                                                  |                 |       | 1800 Ω              |       |          | RW   | Num |    |    |    |    | US |
| 03.122    | P1 Thermistor Temperature            | -50 to 300 °C                                                                                                |                 |       |                     |       |          | RO   | Num | ND | NC | PT |    |    |
| 03.123    | P1 Thermistor Fault Detection        | None (0), Temperature (1), Temp or Short (2)                                                                 |                 |       | None (0)            |       |          | RW   | Txt |    |    |    |    | US |
| 03.127    | P2 Speed Feedback                    | ±VM_SPEED                                                                                                    |                 |       |                     |       |          | RO   | Num | ND | NC | PT | FI |    |
| 03.128    | P2 Revolution/Pole Pitch Counter     | 0 to 65535                                                                                                   |                 |       |                     |       |          | RO   | Num | ND | NC | PT | PS |    |
| 03.129    | P2 Position                          | 0 to 65535                                                                                                   |                 |       |                     |       |          | RO   | Num | ND | NC | PT | PS |    |
| 03.130    | P2 Fine Position                     | 0 to 65535                                                                                                   |                 |       |                     |       |          | RO   | Num | ND | NC | PT |    |    |
| 03.131    | P2 Marker Mode                       | 0000 to 1111                                                                                                 |                 |       | 0100                |       |          | RW   | Bin |    |    |    |    | US |
| 03.132    | P2 Marker Flag                       | Off (0) or On (1)                                                                                            |                 |       | Off (0)             |       |          | RW   | Bit |    | NC |    |    |    |
| 03.133    | P2 Rotary Turns Bits                 | 0 to 16                                                                                                      |                 |       | 16                  |       |          | RW   | Num |    |    |    |    | US |
| 03.134    | P2 Rotary Lines Per Revolution       | 0 to 100000                                                                                                  |                 |       | 1024                |       | 4096     | RW   | Num |    |    |    |    | US |
| 03.135    | P2 Comms Bits                        | 0 to 48                                                                                                      |                 |       | 0                   |       |          | RW   | Num |    |    |    |    | US |
| 03.137    | P2 Comms Baud Rate                   | 100k (0), 200k (1), 300k (2), 400k (3), 500k (4), 1M (5), 1.5M (6), 2M (7), 4M (8) Baud                      |                 |       | 300k (2) Baud       |       |          | RW   | Txt |    |    |    |    | US |
| 03.138    | P2 Device type                       | None (0), AB (1), FD (2), FR (3), EnDat (4), SSI (5), BiSS (6)                                               |                 |       | None (0)            |       |          | RW   | Txt |    |    |    |    | US |
| 03.140    | P2 Error Detection Level             | 00000 to 11111                                                                                               |                 |       | 00001               |       |          | RW   | Bin |    |    |    |    | US |
| 03.141    | P2 Auto-configuration Select         | Disabled (0), Enabled (1)                                                                                    |                 |       | Enabled (1)         |       |          | RW   | Txt |    |    |    |    | US |
| 03.142    | P2 Feedback Filter                   | Disabled (0), 1 (1), 2 (2), 4 (3), 8 (4), 16 (5) ms                                                          |                 |       | Disabled (0)        |       |          | RW   | Txt |    |    |    |    | US |
| 03.143    | P2 Maximum Reference                 | 0 to 35,940 rpm                                                                                              | 0 to 33,000 rpm |       | 1500 rpm            |       | 3000 rpm | RW   | Txt |    |    |    |    | US |
| 03.144    | P2 Reference Scaling                 | 0.000 to 4.000                                                                                               |                 |       | 1.000               |       |          | RW   | Num |    |    |    |    | US |
| 03.145    | P2 Reference                         | ±100.0 %                                                                                                     |                 |       |                     |       |          | RO   | Num | ND | NC | PT | FI |    |
| 03.146    | P2 Reference Destination             | 0.000 to 59.999                                                                                              |                 |       | 0.000               |       |          | RW   | Num | DE |    | PT | US |    |
| 03.147    | P2 SSI Incremental Mode              | Off (0) or On (1)                                                                                            |                 |       | Off (0)             |       |          | RW   | Bit |    |    |    |    | US |
| 03.148    | P2 SSI Binary Mode                   | Off (0) or On (1)                                                                                            |                 |       | Off (0)             |       |          | RW   | Bit |    |    |    |    | US |
| 03.149    | P2 Additional Power-up Delay         | 0.0 to 25.0 s                                                                                                |                 |       | 0.0 s               |       |          | RW   | Num |    |    |    |    | US |
| 03.150    | P2 Feedback Lock                     | Off (0) or On (1)                                                                                            |                 |       | Off (0)             |       |          | RW   | Bit |    |    |    |    | US |
| 03.151    | P2 Linear Feedback Select            | Off (0) or On (1)                                                                                            |                 |       | Off (0)             |       |          | RW   | Bit |    |    |    |    | US |
| 03.152    | P2 Linear Comms Pitch                | 0.001 to 100.000                                                                                             |                 |       | 0.001               |       |          | RW   | Num |    |    |    |    | US |
| 03.153    | P2 Linear Line Pitch                 | 0.001 to 100.000                                                                                             |                 |       | 0.001               |       |          | RW   | Num |    |    |    |    | US |
| 03.154    | P2 Linear Comms And Line Pitch Units | Millimetres (0) or Micrometres (1)                                                                           |                 |       | Millimetres (0)     |       |          | RW   | Txt |    |    |    |    | US |
| 03.155    | P2 Pole Pitch                        | 0.01 to 1000.00 mm                                                                                           |                 |       | 10.00 mm            |       |          | RW   | Num |    |    |    |    | US |
| 03.156    | P2 Feedback Reverse                  | Off (0) or On (1)                                                                                            |                 |       | Off (0)             |       |          | RW   | Bit |    |    |    |    | US |
| 03.157    | P2 Normalization Turns               | 0 to 16                                                                                                      |                 |       | 16                  |       |          | RW   | Num |    |    |    |    | US |
| 03.158    | P2 Normalized Position               | -2147483648 to 2147483647                                                                                    |                 |       |                     |       |          | RO   | Num | ND | NC | PT |    |    |
| 03.159    | P2 Normalized Marker Position        | -2147483648 to 2147483647                                                                                    |                 |       |                     |       |          | RO   | Num | ND | NC | PT |    |    |
| 03.160    | P2 Calculation Time                  | 0 to 20 μs                                                                                                   |                 |       | 5 μs                |       |          | RW   | Num |    |    |    |    | US |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
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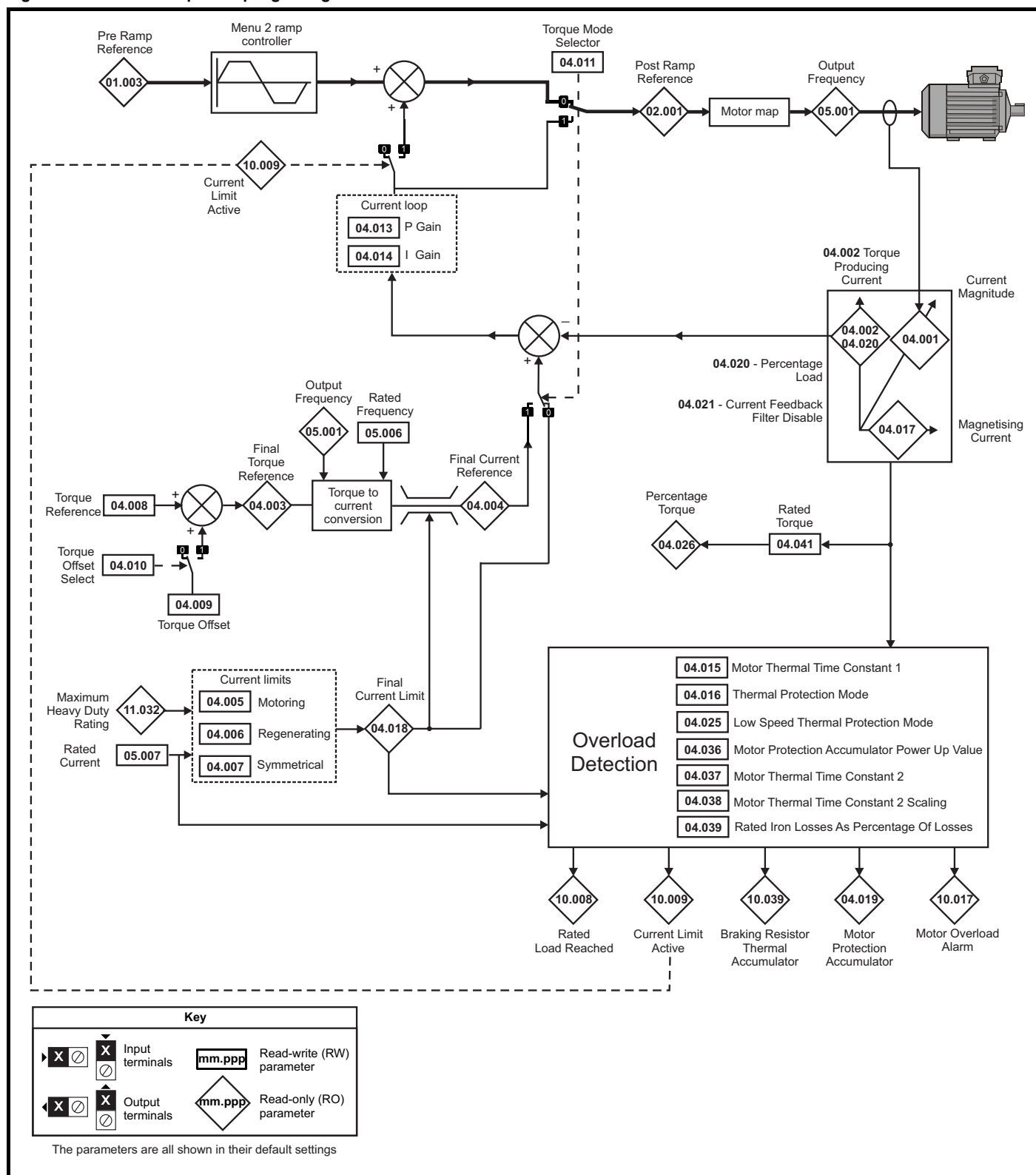
| Parameter |                                   | Range                                                                                                    |       |       | Default    |       |       | Type |     |    |    |    |    |
|-----------|-----------------------------------|----------------------------------------------------------------------------------------------------------|-------|-------|------------|-------|-------|------|-----|----|----|----|----|
|           |                                   | OL                                                                                                       | RFC-A | RFC-S | OL         | RFC-A | RFC-S |      |     |    |    |    |    |
| 03.161    | P2 Recovery Time                  | 5 to 100 $\mu$ s                                                                                         |       |       | 30 $\mu$ s |       |       | RW   | Num |    |    |    | US |
| 03.162    | P2 Line Delay Time                | 0 to 5000 ns                                                                                             |       |       |            |       |       | RO   | Num | ND | NC | PT | US |
| 03.163    | P2 Low Speed Update Rate Active   | Off (0) or On (1)                                                                                        |       |       |            |       |       | RO   | Bit | ND | NC | PT |    |
| 03.164    | P2 Encoder Protocol Detected      | None (0), Hiperface (1), EnDat 2.1 (2), EnDat 2.2 (3), BiSS (4)                                          |       |       |            |       |       | RO   | Txt | ND | NC | PT |    |
| 03.167    | P2 User Comms Enable              | 0 to 1                                                                                                   |       |       | 0          |       |       | RW   | Num |    | NC | PT |    |
| 03.168    | P2 User Comms Transmit Register   | 0 to 65535                                                                                               |       |       | 0          |       |       | RW   | Num |    | NC | PT |    |
| 03.169    | P2 User Comms Receive Register    | 0 to 65535                                                                                               |       |       | 0          |       |       | RW   | Num |    | NC | PT |    |
| 03.171    | P2 Error Detected                 | Off (0) or On (1)                                                                                        |       |       |            |       |       | RO   | Bit | ND | NC | PT |    |
| 03.172    | P2 Status                         | None (0), AB (1), FD (2), FR (3), EnDat (4), SSI (5), BiSS (6), EnDat Alt (7), SSI Alt (8), BiSS Alt (9) |       |       |            |       |       | RO   | Txt | ND | NC | PT |    |
| 03.173    | P2 Absolute Turns Recovery Enable | Off (0) or On (1)                                                                                        |       |       | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 03.174    | P2 Additional Configuration       | 0 to 511116116                                                                                           |       |       | 0          |       |       | RW   | Num |    |    |    | US |

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

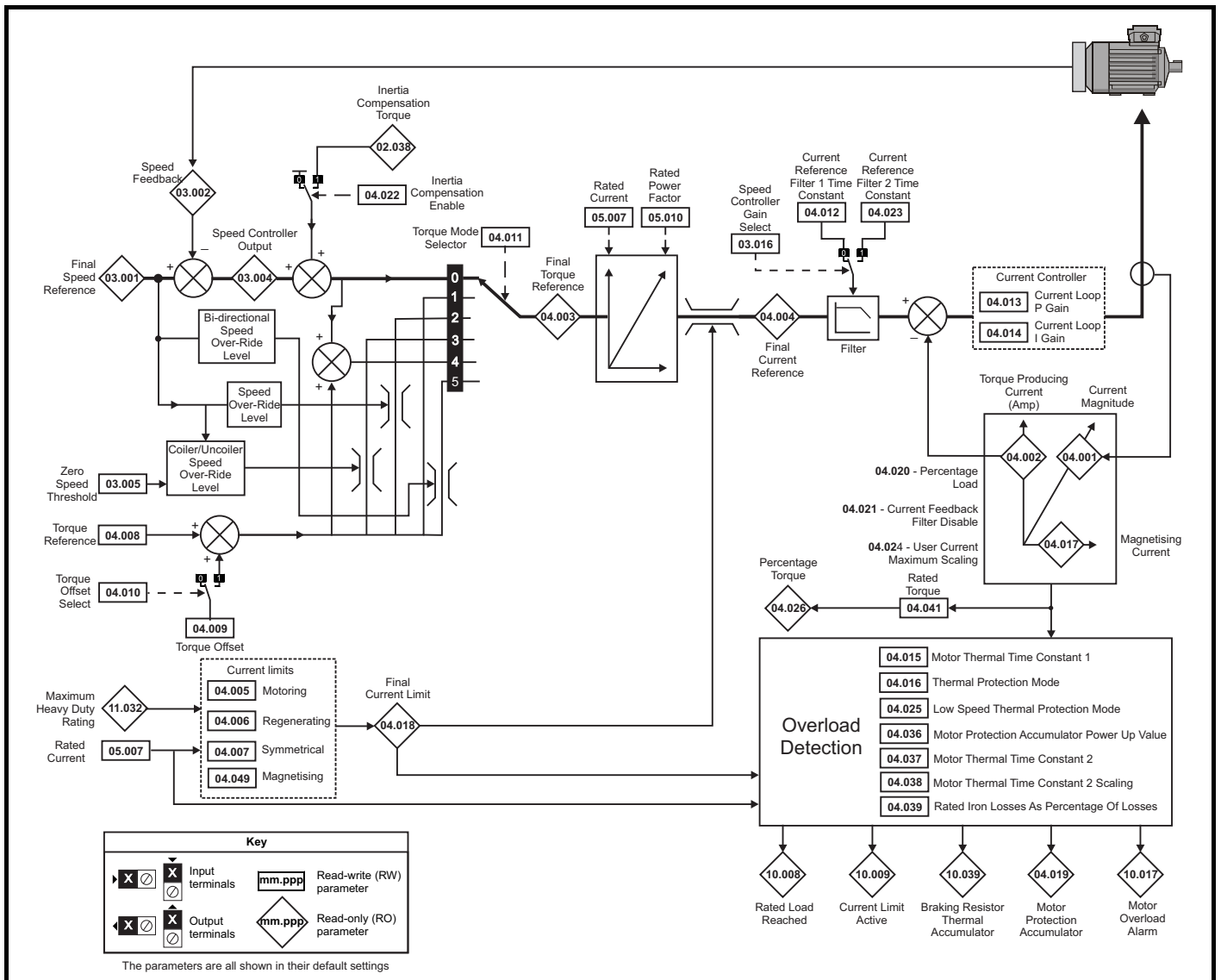
## 12.5 Menu 4: Torque and current control

Figure 12-10 Menu 4 Open loop logic diagram



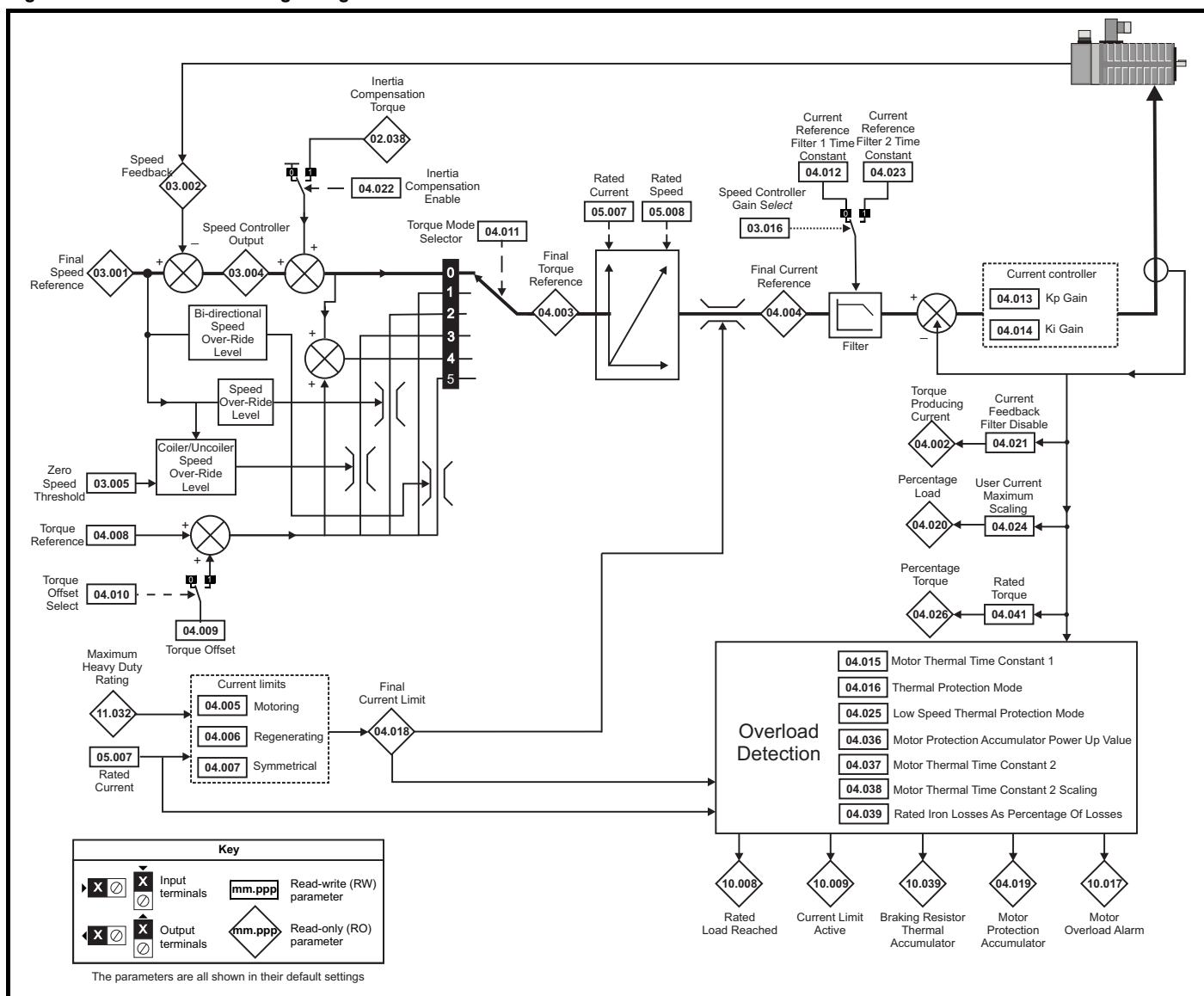
|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-11 Menu 4 RFC-A logic diagram



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-12 Menu 4 RFC-S logic diagram



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                              | Range(⇅)                                                                       |                   | Default(⇅)     |           |       | Type |     |    |    |    |    |
|-----------|----------------------------------------------|--------------------------------------------------------------------------------|-------------------|----------------|-----------|-------|------|-----|----|----|----|----|
|           |                                              | OL                                                                             | RFC-A / S         | OL             | RFC-A     | RFC-S |      |     |    |    |    |    |
| 04.001    | Current Magnitude                            | 0.000 to VM_DRIVE_CURRENT_UNIPOLAR A                                           |                   |                |           |       | RO   | Num | ND | NC | PT | FI |
| 04.002    | Torque Producing Current / Iq                | VM_DRIVE_CURRENT A                                                             |                   |                |           |       | RO   | Num | ND | NC | PT | FI |
| 04.003    | Final Torque Reference                       | VM_TORQUE_CURRENT %                                                            |                   |                |           |       | RO   | Num | ND | NC | PT | FI |
| 04.004    | Final Current Reference                      | VM_TORQUE_CURRENT %                                                            |                   |                |           |       | RO   | Num | ND | NC | PT | FI |
| 04.005    | Motoring Current Limit                       | 0.0 to VM_MOTOR1_CURRENT_LIMIT %                                               |                   | 165.0 %*       | 175.0 %** |       | RW   | Num |    | RA |    | US |
| 04.006    | Regenerating Current Limit                   | 0.0 to VM_MOTOR1_CURRENT_LIMIT %                                               |                   | 165.0 %*       | 175.0 %** |       | RW   | Num |    | RA |    | US |
| 04.007    | Symmetrical Current Limit                    | 0.0 to VM_MOTOR1_CURRENT_LIMIT %                                               |                   | 165.0 %*       | 175.0 %** |       | RW   | Num |    | RA |    | US |
| 04.008    | Torque Reference                             | VM_USER_CURRENT_HIGH_RES %                                                     |                   | 0.00 %         |           |       | RW   | Num |    |    |    | US |
| 04.009    | Torque Offset                                | VM_USER_CURRENT %                                                              |                   | 0.0 %          |           |       | RW   | Num |    |    |    | US |
| 04.010    | Torque Offset Select                         | Off (0) or On (1)                                                              |                   | Off (0)        |           |       | RW   | Bit |    |    |    | US |
| 04.011    | Torque Mode Selector                         | 0 to 1                                                                         | 0 to 5            | 0              |           |       | RW   | Num |    |    |    | US |
| 04.012    | Current Reference Filter 1 Time Constant     |                                                                                | 0.0 to 25.0 ms    |                | 0.0 ms    |       | RW   | Num |    |    |    | US |
| 04.013    | Current Controller Kp Gain                   | 0 to 30000                                                                     |                   | 20             | 150       |       | RW   | Num |    |    |    | US |
| 04.014    | Current Controller Ki Gain                   | 0 to 30000                                                                     |                   | 40             | 2000      |       | RW   | Num |    |    |    | US |
| 04.015    | Motor Thermal Time Constant 1                | 1.0 to 3000.0 s                                                                |                   | 89.0 s         |           |       | RW   | Num |    |    |    | US |
| 04.016    | Thermal Protection Mode                      | Motor Trip (0), Motor Limit (1), Drive Limit (2), Both Limit (3), Disabled (4) |                   | Motor Trip (0) |           |       | RW   | Bin |    |    |    | US |
| 04.017    | Magnetising Current / Id                     | VM_DRIVE_CURRENT A                                                             |                   |                |           |       | RO   | Num | ND | NC | PT | FI |
| 04.018    | Final Current Limit                          | VM_TORQUE_CURRENT %                                                            |                   |                |           |       | RO   | Num | ND | NC | PT |    |
| 04.019    | Motor Protection Accumulator                 | 0.0 to 100.0 %                                                                 | 0.0 to 200.0 %    |                |           |       | RO   | Num | ND | NC | PT | PS |
| 04.020    | Percentage Load                              | VM_USER_CURRENT %                                                              |                   |                |           |       | RO   | Num | ND | NC | PT | FI |
| 04.021    | Current Feedback Filter Disable              | Off (0) or On (1)                                                              |                   | Off (0)        |           |       | RW   | Bit |    |    |    | US |
| 04.022    | Inertia Compensation Enable                  |                                                                                | Off (0) or On (1) |                | Off (0)   |       | RW   | Bit |    |    |    | US |
| 04.023    | Current Reference Filter 2 Time Constant     |                                                                                | 0.0 to 25.0 ms    |                | 0.0 ms    |       | RW   | Num |    |    |    | US |
| 04.024    | User Current Maximum Scaling                 | 0.0 to VM_TORQUE_CURRENT_UNIPOLAR %                                            |                   | 165.0 %*       | 175.0 %** |       | RW   | Num |    | RA |    | US |
| 04.025    | Low Speed Thermal Protection Mode            | 0 to 1                                                                         |                   | 0              |           |       | RW   | Num |    |    |    | US |
| 04.026    | Percentage Torque                            | VM_USER_CURRENT %                                                              |                   |                |           |       | RO   | Num | ND | NC | PT | FI |
| 04.027    | Low Load Detection Level                     | 0.0 to 100.0 %                                                                 |                   | 0.0 %          |           |       | RW   | Num |    |    |    | US |
| 04.028    | Low Load Detection Speed/Frequency Threshold | 0.0 to VM_SPEED_FREQ_REF_UNIPOLAR                                              |                   | 0.0            |           |       | RW   | Num |    |    |    | US |
| 04.029    | Enable Trip On Low Load                      | Off (0) or On (1)                                                              |                   | Off (0)        |           |       | RW   | Bit |    |    |    | US |
| 04.030    | Current Controller Mode                      |                                                                                | Off (0) or On (1) |                | Off (0)   |       | RW   | Bit |    |    |    | US |
| 04.031    | Notch Filter Centre Frequency                |                                                                                | 50 to 1000 Hz     |                | 100 Hz    |       | RW   | Num |    |    |    | US |
| 04.032    | Notch Filter Bandwidth                       |                                                                                | 0 to 500 Hz       |                | 0 Hz      |       | RW   | Num |    |    |    | US |
| 04.033    | Inertia Times 1000                           |                                                                                | Off (0) or On (1) |                | Off (0)   |       | RW   | Bit |    |    |    | US |
| 04.036    | Motor Protection Accumulator Power-up Value  | Power down (0), Zero (1), Real time (2)                                        |                   | Power down (0) |           |       | RW   | Txt |    |    |    | US |
| 04.037    | Motor Thermal Time Constant 2                | 1.0 to 3000.0 s                                                                |                   | 89.0 s         |           |       | RW   | Num |    |    |    | US |
| 04.038    | Motor Thermal Time Constant 2 Scaling        | 0 to 100 %                                                                     |                   | 0 %            |           |       | RW   | Num |    |    |    | US |
| 04.039    | Rated Iron Losses As Percentage Of Losses    | 0 to 100 %                                                                     |                   | 0 %            |           |       | RW   | Num |    |    |    | US |
| 04.041    | Rated Torque                                 | 0.00 to 50000.00 N m                                                           |                   | 0.00 N m       |           |       | RW   | Num |    |    |    | US |
| 04.042    | Torque Estimation Minimum Frequency          | 0 to 100 %                                                                     |                   | 5 %            |           |       | RW   | Num |    |    |    | US |
| 04.043    | Torque Correction Time Constant              |                                                                                | 0.00 to 10.00 s   |                | 0.00 s    |       | RW   | Num |    |    |    | US |
| 04.044    | Torque Correction Maximum                    |                                                                                | 0 to 100 %        |                | 20 %      |       | RW   | Num |    |    |    | US |
| 04.045    | No-load Core Loss                            | 0.000 to 99999.999 kW                                                          |                   | 0.000 kW       |           |       | RW   | Num |    |    |    | US |
| 04.046    | Rated Core Loss                              | 0.000 to 99999.999 kW                                                          |                   | 0.000 kW       |           |       | RW   | Num |    |    |    | US |
| 04.049    | Magnetising Current Limit                    |                                                                                | 0.0 to 100.0 %    |                | 100.0 %   |       | RW   | Num |    |    |    | US |

\* For size 9 and above the default is 141.9 %.

\*\* For size 9 and above the default is 150.0 %.

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

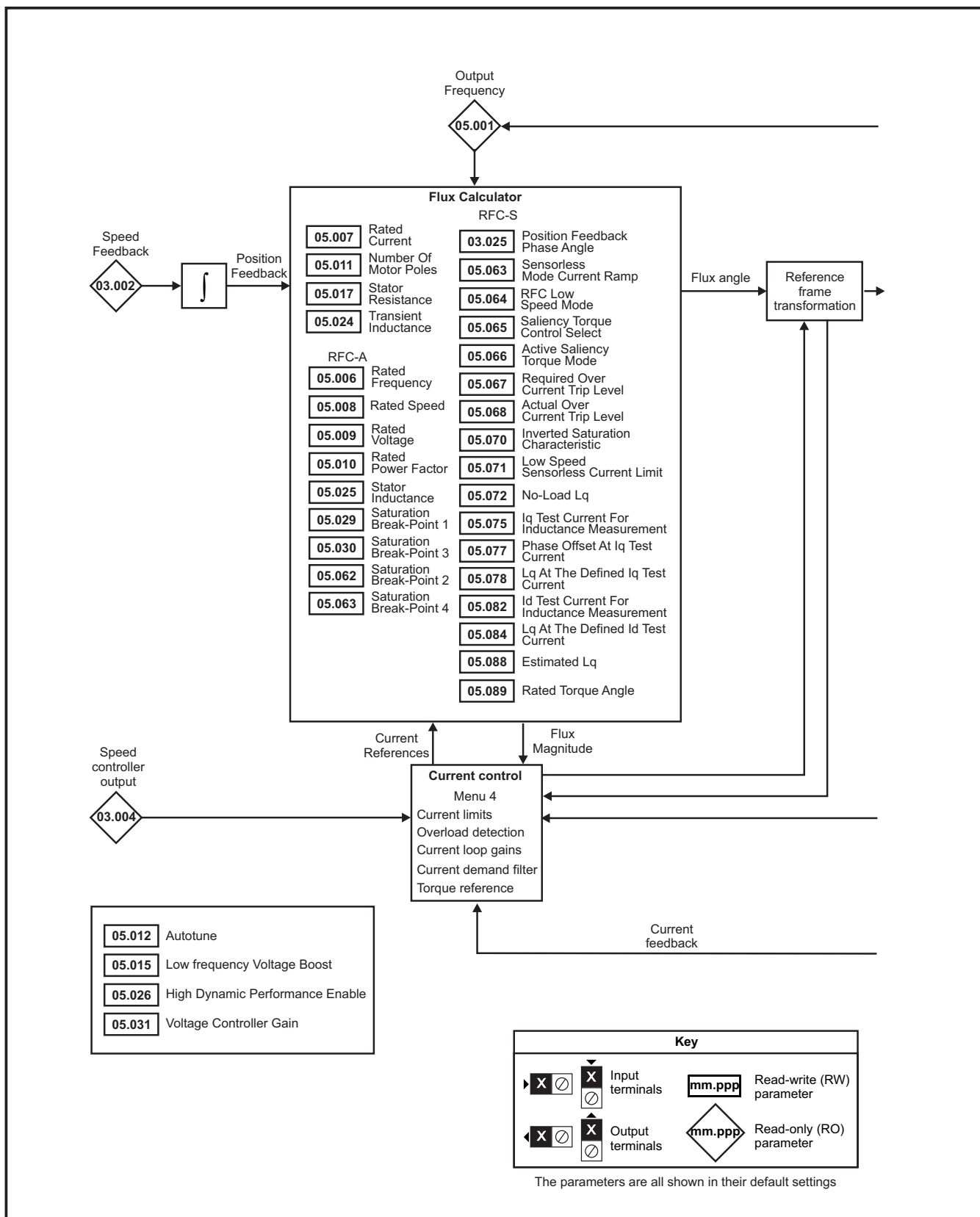
**Figure 12-13 Menu 5 Open-loop logic diagram**



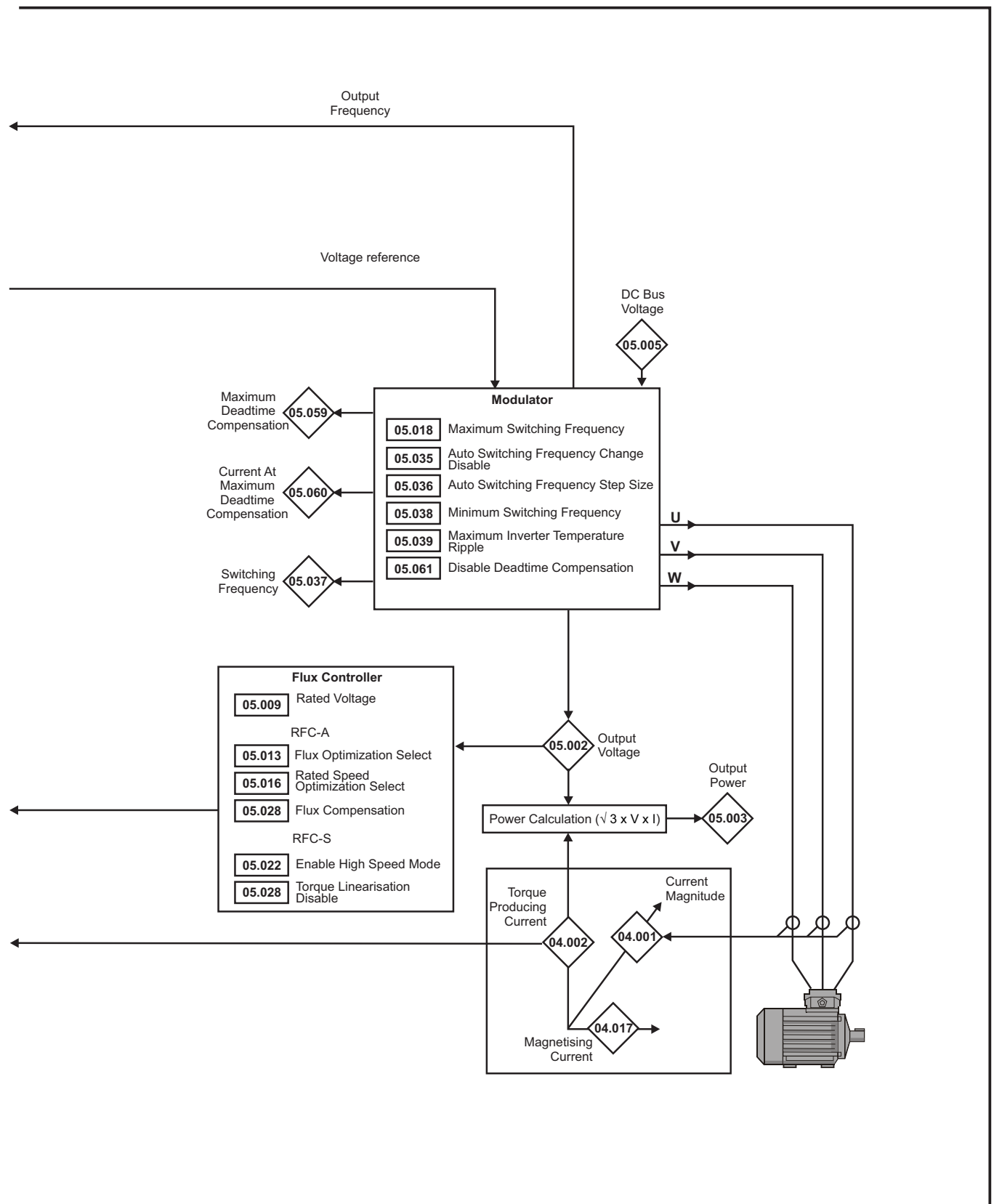
|                       |                        |                            |                            |                    |                     |                      |              |                        |                            |                |                        |             |                   |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|---------------------|----------------------|--------------|------------------------|----------------------------|----------------|------------------------|-------------|-------------------|
| Safety<br>information | Product<br>information | Mechanical<br>installation | Electrical<br>installation | Getting<br>started | Basic<br>parameters | Running<br>the motor | Optimization | Drive<br>communication | NV Media Card<br>Operation | Onboard<br>PLC | Advanced<br>parameters | Diagnostics | UL<br>information |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|---------------------|----------------------|--------------|------------------------|----------------------------|----------------|------------------------|-------------|-------------------|

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-14 Menu 5 RFC-A, RFC-S logic diagram



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                            |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|----------------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | <b>Advanced parameters</b> | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|----------------------------|-------------|----------------|



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                                            | Range(⇅)                                                                         |                                                                                                                |                                                                                                          | Default(⇅)                                                                                                                 |                                              |              | Type |     |    |    |    |    |
|-----------|------------------------------------------------------------|----------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------|----------------------------------------------|--------------|------|-----|----|----|----|----|
|           |                                                            | OL                                                                               | RFC-A                                                                                                          | RFC-S                                                                                                    | OL                                                                                                                         | RFC-A                                        | RFC-S        |      |     |    |    |    |    |
| 05.001    | Output Frequency                                           | VM_SPEED_FREQ_REF                                                                | ±2000.0 Hz                                                                                                     |                                                                                                          |                                                                                                                            |                                              |              | RO   | Num | ND | NC | PT | FI |
| 05.002    | Output Voltage                                             | 0 to VM_AC_VOLTAGE V                                                             |                                                                                                                |                                                                                                          |                                                                                                                            |                                              |              | RO   | Num | ND | NC | PT | FI |
| 05.003    | Output Power                                               | VM_POWER kW                                                                      |                                                                                                                |                                                                                                          |                                                                                                                            |                                              |              | RO   | Num | ND | NC | PT | FI |
| 05.004    | Motor Rpm                                                  | ±180000 rpm                                                                      |                                                                                                                |                                                                                                          |                                                                                                                            |                                              |              | RO   | Num | ND | NC | PT | FI |
| 05.005    | D.c. Bus Voltage                                           | 0 to VM_DC_VOLTAGE V                                                             |                                                                                                                |                                                                                                          |                                                                                                                            |                                              |              | RO   | Num | ND | NC | PT | FI |
| 05.006    | Rated Frequency                                            | 0.0 to 599.0 Hz                                                                  | 0.0 to 550.0 Hz                                                                                                |                                                                                                          | 50Hz: 50.0<br>60Hz: 60.0                                                                                                   |                                              |              | RW   | Num |    |    |    | US |
| 05.007    | Rated Current                                              | 0.000 to VM_RATED_CURRENT A                                                      |                                                                                                                |                                                                                                          | Maximum Heavy Duty Rating (11.032)                                                                                         |                                              |              | RW   | Num |    | RA |    | US |
| 05.008    | Rated Speed                                                | 0 to 35940 rpm                                                                   | 0.00 to 33000.00 rpm                                                                                           |                                                                                                          | 50Hz:<br>1500 rpm<br>60Hz:<br>1800 rpm                                                                                     | 50Hz:<br>1450.00 rpm<br>60Hz:<br>1750.00 rpm | 3000.00 rpm  | RW   | Num |    |    |    | US |
| 05.009    | Rated Voltage                                              | 0 to VM_AC_VOLTAGE_SET                                                           |                                                                                                                |                                                                                                          | 200 V drive: 230 V<br>50 Hz - 400 V drive: 400 V<br>60 Hz - 400 V drive: 460 V<br>575 V drive: 575 V<br>690 V drive: 690 V |                                              |              | RW   | Num |    | RA |    | US |
| 05.010    | Rated Power Factor                                         | 0.000 to 1.000                                                                   |                                                                                                                |                                                                                                          | 0.850                                                                                                                      |                                              |              | RW   | Num |    | RA |    | US |
| 05.011    | Number Of Motor Poles                                      | Automatic (0) to 480 Poles (240)                                                 |                                                                                                                |                                                                                                          | Automatic (0)                                                                                                              |                                              | 6 Poles (3)  | RW   | Num |    |    |    | US |
| 05.012    | Autotune                                                   | None (0),<br>Basic (1),<br>Improved (2)                                          | None (0),<br>Basic (1),<br>Improved (2),<br>Inertia 1 (3),<br>Inertia 2 (4)                                    | None (0),<br>Stationary (1),<br>Rotating (2),<br>Inertia 1 (3),<br>Inertia 2 (4), Full<br>Stationary (5) | None (0)                                                                                                                   |                                              |              | RW   | Num |    | NC |    |    |
| 05.013    | Open Loop: Dynamic V To F Select                           | Off (0) or On (1)                                                                |                                                                                                                |                                                                                                          | Off (0)                                                                                                                    |                                              |              | RW   | Bit |    |    |    | US |
|           | RFC A: Flux Optimisation Select                            |                                                                                  | Off (0) or On (1)                                                                                              |                                                                                                          |                                                                                                                            | Off (0)                                      |              | RW   | Bit |    |    |    | US |
|           | RFC S: Minimal Movement Phasing Test Mode                  |                                                                                  |                                                                                                                | Free (0),<br>Constrained (1)                                                                             |                                                                                                                            |                                              | Free (0)     | RW   | Txt |    |    |    | US |
| 05.014    | Open-loop Control Mode                                     | Ur S (0), Ur (1),<br>Fixed (2),<br>Ur Auto (3),<br>Ur I (4),<br>Square (5),      |                                                                                                                |                                                                                                          | Ur I (4)                                                                                                                   |                                              |              | RW   | Txt |    |    |    | US |
|           | Phasing Test On Enable                                     |                                                                                  |                                                                                                                | Disabled (0),<br>Short, (1),<br>Short Once (2),<br>Long (3),<br>Long Once (4)                            |                                                                                                                            |                                              | Disabled (0) | RW   | Txt |    |    |    | US |
| 05.015    | Low Frequency Voltage Boost                                | 0.0 to 25.0 %                                                                    |                                                                                                                |                                                                                                          | 3.0 %                                                                                                                      |                                              |              | RW   | Num |    |    |    | US |
|           | Minimal Movement Phasing Test Current                      |                                                                                  |                                                                                                                | 1 % (0), 2 % (1),<br>3 % (2), 6 % (3),<br>12 % (4),<br>25 % (5),<br>50 % (6),<br>100 % (7)               |                                                                                                                            |                                              | 1 % (0)      | RW   | Txt |    |    |    | US |
| 05.016    | Rated Speed Optimization Select                            |                                                                                  | Disabled (0),<br>Classic Slow (1),<br>Classic Fast (2),<br>Combined (3),<br>VARs Only (4),<br>Voltage Only (5) |                                                                                                          |                                                                                                                            | Disabled (0)                                 |              | RW   | Txt |    |    |    | US |
|           | Minimal Movement Phasing Test Angle                        |                                                                                  |                                                                                                                | 0.00 to 25.00 °                                                                                          |                                                                                                                            |                                              | 0.00 °       | RW   | Num |    |    |    | US |
| 05.017    | Stator Resistance                                          | 0.000000 to 1000.000000 Ω                                                        |                                                                                                                |                                                                                                          | 0.000000 Ω                                                                                                                 |                                              |              | RW   | Num |    | RA |    | US |
| 05.018    | Maximum Switching Frequency                                | 2 kHz (0), 3 kHz (1), 4 kHz (2), 6 kHz (3), 8 kHz (4),<br>12 kHz (5), 16 kHz (6) |                                                                                                                |                                                                                                          | 3 kHz (1)                                                                                                                  |                                              | 6 kHz (3)    | RW   | Txt |    | RA |    | US |
| 05.019    | Open Loop: High Stability Space Vector Modulation          | Off (0) or On (1)                                                                |                                                                                                                |                                                                                                          | Off (0)                                                                                                                    |                                              |              | RW   | Bit |    |    |    | US |
|           | RFC A: Rated Speed Optimisation Minimum Frequency          |                                                                                  | 0 to 100 %                                                                                                     |                                                                                                          |                                                                                                                            | 10 %                                         |              | RW   | Num |    |    |    | US |
|           | RFC S: Minimal Movement Phasing Test Mechanical Load Phase |                                                                                  |                                                                                                                | -180 to 179 °                                                                                            |                                                                                                                            |                                              | -180 °       | RW   | Num |    |    |    | US |
| 05.020    | Quasi-square Enable                                        | Off (0) or On (1)                                                                |                                                                                                                |                                                                                                          | Off (0)                                                                                                                    |                                              |              | RW   | Bit |    |    |    | US |
|           | Rated Speed Optimization Minimum Load                      |                                                                                  | 0 to 100 %                                                                                                     |                                                                                                          |                                                                                                                            | 50 %                                         |              | RW   | Num |    |    |    | US |
| 05.021    | Mechanical Load Test Level                                 |                                                                                  | 0 to 100 %                                                                                                     |                                                                                                          |                                                                                                                            | 0 %                                          |              | RW   | Num |    |    |    | US |
| 05.022    | Enable High Speed Mode                                     |                                                                                  |                                                                                                                | Limit (-2),<br>Limit (Servo)(-1),<br>Disable (0),<br>Enable (Servo) (1), Enable (2)                      |                                                                                                                            |                                              | Disable (0)  | RW   | Txt |    |    |    | US |
| 05.023    | D.c. Bus Voltage High Range                                | 0 to VM_HIGH_DC_VOLTAGE V                                                        |                                                                                                                |                                                                                                          |                                                                                                                            |                                              |              | RO   | Num | ND | NC | PT | FI |
| 05.024    | Transient Inductance                                       | 0.000 to 500.000 mH                                                              |                                                                                                                |                                                                                                          | 0.000 mH                                                                                                                   |                                              |              | RW   | Num |    | RA |    | US |
|           | Ld                                                         |                                                                                  |                                                                                                                | 0.000 to<br>500.000 mH                                                                                   |                                                                                                                            |                                              | 0.000 mH     | RW   | Num |    | RA |    | US |
| 05.025    | Stator Inductance                                          | 0.00 to 5000.00 mH                                                               |                                                                                                                |                                                                                                          | 0.00 mH                                                                                                                    |                                              |              | RW   | Num |    | RA |    | US |
| 05.026    | High Dynamic Performance Enable                            |                                                                                  | Off (0) or On (1)                                                                                              |                                                                                                          |                                                                                                                            | Off (0)                                      |              | RW   | Bit |    |    |    | US |

| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                                        | Range(⇄)                                                                                        |                         |                                                                                                      | Default(⇄)               |        |                          | Type |     |    |    |    |    |
|-----------|--------------------------------------------------------|-------------------------------------------------------------------------------------------------|-------------------------|------------------------------------------------------------------------------------------------------|--------------------------|--------|--------------------------|------|-----|----|----|----|----|
|           |                                                        | OL                                                                                              | RFC-A                   | RFC-S                                                                                                | OL                       | RFC-A  | RFC-S                    |      |     |    |    |    |    |
| 05.027    | Open Loop: Enable Slip Compensation                    | Off (0) or On (1)                                                                               |                         |                                                                                                      | On (1)                   |        |                          | RW   | Bit |    |    |    | US |
|           | RFC A: Flux Control Gain                               |                                                                                                 | ±10.0                   |                                                                                                      |                          | 1.0    |                          | RW   | Num |    |    |    | US |
|           | RFC S: Flux Control Gain                               |                                                                                                 |                         | 0.1 to 10.0                                                                                          |                          |        | 1.0                      | RW   | Num |    |    |    | US |
| 05.028    | Flux Compensation                                      |                                                                                                 | 0 to 2                  |                                                                                                      |                          | 0      |                          | RW   | Num |    |    |    | US |
|           | Torque Linearization Disable                           |                                                                                                 |                         | Off (0) or On (1)                                                                                    |                          |        | Off (0)                  | RW   | Bit |    |    |    | US |
| 05.029    | Saturation Breakpoint 1                                |                                                                                                 | 0.0 to 100.0 %          |                                                                                                      |                          | 50.0 % |                          | RW   | Num |    |    |    | US |
| 05.030    | Saturation Breakpoint 3                                |                                                                                                 | 0.0 to 100.0 %          |                                                                                                      |                          | 75.0 % |                          | RW   | Num |    |    |    | US |
| 05.031    | Voltage Controller Gain                                | 1 to 30                                                                                         |                         |                                                                                                      | 1                        |        |                          | RW   | Num |    |    |    | US |
| 05.032    | Torque Per Amp                                         |                                                                                                 | 0.00 to 500.00 Nm/A     |                                                                                                      |                          |        |                          | RO   | Num | ND | NC | PT |    |
|           |                                                        |                                                                                                 |                         | 0.00 to 500.00 Nm/A                                                                                  |                          |        | 1.60 Nm/A                | RW   | Num |    |    |    | US |
| 05.033    | Volts Per 1000 rpm                                     |                                                                                                 |                         | 0 to 10,000 V                                                                                        |                          |        | 98                       | RW   | Num |    |    |    | US |
| 05.034    | Percentage Flux                                        |                                                                                                 | 0.0 to 150.0 %          |                                                                                                      |                          |        |                          | RO   | Num | ND | NC | PT | FI |
| 05.035    | Auto-switching Frequency Change Disable                | Enabled (0), Disabled (1), No Ripple Detect (2)                                                 |                         |                                                                                                      | Enabled (0)              |        |                          | RW   | Txt |    |    |    | US |
| 05.036    | Auto-switching Frequency Step Size                     | 1 to 2                                                                                          |                         |                                                                                                      | 2                        |        |                          | RW   | Num |    |    |    | US |
| 05.037    | Switching Frequency                                    | 2 kHz (0), 3 kHz (1), 4 kHz (2), 6 kHz (3), 8 kHz (4), 12 kHz (5), 16 kHz (6)                   |                         |                                                                                                      |                          |        |                          | RO   | Txt | ND | NC | PT |    |
| 05.038    | Minimum Switching Frequency                            | 0 to VM_MIN_SWITCHING_FREQUENCY kHz                                                             |                         |                                                                                                      | 2 (0) kHz                |        |                          | RW   | Txt |    |    |    | US |
| 05.039    | Maximum Inverter Temperature Ripple                    | 20 to 60 °C                                                                                     |                         |                                                                                                      | 60 °C                    |        |                          | RW   | Num |    |    |    | US |
| 05.040    | Spin Start Boost                                       | 0.0 to 10.0                                                                                     |                         |                                                                                                      | 1.0                      |        |                          | RW   | Num |    |    |    | US |
| 05.041    | Voltage Headroom                                       |                                                                                                 | 0 to 20 %               |                                                                                                      |                          | 0 %    |                          | RW   | Num |    |    |    | US |
| 05.042    | Reverse Output Phase Sequence                          | Off (0) or On (1)                                                                               |                         |                                                                                                      | Off (0)                  |        |                          | RW   | Bit |    |    |    | US |
| 05.044    | Stator Temperature Source                              | An In 3 (0), User (1), P1 Drive (2), P1 Slot 1 (3), P1 Slot 2 (4), P1 Slot 3 (5), P1 Slot 4 (6) |                         |                                                                                                      | An In 3 (0)*             |        |                          | RW   | Txt |    |    |    | US |
| 05.045    | User Stator Temperature                                | -50 to 300 °C                                                                                   |                         |                                                                                                      | 0 °C                     |        |                          | RW   | Num |    |    |    |    |
| 05.046    | Stator Temperature                                     | -50 to 300 °C                                                                                   |                         |                                                                                                      |                          |        |                          | RO   | Num | ND | NC | PT |    |
| 05.047    | Stator Temperature Coefficient                         | 0.00000 to 0.10000 °C <sup>-1</sup>                                                             |                         |                                                                                                      | 0.00390 °C <sup>-1</sup> |        |                          | RW   | Num |    |    |    | US |
| 05.048    | Stator Base Temperature                                | -50 to 300 °C                                                                                   |                         |                                                                                                      | 0 °C                     |        |                          | RW   | Num |    |    |    | US |
| 05.049    | Enable Stator Compensation                             | Off (0) or On (1)                                                                               |                         |                                                                                                      | Off (0)                  |        |                          | RW   | Bit |    |    |    | US |
| 05.050    | Temperature Compensated Stator Resistance              | 0.000000 to 1000.000000 Ω                                                                       | 0.000000 to 1000.000000 |                                                                                                      |                          |        |                          | RO   | Num | ND | NC | PT |    |
| 05.051    | Rotor Temperature Source                               | An In 3 (0), User (1), P1 Drive (2), P1 Slot 1 (3), P1 Slot 2 (4), P1 Slot 3 (5), P1 Slot 4 (6) |                         |                                                                                                      | An In 3 (0)*             |        |                          | RW   | Txt |    |    |    | US |
| 05.052    | User Rotor Temperature                                 | -50 to 300 °C                                                                                   |                         |                                                                                                      | 0 °C                     |        |                          | RW   | Num |    |    |    | US |
| 05.053    | Rotor Temperature                                      | -50 to 300 °C                                                                                   |                         |                                                                                                      |                          |        |                          | RO   | Num | ND | NC | PT |    |
| 05.054    | Rotor Temperature Coefficient                          | 0.00000 to 0.10000 °C <sup>-1</sup>                                                             |                         |                                                                                                      | 0.00390 °C <sup>-1</sup> |        | 0.00100 °C <sup>-1</sup> | RW   | Num |    |    |    | US |
| 05.055    | Rotor Base Temperature                                 | -50 to 300 °C                                                                                   |                         |                                                                                                      | 0 °C                     |        |                          | RW   | Num |    |    |    | US |
| 05.056    | Enable Rotor Compensation                              | Off (0) or On (1)                                                                               |                         |                                                                                                      | Off (0)                  |        |                          | RW   | Bit |    |    |    | US |
| 05.057    | Temperature compensated rated speed                    | 0.00 to 18000.00 rpm                                                                            | 0.00 to 50000.00 rpm    |                                                                                                      |                          |        |                          | RO   | Num | ND | NC | PT |    |
|           | Rotor Temperature Compensation                         |                                                                                                 |                         | 0.000 to 2.000                                                                                       |                          |        |                          | RO   | Num | ND | NC | PT |    |
| 05.059    | Maximum Deadtime Compensation                          | 0.000 to 10.000 μs                                                                              |                         |                                                                                                      |                          |        |                          | RO   | Num |    | NC | PT | US |
| 05.060    | Current At Maximum Deadtime Compensation               | 0.00 to 100.00 %                                                                                |                         |                                                                                                      |                          |        |                          | RO   | Num |    | NC | PT | US |
| 05.061    | Disable Deadtime Compensation                          | Off (0) or On (1)                                                                               |                         |                                                                                                      | Off (0)                  |        |                          | RW   | Bit |    |    |    | US |
| 05.062    | Saturation Breakpoint 2                                |                                                                                                 | 0.0 to 100.0 %          |                                                                                                      |                          | 0.0 %  |                          | RW   | Num |    |    |    | US |
| 05.063    | Saturation Breakpoint 4                                |                                                                                                 | 0.0 to 100.0 %          |                                                                                                      |                          | 0.0 %  |                          | RW   | Num |    |    |    | US |
|           | Sensorless Mode Current Ramp                           |                                                                                                 |                         | 0.00 to 1.00 s                                                                                       |                          |        | 0.20 s                   | RW   | Num |    |    |    | US |
| 05.064    | RFC Low Speed Mode                                     |                                                                                                 |                         | Injection (0), Non-salient (1), Current (2), Current No Test (3), Current Step (4), Current Only (5) |                          |        | Current (2)              | RW   | Txt |    |    |    | US |
| 05.065    | Saliency Torque Control Select                         |                                                                                                 |                         | Disabled (0), Low (1), High (2), Auto (3)                                                            |                          |        | Disabled (0)             | RW   | Txt |    |    |    | US |
| 05.066    | Active Saliency Torque Mode                            |                                                                                                 |                         | Disabled (0), Low (1), High (2)                                                                      |                          |        |                          | RO   | Txt | ND | NC | PT |    |
| 05.067    | Required Over-current Trip Level                       |                                                                                                 |                         | 0 to 100 %                                                                                           |                          |        | 0 %                      | RW   | Num |    |    |    | US |
| 05.068    | Actual Over-current Trip Level                         |                                                                                                 |                         | 0 to 500 %                                                                                           |                          |        |                          | RO   | Num | ND | NC | PT |    |
| 05.069    | Over current Trip Level as Percentage of Rated Current |                                                                                                 |                         | 0 to 1000 %                                                                                          |                          |        | 0 %                      | RW   | Num |    |    |    | US |
| 05.070    | Inverted Saturation Characteristic                     |                                                                                                 |                         | Off (0) or On (1)                                                                                    |                          |        | Off (0)                  | RW   | Bit |    |    |    | US |

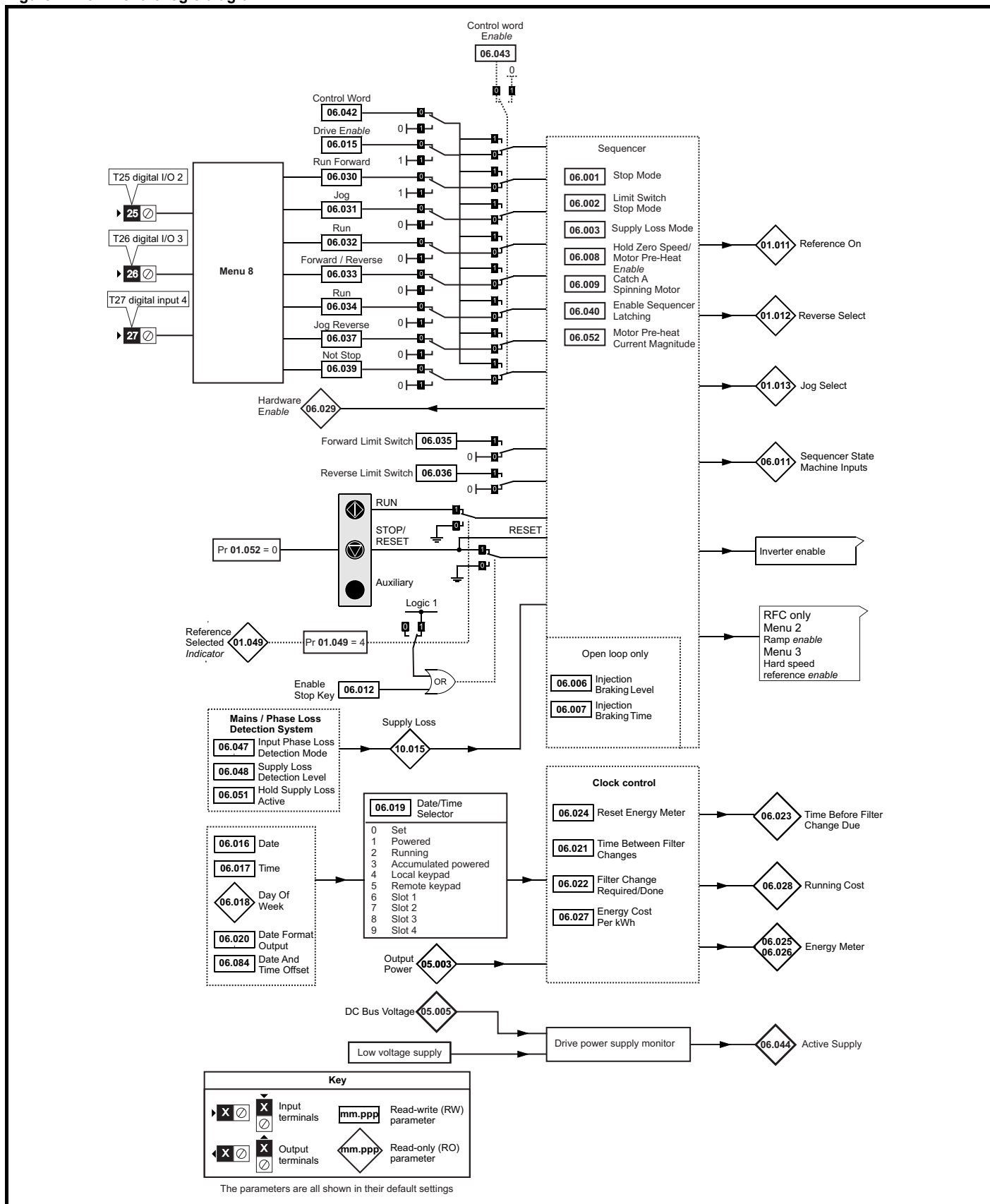
|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                                   | Range(↕) |       |                     | Default(⇒) |       |          | Type |     |    |    |    |    |
|-----------|---------------------------------------------------|----------|-------|---------------------|------------|-------|----------|------|-----|----|----|----|----|
|           |                                                   | OL       | RFC-A | RFC-S               | OL         | RFC-A | RFC-S    |      |     |    |    |    |    |
| 05.071    | Low Speed Sensorless Mode Current Limit           |          |       | 0.0 to 1000.0 %     |            |       | 100.0 %  | RW   | Num |    | RA |    | US |
| 05.072    | No-load Lq                                        |          |       | 0.000 to 500.000 mH |            |       | 0.000 mH | RW   | Num |    | RA |    | US |
| 05.075    | q Axis Current For Inductance Values With Current |          |       | 0 to 200 %          |            |       | 100 %    | RW   | Num |    |    |    | US |
| 05.077    | Phase Offset At Defined Iq Current                |          |       | ±90.0°              |            |       | 0.0°     | RW   | Num |    | RA |    | US |
| 05.078    | Lq At The Defined Iq Current                      |          |       | 0.000 to 500.000 mH |            |       | 0.000 mH | RW   | Num |    | RA |    | US |
| 05.079    | Lq Incremental Inductance At Defined Iq Current   |          |       | 0.000 to 500.000 mH |            |       | 0.000 mH | RW   | Num |    | RA |    | US |
| 05.082    | d Axis Current For Inductance Values With Current |          |       | -100 to 0 %         |            |       | -100%    | RW   | Num |    |    |    | US |
| 05.084    | Lq At The Defined Id Current                      |          |       | 0.000 to 500.000 mH |            |       | 0.000 mH | RW   | Num |    | RA |    | US |
| 05.085    | Lq Incremental Inductance At Defined Id Current   |          |       | 0.000 to 500.000 mH |            |       | 0.000 mH | RW   | Num |    | RA |    | US |
| 05.087    | User Defined Rated Torque Angle                   |          |       | 0 to 90 °           |            |       | 0 °      | RW   | Num |    |    |    | US |
| 05.088    | Estimated Lq                                      |          |       | 0.000 to 500.000 mH |            |       |          | RO   | Num | ND | NC | PT | FI |
| 05.089    | Rated Torque Angle                                |          |       | 0 to 90°            |            |       |          | RO   | Num | ND | NC | PT |    |

\* User (1) on *Unidrive M702*.

## 12.7 Menu 6: Sequencer and clock

Figure 12-15 Menu 6 logic diagram



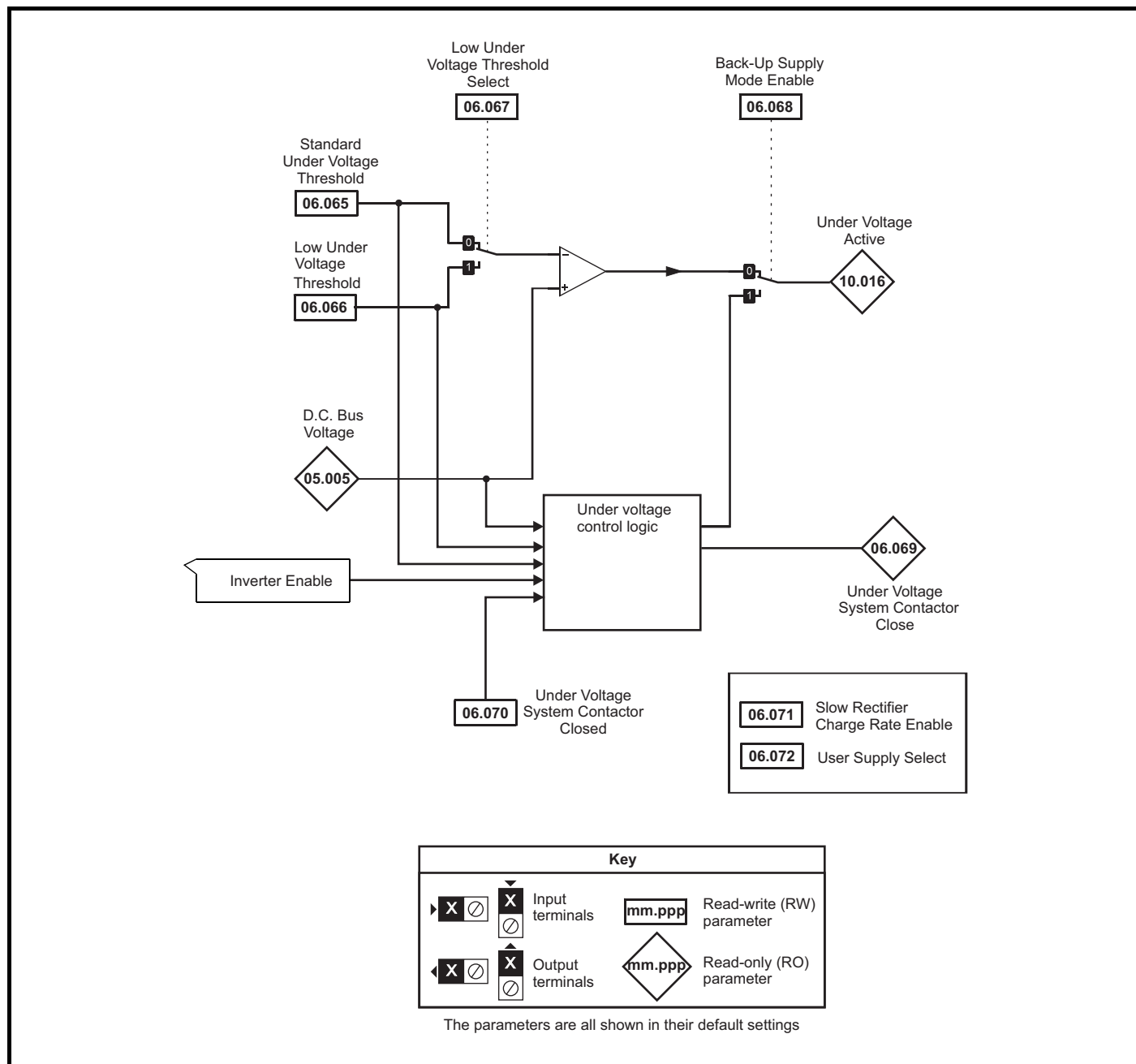
\* Not available on Unidrive M702.

\*\* Terminal 7 on Unidrive M702.

\*\*\* Terminal 8 on Unidrive M702.

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-16 Menu 6 logic diagram: Under voltage and power supply control



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                      | Range(\$)                                                                                                                               |                                                           | Default(⇄)                                                                           |            |             | Type |      |    |    |    |    |
|-----------|--------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------|--------------------------------------------------------------------------------------|------------|-------------|------|------|----|----|----|----|
|           |                                      | OL                                                                                                                                      | RFC-A / S                                                 | OL                                                                                   | RFC-A      | RFC-S       |      |      |    |    |    |    |
| 06.001    | Stop Mode                            | Coast (0), Ramp (1), Ramp dc I (2), dc I (3), Timed dc I (4), Disable (5)                                                               | Coast (0), Ramp (1), No Ramp (2)                          | Ramp (1)                                                                             | Ramp (1)   | No Ramp (2) | RW   | Txt  |    |    |    | US |
| 06.002    | Limit Switch Stop Mode               |                                                                                                                                         | Stop (0) or Ramp (1)                                      |                                                                                      | Stop (0)   |             | RW   | Txt  |    |    |    | US |
| 06.003    | Supply Loss Mode                     | Disable (0), Ramp Stop (1), Ride Thru (2)                                                                                               | Disable (0), Ramp Stop (1), Ride Thru (2), Limit Stop (3) | Disable (0)                                                                          |            |             | RW   | Txt  |    |    |    | US |
| 06.006    | Injection Braking Level              | 0.0 to 150.0 %                                                                                                                          |                                                           | 100.0 %                                                                              |            |             | RW   | Num  |    | RA |    | US |
| 06.007    | Injection Braking Time               | 0.0 to 100.0 s                                                                                                                          |                                                           | 1.0 s                                                                                |            |             | RW   | Num  |    |    |    | US |
| 06.008    | Hold Zero Speed                      | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            | On (1)      | RW   | Bit  |    |    |    | US |
| 06.009    | Catch A Spinning Motor               | Disable (0), Enable (1), Fwd Only (2), Rev Only (3)                                                                                     |                                                           | Disable (0)                                                                          | Enable (1) |             | RW   | Txt  |    |    |    | US |
| 06.010    | Enable Conditions                    | 000000000000 to 111111111111                                                                                                            |                                                           |                                                                                      |            |             | RO   | Bin  | ND | NC | PT |    |
| 06.011    | Sequencer State Machine Inputs       | 000000 to 111111                                                                                                                        |                                                           |                                                                                      |            |             | RO   | Bin  | ND | NC | PT |    |
| 06.012    | Enable Stop Key                      | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    |    |    | US |
| 06.013    | Enable Auxiliary Key                 | Disabled (0), Forward / Reverse (1), Run Reverse (2)                                                                                    |                                                           | Disabled (0)                                                                         |            |             | RW   | Txt  |    |    |    | US |
| 06.015    | Drive Enable                         | Off (0) or On (1)                                                                                                                       |                                                           | On (1)                                                                               |            |             | RW   | Bit  |    |    |    | US |
| 06.016    | Date                                 | 00-00-00 to 31-12-99                                                                                                                    |                                                           | 00-00-00                                                                             |            |             | RW   | Date | ND | NC | PT |    |
| 06.017    | Time                                 | 00:00:00 to 23:59:59                                                                                                                    |                                                           |                                                                                      |            |             | RW   | Time | ND | NC | PT |    |
| 06.018    | Day Of Week                          | Sunday (0), Monday (1), Tuesday (2), Wednesday (3), Thursday (4), Friday (5), Saturday (6)                                              |                                                           |                                                                                      |            |             | RO   | Txt  | ND | NC | PT |    |
| 06.019    | Date/Time Selector                   | Set (0), Powered (1), Running (2), Acc Powered (3), Local Keypad (4), Remote Keypad (5), Slot 1 (6), Slot 2 (7), Slot 3 (8), Slot 4 (9) |                                                           | Powered (1)                                                                          |            |             | RW   | Txt  |    |    |    | US |
| 06.020    | Date Format                          | Std (0) or US (1)                                                                                                                       |                                                           | Std (0)                                                                              |            |             | RW   | Txt  |    |    |    | US |
| 06.021    | Time Between Filter Changes          | 0 to 30000 Hours                                                                                                                        |                                                           | 0 Hours                                                                              |            |             | RW   | Num  |    |    |    | US |
| 06.022    | Filter Change Required / Change Done | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  | ND | NC |    |    |
| 06.023    | Time Before Filter Change Due        | 0 to 30000 Hours                                                                                                                        |                                                           |                                                                                      |            |             | RO   | Num  | ND | NC | PT | PS |
| 06.024    | Reset Energy Meter                   | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    |    |    |    |
| 06.025    | Energy Meter: MWh                    | -999.9 to 999.9 MWh                                                                                                                     |                                                           |                                                                                      |            |             | RO   | Num  | ND | NC | PT | PS |
| 06.026    | Energy Meter: kWh                    | ±99.99 kWh                                                                                                                              |                                                           |                                                                                      |            |             | RO   | Num  | ND | NC | PT | PS |
| 06.027    | Energy Cost Per kWh                  | 0.0 to 600.0                                                                                                                            |                                                           | 0.0                                                                                  |            |             | RW   | Num  |    |    |    | US |
| 06.028    | Running Cost                         | ±32000                                                                                                                                  |                                                           |                                                                                      |            |             | RO   | Num  | ND | NC | PT |    |
| 06.029    | Hardware Enable                      | Off (0) or On (1)                                                                                                                       |                                                           |                                                                                      |            |             | RO   | Bit  | ND | NC | PT |    |
| 06.030    | Run Forward                          | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.031    | Jog                                  | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.032    | Run Reverse                          | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.033    | Forward/Reverse                      | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.034    | Run                                  | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.035    | Forward Limit Switch                 | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.036    | Reverse Limit Switch                 | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.037    | Jog Reverse                          | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.039    | Not Stop                             | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.040    | Enable Sequencer Latching            | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    |    |    | US |
| 06.041    | Drive Event Flags                    | 00 to 11                                                                                                                                |                                                           | 00                                                                                   |            |             | RW   | Bin  |    | NC |    |    |
| 06.042    | Control Word                         | 000000000000000 to 1111111111111111                                                                                                     |                                                           | 0000000000000000                                                                     |            |             | RW   | Bin  |    | NC |    |    |
| 06.043    | Control Word Enable                  | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    |    |    | US |
| 06.044    | Active Supply                        | Off (0) or On (1)                                                                                                                       |                                                           |                                                                                      |            |             | RO   | Bit  | ND | NC | PT |    |
| 06.045    | Cooling Fan control                  | -10 to 11                                                                                                                               |                                                           | 10                                                                                   |            |             | RW   | Num  |    |    |    | US |
| 06.046    | Cooling Fan Speed                    | 0 to 10                                                                                                                                 |                                                           |                                                                                      |            |             | RO   | Num  | ND | NC | PT |    |
| 06.047    | Input Phase Loss Detection Mode      | Full (0), Ripple Only (1), Disabled (2)                                                                                                 |                                                           | Full (0)                                                                             |            |             | RW   | Txt  |    |    |    | US |
| 06.048    | Supply Loss Detection Level          | 0 to VM_SUPPLY_LOSS_LEVEL V                                                                                                             |                                                           | 200 V drive: 205 V<br>400 V drive: 410 V<br>575 V drive: 540 V<br>690 V drive: 540 V |            |             | RW   | Num  |    | RA |    | US |
| 06.051    | Hold Supply Loss Active              | Off (0) or On (1)                                                                                                                       |                                                           | Off (0)                                                                              |            |             | RW   | Bit  |    | NC |    |    |
| 06.052    | Motor Pre-heat Current Magnitude     | 0 to 100 %                                                                                                                              |                                                           | 0 %                                                                                  |            |             | RW   | Num  |    |    |    | US |
| 06.053    | Sleep / Wake Threshold               | 0.0 to VM_SPEED_FREQ_REF_UNIPOLAR                                                                                                       |                                                           | 0.0                                                                                  |            |             | RW   | Num  |    |    |    | US |
| 06.054    | Sleep Time                           | 0.0 to 250.0 s                                                                                                                          |                                                           | 10.0 s                                                                               |            |             | RW   | Num  |    |    |    | US |
| 06.055    | Wake Time                            | 0.0 to 250.0 s                                                                                                                          |                                                           | 10.0 s                                                                               |            |             | RW   | Num  |    |    |    | US |
| 06.056    | Sleep Required                       | Off (0) or On (1)                                                                                                                       |                                                           |                                                                                      |            |             | RO   | Bit  | ND | NC | PT |    |
| 06.057    | Sleep Active                         | Off (0) or On (1)                                                                                                                       |                                                           |                                                                                      |            |             | RO   | Bit  | ND | NC | PT |    |

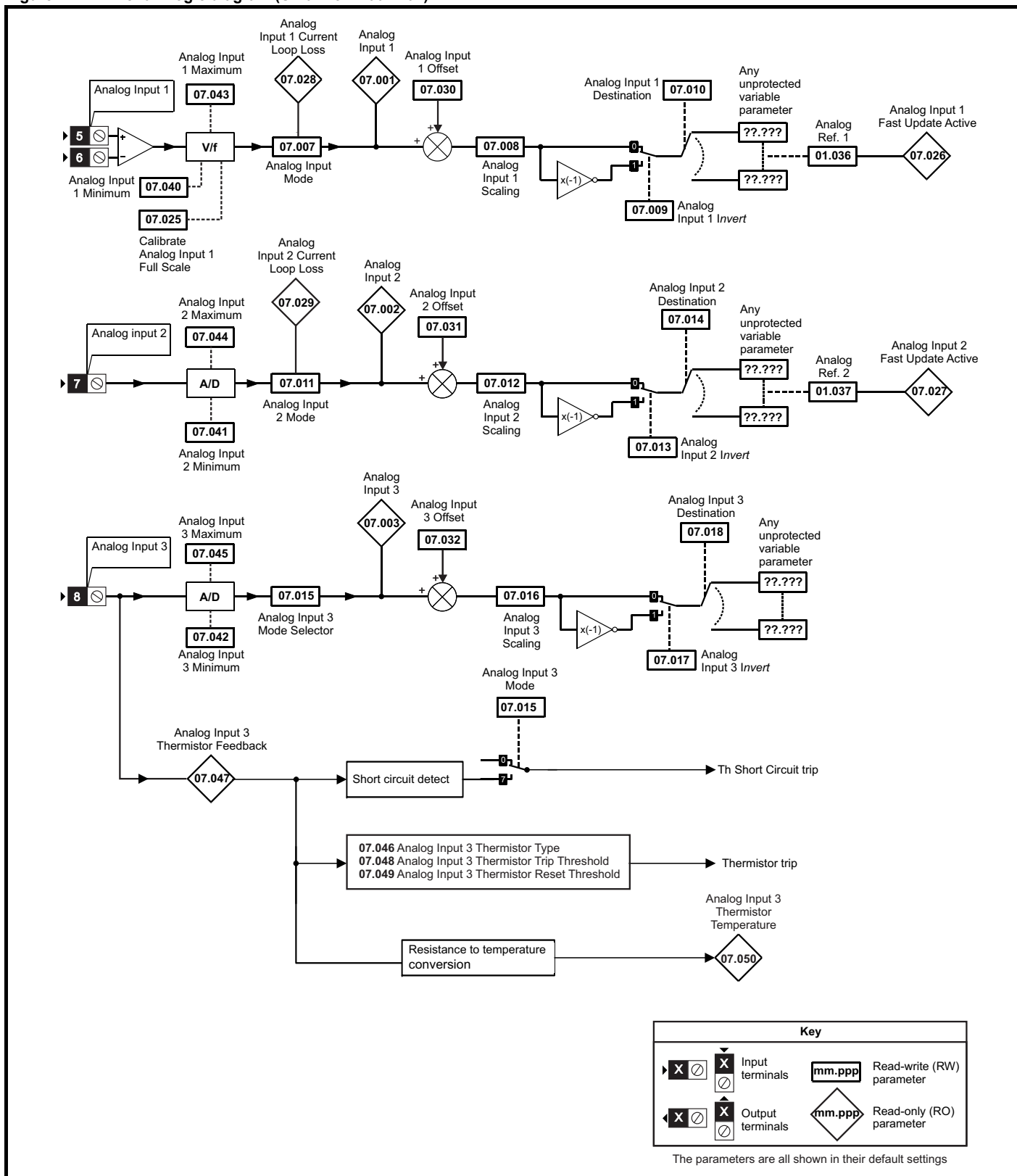
|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                           | Range(⇅)                                   |           | Default(⇄)                                                                            |       |       | Type |     |    |    |    |    |
|-----------|-------------------------------------------|--------------------------------------------|-----------|---------------------------------------------------------------------------------------|-------|-------|------|-----|----|----|----|----|
|           |                                           | OL                                         | RFC-A / S | OL                                                                                    | RFC-A | RFC-S |      |     |    |    |    |    |
| 06.058    | Output Phase Loss Detection Time          | 0.5 s (0), 1.0 s (1), 2.0 s (2), 4.0 s (3) |           | 0.5 s (0)                                                                             |       |       | RW   | Txt |    |    |    | US |
| 06.059    | Output Phase Loss Detection Enable        | Disabled (0) or Enabled (1)                |           | Disabled (0)                                                                          |       |       | RW   | Txt |    |    |    | US |
| 06.060    | Standby Mode Enable                       | Off (0) or On (1)                          |           | Off (0)                                                                               |       |       | RW   | Bit |    |    |    | US |
| 06.061    | Standby Mode Mask                         | 0000000 to 1111111                         |           | 0000000                                                                               |       |       | RW   | Bin |    |    |    | US |
| 06.065    | Standard Under Voltage Threshold          | 0 to VM_STD_UNDER_VOLTS V                  |           | 200 V drive: 175 V<br>400 V drive: 330 V<br>575 V drive: 435 V<br>690 V drive: 435 V  |       |       | RW   | Num |    | RA |    | US |
| 06.066    | Low Under Voltage Threshold               | 24 to VM_LOW_UNDER_VOLTS V                 |           | 200 V drive: 175 V<br>400 V drive: 330 V<br>575 V drive: 435 V<br>690 V drive: 435 V  |       |       | RW   | Num |    | RA |    | US |
| 06.067    | Low Under Voltage Threshold Select        | Off (0) or On (1)                          |           | Off (0)                                                                               |       |       | RW   | Bit |    |    |    | US |
| 06.068    | Back Up Supply Mode Enable                | Off (0) or On (1)                          |           | Off (0)                                                                               |       |       | RW   | Bit |    |    |    | US |
| 06.069    | Under-Voltage System Contactor Close      | Off (0) or On (1)                          |           |                                                                                       |       |       | RO   | Bit | ND | NC | PT |    |
| 06.070    | Under-Voltage System Contactor Closed     | Off (0) or On (1)                          |           | Off (0)                                                                               |       |       | RW   | Bit |    |    |    |    |
| 06.071    | Slow Rectifier Charge Rate Enable         | Off (0) or On (1)                          |           | Off (0)                                                                               |       |       | RW   | Bit |    |    |    | US |
| 06.072    | User Supply Select                        | Off (0) or On (1)                          |           | Off (0)                                                                               |       |       | RW   | Bit |    |    |    | US |
| 06.073    | Braking IGBT Lower Threshold              | 0 to VM_DC_VOLTAGE_SET V                   |           | 200 V drive: 390 V<br>400 V drive: 780 V<br>575 V drive: 930 V<br>690 V drive: 1120 V |       |       | RW   | Num |    | RA |    | US |
| 06.074    | Braking IGBT Upper Threshold              | 0 to VM_DC_VOLTAGE_SET V                   |           | 200 V drive: 390 V<br>400 V drive: 780 V<br>575 V drive: 930 V<br>690 V drive: 1120 V |       |       | RW   | Num |    | RA |    | US |
| 06.075    | Low Voltage Braking IGBT Threshold        | 0 to VM_DC_VOLTAGE_SET V                   |           | 0V                                                                                    |       |       | RW   | Num |    | RA |    | US |
| 06.076    | Low Voltage Braking IGBT Threshold Select | Off (0) or On (1)                          |           | Off (0)                                                                               |       |       | RW   | Bit |    |    |    |    |
| 06.084    | Date And Time Offset                      | ± 12.00 Hours                              |           | 0.00 Hours                                                                            |       |       | RW   | Num |    |    |    | US |

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

## 12.8 Menu 7: Analog I/O / Temperature Monitoring

Figure 12-17 Menu 7 logic diagram (Unidrive M700 / 701)



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-18 Menu 7 logic diagram (Unidrive M702 with date code 1710 or later)

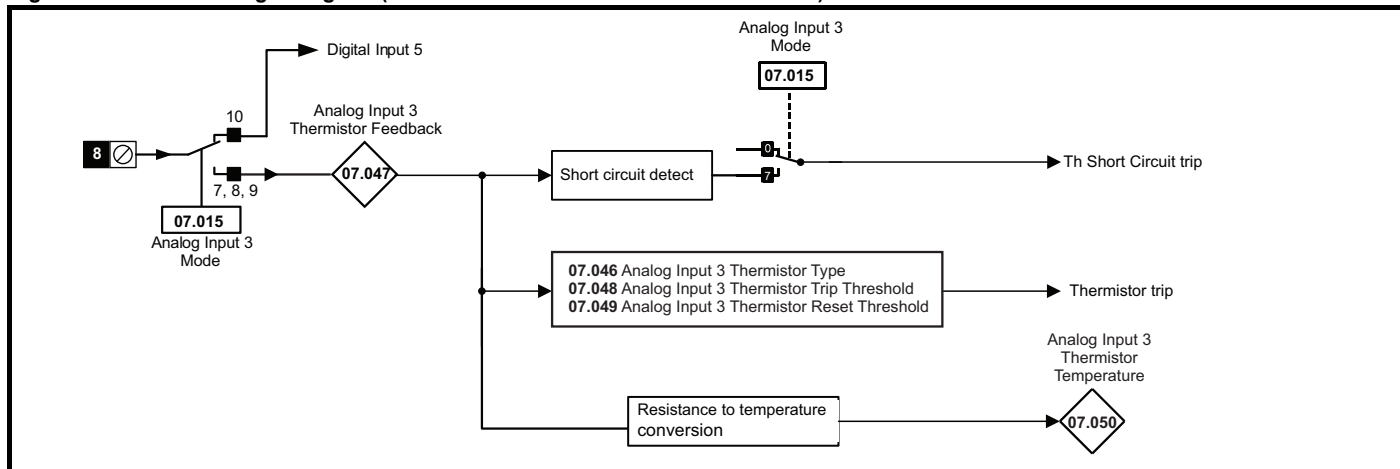


Figure 12-19 Menu 7 logic diagram: Analog outputs diagram (Unidrive M700 / 701)

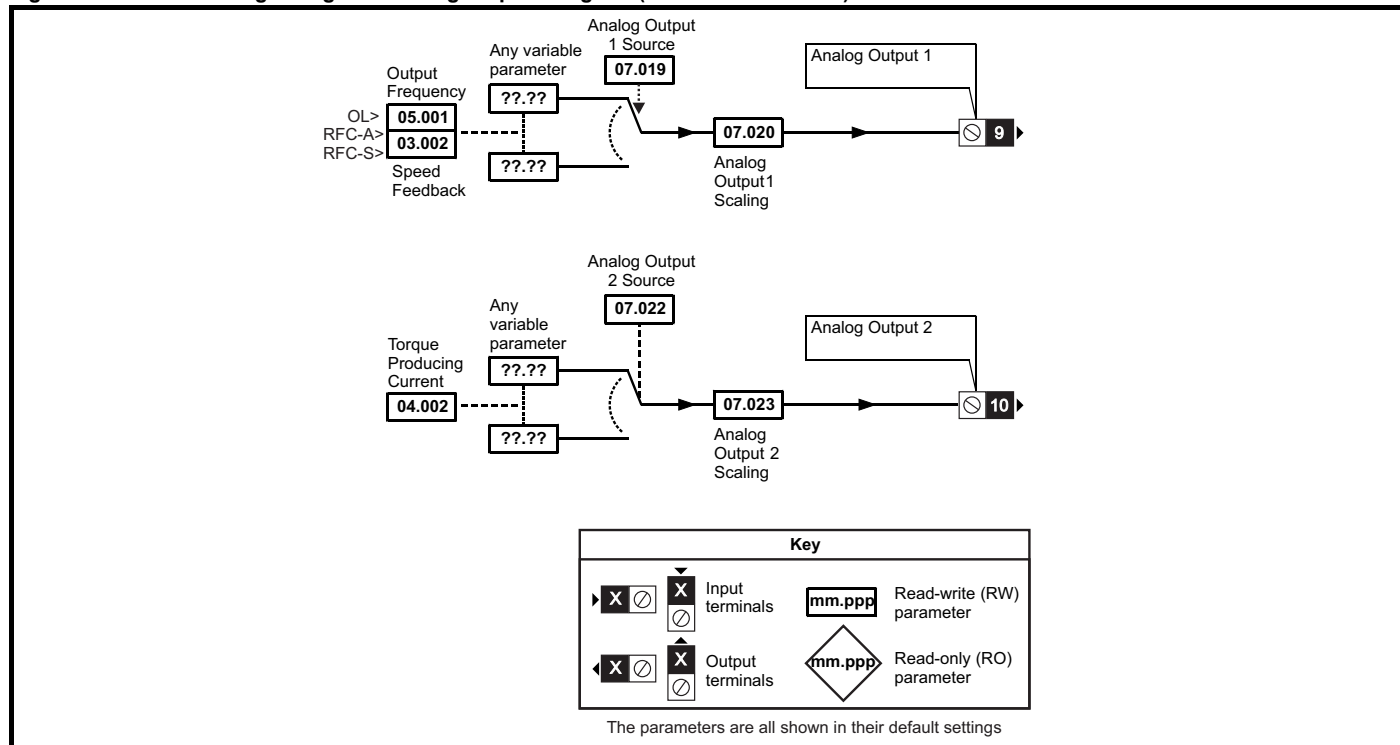
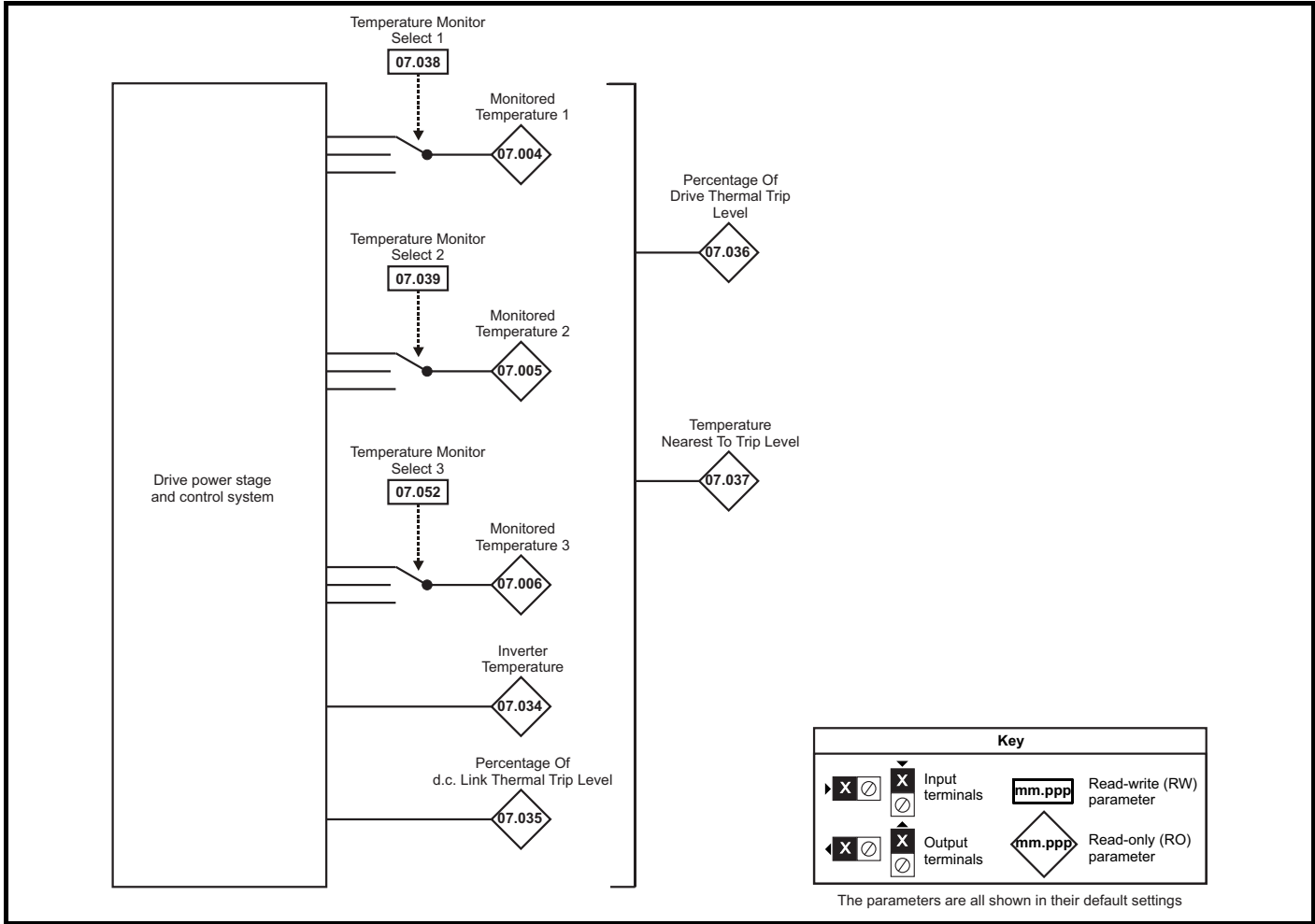


**Figure 12-20 Menu 7 thermal monitoring diagram**



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                           | Range(⇆)                                                                                                                                                                   |           | Default(⇒)           |           |       | Type |     |    |    |    |    |
|-----------|-------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|----------------------|-----------|-------|------|-----|----|----|----|----|
|           |                                           | OL                                                                                                                                                                         | RFC-A / S | OL                   | RFC-A     | RFC-S |      |     |    |    |    |    |
| 07.001    | Analog Input 1*                           | ±100.00 %                                                                                                                                                                  |           |                      |           |       | RO   | Num | ND | NC | PT | FI |
| 07.002    | Analog Input 2*                           | ±100.00 %                                                                                                                                                                  |           |                      |           |       | RO   | Num | ND | NC | PT | FI |
| 07.003    | Analog Input 3                            | ±100.00 %                                                                                                                                                                  |           |                      |           |       | RO   | Num | ND | NC | PT | FI |
| 07.004    | Monitored Temperature 1                   | ±250 °C                                                                                                                                                                    |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.005    | Monitored Temperature 2                   | ±250 °C                                                                                                                                                                    |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.006    | Monitored Temperature 3                   | ±250 °C                                                                                                                                                                    |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.007    | Analog Input 1 Mode*                      | 4-20 mA Low (-4), 20-4 mA Low (-3), 4-20 mA Hold (-2), 20-4 mA Hold (-1), 0-20 mA (0), 20-0 mA (1), 4-20 mA Trip (2), 20-4 mA Trip (3), 4-20 mA (4), 20-4 mA (5), Volt (6) |           |                      | Volt (6)  |       | RW   | Txt |    |    |    | US |
| 07.008    | Analog Input 1 Scaling*                   | 0.000 to 10.000                                                                                                                                                            |           |                      | 1.000     |       | RW   | Num |    |    |    | US |
| 07.009    | Analog Input 1 Invert*                    | Off (0) or On (1)                                                                                                                                                          |           |                      | Off (0)   |       | RW   | Bit |    |    |    | US |
| 07.010    | Analog Input 1 Destination*               | 0.000 to 59.999                                                                                                                                                            |           |                      | 1.036     |       | RW   | Num | DE |    | PT | US |
| 07.011    | Analog Input 2 Mode*                      | 4-20 mA Low (-4), 20-4 mA Low (-3), 4-20 mA Hold (-2), 20-4 mA Hold (-1), 0-20 mA (0), 20-0 mA (1), 4-20 mA Trip (2), 20-4 mA Trip (3), 4-20 mA (4), 20-4 mA (5), Volt (6) |           |                      | Volt (6)  |       | RW   | Txt |    |    |    | US |
| 07.012    | Analog Input 2 Scaling*                   | 0.000 to 10.000                                                                                                                                                            |           |                      | 1.000     |       | RW   | Num |    |    |    | US |
| 07.013    | Analog Input 2 Invert*                    | Off (0) or On (1)                                                                                                                                                          |           |                      | Off (0)   |       | RW   | Bit |    |    |    | US |
| 07.014    | Analog Input 2 Destination*               | 0.000 to 59.999                                                                                                                                                            |           |                      | 1.037     |       | RW   | Num | DE |    | PT | US |
| 07.015    | Analog Input 3 Mode                       | M700, M701: Volt (6), Therm Short Cct (7), Thermistor (8), Therm No Trip (9)                                                                                               |           | M700, M701: Volt (6) |           |       | RW   | Txt |    |    |    | US |
|           |                                           | M702*: Therm Short Cct (7), Thermistor (8), Therm No Trip (9), Disable (10)                                                                                                |           | M702*: Disable (10)  |           |       |      |     |    |    |    |    |
| 07.016    | Analog Input 3 Scaling*                   | 0.000 to 10.000                                                                                                                                                            |           |                      | 1.000     |       | RW   | Num |    |    |    | US |
| 07.017    | Analog Input 3 Invert*                    | Off (0) or On (1)                                                                                                                                                          |           |                      | Off (0)   |       | RW   | Bit |    |    |    | US |
| 07.018    | Analog Input 3 Destination*               | 0.000 to 59.999                                                                                                                                                            |           |                      | 0.000     |       | RW   | Num | DE |    | PT | US |
| 07.019    | Analog Output 1 Source*                   | 0.000 to 59.999                                                                                                                                                            |           | 5.001                | 3.002     |       | RW   | Num |    |    | PT | US |
| 07.020    | Analog Output 1 Scaling*                  | 0.000 to 10.000                                                                                                                                                            |           |                      | 1.000     |       | RW   | Num |    |    |    | US |
| 07.022    | Analog Output 2 Source*                   | 0.000 to 59.999                                                                                                                                                            |           |                      | 4.002     |       | RW   | Num |    |    | PT | US |
| 07.023    | Analog Output 2 Scaling*                  | 0.000 to 10.000                                                                                                                                                            |           |                      | 1.000     |       | RW   | Num |    |    |    | US |
| 07.025    | Calibrate Analog Input 1 Full Scale*      | Off (0) or On (1)                                                                                                                                                          |           |                      | Off (0)   |       | RW   | Bit |    | NC |    |    |
| 07.026    | Analog Input 1 Fast Update Active*        | Off (0) or On (1)                                                                                                                                                          |           |                      |           |       | RO   | Bit | ND | NC | PT |    |
| 07.027    | Analog Input 2 Fast Update Active*        | Off (0) or On (1)                                                                                                                                                          |           |                      |           |       | RO   | Bit | ND | NC | PT |    |
| 07.028    | Analog Input 1 Current Loop Loss*         | Off (0) or On (1)                                                                                                                                                          |           |                      |           |       | RO   | Bit | ND | NC | PT |    |
| 07.029    | Analog Input 2 Current Loop Loss*         | Off (0) or On (1)                                                                                                                                                          |           |                      |           |       | RO   | Bit | ND | NC | PT |    |
| 07.030    | Analog Input 1 Offset*                    | ±100.00 %                                                                                                                                                                  |           |                      | 0.00 %    |       | RW   | Num |    |    |    | US |
| 07.031    | Analog Input 2 Offset*                    | ±100.00 %                                                                                                                                                                  |           |                      | 0.00 %    |       | RW   | Num |    |    |    | US |
| 07.032    | Analog Input 3 Offset*                    | ±100.00 %                                                                                                                                                                  |           |                      | 0.00 %    |       | RW   | Num |    |    |    | US |
| 07.033    | Power Output                              | ±100.0 %                                                                                                                                                                   |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.034    | Inverter Temperature                      | ±250 °C                                                                                                                                                                    |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.035    | Percentage Of d.c. Bus Thermal Trip Level | 0 to 100 %                                                                                                                                                                 |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.036    | Percentage Of Drive Thermal Trip Level    | 0 to 100 %                                                                                                                                                                 |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.037    | Temperature Nearest To Trip Level         | 0 to 20999                                                                                                                                                                 |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.038    | Temperature Monitor Select 1              | 0 to 1999                                                                                                                                                                  |           |                      | 1001      |       | RW   | Num |    |    |    | US |
| 07.039    | Temperature Monitor Select 2              | 0 to 1999                                                                                                                                                                  |           |                      | 1002      |       | RW   | Num |    |    |    | US |
| 07.040    | Analog Input 1 Minimum*                   | ±100.00 %                                                                                                                                                                  |           |                      | -100.00 % |       | RW   | Num |    |    |    | US |
| 07.041    | Analog Input 2 Minimum*                   | ±100.00 %                                                                                                                                                                  |           |                      | -100.00 % |       | RW   | Num |    |    |    | US |
| 07.042    | Analog Input 3 Minimum*                   | ±100.00 %                                                                                                                                                                  |           |                      | -100.00 % |       | RW   | Num |    |    |    | US |
| 07.043    | Analog Input 1 Maximum*                   | ±100.00 %                                                                                                                                                                  |           |                      | 100.00 %  |       | RW   | Num |    |    |    | US |
| 07.044    | Analog Input 2 Maximum*                   | ±100.00 %                                                                                                                                                                  |           |                      | 100.00 %  |       | RW   | Num |    |    |    | US |
| 07.045    | Analog Input 3 Maximum*                   | ±100.00 %                                                                                                                                                                  |           |                      | 100.00 %  |       | RW   | Num |    |    |    | US |
| 07.046    | Analog Input 3 Thermistor Type            | DIN44082 (0), KTY84 (1), PT100 (4W) (2), PT1000 (4W) (3), PT2000 (4W) (4), 2.0 mA (4W) (5), PT100 (2W) (6), PT1000 (2W) (7), PT2000 (2W) (8), 2.0 mA (2W) (9)              |           | DIN44082 (0)         |           |       | RW   | Txt |    |    |    | US |
| 07.047    | Analog Input 3 Thermistor Feedback        | 0 to 5000 Ω                                                                                                                                                                |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.048    | Analog Input 3 Thermistor Trip Threshold  | 0 to 5000 Ω                                                                                                                                                                |           |                      | 3300 Ω    |       | RW   | Num |    |    |    | US |
| 07.049    | Analog Input 3 Thermistor Reset Threshold | 0 to 5000 Ω                                                                                                                                                                |           |                      | 1800 Ω    |       | RW   | Num |    |    |    | US |
| 07.050    | Analog Input 3 Thermistor Temperature     | -50 to 300 °C                                                                                                                                                              |           |                      |           |       | RO   | Num | ND | NC | PT |    |
| 07.051    | Analog Input 1 Full Scale*                | 0 to 65535                                                                                                                                                                 |           |                      |           |       | RO   | Num | ND | NC | PT | PS |
| 07.052    | Temperature Monitor Select 3              | 0 to 1999                                                                                                                                                                  |           |                      | 1         |       | RW   | Num |    |    |    | US |

\* Not available on Unidrive M702

\*\* Not available on Unidrive M702 with date code earlier than 1710

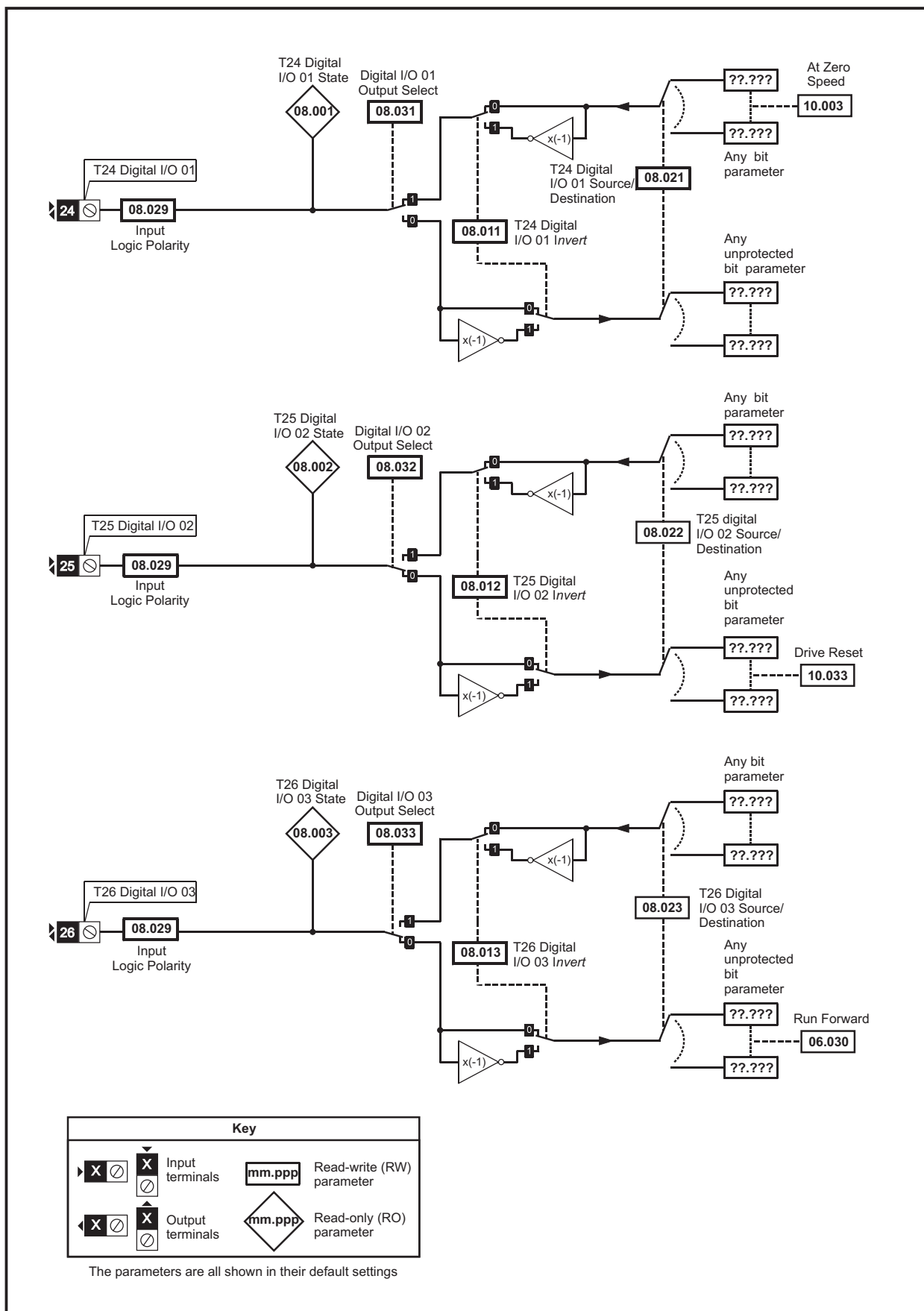
|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

|                       |                        |                            |                            |                    |                     |                      |              |                        |                            |                |                                |             |                   |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|---------------------|----------------------|--------------|------------------------|----------------------------|----------------|--------------------------------|-------------|-------------------|
| Safety<br>information | Product<br>information | Mechanical<br>installation | Electrical<br>installation | Getting<br>started | Basic<br>parameters | Running<br>the motor | Optimization | Drive<br>communication | NV Media Card<br>Operation | Onboard<br>PLC | <b>Advanced<br/>parameters</b> | Diagnostics | UL<br>information |
|-----------------------|------------------------|----------------------------|----------------------------|--------------------|---------------------|----------------------|--------------|------------------------|----------------------------|----------------|--------------------------------|-------------|-------------------|

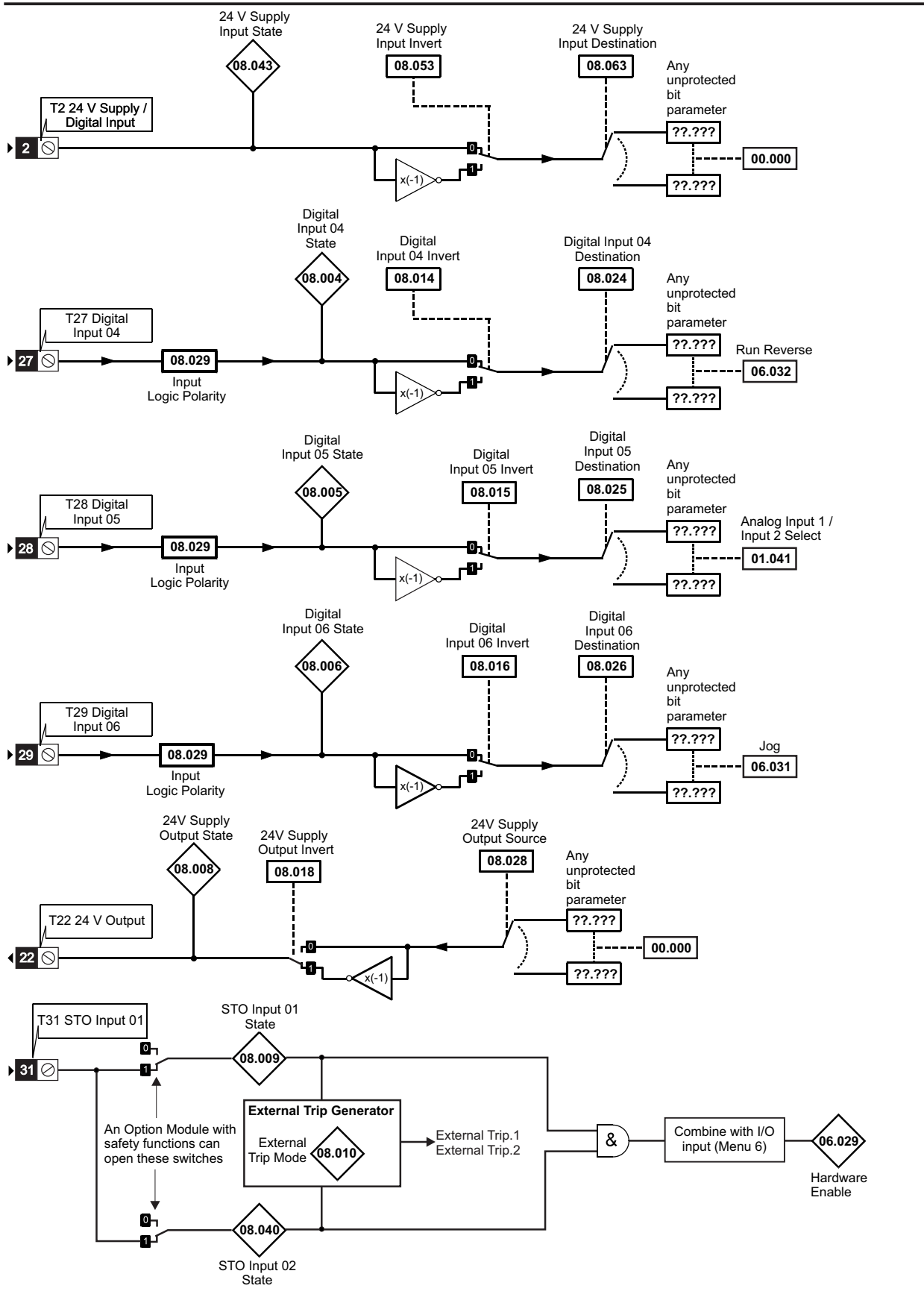
|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 12.9 Menu 8: Digital I/O

Figure 12-21 Menu 8 Digital input and outputs logic diagram (Unidrive M700 / M701)

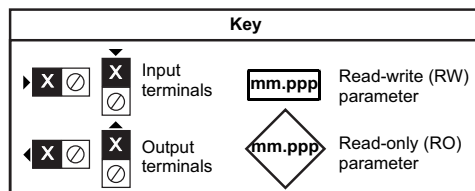
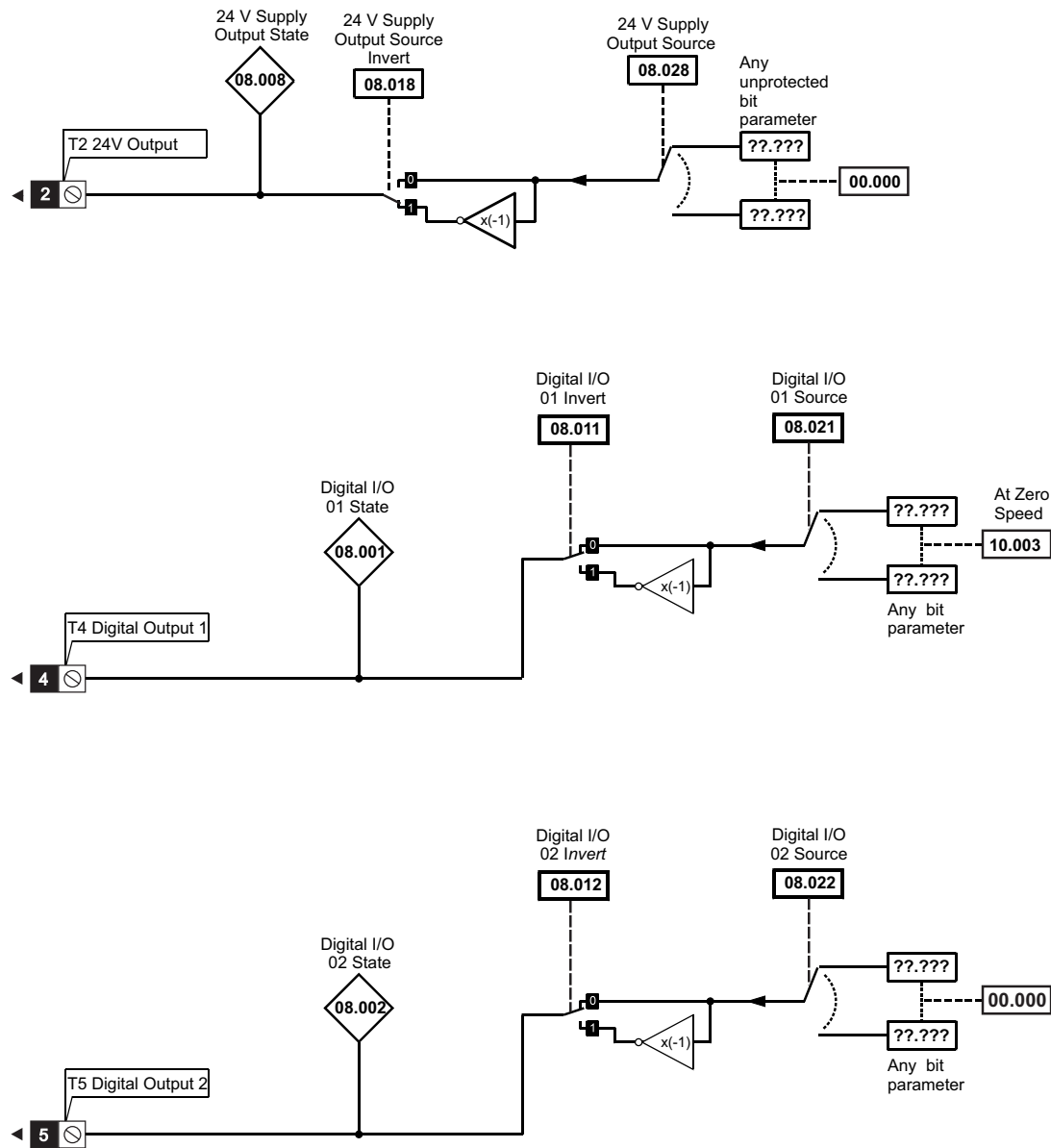


|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

Figure 12-22 Menu 8 Digital input and outputs logic diagram (Unidrive M702)



The parameters are all shown in their default settings

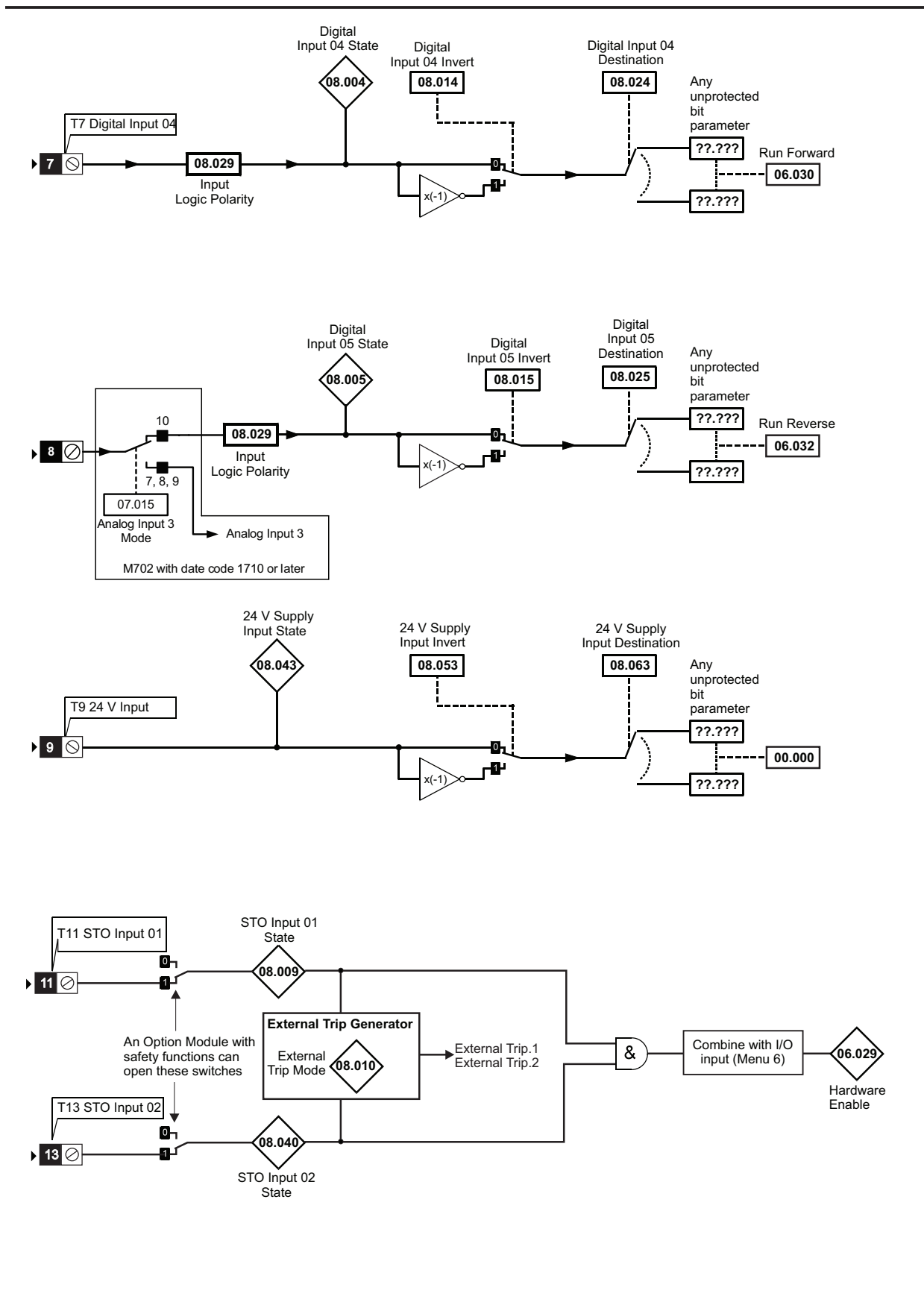


Figure 12-23 Menu 8 Relay output logic diagram

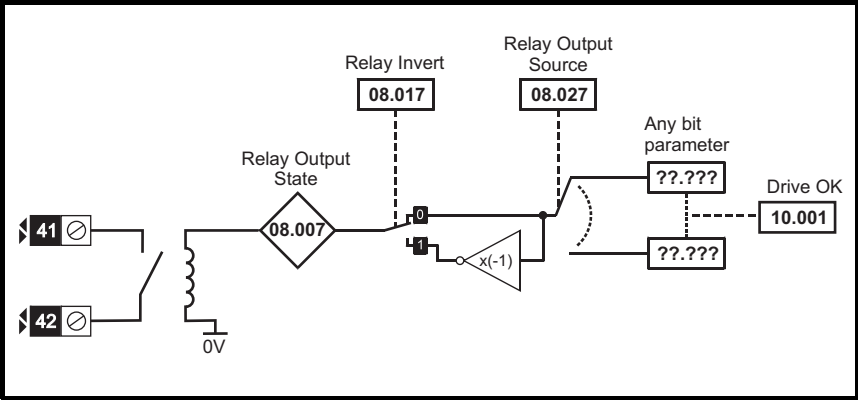
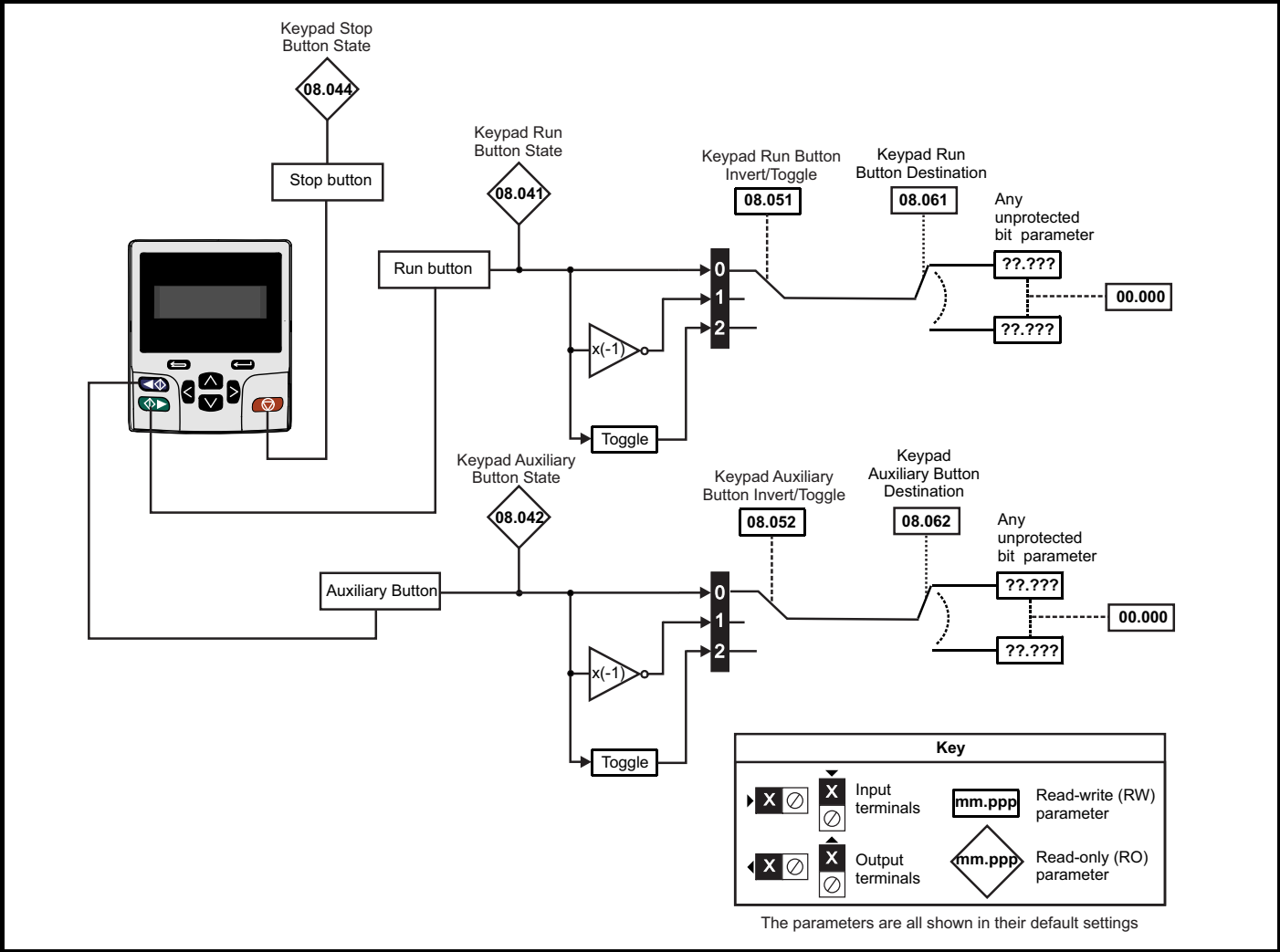


Figure 12-24 Menu 8 Keypad buttons logic diagram



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                       | Range(⇅)                                              |           | Default(⇒)         |       |       | Type |     |    |    |    |    |
|-----------|---------------------------------------|-------------------------------------------------------|-----------|--------------------|-------|-------|------|-----|----|----|----|----|
|           |                                       | OL                                                    | RFC-A / S | OL                 | RFC-A | RFC-S |      |     |    |    |    |    |
| 08.001    | Digital I/O 01 State                  | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.002    | Digital I/O 02 State                  | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.003    | Digital I/O 03 State*                 | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.004    | Digital Input 04 State                | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.005    | Digital Input 05 State                | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.006    | Digital Input 06 State*               | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.007    | Relay Output State                    | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.008    | 24V Supply Output State               | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.009    | STO Input 01 State                    | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.010    | External Trip Mode                    | Disable (0), STO 1 (1), STO 2 (2), STO 1 OR STO 2 (3) |           | Disable (0)        |       |       | RW   | Txt |    |    |    | US |
| 08.011    | Digital I/O 01 Invert                 | Not Invert (0) or Invert (1)                          |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.012    | Digital I/O 02 Invert                 | Not Invert (0) or Invert (1)                          |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.013    | Digital I/O 03 Invert*                | Not Invert (0) or Invert (1)                          |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.014    | Digital Input 04 Invert               | Not Invert (0) or Invert (1)                          |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.015    | Digital Input 05 Invert               | Not Invert (0) or Invert (1)                          |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.016    | Digital Input 06 Invert*              | Not Invert (0) or Invert (1)                          |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.017    | Relay Invert                          | Not Invert (0) or Invert (1)                          |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.018    | 24V Supply Output Invert              | Not Invert (0) or Invert (1)                          |           | Invert (1)         |       |       | RW   | Txt |    |    |    | US |
| 08.020    | Digital I/O Read Word                 | 0 to 511                                              |           |                    |       |       | RO   | Num | ND | NC | PT |    |
| 08.021    | Digital I/O 01 Source/Destination     | 0.000 to 59.999                                       |           | 10.003             |       |       | RW   | Num | DE |    | PT | US |
| 08.022    | Digital I/O 02 Source/Destination     | 0.000 to 59.999                                       |           | 10.033**           |       |       | RW   | Num | DE |    | PT | US |
| 08.023    | Digital I/O 03 Source/Destination*    | 0.000 to 59.999                                       |           | 6.030              |       |       | RW   | Num | DE |    | PT | US |
| 08.024    | Digital Input 04 Destination          | 0.000 to 59.999                                       |           | 6.032***           |       |       | RW   | Num | DE |    | PT | US |
| 08.025    | Digital Input 05 Destination          | 0.000 to 59.999                                       |           | 1.041****          |       |       | RW   | Num | DE |    | PT | US |
| 08.026    | Digital Input 06 Destination*         | 0.000 to 59.999                                       |           | 6.031              |       |       | RW   | Num | DE |    | PT | US |
| 08.027    | Relay Output Source                   | 0.000 to 59.999                                       |           | 10.001             |       |       | RW   | Num |    |    | PT | US |
| 08.028    | 24V Supply Output Source              | 0.000 to 59.999                                       |           | 0.000              |       |       | RW   | Num |    |    | PT | US |
| 08.029    | Input Logic Polarity                  | Negative Logic (0) or Positive Logic (1)              |           | Positive Logic (1) |       |       | RW   | Txt |    |    |    | US |
| 08.031    | Digital I/O 01 Output Select*         | Off (0) or On (1)                                     |           | On (1)             |       |       | RW   | Bit |    |    |    | US |
| 08.032    | Digital I/O 02 Output Select*         | Off (0) or On (1)                                     |           | Off (0)            |       |       | RW   | Bit |    |    |    | US |
| 08.033    | Digital I/O 03 Output Select*         | Off (0) or On (1)                                     |           | Off (0)            |       |       | RW   | Bit |    |    |    | US |
| 08.040    | STO Input 02 State                    | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.041    | Keypad Run Button State               | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.042    | Keypad Auxiliary Button State         | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.043    | 24V Supply Input State                | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.044    | Keypad Stop Button State              | Off (0) or On (1)                                     |           |                    |       |       | RO   | Bit | ND | NC | PT |    |
| 08.051    | Keypad Run Button Invert/Toggle       | Not Invert (0), Invert (1) or Toggle (2)              |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.052    | Keypad Auxiliary Button Invert/Toggle | Not Invert (0), Invert (1) or Toggle (2)              |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.053    | 24V Supply Input Invert               | Not Invert (0) or Invert (1)                          |           | Not Invert (0)     |       |       | RW   | Txt |    |    |    | US |
| 08.061    | Keypad Run Button Destination         | 0.000 to 59.999                                       |           | 0.000              |       |       | RW   | Num | DE |    | PT | US |
| 08.062    | Keypad Auxiliary Button Destination   | 0.000 to 59.999                                       |           | 0.000              |       |       | RW   | Num | DE |    | PT | US |
| 08.063    | 24V Supply Input Destination          | 0.000 to 59.999                                       |           | 0.000              |       |       | RW   | Num | DE |    | PT | US |
| 08.071    | DI/O Output Enable Register 1         | 0000000000000000 to 1111111111111111                  |           | 0000000000000000   |       |       | RW   | Bin |    |    | PT | US |
| 08.072    | DI/O Input Register 1                 | 0000000000000000 to 1111111111111111                  |           |                    |       |       | RO   | Bin | ND | NC | PT |    |
| 08.073    | DI/O Output Register 1                | 0000000000000000 to 1111111111111111                  |           | 0000000000000000   |       |       | RW   | Bin |    |    | PT |    |

\* Not available on *Unidrive M702*.

\*\* 0.000 with *Unidrive M702*.

\*\*\* 06.030 with *Unidrive M702*.

\*\*\*\* 06.032 with *Unidrive M702*.

| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

12.10 Menu 9: Programmable logic, motorized pot, binary sum and timers

Figure 12-25 Menu 9 logic diagram: Programmable logic

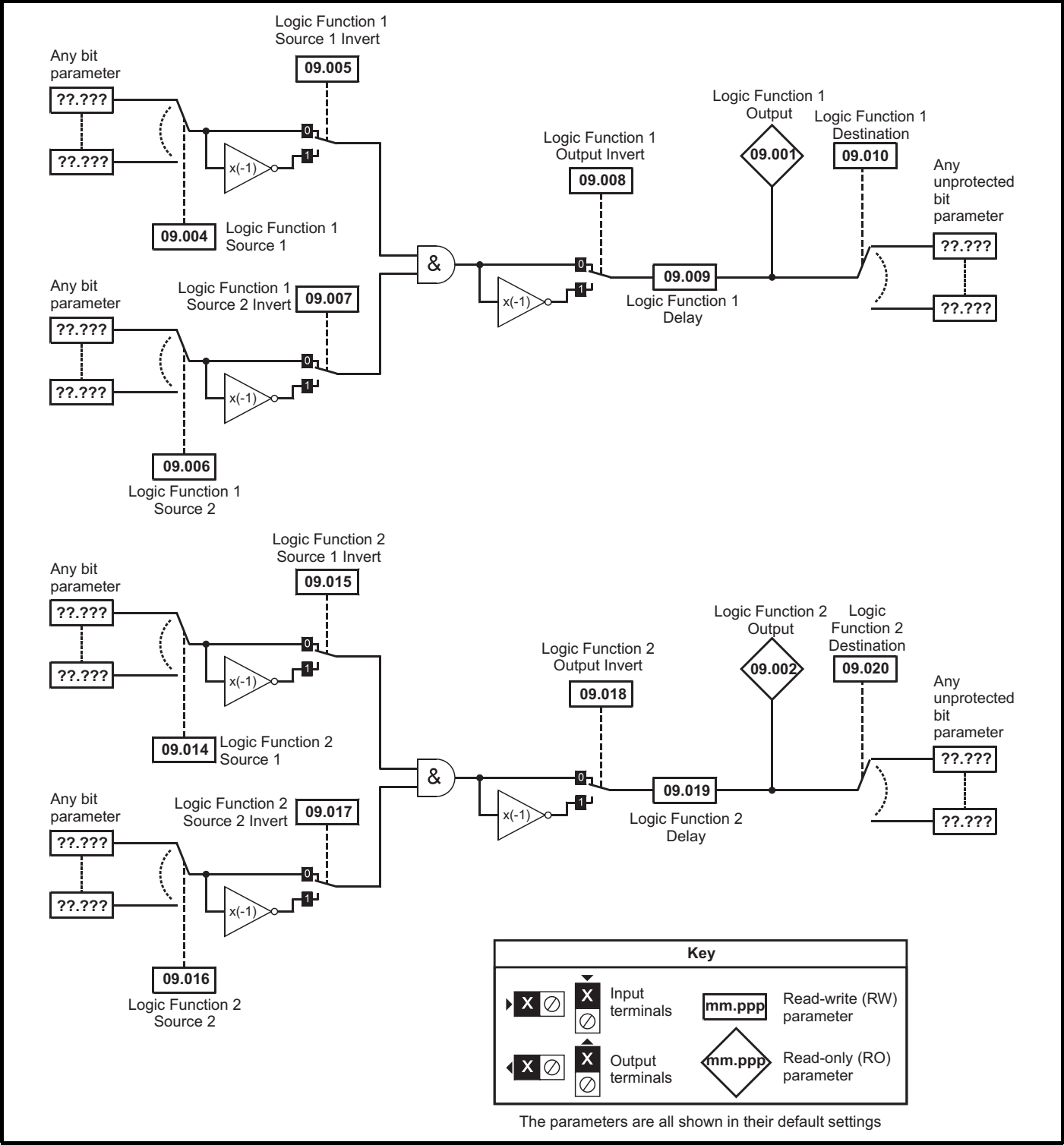


**Figure 12-26 Menu 9 logic diagram: Motorized pot and binary sum**

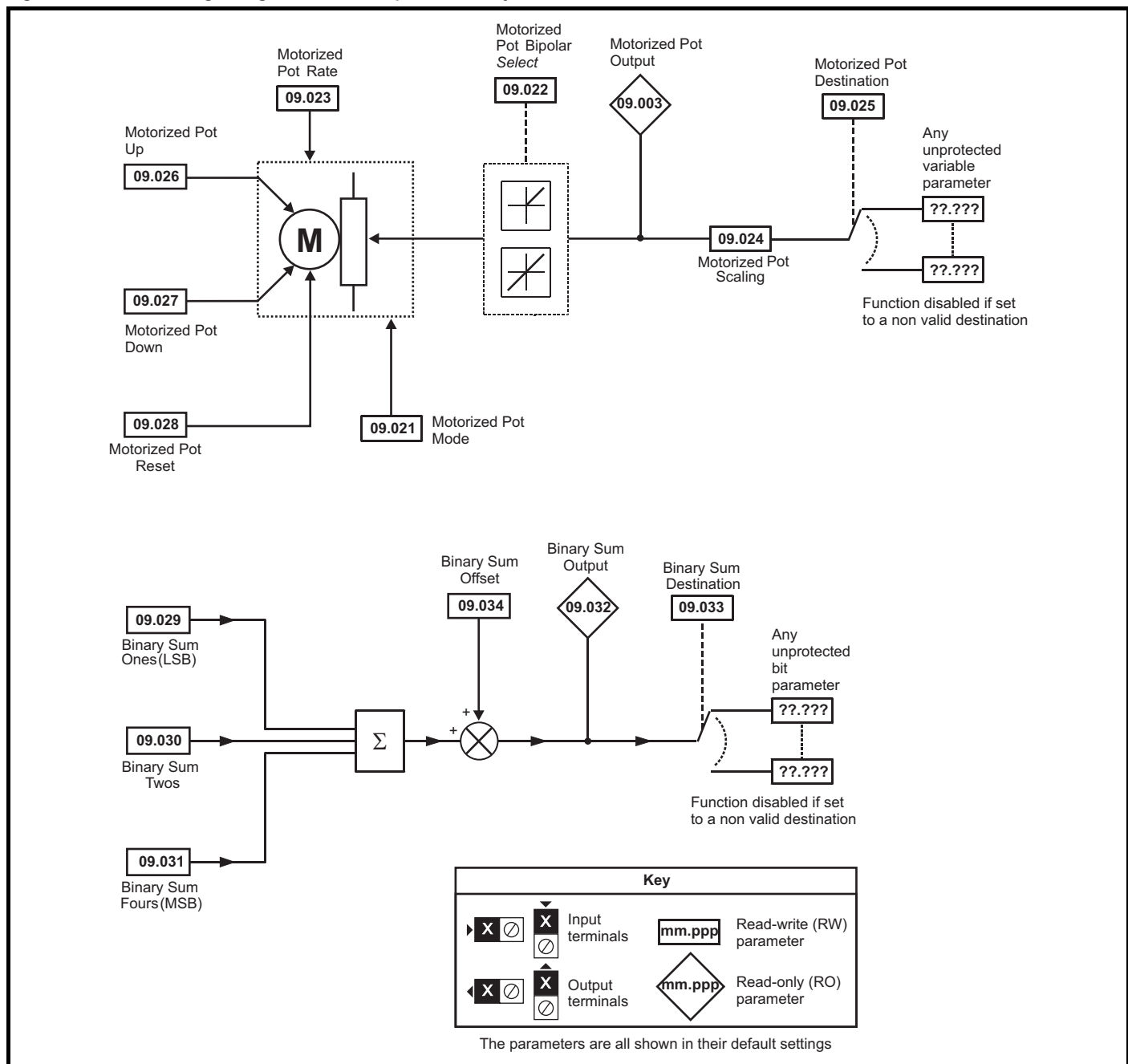


Figure 12-27 Menu 9 logic diagram: Timers

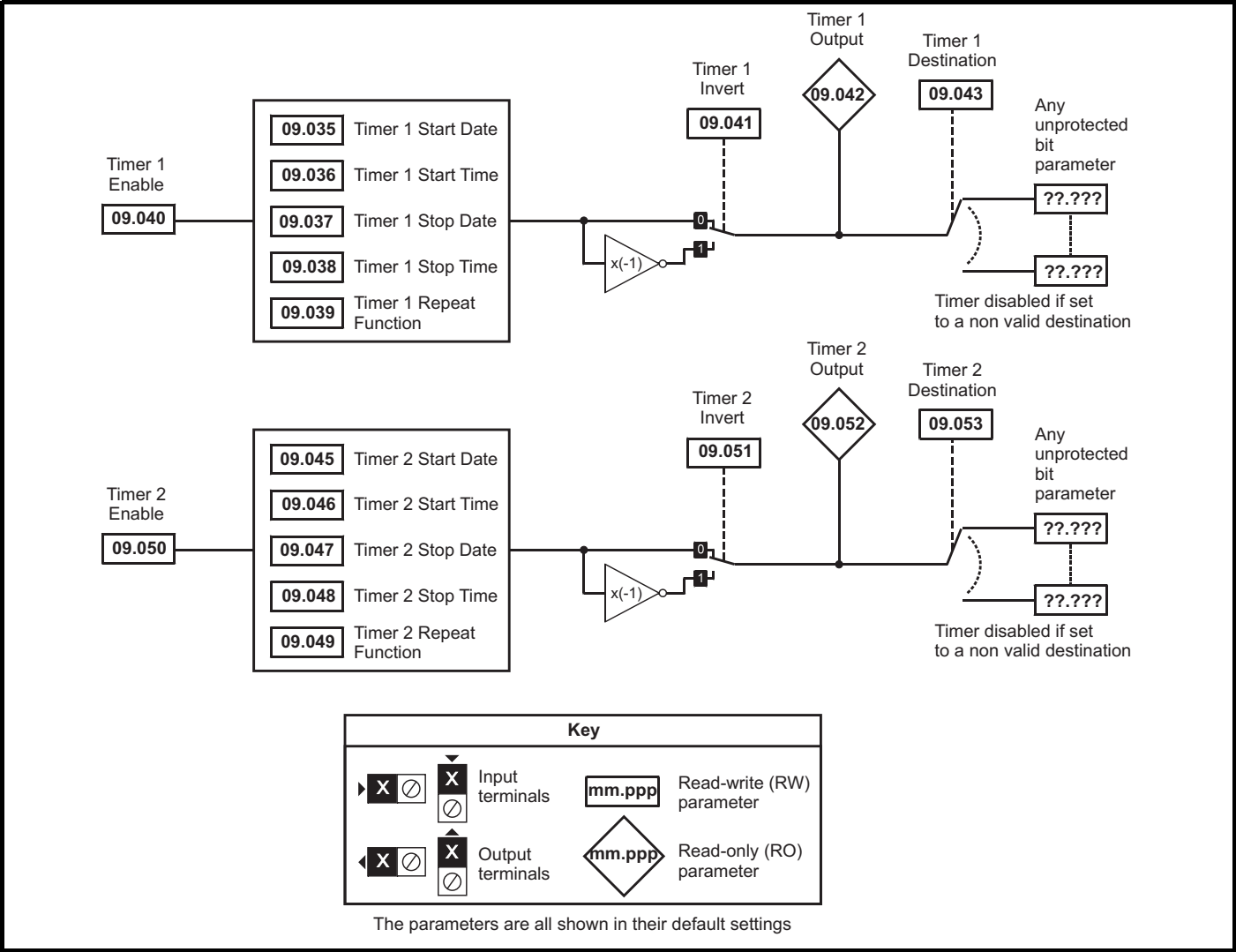
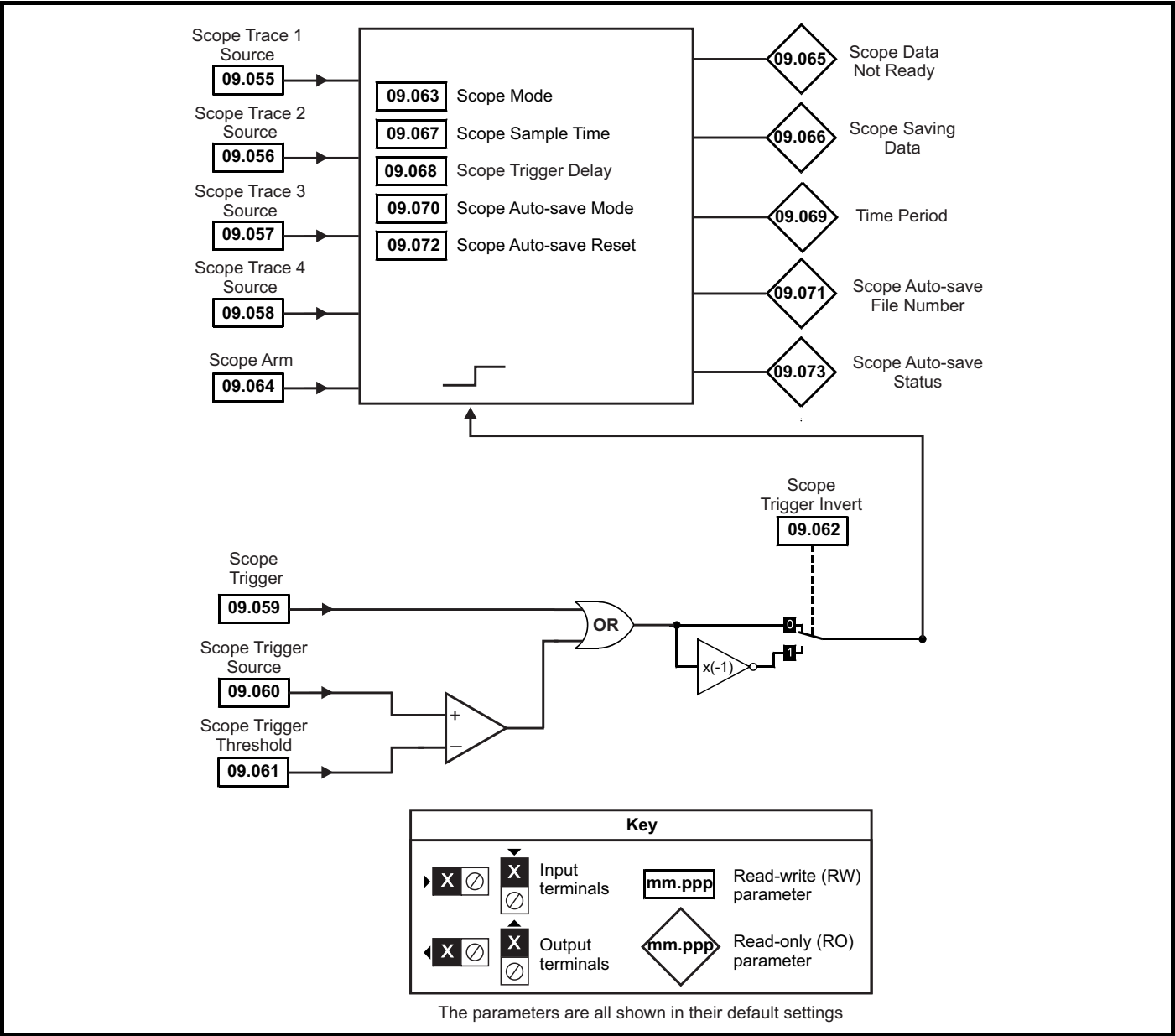


Figure 12-28 Menu 9 logic diagram: Scope function



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                  | Range(⌀)                                                                            |           | Default(⇌) |       |       | Type |      |    |    |    |    |
|-----------|----------------------------------|-------------------------------------------------------------------------------------|-----------|------------|-------|-------|------|------|----|----|----|----|
|           |                                  | OL                                                                                  | RFC-A / S | OL         | RFC-A | RFC-S |      |      |    |    |    |    |
| 09.001    | Logic Function 1 Output          | Off (0) or On (1)                                                                   |           |            |       |       | RO   | Bit  | ND | NC | PT |    |
| 09.002    | Logic Function 2 Output          | Off (0) or On (1)                                                                   |           |            |       |       | RO   | Bit  | ND | NC | PT |    |
| 09.003    | Motorized Pot Output             | ±100.00 %                                                                           |           |            |       |       | RO   | Num  | ND | NC | PT | PS |
| 09.004    | Logic Function 1 Source 1        | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.005    | Logic Function 1 Source 1 Invert | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.006    | Logic Function 1 Source 2        | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.007    | Logic Function 1 Source 2 Invert | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.008    | Logic Function 1 Output Invert   | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.009    | Logic Function 1 Delay           | ±25.0 s                                                                             |           | 0.0 s      |       |       | RW   | Num  |    |    |    | US |
| 09.010    | Logic Function 1 Destination     | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  | DE |    | PT | US |
| 09.014    | Logic Function 2 Source 1        | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.015    | Logic Function 2 Source 1 Invert | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.016    | Logic Function 2 Source 2        | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.017    | Logic Function 2 Source 2 Invert | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.018    | Logic Function 2 Output Invert   | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.019    | Logic Function 2 Delay           | ±25.0 s                                                                             |           | 0.0 s      |       |       | RW   | Num  |    |    |    | US |
| 09.020    | Logic Function 2 Destination     | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  | DE |    | PT | US |
| 09.021    | Motorized Pot Mode               | 0 to 4                                                                              |           | 0          |       |       | RW   | Num  |    |    |    | US |
| 09.022    | Motorized Pot Bipolar Select     | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.023    | Motorized Pot Rate               | 0 to 250 s                                                                          |           | 20 s       |       |       | RW   | Num  |    |    |    | US |
| 09.024    | Motorized Pot Scaling            | 0.000 to 4.000                                                                      |           | 1.000      |       |       | RW   | Num  |    |    |    | US |
| 09.025    | Motorized Pot Destination        | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  | DE |    | PT | US |
| 09.026    | Motorized Pot Up                 | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    | NC |    |    |
| 09.027    | Motorized Pot Down               | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    | NC |    |    |
| 09.028    | Motorized Pot Reset              | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    | NC |    |    |
| 09.029    | Binary Sum Ones                  | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    | NC |    |    |
| 09.030    | Binary Sum Twos                  | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    | NC |    |    |
| 09.031    | Binary Sum Fours                 | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    | NC |    |    |
| 09.032    | Binary Sum Output                | 0 to 255                                                                            |           |            |       |       | RO   | Num  | ND | NC | PT |    |
| 09.033    | Binary Sum Destination           | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  | DE |    | PT | US |
| 09.034    | Binary Sum Offset                | 0 to 248                                                                            |           | 0          |       |       | RW   | Num  |    |    |    | US |
| 09.035    | Timer 1 Start Date               | 00-00-00 to 31-12-99                                                                |           | 00-00-00   |       |       | RW   | Date |    |    |    | US |
| 09.036    | Timer 1 Start Time               | 00:00:00 to 23:59:59                                                                |           | 00:00:00   |       |       | RW   | Time |    |    |    | US |
| 09.037    | Timer 1 Stop Date                | 00-00-00 to 31-12-99                                                                |           | 00-00-00   |       |       | RW   | Date |    |    |    | US |
| 09.038    | Timer 1 Stop Time                | 00:00:00 to 23:59:59                                                                |           | 00:00:00   |       |       | RW   | Time |    |    |    | US |
| 09.039    | Timer 1 Repeat Function          | None (0), Hour (1), Day (2), Week (3), Month (4), Year (5), One off (6), Minute (7) |           | None (0)   |       |       | RW   | Txt  |    |    |    | US |
| 09.040    | Timer 1 Enable                   | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.041    | Timer 1 Invert                   | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.042    | Timer 1 Output                   | Off (0) or On (1)                                                                   |           |            |       |       | RO   | Bit  | ND | NC | PT |    |
| 09.043    | Timer 1 Destination              | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  | DE |    | PT | US |
| 09.045    | Timer 2 Start Date               | 00-00-00 to 31-12-99                                                                |           | 00-00-00   |       |       | RW   | Date |    |    |    | US |
| 09.046    | Timer 2 Start Time               | 00:00:00 to 23:59:59                                                                |           | 00:00:00   |       |       | RW   | Time |    |    |    | US |
| 09.047    | Timer 2 Stop Date                | 00-00-00 to 31-12-99                                                                |           | 00-00-00   |       |       | RW   | Date |    |    |    | US |
| 09.048    | Timer 2 Stop Time                | 00:00:00 to 23:59:59                                                                |           | 00:00:00   |       |       | RW   | Time |    |    |    | US |
| 09.049    | Timer 2 Repeat Function          | None (0), Hour (1), Day (2), Week (3), Month (4), Year (5), One off (6), Minute (7) |           | None (0)   |       |       | RW   | Txt  |    |    |    | US |
| 09.050    | Timer 2 Enable                   | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.051    | Timer 2 Invert                   | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |
| 09.052    | Timer 2 Output                   | Off (0) or On (1)                                                                   |           |            |       |       | RO   | Bit  | ND | NC | PT |    |
| 09.053    | Timer 2 Destination              | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  | DE |    | PT | US |
| 09.055    | Scope Trace 1 Source             | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.056    | Scope Trace 2 Source             | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.057    | Scope Trace 3 Source             | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.058    | Scope Trace 4 Source             | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.059    | Scope Trigger                    | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    |    |
| 09.060    | Scope Trigger Source             | 0.000 to 59.999                                                                     |           | 0.000      |       |       | RW   | Num  |    |    | PT | US |
| 09.061    | Scope Trigger Threshold          | -2147483648 to 2147483647                                                           |           | 0          |       |       | RW   | Num  |    |    |    | US |
| 09.062    | Scope Trigger Invert             | Off (0) or On (1)                                                                   |           | Off (0)    |       |       | RW   | Bit  |    |    |    | US |

| Parameter |                             | Range(↕)                                          |           | Default(⇄)   |       |       | Type |     |    |    |    |
|-----------|-----------------------------|---------------------------------------------------|-----------|--------------|-------|-------|------|-----|----|----|----|
|           |                             | OL                                                | RFC-A / S | OL           | RFC-A | RFC-S |      |     |    |    |    |
| 09.063    | Scope Mode                  | Single (0), Normal (1), Auto (2)                  |           | Single (0)   |       |       | RW   | Txt |    |    | US |
| 09.064    | Scope Arm                   | Off (0) or On (1)                                 |           | Off (0)      |       |       | RW   | Bit |    | NC |    |
| 09.065    | Scope Data Not Ready        | Off (0) or On (1)                                 |           |              |       |       | RO   | Bit | ND | NC | PT |
| 09.066    | Scope Saving Data           | Off (0) or On (1)                                 |           |              |       |       | RO   | Bit | ND | NC | PT |
| 09.067    | Scope Sample Time           | 1 to 200                                          |           | 1            |       |       | RW   | Num |    |    | US |
| 09.068    | Scope Trigger Delay         | 0 to 100 %                                        |           | 0 %          |       |       | RW   | Num |    |    | US |
| 09.069    | Scope Time Period           | 0.00 to 200000.00 ms                              |           |              |       |       | RO   | Num | ND | NC | PT |
| 09.070    | Scope Auto-save Mode        | Disabled (0), Overwrite (1), Keep (2)             |           | Disabled (0) |       |       | RW   | Txt |    |    | US |
| 09.071    | Scope Auto-save File Number | 0 to 99                                           |           |              |       |       | RO   | Num |    |    | PS |
| 09.072    | Scope Auto-save Reset       | Off (0) or On (1)                                 |           | Off (0)      |       |       | RW   | Bit |    |    |    |
| 09.073    | Scope Auto-save Status      | Disabled (0), Active (1), Stopped (2), Failed (3) |           |              |       |       | RO   | Txt |    |    | PS |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

## 12.11 Menu 10: Status and trips

| Parameter |                                        | Range(⌘)                                                  |           | Default(⇔)     |       |       | Type |      |    |    |    |    |
|-----------|----------------------------------------|-----------------------------------------------------------|-----------|----------------|-------|-------|------|------|----|----|----|----|
|           |                                        | OL                                                        | RFC-A / S | OL             | RFC-A | RFC-S |      |      |    |    |    |    |
| 10.001    | Drive OK                               | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.002    | Drive Active                           | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.003    | Zero Speed                             | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.004    | Running At Or Below Minimum Speed      | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.005    | Below Set Speed                        | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.006    | At Speed                               | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.007    | Above Set Speed                        | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.008    | Rated Load Reached                     | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.009    | Current Limit Active                   | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.010    | Regenerating                           | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.011    | Braking IGBT Active                    | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.012    | Braking Resistor Alarm                 | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.013    | Reverse Direction Commanded            | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.014    | Reverse Direction Running              | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.015    | Supply Loss                            | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.016    | Under Voltage Active                   | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.017    | Motor Overload Alarm                   | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.018    | Drive Over-temperature Alarm           | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.019    | Drive Warning                          | Off (0) or On (1)                                         |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.020    | Trip 0                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.021    | Trip 1                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.022    | Trip 2                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.023    | Trip 3                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.024    | Trip 4                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.025    | Trip 5                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.026    | Trip 6                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.027    | Trip 7                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.028    | Trip 8                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.029    | Trip 9                                 | 0 to 255                                                  |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.030    | Braking Resistor Rated Power           | 0.000 to 99999.999 kW                                     |           | See Table 12-5 |       |       | RW   | Num  |    |    |    | US |
| 10.031    | Braking Resistor Thermal Time Constant | 0.000 to 1500.000 s                                       |           | See Table 12-5 |       |       | RW   | Num  |    |    |    | US |
| 10.032    | External Trip                          | Off (0) or On (1)                                         |           | Off (0)        |       |       | RW   | Bit  |    | NC |    |    |
| 10.033    | Drive Reset                            | Off (0) or On (1)                                         |           | Off (0)        |       |       | RW   | Bit  |    | NC |    |    |
| 10.034    | Number Of Auto-reset Attempts          | None (0), 1 (1), 2 (2), 3 (3), 4 (4), 5 (5), Infinite (6) |           | None (0)       |       |       | RW   | Txt  |    |    |    | US |
| 10.035    | Auto-reset Delay                       | 1.0 to 600.0 s                                            |           | 1.0 s          |       |       | RW   | Num  |    |    |    | US |
| 10.036    | Auto-reset Hold Drive ok               | Off (0) or On (1)                                         |           | Off (0)        |       |       | RW   | Bit  |    |    |    | US |
| 10.037    | Action On Trip Detection               | 00000 to 11111                                            |           | 00000          |       |       | RW   | Bin  |    |    |    | US |
| 10.038    | User Trip                              | 0 to 255                                                  |           | 0              |       |       | RW   | Num  | ND | NC |    |    |
| 10.039    | Braking Resistor Thermal Accumulator   | 0.0 to 100.0 %                                            |           |                |       |       | RO   | Num  | ND | NC | PT |    |
| 10.040    | Status Word                            | 0000000000000000 to 1111111111111111                      |           |                |       |       | RO   | Bin  | ND | NC | PT |    |
| 10.041    | Trip 0 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.042    | Trip 0 Time                            | 00:00:00 to 23:59:59                                      |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.043    | Trip 1 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.044    | Trip 1 Time                            | 00:00:00 to 23:59:59                                      |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.045    | Trip 2 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.046    | Trip 2 Time                            | 00:00:00 to 23:59:59                                      |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.047    | Trip 3 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.048    | Trip 3 Time                            | 00:00:00 to 23:59:59                                      |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.049    | Trip 4 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.050    | Trip 4 Time                            | 00:00:00 to 23:59:59                                      |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.051    | Trip 5 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.052    | Trip 5 Time                            | 00:00:00 to 23:59:59                                      |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.053    | Trip 6 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.054    | Trip 6 Time                            | 00:00:00 to 23:59:59                                      |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.055    | Trip 7 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.056    | Trip 7 Time                            | 00:00:00 to 23:59:59                                      |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.057    | Trip 8 Date                            | 00-00-00 to 31-12-99                                      |           |                |       |       | RO   | Date | ND | NC | PT | PS |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                     | Range(⌘)                                                                                                                                                                                                                            |           | Default(⇌)     |       |       | Type |      |    |    |    |    |
|-----------|-------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|----------------|-------|-------|------|------|----|----|----|----|
|           |                                     | OL                                                                                                                                                                                                                                  | RFC-A / S | OL             | RFC-A | RFC-S |      |      |    |    |    |    |
| 10.058    | Trip 8 Time                         | 00:00:00 to 23:59:59                                                                                                                                                                                                                |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.059    | Trip 9 Date                         | 00-00-00 to 31-12-99                                                                                                                                                                                                                |           |                |       |       | RO   | Date | ND | NC | PT | PS |
| 10.060    | Trip 9 Time                         | 00:00:00 to 23:59:59                                                                                                                                                                                                                |           |                |       |       | RO   | Time | ND | NC | PT | PS |
| 10.061    | Braking Resistor Resistance         | 0.00 to 10000.00 Ω                                                                                                                                                                                                                  |           | See Table 12-5 |       |       | RW   | Num  |    |    |    | US |
| 10.062    | Low Load Detected Alarm             | Off (0) or On (1)                                                                                                                                                                                                                   |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.063    | Local Keypad Battery Low            | Off (0) or On (1)                                                                                                                                                                                                                   |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.064    | Remote Keypad Battery Low           | Off (0) or On (1)                                                                                                                                                                                                                   |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.065    | Auto-tune Active                    | Off (0) or On (1)                                                                                                                                                                                                                   |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.066    | Limit Switch Active                 | Off (0) or On (1)                                                                                                                                                                                                                   |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.068    | Hold Drive Healthy On Under Voltage | Off (0) or On (1)                                                                                                                                                                                                                   |           | Off (0)        |       |       | RW   | Bit  |    |    |    | US |
| 10.069    | Additional Status Bits              | 0000000000 to 1111111111                                                                                                                                                                                                            |           |                |       |       | RO   | Bin  | ND | NC | PT |    |
| 10.070    | Trip 0 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.071    | Trip 1 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.072    | Trip 2 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.073    | Trip 3 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.074    | Trip 4 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.075    | Trip 5 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.076    | Trip 6 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.077    | Trip 7 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.078    | Trip 8 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.079    | Trip 9 Sub-trip Number              | 0 to 65535                                                                                                                                                                                                                          |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.080    | Stop Motor                          | Off (0) or On (1)                                                                                                                                                                                                                   |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.081    | Phase Loss                          | Off (0) or On (1)                                                                                                                                                                                                                   |           |                |       |       | RO   | Bit  | ND | NC | PT |    |
| 10.101    | Drive Status                        | Inhibit (0), Ready (1), Stop (2), Scan (3), Run (4), Supply Loss (5), Deceleration (6), dc Injection (7), Position (8), Trip (9), Active (10), Off (11), Hand (12), Auto (13), Heat (14), Under Voltage (15), Phasing (16)          |           |                |       |       | RO   | Txt  | ND | NC | PT |    |
| 10.102    | Trip Reset Source                   | 0 to 1023                                                                                                                                                                                                                           |           |                |       |       | RO   | Num  | ND | NC | PT | PS |
| 10.103    | Trip Time Identifier                | -2147483648 to 2147483647 ms                                                                                                                                                                                                        |           |                |       |       | RO   | Num  | ND | NC | PT |    |
| 10.104    | Active Alarm                        | None (0), Brake Resistor (1), Motor Overload (2), Ind Overload (3), Drive Overload (4), Auto Tune (5), Limit Switch (6), Fire Mode (7), Low Load (8), Option Slot 1 (9), Option Slot 2 (10), Option Slot 3 (11), Option Slot 4 (12) |           |                |       |       | RO   | Txt  | ND | NC | PT |    |
| 10.105    | Hand Off Auto State                 | Not Active (0), Off (1), Hand (2), Auto (3)                                                                                                                                                                                         |           |                |       |       | RO   | Txt  | ND | NC | PT | PS |
| 10.106    | Potential Drive Damage Conditions   | 0000 to 1111                                                                                                                                                                                                                        |           |                |       |       | RO   | Bin  | ND | NC | PT | PS |
| 10.107    | Auto tune State                     | Not Active (0), Resistance (1), pLs (2), Ls (3), Flux (4), Flux Repeat (5), Ld Lq No load (6), Lq (7), Ke (8), Inertia (9)                                                                                                          |           |                |       |       | RO   | Txt  | ND | NC | PT |    |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | Fl  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

**Table 12-5 Defaults for Pr 10.030, Pr 10.031 and Pr 10.061**

| Drive size                        | Pr 10.030 | Pr 10.031 | Pr 10.061 |
|-----------------------------------|-----------|-----------|-----------|
| Size 3                            | 50 W      | 3.3 s     | 75 Ω      |
| Size 4 and 5                      | 100 W     | 2.0 s     | 38 Ω      |
| All other ratings and frame sizes | 0.000     |           | 0.00      |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 12.12 Menu 11: General drive set-up

| Parameter |                                                     | Range(⇅)                                                                                                                                                                                                                                                     |           | Default(⇒)    |           |           | Type |     |    |    |    |    |
|-----------|-----------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------|---------------|-----------|-----------|------|-----|----|----|----|----|
|           |                                                     | OL                                                                                                                                                                                                                                                           | RFC-A / S | OL            | RFC-A     | RFC-S     |      |     |    |    |    |    |
| 11.001    | Option Synchronisation Select                       | Not Active (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4), Automatic (5)                                                                                                                                                                                |           | Slot 4 (4)    |           |           | RW   | Txt |    |    |    | US |
| 11.002    | Option synchronisation Active                       | Not Active (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4)                                                                                                                                                                                               |           |               |           |           | RO   | Txt | ND | NC | PT |    |
| 11.018    | Status Mode Parameter 1                             | 0.000 to 59.999                                                                                                                                                                                                                                              |           | 0.000         |           |           | RW   | Num |    |    | PT | US |
| 11.019    | Status Mode Parameter 2                             | 0.000 to 59.999                                                                                                                                                                                                                                              |           | 0.000         |           |           | RW   | Num |    |    | PT | US |
| 11.020    | Reset Serial Communications*                        | Off (0) or On (1)                                                                                                                                                                                                                                            |           | Off (0)       |           |           | RW   | Bit | ND | NC |    |    |
| 11.021    | Parameter 00.030 Scaling                            | 0.000 to 10.000                                                                                                                                                                                                                                              |           | 1.000         |           |           | RW   | Num |    |    |    | US |
| 11.022    | Parameter Displayed At Power-up                     | 0.000 to 0.080                                                                                                                                                                                                                                               |           | 0.010         |           |           | RW   | Num |    |    | PT | US |
| 11.023    | Serial Address*                                     | 1 to 247                                                                                                                                                                                                                                                     |           | 1             |           |           | RW   | Num |    |    |    | US |
| 11.024    | Serial Mode*                                        | 8 2 NP (0), 8 1 NP (1), 8 1 EP (2), 8 1 OP (3), 8 2 NP M (4), 8 1 NP M (5), 8 1 EP M (6), 8 1 OP M (7), 7 2 NP (8), 7 1 NP (9), 7 1 EP (10), 7 1 OP (11), 7 2 NP M (12), 7 1 NP M (13), 7 1 EP M (14), 7 1 OP M (15)                                         |           | 8 2 NP (0)    |           |           | RW   | Txt |    |    |    | US |
| 11.025    | Serial Baud Rate*                                   | 300 (0), 600 (1), 1200 (2), 2400 (3), 4800 (4), 9600 (5), 19200 (6), 38400 (7), 57600 (8), 76800 (9), 115200 (10)                                                                                                                                            |           | 19200 (6)     |           |           | RW   | Txt |    |    |    | US |
| 11.026    | Minimum Comms Transmit Delay*                       | 0 to 250 ms                                                                                                                                                                                                                                                  |           | 2 ms          |           |           | RW   | Num |    |    |    | US |
| 11.027    | Silent Period*                                      | 0 to 250 ms                                                                                                                                                                                                                                                  |           | 0 ms          |           |           | RW   | Num |    |    |    | US |
| 11.028    | Drive Derivative                                    | 0 to 255                                                                                                                                                                                                                                                     |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.029    | Software Version                                    | 00.00.00.00 to 99.99.99.99                                                                                                                                                                                                                                   |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.030    | User Security Code                                  | 0 to 2147483647                                                                                                                                                                                                                                              |           | 0             |           |           | RW   | Num | ND | NC | PT | US |
| 11.031    | User Drive Mode                                     | Open-loop (1), RFC-A (2), RFC-S (3), Regen (4)                                                                                                                                                                                                               |           | Open-loop (1) | RFC-A (2) | RFC-S (3) | RW   | Txt | ND | NC | PT |    |
| 11.032    | Maximum Heavy Duty Rating                           | 0.000 to 99999.999 A                                                                                                                                                                                                                                         |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.033    | Drive Rated Voltage                                 | 200 V (0), 400 V (1), 575 V (2), 690 V (3)                                                                                                                                                                                                                   |           |               |           |           | RO   | Txt | ND | NC | PT |    |
| 11.034    | Software Sub Version                                | 0 to 99                                                                                                                                                                                                                                                      |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.035    | Number Of Power Modules Test                        | -1 to 20                                                                                                                                                                                                                                                     |           | -1            |           |           | RW   | Num |    |    |    | US |
| 11.036    | NV Media Card File Previously Loaded                | 0 to 999                                                                                                                                                                                                                                                     |           |               |           |           | RO   | Num |    | NC | PT |    |
| 11.037    | NV Media Card File Number                           | 0 to 999                                                                                                                                                                                                                                                     |           | 0             |           |           | RW   | Num |    |    |    |    |
| 11.038    | NV Media Card File Type                             | None (0), Open-loop (1), RFC-A (2), RFC-S (3), Regen (4), User Prog (5)                                                                                                                                                                                      |           |               |           |           | RO   | Txt | ND | NC | PT |    |
| 11.039    | NV Media Card File Version                          | 0 to 9999                                                                                                                                                                                                                                                    |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.040    | NV Media Card File Checksum                         | -2147483648 to 2147483647                                                                                                                                                                                                                                    |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.042    | Parameter Cloning                                   | None (0), Read (1), Program (2), Auto (3), Boot (4)                                                                                                                                                                                                          |           | None (0)      |           |           | RW   | Txt |    | NC |    | US |
| 11.043    | Load Defaults                                       | None (0), Standard (1), US (2)                                                                                                                                                                                                                               |           | None (0)      |           |           | RW   | Txt |    | NC |    |    |
| 11.044    | User Security Status                                | Menu 0 (0), All Menus (1), Read-only Menu 0 (2), Read-only (3), Status Only (4), No Access (5)                                                                                                                                                               |           | Menu 0 (0)    |           |           | RW   | Txt | ND |    | PT |    |
| 11.045    | Select Motor 2 Parameters                           | Motor 1 (0) or Motor 2 (1)                                                                                                                                                                                                                                   |           | Motor 1 (0)   |           |           | RW   | Txt |    |    |    | US |
| 11.046    | Defaults Previously Loaded                          | 0 to 2000                                                                                                                                                                                                                                                    |           |               |           |           | RO   | Num | ND | NC | PT | US |
| 11.047    | Onboard User Program: Enable                        | Reset And Run (-1), Stop (0), Run (1)                                                                                                                                                                                                                        |           | Run (1)       |           |           | RW   | Txt |    |    |    | US |
| 11.048    | Onboard User Program: Status                        | -2147483648 to 2147483647                                                                                                                                                                                                                                    |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.049    | Onboard User Program: Programming Events            | 0 to 65535                                                                                                                                                                                                                                                   |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.050    | Onboard User Program: Freewheeling Tasks Per Second | 0 to 65535                                                                                                                                                                                                                                                   |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.051    | Onboard User Program: Clock Task Time Used          | 0.0 to 100.0 %                                                                                                                                                                                                                                               |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.052    | Serial Number LS                                    | 000000000 to 999999999                                                                                                                                                                                                                                       |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.053    | Serial Number MS                                    | 0 to 999999999                                                                                                                                                                                                                                               |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.054    | Drive Date Code                                     | 0 to 65535                                                                                                                                                                                                                                                   |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.055    | Onboard User Program: Clock Task Scheduled Interval | 0 to 262140 ms                                                                                                                                                                                                                                               |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.056    | Option Slot Identifiers                             | 1234 (0), 1243 (1), 1324 (2), 1342 (3), 1423 (4), 1432 (5), 4123 (6), 3124 (7), 4132 (8), 2134 (9), 3142 (10), 2143 (11), 3412 (12), 4312 (13), 2413 (14), 4213 (15), 2314 (16), 3214 (17), 2341 (18), 2431 (19), 3241 (20), 3421 (21), 4231 (22), 4321 (23) |           | 1234 (0)      |           |           | RW   | Txt |    |    | PT |    |
| 11.060    | Maximum Rated Current                               | 0.000 to 99999.999 A                                                                                                                                                                                                                                         |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.061    | Full Scale Current Kc                               | 0.000 to 99999.999 A                                                                                                                                                                                                                                         |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.062    | Power Board Software Version Number                 | 0.00 to 99.99                                                                                                                                                                                                                                                |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.063    | Product Type                                        | 0 to 255                                                                                                                                                                                                                                                     |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.064    | Product Identifier Characters                       | M700 / M701 / M702                                                                                                                                                                                                                                           |           |               |           |           | RO   | Chr | ND | NC | PT |    |
| 11.065    | Drive Rating And Configuration                      | 00000000 to 99999999                                                                                                                                                                                                                                         |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.066    | Power Stage Identifier                              | 0 to 255                                                                                                                                                                                                                                                     |           |               |           |           | RO   | Num | ND | NC | PT |    |
| 11.067    | Control Board Identifier                            | 0.000 to 65.535                                                                                                                                                                                                                                              |           |               |           |           | RO   | Num | ND | NC | PT |    |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                        | Range(↕)                                                |           | Default(⇄) |       |       | Type |     |    |    |    |    |
|-----------|----------------------------------------|---------------------------------------------------------|-----------|------------|-------|-------|------|-----|----|----|----|----|
|           |                                        | OL                                                      | RFC-A / S | OL         | RFC-A | RFC-S |      |     |    |    |    |    |
| 11.068    | Internal I/O Identifier                | 0 to 255                                                |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 11.069    | Position Feedback Interface Identifier | 0 to 255                                                |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 11.070    | Core Parameter Database Version        | 0.00 to 99.99                                           |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 11.071    | Number Of Power Modules Detected       | 0 to 20                                                 |           |            |       |       | RO   | Num | ND | NC | PT | US |
| 11.072    | NV Media Card Create Special File      | 0 to 1                                                  |           | 0          |       |       | RW   | Num |    | NC |    |    |
| 11.073    | NV Media Card Type                     | None (0), SMART Card (1), SD Card (2)                   |           |            |       |       | RO   | Txt | ND | NC | PT |    |
| 11.075    | NV Media Card Read-only Flag           | Off (0) or On (1)                                       |           |            |       |       | RO   | Bit | ND | NC | PT |    |
| 11.076    | NV Media Card Warning Suppression Flag | Off (0) or On (1)                                       |           |            |       |       | RO   | Bit | ND | NC | PT |    |
| 11.077    | NV Media Card File Required Version    | 0 to 9999                                               |           | 0          |       |       | RW   | Num | ND | NC | PT |    |
| 11.079    | Drive Name Characters 1-4              | ---- (-2147483648) to --- (2147483647)                  |           | ---- (0)   |       |       | RW   | Chr |    |    | PT | US |
| 11.080    | Drive Name Characters 5-8              | ---- (-2147483648) to --- (2147483647)                  |           | ---- (0)   |       |       | RW   | Chr |    |    | PT | US |
| 11.081    | Drive Name Characters 9-12             | ---- (-2147483648) to --- (2147483647)                  |           | ---- (0)   |       |       | RW   | Chr |    |    | PT | US |
| 11.082    | Drive Name Characters 13-16            | ---- (-2147483648) to --- (2147483647)                  |           | ---- (0)   |       |       | RW   | Chr |    |    | PT | US |
| 11.084    | Drive Mode                             | Open-loop (1), RFC-A (2), RFC-S (3), Regen (4)          |           |            |       |       | RO   | Txt | ND | NC | PT | US |
| 11.085    | Security Status                        | None (0), Read-only (1), Status-only (2), No Access (3) |           |            |       |       | RO   | Txt | ND | NC | PT | PS |
| 11.086    | Menu Access Status                     | Menu 0 (0) or All Menus (1)                             |           |            |       |       | RO   | Txt | ND | NC | PT | PS |
| 11.090    | Keypad Port Serial Address             | 1 to 16                                                 |           | 1          |       |       | RW   | Num |    |    |    | US |
| 11.091    | Additional Identifier Characters 1     | ---- (-2147483648) to --- (2147483647)                  |           |            |       |       | RO   | Chr | ND | NC | PT |    |
| 11.092    | Additional Identifier Characters 2     | ---- (-2147483648) to --- (2147483647)                  |           |            |       |       | RO   | Chr | ND | NC | PT |    |
| 11.093    | Additional Identifier Characters 3     | ---- (-2147483648) to --- (2147483647)                  |           |            |       |       | RO   | Chr | ND | NC | PT |    |
| 11.095    | Number Of Rectifiers Detected          | 0 to 9                                                  |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 11.096    | Number Of Rectifiers Expected          | 0 to 9                                                  |           | 0          |       |       | RW   | Num |    |    |    | US |

\* On Unidrive M701 only.

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

12.13 Menu 12: Threshold detectors, variable selectors and brake control function

Figure 12-29 Menu 12 logic diagram

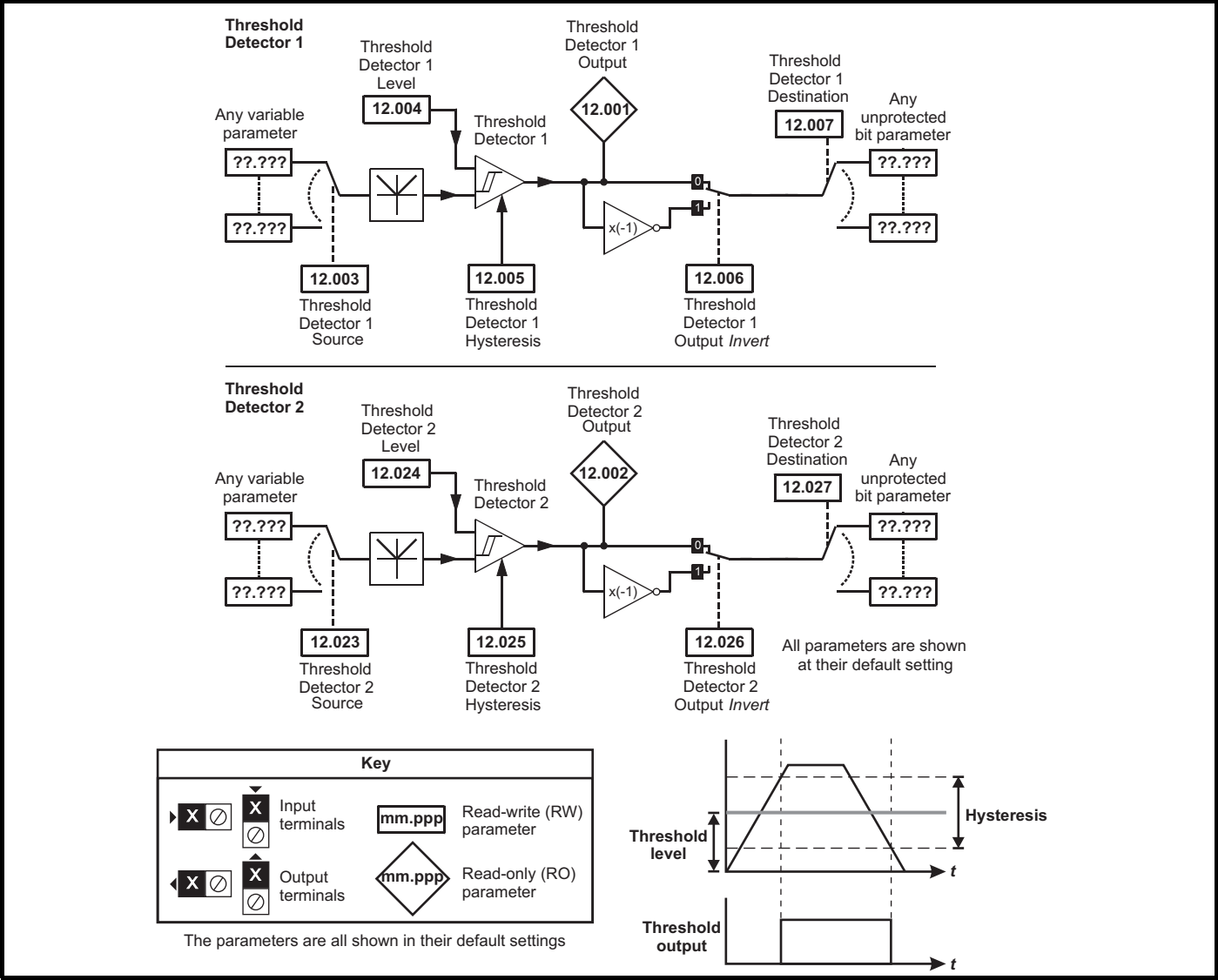
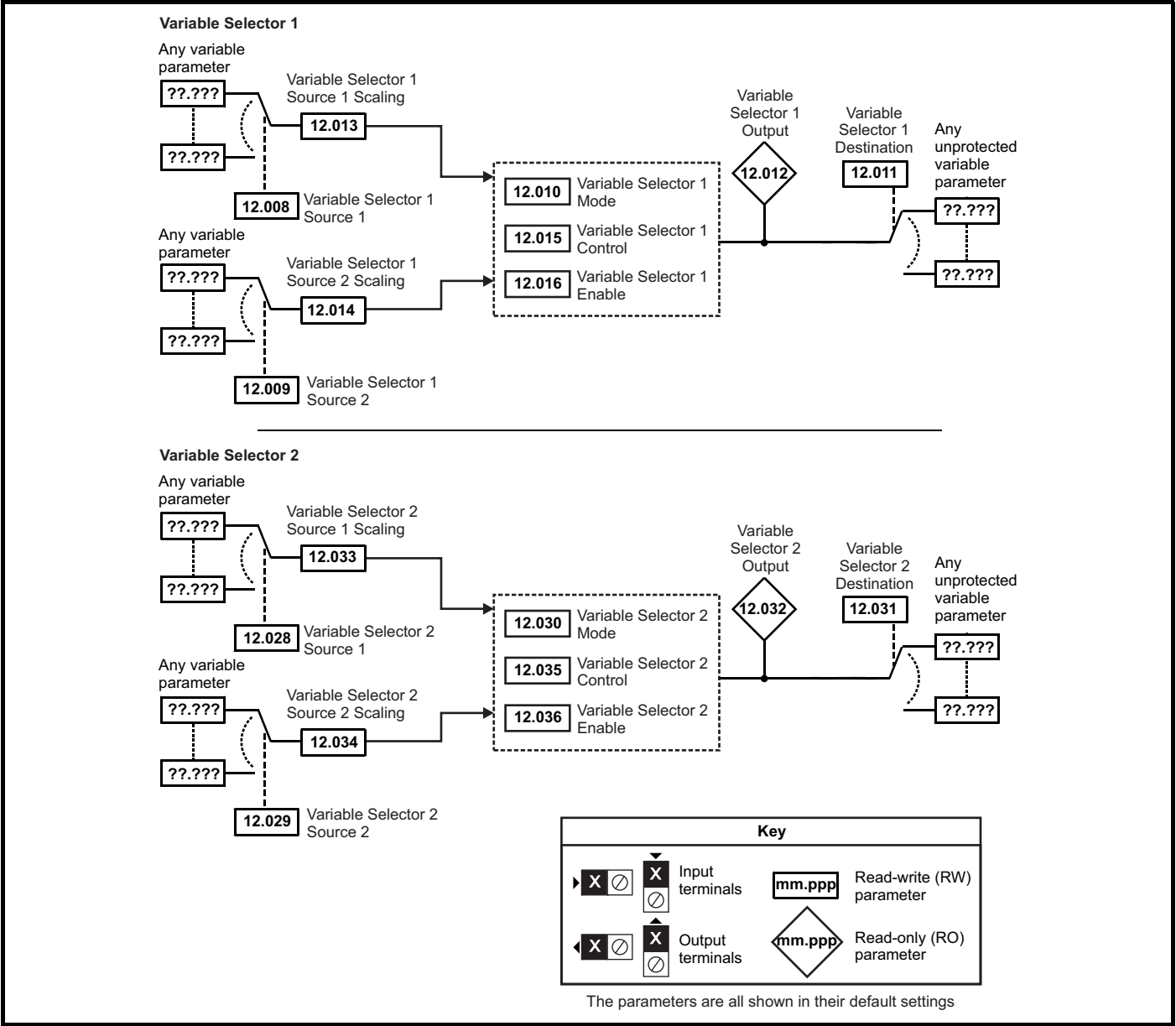


Figure 12-30 Menu 12 logic diagram (continued)





The brake control functions are provided to allow well co-ordinated operation of an external brake with the drive. While both hardware and software are designed to high standards of quality and robustness, they are not intended for use as safety functions, i.e. where a fault or failure would result in a risk of injury. In any application where the incorrect operation of the brake release mechanism could result in injury, independent protection devices of proven integrity must also be incorporated.



The control terminal relay can be selected as an output to release a brake. If a drive is set up in this manner and a drive replacement takes place, prior to programming the drive on initial power up, the brake may be released. When drive terminals are programmed to non default settings the result of incorrect or delayed programming must be considered. The use of a NV media card in boot mode or an SI-Applications module can ensure drive parameters are immediately programmed to avoid this situation.

**Figure 12-31 Open-loop brake function**

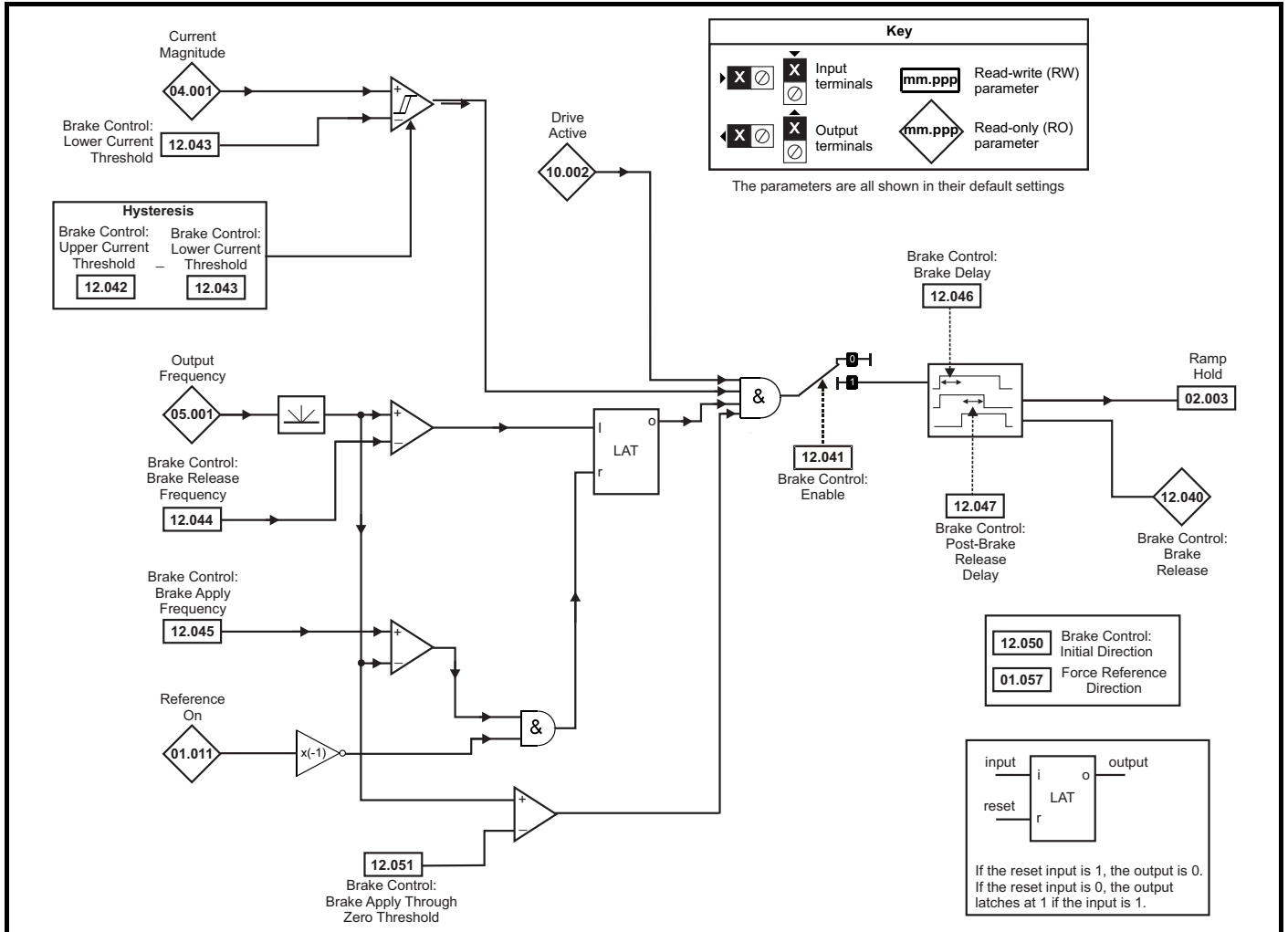
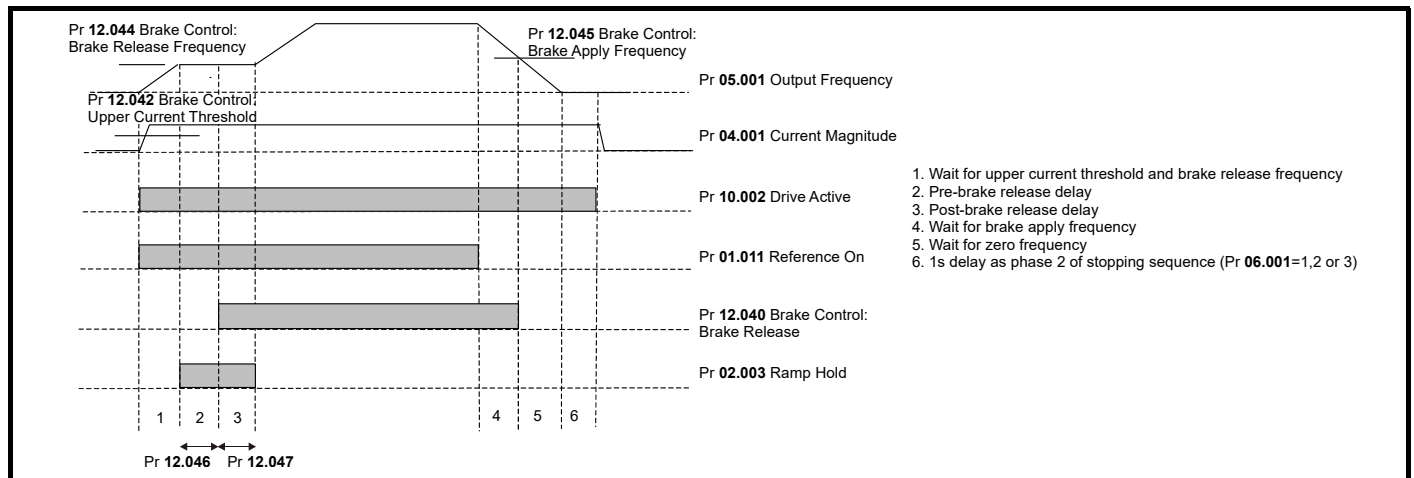


**Figure 12-32 Open-loop brake sequence**



The brake control functions are provided to allow well co-ordinated operation of an external brake with the drive. While both hardware and software are designed to high standards of quality and robustness, they are not intended for use as safety functions, i.e. where a fault or failure would result in a risk of injury. In any application where the incorrect operation of the brake release mechanism could result in injury, independent protection devices of proven integrity must also be incorporated.



The control terminal relay can be selected as an output to release a brake. If a drive is set up in this manner and a drive replacement takes place, prior to programming the drive on initial power up, the brake may be released. When drive terminals are programmed to non default settings the result of incorrect or delayed programming must be considered. The use of a NV media card in boot mode or an SI-Applications module can ensure drive parameters are immediately programmed to avoid this situation.

**Figure 12-33 RFC-A mode with brake controller mode (12.052) =0 (RFC-A with position feedback mode)**

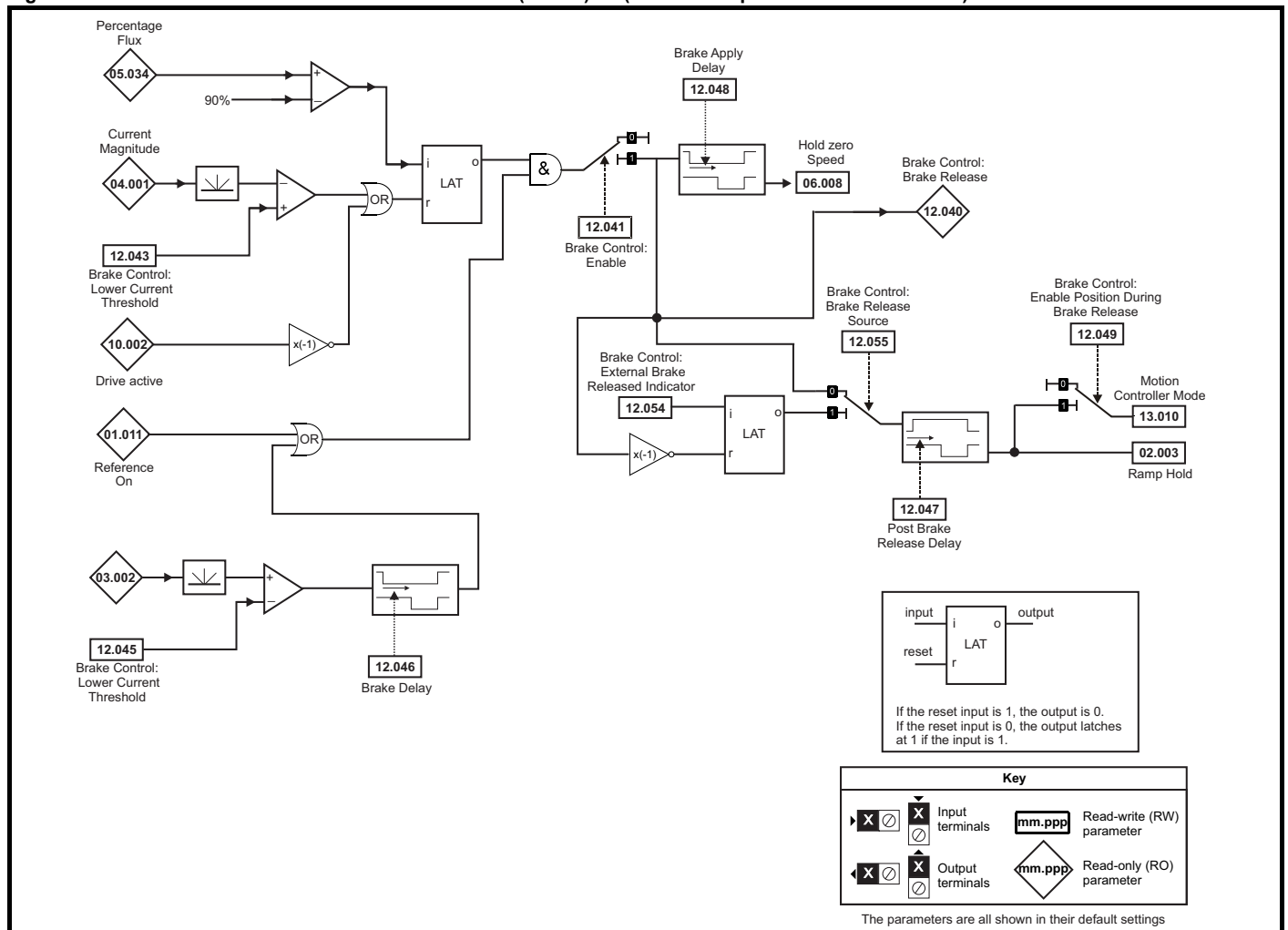
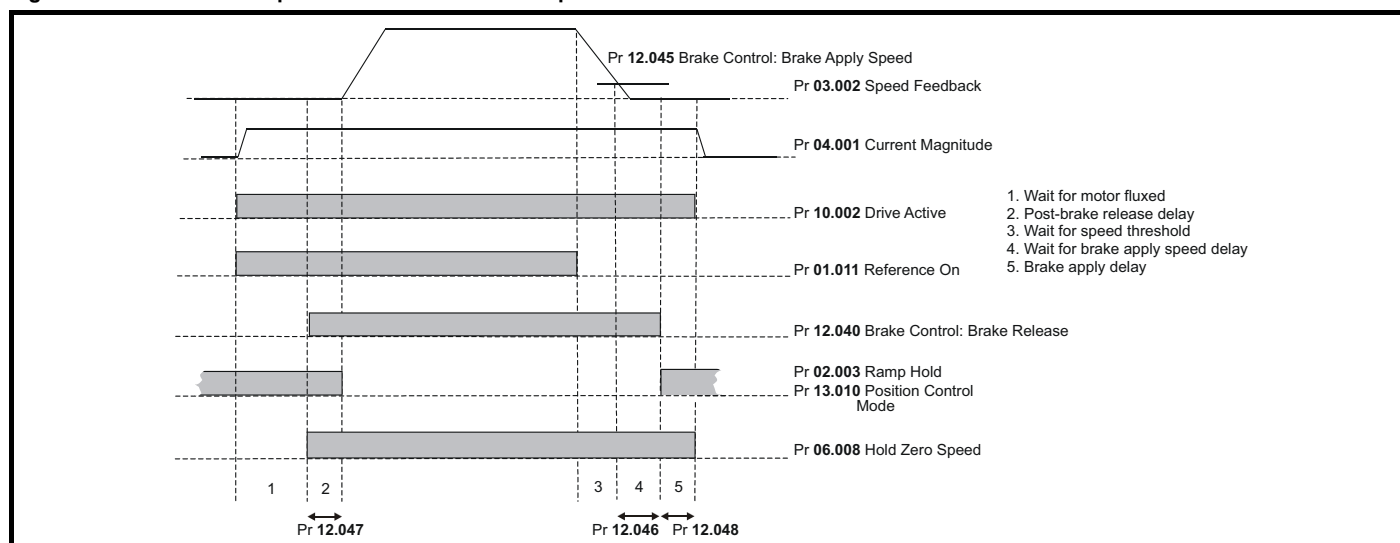


**Figure 12-34 RFC-A with position feedback brake sequence**

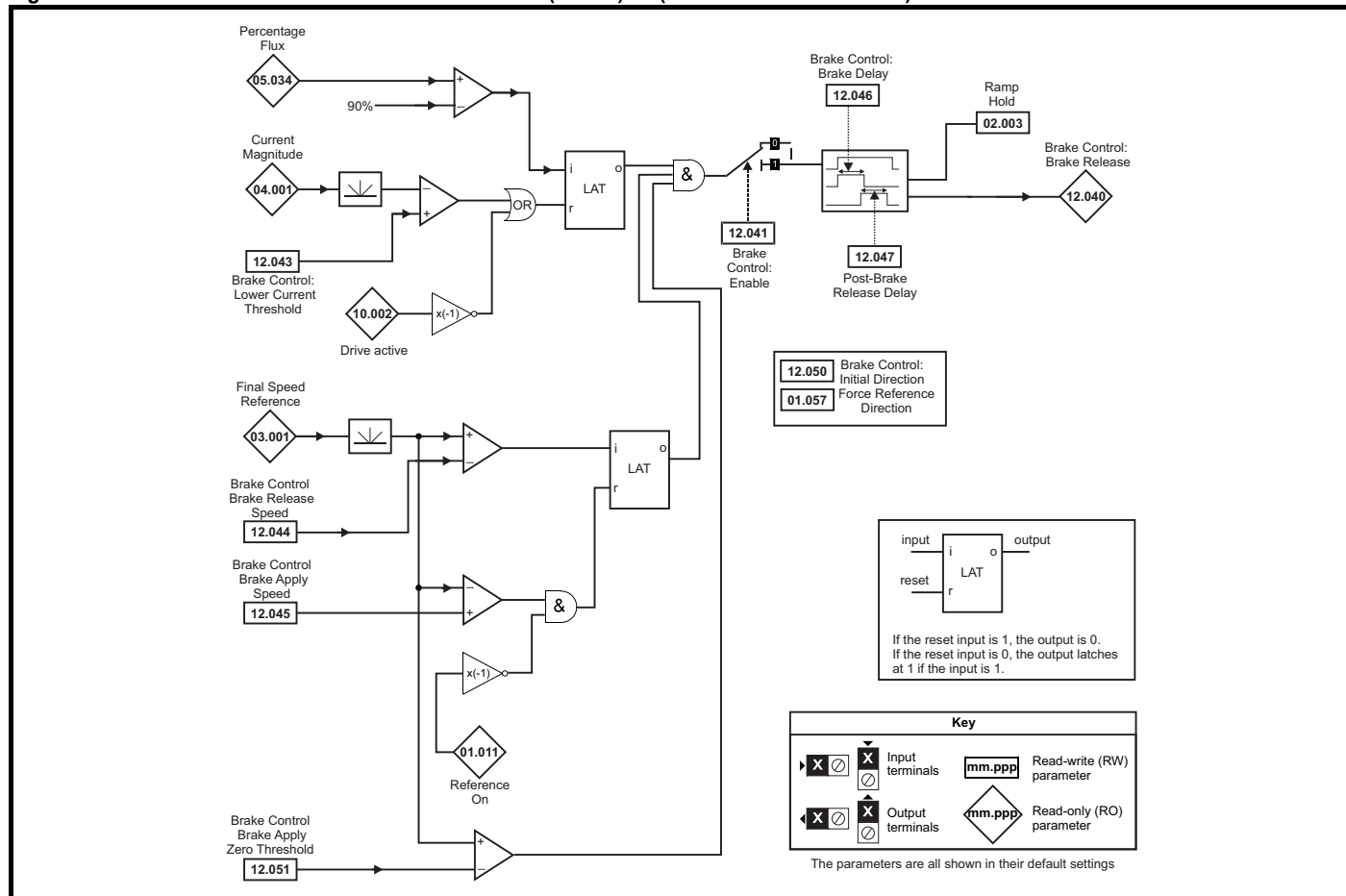


The brake control functions are provided to allow well co-ordinated operation of an external brake with the drive. While both hardware and software are designed to high standards of quality and robustness, they are not intended for use as safety functions, i.e. where a fault or failure would result in a risk of injury. In any application where the incorrect operation of the brake release mechanism could result in injury, independent protection devices of proven integrity must also be incorporated.



The control terminal relay can be selected as an output to release a brake. If a drive is set up in this manner and a drive replacement takes place, prior to programming the drive on initial power up, the brake may be released. When drive terminals are programmed to non default settings the result of incorrect or delayed programming must be considered. The use of a NV media card in boot mode or an SI-Applications module can ensure drive parameters are immediately programmed to avoid this situation.

**Figure 12-35 RFC-A mode with brake controller mode (12.052) =1 (RFC-A Sensorless mode)**



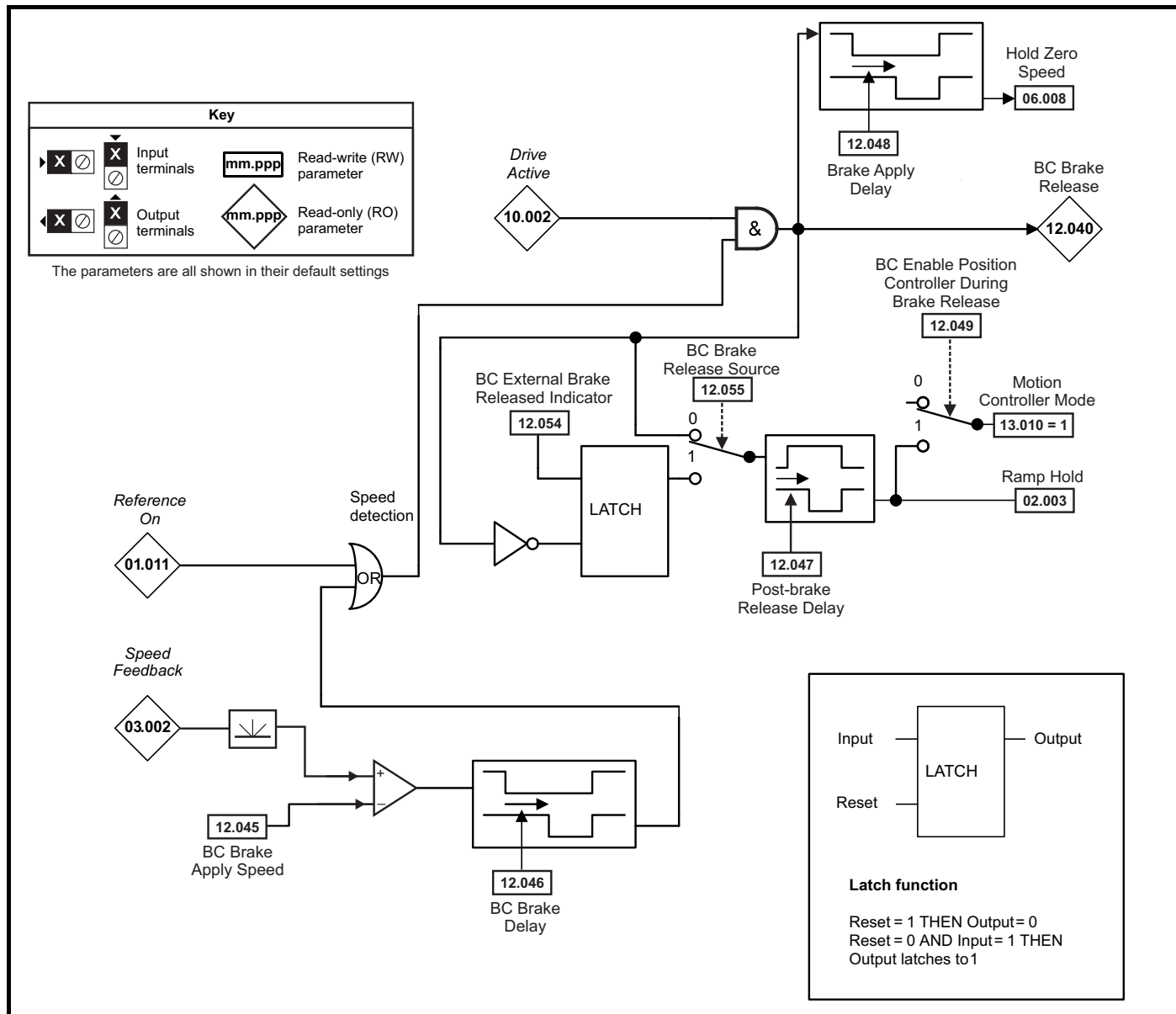


The brake control functions are provided to allow well co-ordinated operation of an external brake with the drive. While both hardware and software are designed to high standards of quality and robustness, they are not intended for use as safety functions, i.e. where a fault or failure would result in a risk of injury. In any application where the incorrect operation of the brake release mechanism could result in injury, independent protection devices of proven integrity must also be incorporated.



The control terminal relay can be selected as an output to release a brake. If a drive is set up in this manner and a drive replacement takes place, prior to programming the drive on initial power up, the brake may be released. When drive terminals are programmed to non default settings the result of incorrect or delayed programming must be considered. The use of a NV media card in boot mode or an SI-Applications module can ensure drive parameters are immediately programmed to avoid this situation.

**Figure 12-36 RFC-S brake function**



|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

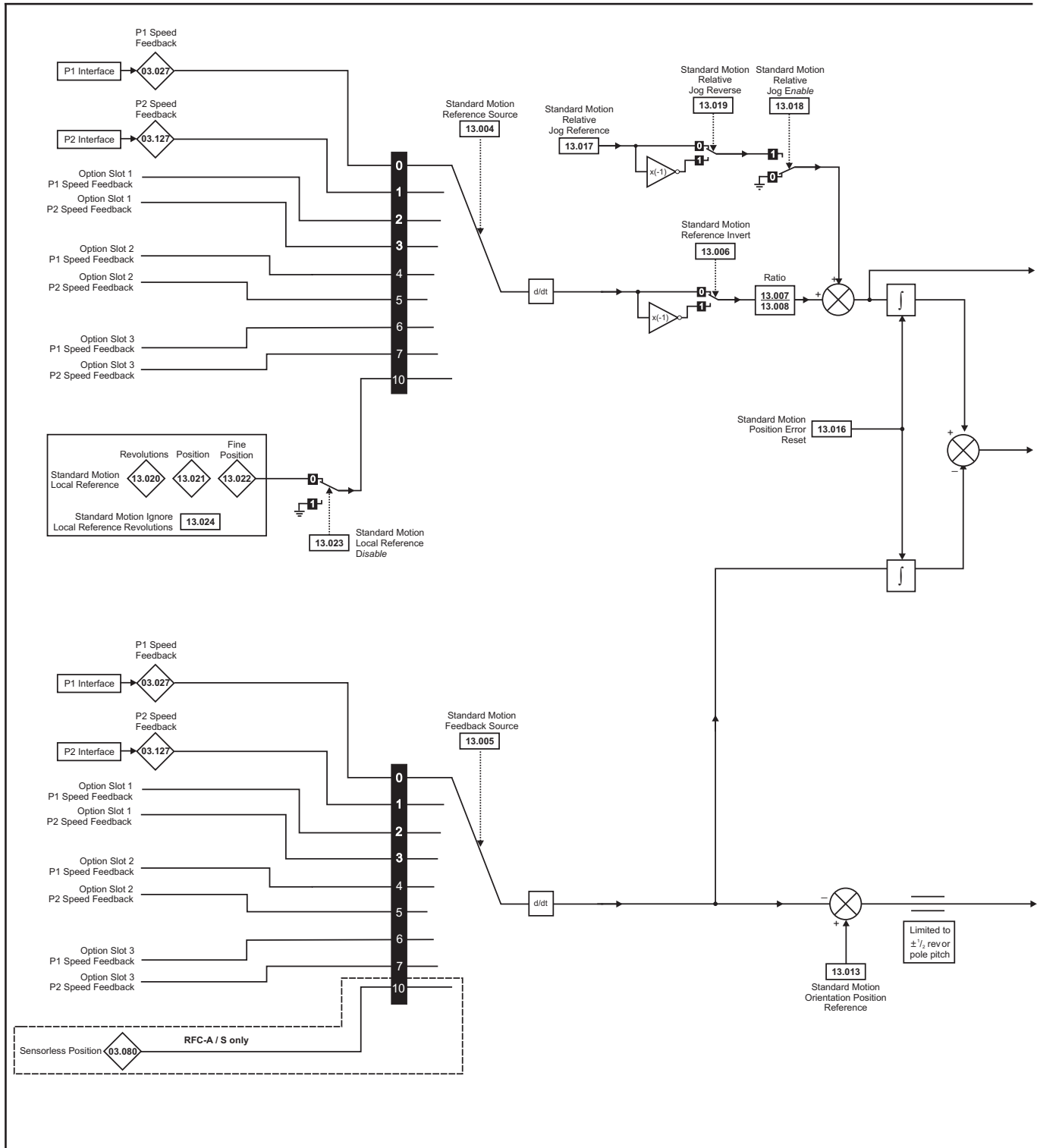
| Parameter |                                                             | Range(⌘)                                                                                                                                     |                   |        | Default(⇔)  |         |       | Type |     |    |    |    |    |
|-----------|-------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------|-------------------|--------|-------------|---------|-------|------|-----|----|----|----|----|
|           |                                                             | OL                                                                                                                                           | RFC- A            | RFC- S | OL          | RFC-A   | RFC-S |      |     |    |    |    |    |
| 12.001    | Threshold Detector 1 Output                                 | Off (0) or On (1)                                                                                                                            |                   |        |             |         |       | RO   | Bit | ND | NC | PT |    |
| 12.002    | Threshold Detector 2 Output                                 | Off (0) or On (1)                                                                                                                            |                   |        |             |         |       | RO   | Bit | ND | NC | PT |    |
| 12.003    | Threshold Detector 1 Source                                 | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num |    |    | PT | US |
| 12.004    | Threshold Detector 1 Level                                  | 0.00 to 100.00 %                                                                                                                             |                   |        | 0.00 %      |         |       | RW   | Num |    |    |    | US |
| 12.005    | Threshold Detector 1 Hysteresis                             | 0.00 to 25.00 %                                                                                                                              |                   |        | 0.00 %      |         |       | RW   | Num |    |    |    | US |
| 12.006    | Threshold Detector 1 Output Invert                          | Off (0) or On (1)                                                                                                                            |                   |        | Off (0)     |         |       | RW   | Bit |    |    |    | US |
| 12.007    | Threshold Detector 1 Destination                            | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num | DE |    | PT | US |
| 12.008    | Variable Selector 1 Source 1                                | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num |    |    | PT | US |
| 12.009    | Variable Selector 1 Source 2                                | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num |    |    | PT | US |
| 12.010    | Variable Selector 1 Mode                                    | Input 1 (0), Input 2 (1), Add (2), Subtract (3), Multiply (4), Divide (5), Time Const (6), Ramp (7), Modulus (8), Powers (9), Sectional (10) |                   |        | Input 1 (0) |         |       | RW   | Txt |    |    |    | US |
| 12.011    | Variable Selector 1 Destination                             | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num | DE |    | PT | US |
| 12.012    | Variable Selector 1 Output                                  | ±100.00 %                                                                                                                                    |                   |        |             |         |       | RO   | Num | ND | NC | PT |    |
| 12.013    | Variable Selector 1 Source 1 Scaling                        | ±4.000                                                                                                                                       |                   |        | 1.000       |         |       | RW   | Num |    |    |    | US |
| 12.014    | Variable Selector 1 Source 2 Scaling                        | ±4.000                                                                                                                                       |                   |        | 1.000       |         |       | RW   | Num |    |    |    | US |
| 12.015    | Variable Selector 1 Control                                 | 0.00 to 100.00                                                                                                                               |                   |        | 0.00        |         |       | RW   | Num |    |    |    | US |
| 12.016    | Variable Selector 1 Enable                                  | Off (0) or On (1)                                                                                                                            |                   |        | On (1)      |         |       | RW   | Bit |    |    |    | US |
| 12.023    | Threshold Detector 2 Source                                 | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num |    |    | PT | US |
| 12.024    | Threshold Detector 2 Level                                  | 0.00 to 100.00 %                                                                                                                             |                   |        | 0.00 %      |         |       | RW   | Num |    |    |    | US |
| 12.025    | Threshold Detector 2 Hysteresis                             | 0.00 to 25.00 %                                                                                                                              |                   |        |             |         |       | RW   | Num |    |    |    | US |
| 12.026    | Threshold Detector 2 Output Invert                          | Off (0) or On (1)                                                                                                                            |                   |        | Off (0)     |         |       | RW   | Bit |    |    |    | US |
| 12.027    | Threshold Detector 2 Destination                            | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num | DE |    | PT | US |
| 12.028    | Variable Selector 2 Source 1                                | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num |    |    | PT | US |
| 12.029    | Variable Selector 2 Source 2                                | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num |    |    | PT | US |
| 12.030    | Variable Selector 2 Mode                                    | Input 1 (0), Input 2 (1), Add (2), Subtract (3), Multiply (4), Divide (5), Time Const (6), Ramp (7), Modulus (8), Powers (9), Sectional (10) |                   |        | Input 1 (0) |         |       | RW   | Txt |    |    |    | US |
| 12.031    | Variable Selector 2 Destination                             | 0.000 to 59.999                                                                                                                              |                   |        | 0.000       |         |       | RW   | Num | DE |    | PT | US |
| 12.032    | Variable Selector 2 Output                                  | ±100.00 %                                                                                                                                    |                   |        |             |         |       | RO   | Num | ND | NC | PT |    |
| 12.033    | Variable Selector 2 Source 1 Scaling                        | ±4.000                                                                                                                                       |                   |        | 1.000       |         |       | RW   | Num |    |    |    | US |
| 12.034    | Variable Selector 2 Source 2 Scaling                        | ±4.000                                                                                                                                       |                   |        | 1.000       |         |       | RW   | Num |    |    |    | US |
| 12.035    | Variable Selector 2 Control                                 | 0.00 to 100.00                                                                                                                               |                   |        | 0.00        |         |       | RW   | Num |    |    |    | US |
| 12.036    | Variable Selector 2 Enable                                  | Off (0) or On (1)                                                                                                                            |                   |        | On (1)      |         |       | RW   | Bit |    |    |    | US |
| 12.040    | Brake Control: Brake Release                                | Off (0) or On (1)                                                                                                                            |                   |        |             |         |       | RO   | Bit | ND | NC | PT |    |
| 12.041    | Brake Control: Enable                                       | Off (0) or On (1)                                                                                                                            |                   |        | Off (0)     |         |       | RW   | Bit |    |    |    | US |
| 12.042    | Brake Control: Upper Current Threshold                      | 0 to 200 %                                                                                                                                   |                   |        | 50 %        |         |       | RW   | Num |    |    |    | US |
| 12.043    | Brake Control: Lower Current Threshold                      | 0 to 200 %                                                                                                                                   |                   |        | 10 %        |         |       | RW   | Num |    |    |    | US |
| 12.044    | Brake Control: Brake Release Frequency                      | 0.0 to 20.0 Hz                                                                                                                               |                   |        | 1.0 Hz      |         |       | RW   | Num |    |    |    | US |
|           | Brake Control: Brake Release Speed                          |                                                                                                                                              | 0 to 200 rpm      |        |             | 10 rpm  |       | RW   | Num |    |    |    | US |
| 12.045    | Brake Control: Brake Apply Frequency                        | 0.0 to 20.0 Hz                                                                                                                               |                   |        | 2.0 Hz      |         |       | RW   | Num |    |    |    | US |
|           | Brake Control: Brake Apply Speed                            |                                                                                                                                              | 0 to 200 rpm      |        |             | 5 rpm   |       | RW   | Num |    |    |    | US |
| 12.046    | Brake Control: Brake Delay                                  | 0.0 to 25.0 s                                                                                                                                |                   |        | 1.0 s       |         |       | RW   | Num |    |    |    | US |
| 12.047    | Brake Control: Post-brake Release Delay                     | 0.0 to 25.0 s                                                                                                                                |                   |        | 1.0 s       |         |       | RW   | Num |    |    |    | US |
| 12.048    | Brake Control: Brake Apply Delay                            |                                                                                                                                              | 0.0 to 25.0 s     |        |             | 1.0 s   |       | RW   | Num |    |    |    | US |
| 12.049    | Brake Control: Enable Position Control During Brake Release |                                                                                                                                              | Off (0) or On (1) |        |             | Off (0) |       | RW   | Bit |    |    |    | US |
| 12.050    | Brake Control: Initial Direction                            | Ref (0), Forward (1), Reverse (2)                                                                                                            |                   |        | Ref (0)     |         |       | RW   | Txt |    |    |    | US |
| 12.051    | Brake Control: Brake Apply Through Zero Threshold           | 0.0 to 20.0 Hz                                                                                                                               | 0 to 200 rpm      |        | 1.0 Hz      | 5 rpm   |       | RW   | Num |    |    |    | US |
| 12.052    | Brake Control: Mode                                         |                                                                                                                                              | Off (0) or On (1) |        |             | Off (0) |       | RW   | Bit |    |    |    | US |
| 12.054    | External Brake Released Indicator                           |                                                                                                                                              | Off (0) or On (1) |        |             | Off (0) |       | RW   | Bit |    |    |    |    |
| 12.055    | Brake Release Source                                        |                                                                                                                                              | Off (0) or On (1) |        |             | Off (0) |       | RW   | Bit |    |    |    | US |

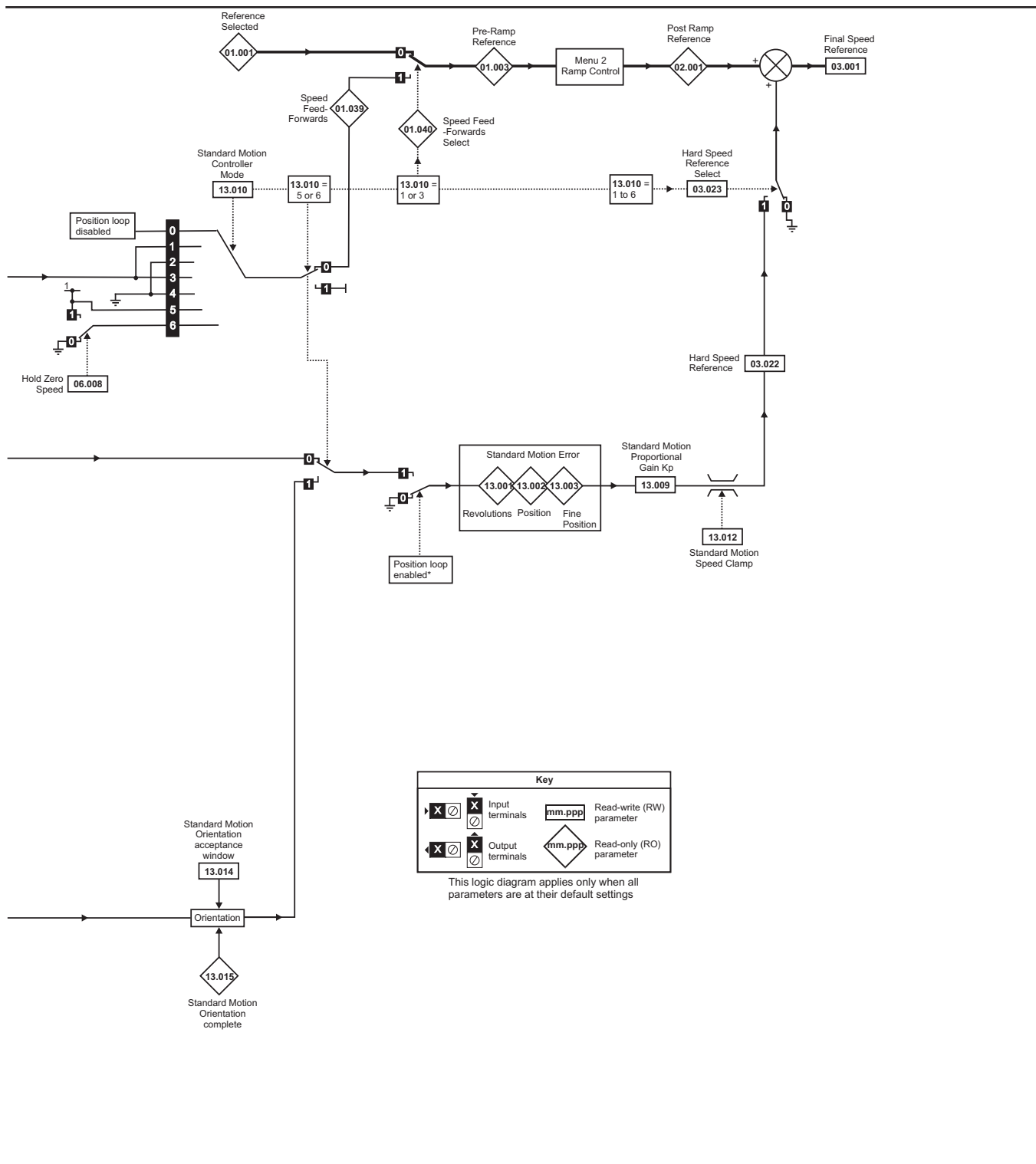
|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 12.14 Menu 13: Standard motion controller

Figure 12-37 Menu 13 logic diagram





\*The position controller is disabled and the error integrator is also reset under the following conditions:

1. If the drive is disabled (i.e. inhibited, ready or tripped)
2. If the position controller mode (Pr 13.010) is changed. The position controller is disabled transiently to reset the error integrator.
3. The absolute mode parameter (Pr 13.011) is changed. The position controller is disabled transiently to reset the error integrator.
4. One of the position sources is invalid.
5. The position feedback initialized parameter (Pr 03.048) is zero.

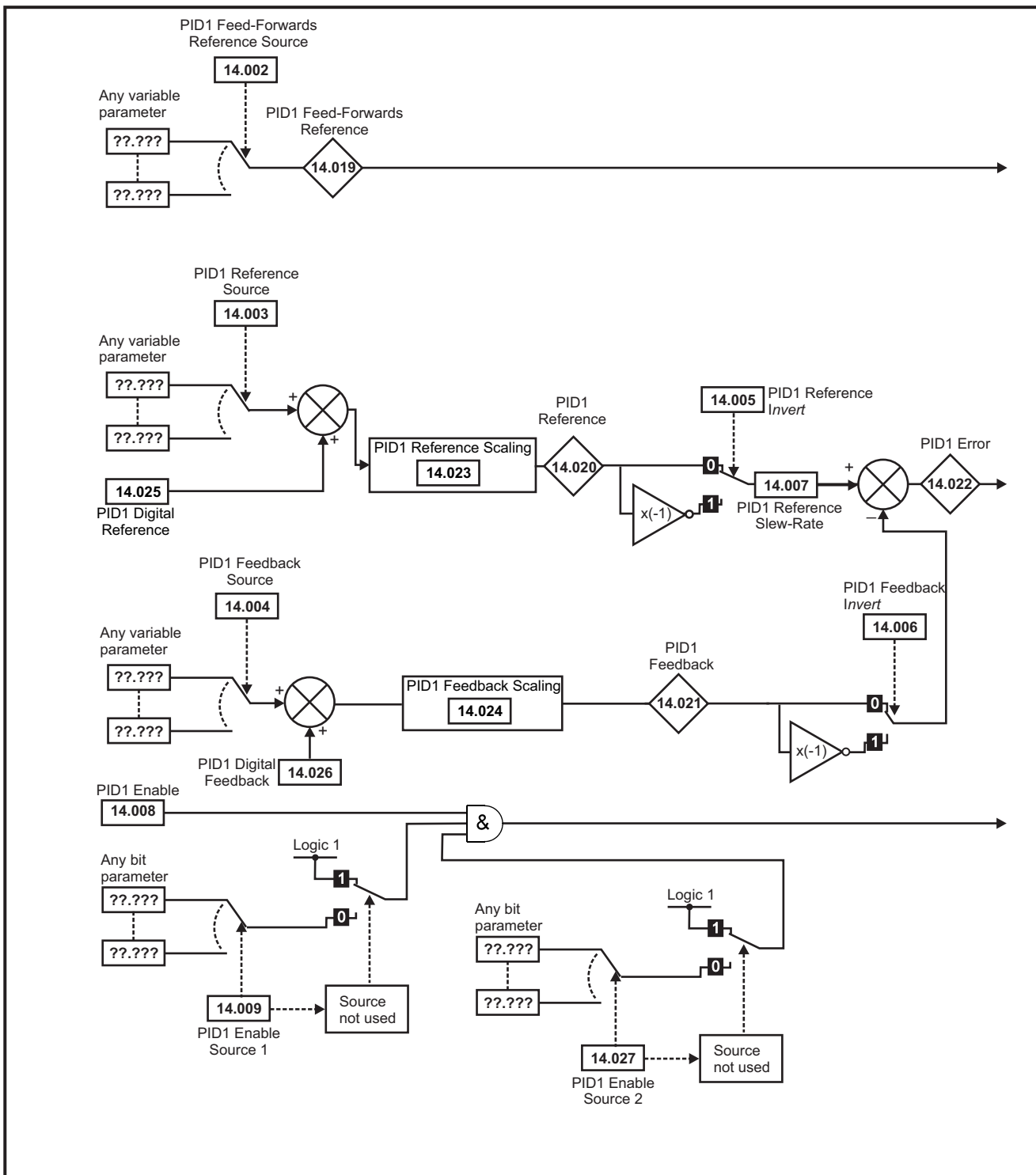
| Parameter |                                                    | Range(⇅)                                                                                                                         |                                                                                                                                       | Default(⇄)   |       |       | Type |     |    |    |    |    |
|-----------|----------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------|--------------|-------|-------|------|-----|----|----|----|----|
|           |                                                    | OL                                                                                                                               | RFC-A / S                                                                                                                             | OL           | RFC-A | RFC-S |      |     |    |    |    |    |
| 13.001    | Standard Motion Revolutions Error                  | -32768 to 32767 revs                                                                                                             |                                                                                                                                       |              |       |       | RO   | Num | ND | NC | PT |    |
| 13.002    | Standard Motion Position Error                     | -32768 to 32767                                                                                                                  |                                                                                                                                       |              |       |       | RO   | Num | ND | NC | PT |    |
| 13.003    | Standard Motion Fine Position Error                | -32768 to 32767                                                                                                                  |                                                                                                                                       |              |       |       | RO   | Num | ND | NC | PT |    |
| 13.004    | Standard Motion Reference Source                   | P1 Drive (0), P2 Drive (1), P1 Slot 1 (2), P2 Slot 1 (3), P1 Slot 2 (4), P2 Slot 2 (5), P1 Slot 3 (6), P2 Slot 3 (7), Local (10) |                                                                                                                                       | P1 Drive (0) |       |       | RW   | Txt |    |    |    | US |
| 13.005    | Standard Motion Feedback Source                    | P1 Drive (0), P2 Drive (1), P1 Slot 1 (2), P2 Slot 1 (3), P1 Slot 2 (4), P2 Slot 2 (5), P1 Slot 3 (6), P2 Slot 3 (7)             | P1 Drive (0), P2 Drive (1), P1 Slot 1 (2), P2 Slot 1 (3), P1 Slot 2 (4), P2 Slot 2 (5), P1 Slot 3 (6), P2 Slot 3 (7), Sensorless (10) | P1 Drive (0) |       |       | RW   | Txt |    |    |    | US |
| 13.006    | Standard Motion Reference Invert                   | Off (0) or On (1)                                                                                                                |                                                                                                                                       | Off (0)      |       |       | RW   | Bit |    |    |    | US |
| 13.007    | Standard Motion Ratio Numerator                    | 0.000 to 10.000                                                                                                                  |                                                                                                                                       | 1.000        |       |       | RW   | Num |    |    |    | US |
| 13.008    | Standard Motion Ratio Denominator                  | 0.000 to 4.000                                                                                                                   |                                                                                                                                       | 1.000        |       |       | RW   | Num |    |    |    | US |
| 13.009    | Standard Motion Proportional Gain Kp               | 0.00 to 100.00                                                                                                                   |                                                                                                                                       | 25.00        |       |       | RW   | Num |    |    |    | US |
| 13.010    | Standard Motion Controller Mode                    | Disabled (0), Rigid Spd FF (1), Rigid (2), Non-rigid Spd FF(3), Non-Rigid (4)                                                    | Disabled (0), Rigid Spd FF (1), Rigid (2), Non-rigid Spd FF (3), Non-Rigid (4), Orientate Stop (5), Orientate (6)                     | Disabled (0) |       |       | RW   | Txt |    |    |    | US |
| 13.011    | Standard Motion Absolute Mode Enable               | Off (0) or On (1)                                                                                                                |                                                                                                                                       | Off (0)      |       |       | RW   | Bit |    |    |    | US |
| 13.012    | Standard Motion Speed Clamp                        | 0 to 250 rpm                                                                                                                     |                                                                                                                                       | 150 rpm      |       |       | RW   | Num |    |    |    | US |
| 13.013    | Standard Motion Orientation Position Reference     | 0 to 65535                                                                                                                       |                                                                                                                                       | 0            |       |       | RW   | Num |    |    |    | US |
| 13.014    | Standard Motion Orientation Acceptance Window      | 0 to 4096                                                                                                                        |                                                                                                                                       | 256          |       |       | RW   | Num |    |    |    | US |
| 13.015    | Standard Motion Orientation Complete               | Off (0) or On (1)                                                                                                                |                                                                                                                                       |              |       |       | RO   | Bit | ND | NC | PT |    |
| 13.016    | Standard Motion Position Error Reset               | Off (0) or On (1)                                                                                                                |                                                                                                                                       | Off (0)      |       |       | RW   | Bit |    | NC |    |    |
| 13.017    | Standard Motion Relative Jog Reference             | 0.0 to 4000.0 rpm                                                                                                                |                                                                                                                                       | 0.0 rpm      |       |       | RW   | Num |    |    |    | US |
| 13.018    | Standard Motion Relative Jog Enable                | Off (0) or On (1)                                                                                                                |                                                                                                                                       | Off (0)      |       |       | RW   | Bit |    | NC |    |    |
| 13.019    | Standard Motion Relative Jog Reverse               | Off (0) or On (1)                                                                                                                |                                                                                                                                       | Off (0)      |       |       | RW   | Bit |    | NC |    |    |
| 13.020    | Standard Motion Local Reference Revolutions        | 0 to 65535 revs                                                                                                                  |                                                                                                                                       | 0 revs       |       |       | RW   | Num |    | NC |    |    |
| 13.021    | Standard Motion Local Reference Position           | 0 to 65535                                                                                                                       |                                                                                                                                       | 0            |       |       | RW   | Num |    | NC |    |    |
| 13.022    | Standard Motion Local Reference Fine Position      | 0 to 65535                                                                                                                       |                                                                                                                                       | 0            |       |       | RW   | Num |    | NC |    |    |
| 13.023    | Standard Motion Local Reference Disable            | Off (0) or On (1)                                                                                                                |                                                                                                                                       | Off (0)      |       |       | RW   | Bit |    | NC |    |    |
| 13.024    | Standard Motion Ignore Local Reference Revolutions | Off (0) or On (1)                                                                                                                |                                                                                                                                       | Off (0)      |       |       | RW   | Bit |    |    |    | US |
| 13.026    | Standard Motion Sample Rate                        | Not Active (0), 4ms (1)                                                                                                          |                                                                                                                                       |              |       |       | RO   | Txt |    |    |    | US |

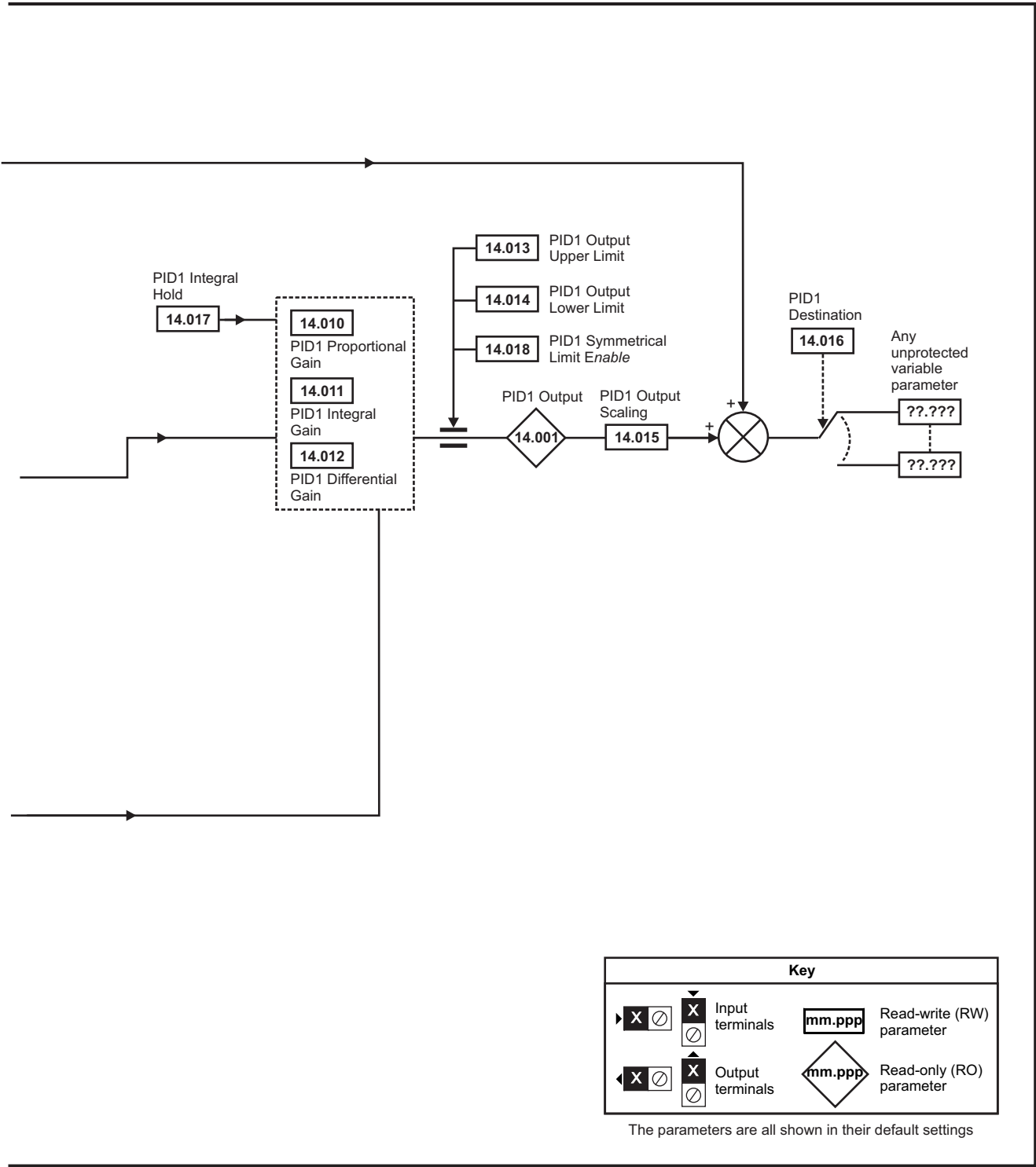
|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |



## 12.15 Menu 14: User PID controller

Figure 12-38 Menu 14 Logic diagram





**NOTE**

The same logic diagram above (Menu 14) can also be used for PID2 as they are the same.

| Parameter |                                     | Range(⌘)          |           | Default(⇆) |       |       | Type |     |    |    |    |    |
|-----------|-------------------------------------|-------------------|-----------|------------|-------|-------|------|-----|----|----|----|----|
|           |                                     | OL                | RFC-A / S | OL         | RFC-A | RFC-S |      |     |    |    |    |    |
| 14.001    | PID1 Output                         | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.002    | PID1 Feed-forwards Reference Source | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.003    | PID1 Reference Source               | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.004    | PID1 Feedback Source                | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.005    | PID1 Reference Invert               | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.006    | PID1 Feedback Invert                | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.007    | PID1 Reference Slew Rate            | 0.0 to 3200.0 s   |           | 0.0 s      |       |       | RW   | Num |    |    |    | US |
| 14.008    | PID1 Enable                         | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.009    | PID1 Enable Source 1                | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.010    | PID1 Proportional Gain              | 0.000 to 4.000    |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.011    | PID1 Integral Gain                  | 0.000 to 4.000    |           | 0.500      |       |       | RW   | Num |    |    |    | US |
| 14.012    | PID1 Differential Gain              | 0.000 to 4.000    |           | 0.000      |       |       | RW   | Num |    |    |    | US |
| 14.013    | PID1 Output Upper Limit             | 0.00 to 100.00 %  |           | 100.00 %   |       |       | RW   | Num |    |    |    | US |
| 14.014    | PID1 Output Lower Limit             | ±100.00 %         |           | -100.00 %  |       |       | RW   | Num |    |    |    | US |
| 14.015    | PID1 Output Scaling                 | 0.000 to 4.000    |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.016    | PID1 Destination                    | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num | DE |    | PT | US |
| 14.017    | PID1 Integral Hold                  | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    |    |
| 14.018    | PID1 Symmetrical Limit Enable       | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.019    | PID1 Feed-forwards Reference        | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.020    | PID1 Reference                      | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.021    | PID1 Feedback                       | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.022    | PID1 Error                          | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.023    | PID1 Reference Scaling              | 0.000 to 4.000    |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.024    | PID1 Feedback Scaling               | 0.000 to 4.000    |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.025    | PID1 Digital Reference              | ±100.00 %         |           | 0.00 %     |       |       | RW   | Num |    |    |    | US |
| 14.026    | PID1 Digital Feedback               | ±100.00 %         |           | 0.00 %     |       |       | RW   | Num |    |    |    | US |
| 14.027    | PID1 Enable Source 2                | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.028    | PID1 Pre-sleep Boost Level          | 0.00 to 100.00 %  |           | 0.00 %     |       |       | RW   | Num |    |    |    | US |
| 14.029    | PID1 Maximum Boost Time             | 0.0 to 250.0 s    |           | 0.0 s      |       |       | RW   | Num |    |    |    | US |
| 14.030    | PID1 Pre-sleep Boost Level Enable   | Off (0) or On (1) |           |            |       |       | RO   | Bit | ND | NC | PT |    |
| 14.031    | PID2 Output                         | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.032    | PID2 Feed-forwards Reference Source | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.033    | PID2 Reference Source               | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.034    | PID2 Feedback Source                | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.035    | PID2 Reference Invert               | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.036    | PID2 Feedback Invert                | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.037    | PID2 Reference Slew Rate Limit      | 0.0 to 3200.0 s   |           | 0.0 s      |       |       | RW   | Num |    |    |    | US |
| 14.038    | PID2 Enable                         | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.039    | PID2 Enable Source 1                | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.040    | PID2 Proportional Gain              | 0.000 to 4.000    |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.041    | PID2 Integral Gain                  | 0.000 to 4.000    |           | 0.500      |       |       | RW   | Num |    |    |    | US |
| 14.042    | PID2 Differential Gain              | 0.000 to 4.000    |           | 0.000      |       |       | RW   | Num |    |    |    | US |
| 14.043    | PID2 Output Upper Limit             | 0.00 to 100.00 %  |           | 100.00 %   |       |       | RW   | Num |    |    |    | US |
| 14.044    | PID2 Output Lower Limit             | ±100.00 %         |           | -100.00 %  |       |       | RW   | Num |    |    |    | US |
| 14.045    | PID2 Output Scaling                 | 0.000 to 4.000    |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.046    | PID2 Destination                    | 0.000 to 59.999   |           | 0.000      |       |       | RW   | Num | DE |    | PT | US |
| 14.047    | PID2 Integral Hold                  | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    |    |
| 14.048    | PID2 Symmetrical Limit Enable       | Off (0) or On (1) |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.049    | PID2 Feed-forwards Reference        | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.050    | PID2 Reference                      | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.051    | PID2 Feedback                       | ±100.00 %         |           |            |       |       | RO   | Num | ND | NC | PT |    |

| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

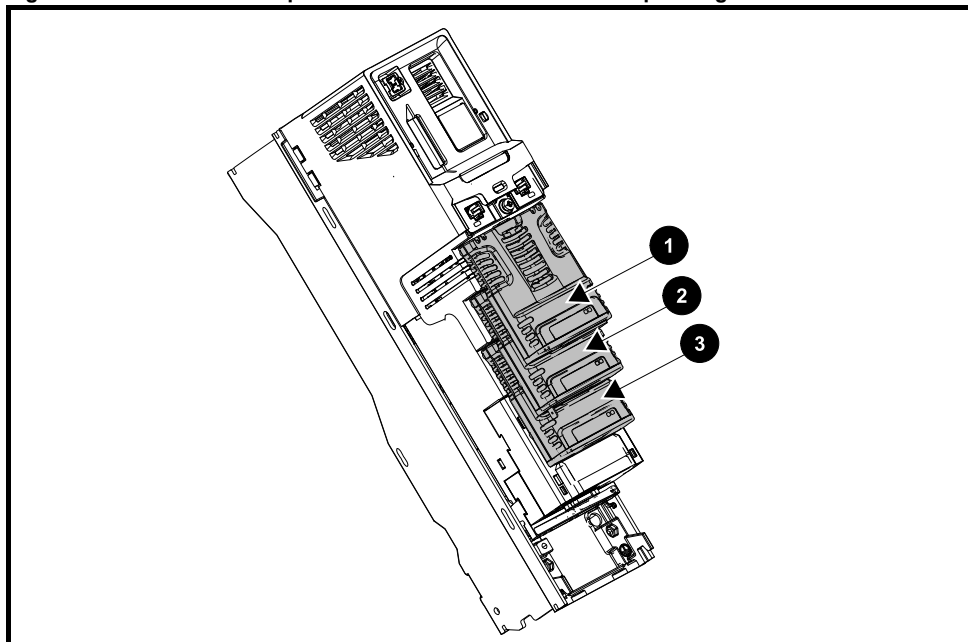
| Parameter |                                    | Range(↕)                                                                                                |           | Default(↔) |       |       | Type |     |    |    |    |    |
|-----------|------------------------------------|---------------------------------------------------------------------------------------------------------|-----------|------------|-------|-------|------|-----|----|----|----|----|
|           |                                    | OL                                                                                                      | RFC-A / S | OL         | RFC-A | RFC-S |      |     |    |    |    |    |
| 14.052    | PID2 Error                         | ±100.00 %                                                                                               |           |            |       |       | RO   | Num | ND | NC | PT |    |
| 14.053    | PID2 Reference Scaling             | 0.000 to 4.000                                                                                          |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.054    | PID2 Feedback Scaling              | 0.000 to 4.000                                                                                          |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.055    | PID2 Digital Reference             | ±100.00 %                                                                                               |           | 0.00 %     |       |       | RW   | Num |    |    |    | US |
| 14.056    | PID2 Digital Feedback              | ±100.00 %                                                                                               |           | 0.00 %     |       |       | RW   | Num |    |    |    | US |
| 14.057    | PID2 Enable Source 2               | 0.000 to 59.999                                                                                         |           | 0.000      |       |       | RW   | Num |    |    | PT | US |
| 14.058    | PID1 Feedback Output Scaling       | 0.000 to 4.000                                                                                          |           | 1.000      |       |       | RW   | Num |    |    |    | US |
| 14.059    | PID1 Mode Selector                 | Fbk1 (0), Fbk2 (1), Fbk1 + Fbk2 (2), Min Fbk (3), Max Fbk (4), Av Fbk (5), Min Error (6), Max Error (7) |           | Fbk1 (0)   |       |       | RW   | Txt |    |    |    | US |
| 14.060    | PID1 Feedback Square Root Enable 1 | Off (0) or On (1)                                                                                       |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.061    | PID2 Feedback Square Root Enable   | Off (0) or On (1)                                                                                       |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |
| 14.062    | PID1 Feedback Square Root Enable 2 | Off (0) or On (1)                                                                                       |           | Off (0)    |       |       | RW   | Bit |    |    |    | US |

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

## 12.16 Menus 15, 16 and 17: Option module set-up

Figure 12-39 Location of option module slots and their corresponding menu numbers



1. Solutions Module Slot 1 - Menu 15
2. Solutions Module Slot 2 - Menu 16
3. Solutions Module Slot 3 - Menu 17

### 12.16.1 Parameters common to all categories

| Parameter                      | Range(⇅)                      | Default(⇒) | Type            |
|--------------------------------|-------------------------------|------------|-----------------|
| <b>mm.001</b> Module ID        | 0 to 65535                    |            | RO Num ND NC PT |
| <b>mm.002</b> Software Version | 00.00.00.00 to 99.99.99.99    |            | RO Ver ND NC PT |
| <b>mm.003</b> Hardware Version | 0.00 to 99.99                 |            | RO Num ND NC PT |
| <b>mm.004</b> Serial Number LS | 0 to 99999999                 |            | RO Num ND NC PT |
| <b>mm.005</b> Serial Number MS |                               |            | RO Num ND NC PT |
| <b>mm.006</b> Module Status    | Initialising (0) to Error (3) |            | RO Txt ND NC PT |
| <b>mm.007</b> Module Reset     | Off (0) or On (1)             | Off (0)    | RW Bit NC       |

The option module ID indicates the type of module that is installed in the corresponding slot. See the relevant option module user guide for more information regarding the module.

| Option module ID | Module               | Category                   |
|------------------|----------------------|----------------------------|
| 0                | No module installed  |                            |
| 0*               | SI-Safety            | Safety                     |
| 105              | SI-Encoder           | Feedback                   |
| 106              | SI-Universal Encoder |                            |
| 209              | SI-I/O               | Automation (I/O Expansion) |
| 304              | SI-Applications Plus | Automation (Applications)  |
| 310              | MCi210               |                            |
| 311              | MCi200               |                            |
| 431              | SI-EtherCAT          | Fieldbus                   |
| 432              | SI-PROFINET RT       |                            |
| 433              | SI-Ethernet          |                            |
| 434              | SI-PROFINET V2       |                            |
| 443              | SI-PROFIBUS          |                            |
| 447              | SI-DeviceNet         |                            |
| 448              | SI-CANopen           |                            |

\* There is no communication between the SI-Safety option module and the host drive via the option module connector, this is why the SI-Safety module ID is displayed as zero.

## 12.17 Menu 18: Application menu 1

| Parameter        |                                                 | Range(⌘)                  |           | Default(⇌) |       |       | Type |     |    |    |    |
|------------------|-------------------------------------------------|---------------------------|-----------|------------|-------|-------|------|-----|----|----|----|
|                  |                                                 | OL                        | RFC-A / S | OL         | RFC-A | RFC-S |      |     |    |    |    |
| 18.001           | Application Menu 1 Power-down Save Integer      | -32768 to 32767           |           | 0          |       |       | RW   | Num |    |    | PS |
| 18.002 to 18.010 | Application Menu 1 Read-only Integer            | -32768 to 32767           |           |            |       |       | RO   | Num | ND | NC | US |
| 18.011 to 18.030 | Application Menu 1 Read-write Integer           | -32768 to 32767           |           | 0          |       |       | RW   | Num |    |    | US |
| 18.031 to 18.050 | Application Menu 1 Read-write bit               | Off (0) or On (1)         |           | Off (0)    |       |       | RW   | Bit |    |    | US |
| 18.051 to 18.054 | Application Menu 1 Power-down Save long Integer | -2147483648 to 2147483647 |           | 0          |       |       | RW   | Num |    |    | PS |

## 12.18 Menu 19: Application menu 2

| Parameter        |                                                 | Range(⌘)                  |           | Default(⇌) |       |       | Type |     |    |    |    |
|------------------|-------------------------------------------------|---------------------------|-----------|------------|-------|-------|------|-----|----|----|----|
|                  |                                                 | OL                        | RFC-A / S | OL         | RFC-A | RFC-S |      |     |    |    |    |
| 19.001           | Application Menu 2 Power-down Save Integer      | -32768 to 32767           |           | 0          |       |       | RW   | Num |    |    | PS |
| 19.002 to 19.010 | Application Menu 2 Read-only Integer            | -32768 to 32767           |           |            |       |       | RO   | Num | ND | NC | US |
| 19.011 to 19.030 | Application Menu 2 Read-write Integer           | -32768 to 32767           |           | 0          |       |       | RW   | Num |    |    | US |
| 19.031 to 19.050 | Application Menu 2 Read-write bit               | Off (0) or On (1)         |           | Off (0)    |       |       | RW   | Bit |    |    | US |
| 19.051 to 19.054 | Application Menu 2 Power-down Save long Integer | -2147483648 to 2147483647 |           | 0          |       |       | RW   | Num |    |    | PS |

## 12.19 Menu 20: Application menu 3

| Parameter        |                                            | Range(⌘)                  |           | Default(⇌) |       |       | Type |     |  |  |  |
|------------------|--------------------------------------------|---------------------------|-----------|------------|-------|-------|------|-----|--|--|--|
|                  |                                            | OL                        | RFC-A / S | OL         | RFC-A | RFC-S |      |     |  |  |  |
| 20.001 to 20.020 | Application Menu 3 Read-write Integer      | -32768 to 32767           |           | 0          |       |       | RW   | Num |  |  |  |
| 20.021 to 20.040 | Application Menu 3 Read-write Long Integer | -2147483648 to 2147483647 |           | 0          |       |       | RW   | Num |  |  |  |

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

## 12.20 Menu 21: Second motor parameters

| Parameter |                                                    | Range(⌘)                                                                                       |                                                                                                                      |                     | Default(⇒)                                                                                                      |                                          |                          | Type |     |    |    |    |    |
|-----------|----------------------------------------------------|------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------|---------------------|-----------------------------------------------------------------------------------------------------------------|------------------------------------------|--------------------------|------|-----|----|----|----|----|
|           |                                                    | OL                                                                                             | RFC-A                                                                                                                | RFC-S               | OL                                                                                                              | RFC-A                                    | RFC-S                    |      |     |    |    |    |    |
| 21.001    | M2 Maximum Reference Clamp                         | VM_POSITIVE_REF_CLAMP2 Hz                                                                      | VM_POSITIVE_REF_CLAMP2 rpm                                                                                           |                     | 50 Hz: 50.0<br>60 Hz: 60.0                                                                                      | 50 Hz: 1500.0<br>60 Hz: 1800.0           | 3000.0                   | RW   | Num |    |    |    | US |
| 21.002    | M2 Minimum Reference Clamp                         | VM_NEGATIVE_REF_CLAMP2 Hz                                                                      | VM_NEGATIVE_REF_CLAMP2 rpm                                                                                           |                     | 0.0                                                                                                             |                                          |                          | RW   | Num |    |    |    | US |
| 21.003    | M2 Reference Selector                              | A1 A2 (0), A1 Preset (1), A2 Preset (2), Preset (3), Keypad (4), Precision (5), Keypad Ref (6) |                                                                                                                      |                     | A1 A2 (0)                                                                                                       |                                          |                          | RW   | Txt |    |    |    | US |
| 21.004    | M2 Acceleration Rate 1                             | 0.0 to VM_ACCEL_RATE s/100 Hz                                                                  | 0.000 to VM_ACCEL_RATE s/100 rpm                                                                                     |                     | 5.0 s                                                                                                           | 2.000 s                                  | 0.200 s                  | RW   | Num |    |    |    | US |
| 21.005    | M2 Deceleration Rate 1                             | 0.0 to VM_ACCEL_RATE s/100 Hz                                                                  | 0.000 to VM_ACCEL_RATE s/100 rpm                                                                                     |                     | 10.0 s                                                                                                          | 2.000 s                                  | 0.200 s                  | RW   | Num |    |    |    | US |
| 21.006    | M2 Rated Frequency                                 | 0.0 to 599.0 Hz                                                                                | 0.0 to 550.0 Hz                                                                                                      |                     | 50Hz: 50.0 Hz<br>60Hz: 60.0 Hz                                                                                  |                                          |                          | RW   | Num |    |    |    | US |
| 21.007    | M2 Rated Current                                   | 0.000 to VM_RATED_CURRENT A                                                                    |                                                                                                                      |                     | Maximum Heavy Duty Rating (11.032)                                                                              |                                          |                          | RW   | Num |    | RA |    | US |
| 21.008    | M2 Rated Speed                                     | 0 to 35940 rpm                                                                                 | 0.00 to 33000.00 rpm                                                                                                 |                     | 50 Hz: 1500 rpm<br>60 Hz: 1800 rpm                                                                              | 50 Hz: 1450.00 rpm<br>60 Hz: 1750.00 rpm | 3000.00 rpm              | RW   | Num |    |    |    | US |
| 21.009    | M2 Rated Voltage                                   | 0 to VM_AC_VOLTAGE_SET V                                                                       |                                                                                                                      |                     | 200V drive: 230 V<br>400V drive 50Hz: 400 V<br>400V drive 60Hz: 460 V<br>575V drive: 575 V<br>690V drive: 690 V |                                          |                          | RW   | Num |    | RA |    | US |
| 21.010    | M2 Rated Power Factor                              | 0.000 to 1.000                                                                                 |                                                                                                                      |                     | 0.850                                                                                                           |                                          |                          | RW   | Num |    | RA |    | US |
| 21.011    | M2 Number Of Motor Poles                           | Automatic (0) to 480 Poles (240)                                                               |                                                                                                                      |                     | Automatic (0)                                                                                                   |                                          | 6 Poles (3)              | RW   | Txt |    |    |    | US |
| 21.012    | M2 Stator Resistance                               | 0.000000 to 1000.000000 Ω                                                                      |                                                                                                                      |                     | 0.000000 Ω                                                                                                      |                                          |                          | RW   | Num |    | RA |    | US |
| 21.014    | M2 Transient Inductance / Ld                       | 0.000 to 500.000 mH                                                                            |                                                                                                                      |                     | 0.000 mH                                                                                                        |                                          |                          | RW   | Num |    | RA |    | US |
| 21.015    | Motor 2 Active                                     | Off (0) or On (1)                                                                              |                                                                                                                      |                     |                                                                                                                 |                                          |                          | RO   | Bit | ND | NC | PT |    |
| 21.016    | M2 Motor Thermal Time Constant 1                   | 1.0 to 3000.0 s                                                                                |                                                                                                                      |                     | 89.0 s                                                                                                          |                                          |                          | RW   | Num |    |    |    | US |
| 21.017    | M2 Speed Controller Proportional Gain Kp1          |                                                                                                | 0.0000 to 200.0000 s/rad                                                                                             |                     |                                                                                                                 | 0.0300 s/rad                             | 0.0100 s/rad             | RW   | Num |    |    |    | US |
| 21.018    | M2 Speed Controller Integral Gain Ki1              |                                                                                                | 0.00 to 655.35 s <sup>2</sup> /rad                                                                                   |                     |                                                                                                                 | 0.10 s <sup>2</sup> /rad                 | 1.00 s <sup>2</sup> /rad | RW   | Num |    |    |    | US |
| 21.019    | M2 Speed Controller Differential Feedback Gain Kd1 |                                                                                                | 0.00000 to 0.65535 1/rad                                                                                             |                     |                                                                                                                 | 0.00000 1/rad                            |                          | RW   | Num |    |    |    | US |
| 21.020    | M2 Position Feedback Phase Angle                   |                                                                                                |                                                                                                                      | 0.0 to 359.9 °      |                                                                                                                 |                                          | 0.0 °                    | RW   | Num | ND |    |    | US |
| 21.021    | M2 Motor Control Feedback Select                   |                                                                                                | P1 Drive (0), P2 Drive (1), P1 Slot 1 (2), P2 Slot 1 (3), P1 Slot 2 (4), P2 Slot 2 (5), P1 Slot 3 (6), P2 Slot 3 (7) |                     |                                                                                                                 | P1 Drive (0)                             |                          | RW   | Txt |    |    |    | US |
| 21.022    | M2 Current Controller Kp Gain                      | 0 to 30000                                                                                     |                                                                                                                      |                     | 20                                                                                                              | 150                                      |                          | RW   | Num |    |    |    | US |
| 21.023    | M2 Current Controller Ki Gain                      | 0 to 30000                                                                                     |                                                                                                                      |                     | 40                                                                                                              | 2000                                     |                          | RW   | Num |    |    |    | US |
| 21.024    | M2 Stator Inductance                               | 0.00 to 5000.00 mH                                                                             |                                                                                                                      |                     | 0.00 mH                                                                                                         |                                          |                          | RW   | Num |    | RA |    | US |
| 21.025    | M2 Saturation Breakpoint 1                         |                                                                                                | 0.0 to 100.0 %                                                                                                       |                     |                                                                                                                 | 50.0 %                                   |                          | RW   | Num |    |    |    | US |
| 21.026    | M2 Saturation Breakpoint 3                         |                                                                                                | 0.0 to 100.0 %                                                                                                       |                     |                                                                                                                 | 75.0 %                                   |                          | RW   | Num |    |    |    | US |
| 21.027    | M2 Motoring Current Limit                          | 0.0 to VM_MOTOR2_CURRENT_LIMIT %                                                               |                                                                                                                      |                     | 165.0 %*                                                                                                        | 175.0 %**                                |                          | RW   | Num |    | RA |    | US |
| 21.028    | M2 Regenerating Current Limit                      | 0.0 to VM_MOTOR2_CURRENT_LIMIT %                                                               |                                                                                                                      |                     | 165.0 %*                                                                                                        | 175.0 %**                                |                          | RW   | Num |    | RA |    | US |
| 21.029    | M2 Symmetrical Current Limit                       | 0.0 to VM_MOTOR2_CURRENT_LIMIT %                                                               |                                                                                                                      |                     | 165.0 %*                                                                                                        | 175.0 %**                                |                          | RW   | Num |    | RA |    | US |
| 21.030    | M2 Volts Per 1000 rpm                              |                                                                                                |                                                                                                                      | 0 to 10,000 V       |                                                                                                                 |                                          | 98 V                     | RW   | Num |    |    |    | US |
| 21.032    | M2 Current Reference Filter Time Constant 1        |                                                                                                | 0.0 to 25.0 ms                                                                                                       |                     |                                                                                                                 | 0.0 ms                                   |                          | RW   | Num |    |    |    | US |
| 21.033    | M2 Low Speed Thermal Protection Mode               | 0 to 1                                                                                         |                                                                                                                      |                     | 0                                                                                                               |                                          |                          | RW   | Num |    |    |    | US |
| 21.034    | M2 Current Controller Mode                         |                                                                                                | Off (0) or On (1)                                                                                                    |                     |                                                                                                                 | Off (0)                                  |                          | RW   | Bit |    |    |    | US |
| 21.035    | M2 Notch Filter Centre Frequency                   |                                                                                                | 50 to 1000 Hz                                                                                                        |                     |                                                                                                                 | 100 Hz                                   |                          | RW   | Num |    |    |    | US |
| 21.036    | M2 Notch Filter Bandwidth                          |                                                                                                | 0 to 500 Hz                                                                                                          |                     |                                                                                                                 | 0 Hz                                     |                          | RW   | Num |    |    |    | US |
| 21.039    | M2 Motor Thermal Time Constant 2                   | 1.0 to 3000.0 s                                                                                |                                                                                                                      |                     | 89.0 s                                                                                                          |                                          |                          | RW   | Num |    |    |    | US |
| 21.040    | M2 Motor Thermal Time Constant 2 Scaling           | 0 to 100 %                                                                                     |                                                                                                                      |                     | 0 %                                                                                                             |                                          |                          | RW   | Num |    |    |    | US |
| 21.041    | M2 Saturation Breakpoint 2                         |                                                                                                | 0.0 to 100.0 %                                                                                                       |                     |                                                                                                                 | 0.0 %                                    |                          | RW   | Num |    |    |    | US |
| 21.042    | M2 Saturation Breakpoint 4                         |                                                                                                | 0.0 to 100.0 %                                                                                                       |                     |                                                                                                                 | 0.0 %                                    |                          | RW   | Num |    |    |    | US |
| 21.043    | M2 Torque Per Amp                                  |                                                                                                | 0.00 to 500.00 Nm/A                                                                                                  |                     |                                                                                                                 |                                          |                          | RO   | Num | ND | NC | PT |    |
|           | M2 Torque Per Amp                                  |                                                                                                |                                                                                                                      | 0.00 to 500.00 Nm/A |                                                                                                                 |                                          | 1.60 Nm/A                | RW   | Num |    |    |    | US |

| Parameter |                                                    | Range(⇅)              |                |       | Default(⇄)          |         |       | Type |     |  |    |    |
|-----------|----------------------------------------------------|-----------------------|----------------|-------|---------------------|---------|-------|------|-----|--|----|----|
|           |                                                    | OL                    | RFC-A          | RFC-S | OL                  | RFC-A   | RFC-S |      |     |  |    |    |
| 21.044    | M2 No-load Core Loss                               | 0.000 to 99999.999 kW |                |       | 0.000 kW            |         |       | RW   | Num |  |    | US |
| 21.045    | M2 Rated Core Loss                                 | 0.000 to 99999.999 kW |                |       | 0.000 kW            |         |       | RW   | Num |  |    | US |
| 21.046    | RFC A: M2 Magnetising Current Limit                |                       | 0.0 to 100.0 % |       |                     | 100.0 % |       | RW   | Num |  |    | US |
|           | RFC S: M2 Inverted Motor Saturation Characteristic |                       |                |       | Off (0) or On (1)   |         |       | RW   | Bit |  |    | US |
| 21.048    | M2 No-load Lq                                      |                       |                |       | 0.000 to 500.000 mH |         |       | RW   | Num |  | RA | US |

\* For size 9 and above the default is 141.9 %

\*\* For size 9 and above the default is 150.0 %

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

## 12.21 Menu 22: Additional Menu 0 set-up

| Parameter |                         | Range(⇅)        |       |       | Default(⇄)           |       |       | Type |     |  |  |    |    |
|-----------|-------------------------|-----------------|-------|-------|----------------------|-------|-------|------|-----|--|--|----|----|
|           |                         | OL              | RFC-A | RFC-S | OL                   | RFC-A | RFC-S |      |     |  |  |    |    |
| 22.001    | Parameter 00.001 Set-up | 0.000 to 59.999 |       |       | 1.007                |       |       | RW   | Num |  |  | PT | US |
| 22.002    | Parameter 00.002 Set-up | 0.000 to 59.999 |       |       | 1.006                |       |       | RW   | Num |  |  | PT | US |
| 22.003    | Parameter 00.003 Set-up | 0.000 to 59.999 |       |       | 2.011                |       |       | RW   | Num |  |  | PT | US |
| 22.004    | Parameter 00.004 Set-up | 0.000 to 59.999 |       |       | 2.021                |       |       | RW   | Num |  |  | PT | US |
| 22.005    | Parameter 00.005 Set-up | 0.000 to 59.999 |       |       | 1.014                |       |       | RW   | Num |  |  | PT | US |
| 22.006    | Parameter 00.006 Set-up | 0.000 to 59.999 |       |       | 4.007                |       |       | RW   | Num |  |  | PT | US |
| 22.007    | Parameter 00.007 Set-up | 0.000 to 59.999 |       |       | 5.014                | 3.010 |       | RW   | Num |  |  | PT | US |
| 22.008    | Parameter 00.008 Set-up | 0.000 to 59.999 |       |       | 5.015                | 3.011 |       | RW   | Num |  |  | PT | US |
| 22.009    | Parameter 00.009 Set-up | 0.000 to 59.999 |       |       | 5.013                | 3.012 |       | RW   | Num |  |  | PT | US |
| 22.010    | Parameter 00.010 Set-up | 0.000 to 59.999 |       |       | 5.004                | 3.002 |       | RW   | Num |  |  | PT | US |
| 22.011    | Parameter 00.011 Set-up | 0.000 to 59.999 |       |       | 5.001                |       | 3.029 | RW   | Num |  |  | PT | US |
| 22.012    | Parameter 00.012 Set-up | 0.000 to 59.999 |       |       | 4.001                |       |       | RW   | Num |  |  | PT | US |
| 22.013    | Parameter 00.013 Set-up | 0.000 to 59.999 |       |       | 4.002                |       |       | RW   | Num |  |  | PT | US |
| 22.014    | Parameter 00.014 Set-up | 0.000 to 59.999 |       |       | 4.011                |       |       | RW   | Num |  |  | PT | US |
| 22.015    | Parameter 00.015 Set-up | 0.000 to 59.999 |       |       | 2.004                |       |       | RW   | Num |  |  | PT | US |
| 22.016    | Parameter 00.016 Set-up | 0.000 to 59.999 |       |       | 0.000                | 2.002 |       | RW   | Num |  |  | PT | US |
| 22.017    | Parameter 00.017 Set-up | 0.000 to 59.999 |       |       | 8.026                | 4.012 |       | RW   | Num |  |  | PT | US |
| 22.018    | Parameter 00.018 Set-up | 0.000 to 59.999 |       |       | 3.123                |       |       | RW   | Num |  |  | PT | US |
| 22.019    | Parameter 00.019 Set-up | 0.000 to 59.999 |       |       | 7.011*               |       |       | RW   | Num |  |  | PT | US |
| 22.020    | Parameter 00.020 Set-up | 0.000 to 59.999 |       |       | 7.014*               |       |       | RW   | Num |  |  | PT | US |
| 22.021    | Parameter 00.021 Set-up | 0.000 to 59.999 |       |       | 7.015*               |       |       | RW   | Num |  |  | PT | US |
| 22.022    | Parameter 00.022 Set-up | 0.000 to 59.999 |       |       | 1.010                |       |       | RW   | Num |  |  | PT | US |
| 22.023    | Parameter 00.023 Set-up | 0.000 to 59.999 |       |       | 1.005                |       |       | RW   | Num |  |  | PT | US |
| 22.024    | Parameter 00.024 Set-up | 0.000 to 59.999 |       |       | 1.021                |       |       | RW   | Num |  |  | PT | US |
| 22.025    | Parameter 00.025 Set-up | 0.000 to 59.999 |       |       | 1.022                |       |       | RW   | Num |  |  | PT | US |
| 22.026    | Parameter 00.026 Set-up | 0.000 to 59.999 |       |       | 1.023                | 3.008 |       | RW   | Num |  |  | PT | US |
| 22.027    | Parameter 00.027 Set-up | 0.000 to 59.999 |       |       | 1.024                | 3.034 |       | RW   | Num |  |  | PT | US |
| 22.028    | Parameter 00.028 Set-up | 0.000 to 59.999 |       |       | 6.013                |       |       | RW   | Num |  |  | PT | US |
| 22.029    | Parameter 00.029 Set-up | 0.000 to 59.999 |       |       | 11.036               |       |       | RW   | Num |  |  | PT | US |
| 22.030    | Parameter 00.030 Set-up | 0.000 to 59.999 |       |       | 11.042               |       |       | RW   | Num |  |  | PT | US |
| 22.031    | Parameter 00.031 Set-up | 0.000 to 59.999 |       |       | 11.033               |       |       | RW   | Num |  |  | PT | US |
| 22.032    | Parameter 00.032 Set-up | 0.000 to 59.999 |       |       | 11.032               |       |       | RW   | Num |  |  | PT | US |
| 22.033    | Parameter 00.033 Set-up | 0.000 to 59.999 |       |       | 6.009                | 5.016 | 0.000 | RW   | Num |  |  | PT | US |
| 22.034    | Parameter 00.034 Set-up | 0.000 to 59.999 |       |       | 11.030               |       |       | RW   | Num |  |  | PT | US |
| 22.035    | Parameter 00.035 Set-up | 0.000 to 59.999 |       |       | 11.024**             |       |       | RW   | Num |  |  | PT | US |
| 22.036    | Parameter 00.036 Set-up | 0.000 to 59.999 |       |       | 11.025**             |       |       | RW   | Num |  |  | PT | US |
| 22.037    | Parameter 00.037 Set-up | 0.000 to 59.999 |       |       | 11.023** / 24.010*** |       |       | RW   | Num |  |  | PT | US |
| 22.038    | Parameter 00.038 Set-up | 0.000 to 59.999 |       |       | 4.013                |       |       | RW   | Num |  |  | PT | US |
| 22.039    | Parameter 00.039 Set-up | 0.000 to 59.999 |       |       | 4.014                |       |       | RW   | Num |  |  | PT | US |
| 22.040    | Parameter 00.040 Set-up | 0.000 to 59.999 |       |       | 5.012                |       |       | RW   | Num |  |  | PT | US |
| 22.041    | Parameter 00.041 Set-up | 0.000 to 59.999 |       |       | 5.018                |       |       | RW   | Num |  |  | PT | US |
| 22.042    | Parameter 00.042 Set-up | 0.000 to 59.999 |       |       | 5.011                |       |       | RW   | Num |  |  | PT | US |
| 22.043    | Parameter 00.043 Set-up | 0.000 to 59.999 |       |       | 5.010                |       | 3.025 | RW   | Num |  |  | PT | US |
| 22.044    | Parameter 00.044 Set-up | 0.000 to 59.999 |       |       | 5.009                |       |       | RW   | Num |  |  | PT | US |
| 22.045    | Parameter 00.045 Set-up | 0.000 to 59.999 |       |       | 5.008                |       | 0.000 | RW   | Num |  |  | PT | US |
| 22.046    | Parameter 00.046 Set-up | 0.000 to 59.999 |       |       | 5.007                |       |       | RW   | Num |  |  | PT | US |
| 22.047    | Parameter 00.047 Set-up | 0.000 to 59.999 |       |       | 5.006                |       | 5.033 | RW   | Num |  |  | PT | US |
| 22.048    | Parameter 00.048 Set-up | 0.000 to 59.999 |       |       | 11.031               |       |       | RW   | Num |  |  | PT | US |
| 22.049    | Parameter 00.049 Set-up | 0.000 to 59.999 |       |       | 11.044               |       |       | RW   | Num |  |  | PT | US |
| 22.050    | Parameter 00.050 Set-up | 0.000 to 59.999 |       |       | 11.029               |       |       | RW   | Num |  |  | PT | US |
| 22.051    | Parameter 00.051 Set-up | 0.000 to 59.999 |       |       | 10.037               |       |       | RW   | Num |  |  | PT | US |
| 22.052    | Parameter 00.052 Set-up | 0.000 to 59.999 |       |       | 11.020**             |       |       | RW   | Num |  |  | PT | US |
| 22.053    | Parameter 00.053 Set-up | 0.000 to 59.999 |       |       | 4.015                |       |       | RW   | Num |  |  | PT | US |
| 22.054    | Parameter 00.054 Set-up | 0.000 to 59.999 |       |       | 0.000                |       |       | RW   | Num |  |  | PT | US |
| 22.055    | Parameter 00.055 Set-up | 0.000 to 59.999 |       |       | 0.000                |       |       | RW   | Num |  |  | PT | US |
| 22.056    | Parameter 00.056 Set-up | 0.000 to 59.999 |       |       | 0.000                |       |       | RW   | Num |  |  | PT | US |
| 22.057    | Parameter 00.057 Set-up | 0.000 to 59.999 |       |       | 0.000                |       |       | RW   | Num |  |  | PT | US |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                         | Range(↕)        |       |       | Default(⇄) |       |       | Type |     |  |  |    |    |
|-----------|-------------------------|-----------------|-------|-------|------------|-------|-------|------|-----|--|--|----|----|
|           |                         | OL              | RFC-A | RFC-S | OL         | RFC-A | RFC-S |      |     |  |  |    |    |
| 22.058    | Parameter 00.058 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.059    | Parameter 00.059 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.060    | Parameter 00.060 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.061    | Parameter 00.061 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.062    | Parameter 00.062 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.063    | Parameter 00.063 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.064    | Parameter 00.064 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.065    | Parameter 00.065 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.066    | Parameter 00.066 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.067    | Parameter 00.067 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.068    | Parameter 00.068 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.069    | Parameter 00.069 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.070    | Parameter 00.070 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.071    | Parameter 00.071 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.072    | Parameter 00.072 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.073    | Parameter 00.073 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.074    | Parameter 00.074 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.075    | Parameter 00.075 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.076    | Parameter 00.076 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.077    | Parameter 00.077 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.078    | Parameter 00.078 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.079    | Parameter 00.079 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |
| 22.080    | Parameter 00.080 Set-up | 0.000 to 59.999 |       |       | 0.000      |       |       | RW   | Num |  |  | PT | US |

\* 0.000 on *Unidrive M702*.

\*\* On *Unidrive M701*.

\*\*\* On *Unidrive M700 / M702*.

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

## 12.22 Menu 24: Ethernet interface information (*Unidrive M700 / M702*)

| Parameter |                   | Range                                                                                   |       |       | Default |       |       | Type |     |    |    |    |  |
|-----------|-------------------|-----------------------------------------------------------------------------------------|-------|-------|---------|-------|-------|------|-----|----|----|----|--|
|           |                   | OL                                                                                      | RFC-A | RFC-S | OL      | RFC-A | RFC-S |      |     |    |    |    |  |
| 24.001    | Module ID         | 0 to 65535                                                                              |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 24.002    | Software Version  | 00.00.00.00 to 99.99.99.99                                                              |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 24.003    | Hardware Version  | 0.00 to 99.99                                                                           |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 24.004    | Serial Number LS  | 00000000 to 99999999                                                                    |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 24.005    | Serial Number MS  | 0 to 99999999                                                                           |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 24.006    | Status            | Bootldr-Update (-2), Bootldr-Idle (-1), Initializing (0), OK (1), Config (2), Error (3) |       |       |         |       |       | RO   | Txt | ND | NC | PT |  |
| 24.007    | Reset             | Off (0) or On (1)                                                                       |       |       | Off (0) |       |       | RW   | Bit |    | NC |    |  |
| 24.008    | Default           | Off (0) or On (1)                                                                       |       |       | Off (0) |       |       | RW   | Bit |    | NC |    |  |
| 24.009    | Active Alarm Bits | 0000000000000000 to 1111111111111111                                                    |       |       |         |       |       | RO   | Bin |    | NC |    |  |
| 24.010    | Active IP Address | 0.0.0.0 to 255.255.255.255                                                              |       |       |         |       |       | RO   | IP  |    | NC | PT |  |
| 24.011    | Date Code         | 0 to 65535                                                                              |       |       |         |       |       | RO   | Num | ND | NC | PT |  |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

## 12.23 Slot 4 Menus (*Unidrive M700 / M702*)

The following table shows the internal menus of the Ethernet interface.

| Menu | Description                 |
|------|-----------------------------|
| 4.00 | Module information          |
| 4.02 | Ethernet configuration      |
| 4.09 | Resources                   |
| 4.10 | RTMoE Easy mode cyclic data |
| 4.11 | RTMoE Synchronisation       |
| 4.15 | Modbus TCP/IP Setup         |
| 4.20 | EtherNet/IP Setup           |
| 4.21 | EtherNet/IP Input mappings  |
| 4.22 | EtherNet/IP Output mappings |
| 4.23 | EtherNet/IP Fault values    |
| 4.24 | Profinet Setup              |

## 12.24 Slot 4 Menu 0: Ethernet interface information (*Unidrive M700 / M702*)

| Parameter |                   | Range                                                                                   |       |       | Default |       |       | Type |     |    |    |    |  |
|-----------|-------------------|-----------------------------------------------------------------------------------------|-------|-------|---------|-------|-------|------|-----|----|----|----|--|
|           |                   | OL                                                                                      | RFC-A | RFC-S | OL      | RFC-A | RFC-S |      |     |    |    |    |  |
| 4.00.001  | Module ID         | 0 to 65535                                                                              |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.00.002  | Software Version  | 00.00.00.00 to 99.99.99.99                                                              |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.00.003  | Hardware Version  | 0.00 to 99.99                                                                           |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.00.004  | Serial Number LS  | 00000000 to 99999999                                                                    |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.00.005  | Serial Number MS  | 0 to 99999999                                                                           |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.00.006  | Status            | Bootldr-Update (-2), Bootldr-Idle (-1), Initializing (0), OK (1), Config (2), Error (3) |       |       |         |       |       | RO   | Txt | ND | NC | PT |  |
| 4.00.007  | Reset             | Off (0) or On (1)                                                                       |       |       | Off (0) |       |       | RW   | Bit |    | NC |    |  |
| 4.00.008  | Default           | Off (0) or On (1)                                                                       |       |       | Off (0) |       |       | RW   | Bit |    | NC |    |  |
| 4.00.009  | Active Alarm Bits | 0000000000000000 to 1111111111111111                                                    |       |       |         |       |       | RO   | Bin |    | NC |    |  |
| 4.00.010  | Active IP Address | 0.0.0.0 to 255.255.255.255                                                              |       |       |         |       |       | RO   | IP  |    | NC | PT |  |
| 4.00.011  | Date Code         | 0 to 65535                                                                              |       |       |         |       |       | RO   | Num | ND | NC | PT |  |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

## 12.25 Slot 4 Menu 2: Ethernet configuration (Unidrive M700 / M702)

| Parameter |                           | Range                                                                                         |       |       | Default         |       |       | Type |     |    |    |    |    |
|-----------|---------------------------|-----------------------------------------------------------------------------------------------|-------|-------|-----------------|-------|-------|------|-----|----|----|----|----|
|           |                           | OL                                                                                            | RFC-A | RFC-S | OL              | RFC-A | RFC-S |      |     |    |    |    |    |
| 4.02.003  | Network Status            | Initializing (0), Links Down (1), DHCP In Progress (2), No Address (3), Ready (4), Active (5) |       |       |                 |       |       | RO   | Txt | ND | NC | PT |    |
| 4.02.004  | Network Message Count     | 0 to 65535 Messages/s                                                                         |       |       |                 |       |       | RO   | Num | ND | NC | PT |    |
| 4.02.005  | DHCP Enable               | Off (0) or On (1)                                                                             |       |       | On (1)          |       |       | RW   | Bit |    |    |    | US |
| 4.02.006  | IP Address                | 0.0.0.0 to 255.255.255.255                                                                    |       |       | 192.168.001.100 |       |       | RW   | IP  |    |    |    | US |
| 4.02.007  | Subnet Mask               | 0.0.0.0 to 255.255.255.255                                                                    |       |       | 255.255.255.000 |       |       | RW   | IP  |    |    |    | US |
| 4.02.008  | Default Gateway           | 0.0.0.0 to 255.255.255.255                                                                    |       |       | 192.168.1.254   |       |       | RW   | IP  |    |    |    | US |
| 4.02.009  | Primary DNS               | 0.0.0.0 to 255.255.255.255                                                                    |       |       | 0.0.0.0         |       |       | RW   | IP  |    |    |    | US |
| 4.02.010  | Secondary DNS             | 0.0.0.0 to 255.255.255.255                                                                    |       |       | 0.0.0.0         |       |       | RW   | IP  |    |    |    | US |
| 4.02.011  | MAC Address               | 00:00:00:00:00:00 to FF:FF:FF:FF:FF:FF                                                        |       |       |                 |       |       | RO   | Mac | ND | NC | PT |    |
| 4.02.018  | Protocol Mode Select      | Ethernet/IP (1) to Profinet (2)                                                               |       |       | Ethernet/IP (1) |       |       | RW   | Txt |    |    |    | US |
| 4.02.019  | Active Protocol Mode      | Ethernet/IP (1) to Profinet (2)                                                               |       |       |                 |       |       | RO   | Txt |    | NC | PT |    |
| 4.02.020  | Priority Protocol         | None (0), Modbus TCP (1), EtherNet/IP (2)                                                     |       |       | 0               |       |       | RW   | Txt |    |    |    | US |
| 4.02.021  | Web Server Enable         | Off (0) or On (1)                                                                             |       |       | On (1)          |       |       | RW   | Bit |    |    |    | US |
| 4.02.022  | Web Server Port           | 0 to 65535                                                                                    |       |       | 80              |       |       | RW   | Num |    |    |    | US |
| 4.02.024  | Ethernet MTU*             | 158 to 1500 Bytes                                                                             |       |       | 1500 Bytes      |       |       | RW   | Num |    |    |    | US |
| 4.02.025  | Gateway Mode              | Switch (0), Gateway (1), Strict Gateway (2)                                                   |       |       | Switch (0)      |       |       | RW   | Txt |    |    |    | US |
| 4.02.030  | VLAN Enable               | Off (0) or On (1)                                                                             |       |       | Off (0)         |       |       | RW   | Bit |    |    |    | US |
| 4.02.034  | Drive compatibility mode  | Unidrive M (0) or Unidrive SP (1)                                                             |       |       | Unidrive M (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.02.035  | Non cyclic enable         | Off (0) or On (1)                                                                             |       |       | Off (0)         |       |       | RW   | Bit |    |    |    | US |
| 4.02.036  | Non cyclic base parameter | 0.00.000 to 0.59.999                                                                          |       |       | 0.00.000        |       |       | RW   | SMP |    |    |    | US |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

\* This parameter is now not used, the maximum Ethernet packet size is limited to 400 bytes.

## 12.26 Slot 4 Menu 9: Resources (Unidrive M700 / M702)

| Parameter |                                | Range          |       |       | Default |       |       | Type |     |    |    |    |  |
|-----------|--------------------------------|----------------|-------|-------|---------|-------|-------|------|-----|----|----|----|--|
|           |                                | OL             | RFC-A | RFC-S | OL      | RFC-A | RFC-S |      |     |    |    |    |  |
| 4.09.001  | Cyclic Tx Links Free           | 0 to 255       |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.002  | Cyclic Rx Links Free           | 0 to 255       |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.003  | Fieldbus Links Free            | 0 to 255       |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.004  | Cyclic Mappings Free           | 0 to 255       |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.008  | Background cycles per second   | 0 to 65535     |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.010  | Synchronous Task % Free        | 0 to 255 %     |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.011  | Nonsync link update period     | 0.00 to 655.35 |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.020  | Synchronous Task % Worst Free  | 0 to 255 %     |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.021  | Max nonsync link update period | 0.00 to 655.35 |       |       |         |       |       | RO   | Num | ND | NC | PT |  |
| 4.09.030  | PCB Temperature                | -128 to 127 °C |       |       |         |       |       | RO   | Num | ND | NC | PT |  |

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

## 12.27 Slot 4 Menu 10: RTMoE Easy Mode Cyclic Data (*Unidrive M700 / M702*)

| Parameter |                            | Range                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |       |       | Default     |       |       | Type |     |    |    |    |    |
|-----------|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|-------|-------------|-------|-------|------|-----|----|----|----|----|
|           |                            | OL                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | RFC-A | RFC-S | OL          | RFC-A | RFC-S |      |     |    |    |    |    |
| 4.10.001  | Enable                     | Off (0) or On (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | On (1)      |       |       | RW   | Bit |    |    |    | US |
| 4.10.002  | Reset                      | Off (0) or On (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | Off (0)     |       |       | RW   | Bit |    | NC |    |    |
| 4.10.003  | Default                    | Off (0) or On (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | Off (0)     |       |       | RW   | Bit |    | NC |    |    |
| 4.10.004  | Cyclic Messages Per Second | 0 to 65535 Messages/s                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |       |       |             |       |       | RO   | Num | ND | NC | PT |    |
| 4.10.005  | Configuration Valid        | Off (0) or On (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       |             |       |       | RO   | Bit | ND | NC | PT |    |
| 4.10.006  | Operational                | Off (0) or On (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       |             |       |       | RO   | Bit | ND | NC | PT |    |
| 4.10.007  | Active Configuration       | None (0), Easy Mode (1), Offline (2)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |       |       |             |       |       | RO   | Txt | ND | NC | PT |    |
| 4.10.008  | Timeout Count              | 0 to 65535                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |       |       |             |       |       | RO   | Num | ND | NC | PT |    |
| 4.10.009  | Data Late Count            | 0 to 65535                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |       |       |             |       |       | RO   | Num | ND | NC | PT |    |
| 4.10.010  | Tx1 Link Profile           | Std (0), Sync (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | Std (0)     |       |       | RW   | Txt |    |    |    | US |
| 4.10.011  | Tx1 Link Number            | 0 to 255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |       |       | 0           |       |       | RW   | Num |    |    |    | US |
| 4.10.012  | Tx1 Source Parameter       | 0.00.000 to 4.99.999                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |       |       | 0.00.000    |       |       | RW   | SMP |    |    | PT | US |
| 4.10.013  | Tx1 Parameter Count        | 0 to 10                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |       |       | 0           |       |       | RW   | Num |    |    |    | US |
| 4.10.014  | Tx1 Link Transmission Type | Unicast (0), Broadcast (1), Multicast1 (2), Multicast2 (3), Multicast3 (4), Multicast4 (5), Multicast5 (6), Multicast6 (7), Multicast7 (8), Multicast8 (9), Multicast9 (10), Multicast10 (11)                                                                                                                                                                                                                                                                                                                                          |       |       | Unicast (0) |       |       | RW   | Txt |    |    |    | US |
| 4.10.015  | Tx1 Destination Address    | 0.0.0.0 to 255.255.255.255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |       |       | 0.0.0.0     |       |       | RW   | IP  |    |    |    | US |
| 4.10.016  | Tx1 Message Rate           | 0 to 100 ms                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |       |       | 0 ms        |       |       | RW   | Num |    |    |    | US |
| 4.10.019  | Tx1 Link Status            | Disabled (-31), VLAN disabled (-30), Invalid DST IP (-22), SYNC unsupported (-21), MEC offset (-20), Invalid tx rate (-19), Too many mapping (-18), Link busy (-17), Invalid profile (-16), Invalid mapping (-15), Read only param (-14), Msg mismatch (-13), Msg too long (-12), Attrib NA (-11), Attrib RO (-10), Attrib missing (-9), Timeout (-8), In error (-7), Link num in use (-6), Not editable (-5), Invalid link num (-4), Invalid args (-3), Too many links (-2), Out of memory (-1), OK (0), Not running (1), OK sync (2) |       |       |             |       |       | RO   | Txt | ND | NC | PT |    |
| 4.10.020  | Tx2 Link Profile           | Std (0), Sync (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | Std (0)     |       |       | RW   | Txt |    |    |    | US |
| 4.10.021  | Tx2 Link Number            | 0 to 255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |       |       | 0           |       |       | RW   | Num |    |    |    | US |
| 4.10.022  | Tx2 Source Parameter       | 0.00.000 to 4.99.999                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |       |       | 0.00.000    |       |       | RW   | SMP |    |    | PT | US |
| 4.10.023  | Tx2 Parameter Count        | 0 to 10                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |       |       | 0           |       |       | RW   | Num |    |    |    | US |
| 4.10.024  | Tx2 Link Transmission Type | Unicast (0), Broadcast (1), Multicast1 (2), Multicast2 (3), Multicast3 (4), Multicast4 (5), Multicast5 (6), Multicast6 (7), Multicast7 (8), Multicast8 (9), Multicast9 (10), Multicast10 (11)                                                                                                                                                                                                                                                                                                                                          |       |       | Unicast (0) |       |       | RW   | Txt |    |    |    | US |
| 4.10.025  | Tx2 Destination Address    | 0.0.0.0 to 255.255.255.255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |       |       | 0.0.0.0     |       |       | RW   | IP  |    |    |    | US |
| 4.10.026  | Tx2 Message Rate           | 0 to 100 ms                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |       |       | 0 ms        |       |       | RW   | Num |    |    |    | US |
| 4.10.029  | Tx2 Link Status            | Disabled (-31), VLAN disabled (-30), Invalid DST IP (-22), SYNC unsupported (-21), MEC offset (-20), Invalid tx rate (-19), Too many mapping (-18), Link busy (-17), Invalid profile (-16), Invalid mapping (-15), Read only param (-14), Msg mismatch (-13), Msg too long (-12), Attrib NA (-11), Attrib RO (-10), Attrib missing (-9), Timeout (-8), In error (-7), Link num in use (-6), Not editable (-5), Invalid link num (-4), Invalid args (-3), Too many links (-2), Out of memory (-1), OK (0), Not running (1), OK sync (2) |       |       |             |       |       | RO   | Txt | ND | NC | PT |    |
| 4.10.030  | Tx3 Link Profile           | Std (0), Sync (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | Std (0)     |       |       | RW   | Txt |    |    |    | US |
| 4.10.031  | Tx3 Link Number            | 0 to 255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |       |       | 0           |       |       | RW   | Num |    |    |    | US |
| 4.10.032  | Tx3 Source Parameter       | 0.00.000 to 4.99.999                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |       |       | 0.00.000    |       |       | RW   | SMP |    |    | PT | US |
| 4.10.033  | Tx3 Parameter Count        | 0 to 10                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |       |       | 0           |       |       | RW   | Num |    |    |    | US |
| 4.10.034  | Tx3 Link Transmission Type | Unicast (0), Broadcast (1), Multicast1 (2), Multicast2 (3), Multicast3 (4), Multicast4 (5), Multicast5 (6), Multicast6 (7), Multicast7 (8), Multicast8 (9), Multicast9 (10), Multicast10 (11)                                                                                                                                                                                                                                                                                                                                          |       |       | Unicast (0) |       |       | RW   | Txt |    |    |    | US |
| 4.10.035  | Tx3 Destination Address    | 0.0.0.0 to 255.255.255.255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |       |       | 0.0.0.0     |       |       | RW   | IP  |    |    |    | US |
| 4.10.036  | Tx3 Message Rate           | 0 to 100 ms                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |       |       | 0 ms        |       |       | RW   | Num |    |    |    | US |
| 4.10.039  | Tx3 Link Status            | Disabled (-31), VLAN disabled (-30), Invalid DST IP (-22), SYNC unsupported (-21), MEC offset (-20), Invalid tx rate (-19), Too many mapping (-18), Link busy (-17), Invalid profile (-16), Invalid mapping (-15), Read only param (-14), Msg mismatch (-13), Msg too long (-12), Attrib NA (-11), Attrib RO (-10), Attrib missing (-9), Timeout (-8), In error (-7), Link num in use (-6), Not editable (-5), Invalid link num (-4), Invalid args (-3), Too many links (-2), Out of memory (-1), OK (0), Not running (1), OK sync (2) |       |       |             |       |       | RO   | Txt | ND | NC | PT |    |
| 4.10.040  | Rx1 Link Profile           | Std (0), Sync (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | Std (0)     |       |       | RW   | Txt |    |    |    | US |
| 4.10.041  | Rx1 Link Number            | 0 to 255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |       |       | 0           |       |       | RW   | Num |    |    |    | US |
| 4.10.042  | Rx1 Destination Parameter  | 0.00.000 to 4.99.999                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |       |       | 0.00.000    |       |       | RW   | SMP |    |    |    | US |

|                    |                     |                         |                         |                 |                  |                   |              |                     |                         |             |                     |             |                |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|
| Safety information | Product information | Mechanical installation | Electrical installation | Getting started | Basic parameters | Running the motor | Optimization | Drive communication | NV Media Card Operation | Onboard PLC | Advanced parameters | Diagnostics | UL information |
|--------------------|---------------------|-------------------------|-------------------------|-----------------|------------------|-------------------|--------------|---------------------|-------------------------|-------------|---------------------|-------------|----------------|

| Parameter |                                | Range                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |       |       | Default       |       |       | Type |     |    |    |    |    |
|-----------|--------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|-------|---------------|-------|-------|------|-----|----|----|----|----|
|           |                                | OL                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | RFC-A | RFC-S | OL            | RFC-A | RFC-S |      |     |    |    |    |    |
| 4.10.043  | Rx1 Parameter Count            | 0 to 10                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |       |       | 0             |       |       | RW   | Num |    |    |    | US |
| 4.10.044  | Rx1 Source Type                | Direct (0), Multicast1 (1), Multicast2 (2), Multicast3 (3), Multicast4 (4), Local (5), Multicast5 (6), Multicast6 (7), Multicast7 (8), Multicast8 (9), Multicast9 (10), Multicast10 (11)                                                                                                                                                                                                                                                                                                                                               |       |       | Direct (0)    |       |       | RW   | Txt |    |    |    | US |
| 4.10.045  | Rx1 Timeout                    | 0 to 65535 ms                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |       |       | 100 ms        |       |       | RW   | Num |    |    |    | US |
| 4.10.046  | Rx1 Timeout Action             | Trip (0), Clear output (1), Hold last (2)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |       |       | Trip (0)      |       |       | RW   | Txt |    |    |    | US |
| 4.10.047  | Rx1 Timeout Event Destination* | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4)                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |       |       | This slot (0) |       |       | RW   | Txt |    |    |    | US |
| 4.10.048  | Rx1 Timeout Event Type         | No Event (0), Event (1), Event1 (2), Event2 (3), Event3 (4)                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |       |       | No Event (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.10.049  | Rx1 Link Status                | Disabled (-31), VLAN disabled (-30), Invalid DST IP (-22), SYNC unsupported (-21), MEC offset (-20), Invalid tx rate (-19), Too many mapping (-18), Link busy (-17), Invalid profile (-16), Invalid mapping (-15), Read only param (-14), Msg mismatch (-13), Msg too long (-12), Attrib NA (-11), Attrib RO (-10), Attrib missing (-9), Timeout (-8), In error (-7), Link num in use (-6), Not editable (-5), Invalid link num (-4), Invalid args (-3), Too many links (-2), Out of memory (-1), OK (0), Not running (1), OK sync (2) |       |       |               |       |       | RO   | Txt | ND | NC | PT |    |
| 4.10.050  | Rx2 Link Profile               | Std (0), Sync (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | Std (0)       |       |       | RW   | Txt |    |    |    | US |
| 4.10.051  | Rx2 Link Number                | 0 to 255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |       |       | 0             |       |       | RW   | Num |    |    |    | US |
| 4.10.052  | Rx2 Destination Parameter      | 0.00.000 to 4.99.999                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |       |       | 0.00.000      |       |       | RW   | SMP |    |    |    | US |
| 4.10.053  | Rx2 Parameter Count            | 0 to 10                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |       |       | 0             |       |       | RW   | Num |    |    |    | US |
| 4.10.054  | Rx2 Source Type                | Direct (0), Multicast1 (1), Multicast2 (2), Multicast3 (3), Multicast4 (4), Local (5), Multicast5 (6), Multicast6 (7), Multicast7 (8), Multicast8 (9), Multicast9 (10), Multicast10 (11)                                                                                                                                                                                                                                                                                                                                               |       |       | Direct (0)    |       |       | RW   | Txt |    |    |    | US |
| 4.10.055  | Rx2 Timeout                    | 0 to 65535 ms                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |       |       | 100 ms        |       |       | RW   | Num |    |    |    | US |
| 4.10.056  | Rx2 Timeout Action             | Trip (0), Clear output (1), Hold last (2)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |       |       | Trip (0)      |       |       | RW   | Txt |    |    |    | US |
| 4.10.057  | Rx2 Timeout Event Destination* | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4)                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |       |       | This slot (0) |       |       | RW   | Txt |    |    |    | US |
| 4.10.058  | Rx2 Timeout Event Type         | No Event (0), Event (1), Event1 (2), Event2 (3), Event3 (4)                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |       |       | No Event (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.10.059  | Rx2 Link Status                | Disabled (-31), VLAN disabled (-30), Invalid DST IP (-22), SYNC unsupported (-21), MEC offset (-20), Invalid tx rate (-19), Too many mapping (-18), Link busy (-17), Invalid profile (-16), Invalid mapping (-15), Read only param (-14), Msg mismatch (-13), Msg too long (-12), Attrib NA (-11), Attrib RO (-10), Attrib missing (-9), Timeout (-8), In error (-7), Link num in use (-6), Not editable (-5), Invalid link num (-4), Invalid args (-3), Too many links (-2), Out of memory (-1), OK (0), Not running (1), OK sync (2) |       |       |               |       |       | RO   | Txt | ND | NC | PT |    |
| 4.10.060  | Rx3 Link Profile               | Std (0), Sync (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |       |       | Std (0)       |       |       | RW   | Txt |    |    |    | US |
| 4.10.061  | Rx3 Link Number                | 0 to 255                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |       |       | 0             |       |       | RW   | Num |    |    |    | US |
| 4.10.062  | Rx3 Destination Parameter      | 0.00.000 to 4.99.999                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |       |       | 0.00.000      |       |       | RW   | SMP |    |    |    | US |
| 4.10.063  | Rx3 Parameter Count            | 0 to 10                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |       |       | 0             |       |       | RW   | Num |    |    |    | US |
| 4.10.064  | Rx3 Source Type                | Direct (0), Multicast1 (1), Multicast2 (2), Multicast3 (3), Multicast4 (4), Local (5), Multicast5 (6), Multicast6 (7), Multicast7 (8), Multicast8 (9), Multicast9 (10), Multicast10 (11)                                                                                                                                                                                                                                                                                                                                               |       |       | Direct (0)    |       |       | RW   | Txt |    |    |    | US |
| 4.10.065  | Rx3 Timeout                    | 0 to 65535 ms                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |       |       | 100 ms        |       |       | RW   | Num |    |    |    | US |
| 4.10.066  | Rx3 Timeout Action             | Trip (0), Clear output (1), Hold last (2)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |       |       | Trip (0)      |       |       | RW   | Txt |    |    |    | US |
| 4.10.067  | Rx3 Timeout Event Destination* | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4)                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |       |       | This slot (0) |       |       | RW   | Txt |    |    |    | US |
| 4.10.068  | Rx3 Timeout Event Type         | No Event (0), Event (1), Event1 (2), Event2 (3), Event3 (4)                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |       |       | No Event (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.10.069  | Rx3 Link Status                | Disabled (-31), VLAN disabled (-30), Invalid DST IP (-22), SYNC unsupported (-21), MEC offset (-20), Invalid tx rate (-19), Too many mapping (-18), Link busy (-17), Invalid profile (-16), Invalid mapping (-15), Read only param (-14), Msg mismatch (-13), Msg too long (-12), Attrib NA (-11), Attrib RO (-10), Attrib missing (-9), Timeout (-8), In error (-7), Link num in use (-6), Not editable (-5), Invalid link num (-4), Invalid args (-3), Too many links (-2), Out of memory (-1), OK (0), Not running (1), OK sync (2) |       |       |               |       |       | RO   | Txt | ND | NC | PT |    |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

\* This feature is not currently supported

## 12.28 Slot 4 Menu 11: Synchronization (*Unidrive M700 / M702*)

| Parameter |                                             | Range                                                         |       |       | Default       |       |       | Type |      |    |    |    |    |
|-----------|---------------------------------------------|---------------------------------------------------------------|-------|-------|---------------|-------|-------|------|------|----|----|----|----|
|           |                                             | OL                                                            | RFC-A | RFC-S | OL            | RFC-A | RFC-S |      |      |    |    |    |    |
| 4.11.001  | Preferred Sync Master                       | 0 to 4                                                        |       |       | 1             |       |       | RW   | Num  |    |    |    | US |
| 4.11.002  | Master Clock Domain                         | 0 to 3                                                        |       |       | 0             |       |       | RW   | Num  |    |    |    | US |
| 4.11.005  | Grandmaster MAC Address                     | 00:00:00:00:00:00 to FF:FF:FF:FF:FF:FF                        |       |       |               |       |       | RO   | Mac  | ND | NC | PT |    |
| 4.11.006  | Synchronisation Jitter From Grandmaster     | -2147483648 to 2147483647 ns                                  |       |       |               |       |       | RO   | Num  | ND | NC | PT |    |
| 4.11.007  | Synchronisation Jitter Threshold            | 500 to 1000000 ns                                             |       |       | 1000 ns       |       |       | RW   | Num  |    |    |    | US |
| 4.11.008  | Module Synchronised Flag                    | Off (0) or On (1)                                             |       |       | Off (0)       |       |       | RO   | Bit  |    |    |    |    |
| 4.11.009  | Inhibit Drive Synchronisation               | Off (0) or On (1)                                             |       |       | Off (0)       |       |       | RW   | Bit  |    |    |    | US |
| 4.11.010  | PTP Date                                    | 00-00-00 to 31-12-99                                          |       |       |               |       |       | RO   | Date | ND | NC | PT |    |
| 4.11.011  | PTP Time                                    | 00:00:00 to 23:59:59                                          |       |       |               |       |       | RO   | Time | ND | NC | PT |    |
| 4.11.015  | PTP Delay Measurement Select                | P2P DELAY (1), OFF (2)                                        |       |       | P2P DELAY (1) |       |       | RW   | Txt  |    |    |    | US |
| 4.11.016  | PTP Sync Rate                               | -4 to 0                                                       |       |       | -4            |       |       | RW   | Num  |    |    |    | US |
| 4.11.017  | In sync window length                       | 3 to 255 s                                                    |       |       | 20 s          |       |       | RW   | Num  |    |    |    | US |
| 4.11.020  | Network Error Count                         | 0 to 4294967295                                               |       |       |               |       |       | RO   | Num  | ND | NC | PT |    |
| 4.11.022  | Interoption Sync Status                     | MASTER (0), PRODUCER (1), INDEPENDENT (2)                     |       |       |               |       |       | RO   | Txt  | ND | NC | PT |    |
| 4.11.030  | Easy Mode Maximum Network Delay             | 1 to 100 ms                                                   |       |       | 3 ms          |       |       | RW   | Num  |    |    |    | US |
| 4.11.040  | Rx1 Late Synchronisation Frame Action       | Trip (1), Do not use (2), Use (3)                             |       |       | Trip (1)      |       |       | RW   | Txt  |    |    |    | US |
| 4.11.041  | Rx1 Late Synchronisation Frame Destination* | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4) |       |       | This slot (0) |       |       | RW   | Txt  |    |    |    | US |
| 4.11.042  | Rx1 Late Synchronisation Frame Event        | No Event (0), Event (1), Event1 (2), Event2 (3), Event3 (4)   |       |       | No Event (0)  |       |       | RW   | Txt  |    |    |    | US |
| 4.11.050  | Rx2 Late Synchronisation Frame Action       | Trip (1), Do not use (2), Use (3)                             |       |       | Trip (1)      |       |       | RW   | Txt  |    |    |    | US |
| 4.11.051  | Rx2 Late Synchronisation Frame Destination* | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4) |       |       | This slot (0) |       |       | RW   | Txt  |    |    |    | US |
| 4.11.052  | Rx2 Late Synchronisation Frame Event        | No Event (0), Event (1), Event1 (2), Event2 (3), Event3 (4)   |       |       | No Event (0)  |       |       | RW   | Txt  |    |    |    | US |
| 4.11.060  | Rx3 Late Synchronisation Frame Action       | Trip (1), Do not use (2), Use (3)                             |       |       | Trip (1)      |       |       | RW   | Txt  |    |    |    | US |
| 4.11.061  | Rx3 Late Synchronisation Frame Destination* | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4) |       |       | This slot (0) |       |       | RW   | Txt  |    |    |    | US |
| 4.11.062  | Rx3 Late Synchronisation Frame Event        | No Event (0), Event (1), Event1 (2), Event2 (3), Event3 (4)   |       |       | No Event (0)  |       |       | RW   | Txt  |    |    |    | US |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

\* This feature is not currently supported

## 12.29 Slot 4 Menu 15: Modbus TCP/IP Set-up (Unidrive M700 / M702)

| Parameter |                                   | Range                                                                                                               |       |       | Default       |       |       | Type |     |    |    |    |    |
|-----------|-----------------------------------|---------------------------------------------------------------------------------------------------------------------|-------|-------|---------------|-------|-------|------|-----|----|----|----|----|
|           |                                   | OL                                                                                                                  | RFC-A | RFC-S | OL            | RFC-A | RFC-S |      |     |    |    |    |    |
| 4.15.001  | Enable                            | Off (0) or On (1)                                                                                                   |       |       | On (1)        |       |       | RW   | Bit |    |    |    | US |
| 4.15.002  | Reset                             | Off (0) or On (1)                                                                                                   |       |       | Off (0)       |       |       | RW   | Bit |    | NC |    |    |
| 4.15.003  | Default                           | Off (0) or On (1)                                                                                                   |       |       | Off (0)       |       |       | RW   | Bit |    | NC |    |    |
| 4.15.004  | Modbus Configuration Error        | No error (0), Port in use (1), Timeout event (2), Num Connections (3)                                               |       |       |               |       |       | RO   | Txt | ND | NC | PT |    |
| 4.15.005  | Modbus Listening Port             | 0 to 65535                                                                                                          |       |       | 502           |       |       | RW   | Num |    |    |    | US |
| 4.15.006  | Maximum Connections               | 0 to 10                                                                                                             |       |       | 2             |       |       | RW   | Num |    |    |    | US |
| 4.15.007  | Maximum Priority Connections      | 0 to 5                                                                                                              |       |       | 0             |       |       | RW   | Num |    |    |    | US |
| 4.15.008  | Maximum Connections Per Client    | 1 to 4                                                                                                              |       |       | 2             |       |       | RW   | Num |    |    |    | US |
| 4.15.009  | Modbus Timeout                    | 1 to 10000 ms                                                                                                       |       |       | 100 ms        |       |       | RW   | Num |    |    |    | US |
| 4.15.010  | Modbus Timeout Action             | Trip (0), No action (1)                                                                                             |       |       | No action (1) |       |       | RW   | Txt |    |    |    | US |
| 4.15.011  | Modbus Timeout Event Destination* | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4)                                                       |       |       | This slot (0) |       |       | RW   | Txt |    |    |    | US |
| 4.15.012  | Modbus Timeout Event Type         | No event (0), Trigger Event (1), Trigger Event 1 (2), Trigger Event 2 (3), Trigger Event 3 (4), Trigger Event 4 (5) |       |       | No event (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.15.013  | Modbus Resister Addressing Mode   | Standard (0), Modified (1)                                                                                          |       |       | Standard (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.15.020  | Priority Connection 1             | 0.0.0.0 to 255.255.255.255                                                                                          |       |       | 0.0.0.0       |       |       | RW   | IP  |    |    |    | US |
| 4.15.021  | Priority Connection 2             | 0.0.0.0 to 255.255.255.255                                                                                          |       |       | 0.0.0.0       |       |       | RW   | IP  |    |    |    | US |
| 4.15.022  | Priority Connection 3             | 0.0.0.0 to 255.255.255.255                                                                                          |       |       | 0.0.0.0       |       |       | RW   | IP  |    |    |    | US |
| 4.15.023  | Priority Connection 4             | 0.0.0.0 to 255.255.255.255                                                                                          |       |       | 0.0.0.0       |       |       | RW   | IP  |    |    |    | US |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

\* This feature is not currently supported

## 12.30 Slot 4 Menu 20: EtherNet/IP Set-up (Unidrive M700 / M702)

| Parameter |                                                      | Range                                                                                                                                                                          |       |       | Default       |       |       | Type |     |    |    |    |    |
|-----------|------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|-------|---------------|-------|-------|------|-----|----|----|----|----|
|           |                                                      | OL                                                                                                                                                                             | RFC-A | RFC-S | OL            | RFC-A | RFC-S |      |     |    |    |    |    |
| 4.20.001  | Enable EtherNet/IP                                   | Off (0) or On (1)                                                                                                                                                              |       |       | On (1)        |       |       | RW   | Bit |    |    |    | US |
| 4.20.002  | Reset                                                | Off (0) or On (1)                                                                                                                                                              |       |       | Off (0)       |       |       | RW   | Bit |    | NC |    |    |
| 4.20.003  | Default                                              | Off (0) or On (1)                                                                                                                                                              |       |       | Off (0)       |       |       | RW   | Bit |    | NC |    |    |
| 4.20.004  | Configuration error                                  | No error (0), RPI event dst (1), RPI event type (2), IDLE event dst (3), IDLE event type (4), Input mapping (5), Output mapping (6), In cons trig pr (7), Out cons trig pr (8) |       |       |               |       |       | RO   | Txt | ND | NC | PT |    |
| 4.20.007  | Cyclic data transfers per second                     | 0 to 65535 Messages/s                                                                                                                                                          |       |       |               |       |       | RO   | Num | ND | NC | PT |    |
| 4.20.011  | RPI timeout action                                   | Trip (0), Send flt values (1), Clear output (2), Hold last (3), No Action (4)                                                                                                  |       |       | Hold last (3) |       |       | RW   | Txt |    |    |    | US |
| 4.20.012  | RPI timeout event destination*                       | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4)                                                                                                                  |       |       | This slot (0) |       |       | RW   | Txt |    |    |    | US |
| 4.20.013  | RPI timeout event type                               | No event (0), Trigger Event (1), Trigger Event 1 (2), Trigger Event 2 (3), Trigger Event 3 (4), Trigger Event 4 (5)                                                            |       |       | No event (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.20.015  | PLC idle action                                      | Trip (0), Send flt values (1), Clear output (2), Hold last (3), No Action (4)                                                                                                  |       |       | No Action (4) |       |       | RW   | Txt |    |    |    | US |
| 4.20.016  | PLC idle event destination*                          | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4)                                                                                                                  |       |       | This slot (0) |       |       | RW   | Txt |    |    |    | US |
| 4.20.017  | PLC idle event type                                  | No event (0), Trigger Event (1), Trigger Event 1 (2), Trigger Event 2 (3), Trigger Event 3 (4), Trigger Event 4 (5)                                                            |       |       | No event (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.20.018  | Active input assembly object                         | 100-PrimaryI (0), 70-BscSpdCtrlI (1), 71-ExtSpdCtrlI (2), 72-SpdTqCtrlI (3), 73-ExtSpdTqCtrlI (4)                                                                              |       |       |               |       |       | RO   | Txt | ND | NC | PT |    |
| 4.20.019  | Active output assembly object                        | 101-PrimaryO (0), 20-BscSpdCtrlO (1), 21-ExtSpdCtrlO (2), 22-SpdTqCtrlO (3), 23-ExtSpdTqCtrlO (4)                                                                              |       |       |               |       |       | RO   | Txt | ND | NC | PT |    |
| 4.20.020  | Input assembly object size                           | 4 to 128 Bytes                                                                                                                                                                 |       |       | 8 Bytes       |       |       | RW   | Num |    |    |    | US |
| 4.20.021  | Output assembly object size                          | 4 to 128 Bytes                                                                                                                                                                 |       |       | 8 Bytes       |       |       | RW   | Num |    |    |    | US |
| 4.20.024  | Input assembly object process time                   | 0 to 65535 ms                                                                                                                                                                  |       |       |               |       |       | RO   | Num | ND | NC | PT |    |
| 4.20.025  | Output assembly object process time                  | 0 to 65535 ms                                                                                                                                                                  |       |       |               |       |       | RO   | Num | ND | NC | PT |    |
| 4.20.026  | Input assembly object consistency enable             | Off (0) or On (1)                                                                                                                                                              |       |       | Off (0)       |       |       | RW   | Bit |    |    |    | US |
| 4.20.027  | Input assembly object consistency trigger parameter  | 0.00.000 to 4.99.999                                                                                                                                                           |       |       | 0.00.000      |       |       | RW   | SMP |    |    |    | US |
| 4.20.028  | Output assembly object consistency enable            | Off (0) or On (1)                                                                                                                                                              |       |       | Off (0)       |       |       | RW   | Bit |    |    |    | US |
| 4.20.029  | Output assembly object consistency trigger parameter | 0.00.000 to 4.99.999                                                                                                                                                           |       |       | 0.00.000      |       |       | RW   | SMP |    |    |    | US |
| 4.20.030  | Custom Vendor ID                                     | 257 - CT (0), 553 - CT AMERICA (1)                                                                                                                                             |       |       | 257 - CT (0)  |       |       | RW   | Txt |    |    |    | US |
| 4.20.031  | Custom product code                                  | 0 to 65535                                                                                                                                                                     |       |       | 0             |       |       | RW   | Num |    |    |    | US |
| 4.20.032  | Custom product revision code                         | 0 to 65535                                                                                                                                                                     |       |       | 0             |       |       | RW   | Num |    |    |    | US |
| 4.20.033  | Actual Product Code                                  | 0 to 65535                                                                                                                                                                     |       |       |               |       |       | RO   | Num | ND | NC | PT |    |
| 4.20.034  | Actual Product Revision                              | 0 to 65535                                                                                                                                                                     |       |       |               |       |       | RO   | Num | ND | NC | PT |    |
| 4.20.040  | Type of Motor 1                                      | 2-FC DC (0), 6-WRI (1), 7-SCI (2), 9-Sin PM BL (3), 10-Trap PM BL (4)                                                                                                          |       |       |               |       |       | RO   | Txt |    |    | PT | US |
| 4.20.041  | Type of Motor 2                                      | 2-FC DC (0), 6-WRI (1), 7-SCI (2), 9-Sin PM BL (3), 10-Trap PM BL (4)                                                                                                          |       |       |               |       |       | RO   | Txt |    |    | PT | US |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

\* This feature is not currently supported

## 12.31 Slot 4 Menu 21: EtherNet/IP In Mappings (*Unidrive M700 / M702*)

| Parameter |                            | Range                |       |       | Default  |       |       | Type |     |  |  |    |    |
|-----------|----------------------------|----------------------|-------|-------|----------|-------|-------|------|-----|--|--|----|----|
|           |                            | OL                   | RFC-A | RFC-S | OL       | RFC-A | RFC-S |      |     |  |  |    |    |
| 4.21.001  | Input Mapping Parameter 1  | 0.00.000 to 4.99.999 |       |       | 0.10.040 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.002  | Input Mapping Parameter 2  | 0.00.000 to 4.99.999 |       |       | 0.02.001 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.003  | Input Mapping Parameter 3  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.004  | Input Mapping Parameter 4  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.005  | Input Mapping Parameter 5  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.006  | Input Mapping Parameter 6  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.007  | Input Mapping Parameter 7  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.008  | Input Mapping Parameter 8  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.009  | Input Mapping Parameter 9  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.010  | Input Mapping Parameter 10 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.011  | Input Mapping Parameter 11 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.012  | Input Mapping Parameter 12 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.013  | Input Mapping Parameter 13 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.014  | Input Mapping Parameter 14 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.015  | Input Mapping Parameter 15 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.016  | Input Mapping Parameter 16 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.017  | Input Mapping Parameter 17 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.018  | Input Mapping Parameter 18 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.019  | Input Mapping Parameter 19 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.020  | Input Mapping Parameter 20 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.021  | Input Mapping Parameter 21 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.022  | Input Mapping Parameter 22 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.023  | Input Mapping Parameter 23 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.024  | Input Mapping Parameter 24 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.025  | Input Mapping Parameter 25 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.026  | Input Mapping Parameter 26 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.027  | Input Mapping Parameter 27 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.028  | Input Mapping Parameter 28 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.029  | Input Mapping Parameter 29 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.030  | Input Mapping Parameter 30 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.031  | Input Mapping Parameter 31 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.21.032  | Input Mapping Parameter 32 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | Fl  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

## 12.32 Slot 4 Menu 22: EtherNet/IP Out Mappings (*Unidrive M700 / M702*)

| Parameter |                             | Range                |       |       | Default  |       |       | Type |     |  |  |    |    |
|-----------|-----------------------------|----------------------|-------|-------|----------|-------|-------|------|-----|--|--|----|----|
|           |                             | OL                   | RFC-A | RFC-S | OL       | RFC-A | RFC-S |      |     |  |  |    |    |
| 4.22.001  | Output Mapping Parameter 1  | 0.00.000 to 4.99.999 |       |       | 0.06.042 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.002  | Output Mapping Parameter 2  | 0.00.000 to 4.99.999 |       |       | 0.01.021 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.003  | Output Mapping Parameter 3  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.004  | Output Mapping Parameter 4  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.005  | Output Mapping Parameter 5  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.006  | Output Mapping Parameter 6  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.007  | Output Mapping Parameter 7  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.008  | Output Mapping Parameter 8  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.009  | Output Mapping Parameter 9  | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.010  | Output Mapping Parameter 10 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.011  | Output Mapping Parameter 11 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.012  | Output Mapping Parameter 12 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.013  | Output Mapping Parameter 13 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.014  | Output Mapping Parameter 14 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.015  | Output Mapping Parameter 15 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.016  | Output Mapping Parameter 16 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.017  | Output Mapping Parameter 17 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.018  | Output Mapping Parameter 18 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.019  | Output Mapping Parameter 19 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.020  | Output Mapping Parameter 20 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.021  | Output Mapping Parameter 21 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.022  | Output Mapping Parameter 22 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.023  | Output Mapping Parameter 23 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.024  | Output Mapping Parameter 24 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.025  | Output Mapping Parameter 25 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.026  | Output Mapping Parameter 26 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.027  | Output Mapping Parameter 27 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.028  | Output Mapping Parameter 28 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.029  | Output Mapping Parameter 29 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.030  | Output Mapping Parameter 30 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.031  | Output Mapping Parameter 31 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |
| 4.22.032  | Output Mapping Parameter 32 | 0.00.000 to 4.99.999 |       |       | 0.00.000 |       |       | RW   | SMP |  |  | PT | US |

|    |                  |     |             |      |                     |      |                  |     |                     |     |                     |     |                |
|----|------------------|-----|-------------|------|---------------------|------|------------------|-----|---------------------|-----|---------------------|-----|----------------|
| RW | Read / Write     | RO  | Read only   | Num  | Number parameter    | Bit  | Bit parameter    | Txt | Text string         | Bin | Binary parameter    | FI  | Filtered       |
| ND | No default value | NC  | Not copied  | PT   | Protected parameter | RA   | Rating dependent | US  | User save           | PS  | Power-down save     | DE  | Destination    |
| IP | IP address       | Mac | Mac address | Date | Date parameter      | Time | Time parameter   | SMP | Slot,menu,parameter | Chr | Character parameter | Ver | Version number |

## 12.33 Slot 4 Menu 23: EtherNet/IP Fault Values (*Unidrive M700 / M702*)

| Parameter |                       | Range                     |       |       | Default |       |       | Type |     |  |  |    |    |
|-----------|-----------------------|---------------------------|-------|-------|---------|-------|-------|------|-----|--|--|----|----|
|           |                       | OL                        | RFC-A | RFC-S | OL      | RFC-A | RFC-S |      |     |  |  |    |    |
| 4.23.001  | Output Fault Value 1  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.002  | Output Fault Value 2  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.003  | Output Fault Value 3  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.004  | Output Fault Value 4  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.005  | Output Fault Value 5  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.006  | Output Fault Value 6  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.007  | Output Fault Value 7  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.008  | Output Fault Value 8  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.009  | Output Fault Value 9  | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.010  | Output Fault Value 10 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.011  | Output Fault Value 11 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.012  | Output Fault Value 12 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.013  | Output Fault Value 13 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.014  | Output Fault Value 14 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.015  | Output Fault Value 15 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.016  | Output Fault Value 16 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.017  | Output Fault Value 17 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.018  | Output Fault Value 18 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.019  | Output Fault Value 19 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.020  | Output Fault Value 20 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.021  | Output Fault Value 21 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.022  | Output Fault Value 22 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.023  | Output Fault Value 23 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.024  | Output Fault Value 24 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.025  | Output Fault Value 25 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.026  | Output Fault Value 26 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.027  | Output Fault Value 27 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.028  | Output Fault Value 28 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.029  | Output Fault Value 29 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.030  | Output Fault Value 30 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.031  | Output Fault Value 31 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |
| 4.23.032  | Output Fault Value 32 | -2147483648 to 2147483647 |       |       | 0       |       |       | RW   | Num |  |  | PT | US |

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | Fl | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

12.34 Slot 4 Menu 24: Profinet Set-up (*Unidrive M700 / M702*)

| Parameter |                                     | Range                                                                                                               |       |       | Default       |       |       | Type |      |    |    |    |    |
|-----------|-------------------------------------|---------------------------------------------------------------------------------------------------------------------|-------|-------|---------------|-------|-------|------|------|----|----|----|----|
|           |                                     | OL                                                                                                                  | RFC-A | RFC-S | OL            | RFC-A | RFC-S |      |      |    |    |    |    |
| 4.24.001  | Enable Profinet Interface           | Off (0) or On (1)                                                                                                   |       |       | On (1)        |       |       | RW   | Bit  |    |    |    | US |
| 4.24.002  | Reset Profinet                      | Off (0) or On (1)                                                                                                   |       |       | Off (0)       |       |       | RW   | Bit  |    | NC |    |    |
| 4.24.003  | Profinet Default                    | Off (0) or On (1)                                                                                                   |       |       | Off (0)       |       |       | RW   | Bit  |    | NC |    |    |
| 4.24.004  | Configuration Error                 | No Error (0), Input Mapping (1), Output Mapping (2), Data Size (3), Param Config (4)                                |       |       |               |       |       | RO   | Txt  |    | NC | PT |    |
| 4.24.005  | Cyclic data transfers per second    | o to 65535 Messages/s                                                                                               |       |       |               |       |       | RO   | Num  | ND | NC | PT |    |
| 4.24.006  | Revision Counter                    | 0 to 65535                                                                                                          |       |       |               |       |       | RO   | Num  | ND |    | PT |    |
| 4.24.007  | Profile ID                          | 0 to 65535                                                                                                          |       |       | 62976         |       |       | RO   | Num  |    |    | PT |    |
| 4.24.008  | Installation Date                   | 00-00-00 to 31-12-99                                                                                                |       |       |               |       |       | RO   | Date | ND |    | PT |    |
| 4.24.009  | Profinet Timeout Value              | 0 to 10000                                                                                                          |       |       | 100           |       |       | RO   | Num  |    |    | PT |    |
| 4.24.010  | Profinet Timeout Action             | Trip (0), Reserved (1), Clear output (2), Hold last (3), No Action (4)                                              |       |       | No Action (4) |       |       | RW   | Txt  |    |    | PT | US |
| 4.24.011  | Timeout Event Destination*          | This slot (0), Slot 1 (1), Slot 2 (2), Slot 3 (3), Slot 4 (4)                                                       |       |       | This slot (0) |       |       | RW   | Txt  |    |    | PT | US |
| 4.24.012  | Profinet Timeout Event Type*        | No Event (0), Trigger Event (1), Trigger Event 1 (2), Trigger Event 2 (3), Trigger Event 3 (4), Trigger Event 4 (5) |       |       | No Event (0)  |       |       | RW   | Txt  |    |    | PT | US |
| 4.23.026  | Profinet Input Consistency Enable   | Off (0) or On (1)                                                                                                   |       |       | Off (0)       |       |       | RW   | Bit  |    |    |    | US |
| 4.23.027  | Profinet Input Consistency Trigger  | 0 to 499999                                                                                                         |       |       | 0             |       |       | RW   | SMP  |    |    |    | US |
| 4.23.028  | Profinet Output Consistency Enable  | Off (0) or On (1)                                                                                                   |       |       | Off (0)       |       |       | RW   | Bit  |    |    |    | US |
| 4.24.029  | Profinet Output Consistency Trigger | 0 to 499999                                                                                                         |       |       | 0             |       |       | RW   | SMP  |    |    |    | US |

|    |                  |    |            |     |                     |     |                  |     |             |     |                  |    |             |
|----|------------------|----|------------|-----|---------------------|-----|------------------|-----|-------------|-----|------------------|----|-------------|
| RW | Read / Write     | RO | Read only  | Num | Number parameter    | Bit | Bit parameter    | Txt | Text string | Bin | Binary parameter | FI | Filtered    |
| ND | No default value | NC | Not copied | PT  | Protected parameter | RA  | Rating dependent | US  | User save   | PS  | Power-down save  | DE | Destination |

\* This feature is not currently supported

## 13 Diagnostics

The keypad display on the drive gives various information about the status of the drive. The keypad display provides information on the following categories:

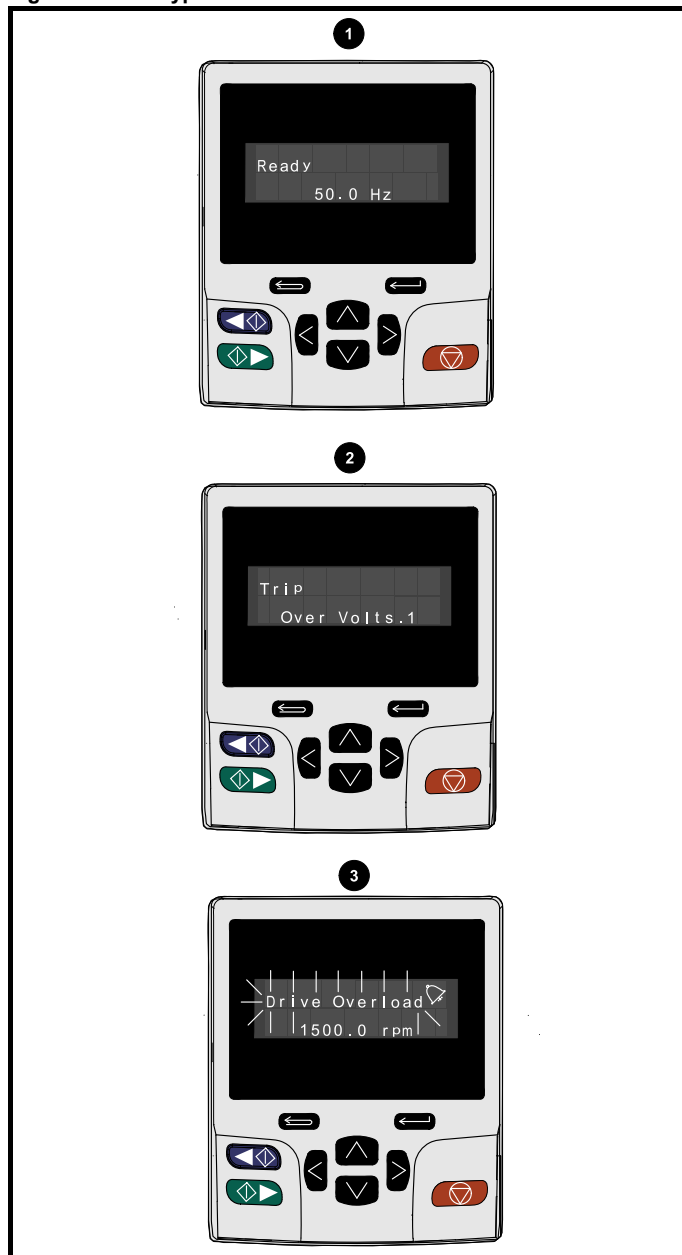
- Trip indications
- Alarm indications
- Status indications



Users must not attempt to repair a drive if it is faulty, nor carry out fault diagnosis other than through the use of the diagnostic features described in this chapter. If a drive is faulty, it must be returned to an authorized Control Techniques distributor for repair.

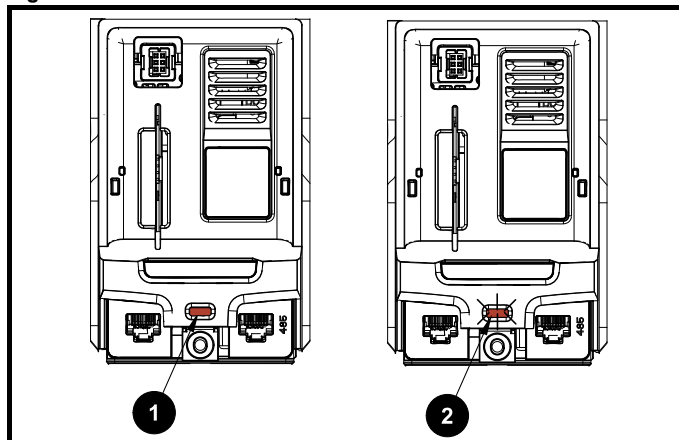
### 13.1 Status modes (Keypad and LED status)

Figure 13-1 Keypad status modes



1. Drive OK status
2. Trip status
3. Alarm status

Figure 13-2 Location of the status LED

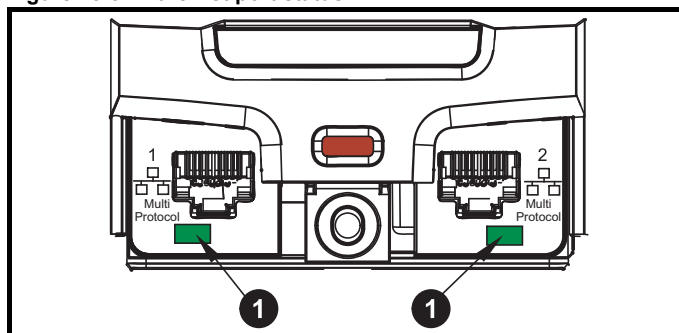


1. Non flashing: Normal status
2. Flashing: Trip status

#### 13.1.1 Unidrive M700 / M702 Ethernet status LED

Each of the Ethernet ports provide a status LED for diagnostic and information purposes. Refer to Table 13-1 for Ethernet LED status.

Figure 13-3 Ethernet port status LED



1. Ethernet port status LED.

Table 13-1 Ethernet LED status

| LED status     | Description                                |
|----------------|--------------------------------------------|
| Off            | Ethernet connection not detected           |
| Solid green    | Ethernet connection detected but no data   |
| Flashing green | Ethernet connection detected and data flow |

### 13.2 Trip indications

The output of the drive is disabled under any trip condition so that the drive stops controlling the motor. If the motor is running when the trip occurs it will coast to a stop.

During a trip condition, where a KI-Keypad is being used, the upper row of the display indicates that a trip has occurred and the lower row of the keypad display will display the trip string. Some trips have a sub-trip number to provide additional information about the trip. If a trip has a sub-trip number, the sub-trip number is flashed alternately with the trip string unless there is space on the second row for both the trip string and the sub-trip number in which case both the trip string and sub-trip information is displayed separated by a decimal place.

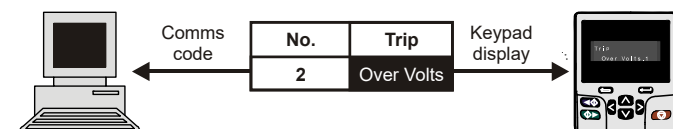
The back-light of the KI-Keypad display will also flash during a trip condition. If a display is not being used, the drive LED Status indicator will flash with 0.5 s duty cycle if the drive has tripped. Refer to Figure 13-2.

Trips are listed alphabetically in Table 13-4 based on the trip indication shown on the drive display. Alternatively, the drive status can be read in Pr 10.001 'Drive OK' using communication protocols. The most recent trip can be read in Pr 10.020 providing a trip number. It must be noted that the hardware trips (HF01 to HF20) do not have trip numbers. The

trip number must be checked in Table 13-5 to identify the specific trip.

### Example

1. Trip code 2 is read from Pr 10.020 via serial communications.
2. Checking Table 13-4 shows Trip 2 is an Over Volts trip.



3. Look up Over Volts in Table 13-4.
4. Perform checks detailed under *Diagnosis*.

## 13.3 Identifying a trip / trip source

Some trips only contain a trip string whereas some other trips have a trip string along with a sub-trip number which provides the user with additional information about the trip.

A trip can be generated from a control system or from a power system. The sub-trip number associated with the trips listed in Table 13-2 is in the form xxyzz and used to identify the source of the trip.

**Table 13-2 Trips associated with xxyzz sub-trip number**

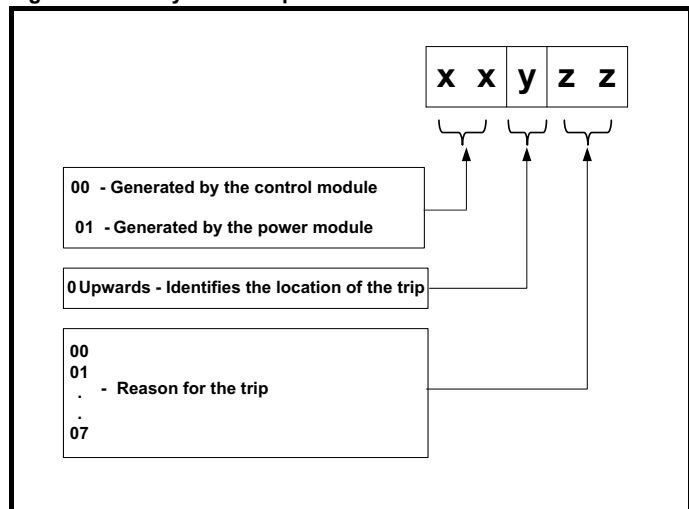
|              |               |
|--------------|---------------|
| Over Volts   | Oht dc bus    |
| OI ac        | Phase Loss    |
| OI Brake     | Power Comms   |
| PSU          | OI Snubber    |
| Oht Inverter | Temp Feedback |
| Oht Power    | Power Data    |
| Oht Control  |               |

The digits xx are 00 for a trip generated by the control system. For a single drive (not part of a multi-power module drive), if the trip is related to the power system then xx will have a value of 01, when displayed the leading zeros are suppressed.

The y digit is used to identify the location of a trip which is generated by a rectifier module connected to a power module (if xx is non zero). For a control system trip (xx is zero), the y digit, where relevant is defined for each trip. If not relevant, the y digit will have a value of zero.

The zz digits give the reason for the trip and are defined in each trip description.

**Figure 13-4 Key to sub-trip number**



For example, if the drive has tripped and the lower line of the display shows 'Oht Control.2', with the help of Table 13-3 below the trip can be interpreted as; an over temperature has been detected; the trip was generated by fault in the control module, the control board thermistor 2 over temperature. For further information on individual sub-trips, refer to the diagnosis column in Table 13-4.

**Table 13-3 Sub-trip identification**

| Source         | xx | y | zz | Description                                 |
|----------------|----|---|----|---------------------------------------------|
| Control system | 00 | 0 | 01 | Control board thermistor 1 over temperature |
| Control system | 00 | 0 | 02 | Control board thermistor 2 over temperature |
| Control system | 00 | 0 | 03 | Control board thermistor 3 over temperature |

## 13.4 Trips, Sub-trip numbers

Table 13-4 Trip indications

| Trip                    | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |          |        |   |                              |   |                               |   |         |
|-------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|--------|---|------------------------------|---|-------------------------------|---|---------|
| <b>An Input 1 Loss</b>  | <b>Analog input 1 current loss (<i>Unidrive M700 / M701</i>)</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                              |   |                               |   |         |
| 28                      | <p><i>An Input 1 Loss</i> trip indicates that a current loss was detected in current mode on Analog input 1 (Terminal 5, 6). In 4-20 mA and 20-4 mA modes loss of input is detected if the current falls below 3 mA.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check control wiring is correct</li> <li>Check control wiring is undamaged</li> <li>Check the <i>Analog Input 1 Mode</i> (07.007)</li> <li>Current signal is present and greater than 3 mA</li> </ul>                                                                                                                                                                                                                                                                                                                               |          |        |   |                              |   |                               |   |         |
| <b>An Input 2 Loss</b>  | <b>Analog input 2 current loss (<i>Unidrive M700 / M701</i>)</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                              |   |                               |   |         |
| 29                      | <p><i>An Input 2 Loss</i> indicates that a current loss was detected in current mode on Analog input 2 (Terminal 7). In 4-20 mA and 20-4 mA modes loss of input is detected if the current falls below 3 mA.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check control wiring is correct</li> <li>Check control wiring is undamaged</li> <li>Check the <i>Analog Input 2 Mode</i> (07.011)</li> <li>Current signal is present and greater than 3 mA</li> </ul>                                                                                                                                                                                                                                                                                                                                       |          |        |   |                              |   |                               |   |         |
| <b>An Output Calib</b>  | <b>Analog output calibration failed (<i>Unidrive M700 / M701</i>)</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                              |   |                               |   |         |
| 219                     | <p>The zero offset calibration of one or both of the analog outputs has failed. This indicates that the drive hardware has failed or a voltage is applied to the output via a low impedance, possibly due to a wiring error. The failed output can be identified by the sub-trip number.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>Output 1 failed (Terminal 9)</td></tr> <tr> <td>2</td><td>Output 2 failed (Terminal 10)</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check the wiring associated with analog outputs</li> <li>Remove all the wiring that is connected to analog outputs and perform a re-calibration by power cycling the drive</li> <li>If trip persists replace the drive</li> </ul> | Sub-trip | Reason | 1 | Output 1 failed (Terminal 9) | 2 | Output 2 failed (Terminal 10) |   |         |
| Sub-trip                | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |        |   |                              |   |                               |   |         |
| 1                       | Output 1 failed (Terminal 9)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |          |        |   |                              |   |                               |   |         |
| 2                       | Output 2 failed (Terminal 10)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |          |        |   |                              |   |                               |   |         |
| <b>App Menu Changed</b> | <b>Customization table for an application module has changed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                              |   |                               |   |         |
| 217                     | <p>The <i>App Menu Changed</i> trip indicates that the customization table for an application menu has changed. The menu that has been changed can be identified by the sub-trip number.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>Menu 18</td></tr> <tr> <td>2</td><td>Menu 19</td></tr> <tr> <td>3</td><td>Menu 20</td></tr> </tbody> </table> <p>If more than one menu has changed the lowest menu has priority. Drive user parameters must be saved to prevent this trip on the next power-up.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Reset the trip and perform a parameter save to accept the new settings</li> </ul>                                                                                                 | Sub-trip | Reason | 1 | Menu 18                      | 2 | Menu 19                       | 3 | Menu 20 |
| Sub-trip                | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |        |   |                              |   |                               |   |         |
| 1                       | Menu 18                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                              |   |                               |   |         |
| 2                       | Menu 19                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                              |   |                               |   |         |
| 3                       | Menu 20                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                              |   |                               |   |         |

| Trip              | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                                                                                                  |                                                                                                                                                                                                |
|-------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Autotune 1</b> | <b>Position feedback did not change or required speed could not be reached</b>                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                  |                                                                                                                                                                                                |
| 11                | The drive has tripped during an autotune. The cause of the trip can be identified from the sub-trip number.                                                                                                                                                                                                                                                                                                                                                               |                                                                                                                                                                  |                                                                                                                                                                                                |
|                   | <b>Sub-trip</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                           | <b>Reason</b>                                                                                                                                                    | <b>Recommended actions</b>                                                                                                                                                                     |
|                   | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The position feedback did not change when position feedback is being used during rotating auto-tune.                                                             | Ensure that the motor is free to turn (i.e. mechanical brake is released).<br>Check that the position feedback is selected correctly and operates correctly.                                   |
|                   | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The motor did not reach the required speed during mechanical load measurement.                                                                                   | Ensure that the motor is free to turn and that the static load plus inertia is not too large for the drive to accelerate within the test time.                                                 |
|                   | 3                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The required commutation signal edge could not be found during a rotating auto-tune with a Commutation Only position feedback device.                            | Check that the position feedback signals are connected correctly.                                                                                                                              |
|                   | 4                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The required movement angle cannot be produced during a minimal movement test.                                                                                   | Reduce the angular movement required.                                                                                                                                                          |
|                   | 5                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The second part of the minimal movement test during auto-tuning cannot locate the motor flux position accurately.                                                | Reduce the angular movement required.                                                                                                                                                          |
|                   | 6                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The phasing offset angle is measured twice during a stationary auto-tune and the results are not within 30° of each other.                                       | If a minimal movement test is being used and excessive motor movement is occurring during the test reduce the required angle movement. Otherwise try and increase the required angle movement. |
|                   | 7                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The motor is moving when a phasing test on enable is selected and the drive is enabled, but the motor is still moving at a speed above the zero speed threshold. | Ensure that the motor is stationary before the drive is enabled.                                                                                                                               |
|                   | <b>Recommended actions:</b> <ul style="list-style-type: none"> <li>• Ensure the motor is free to turn i.e. mechanical brake was released</li> <li>• Ensure Pr <b>03.026</b> and Pr <b>03.038</b> are set correctly (or appropriate 2<sup>nd</sup> motor map parameters)</li> <li>• Check feedback device wiring is correct</li> <li>• Check encoder mechanical coupling to the motor</li> </ul>                                                                           |                                                                                                                                                                  |                                                                                                                                                                                                |
| <b>Autotune 2</b> | <b>Position feedback direction incorrect</b>                                                                                                                                                                                                                                                                                                                                                                                                                              |                                                                                                                                                                  |                                                                                                                                                                                                |
| 12                | The drive has tripped during a rotating autotune. The cause of the trip can be identified from the associated sub-trip number.                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                  |                                                                                                                                                                                                |
|                   | <b>Sub-trip</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                           | <b>Reason</b>                                                                                                                                                    |                                                                                                                                                                                                |
|                   | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The position feedback direction is incorrect when position feedback is being used during a rotating autotune                                                     |                                                                                                                                                                                                |
|                   | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | A SINCOS encoder with comms is being used for position feedback and the comms position is rotating in the opposite direction to the sine wave based position.    |                                                                                                                                                                                                |
|                   | <b>Recommended actions:</b> <ul style="list-style-type: none"> <li>• Check motor cable wiring is correct</li> <li>• Check feedback device wiring is correct</li> <li>• Swap any two motor phases</li> </ul>                                                                                                                                                                                                                                                               |                                                                                                                                                                  |                                                                                                                                                                                                |
| <b>Autotune 3</b> | <b>Measured inertia has exceeded the parameter range or commutation signals changed in wrong direction</b>                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                  |                                                                                                                                                                                                |
| 13                | The drive has tripped during a rotating autotune or mechanical load measurement test. The cause of the trip can be identified from the associated sub-trip number.                                                                                                                                                                                                                                                                                                        |                                                                                                                                                                  |                                                                                                                                                                                                |
|                   | <b>Sub-trip</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                           | <b>Reason</b>                                                                                                                                                    |                                                                                                                                                                                                |
|                   | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | Measured inertia has exceeded the parameter range during a mechanical load measurement                                                                           |                                                                                                                                                                                                |
|                   | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The commutation signals changed in the wrong direction during a rotating autotune                                                                                |                                                                                                                                                                                                |
|                   | 3                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | The mechanical load test has been unable to identify the motor inertia.                                                                                          |                                                                                                                                                                                                |
|                   | <b>Recommended actions for sub-trip 2:</b> <ul style="list-style-type: none"> <li>• Check motor cable wiring is correct</li> <li>• Check feedback device U,V and W commutation signal wiring is correct</li> </ul> <b>Recommended actions for sub-trip 3:</b> <ul style="list-style-type: none"> <li>• Increase the test level</li> <li>• If the test was carried out at standstill repeat the test with the motor rotating within the recommended speed range</li> </ul> |                                                                                                                                                                  |                                                                                                                                                                                                |

| Trip                    | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
|-------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|--------|---|---------------------------------------------------------------------------------------------------------------------------------------|---|-----------------------------------------------------------------------------|---|-------------------------------------------------------------------------|---|-----------------------------------------------------------------------------------------------------------------------|
| <b>Autotune 4</b>       | <b>Drive encoder U commutation signal fail</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 14                      | <p>A position feedback device with commutation signals is being used (i.e. AB Servo, FD Servo, FR Servo, SC Servo, or Commutations only encoder) and the U commutation signal did not change during a rotating autotune.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check feedback device U commutation signal wiring is correct (Encoder terminals 7 and 8)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| <b>Autotune 5</b>       | <b>Drive encoder V commutation signal fail</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 15                      | <p>A position feedback device with commutation signals is being used (i.e. AB Servo, FD Servo, FR Servo, SC Servo, or Commutations only encoder) and the V commutation signal did not change during a rotating autotune.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check feedback device V commutation signal wiring is correct (Encoder terminals 9 and 10)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| <b>Autotune 6</b>       | <b>Drive encoder W commutation signal fail</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 16                      | <p>A position feedback device with commutation signals is being used (i.e. AB Servo, FD Servo, FR Servo, SC Servo, or Commutations only encoder) and the W commutation signal did not change during a rotating autotune.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check feedback device W commutation signal wiring is correct (Encoder terminals 11 and 12)</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| <b>Autotune 7</b>       | <b>Motor number of poles / position feedback resolution set incorrectly</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 17                      | <p>An <i>Autotune 7</i> trip is initiated during a rotating autotune, if the motor poles or the position feedback resolution have been set up incorrectly where position feedback is being used.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check line per revolution for feedback device</li> <li>Check the number of poles in Pr <b>05.011</b></li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| <b>Autotune Stopped</b> | <b>Autotune test stopped before completion</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 18                      | <p>The drive was prevented from completing an autotune test, because either the drive enable or the drive run were removed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check the drive enable signal (terminal 31 on <i>Unidrive M700 / M701</i> and terminal 11 &amp; 13 on <i>Unidrive M702</i>) was active during the autotune</li> <li>Check the run command was active in Pr <b>08.005</b> during autotune</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                 |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| <b>Brake R Too Hot</b>  | <b>Braking resistor overload timed out (I<sup>2</sup>t)</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 19                      | <p>The <i>Brake R Too Hot</i> indicates that braking resistor overload has timed out. The value in <i>Braking Resistor Thermal Accumulator</i> (10.039) is calculated using <i>Braking Resistor Rated Power</i> (10.030), <i>Braking Resistor Thermal Time Constant</i> (10.031) and <i>Braking Resistor Resistance</i> (10.061). The <i>Brake R Too Hot</i> trip is initiated when <i>Braking Resistor Thermal Accumulator</i> (10.039) reaches 100 %.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure the values entered in Pr <b>10.030</b>, Pr <b>10.031</b> and Pr <b>10.061</b> are correct</li> <li>If an external thermal protection device is being used and the braking resistor software overload protection is not required, set Pr <b>10.030</b>, Pr <b>10.031</b> or Pr <b>10.061</b> to 0 to disable the trip.</li> </ul> |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| <b>CAM</b>              | <b>Advanced motion controller CAM failure</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 99                      | <p>The CAM trip indicates that the advanced motion controller CAM has detected a problem.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>AMC Cam Start Index (35.001) &gt; AMC Cam Size (35.003) or AMC Cam Start Position In Segment (35.002) &gt; Cam Table In for the start index</td></tr> <tr> <td>2</td><td>AMC CAM Index (35.007) has been made to change by more than 2 in one sample</td></tr> <tr> <td>3</td><td>The rate of change at a segment boundary has exceeded the maximum value</td></tr> <tr> <td>4</td><td>The sum of the AMC Cam Position In Segment (35.008) and the change of master position has exceeded the maximum value.</td></tr> </tbody> </table>                                                                                                                              | Sub-trip | Reason | 1 | AMC Cam Start Index (35.001) > AMC Cam Size (35.003) or AMC Cam Start Position In Segment (35.002) > Cam Table In for the start index | 2 | AMC CAM Index (35.007) has been made to change by more than 2 in one sample | 3 | The rate of change at a segment boundary has exceeded the maximum value | 4 | The sum of the AMC Cam Position In Segment (35.008) and the change of master position has exceeded the maximum value. |
| Sub-trip                | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 1                       | AMC Cam Start Index (35.001) > AMC Cam Size (35.003) or AMC Cam Start Position In Segment (35.002) > Cam Table In for the start index                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 2                       | AMC CAM Index (35.007) has been made to change by more than 2 in one sample                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 3                       | The rate of change at a segment boundary has exceeded the maximum value                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 4                       | The sum of the AMC Cam Position In Segment (35.008) and the change of master position has exceeded the maximum value.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| <b>Card Access</b>      | <b>NV Media Card Write fail</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |
| 185                     | <p>The <i>Card Access</i> trip indicates that the drive was unable to access the NV Media Card. If the trip occurs during the data transfer to the card then the file being written may be corrupted. If the trip occurs when the data being transferred to the drive then the data transfer may be incomplete. If a parameter file is transferred to the drive and this trip occurs during the transfer, the parameters are not saved to non-volatile memory, and so the original parameters can be restored by powering the drive down and up again.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check NV Media Card is installed / located correctly</li> <li>Replace the NV Media Card</li> </ul>                                                                                                                                       |          |        |   |                                                                                                                                       |   |                                                                             |   |                                                                         |   |                                                                                                                       |

| Trip                    | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |        |   |                                                       |   |                              |   |                                                                                   |
|-------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|--------|---|-------------------------------------------------------|---|------------------------------|---|-----------------------------------------------------------------------------------|
| <b>Card Boot</b>        | <b>The Menu 0 parameter modification cannot be saved to the NV Media Card</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |          |        |   |                                                       |   |                              |   |                                                                                   |
| 177                     | <p>Menu 0 changes are automatically saved on exiting edit mode.</p> <p>The <i>Card Boot</i> trip will occur if a write to a Menu 0 parameter has been initiated via the keypad by exiting edit mode and Pr <b>11.042</b> is set for auto or boot mode, but the necessary boot file has not been created on the NV Media Card to take the new parameter value. This occurs when Pr <b>11.042</b> is changed to Auto (3) or Boot (4) mode, but the drive is not subsequently reset. The action of resetting the trip will create the necessary file and prevent further trips.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure that Pr <b>11.042</b> is correctly set, and then reset the drive to create the necessary file on the NV Media Card</li> <li>Re-attempt the parameter write to the Menu 0 parameter</li> </ul>                                                                      |          |        |   |                                                       |   |                              |   |                                                                                   |
| <b>Card Busy</b>        | <b>NV Media Card cannot be accessed as it is being accessed by an option module</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                       |   |                              |   |                                                                                   |
| 178                     | <p>The <i>Card Busy</i> trip indicates that an attempt has been made to access a file on NV Media Card, but the NV Media Card is already being accessed by an Option Module, such as one of the Applications modules. No data is transferred.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Wait for the option module to finish accessing the NV Media Card and re-attempt the required function</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |          |        |   |                                                       |   |                              |   |                                                                                   |
| <b>Card Compare</b>     | <b>NV Media Card file/data is different to the one in the drive</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                       |   |                              |   |                                                                                   |
| 188                     | <p>A compare has been carried out between a file on the NV Media Card and the drive. A Card Compare trip is initiated if the parameters on the NV Media Card are different to the drive.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Set Pr <b>mm.000</b> to 0 and reset the trip</li> <li>Check to ensure the correct data block on the NV Media Card has been used for the compare.</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                       |   |                              |   |                                                                                   |
| <b>Card Data Exists</b> | <b>NV Media Card data location already contains data</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                                       |   |                              |   |                                                                                   |
| 179                     | <p>The <i>Card Data Exists</i> trip indicates that an attempt has been made to store data on a NV Media Card in a data block which already contains data. No data is transferred. The data should be erased from the card first to prevent this trip.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Erase the data in data location</li> <li>Write data to an alternative data location</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                       |   |                              |   |                                                                                   |
| <b>Card Drive Mode</b>  | <b>NV Media Card parameter set not compatible with current drive mode</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |        |   |                                                       |   |                              |   |                                                                                   |
| 187                     | <p>The <i>Card Drive Mode</i> trip is produced during a compare if the drive mode in the data block on the NV Media Card is different from the current drive mode. This trip is also produced if an attempt is made to transfer parameters from a NV Media Card to the drive if the operating mode in the data block is outside the allowed range of operating modes.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure the destination drive supports the drive operating mode in the parameter file.</li> <li>Clear the value in Pr <b>mm.000</b> and reset the drive</li> <li>Ensure destination drive operating mode is the same as the source parameter file</li> </ul>                                                                                                                                                                                                                      |          |        |   |                                                       |   |                              |   |                                                                                   |
| <b>Card Error</b>       | <b>NV Media Card data structure error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |        |   |                                                       |   |                              |   |                                                                                   |
| 182                     | <p>The <i>Card Error</i> trip indicates that an attempt has been made to access a NV Media Card but an error has been detected in the data structure on the card. Resetting the trip will cause the drive to erase and create the correct folder structure. The cause of the trip can be identified by the sub-trip.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>The required folder and file structure is not present</td></tr> <tr> <td>2</td><td>The &lt;000&gt; file is corrupted.</td></tr> <tr> <td>3</td><td>Two or more files in the &lt;MCDF\&gt; folder have the same file identification number.</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Erase all the data blocks and re-attempt the process</li> <li>Ensure the card is located correctly</li> <li>Replace the NV Media Card</li> </ul> | Sub-trip | Reason | 1 | The required folder and file structure is not present | 2 | The <000> file is corrupted. | 3 | Two or more files in the <MCDF\> folder have the same file identification number. |
| Sub-trip                | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                                       |   |                              |   |                                                                                   |
| 1                       | The required folder and file structure is not present                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                       |   |                              |   |                                                                                   |
| 2                       | The <000> file is corrupted.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |          |        |   |                                                       |   |                              |   |                                                                                   |
| 3                       | Two or more files in the <MCDF\> folder have the same file identification number.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                                       |   |                              |   |                                                                                   |
| <b>Card Full</b>        | <b>NV Media Card full</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |        |   |                                                       |   |                              |   |                                                                                   |
| 184                     | <p>The <i>Card Full</i> trip indicates that an attempt has been made to create a data block on a NV Media Card, but there is not enough space left on the card.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Delete a data block or the entire NV Media Card to create space</li> <li>Use a different NV Media Card</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |          |        |   |                                                       |   |                              |   |                                                                                   |
| <b>Card No Data</b>     | <b>NV Media Card data not found</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                       |   |                              |   |                                                                                   |
| 183                     | <p>The <i>Card No Data</i> trip indicates that an attempt has been made to access non-existent file or block on a NV Media Card. No data is transferred.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure data block number is correct</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                       |   |                              |   |                                                                                   |

| Trip                  | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
|-----------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|--------|---|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Card Option</b>    | <b>NV Media Card trip; option modules installed are different between source drive and destination drive</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>180</b>            | <p>The <i>Card Option</i> trip indicates that parameter data or default difference data is being transferred from a NV Media Card to the drive, but the option module categories are different between source and destination drives. This trip does not stop the data transfer, but is a warning that the data for the option modules that are different will be set to the default values and not the values from the card. This trip also applies if a compare is attempted between the data block and the drive.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure the correct option modules are installed.</li> <li>Ensure the option modules are in the same option module slot as the parameter set stored.</li> <li>Press the red reset button to acknowledge that the parameters for one or more of the option modules installed will be at their default values</li> <li>This trip can be suppressed by setting Pr <b>mm.000</b> to 9666 and resetting the drive.</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>Card Product</b>   | <b>NV Media Card data blocks are not compatible with the drive derivative</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>175</b>            | <p>If <i>Drive Derivative</i> (11.028) or <i>Product Type</i> (11.063) are different between the source and target drives then this trip is initiated either at power-up or when the card is accessed. It will have one of the following sub-trip numbers:</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>If <i>Drive Derivative</i> (11.028) is different between the source and target drives, this trip is initiated either at power-up or when the SD Card is accessed. Data is still transferred, since this is a warning trip; the trip can be suppressed by entering code 9666 in parameter xx.000, and resetting the drive (this applies the warning suppression flag to the card).</td></tr> <tr> <td>2</td><td>If <i>Product Type</i> (11.063) is different between the source and target drives or if corruption is detected in the parameter file, this trip is initiated either at power-up or when the SD Card is accessed. This trip can be reset but no data are transferred in either direction between the drive and the card.</td></tr> <tr> <td>3</td><td>A Unidrive SP parameter value was found that has no equivalent parameter on the destination drive. Data is still transferred, since this is a warning trip; the trip can be suppressed by entering code 9666 in Pr <b>xx.000</b>, and resetting the drive (this applies the warning suppression flag to the card).</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Use a different NV Media Card</li> <li>This trip can be suppressed by setting Pr <b>mm.000</b> to 9666 and resetting the drive</li> </ul> | Sub-trip | Reason | 1 | If <i>Drive Derivative</i> (11.028) is different between the source and target drives, this trip is initiated either at power-up or when the SD Card is accessed. Data is still transferred, since this is a warning trip; the trip can be suppressed by entering code 9666 in parameter xx.000, and resetting the drive (this applies the warning suppression flag to the card). | 2 | If <i>Product Type</i> (11.063) is different between the source and target drives or if corruption is detected in the parameter file, this trip is initiated either at power-up or when the SD Card is accessed. This trip can be reset but no data are transferred in either direction between the drive and the card. | 3 | A Unidrive SP parameter value was found that has no equivalent parameter on the destination drive. Data is still transferred, since this is a warning trip; the trip can be suppressed by entering code 9666 in Pr <b>xx.000</b> , and resetting the drive (this applies the warning suppression flag to the card). |
| Sub-trip              | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| 1                     | If <i>Drive Derivative</i> (11.028) is different between the source and target drives, this trip is initiated either at power-up or when the SD Card is accessed. Data is still transferred, since this is a warning trip; the trip can be suppressed by entering code 9666 in parameter xx.000, and resetting the drive (this applies the warning suppression flag to the card).                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| 2                     | If <i>Product Type</i> (11.063) is different between the source and target drives or if corruption is detected in the parameter file, this trip is initiated either at power-up or when the SD Card is accessed. This trip can be reset but no data are transferred in either direction between the drive and the card.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| 3                     | A Unidrive SP parameter value was found that has no equivalent parameter on the destination drive. Data is still transferred, since this is a warning trip; the trip can be suppressed by entering code 9666 in Pr <b>xx.000</b> , and resetting the drive (this applies the warning suppression flag to the card).                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>Card Rating</b>    | <b>NV Media Card Trip; The voltage and / or current rating of the source and destination drives are different</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>186</b>            | <p>The Card Rating trip indicates that parameter data is being transferred from a NV Media Card to the drive, but the current and / or voltage ratings are different between source and destination drives. This trip also applies if a compare (using Pr <b>mm.000</b> set to 8yyy) is attempted between the data block on a NV Media Card and the drive. The Card Rating trip does not stop the data transfer but is a warning that rating specific parameters with the RA attribute may not be transferred to the destination drive.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Reset the drive to clear the trip</li> <li>Ensure that the drive rating dependent parameters have transferred correctly</li> <li>This trip can be suppressed by setting Pr <b>mm.000</b> to 9666 and resetting the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>Card Read Only</b> | <b>NV Media Card has the Read Only bit set</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>181</b>            | <p>The <i>Card Read Only</i> trip indicates that an attempt has been made to modify a read-only NV Media Card or a read-only data block. A NV Media Card is read-only if the read-only flag has been set.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Clear the read only flag by setting Pr <b>mm.000</b> to 9777 and reset the drive. This will clear the read-only flag for all data blocks in the NV Media Card</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>Card Slot</b>      | <b>NV Media Card Trip; Option module application program transfer has failed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |
| <b>174</b>            | <p>The <i>Card Slot</i> trip is initiated, if the transfer of an option module application program to or from an application module failed because the option module does not respond correctly. If this happens this trip is produced with the sub-trip indicating the option module slot number.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure the source / destination option module is installed on the correct slot</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |          |        |   |                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |   |                                                                                                                                                                                                                                                                                                                     |

| Trip                  | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                                                             |   |                                 |   |                                        |
|-----------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|--------|---|-----------------------------------------------------------------------------|---|---------------------------------|---|----------------------------------------|
| <b>Configuration</b>  | <b>The number of power modules installed is different from the modules expected</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |          |        |   |                                                                             |   |                                 |   |                                        |
| 111                   | <p>The <i>Configuration</i> trip indicates that the <i>Number Of Power Modules Detected</i> (11.071) does not match the previous value stored. The sub-trip value indicates the number of power modules expected.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Ensure that all the power modules are correctly connected</li> <li>• Ensure all the power modules have powered up correctly</li> <li>• Ensure that the value in Pr <b>11.071</b> is set to the number of power modules connected</li> <li>• Set Pr <b>11.035</b> to 0 to disable the trip if it is not required</li> </ul> <p>This trip is also initiated if the number of external rectifiers connected to each power module is less than the number defined by <i>Number Of Rectifiers Expected</i> (11.096). If this is the reason for the trip the sub-trip is 10x where x is the number of external rectifiers that should be connected.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Ensure that all the external rectifiers are connected correctly</li> <li>• Ensure that the value in <i>Number Of Rectifiers Expected</i> (11.096) is correct</li> </ul> |          |        |   |                                                                             |   |                                 |   |                                        |
| <b>Control Word</b>   | <b>Trip initiated from the Control Word (06.042)</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                                                             |   |                                 |   |                                        |
| 35                    | <p>The Control Word trip is initiated by setting bit 12 on the control word in Pr <b>06.042</b> when the control word is enabled (Pr <b>06.043</b> = On).</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Check the value of Pr <b>06.042</b>.</li> <li>• Disable the control word in <i>Control Word Enable</i> (Pr <b>06.043</b>) <ul style="list-style-type: none"> <li>Bit 12 of the control word set to a one causes the drive to trip on Control Word</li> <li>When the control word is enabled, the trip can only be cleared by setting bit 12 to zero</li> </ul> </li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                                                             |   |                                 |   |                                        |
| <b>Current Offset</b> | <b>Current feedback offset error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                                                             |   |                                 |   |                                        |
| 225                   | <p>The current feedback offset is too large to be trimmed correctly. The sub-trip relates to the output phase for which the offset error has been detected.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Phase</th></tr> </thead> <tbody> <tr> <td>1</td><td>U</td></tr> <tr> <td>2</td><td>V</td></tr> <tr> <td>3</td><td>W</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Ensure that there is no possibility of current flowing in the output phases of the drive when the drive is not enabled</li> <li>• Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | Sub-trip | Phase  | 1 | U                                                                           | 2 | V                               | 3 | W                                      |
| Sub-trip              | Phase                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                                             |   |                                 |   |                                        |
| 1                     | U                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                                                                             |   |                                 |   |                                        |
| 2                     | V                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                                                                             |   |                                 |   |                                        |
| 3                     | W                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                                                                             |   |                                 |   |                                        |
| <b>Data Changing</b>  | <b>Drive parameters are being changed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                                                             |   |                                 |   |                                        |
| 97                    | <p>A user action or a file system write is active that is changing the drive parameters and the drive has been commanded to enable, i.e. <i>Drive Active</i> (10.002) = 1. The user actions that change drive parameters are loading defaults, changing drive mode, or transferring data from an NV memory card or a position feedback device to the drive. The file system actions that will cause this trip to be initiated if the drive is enabled during the transfer are writing a parameter or macro file to the drive, or transferring a derivative or user program to the drive. It should be noted that none of these actions can be started if the drive is active, and so the trip only occurs if the action is started and then the drive is enabled.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Ensure the drive is not enabled when one of the following is being carried out <ul style="list-style-type: none"> <li>Loading defaults</li> <li>Changing drive mode</li> <li>Transferring data from NV Media Card or position feedback device</li> <li>Transferring user programs</li> </ul> </li> </ul>                                              |          |        |   |                                                                             |   |                                 |   |                                        |
| <b>Derivative ID</b>  | <b>Derivative identification error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                             |   |                                 |   |                                        |
| 247                   | <p>There is a problem with the identifier associated with derivative image which customizes the drive. The reason for the trip is given by the sub-trip as follows:</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>There should be a derivative image in the product but this has been erased.</td></tr> <tr> <td>2</td><td>The identifier is out of range.</td></tr> <tr> <td>3</td><td>The derivative image has been changed.</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <p>Contact the supplier of the drive</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Sub-trip | Reason | 1 | There should be a derivative image in the product but this has been erased. | 2 | The identifier is out of range. | 3 | The derivative image has been changed. |
| Sub-trip              | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                             |   |                                 |   |                                        |
| 1                     | There should be a derivative image in the product but this has been erased.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                                                             |   |                                 |   |                                        |
| 2                     | The identifier is out of range.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |          |        |   |                                                                             |   |                                 |   |                                        |
| 3                     | The derivative image has been changed.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                             |   |                                 |   |                                        |

| Trip             | Diagnosis                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                           |  |
|------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------|--|
| Derivative Image | Derivative Image error                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                           |  |
| 248              | The <i>Derivative Image</i> trip indicates that an error has been detected in the derivative image. The sub-trip number indicates the reason for the trip.                                                                                                                                                                               |                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                           |  |
|                  | Sub-trip                                                                                                                                                                                                                                                                                                                                 | Reason                                                                                                                                                                                                                                                                                                                                                                          | Comments                                                                                  |  |
|                  | 1 to 52                                                                                                                                                                                                                                                                                                                                  | An error has been detected in the derivative image, contact the supplier of the drive.                                                                                                                                                                                                                                                                                          |                                                                                           |  |
|                  | 61                                                                                                                                                                                                                                                                                                                                       | The option module fitted in slot 1 is not allowed with the derivative image                                                                                                                                                                                                                                                                                                     | Occurs when the drive powers-up or the image is programmed. The image tasks will not run. |  |
|                  | 62                                                                                                                                                                                                                                                                                                                                       | The option module fitted in slot 2 is not allowed with the derivative image                                                                                                                                                                                                                                                                                                     |                                                                                           |  |
|                  | 63                                                                                                                                                                                                                                                                                                                                       | The option module fitted in slot 3 is not allowed with the derivative image                                                                                                                                                                                                                                                                                                     |                                                                                           |  |
|                  | 64                                                                                                                                                                                                                                                                                                                                       | The option module fitted in slot 4 is not allowed with the derivative image                                                                                                                                                                                                                                                                                                     |                                                                                           |  |
|                  | 70                                                                                                                                                                                                                                                                                                                                       | An option module that is required by the derivative image is not fitted in any slot                                                                                                                                                                                                                                                                                             | Occurs when the drive powers-up or the image is programmed. The image tasks will not run. |  |
|                  | 71                                                                                                                                                                                                                                                                                                                                       | An option module specifically required to be fitted in slot 1 not present                                                                                                                                                                                                                                                                                                       |                                                                                           |  |
|                  | 72                                                                                                                                                                                                                                                                                                                                       | An option module specifically required to be fitted in slot 2 not present                                                                                                                                                                                                                                                                                                       |                                                                                           |  |
|                  | 73                                                                                                                                                                                                                                                                                                                                       | An option module specifically required to be fitted in slot 3 not present                                                                                                                                                                                                                                                                                                       |                                                                                           |  |
|                  | 74                                                                                                                                                                                                                                                                                                                                       | An option module specifically required to be fitted in slot 4 not present                                                                                                                                                                                                                                                                                                       |                                                                                           |  |
|                  | 80 to 81                                                                                                                                                                                                                                                                                                                                 | An error has been detected in the derivative image, contact the supplier of the drive.                                                                                                                                                                                                                                                                                          |                                                                                           |  |
|                  | <b>Recommended action:</b><br>Contact the supplier of the drive                                                                                                                                                                                                                                                                          |                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                           |  |
|                  | Destination                                                                                                                                                                                                                                                                                                                              | Two or more parameters are writing to the same destination parameter                                                                                                                                                                                                                                                                                                            |                                                                                           |  |
|                  | 199                                                                                                                                                                                                                                                                                                                                      | The Destination trip indicates that destination parameters of two or more functions (Menus 3, 7, 8, 9, 12 or 14) within the drive are writing to the same parameter.<br><b>Recommended actions:</b> <ul style="list-style-type: none"><li>Set Pr <b>mm.000</b> to 'Destinations' or 12001 and check all visible parameters in all menus for parameter write conflicts</li></ul> |                                                                                           |  |
| Drive Size       | Power stage recognition: Unrecognized drive size                                                                                                                                                                                                                                                                                         |                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                           |  |
| 224              | The <i>Drive Size</i> trip indicates that the control PCB has not recognized the drive size of the power circuit to which it is connected.<br><b>Recommended action:</b> <ul style="list-style-type: none"><li>Ensure the drive is programmed to the latest firmware version</li><li>Hardware fault - return drive to supplier</li></ul> |                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                           |  |

| Trip        | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                       |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|-------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------|---|------------------------------------------------------------------------------------------|---|----------------------------------------------------------------------------------------------------------------------------------------|----|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------|----|------------------------------------------------------|----|------------------------------------------------------|---|---------------------------------------|---|------------------------------------------------------|---|----------------------------------------|---|-----------------------------------------------------------------|
| EEPROM Fail | Default parameters have been loaded                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                                                                                                                                       |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
| 31          | <p>The <i>EEPROM Fail</i> trip indicates that default parameters have been loaded. The exact cause/reason of the trip can be identified from the sub-trip number.</p> <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>The most significant digit of the internal parameter database version number has changed</td></tr><tr><td>2</td><td>The CRCs applied to the parameter data stored in internal non-volatile memory indicate that a valid set of parameters cannot be loaded</td></tr><tr><td>3</td><td>The drive mode restored from internal non-volatile memory is outside the allowed range for the product or the derivative image does not allow the previous drive mode</td></tr><tr><td>4</td><td>The drive derivative image has changed</td></tr><tr><td>5</td><td>The power stage hardware has changed</td></tr><tr><td>6</td><td>The internal I/O hardware has changed</td></tr><tr><td>7</td><td>The position feedback interface hardware has changed</td></tr><tr><td>8</td><td>The control board hardware has changed</td></tr><tr><td>9</td><td>The checksum on the non-parameter area of the EEPROM has failed</td></tr></table> <p>The drive holds two banks of user save parameters and two banks of power down save parameters in non-volatile memory. If the last bank of either set of parameters that was saved is corrupted a <i>User Save</i> or <i>Power Down Save</i> trip is produced. If one of these trips occurs the parameters values that were last saved successfully are used. It can take some time to save parameters when requested by the user and if the power is removed from the drive during this process it is possible to corrupt the data in the non-volatile memory.</p> <p>If both banks of user save parameters or both banks of power down save parameters are corrupted or one of the other conditions given in the table above occurs EEPROM Fail.xxx trip is produced. If this trip occurs it is not possible to use the data that has been saved previously, and so the drive will be in lowest allowed drive mode with default parameters. The trip can only be reset if Pr <b>mm.000</b> (mm.000) is set to 10, 11, 1233 or 1244 or if <i>Load Defaults</i> (11.043) is set to a non-zero value.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Default the drive and perform a reset</li><li>• Allow sufficient time to perform a save before the supply to the drive is removed</li><li>• If the trip persists - return drive to supplier</li></ul> | Sub-trip                                                                                                                                                              | Reason | 1 | The most significant digit of the internal parameter database version number has changed | 2 | The CRCs applied to the parameter data stored in internal non-volatile memory indicate that a valid set of parameters cannot be loaded | 3  | The drive mode restored from internal non-volatile memory is outside the allowed range for the product or the derivative image does not allow the previous drive mode | 4  | The drive derivative image has changed               | 5  | The power stage hardware has changed                 | 6 | The internal I/O hardware has changed | 7 | The position feedback interface hardware has changed | 8 | The control board hardware has changed | 9 | The checksum on the non-parameter area of the EEPROM has failed |
|             | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | Reason                                                                                                                                                                |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The most significant digit of the internal parameter database version number has changed                                                                              |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The CRCs applied to the parameter data stored in internal non-volatile memory indicate that a valid set of parameters cannot be loaded                                |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 3                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The drive mode restored from internal non-volatile memory is outside the allowed range for the product or the derivative image does not allow the previous drive mode |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 4                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The drive derivative image has changed                                                                                                                                |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 5                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The power stage hardware has changed                                                                                                                                  |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 6                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The internal I/O hardware has changed                                                                                                                                 |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 7                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The position feedback interface hardware has changed                                                                                                                  |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 8                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The control board hardware has changed                                                                                                                                |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
| 9           | The checksum on the non-parameter area of the EEPROM has failed                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                                       |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
| Encoder 1   | Drive position feedback interface power supply overload                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                       |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
| 189         | <p>The <i>Encoder 1</i> trip indicates that the drive encoder power supply has been overloaded. Terminals 13 &amp;14 of the 15 way D type connector can supply a maximum current of 200 mA @ 15 V or 300 mA @ 8 V and 5 V.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Check encoder power supply wiring</li><li>• Disable the termination resistors (Pr <b>03.039</b> set to 0) to reduce current consumption</li><li>• For 5 V encoders with long cables, select 8 V (Pr <b>03.036</b>) and install a 5 V voltage regulator close to the encoder</li><li>• Check the encoder specification to confirm if it is compatible with the encoder port power supply current capability</li><li>• Replace the encoder</li><li>• Use an external power supply with higher current capability</li></ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                       |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
| Encoder 2   | Drive encoder (Feedback) wire break                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                                                                                                                                       |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
| 190         | <p>The <i>Encoder 2</i> trip indicates that the drive has detected a wire break on the 15 way D-type connector on the drive. The exact cause of the trip can be identified from the sub-trip number.</p> <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Drive position feedback interface 1 on any input</td></tr><tr><td>2</td><td>Drive position feedback interface 2 on any input</td></tr><tr><td>11</td><td>Drive position feedback interface 1 on the A channel</td></tr><tr><td>12</td><td>Drive position feedback interface 1 on the B channel</td></tr><tr><td>13</td><td>Drive position feedback interface 1 on the Z channel</td></tr></table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Ensure that the position feedback device type selected in Pr <b>03.038</b> is correct for the position feedback device connected to the P1 interface on the drive.</li><li>• If wire break detection on the drive encoder input is not required, set Pr <b>03.040</b> = XXX0 to disable the Encoder 2 trip</li><li>• Check cable continuity</li><li>• Check wiring of feedback signals is correct</li><li>• Check encoder power supply is set correctly (Pr <b>03.036</b>)</li><li>• Replace encoder</li></ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Sub-trip                                                                                                                                                              | Reason | 1 | Drive position feedback interface 1 on any input                                         | 2 | Drive position feedback interface 2 on any input                                                                                       | 11 | Drive position feedback interface 1 on the A channel                                                                                                                  | 12 | Drive position feedback interface 1 on the B channel | 13 | Drive position feedback interface 1 on the Z channel |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | Reason                                                                                                                                                                |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Drive position feedback interface 1 on any input                                                                                                                      |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Drive position feedback interface 2 on any input                                                                                                                      |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 11                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | Drive position feedback interface 1 on the A channel                                                                                                                  |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
|             | 12                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | Drive position feedback interface 1 on the B channel                                                                                                                  |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |
| 13          | Drive position feedback interface 1 on the Z channel                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                                                                                                                                                       |        |   |                                                                                          |   |                                                                                                                                        |    |                                                                                                                                                                       |    |                                                      |    |                                                      |   |                                       |   |                                                      |   |                                        |   |                                                                 |

| Trip      | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                     |        |   |                                     |   |                                     |
|-----------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------|--------|---|-------------------------------------|---|-------------------------------------|
| Encoder 3 | Phase offset incorrect while running                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                     |        |   |                                     |   |                                     |
| 191       | <p>The <i>Encoder 3</i> trip indicates that the drive has detected an incorrect UVW phase angle while running (RFC-S mode only) or SINCOS phase error. The feedback device which has caused the trip can be identified by the sub-trip number.</p> <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Drive position feedback interface 1</td></tr><tr><td>2</td><td>Drive position feedback interface 2</td></tr></table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Check encoder shield connections</li><li>• Ensure the encoder cable is one uninterrupted cable</li><li>• Check the encoder signal for noise with an oscilloscope</li><li>• Check the integrity of the encoder mechanical mounting</li><li>• For a UVW servo encoder, ensure that the phase rotation of the UVW commutation signals is the same as the phase rotation of the motor</li><li>• For a SINCOS encoder, ensure that motor and incremental SINCOS connections are correct and that for forward rotation of the motor, the encoder rotates clockwise (when looking at the shaft of the encoder)</li><li>• Repeat the offset measurement test</li></ul> | Sub-trip                            | Reason | 1 | Drive position feedback interface 1 | 2 | Drive position feedback interface 2 |
|           | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Reason                              |        |   |                                     |   |                                     |
|           | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Drive position feedback interface 1 |        |   |                                     |   |                                     |
|           | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Drive position feedback interface 2 |        |   |                                     |   |                                     |
| Encoder 4 | Feedback device comms failure                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |                                     |        |   |                                     |   |                                     |
| 192       | <p>The Encoder 4 trip indicates that the encoder communications has timed out or the communications position message transfer time is too long. This trip can also be caused due to wire break in the communication channel between the drive and the encoder. The feedback device which has caused the trip can be identified by the sub-trip number.</p> <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Drive position feedback interface 1</td></tr><tr><td>2</td><td>Drive position feedback interface 2</td></tr></table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Ensure the encoder power supply setting (Pr <b>03.036</b>) is correct</li><li>• Complete encoder auto-configuration (Pr <b>03.041</b>)</li><li>• Check the encoder wiring</li><li>• Replace the feedback device</li></ul>                                                                                                                                                                                                                                                                                                                              | Sub-trip                            | Reason | 1 | Drive position feedback interface 1 | 2 | Drive position feedback interface 2 |
|           | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Reason                              |        |   |                                     |   |                                     |
|           | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Drive position feedback interface 1 |        |   |                                     |   |                                     |
|           | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Drive position feedback interface 2 |        |   |                                     |   |                                     |
| Encoder 5 | Checksum or CRC error                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                     |        |   |                                     |   |                                     |
| 193       | <p>The <i>Encoder 5</i> trip indicates that there is a checksum or CRC error, or the SSI encoder is not ready. The Encoder 5 trip can also indicate a wire break to a communications based encoder.</p> <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Drive position feedback interface 1</td></tr><tr><td>2</td><td>Drive position feedback interface 2</td></tr></table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Check the encoder cable shield connections</li><li>• Ensure the cable is one uninterrupted cable - remove any connector blocks or if unavoidable minimise the length of any shield pigtails to the connector block</li><li>• Check the encoder signal for noise with an oscilloscope</li><li>• Check the comms resolution setting (Pr <b>03.035</b>)</li><li>• If using a Hiperface, EnDat encoder carry out an encoder auto-configuration (Pr <b>03.041</b> = Enabled)</li><li>• Replace the encoder</li></ul>                                                                                                                                                                                           | Sub-trip                            | Reason | 1 | Drive position feedback interface 1 | 2 | Drive position feedback interface 2 |
|           | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Reason                              |        |   |                                     |   |                                     |
|           | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Drive position feedback interface 1 |        |   |                                     |   |                                     |
|           | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Drive position feedback interface 2 |        |   |                                     |   |                                     |
| Encoder 6 | Encoder has indicated an error                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                     |        |   |                                     |   |                                     |
| 194       | <p>The <i>Encoder 6</i> trip indicates that the encoder has indicated an error or that the power supply has failed to an SSI encoder. The <i>Encoder 6</i> trip can also indicate a wire break to an SSI encoder.</p> <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Drive position feedback interface 1</td></tr><tr><td>2</td><td>Drive position feedback interface 2</td></tr></table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• For SSI encoders, check the wiring and encoder power supply setting (Pr <b>03.036</b>)</li><li>• Replace the encoder / contact the supplier of the encoder</li></ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | Sub-trip                            | Reason | 1 | Drive position feedback interface 1 | 2 | Drive position feedback interface 2 |
|           | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Reason                              |        |   |                                     |   |                                     |
|           | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Drive position feedback interface 1 |        |   |                                     |   |                                     |
|           | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Drive position feedback interface 2 |        |   |                                     |   |                                     |

| Trip                                                                                                                                                                                                                             | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------|--------|----|-------------------------------------|----|-------------------------------------|----|-------------------------|----|-------------------------|----|---------------------------|----|------------------------------|----|-----------------------------------------|
| Encoder 7                                                                                                                                                                                                                        | Set-up parameters for position feedback device have changed                                                                                                                                                                                                                                                                                                                                                                                                            |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| 195                                                                                                                                                                                                                              | The <i>Encoder 7</i> trip indicates that the set-up parameters for position feedback device has changed. The feedback device which has caused the trip can be identified by the sub-trip number.                                                                                                                                                                                                                                                                       |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Drive position feedback interface 1</td></tr><tr><td>2</td><td>Drive position feedback interface 2</td></tr></table>                                                                                                                                                                                                                                                                                 | Sub-trip                                | Reason | 1  | Drive position feedback interface 1 | 2  | Drive position feedback interface 2 |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                               | Reason                                  |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Drive position feedback interface 1     |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Drive position feedback interface 2     |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| Recommended actions:                                                                                                                                                                                                             |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| <ul style="list-style-type: none"><li>Reset the trip and perform a save.</li><li>Ensure Pr <b>3.033</b> and Pr <b>03.035</b> are set correctly or carry out an encoder auto-configuration (Pr <b>03.041</b> = Enabled)</li></ul> |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| Encoder 8                                                                                                                                                                                                                        | Position feedback interface has timed out                                                                                                                                                                                                                                                                                                                                                                                                                              |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| 196                                                                                                                                                                                                                              | The <i>Encoder 8</i> trip indicates that Position feedback interface communications time exceeds 250 μs. The feedback device which has caused the trip can be identified by the sub-trip number.                                                                                                                                                                                                                                                                       |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Drive position feedback interface 1</td></tr><tr><td>2</td><td>Drive position feedback interface 2</td></tr></table>                                                                                                                                                                                                                                                                                 | Sub-trip                                | Reason | 1  | Drive position feedback interface 1 | 2  | Drive position feedback interface 2 |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                               | Reason                                  |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Drive position feedback interface 1     |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Drive position feedback interface 2     |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| Recommended actions:                                                                                                                                                                                                             |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| <ul style="list-style-type: none"><li>Ensure the encoder is connected correctly</li><li>Ensure that the encoder is compatible</li><li>Increase baud rate</li></ul>                                                               |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| Encoder 9                                                                                                                                                                                                                        | Position feedback is selected from a option module slot which does not have a feedback option module installed                                                                                                                                                                                                                                                                                                                                                         |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| 197                                                                                                                                                                                                                              | The <i>Encoder 9</i> trip indicates that position feedback source selected in Pr <b>03.026</b> (or Pr <b>21.021</b> for the second motor map) is not valid                                                                                                                                                                                                                                                                                                             |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | Recommended actions: <ul style="list-style-type: none"><li>Check the setting of Pr <b>03.026</b> (or Pr <b>21.021</b> if the second motor parameters have been enabled)</li><li>Ensure that the option slot selected in Pr <b>03.026</b> has a feedback option module installed</li></ul>                                                                                                                                                                              |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| Encoder 12                                                                                                                                                                                                                       | Encoder could not be identified during auto-configuration                                                                                                                                                                                                                                                                                                                                                                                                              |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| 162                                                                                                                                                                                                                              | The <i>Encoder 12</i> trip indicates that the drive is communicating with the encoder but the encoder type is not recognized.                                                                                                                                                                                                                                                                                                                                          |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Drive position feedback interface 1</td></tr><tr><td>2</td><td>Drive position feedback interface 2</td></tr></table>                                                                                                                                                                                                                                                                                 | Sub-trip                                | Reason | 1  | Drive position feedback interface 1 | 2  | Drive position feedback interface 2 |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                               | Reason                                  |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Drive position feedback interface 1     |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Drive position feedback interface 2     |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| Recommended actions:                                                                                                                                                                                                             |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| <ul style="list-style-type: none"><li>Enter the encoder setup parameters manually</li><li>Check to see the encoder supports auto-configuration</li></ul>                                                                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| Encoder 13                                                                                                                                                                                                                       | Data read from the encoder is out of range during auto-configuration                                                                                                                                                                                                                                                                                                                                                                                                   |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| 163                                                                                                                                                                                                                              | The <i>Encoder 13</i> trip indicates that the data read from the encoder was out of the range during auto-configuration. No parameters will be modified with the data read from the encoder as a result of auto configuration. The tens in the sub-trip number indicate the interface number (i.e. 1 for P1 interface and 2 for P2 interface).                                                                                                                         |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>x1</td><td>Rotary lines per revolution error</td></tr><tr><td>x2</td><td>Linear comms pitch error</td></tr><tr><td>x3</td><td>Linear line pitch error</td></tr><tr><td>x4</td><td>Rotary turns bits error</td></tr><tr><td>x5</td><td>Communications bits error</td></tr><tr><td>x6</td><td>Calculation time is too long</td></tr><tr><td>x7</td><td>Line delay measured is longer than 5 μs</td></tr></table> | Sub-trip                                | Reason | x1 | Rotary lines per revolution error   | x2 | Linear comms pitch error            | x3 | Linear line pitch error | x4 | Rotary turns bits error | x5 | Communications bits error | x6 | Calculation time is too long | x7 | Line delay measured is longer than 5 μs |
|                                                                                                                                                                                                                                  | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                               | Reason                                  |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | x1                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | Rotary lines per revolution error       |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | x2                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | Linear comms pitch error                |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | x3                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | Linear line pitch error                 |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | x4                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | Rotary turns bits error                 |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | x5                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | Communications bits error               |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | x6                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | Calculation time is too long            |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  | x7                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | Line delay measured is longer than 5 μs |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| Recommended actions:                                                                                                                                                                                                             |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
| <ul style="list-style-type: none"><li>Enter the encoder setup parameters manually</li><li>Check to see the encoder supports auto-configuration</li></ul>                                                                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |
|                                                                                                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                         |        |    |                                     |    |                                     |    |                         |    |                         |    |                           |    |                              |    |                                         |

| Trip                 | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |          |        |   |                                                                                |   |                                                                                |   |                                   |
|----------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|--------|---|--------------------------------------------------------------------------------|---|--------------------------------------------------------------------------------|---|-----------------------------------|
| <b>Encoder 14</b>    | <b>The data given in the additional configuration parameter for a position feedback interface is out of range</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>164</b>           | <p>The Encoder 14 trip indicates that the data given in the additional configuration parameter for a position feedback interface is out of range. If the sub-trip number is one then the data is out of range in <i>P1 Additional Configuration</i> (03.074), or if the sub-trip number is 2 the data is out of range in <i>P2 Additional Configuration</i> (03.174). Not all position feedback devices use the additional configuration, but those that do are listed below.</p> <p><b>BISS</b></p> <p>Range checking is applied to the turns padding (decimal digits 5-3) and position padding (decimal digits 2-0). If these give a padding value outside +/-16 then the trip is initiated. Note that in each case the most significant digit indicates left (0) or right (1) padding, and the least significant 2 digits indicate the number of bits</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>External Trip</b> | <b>An External trip is initiated</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>6</b>             | <p>An <i>External Trip</i> has occurred. The cause of the trip can be identified from the sub trip number displayed after the trip string. See table below. An external trip can also be initiated by writing a value of 6 in Pr <b>10.038</b>.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td><i>External Trip Mode</i> (08.010) = 1 or 3 and Safe Torque Off input 1 is low</td></tr> <tr> <td>2</td><td><i>External Trip Mode</i> (08.010) = 2 or 3 and Safe Torque Off input 2 is low</td></tr> <tr> <td>3</td><td><i>External Trip</i> (10.032) = 1</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check the Safe Torque Off signal voltage (on terminal 31 on <i>Unidrive M700 / M701</i> and terminal 11 &amp; 13 on <i>Unidrive M702</i>) equals to 24 V.</li> <li>Check the value of Pr <b>08.009</b> which indicates the digital state of terminal 31 on <i>Unidrive M700 / M701</i> and terminal 11 &amp; 13 on <i>Unidrive M702</i>, equates to 'on'.</li> <li>If external trip detection of the Safe Torque Off input is not required, set Pr <b>08.010</b> to OFF (0).</li> <li>Check the value of Pr <b>10.032</b>.</li> <li>Select 'Destinations' (or enter 12001) in Pr <b>mm.000</b> and check for a parameter controlling Pr <b>10.032</b>.</li> <li>Ensure Pr <b>10.032</b> or Pr <b>10.038</b> (= 6) is not being controlled by serial comms</li> </ul> | Sub-trip | Reason | 1 | <i>External Trip Mode</i> (08.010) = 1 or 3 and Safe Torque Off input 1 is low | 2 | <i>External Trip Mode</i> (08.010) = 2 or 3 and Safe Torque Off input 2 is low | 3 | <i>External Trip</i> (10.032) = 1 |
| Sub-trip             | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                                                                |   |                                                                                |   |                                   |
| 1                    | <i>External Trip Mode</i> (08.010) = 1 or 3 and Safe Torque Off input 1 is low                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |          |        |   |                                                                                |   |                                                                                |   |                                   |
| 2                    | <i>External Trip Mode</i> (08.010) = 2 or 3 and Safe Torque Off input 2 is low                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |          |        |   |                                                                                |   |                                                                                |   |                                   |
| 3                    | <i>External Trip</i> (10.032) = 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>HF01</b>          | <b>Data processing error: CPU address error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                                                                |   |                                                                                |   |                                   |
|                      | <p>The <i>HF01</i> trip indicates that a CPU address error has occurred. This trip indicates that the control PCB on the drive has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>HF02</b>          | <b>Data processing error: DMAC address error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                                                |   |                                                                                |   |                                   |
|                      | <p>The <i>HF02</i> trip indicates that a DMAC address error has occurred. This trip indicates that the control PCB on the drive has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>HF03</b>          | <b>Data processing error: Illegal instruction</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                                |   |                                                                                |   |                                   |
|                      | <p>The <i>HF03</i> trip indicates that an illegal instruction has occurred. This trip indicates that the control PCB on the drive has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>HF04</b>          | <b>Data processing error: Illegal slot instruction</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                                                                |   |                                                                                |   |                                   |
|                      | <p>The <i>HF04</i> trip indicates that an illegal slot instruction has occurred. This trip indicates that the control PCB on the drive has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>HF05</b>          | <b>Data processing error: Undefined exception</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                                                                |   |                                                                                |   |                                   |
|                      | <p>The <i>HF05</i> trip indicates that an undefined exception error has occurred. This trip indicates that the control PCB on the drive has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                                                                |   |                                                                                |   |                                   |
| <b>HF06</b>          | <b>Data processing error: Reserved exception</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                                                                |   |                                                                                |   |                                   |
|                      | <p>The <i>HF06</i> trip indicates that a reserved exception error has occurred. This trip indicates that the control PCB on the drive has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |          |        |   |                                                                                |   |                                                                                |   |                                   |

| Trip        | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |       |   |                  |   |             |   |                        |
|-------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|-------|---|------------------|---|-------------|---|------------------------|
| <b>HF07</b> | <b>Data processing error: Watchdog failure</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |       |   |                  |   |             |   |                        |
|             | The <i>HF07</i> trip indicates that a watchdog failure has occurred. This trip indicates that the control PCB on the drive has failed.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                   |          |       |   |                  |   |             |   |                        |
| <b>HF08</b> | <b>Data processing error: CPU interrupt crash</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |       |   |                  |   |             |   |                        |
|             | The <i>HF08</i> trip indicates that a CPU interrupt crash has occurred. This trip indicates that the control PCB on the drive has failed.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                |          |       |   |                  |   |             |   |                        |
| <b>HF09</b> | <b>Data processing error: Free store overflow</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |       |   |                  |   |             |   |                        |
|             | The <i>HF09</i> trip indicates that a free store overflow has occurred. This trip indicates that the control PCB on the drive has failed.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                |          |       |   |                  |   |             |   |                        |
| <b>HF10</b> | <b>Data processing error: Parameter routing system error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |       |   |                  |   |             |   |                        |
|             | The <i>HF10</i> trip indicates that a Parameter routing system error has occurred. This trip indicates that the control PCB on the drive has failed.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                     |          |       |   |                  |   |             |   |                        |
| <b>HF11</b> | <b>Data processing error: Access to EEPROM failed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |          |       |   |                  |   |             |   |                        |
|             | The <i>HF11</i> trip indicates that access to the drive EEPROM has failed. This trip indicates that the control PCB on the drive has failed.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                             |          |       |   |                  |   |             |   |                        |
| <b>HF12</b> | <b>Data processing error: Main program stack overflow</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |       |   |                  |   |             |   |                        |
|             | The <i>HF12</i> trip indicates that the main program stack over flow has occurred. The stack can be identified by the sub-trip number. This trip indicates that the control PCB on the drive has failed. <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Stack</th></tr> </thead> <tbody> <tr> <td>1</td><td>Background tasks</td></tr> <tr> <td>2</td><td>Timed tasks</td></tr> <tr> <td>3</td><td>Main system interrupts</td></tr> </tbody> </table> <b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul> | Sub-trip | Stack | 1 | Background tasks | 2 | Timed tasks | 3 | Main system interrupts |
| Sub-trip    | Stack                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |          |       |   |                  |   |             |   |                        |
| 1           | Background tasks                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |       |   |                  |   |             |   |                        |
| 2           | Timed tasks                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |       |   |                  |   |             |   |                        |
| 3           | Main system interrupts                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |       |   |                  |   |             |   |                        |
| <b>HF13</b> | <b>Data processing error: Firmware incompatible with hardware</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |       |   |                  |   |             |   |                        |
|             | The <i>HF13</i> trip indicates that the drive firmware is not compatible with the hardware. This trip indicates that the control PCB on the drive has failed. The sub-trip number gives the actual ID code of the control board hardware.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Re-program the drive with the latest version of the drive firmware for <i>Unidrive M700 / M701 / M702</i></li> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                             |          |       |   |                  |   |             |   |                        |
| <b>HF14</b> | <b>Data processing error: CPU register bank error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |          |       |   |                  |   |             |   |                        |
|             | The <i>HF14</i> trip indicates that a CPU register bank error has occurred. This trip indicates that the control PCB on the drive has failed.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                            |          |       |   |                  |   |             |   |                        |
| <b>HF15</b> | <b>Data processing error: CPU divide error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |       |   |                  |   |             |   |                        |
|             | The <i>HF15</i> trip indicates that a CPU divide error has occurred. This trip indicates that the control PCB on the drive has failed.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                   |          |       |   |                  |   |             |   |                        |
| <b>HF16</b> | <b>Data processing error: RTOS error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |          |       |   |                  |   |             |   |                        |
|             | The <i>HF16</i> trip indicates that a RTOS error has occurred. This trip indicates that the control PCB on the drive has failed.<br><b>Recommended actions:</b> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                         |          |       |   |                  |   |             |   |                        |

| Trip                | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |        |   |                                               |   |                                                 |   |                                                       |
|---------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|--------|---|-----------------------------------------------|---|-------------------------------------------------|---|-------------------------------------------------------|
| <b>HF17</b>         | <b>Data processing error: Clock supplied to the control board is out of specification</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |        |   |                                               |   |                                                 |   |                                                       |
|                     | <p>The <i>HF17</i> trip indicates that the clock supplied to the control board logic is out of specification. This trip indicates that the control PCB on the drive has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                               |   |                                                 |   |                                                       |
| <b>HF18</b>         | <b>Data processing error: Internal flash memory has failed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |        |   |                                               |   |                                                 |   |                                                       |
|                     | <p>The <i>HF18</i> trip indicates that the internal flash memory has failed when writing option module parameter data. The reason for the trip can be identified by the sub-trip number.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>Programming error while writing menu in flash</td></tr> <tr> <td>2</td><td>Erase flash block containing setup menus failed</td></tr> <tr> <td>3</td><td>Erase flash block containing application menus failed</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault - Contact the supplier of the drive.</li> </ul> | Sub-trip | Reason | 1 | Programming error while writing menu in flash | 2 | Erase flash block containing setup menus failed | 3 | Erase flash block containing application menus failed |
| Sub-trip            | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                               |   |                                                 |   |                                                       |
| 1                   | Programming error while writing menu in flash                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                               |   |                                                 |   |                                                       |
| 2                   | Erase flash block containing setup menus failed                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |          |        |   |                                               |   |                                                 |   |                                                       |
| 3                   | Erase flash block containing application menus failed                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |          |        |   |                                               |   |                                                 |   |                                                       |
| <b>HF19</b>         | <b>Data processing error: CRC check on the firmware has failed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |          |        |   |                                               |   |                                                 |   |                                                       |
|                     | <p>The <i>HF19</i> trip indicates that the CRC check on the drive firmware has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Re-program the drive</li> <li>Hardware fault - Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                          |          |        |   |                                               |   |                                                 |   |                                                       |
| <b>HF20</b>         | <b>Data processing error: ASIC is not compatible with the hardware</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                               |   |                                                 |   |                                                       |
|                     | <p>The <i>HF20</i> trip indicates that the ASIC version is not compatible with the drive firmware. The ASIC version can be identified from the sub-trip number.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault - Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                               |   |                                                 |   |                                                       |
| <b>HF23 to HF25</b> | <b>Hardware fault</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |          |        |   |                                               |   |                                                 |   |                                                       |
|                     | <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>If this trip occurs please consult the drive supplier.</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                               |   |                                                 |   |                                                       |

| Trip                         | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
|------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------|---|-------|--------|-------|--------|-------|--------|-------|--------|----------|--------|---|-----------------------------------------------------------------------------------------------------|---|-------------------------------------------------------------------------------------------------------------------|---|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Inductance</b>            | <b>Inductance measurement out of range or motor saturation not detected</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 8                            | <p>This trip occurs in RFC-S mode when the drive has detected that the motor inductances are not suitable for the operation being attempted. The trip is either caused because the ratio or difference between <math>L_d</math> and <math>L_q</math> is too small or because the saturation characteristic of the motor cannot be measured.</p> <p>If the inductance ratio or difference is too small this is because one of the following conditions is true:</p> $(No\text{-}load\ L_q\ (05.072) - L_d\ (05.024)) / L_d\ (05.024) < 0.1$ $(No\text{-}load\ L_q\ (05.072) - L_d\ (05.024)) < (K / Full\ Scale\ Current\ K_c\ (11.061))H$ <p>where:</p> <table border="1"> <tr> <th>Drive Rated voltage (11.033)</th><th>K</th></tr> <tr> <td>200 V</td><td>0.0073</td></tr> <tr> <td>400 V</td><td>0.0146</td></tr> <tr> <td>575 V</td><td>0.0174</td></tr> <tr> <td>690 V</td><td>0.0209</td></tr> </table> <p>If the saturation characteristic of the motor cannot be measured this is because when the flux in the motor is changed the measured value of <math>L_d</math> does change sufficiently due to saturation to be measured. When half of <i>Rated Current</i> (05.007) is applied in the d axis of the motor in each direction the inductance must fall change at least <math>(K / (2 \times Full\ Scale\ Current\ K_c\ (11.061)))</math>.</p> <p>The specific reasons for each of the sub-trips are given in the table below:</p> <table border="1"> <tr> <th>Sub-trip</th><th>Reason</th></tr> <tr> <td>1</td><td>The inductance ratio or difference is too small when the drive has been started in sensorless mode.</td></tr> <tr> <td>2</td><td>The saturation characteristic of the motor cannot be measured when the drive has been started in sensorless mode.</td></tr> <tr> <td>3</td><td>The inductance ratio or difference is too small when an attempt is made to determine the location of the motor flux during a stationary auto-tune in RFC-S mode. This trip is also produced when the inductance ratio or inductance difference is too small when carrying out a phasing test on starting in RFC-S mode. If position feedback is being used the measured value for <i>Position Feedback Phase Angle</i> (03.025) may not be reliable. Also the measured values of <math>L_d</math> (05.024) and <i>No-load <math>L_q</math></i> (05.072) may not correspond to the d and q axis respectively.</td></tr> <tr> <td>4</td><td>The direction of the flux in the motor is detected by the change of inductance with different currents. This trip is initiated if the change cannot be detected when an attempt is made to perform a stationary auto-tune when position feedback is being used, or to perform a phasing test on starting in RFC-S mode.</td></tr> </table> <p><b>Recommended actions for sub-trip 1:</b></p> <ul style="list-style-type: none"> <li>Ensure that <i>RFC Low Speed Mode</i> (05.064) is set to Non-salient (1), Current (2) or Current No test (3).</li> </ul> <p><b>Recommended actions for sub-trip 2:</b></p> <ul style="list-style-type: none"> <li>Ensure that <i>RFC Low Speed Mode</i> (05.064) is set to Non-salient (1), Current (2) or Current No test (3).</li> </ul> <p><b>Recommended actions for sub-trip 3:</b></p> <ul style="list-style-type: none"> <li>None. The trip acts as a warning.</li> </ul> <p><b>Recommended actions for sub-trip 4:</b></p> <ul style="list-style-type: none"> <li>Stationary autotune is not possible. Perform a minimal movement or rotating autotune.</li> <li>Phasing test on starting is not possible. Use a position feedback device with commutation signals or absolute position.</li> </ul> | Drive Rated voltage (11.033) | K | 200 V | 0.0073 | 400 V | 0.0146 | 575 V | 0.0174 | 690 V | 0.0209 | Sub-trip | Reason | 1 | The inductance ratio or difference is too small when the drive has been started in sensorless mode. | 2 | The saturation characteristic of the motor cannot be measured when the drive has been started in sensorless mode. | 3 | The inductance ratio or difference is too small when an attempt is made to determine the location of the motor flux during a stationary auto-tune in RFC-S mode. This trip is also produced when the inductance ratio or inductance difference is too small when carrying out a phasing test on starting in RFC-S mode. If position feedback is being used the measured value for <i>Position Feedback Phase Angle</i> (03.025) may not be reliable. Also the measured values of $L_d$ (05.024) and <i>No-load <math>L_q</math></i> (05.072) may not correspond to the d and q axis respectively. | 4 | The direction of the flux in the motor is detected by the change of inductance with different currents. This trip is initiated if the change cannot be detected when an attempt is made to perform a stationary auto-tune when position feedback is being used, or to perform a phasing test on starting in RFC-S mode. |
| Drive Rated voltage (11.033) | K                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 200 V                        | 0.0073                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 400 V                        | 0.0146                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 575 V                        | 0.0174                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 690 V                        | 0.0209                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| Sub-trip                     | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 1                            | The inductance ratio or difference is too small when the drive has been started in sensorless mode.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 2                            | The saturation characteristic of the motor cannot be measured when the drive has been started in sensorless mode.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 3                            | The inductance ratio or difference is too small when an attempt is made to determine the location of the motor flux during a stationary auto-tune in RFC-S mode. This trip is also produced when the inductance ratio or inductance difference is too small when carrying out a phasing test on starting in RFC-S mode. If position feedback is being used the measured value for <i>Position Feedback Phase Angle</i> (03.025) may not be reliable. Also the measured values of $L_d$ (05.024) and <i>No-load <math>L_q</math></i> (05.072) may not correspond to the d and q axis respectively.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 4                            | The direction of the flux in the motor is detected by the change of inductance with different currents. This trip is initiated if the change cannot be detected when an attempt is made to perform a stationary auto-tune when position feedback is being used, or to perform a phasing test on starting in RFC-S mode.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| <b>Inductor Too Hot</b>      | <b>The regen inductor has overloaded</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 93                           | <p>In Regen mode, this trip indicates a regen inductor thermal overload based on the <i>Rated Current</i> (Pr 05.007) and the <i>Inductor Thermal Time Constant</i> (Pr 04.015). Pr 04.019 displays the inductor temperature as a percentage of the maximum value. The drive will trip on <i>Inductor Too Hot</i> when Pr 04.019 gets to 100 %.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check the load / current through the inductor has not changed.</li> <li>Ensure the <i>Rated Current</i> (Pr 05.007) is not zero.</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| <b>Inter-connect</b>         | <b>Multi-Power module drive interconnection cable error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |
| 103                          | <p>The Inter-connect trip indicates a multi-power module drive interconnection cable error. The sub-trip "xx.0.00" indicates which power module has detected the fault where xx is the power module number. It should be noted that this trip is also initiated if the communication fails either when a rectifier signals a fault or a trip is reset. In this case, the sub-trip is the number of modules that are still communicating correctly.</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                              |   |       |        |       |        |       |        |       |        |          |        |   |                                                                                                     |   |                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |   |                                                                                                                                                                                                                                                                                                                         |

| Trip                 | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |             |   |                                                                           |   |                                                                                                                                                                              |
|----------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|-------------|---|---------------------------------------------------------------------------|---|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>I/O Overload</b>  | <b>Digital output overload</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |          |             |   |                                                                           |   |                                                                                                                                                                              |
| 26                   | <p>The <i>I/O Overload</i> trip indicates that the total current drawn from 24 V user supply or from the digital output has exceeded the limit. A trip is initiated if one or more of the following conditions:</p> <ul style="list-style-type: none"> <li>Maximum output current from one digital output is 100 mA.</li> <li>The combined maximum output current from outputs 1 and 2 is 100 mA</li> <li>The combined maximum output current from output 3 and +24 V output is 100 mA</li> </ul> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check total loads on digital outputs</li> <li>Check control wiring is correct</li> <li>Check output wiring is undamaged</li> </ul>                                                                                                                                                                                                                                                                                           |          |             |   |                                                                           |   |                                                                                                                                                                              |
| <b>Island</b>        | <b>Island condition detected in regen mode</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |          |             |   |                                                                           |   |                                                                                                                                                                              |
| 160                  | <p>The <i>Island</i> trip indicates that the AC mains is no longer present and the inverter would be an 'islanded' power supply if it continued to operate. The sub-trip indicates the reason for the trip.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Description</th></tr> </thead> <tbody> <tr> <td>1</td><td>Island detection system has been enabled and detected an island condition</td></tr> <tr> <td>2</td><td>The minimum synchronization voltage is non-zero and the supply voltage has been below this threshold and been simulating its own supply synchronization for more than 2.0 s.</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check the supply / supply connections to the regen drive</li> </ul>                                                                                                                                                                                                             | Sub-trip | Description | 1 | Island detection system has been enabled and detected an island condition | 2 | The minimum synchronization voltage is non-zero and the supply voltage has been below this threshold and been simulating its own supply synchronization for more than 2.0 s. |
| Sub-trip             | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |          |             |   |                                                                           |   |                                                                                                                                                                              |
| 1                    | Island detection system has been enabled and detected an island condition                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |             |   |                                                                           |   |                                                                                                                                                                              |
| 2                    | The minimum synchronization voltage is non-zero and the supply voltage has been below this threshold and been simulating its own supply synchronization for more than 2.0 s.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |             |   |                                                                           |   |                                                                                                                                                                              |
| <b>Keypad Mode</b>   | <b>Keypad has been removed when the drive is receiving the speed reference from the keypad</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |          |             |   |                                                                           |   |                                                                                                                                                                              |
| 34                   | <p>The <i>Keypad Mode</i> trip indicates that the drive is in keypad mode [<i>Reference Selector</i> (01.014) = 4 or 6 or M2 reference selector (21.003 = 4 or 6 if motor map 2 is selected)] and the keypad has been removed or disconnected from the drive.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Re-install keypad and reset</li> <li>Change <i>Reference Selector</i> (01.014) to select the reference from another source</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |          |             |   |                                                                           |   |                                                                                                                                                                              |
| <b>Line Sync</b>     | <b>Synchronization to the power supply has been lost</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |             |   |                                                                           |   |                                                                                                                                                                              |
| 39                   | <p>The <i>Line Sync</i> trip indicates that the inverter has lost the synchronization with the ac supply in Regen mode.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check the supply / supply connections to the regen drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |             |   |                                                                           |   |                                                                                                                                                                              |
| <b>Low Load</b>      | <b>The load on the drive has fallen below the low load detection level</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |             |   |                                                                           |   |                                                                                                                                                                              |
| 38                   | <p>When the low load detector is active, the low load condition is detected when the <i>Percentage Load</i> (Pr 04.020) falls below the threshold defined by the <i>Low Load Detection Level</i> (Pr 04.027).</p> <p><i>Enable Trip On Low Load</i> (Pr 04.029) defines the action taken when low load is detected. If <i>Enable Trip On Low Load</i> (Pr 04.029) = 0, a Low Load warning is displayed and <i>Low Load Detected Alarm</i> (Pr 10.062) = 1. If <i>Enable Trip On Low Load</i> (Pr 04.029) = 1 no warning is given, but a Low Load trip is initiated.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Check the load on the motor has not changed</li> </ul>                                                                                                                                                                                                                                                                                                 |          |             |   |                                                                           |   |                                                                                                                                                                              |
| <b>Motor Too Hot</b> | <b>Output current overload timed out (<math>I^2t</math>)</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |             |   |                                                                           |   |                                                                                                                                                                              |
| 20                   | <p>The <i>Motor Too Hot</i> trip indicates a motor thermal overload based on the <i>Rated Current</i> (Pr 05.007) and <i>Motor Thermal Time Constant</i> (Pr 04.015). Pr 04.019 displays the motor temperature as a percentage of the maximum value. The drive will trip on <i>Motor Too Hot</i> when Pr 04.019 gets to 100 %.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure the load is not jammed / sticking</li> <li>Check the load on the motor has not changed</li> <li>If seen during an auto-tune test in RFC-S mode, ensure the motor <i>Rated Current</i> in Pr 05.007 is <math>\leq</math> Heavy duty current rating of the drive</li> <li>Tune the <i>Rated Speed</i> (Pr 05.008) (RFC-A mode only)</li> <li>Check feedback signal for noise</li> <li>Ensure the motor rated current is not zero</li> <li>This trip can be disabled and current limiting activated on the motor overload by setting thermal protection mode Pr 04.016 to 1.</li> </ul> |          |             |   |                                                                           |   |                                                                                                                                                                              |

| Trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------|--------|----|--------------------------------------------------|-------------|-----------------------------------|----|-------------------------|----|----------------------------------------------|----------------|----|---|----|---------------------------------------------|----------------|----|---|----|---------------------------------------|
| Name Plate                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Electronic nameplate transfer has failed                                                                                                                                                                                                                                                                                                                                                                                                          |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| 176                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | The <i>Name Plate</i> trip is initiated if an electronic name plate transfer between the drive and the motor has failed. The exact reason for the trip can be identified from the sub-trip number.                                                                                                                                                                                                                                                |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>Not enough memory space to complete the transfer</td></tr><tr><td>2</td><td>Communication with encoder failed</td></tr><tr><td>3</td><td>The transfer has failed</td></tr><tr><td>4</td><td>The checksum of the stored object has failed</td></tr></table>                                                                                                                      | Sub-trip                                         | Reason | 1  | Not enough memory space to complete the transfer | 2           | Communication with encoder failed | 3  | The transfer has failed | 4  | The checksum of the stored object has failed |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                          | Reason                                           |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Not enough memory space to complete the transfer |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Communication with encoder failed                |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 3                                                                                                                                                                                                                                                                                                                                                                                                                                                 | The transfer has failed                          |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| 4                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | The checksum of the stored object has failed                                                                                                                                                                                                                                                                                                                                                                                                      |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| <b>Recommended actions:</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| <ul style="list-style-type: none"><li>• Ensure that the device encoder memory has at least 128 bytes to store the nameplate data</li><li>• When writing the motor object (Pr <b>mm.000</b> = 11000), ensure that the device encoder memory has at least 256 bytes to store all the nameplate data.</li><li>• When transferring between option module and encoder, ensure that the option slot has a feedback option module installed.</li><li>• Check if the encoder has been initialized in <i>Position Feedback Initialized</i> (03.076).</li><li>• Verify the encoder wiring.</li></ul> |                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| Oht Brake                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Braking IGBT over-temperature                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| 101                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | The <i>Oht Brake</i> over-temperature trip indicates that braking IGBT over-temperature has been detected based on software thermal model.                                                                                                                                                                                                                                                                                                        |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Check braking resistor value is greater than or equal to the minimum resistance value</li></ul>                                                                                                                                                                                                                                                                               |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| Oht Control                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | Control stage over temperature                                                                                                                                                                                                                                                                                                                                                                                                                    |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| 23                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | This <i>Oht Control</i> trip indicates that a control stage over-temperature has been detected. From the sub-trip 'xxyzz', the Thermistor location is identified by 'zz'.                                                                                                                                                                                                                                                                         |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th><th>Description</th></tr><tr><td>Control system</td><td>00</td><td>0</td><td>01</td><td>Control board thermistor 1 over temperature</td></tr><tr><td>Control system</td><td>00</td><td>0</td><td>02</td><td>Control board thermistor 2 over temperature</td></tr><tr><td>Control system</td><td>00</td><td>0</td><td>03</td><td>I/O board thermistor over temperature</td></tr></table> | Source                                           | xx     | y  | zz                                               | Description | Control system                    | 00 | 0                       | 01 | Control board thermistor 1 over temperature  | Control system | 00 | 0 | 02 | Control board thermistor 2 over temperature | Control system | 00 | 0 | 03 | I/O board thermistor over temperature |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Source                                                                                                                                                                                                                                                                                                                                                                                                                                            | xx                                               | y      | zz | Description                                      |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                    | 00                                               | 0      | 01 | Control board thermistor 1 over temperature      |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                    | 00                                               | 0      | 02 | Control board thermistor 2 over temperature      |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                    | 00                                               | 0      | 03 | I/O board thermistor over temperature            |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| <b>Recommended actions:</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
| <ul style="list-style-type: none"><li>• Check enclosure / drive fans are still functioning correctly</li><li>• Check enclosure ventilation paths</li><li>• Check enclosure door filters</li><li>• Increase ventilation</li><li>• Reduce the drive switching frequency</li><li>• Check ambient temperature</li></ul>                                                                                                                                                                                                                                                                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                  |        |    |                                                  |             |                                   |    |                         |    |                                              |                |    |   |    |                                             |                |    |   |    |                                       |
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| Trip       | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |        |    |                                                 |                            |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
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| OHT dc bus | DC bus over temperature                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |        |    |                                                 |                            |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
| 27         | <p>The <i>OHT dc bus</i> trip indicates a DC bus component over temperature based on a software thermal model. The drive includes a thermal protection system to protect the DC bus components within the drive. This includes the effects of the output current and DC bus ripple. The estimated temperature is displayed as a percentage of the trip level in Pr <b>07.035</b>. If this parameter reaches 100 % then an <i>OHT dc bus</i> trip with sub-trip 200 is initiated. The drive will attempt to stop the motor before tripping. If the motor does not stop in 10 seconds the drive trips immediately.</p> <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th><th>Description</th></tr><tr><td>Control system</td><td>00</td><td>2</td><td>00</td><td>DC bus thermal model gives trip with sub-trip 0</td></tr></table> <p>It is also possible in a multi-power module system for DC bus over-temperature to be detected from within the power stage. From this source the estimated temperature as a percentage of trip is not available and the trip is indicated as follows:</p> <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th><th>Description</th></tr><tr><td>Control system</td><td>01</td><td>0</td><td>00</td><td>Power stage gives trip with sub-trip 0</td></tr></table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Check the AC supply voltage balance and levels</li><li>• Check DC bus ripple level</li><li>• Reduce duty cycle</li><li>• Reduce motor load</li><li>• Check the output current stability. If unstable;<ul style="list-style-type: none"><li>Check the motor map settings with motor nameplate (Pr <b>05.006</b>, Pr <b>05.007</b>, Pr <b>05.008</b>, Pr <b>05.009</b>, Pr <b>05.010</b>, Pr <b>05.011</b>) – (All Modes)</li><li>Disable slip compensation (Pr <b>05.027</b> = 0) – (Open loop)</li><li>Disable dynamic V to F operation (Pr <b>05.013</b> = 0) - (Open loop)</li><li>Select fixed boost (Pr <b>05.014</b> = Fixed) – (Open loop)</li><li>Select high stability space vector modulation (Pr <b>05.020</b> = 1) – (Open loop)</li><li>Disconnect the load and complete a rotating auto-tune (Pr <b>05.012</b>) – (RFC-A, RFC-S)</li><li>Auto-tune the rated speed value (Pr <b>05.016</b> = 1) – (RFC-A, RFC-S)</li><li>Reduce speed loop gains (Pr <b>03.010</b>, Pr <b>03.011</b>, Pr <b>03.012</b>) – (RFC-A, RFC-S)</li><li>Add a speed feedback filter value (Pr <b>03.042</b>) – (RFC-A, RFC-S)</li><li>Add a current demand filter (Pr <b>04.012</b>) – (RFC-A, RFC-S)</li><li>Check encoder signals for noise with an oscilloscope (RFC-A, RFC-S)</li><li>Check encoder mechanical coupling - (RFC-A, RFC-S)</li></ul></li></ul> | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | xx     | y  | zz                                              | Description                | Control system | 00             | 2  | 00 | DC bus thermal model gives trip with sub-trip 0 | Source                 | xx             | y  | zz | Description | Control system             | 01 | 0 | 00 | Power stage gives trip with sub-trip 0 |
|            | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | xx                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | y      | zz | Description                                     |                            |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
|            | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    | 00                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | 2      | 00 | DC bus thermal model gives trip with sub-trip 0 |                            |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
|            | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | xx                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | y      | zz | Description                                     |                            |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
|            | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    | 01                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | 0      | 00 | Power stage gives trip with sub-trip 0          |                            |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
|            | OHT Inverter                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Inverter over temperature based on thermal model                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |        |    |                                                 |                            |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
|            | 21                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | <p>This trip indicates that an IGBT junction over-temperature has been detected based on a software thermal model. The sub-trip indicates which model has initiated the trip in the form xxyzz as given below:</p> <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th><th>Description</th></tr><tr><td>Control system</td><td>00</td><td>1</td><td>00</td><td>Inverter thermal model</td></tr><tr><td>Control system</td><td>00</td><td>3</td><td>00</td><td>Braking IGBT thermal model</td></tr></table> <p><b>Recommended actions with sub-trip 100:</b></p> <ul style="list-style-type: none"><li>• Reduce the selected drive switching frequency</li><li>• Ensure <i>Auto-switching Frequency Change Disable</i> (05.035) is set to Off</li><li>• Reduce duty cycle</li><li>• Increase acceleration / deceleration rates</li><li>• Reduce motor load</li><li>• Check DC bus ripple</li><li>• Ensure all three input phases are present and balanced</li></ul> <p><b>Recommended actions with sub-trip 300:</b></p> <ul style="list-style-type: none"><li>• Reduce the braking load</li></ul> | Source | xx | y                                               | zz                         | Description    | Control system | 00 | 1  | 00                                              | Inverter thermal model | Control system | 00 | 3  | 00          | Braking IGBT thermal model |    |   |    |                                        |
|            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | xx     | y  | zz                                              | Description                |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
|            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | 00     | 1  | 00                                              | Inverter thermal model     |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |
|            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | 00     | 3  | 00                                              | Braking IGBT thermal model |                |                |    |    |                                                 |                        |                |    |    |             |                            |    |   |    |                                        |

| Trip         | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                     |                  |              |                                                                                             |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
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| Oht Power    | <b>Power stage over temperature</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                     |                  |              |                                                                                             |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
| 22           | <p>This trip indicates that a power stage over-temperature has been detected. From the sub-trip 'xxyz', the Thermistor location which is indicating the over-temperature is identified by 'zz'. The thermistor numbering is different for a single module type drive (i.e. no parallel board fitted) and a multi-module type drive (i.e. parallel board fitted with one or more power modules) as shown below:</p> <p><b>Single module type drive:</b></p> <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th><th>Description</th></tr><tr><td>Power system</td><td>01</td><td>0</td><td>zz</td><td>Thermistor location defined by zz in the power board</td></tr><tr><td>Power system</td><td>01</td><td>Rectifier number</td><td>zz</td><td>Thermistor location defined by zz in the rectifier</td></tr></table> <p><b>Multi-module type system:</b></p> <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th><th>Description</th></tr><tr><td>Power system</td><td>power module number</td><td>0</td><td>01</td><td>U phase power device</td></tr><tr><td>Power system</td><td>power module number</td><td>0</td><td>02</td><td>V phase power device</td></tr><tr><td>Power system</td><td>power module number</td><td>0</td><td>03</td><td>W phase power device</td></tr><tr><td>Power system</td><td>power module number</td><td>0</td><td>04</td><td>Rectifier</td></tr><tr><td>Power system</td><td>power module number</td><td>0</td><td>05</td><td>General power system</td></tr><tr><td>Power system</td><td>power module number</td><td>0</td><td>00</td><td>Braking IGBT</td></tr></table> <p>Note that the power module that has caused the trip cannot be identified except for the braking IGBT temperature measurement</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Check enclosure / drive fans are still functioning correctly</li><li>• Force the heatsink fans to run at maximum speed</li><li>• Check enclosure ventilation paths</li><li>• Check enclosure door filters</li><li>• Increase ventilation</li><li>• Reduce the drive switching frequency</li><li>• Reduce duty cycle</li><li>• Increase acceleration / deceleration rates</li><li>• Use S ramp (Pr <b>02.006</b>)</li><li>• Reduce motor load</li><li>• Check the derating tables and confirm the drive is correctly sized for the application.</li><li>• Use a drive with larger current / power rating</li></ul> | Source              | xx               | y            | zz                                                                                          | Description | Power system   | 01 | 0 | zz | Thermistor location defined by zz in the power board                                        | Power system | 01                  | Rectifier number | zz | Thermistor location defined by zz in the rectifier | Source | xx | y | zz | Description | Power system | power module number | 0 | 01 | U phase power device | Power system | power module number | 0 | 02 | V phase power device | Power system | power module number | 0 | 03 | W phase power device | Power system | power module number | 0 | 04 | Rectifier | Power system | power module number | 0 | 05 | General power system | Power system | power module number | 0 | 00 | Braking IGBT |
|              | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | xx                  | y                | zz           | Description                                                                                 |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | 01                  | 0                | zz           | Thermistor location defined by zz in the power board                                        |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | 01                  | Rectifier number | zz           | Thermistor location defined by zz in the rectifier                                          |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | xx                  | y                | zz           | Description                                                                                 |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | power module number | 0                | 01           | U phase power device                                                                        |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | power module number | 0                | 02           | V phase power device                                                                        |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | power module number | 0                | 03           | W phase power device                                                                        |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | power module number | 0                | 04           | Rectifier                                                                                   |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | power module number | 0                | 05           | General power system                                                                        |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
| Power system | power module number                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 0                   | 00               | Braking IGBT |                                                                                             |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
| OI ac        | <b>Instantaneous output over current detected</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                     |                  |              |                                                                                             |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
| 3            | <p>The instantaneous drive output current has exceeded VM_DRIVE_CURRENT[MAX]. This trip cannot be reset until 10 s after the trip was initiated.</p> <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th><th>Description</th></tr><tr><td>Control system</td><td>00</td><td>0</td><td rowspan="2">00</td><td rowspan="2">Instantaneous over-current trip when the measured AC current exceeds VM_DRIVE_CURRENT[MAX].</td></tr><tr><td>Power system</td><td>Power module number</td><td>0</td></tr></table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Acceleration/deceleration rate is too short</li><li>• If seen during auto-tune reduce the voltage boost</li><li>• Check for short circuit on the output cabling</li><li>• Check integrity of the motor insulation using an insulation tester</li><li>• Check feedback device wiring</li><li>• Check feedback device mechanical coupling</li><li>• Check feedback signals are free from noise</li><li>• Is motor cable length within limits for the frame size</li><li>• Reduce the values in the speed loop gain parameters - (Pr <b>03.010, 03.011, 03.012</b>) or (Pr <b>03.013, 03.014, 03.015</b>)</li><li>• Has the phase angle autotune been completed? (RFC-S mode only)</li><li>• Reduce the values in current loop gain parameters (RFC-A, RFC-S modes only)</li></ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | Source              | xx               | y            | zz                                                                                          | Description | Control system | 00 | 0 | 00 | Instantaneous over-current trip when the measured AC current exceeds VM_DRIVE_CURRENT[MAX]. | Power system | Power module number | 0                |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | xx                  | y                | zz           | Description                                                                                 |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | 00                  | 0                | 00           | Instantaneous over-current trip when the measured AC current exceeds VM_DRIVE_CURRENT[MAX]. |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |
|              | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | Power module number | 0                |              |                                                                                             |             |                |    |   |    |                                                                                             |              |                     |                  |    |                                                    |        |    |   |    |             |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |                      |              |                     |   |    |           |              |                     |   |    |                      |              |                     |   |    |              |

| Trip                                                                                                                                                                                                                      | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------|--------|----|-------------------------------------------------------------|----------------|-------------------------------------------------------------|---------------------|-------------------------------------------------------------|--------------|-------------------------------------------------------|---|----|
| OI Brake                                                                                                                                                                                                                  | Braking IGBT over current detected: short circuit protection for the braking IGBT activated                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| 4                                                                                                                                                                                                                         | The <i>OI Brake</i> trip indicates that over current has been detected in braking IGBT or braking IGBT protection has been activated. This trip cannot be reset until 10 s after the trip was initiated.                                                                                                                                                                                                                                                                                                                                                                                                                      |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th><th>Description</th></tr><tr><td>Power system</td><td>Power module number</td><td>0</td><td>00</td><td>Braking IGBT instantaneous over-current trip</td></tr></table>                                                                                                                                                                                                                                                                                                                                                                                               | Source                                                      | xx     | y  | zz                                                          | Description    | Power system                                                | Power module number | 0                                                           | 00           | Braking IGBT instantaneous over-current trip          |   |    |
|                                                                                                                                                                                                                           | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | xx                                                          | y      | zz | Description                                                 |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Power module number                                         | 0      | 00 | Braking IGBT instantaneous over-current trip                |                |                                                             |                     |                                                             |              |                                                       |   |    |
| Recommended actions:                                                                                                                                                                                                      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| <ul style="list-style-type: none"><li>• Check brake resistor wiring</li><li>• Check braking resistor value is greater than or equal to the minimum resistance value</li><li>• Check braking resistor insulation</li></ul> |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| OI dc                                                                                                                                                                                                                     | Power module over current detected from IGBT on state voltage monitoring                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| 109                                                                                                                                                                                                                       | The <i>OI dc</i> trip indicates that the short circuit protection for the drive output stage has been activated. The table below shows where the trip has been detected. This trip cannot be reset until 10 s after the trip was initiated.                                                                                                                                                                                                                                                                                                                                                                                   |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th></tr><tr><td>Control system</td><td>00</td><td>0</td><td>00</td></tr><tr><td>Power system</td><td>Power module number</td><td>0</td><td>00</td></tr></table>                                                                                                                                                                                                                                                                                                                                                                                                        | Source                                                      | xx     | y  | zz                                                          | Control system | 00                                                          | 0                   | 00                                                          | Power system | Power module number                                   | 0 | 00 |
|                                                                                                                                                                                                                           | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | xx                                                          | y      | zz |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | 00                                                          | 0      | 00 |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| Power system                                                                                                                                                                                                              | Power module number                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | 0                                                           | 00     |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| Recommended actions:                                                                                                                                                                                                      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| <ul style="list-style-type: none"><li>• Disconnect the motor cable at the drive end and check the motor and cable insulation with an insulation tester</li><li>• Replace the drive</li></ul>                              |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| Option Disable                                                                                                                                                                                                            | Option module does not acknowledge during drive mode changeover                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| 215                                                                                                                                                                                                                       | The <i>Option Disable</i> trip indicates that the option module did not acknowledge to the drive that communications with the drive has been stopped during the drive mode changeover with in the allocated time.                                                                                                                                                                                                                                                                                                                                                                                                             |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | Recommended trip: <ul style="list-style-type: none"><li>• Reset the trip</li><li>• If the trip persists, replace the option module</li></ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| Out Phase Loss                                                                                                                                                                                                            | Output phase loss detected                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| 98                                                                                                                                                                                                                        | The <i>Out Phase Loss</i> trip indicates that phase loss has been detected at the drive output.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>U phase detected as disconnected when drive enabled to run.</td></tr><tr><td>2</td><td>V phase detected as disconnected when drive enabled to run.</td></tr><tr><td>3</td><td>W phase detected as disconnected when drive enabled to run.</td></tr><tr><td>4</td><td>Output phase loss detected when the drive is running.</td></tr></table>                                                                                                                                                                                                                | Sub-trip                                                    | Reason | 1  | U phase detected as disconnected when drive enabled to run. | 2              | V phase detected as disconnected when drive enabled to run. | 3                   | W phase detected as disconnected when drive enabled to run. | 4            | Output phase loss detected when the drive is running. |   |    |
|                                                                                                                                                                                                                           | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Reason                                                      |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | U phase detected as disconnected when drive enabled to run. |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | V phase detected as disconnected when drive enabled to run. |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | 3                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | W phase detected as disconnected when drive enabled to run. |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| 4                                                                                                                                                                                                                         | Output phase loss detected when the drive is running.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| <b>NOTE</b>                                                                                                                                                                                                               |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| If Pr <b>05.042</b> = 1 the physical output phases are reversed, and so sub-trip 3 refers to physical output phase V and sub-trip 2 refers to physical output phase W.                                                    |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| Recommended actions:                                                                                                                                                                                                      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| <ul style="list-style-type: none"><li>• Check motor and drive connections</li><li>• To disable the trip set <i>Output Phase Loss Detection Enable</i> (06.059) = 0</li></ul>                                              |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| Over Speed                                                                                                                                                                                                                | Motor speed has exceeded the over speed threshold                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
| 7                                                                                                                                                                                                                         | In open loop mode, if the <i>Output Frequency</i> (05.001) exceeds the threshold set in <i>Over Speed Threshold</i> (03.008) in either direction an <i>Over Speed</i> trip is produced. In RFC-A and RFC-S mode, if the Speed Feedback (03.002) exceeds the <i>Over Speed Threshold</i> in Pr <b>03.008</b> in either direction an <i>Over Speed</i> trip is produced. If Pr <b>03.008</b> is set to 0.0 the threshold is then equal to 1.2 x the value set in Pr <b>01.006</b> .                                                                                                                                             |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | In RFC-A and RFC-S mode, if an SSI encoder is being used and Pr <b>03.047</b> is set to 0 an <i>Over Speed</i> trip will be produced when the encoder passes through the boundary between its maximum position and zero.                                                                                                                                                                                                                                                                                                                                                                                                      |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | Recommended actions:                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |
|                                                                                                                                                                                                                           | <ul style="list-style-type: none"><li>• Check the motor is not being driven by another part of the system</li><li>• Reduce the <i>Speed Controller Proportional Gain</i> (03.010) to reduce the speed overshoot (RFC-A, RFC-S modes only)</li><li>• If an SSI encoder is being used set Pr <b>03.047</b> to 1</li></ul> The above description relates to a standard Over Speed trip, however in RFC-S mode it is possible to produce an <i>Over Speed.1</i> trip. This is caused if the speed is allowed to exceed the safe level in RFC-S mode with flux weakening when <i>Enable High Speed Mode</i> (05.022) is set to -1. |                                                             |        |    |                                                             |                |                                                             |                     |                                                             |              |                                                       |   |    |

| Trip           | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                                           |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------|--------------------------------------------------|-----|----------------|-----|-----|--------------------------------------------|------------------|---------------------|----------------------|--------------------------------------------------|-----|------|------|--------|----|---|----|----------------|----|---|----------------------------------------------------------------------------|----------------|----|---|-------------------------------------------------------------------------------------------|
| Over Volts     | <b>DC bus voltage has exceeded the peak level or maximum continuous level for 15 seconds</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                                           |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
| 2              | <p>The <i>Over Volts</i> trip indicates that the DC bus voltage has exceeded the VM_DC_VOLTAGE[MAX] or VM_DC_VOLTAGE_SET[MAX] for 15 s. The trip threshold varies depending on voltage rating of the drive as shown below</p> <table><tr><th>Voltage rating</th><th>VM_DC_VOLTAGE[MAX]</th><th>VM_DC_VOLTAGE_SET[MAX]</th></tr><tr><td>200</td><td>415</td><td>410</td></tr><tr><td>400</td><td>830</td><td>815</td></tr><tr><td>575</td><td>990</td><td>970</td></tr><tr><td>690</td><td>1190</td><td>1175</td></tr></table> <p><b>Sub-trip Identification</b></p> <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th></tr><tr><td>Control system</td><td>00</td><td>0</td><td>01: Instantaneous trip when the DC bus voltage exceeds VM_DC_VOLTAGE[MAX].</td></tr><tr><td>Control system</td><td>00</td><td>0</td><td>02: Time delayed trip indicating that the DC bus voltage is above VM_DC_VOLTAGE_SET[MAX].</td></tr></table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Increase deceleration ramp (Pr <b>00.004</b>)</li><li>• Decrease the braking resistor value (staying above the minimum value)</li><li>• Check nominal AC supply level</li><li>• Check for supply disturbances which could cause the DC bus to rise</li><li>• Check motor insulation using an insulation tester</li></ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Voltage rating                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | VM_DC_VOLTAGE[MAX]                                                                        | VM_DC_VOLTAGE_SET[MAX]                           | 200 | 415            | 410 | 400 | 830                                        | 815              | 575                 | 990                  | 970                                              | 690 | 1190 | 1175 | Source | xx | y | zz | Control system | 00 | 0 | 01: Instantaneous trip when the DC bus voltage exceeds VM_DC_VOLTAGE[MAX]. | Control system | 00 | 0 | 02: Time delayed trip indicating that the DC bus voltage is above VM_DC_VOLTAGE_SET[MAX]. |
|                | Voltage rating                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | VM_DC_VOLTAGE[MAX]                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | VM_DC_VOLTAGE_SET[MAX]                                                                    |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | 200                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 415                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 410                                                                                       |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | 400                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 830                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 815                                                                                       |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | 575                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 990                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 970                                                                                       |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | 690                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 1190                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | 1175                                                                                      |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
| Source         | xx                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | y                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | zz                                                                                        |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
| Control system | 00                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 01: Instantaneous trip when the DC bus voltage exceeds VM_DC_VOLTAGE[MAX].                |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
| Control system | 00                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 02: Time delayed trip indicating that the DC bus voltage is above VM_DC_VOLTAGE_SET[MAX]. |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
| Phase Loss     | <b>Supply phase loss</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                                                                                           |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
| 32             | <p>The Phase Loss trip indicates that the drive has detected an input phase loss or large supply imbalance. Phase loss can be detected directly from the supply where the drive has a thyristor base charge system (Frame size 8 and above). If phase loss is detected using this method the drive trips immediately and the xx part of the sub-trip is set to 01. In all sizes of drive phase loss is also detected by monitoring the ripple in the DC bus voltage in which case the drive attempts to stop the drive before tripping unless bit 2 of <i>Action On Trip Detection</i> (10.037) is set to one. When phase loss is detected by monitoring the ripple in the DC bus voltage the xx part of the sub-trip is zero.</p> <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th></tr><tr><td>Control system</td><td>00</td><td>0</td><td>00: Phase loss detected from DC bus ripple</td></tr><tr><td>Power system (1)</td><td>Power module number</td><td>Rectifier number (2)</td><td>00: Phase loss detected directly from the supply</td></tr></table> <p>(1) Input phase loss detection can be disabled when the drive required to operate from the DC supply or from a single phase supply in <i>Input Phase Loss Detection Mode</i> (06.047).</p> <p>(2) For a parallel power-module system the rectifier number will be one as it is not possible to determine which rectifier has detected the fault.</p> <p>This trip does not occur in regen mode.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Check the AC supply voltage balance and level at full load</li><li>• Check the DC bus ripple level with an isolated oscilloscope</li><li>• Check the output current stability</li><li>• Check for mechanical resonance with the load</li><li>• Reduce the duty cycle</li><li>• Reduce the motor load</li><li>• Disable the phase loss detection, set Pr <b>06.047</b> to 2.</li></ul> | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | xx                                                                                        | y                                                | zz  | Control system | 00  | 0   | 00: Phase loss detected from DC bus ripple | Power system (1) | Power module number | Rectifier number (2) | 00: Phase loss detected directly from the supply |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | Source                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | xx                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | y                                                                                         | zz                                               |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | Control system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 00                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | 0                                                                                         | 00: Phase loss detected from DC bus ripple       |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | Power system (1)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               | Power module number                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Rectifier number (2)                                                                      | 00: Phase loss detected directly from the supply |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | Phasing Error                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | <b>RFC-S mode phasing failure due to incorrect phase angle</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |                                                                                           |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |
|                | 198                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | <p>The <i>Phasing Error</i> trip indicates that the phase offset angle in Pr <b>03.025</b> (or Pr <b>21.020</b> if the second motor map is being used) is incorrect if position feedback is being used and the drive is unable to control the motor correctly.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Check the encoder wiring</li><li>• Check the encoder signals for noise with an oscilloscope</li><li>• Check the encoder mechanical coupling</li><li>• Perform an auto-tune to measure the encoder phase angle or manually enter the correct phase angle into Pr <b>03.025</b></li><li>• Spurious <i>Phasing Error</i> trips can sometimes be seen in very dynamic applications. This trip can be disabled by setting the over-speed threshold in Pr <b>03.008</b> to a value greater than zero.</li></ul> <p>If sensorless control is being used this indicates that significant instability has occurred and the motor has accelerated without control.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"><li>• Ensure that the motor parameters are set-up correctly.</li><li>• Reduce the speed controller gains.</li></ul> |                                                                                           |                                                  |     |                |     |     |                                            |                  |                     |                      |                                                  |     |      |      |        |    |   |    |                |    |   |                                                                            |                |    |   |                                                                                           |

| Trip                                                                                                                                              | Diagnosis                                                                                                                                                            |                     |                   |                                                                       |                                                                                                                                                                                                                    |
|---------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------|-------------------|-----------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Power Comms                                                                                                                                       | Communication has been lost / errors detected between power, control and rectifier modules                                                                           |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| 90                                                                                                                                                | A <i>Power Comms</i> trip indicates a communications problem within the power system of the drive. The reason for the trip can be identified by the sub-trip number. |                     |                   |                                                                       |                                                                                                                                                                                                                    |
|                                                                                                                                                   | Type of drive                                                                                                                                                        | xx                  | y                 | zz                                                                    |                                                                                                                                                                                                                    |
|                                                                                                                                                   | Single power module system                                                                                                                                           | 01                  | Rectifier number* | 00: Excessive communications errors detected by the rectifier module. |                                                                                                                                                                                                                    |
|                                                                                                                                                   | * For a parallel power-module system the rectifier number will be one as it is not possible to determine which rectifier has detected the fault.                     |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| Recommended actions:                                                                                                                              |                                                                                                                                                                      |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| • Hardware fault – Contact the supplier of the drive                                                                                              |                                                                                                                                                                      |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| Power Data                                                                                                                                        | Power system configuration data error                                                                                                                                |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| 220                                                                                                                                               | The <i>Power Data</i> trip indicates that there is an error in the configuration data stored in the power system.                                                    |                     |                   |                                                                       |                                                                                                                                                                                                                    |
|                                                                                                                                                   | Source                                                                                                                                                               | xx                  | y                 | zz                                                                    | Description                                                                                                                                                                                                        |
|                                                                                                                                                   | Control system                                                                                                                                                       | 00                  | 0                 | 02                                                                    | There is no data table to be uploaded to the control board                                                                                                                                                         |
|                                                                                                                                                   | Control system                                                                                                                                                       | 00                  | 0                 | 03                                                                    | The power system data table is bigger than the space available in the control pod to store it.                                                                                                                     |
|                                                                                                                                                   | Control system                                                                                                                                                       | 00                  | 0                 | 04                                                                    | The size of the table given in the table is incorrect.                                                                                                                                                             |
|                                                                                                                                                   | Control system                                                                                                                                                       | 00                  | 0                 | 05                                                                    | Table CRC error.                                                                                                                                                                                                   |
|                                                                                                                                                   | Control system                                                                                                                                                       | 00                  | 0                 | 06                                                                    | The version number of the generator software that produced the table is too low. i.e. a table from a newer generator is required that includes features that have been added to the table that may not be present. |
|                                                                                                                                                   | Control system                                                                                                                                                       | 00                  | 0                 | 07                                                                    | The power board data table does not match the power board hardware identifier.                                                                                                                                     |
|                                                                                                                                                   | Power system                                                                                                                                                         | 01                  | 0                 | 00                                                                    | The power data table used internally by the power module has an error. (For a multi-power module drive this indicates any error with the code tables in the power system).                                         |
|                                                                                                                                                   | Power system                                                                                                                                                         | 01                  | 0                 | 01                                                                    | The power data table that should be uploaded to the control system on power up has an error.                                                                                                                       |
|                                                                                                                                                   | Power system                                                                                                                                                         | 01                  | 0                 | 02                                                                    | The power data table used internally by the power module does not match the hardware identification of the power module.                                                                                           |
|                                                                                                                                                   | Recommended actions:                                                                                                                                                 |                     |                   |                                                                       |                                                                                                                                                                                                                    |
|                                                                                                                                                   | • Hardware fault – Contact the supplier of the drive                                                                                                                 |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| Power Down Save                                                                                                                                   | Power down save error                                                                                                                                                |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| 37                                                                                                                                                | The <i>Power Down Save</i> trip indicates that an error has been detected in the power down save parameters saved in non-volatile memory.                            |                     |                   |                                                                       |                                                                                                                                                                                                                    |
|                                                                                                                                                   | Recommended actions:                                                                                                                                                 |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| • Perform a 1001 save in Pr mm.000 to ensure that the trip doesn't occur the next time the drive is powered up.                                   |                                                                                                                                                                      |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| PSU                                                                                                                                               | Internal power supply fault                                                                                                                                          |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| 5                                                                                                                                                 | The <i>PSU</i> trip indicates that one or more internal power supply rails are outside limits or overloaded.                                                         |                     |                   |                                                                       |                                                                                                                                                                                                                    |
|                                                                                                                                                   | Source                                                                                                                                                               | xx                  | y                 | zz                                                                    | Description                                                                                                                                                                                                        |
|                                                                                                                                                   | Control system                                                                                                                                                       | 00                  | 0                 | 00                                                                    | Internal power supply overload                                                                                                                                                                                     |
|                                                                                                                                                   | Power system                                                                                                                                                         | Power module number | Rectifier number* |                                                                       | Rectifier internal power supply overload                                                                                                                                                                           |
| * For a parallel power-module system the rectifier number will be zero as it is not possible to determine which rectifier has detected the fault. |                                                                                                                                                                      |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| Recommended actions:                                                                                                                              |                                                                                                                                                                      |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| • Remove any option modules and perform a reset                                                                                                   |                                                                                                                                                                      |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| • Remove encoder connection and perform a reset                                                                                                   |                                                                                                                                                                      |                     |                   |                                                                       |                                                                                                                                                                                                                    |
| • Hardware fault within the drive – return the drive to the supplier                                                                              |                                                                                                                                                                      |                     |                   |                                                                       |                                                                                                                                                                                                                    |

| Trip                                                              | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
|-------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------|-------------|----|-------------------------------------------------------|----|------------------------------------------------------------|-----------|--------------------------------------------------------------------------------------------------|-----------|--------------------------|-----------|--------------------------|----------------|------------------------------|
| <b>PSU 24V</b>                                                    | <b>24V internal power supply overload</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 9                                                                 | <p>The total user load of the drive and option modules has exceeded the internal 24 V power supply limit. The user load consists of the drive digital outputs and main encoder supply.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Reduce the load and reset</li> <li>• Provide an external 24 V power supply on control terminal 2</li> <li>• Remove all option modules</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| <b>Rating Mismatch</b>                                            | <b>Power stage recognition: Multi module voltage or current rating mismatch</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 223                                                               | <p>The <i>Rating Mismatch</i> trip indicates that there is a voltage rating or current rating mismatch in a multi-module drive system. This trip is only applicable to modular drives that are connected in parallel. A mixture of power modules with different voltage or current ratings within the same multi-module drive system is not allowed and will cause a <i>Rating Mismatch</i> trip.</p> <p><b>Recommended action:</b></p> <ul style="list-style-type: none"> <li>• Ensure that all modules in a multi-modular drive system are of the same frame size and rating (voltage and current)</li> <li>• Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| <b>Rectifier Set-up</b>                                           | <b>A rectifier has not been set-up correctly in a multi-power module system</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 94                                                                | <p>A rectifier has not been set-up correctly in a multi-power module system</p> <p><b>Recommended action:</b></p> <ul style="list-style-type: none"> <li>• Check the inter-power module wiring</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| <b>Reserved</b>                                                   | <b>Reserved trips</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 01<br>95<br>104 – 108<br>165 – 168<br>170 – 173<br>222, 228 - 246 | <p>These trip numbers are reserved trip numbers for future use. These trips should not be used by the user application programs.</p> <table border="1"> <thead> <tr> <th>Trip Number</th><th>Description</th></tr> </thead> <tbody> <tr> <td>01</td><td>Reserved resettable trip</td></tr> <tr> <td>95</td><td>Reserved resettable trip</td></tr> <tr> <td>104 - 108</td><td>Reserved resettable trip</td></tr> <tr> <td>165 - 168</td><td>Reserved resettable trip</td></tr> <tr> <td>170 - 173</td><td>Reserved resettable trip</td></tr> <tr> <td>222, 228 - 246</td><td>Reserved non-resettable trip</td></tr> </tbody> </table>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Trip Number | Description | 01 | Reserved resettable trip                              | 95 | Reserved resettable trip                                   | 104 - 108 | Reserved resettable trip                                                                         | 165 - 168 | Reserved resettable trip | 170 - 173 | Reserved resettable trip | 222, 228 - 246 | Reserved non-resettable trip |
| Trip Number                                                       | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 01                                                                | Reserved resettable trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 95                                                                | Reserved resettable trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 104 - 108                                                         | Reserved resettable trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 165 - 168                                                         | Reserved resettable trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 170 - 173                                                         | Reserved resettable trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 222, 228 - 246                                                    | Reserved non-resettable trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| <b>Resistance</b>                                                 | <b>Measured resistance has exceeded the parameter range</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 33                                                                | <p>This trip indicates that either the value being used for motor stator resistance is too high or that an attempt to do a test involving measuring motor stator resistance has failed. The maximum for the stator resistance parameters is generally higher than the maximum value that can be used in the control algorithms. If the value exceeds <math>(V_{FS} / v2) / Full\ Scale\ Current\ Kc</math> (11.061), where <math>V_{FS}</math> is the full scale DC bus voltage then this trip is initiated. If the value is the result of a measurement made by the drive then sub-trip 1 is applied, or if it is because the parameter has been changed by the user then sub-trip 3 is applied. During the stator resistance section of auto-tuning an additional test is performed to measured the drive inverter characteristics to provide the compensation necessary for dead-times. If the inverter characteristic measurement fails then sub-trip 2 is applied.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>Measured stator resistance exceeded the allowed range</td></tr> <tr> <td>2</td><td>It was not possible to measure the inverter characteristic</td></tr> <tr> <td>3</td><td>The stator resistance associated with the presently selected motor map exceeds the allowed range</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Check that the value that has been entered in the stator resistance does not exceed the allowed range (for the presently selected motor map)</li> <li>• Check the motor cable / connections</li> <li>• Check the integrity of the motor stator winding using a insulation tester</li> <li>• Check the motor phase to phase resistance at the drive terminals</li> <li>• Check the motor phase to phase resistance at the motor terminals</li> <li>• Ensure the stator resistance of the motor falls within the range of the drive model</li> <li>• Select fixed boost mode (Pr <b>05.014</b> = Fixed) and verify the output current waveforms with an oscilloscope</li> <li>• Replace the motor</li> </ul> | Sub-trip    | Reason      | 1  | Measured stator resistance exceeded the allowed range | 2  | It was not possible to measure the inverter characteristic | 3         | The stator resistance associated with the presently selected motor map exceeds the allowed range |           |                          |           |                          |                |                              |
| Sub-trip                                                          | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 1                                                                 | Measured stator resistance exceeded the allowed range                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 2                                                                 | It was not possible to measure the inverter characteristic                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |
| 3                                                                 | The stator resistance associated with the presently selected motor map exceeds the allowed range                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |             |             |    |                                                       |    |                                                            |           |                                                                                                  |           |                          |           |                          |                |                              |

| Trip                                                                                                                                                                                                                                                                                                                                                                                                                       | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                                                                                                                          |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------|---|------------------------------------|---|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|---|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|----------------------------------------------------------|
| Slot4 Different                                                                                                                                                                                                                                                                                                                                                                                                            | Ethernet interface in slot 4 has changed ( <i>Unidrive M700 / M702</i> )                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                                                                                                                                                                                          |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
| 254                                                                                                                                                                                                                                                                                                                                                                                                                        | The <i>Slot4 Different</i> trip indicates that the Ethernet interface in slot 4 has changed / not found. The reason for the trip can be identified by the sub-trip number.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                                          |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            | <table><tr><th>Sub-trip</th><th>Reason</th></tr><tr><td>1</td><td>No module was installed previously</td></tr><tr><td>2</td><td>A module with the same identifier is installed, but the set-up menu for this option slot has been changed, and so default parameters have been loaded for this menu.</td></tr><tr><td>3</td><td>A module with the same identifier is installed, but the applications menu for this option slot has been changed, and so default parameters have been loaded for this menu.</td></tr><tr><td>4</td><td>A module with the same identifier is installed, but the set-up and applications menu for this option slot have been changed, and so default parameters have been loaded for these menus.</td></tr><tr><td>&gt;99</td><td>Shows the identifier of the module previously installed.</td></tr></table> | Sub-trip                                                                                                                                                                                 | Reason | 1 | No module was installed previously | 2 | A module with the same identifier is installed, but the set-up menu for this option slot has been changed, and so default parameters have been loaded for this menu. | 3 | A module with the same identifier is installed, but the applications menu for this option slot has been changed, and so default parameters have been loaded for this menu. | 4 | A module with the same identifier is installed, but the set-up and applications menu for this option slot have been changed, and so default parameters have been loaded for these menus. | >99 | Shows the identifier of the module previously installed. |
|                                                                                                                                                                                                                                                                                                                                                                                                                            | Sub-trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Reason                                                                                                                                                                                   |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            | 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | No module was installed previously                                                                                                                                                       |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            | 2                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | A module with the same identifier is installed, but the set-up menu for this option slot has been changed, and so default parameters have been loaded for this menu.                     |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            | 3                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | A module with the same identifier is installed, but the applications menu for this option slot has been changed, and so default parameters have been loaded for this menu.               |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            | 4                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | A module with the same identifier is installed, but the set-up and applications menu for this option slot have been changed, and so default parameters have been loaded for these menus. |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            | >99                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       | Shows the identifier of the module previously installed.                                                                                                                                 |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
| <b>Recommended actions:</b>                                                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                          |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
| <ul style="list-style-type: none"><li>• Turn off the power, ensure that the correct option module is installed in the option slot and re-apply the power.</li><li>• Confirm that the currently installed option module is correct, ensure the option module parameters are set correctly and perform a <i>User Save</i> in Pr <b>mm.000</b>.</li><li>• If the trip persists - Contact the supplier of the drive.</li></ul> |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                          |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                          |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                          |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |
|                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                                                          |        |   |                                    |   |                                                                                                                                                                      |   |                                                                                                                                                                            |   |                                                                                                                                                                                          |     |                                                          |

| Trip                                                                                                                                                                                                                                                   | Diagnosis                                                                                                                                                                         |                                                    |                                                         |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------|---------------------------------------------------------|
| Slot4 Error                                                                                                                                                                                                                                            | Ethernet interface in slot 4 has detected a fault ( <i>Unidrive M700 / M702</i> )                                                                                                 |                                                    |                                                         |
| 252                                                                                                                                                                                                                                                    | The <i>Slot4 Error</i> trip indicates that the Ethernet interface in slot 4 on the drive has detected an error. The reason for the trip can be identified by the sub-trip number. |                                                    |                                                         |
|                                                                                                                                                                                                                                                        | Sub-trip                                                                                                                                                                          | Trip string                                        | Description                                             |
|                                                                                                                                                                                                                                                        | 100                                                                                                                                                                               | Link Loss                                          | Network link has been lost                              |
|                                                                                                                                                                                                                                                        | 101                                                                                                                                                                               | E/IP Timeout                                       | An EtherNet/IP RPI timeout trip has occurred            |
|                                                                                                                                                                                                                                                        | 102                                                                                                                                                                               | E/IP Read Param                                    | Invalid read consistency parameter                      |
|                                                                                                                                                                                                                                                        | 103                                                                                                                                                                               | E/IP Write Param                                   | Invalid write consistency parameter                     |
|                                                                                                                                                                                                                                                        | 104                                                                                                                                                                               | E/IP Fault                                         | An unexpected EtherNet/IP error has occurred            |
|                                                                                                                                                                                                                                                        | 105                                                                                                                                                                               | Modbus Timeout                                     | The Modbus connection has timed out                     |
|                                                                                                                                                                                                                                                        | 106                                                                                                                                                                               | DA-RT Timeout                                      | DA-RX Rx link has timeout                               |
|                                                                                                                                                                                                                                                        | 107                                                                                                                                                                               | DA-RT Rx Late                                      | Rx data was received late                               |
|                                                                                                                                                                                                                                                        | 108                                                                                                                                                                               | INIT Switch                                        | Ethernet switch initialisation error                    |
|                                                                                                                                                                                                                                                        | 109                                                                                                                                                                               | INIT PTP                                           | IEEE1588 (Precision Time Protocol) initialisation error |
|                                                                                                                                                                                                                                                        | 110                                                                                                                                                                               | INIT DA-RT                                         | Cyclic data initialisation error                        |
|                                                                                                                                                                                                                                                        | 111                                                                                                                                                                               | INIT Modbus                                        | Modbus TCP initialisation error                         |
|                                                                                                                                                                                                                                                        | 112                                                                                                                                                                               | INIT SMTP                                          | Email (SMTP) initialisation error                       |
|                                                                                                                                                                                                                                                        | 113                                                                                                                                                                               | INIT EtherNet/IP                                   | Ethernet/IP initialisation error                        |
|                                                                                                                                                                                                                                                        | 114                                                                                                                                                                               | INIT TCP/IP                                        | TCP/IP initialisation error                             |
|                                                                                                                                                                                                                                                        | 115                                                                                                                                                                               | Ethernet Failure                                   | Ethernet controller initialisation error                |
|                                                                                                                                                                                                                                                        | 116                                                                                                                                                                               | E/IP PLC IDLE                                      | Ethernet/IP PLC Idle                                    |
|                                                                                                                                                                                                                                                        | 117                                                                                                                                                                               | Sync Task ORun                                     | Synchronous task overrun                                |
|                                                                                                                                                                                                                                                        | 118                                                                                                                                                                               | INIT Param Chann                                   | Parameter channel initialization error                  |
|                                                                                                                                                                                                                                                        | 119                                                                                                                                                                               | Link Overload                                      | Too many links to be handled in the same cycle          |
|                                                                                                                                                                                                                                                        | 120                                                                                                                                                                               | Mcast Over Limit                                   | Too many multicast addresses being used                 |
|                                                                                                                                                                                                                                                        | 121                                                                                                                                                                               | Init Profinet                                      | Profinet initialisation error                           |
|                                                                                                                                                                                                                                                        | 122                                                                                                                                                                               | Profinet Start                                     | Profinet start error                                    |
|                                                                                                                                                                                                                                                        | 123                                                                                                                                                                               | Profinet Plug                                      | Profinet failed to load the slots                       |
|                                                                                                                                                                                                                                                        | 124                                                                                                                                                                               | Invalid IM                                         | Invalid Identification and Maintenance data             |
|                                                                                                                                                                                                                                                        | 125                                                                                                                                                                               | CPM Watchdog                                       | Profinet cyclic timeout error                           |
|                                                                                                                                                                                                                                                        | 200                                                                                                                                                                               | Software Fault                                     | Software Fault                                          |
|                                                                                                                                                                                                                                                        | 201                                                                                                                                                                               | BG Overrun                                         | Background task overrun                                 |
|                                                                                                                                                                                                                                                        | 202                                                                                                                                                                               | Firmware Invalid                                   | Firmware is not compatible for the hardware version     |
|                                                                                                                                                                                                                                                        | 203                                                                                                                                                                               | Drive Unknown                                      | Unknown drive type                                      |
| 204                                                                                                                                                                                                                                                    | DriveUnsupported                                                                                                                                                                  | Unsupported drive type                             |                                                         |
| 205                                                                                                                                                                                                                                                    | Mode Unknown                                                                                                                                                                      | Unknown drive mode                                 |                                                         |
| 206                                                                                                                                                                                                                                                    | Mode Unsupported                                                                                                                                                                  | Unsupported drive mode                             |                                                         |
| 207                                                                                                                                                                                                                                                    | FLASH Error                                                                                                                                                                       | Corrupted Non-volatile FLASH                       |                                                         |
| 208                                                                                                                                                                                                                                                    | Database Init                                                                                                                                                                     | Database initialization error                      |                                                         |
| 209                                                                                                                                                                                                                                                    | File System Init                                                                                                                                                                  | File system initialization error                   |                                                         |
| 210                                                                                                                                                                                                                                                    | Mem Allocation                                                                                                                                                                    | Memory allocation error                            |                                                         |
| 211                                                                                                                                                                                                                                                    | Filesystem Error                                                                                                                                                                  | File system error                                  |                                                         |
| 212                                                                                                                                                                                                                                                    | Config Save                                                                                                                                                                       | Configuration file save error                      |                                                         |
| 213                                                                                                                                                                                                                                                    | Over Temperature                                                                                                                                                                  | Option module over temperature                     |                                                         |
| 214                                                                                                                                                                                                                                                    | Drive Timeout                                                                                                                                                                     | The drive has not responded within watchdog period |                                                         |
| 215                                                                                                                                                                                                                                                    | eCMP Comms Error                                                                                                                                                                  | eCMP communication failure                         |                                                         |
| 216                                                                                                                                                                                                                                                    | TO eCMP Slot1                                                                                                                                                                     | eCMP communication to slot 1 timeout               |                                                         |
| 217                                                                                                                                                                                                                                                    | TO eCMP Slot2                                                                                                                                                                     | eCMP communication to slot 2 timeout               |                                                         |
| 228                                                                                                                                                                                                                                                    | EEPROM Error                                                                                                                                                                      | EEPROM Initialisation error                        |                                                         |
| <b>Recommended actions:</b>                                                                                                                                                                                                                            |                                                                                                                                                                                   |                                                    |                                                         |
| <ul style="list-style-type: none"><li>Identify the reason for the trip from the trip string or from sub-trip number and resolve the error.</li><li>Reset the trip, If the trip persists, Hardware fault - Contact the supplier of the drive.</li></ul> |                                                                                                                                                                                   |                                                    |                                                         |

| Trip                                                                                                                                                                                                                                                                                                                                                                          | Diagnosis                                                                                                                                                                                                                                                                                                                                        |                                                                                                                                                                                          |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Slot4 HF                                                                                                                                                                                                                                                                                                                                                                      | Ethernet interface in slot 4 hardware fault (Unidrive M700 / M702)                                                                                                                                                                                                                                                                               |                                                                                                                                                                                          |
| 250                                                                                                                                                                                                                                                                                                                                                                           | The <i>Slot4 HF</i> trip indicates that the Ethernet interface in slot 4 cannot operate. The reason for the error can be identified by the sub-trip number.                                                                                                                                                                                      |                                                                                                                                                                                          |
|                                                                                                                                                                                                                                                                                                                                                                               | Sub-trip                                                                                                                                                                                                                                                                                                                                         | Reason                                                                                                                                                                                   |
|                                                                                                                                                                                                                                                                                                                                                                               | 1                                                                                                                                                                                                                                                                                                                                                | The module category cannot be identified                                                                                                                                                 |
|                                                                                                                                                                                                                                                                                                                                                                               | 2                                                                                                                                                                                                                                                                                                                                                | All the required customized menu table information has not been supplied or the tables supplied are corrupt                                                                              |
|                                                                                                                                                                                                                                                                                                                                                                               | 3                                                                                                                                                                                                                                                                                                                                                | There is insufficient memory available to allocate the comms buffers for this module                                                                                                     |
|                                                                                                                                                                                                                                                                                                                                                                               | 4                                                                                                                                                                                                                                                                                                                                                | The module has not indicated that it is running correctly during drive power-up                                                                                                          |
|                                                                                                                                                                                                                                                                                                                                                                               | 5                                                                                                                                                                                                                                                                                                                                                | Module has been removed after power-up or it has stopped working                                                                                                                         |
|                                                                                                                                                                                                                                                                                                                                                                               | 6                                                                                                                                                                                                                                                                                                                                                | The module has not indicated that it has stopped accessing drive parameters during a drive mode change                                                                                   |
|                                                                                                                                                                                                                                                                                                                                                                               | 7                                                                                                                                                                                                                                                                                                                                                | The module has failed to acknowledge that a request has been made to reset the drive processor                                                                                           |
|                                                                                                                                                                                                                                                                                                                                                                               | 8                                                                                                                                                                                                                                                                                                                                                | The drive failed to correctly read the menu table from the module during drive power up                                                                                                  |
|                                                                                                                                                                                                                                                                                                                                                                               | 9                                                                                                                                                                                                                                                                                                                                                | The drive failed to upload menu tables from the module and timed out (5 s)                                                                                                               |
|                                                                                                                                                                                                                                                                                                                                                                               | 10                                                                                                                                                                                                                                                                                                                                               | Menu table CRC invalid                                                                                                                                                                   |
|                                                                                                                                                                                                                                                                                                                                                                               | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Ensure the Ethernet interface is installed correctly</li><li>• Hardware fault - Contact the supplier of the drive.</li></ul>                                                                                                                                                 |                                                                                                                                                                                          |
| Slot4 Not Fitted                                                                                                                                                                                                                                                                                                                                                              | Ethernet interface in slot 4 has been removed (Unidrive M700 / M702)                                                                                                                                                                                                                                                                             |                                                                                                                                                                                          |
| 253                                                                                                                                                                                                                                                                                                                                                                           | The <i>Slot4 Not Fitted</i> trip indicates that the Ethernet interface in slot 4 on the drive has been removed since the last power-up.                                                                                                                                                                                                          |                                                                                                                                                                                          |
|                                                                                                                                                                                                                                                                                                                                                                               | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Ensure the Ethernet interface is installed correctly</li><li>• Hardware fault - Contact the supplier of the drive.</li></ul>                                                                                                                                                 |                                                                                                                                                                                          |
| Slot4 Watchdog                                                                                                                                                                                                                                                                                                                                                                | Ethernet interface watchdog service error (Unidrive M700 / M702)                                                                                                                                                                                                                                                                                 |                                                                                                                                                                                          |
| 251                                                                                                                                                                                                                                                                                                                                                                           | The <i>Slot4 Watchdog</i> trip indicates that the Ethernet interface installed in slot 4 has started the option watchdog function and then failed to service the watchdog correctly.                                                                                                                                                             |                                                                                                                                                                                          |
|                                                                                                                                                                                                                                                                                                                                                                               | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Hardware fault - Contact the supplier of the drive.</li></ul>                                                                                                                                                                                                                |                                                                                                                                                                                          |
| Slot App Menu                                                                                                                                                                                                                                                                                                                                                                 | Application menu Customization conflict error                                                                                                                                                                                                                                                                                                    |                                                                                                                                                                                          |
| 216                                                                                                                                                                                                                                                                                                                                                                           | The Slot App Menu trip indicates that more than one option slot has requested to customize the application menus 18, 19 and 20. The sub-trip number indicates which option slot has been allowed to customize the menus.                                                                                                                         |                                                                                                                                                                                          |
|                                                                                                                                                                                                                                                                                                                                                                               | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Ensure that only one of the Application modules is configured to customize the application menus 18, 19 and 20</li></ul>                                                                                                                                                     |                                                                                                                                                                                          |
| SlotX Different                                                                                                                                                                                                                                                                                                                                                               | Option module in option slot X has changed                                                                                                                                                                                                                                                                                                       |                                                                                                                                                                                          |
| 204<br>209<br>214                                                                                                                                                                                                                                                                                                                                                             | The <i>SlotX Different</i> trip indicates that the option module in option slot X on the drive is a different type to that installed when parameters were last saved on the drive. The sub-trip number gives the identification code of the module that was originally fitted. The reason for the trip can be identified by the sub-trip number. |                                                                                                                                                                                          |
|                                                                                                                                                                                                                                                                                                                                                                               | Sub-trip                                                                                                                                                                                                                                                                                                                                         | Reason                                                                                                                                                                                   |
|                                                                                                                                                                                                                                                                                                                                                                               | 1                                                                                                                                                                                                                                                                                                                                                | No module was installed previously                                                                                                                                                       |
|                                                                                                                                                                                                                                                                                                                                                                               | 2                                                                                                                                                                                                                                                                                                                                                | A module with the same identifier is installed, but the set-up menu for this option slot has been changed, and so default parameters have been loaded for this menu.                     |
|                                                                                                                                                                                                                                                                                                                                                                               | 3                                                                                                                                                                                                                                                                                                                                                | A module with the same identifier is installed, but the applications menu for this option slot has been changed, and so default parameters have been loaded for this menu.               |
|                                                                                                                                                                                                                                                                                                                                                                               | 4                                                                                                                                                                                                                                                                                                                                                | A module with the same identifier is installed, but the set-up and applications menu for this option slot have been changed, and so default parameters have been loaded for these menus. |
|                                                                                                                                                                                                                                                                                                                                                                               | >99                                                                                                                                                                                                                                                                                                                                              | Shows the identifier of the module previously installed.                                                                                                                                 |
| <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Turn off the power, ensure the correct option modules are installed in the correct option slots and re-apply the power.</li><li>• Confirm that the currently installed option module is correct, ensure option module parameters are set correctly and perform a user save in Pr <b>mm.000</b>.</li></ul> |                                                                                                                                                                                                                                                                                                                                                  |                                                                                                                                                                                          |

| Trip                    | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
|-------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------|--------|---|------------------------------------------|---|-------------------------------------------------------------------------------------------------------------|---|--------------------------------------------------------------------------------------|---|---------------------------------------------------------------------------------|---|------------------------------------------------------------------|---|--------------------------------------------------------------------------------------------------------|---|------------------------------------------------------------------------------------------------|---|-----------------------------------------------------------------------------------------|---|----------------------------------------------------------------------------|----|------------------------|
| <b>SlotX Error</b>      | <b>Option module in option slot X has detected a fault</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 202<br>207<br>212       | <p>The <i>SlotX Error</i> trip indicates that the option module in option slot X on the drive has detected an error. The reason for the error can be identified by the sub-trip number.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>See the relevant <i>Option Module User Guide</i> for details of the trip</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| <b>SlotX HF</b>         | <b>Option module X hardware fault</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 200<br>205<br>210       | <p>The <i>SlotX HF</i> trip indicates that the option module in option slot X cannot operate. The possible causes of the trip can be identified by the sub-trip number.</p> <table border="1"> <thead> <tr> <th>Sub-trip</th><th>Reason</th></tr> </thead> <tbody> <tr> <td>1</td><td>The module category cannot be identified</td></tr> <tr> <td>2</td><td>All the required customized menu table information has not been supplied or the tables supplied are corrupt</td></tr> <tr> <td>3</td><td>There is insufficient memory available to allocate the comms buffers for this module</td></tr> <tr> <td>4</td><td>The module has not indicated that it is running correctly during drive power-up</td></tr> <tr> <td>5</td><td>Module has been removed after power-up or it has stopped working</td></tr> <tr> <td>6</td><td>The module has not indicated that it has stopped accessing drive parameters during a drive mode change</td></tr> <tr> <td>7</td><td>The module has failed to acknowledge that a request has been made to reset the drive processor</td></tr> <tr> <td>8</td><td>The drive failed to correctly read the menu table from the module during drive power up</td></tr> <tr> <td>9</td><td>The drive failed to upload menu tables from the module and timed out (5 s)</td></tr> <tr> <td>10</td><td>Menu table CRC invalid</td></tr> </tbody> </table> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure the option module is installed correctly</li> <li>Replace the option module</li> <li>Replace the drive</li> </ul> | Sub-trip | Reason | 1 | The module category cannot be identified | 2 | All the required customized menu table information has not been supplied or the tables supplied are corrupt | 3 | There is insufficient memory available to allocate the comms buffers for this module | 4 | The module has not indicated that it is running correctly during drive power-up | 5 | Module has been removed after power-up or it has stopped working | 6 | The module has not indicated that it has stopped accessing drive parameters during a drive mode change | 7 | The module has failed to acknowledge that a request has been made to reset the drive processor | 8 | The drive failed to correctly read the menu table from the module during drive power up | 9 | The drive failed to upload menu tables from the module and timed out (5 s) | 10 | Menu table CRC invalid |
| Sub-trip                | Reason                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 1                       | The module category cannot be identified                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 2                       | All the required customized menu table information has not been supplied or the tables supplied are corrupt                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 3                       | There is insufficient memory available to allocate the comms buffers for this module                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 4                       | The module has not indicated that it is running correctly during drive power-up                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 5                       | Module has been removed after power-up or it has stopped working                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 6                       | The module has not indicated that it has stopped accessing drive parameters during a drive mode change                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 7                       | The module has failed to acknowledge that a request has been made to reset the drive processor                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 8                       | The drive failed to correctly read the menu table from the module during drive power up                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 9                       | The drive failed to upload menu tables from the module and timed out (5 s)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 10                      | Menu table CRC invalid                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| <b>SlotX Not Fitted</b> | <b>Option module in option slot X has been removed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 203<br>208<br>213       | <p>The <i>SlotX Not Fitted</i> trip indicates that the option module in option slot X on the drive has been removed since the last power up.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Ensure the option module is installed correctly.</li> <li>Re-install the option module.</li> <li>To confirm that the removed option module is no longer required perform a save function in Pr <b>mm.000</b>.</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| <b>SlotX Watchdog</b>   | <b>Option module watchdog function service error</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 201<br>206<br>211       | <p>The <i>SlotX Watchdog</i> trip indicates that the option module installed in Slot X has started the option watchdog function and then failed to service the watchdog correctly.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Replace the option module</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| <b>Soft Start</b>       | <b>Soft start relay failed to close, soft start monitor failed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 226                     | <p>The <i>Soft Start</i> trip indicates that the soft start relay in the drive failed to close or the soft start monitoring circuit has failed.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Hardware fault – Contact the supplier of the drive</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| <b>Stored HF</b>        | <b>Hardware trip has occurred during last power down</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |
| 221                     | <p>The <i>Stored HF</i> trip indicates that a hardware trip (HF01 –HF20) has occurred and the drive has been power cycled. The sub-trip number identifies the HF trip i.e. stored HF.17.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>Enter 1299 in Pr <b>mm.000</b> and press reset to clear the trip</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |          |        |   |                                          |   |                                                                                                             |   |                                                                                      |   |                                                                                 |   |                                                                  |   |                                                                                                        |   |                                                                                                |   |                                                                                         |   |                                                                            |    |                        |

| Trip                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
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| Sub-array RAM                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | RAM allocation error                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| 227                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | The Sub-array RAM indicates that an option module, derivative image or user program image has requested more parameter RAM than is allowed. The RAM allocation is checked in order of resulting sub-trip numbers, and so the failure with the highest sub-trip number is given. The sub-trip is calculated as (parameter size) + (parameter type) + sub-array number.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | <table><tr><th>Parameter size</th><th>Value</th></tr><tr><td>1 bit</td><td>1000</td></tr><tr><td>8 bit</td><td>2000</td></tr><tr><td>16 bit</td><td>3000</td></tr><tr><td>32 bit</td><td>4000</td></tr><tr><td>64 bit</td><td>5000</td></tr></table>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                      | Parameter size         | Value                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 1 bit  | 1000    | 8 bit              | 2000         | 16 bit      | 3000                 | 32 bit                 | 4000                                                                                   | 64 bit             | 5000                 | <table><tr><th>Parameter type</th><th>Value</th></tr><tr><td>Volatile</td><td>0</td></tr><tr><td>User save</td><td>100</td></tr><tr><td>Power-down save</td><td>200</td></tr></table> |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Parameter type | Value                | Volatile                   | 0                    | User save | 100                  | Power-down save        | 200             |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
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| <table><tr><th>Sub-array</th><th>Menus</th><th>Value</th></tr><tr><td>Applications menus</td><td>18-20</td><td>1</td></tr><tr><td>Derivative image</td><td>29</td><td>2</td></tr><tr><td>User program image</td><td>30</td><td>3</td></tr><tr><td>Option slot 1 set-up</td><td>15</td><td>4</td></tr><tr><td>Option slot 1 applications</td><td>25</td><td>5</td></tr><tr><td>Option slot 2 set-up</td><td>16</td><td>6</td></tr><tr><td>Option slot 2 applications</td><td>26</td><td>7</td></tr><tr><td>Option slot 3 set-up</td><td>17</td><td>8</td></tr><tr><td>Option slot 3 applications</td><td>27</td><td>9</td></tr><tr><td>Option slot 4 set-up</td><td>24</td><td>10</td></tr><tr><td>Option slot 4 applications</td><td>28</td><td>11</td></tr></table> |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                      |                        | Sub-array                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | Menus  | Value   | Applications menus | 18-20        | 1           | Derivative image     | 29                     | 2                                                                                      | User program image | 30                   | 3                                                                                                                                                                                     | Option slot 1 set-up                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | 15             | 4                    | Option slot 1 applications | 25                   | 5         | Option slot 2 set-up | 16                     | 6               | Option slot 2 applications | 26                   | 7                      | Option slot 3 set-up          | 17  | 8                    | Option slot 3 applications | 27                   | 9            | Option slot 4 set-up | 24                | 10          | Option slot 4 applications | 28 | 11 |
| Sub-array                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | Menus                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | Value                |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Applications menus                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 18-20                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | 1                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Derivative image                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     | 29                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 2                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| User program image                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | 30                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 3                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Option slot 1 set-up                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 15                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 4                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Option slot 1 applications                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | 25                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 5                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Option slot 2 set-up                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 16                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 6                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Option slot 2 applications                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | 26                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 7                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Option slot 3 set-up                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 17                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 8                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Option slot 3 applications                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | 27                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 9                    |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Option slot 4 set-up                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 | 24                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 10                   |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Option slot 4 applications                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           | 28                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | 11                   |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Temp Feedback                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        | Internal thermistor has failed                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| 218                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | The <i>Temp Feedback</i> trip indicates that an internal thermistor has failed. The thermistor location can be identified by the sub-trip number.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | <table><tr><th>Source</th><th>xx</th><th>y</th><th>zz</th></tr><tr><td>Control PCB</td><td>00</td><td>0</td><td>01: Control PCB thermistor 1<br/>02: Control PCB thermistor 2<br/>03: I/O PCB thermistor</td></tr><tr><td>Power system</td><td>Power module number</td><td>0</td><td>00: Temperature feedback provided via power system comms.<table><tr><td></td><th>Frame 7</th><th>Frame 8</th><th>Frame 9 &amp; 10</th></tr><tr><td>21:</td><td>Rectifier thermistor</td><td>Power PCB thermistor 1</td><td>SMPS thermistor</td></tr><tr><td>22:</td><td>Power PCB thermistor</td><td>Power PCB thermistor 2</td><td>Heat Sink Fan SMPS thermistor</td></tr><tr><td>23:</td><td>Power PCB thermistor</td><td>Rectifier thermistor</td><td>Power PCB thermistor</td></tr></table></td></tr><tr><td>Power system</td><td>01</td><td>Rectifier number*</td><td>Always zero</td></tr></table> |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Source | xx      | y                  | zz           | Control PCB | 00                   | 0                      | 01: Control PCB thermistor 1<br>02: Control PCB thermistor 2<br>03: I/O PCB thermistor | Power system       | Power module number  | 0                                                                                                                                                                                     | 00: Temperature feedback provided via power system comms. <table><tr><td></td><th>Frame 7</th><th>Frame 8</th><th>Frame 9 &amp; 10</th></tr><tr><td>21:</td><td>Rectifier thermistor</td><td>Power PCB thermistor 1</td><td>SMPS thermistor</td></tr><tr><td>22:</td><td>Power PCB thermistor</td><td>Power PCB thermistor 2</td><td>Heat Sink Fan SMPS thermistor</td></tr><tr><td>23:</td><td>Power PCB thermistor</td><td>Rectifier thermistor</td><td>Power PCB thermistor</td></tr></table> |                | Frame 7              | Frame 8                    | Frame 9 & 10         | 21:       | Rectifier thermistor | Power PCB thermistor 1 | SMPS thermistor | 22:                        | Power PCB thermistor | Power PCB thermistor 2 | Heat Sink Fan SMPS thermistor | 23: | Power PCB thermistor | Rectifier thermistor       | Power PCB thermistor | Power system | 01                   | Rectifier number* | Always zero |                            |    |    |
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|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Power system                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | 01                   | Rectifier number*      | Always zero                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | * For a parallel power-module system the rectifier number will be zero as it is not possible to determine which rectifier has detected the fault.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Recommended actions:                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| • Hardware fault – Contact the supplier of the drive                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| Th Brake Res                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | Brake resistor over temperature                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| 10                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | The <i>Th Brake Res</i> is initiated, If hardware based braking resistor thermal monitoring is connected and the resistor overheats. If the braking resistor is not used then this trip must be disabled with bit 3 of Action <i>On Trip Detection</i> (10.037) to prevent this trip.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | Recommended actions:                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| • Check brake resistor wiring                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| • Check braking resistor value is greater than or equal to the minimum resistance value                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |
| • Check braking resistor insulation                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |                      |                        |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |         |                    |              |             |                      |                        |                                                                                        |                    |                      |                                                                                                                                                                                       |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                |                      |                            |                      |           |                      |                        |                 |                            |                      |                        |                               |     |                      |                            |                      |              |                      |                   |             |                            |    |    |

| Trip             | Diagnosis                                                                                                                                                                                                                                                              |                             |
|------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------|
| Th Short Circuit | Motor thermistor short circuit                                                                                                                                                                                                                                         |                             |
| 25               | The <i>Th Short Circuit</i> trip indicates that the motor thermistor connected to the drive is short circuit or low impedance i.e. < 50 Ω. The location of the trip can be identified by the sub-trip number.                                                          |                             |
|                  | Sub-trip                                                                                                                                                                                                                                                               | Source                      |
|                  | 3                                                                                                                                                                                                                                                                      | Analog input 3              |
|                  | 4                                                                                                                                                                                                                                                                      | Position feedback interface |
|                  | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Check thermistor continuity</li><li>• Replace motor / motor thermistor</li></ul>                                                                                                                   |                             |
| Thermistor       | Motor thermistor over-temperature                                                                                                                                                                                                                                      |                             |
| 24               | The <i>Thermistor</i> trip indicates that the motor thermistor connected to the drive has indicated a motor over temperature. The location of the trip can be identified by the sub-trip number.                                                                       |                             |
|                  | Sub-trip                                                                                                                                                                                                                                                               | Source                      |
|                  | 3                                                                                                                                                                                                                                                                      | Analog input 3              |
|                  | 4                                                                                                                                                                                                                                                                      | Position feedback interface |
|                  | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Check motor temperature</li><li>• Check <i>Threshold Level</i> (07.048)</li><li>• Check thermistor continuity</li></ul>                                                                            |                             |
| Undefined        | Drive has tripped and the cause of the trip is Undefined                                                                                                                                                                                                               |                             |
| 110              | The <i>Undefined</i> trip indicates that the power system has generated but did not identify the trip from the power system. The cause of the trip is unknown.                                                                                                         |                             |
|                  | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Hardware fault – return the drive to the supplier</li></ul>                                                                                                                                        |                             |
| User 24V         | User 24 V supply is not present on control terminals (1,2)                                                                                                                                                                                                             |                             |
| 91               | A <i>User 24 V</i> trip is initiated, if <i>User Supply Select</i> (Pr 06.072) is set to 1 or <i>Low Under Voltage Threshold Select</i> (06.067) = 1 or <i>Backup Supply Mode Enable</i> (06.068) = 1 and no user 24 V supply is present on control terminals 1 and 2. |                             |
|                  | <b>Recommended actions:</b> <ul style="list-style-type: none"><li>• Ensure the user 24 V supply is present on control terminals 1 (0V) and 2 (24V)</li></ul>                                                                                                           |                             |

| Trip                | Diagnosis                                                                                                                                                                   |                                                                                                                                                                                                                                         |                                                                                                                                                                                                        |
|---------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>User Program</b> | <b>On board user program error</b>                                                                                                                                          |                                                                                                                                                                                                                                         |                                                                                                                                                                                                        |
| 249                 | The <i>User Program</i> trip indicates that an error has been detected in the onboard user program image. The reason for the trip can be identified by the sub-trip number. |                                                                                                                                                                                                                                         |                                                                                                                                                                                                        |
|                     | <b>Sub-trip</b>                                                                                                                                                             | <b>Reason</b>                                                                                                                                                                                                                           | <b>Comments</b>                                                                                                                                                                                        |
|                     | 1                                                                                                                                                                           | Divide by zero                                                                                                                                                                                                                          |                                                                                                                                                                                                        |
|                     | 2                                                                                                                                                                           | Undefined trip                                                                                                                                                                                                                          |                                                                                                                                                                                                        |
|                     | 3                                                                                                                                                                           | Attempted fast parameter access set-up with non-existent parameter                                                                                                                                                                      |                                                                                                                                                                                                        |
|                     | 4                                                                                                                                                                           | Attempted access to non-existent parameter                                                                                                                                                                                              |                                                                                                                                                                                                        |
|                     | 5                                                                                                                                                                           | Attempted write to read-only parameter                                                                                                                                                                                                  |                                                                                                                                                                                                        |
|                     | 6                                                                                                                                                                           | Attempted an over-range write                                                                                                                                                                                                           |                                                                                                                                                                                                        |
|                     | 7                                                                                                                                                                           | Attempted read from write-only parameter                                                                                                                                                                                                |                                                                                                                                                                                                        |
|                     | 30                                                                                                                                                                          | The image has failed because either its CRC is incorrect, or there are less than 6 bytes in the image or the image header version is less than 5.                                                                                       | Occurs when the drive powers-up or the image is programmed. The image tasks will not run                                                                                                               |
|                     | 31                                                                                                                                                                          | The image requires more RAM for heap and stack than can be provided by the drive.                                                                                                                                                       | As 30                                                                                                                                                                                                  |
|                     | 32                                                                                                                                                                          | The image requires an OS function call that is higher than the maximum allowed                                                                                                                                                          | As 30                                                                                                                                                                                                  |
|                     | 33                                                                                                                                                                          | The ID code within the image is not valid                                                                                                                                                                                               | As 30                                                                                                                                                                                                  |
|                     | 40                                                                                                                                                                          | The timed task has not completed in time and has been suspended                                                                                                                                                                         | <i>Onboard User Program: Enable</i> (11.047) is reset to zero when the trip is initiated                                                                                                               |
|                     | 41                                                                                                                                                                          | Undefined function called, i.e. a function in the host system vector table that has not been assigned.                                                                                                                                  | As 40                                                                                                                                                                                                  |
|                     | 52                                                                                                                                                                          | Customized menu table CRC check failed                                                                                                                                                                                                  | As 30                                                                                                                                                                                                  |
|                     | 53                                                                                                                                                                          | Customized menu table changed                                                                                                                                                                                                           | Occurs when the drive powers-up or the image is programmed and the table has changed. Defaults are loaded for the user program menu and the trip will keep occurring until drive parameters are saved. |
|                     | 80                                                                                                                                                                          | Image is not compatible with the control board                                                                                                                                                                                          | Initiated from within the image code                                                                                                                                                                   |
|                     | 81                                                                                                                                                                          | Image is not compatible with the control board serial number                                                                                                                                                                            | As 80                                                                                                                                                                                                  |
|                     | 100                                                                                                                                                                         | Image has detected and prevented attempted pointer access outside of the IEC task's heap area.                                                                                                                                          |                                                                                                                                                                                                        |
|                     | 101                                                                                                                                                                         | Image has detected and prevented misaligned pointer usage.                                                                                                                                                                              |                                                                                                                                                                                                        |
|                     | 102                                                                                                                                                                         | Image has detected an array bounds violation and prevented its access.                                                                                                                                                                  |                                                                                                                                                                                                        |
|                     | 103                                                                                                                                                                         | Image has attempted to convert a data type to or from an unknown data type, has failed and has shut itself down.                                                                                                                        |                                                                                                                                                                                                        |
|                     | 104                                                                                                                                                                         | Image has attempted to use an unknown user service function.                                                                                                                                                                            |                                                                                                                                                                                                        |
|                     | 200                                                                                                                                                                         | User program has invoked a "divide" service with a denominator of zero. (Note that this is raised by the downloaded image and has therefore been given a distinct error code despite being the same fundamental problem as sub-trip 1.) |                                                                                                                                                                                                        |
|                     | 201                                                                                                                                                                         | Parameter access is not supported. An attempt to read database other than the host drive.                                                                                                                                               |                                                                                                                                                                                                        |
|                     | 202                                                                                                                                                                         | Parameter does not exist. Database was host drive but the specified parameter does not exist.                                                                                                                                           |                                                                                                                                                                                                        |
|                     | 203                                                                                                                                                                         | Parameter is read-only.                                                                                                                                                                                                                 |                                                                                                                                                                                                        |
|                     | 204                                                                                                                                                                         | Parameter is write-only.                                                                                                                                                                                                                |                                                                                                                                                                                                        |
|                     | 205                                                                                                                                                                         | Unknown parameter error.                                                                                                                                                                                                                |                                                                                                                                                                                                        |
|                     | 206                                                                                                                                                                         | Invalid bit present in parameter. The parameter does not contain the specified bit.                                                                                                                                                     |                                                                                                                                                                                                        |
|                     | 207                                                                                                                                                                         | Parameter format lookup failed. Failed to get parameter information data.                                                                                                                                                               |                                                                                                                                                                                                        |
|                     | 208                                                                                                                                                                         | An over-range write has been attempted.                                                                                                                                                                                                 |                                                                                                                                                                                                        |

| Trip                       | Diagnosis                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |
|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>User Prog Trip</b>      | <b>Trip generated by an onboard user program</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |
| <b>96</b>                  | <p>This trip can be initiated from within an onboard user program using a function call which defines the sub-trip number.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Check the user program</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |
| <b>User Save</b>           | <b>User Save error / not completed</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |
| <b>36</b>                  | <p>The <i>User Save</i> trip indicates that an error has been detected in the user save parameters saved in non-volatile memory. For example, following a user save command, If the power to the drive was removed when the user parameters were being saved.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Perform a user save in Pr <b>mm.000</b> to ensure that the trip doesn't occur the next time the drive is powered up.</li> <li>• Ensure that the drive has enough time to complete the save before removing the power to the drive.</li> </ul>                                                                                                                                      |
| <b>User Trip</b>           | <b>User generated trip</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| <b>40 -89<br/>112 -159</b> | <p>These trips are not generated by the drive and are to be used by the user to trip the drive through an application program.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Check the user program</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |
| <b>Voltage Range</b>       | <b>Supply voltage out of range detected in Regen mode</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |
| <b>169</b>                 | <p>The <i>Voltage Range</i> trip is initiated, if the Regen <i>Minimum Voltage</i> (03.026) is set to a non-zero value and the supply voltage is outside the range defined by <i>Regen Maximum Voltage</i> (03.027) and <i>Regen Minimum Voltage</i> (03.026) for more than 100 ms.</p> <p><b>Recommended actions:</b></p> <ul style="list-style-type: none"> <li>• Ensure the supply voltage is operating within the drive specification.</li> <li>• Ensure Pr <b>03.026</b> and Pr <b>03.027</b> are set correctly</li> <li>• Check the supply voltage waveform using an oscilloscope</li> <li>• Reduce the level of supply disturbance</li> <li>• Set <i>Maximum Voltage</i> (03.027) to zero to disable the trip.</li> </ul> |
| <b>Watchdog</b>            | <b>Control word watchdog has timed out</b>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| <b>30</b>                  | <p>The <i>Watchdog</i> trip indicates that the control word has been enabled and has timed out.</p> <p><b>Recommended actions:</b></p> <p>Once Pr <b>06.042</b> bit 14 has been changed from 0 to 1 to enable the watchdog, this must be repeated every 1 s or a Watchdog trip will be initiated. The watchdog is disabled when the trip occurs and must be re-enabled if required when the trip is reset.</p>                                                                                                                                                                                                                                                                                                                   |

**Table 13-5 Serial communications look up table**

| No      | Trip              | No        | Trip                | No        | Trip               |
|---------|-------------------|-----------|---------------------|-----------|--------------------|
| 1       | Reserved 001      | 94        | Rectifier Set-up    | 195       | Encoder 7          |
| 2       | Over Volts        | 95        | Reserved 95         | 196       | Encoder 8          |
| 3       | OI ac             | 96        | User Prog Trip      | 198       | Phasing Error      |
| 4       | OI Brake          | 97        | Data Changing       | 199       | Destination        |
| 5       | PSU               | 98        | Out Phase Loss      | 200       | Slot1 HF           |
| 6       | External Trip     | 99        | CAM                 | 201       | Slot1 Watchdog     |
| 7       | Over Speed        | 100       | Reset               | 202       | Slot1 Error        |
| 8       | Inductance        | 101       | OHT Brake           | 203       | Slot1 Not Fitted   |
| 9       | PSU 24V           | 102       | Reserved 102        | 204       | Slot1 Different    |
| 10      | Th Brake Res      | 103       | Inter-connect       | 205       | Slot2 HF           |
| 11      | Autotune 1        | 104 - 108 | Reserved 104 - 108  | 206       | Slot2 Watchdog     |
| 12      | Autotune 2        | 109       | OI dc               | 207       | Slot2 Error        |
| 13      | Autotune 3        | 110       | Undefined           | 208       | Slot2 Not Fitted   |
| 14      | Autotune 4        | 111       | Configuration       | 209       | Slot2 Different    |
| 15      | Autotune 5        | 112 - 159 | User Trip 112 - 159 | 210       | Slot3 HF           |
| 16      | Autotune 6        | 160       | Island              | 211       | Slot3 Watchdog     |
| 17      | Autotune 7        | 161       | Reserved            | 212       | Slot3 Error        |
| 18      | Autotune Stopped  | 162       | Encoder 12          | 213       | Slot3 Not Fitted   |
| 19      | Brake R Too Hot   | 163       | Encoder 13          | 214       | Slot3 Different    |
| 20      | Motor Too Hot     | 164       | Encoder 14          | 215       | Option Disable     |
| 21      | OHT Inverter      | 165 - 168 | Reserved 165 - 168  | 216       | Slot App Menu      |
| 22      | OHT Power         | 169       | Voltage Range       | 217       | App Menu Changed   |
| 23      | OHT Control       | 170 - 173 | Reserved 170 - 173  | 218       | Temp Feedback      |
| 24      | Thermistor        | 174       | Card Slot           | 219       | An Output Calib    |
| 25      | Th Short Circuit  | 175       | Card Product        | 220       | Power Data         |
| 26      | I/O Overload      | 176       | Name Plate          | 221       | Stored HF          |
| 27      | OHT dc bus        | 177       | Card Boot           | 222       | Reserved 222       |
| 28      | An Input Loss 1   | 178       | Card Busy           | 223       | Rating Mismatch    |
| 29      | An Input Loss 2   | 179       | Card Data Exists    | 224       | Drive Size         |
| 30      | Watchdog          | 180       | Card Option         | 225       | Current Offset     |
| 31      | EEPROM Fail       | 181       | Card Read Only      | 226       | Soft Start         |
| 32      | Phase Loss        | 182       | Card Error          | 227       | Sub-array RAM      |
| 33      | Resistance        | 183       | Card No Data        | 228 - 246 | Reserved 228 - 246 |
| 34      | Keypad Mode       | 184       | Card Full           | 247       | Derivative ID      |
| 35      | Control Word      | 185       | Card Access         | 248       | Derivative Image   |
| 36      | User Save         | 186       | Card Rating         | 249       | User Program       |
| 37      | Power Down Save   | 187       | Card Drive Mode     | 250       | Slot4 HF           |
| 38      | Low Load          | 188       | Card Compare        | 251       | Slot4 Watchdog     |
| 39      | Line Sync         | 189       | Encoder 1           | 252       | Slot4 Error        |
| 40 - 89 | User Trip 40 - 89 | 190       | Encoder 2           | 253       | Slot4 Not Fitted   |
| 90      | Power Comms       | 191       | Encoder 3           | 254       | Slot4 Different    |
| 91      | User 24V          | 192       | Encoder 4           | 255       | Reset Logs         |
| 92      | OI Snubber        | 193       | Encoder 5           |           |                    |
| 93      | Inductor Too Hot  | 194       | Encoder 6           |           |                    |

The trips can be grouped into the following categories. It should be noted that a trip can only occur when the drive is not tripped or is already tripped but with a trip with a lower priority number.

**Table 13-6 Trip categories**

| Priority | Category                                                  | Trips                                                                     | Comments                                                                                                                                                                                                                                                                     |
|----------|-----------------------------------------------------------|---------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1        | Internal faults                                           | HFxx                                                                      | These indicate internal problems and cannot be reset. All drive features are inactive after any of these trips occur. If an KI-Keypad is installed it will show the trip, but the keypad will not function.                                                                  |
| 1        | Stored HF trip                                            | {Stored HF}                                                               | This trip cannot be cleared unless 1299 is entered into <i>Parameter (mm.000)</i> and a reset is initiated.                                                                                                                                                                  |
| 2        | Non-resettable trips                                      | Trip numbers 218 to 247, {Slot1 HF}, {Slot2 HF}, {Slot3 HF} or {Slot4 HF} | These trips cannot be reset.                                                                                                                                                                                                                                                 |
| 3        | Volatile memory failure                                   | {EEPROM Fail}                                                             | This can only be reset if Parameter <b>mm.000</b> is set to 1233 or 1244, or if <i>Load Defaults</i> (11.043) is set to a non-zero value.                                                                                                                                    |
| 4        | NV Media Card trips                                       | Trip numbers 174, 175 and 177 to 188                                      | These trips are priority 5 during power-up.                                                                                                                                                                                                                                  |
| 4        | Internal 24V and position feedback interface power supply | {PSU 24V} and {Encoder 1}                                                 | These trips can override {Encoder 2} to {Encoder 6} trips.                                                                                                                                                                                                                   |
| 5        | Trips with extended reset times                           | {OI ac}, {OI Brake}, and {OI dc}                                          | These trips cannot be reset until 10 s after the trip was initiated.                                                                                                                                                                                                         |
| 5        | Phase loss and d.c. link power circuit protection         | {Phase Loss} and {Oht dc bus}                                             | The drive will attempt to stop the motor before tripping if a {Phase Loss}. 000 trip occurs unless this feature has been disabled (see <i>Action On Trip Detection</i> (10.037)). The drive will always attempt to stop the motor before tripping if an {Oht dc bus} occurs. |
| 5        | Standard trips                                            | All other trips                                                           |                                                                                                                                                                                                                                                                              |

## 13.5 Internal / Hardware trips

Trips {HF01} to {HF25} are internal faults that do not have trip numbers. If one of these trips occurs, the main drive processor has detected an irrecoverable error. All drive functions are stopped and the trip message will be displayed on the drive keypad. If a non permanent trip occurs this may be reset by power cycling the drive. On power up after it has been power cycled the drive will trip on Stored HF. The sub-trip code is the number of the original HF trip. Enter 1299 in **mm.000** to clear the Stored HF trip.

## 13.6 Alarm indications

In any mode, an alarm is an indication given on the display by alternating the alarm string with the drive status string on the first row and showing the alarm symbol in the last character in the first row. If an action is not taken to eliminate any alarm except "Auto Tune and Limit Switch" the drive may eventually trip. Alarms are not displayed when a parameter is being edited, but the user will still see the alarm character on the upper row.

**Table 13-7 Alarm indications**

| Alarm string          | Description                                                                                                                                                                             |
|-----------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Brake Resistor</b> | Brake resistor overload. <i>Braking Resistor Thermal Accumulator</i> (10.039) in the drive has reached 75.0 % of the value at which the drive will trip.                                |
| <b>Motor Overload</b> | <i>Motor Protection Accumulator</i> (04.019) in the drive has reached 75.0 % of the value at which the drive will trip and the load on the drive is >100 %.                             |
| <b>Ind Overload</b>   | Regen inductor overload. <i>Inductor Protection Accumulator</i> (04.019) in the drive has reached 75.0 % of the value at which the drive will trip and the load on the drive is >100 %. |
| <b>Drive Overload</b> | Drive over temperature. <i>Percentage Of Drive Thermal Trip Level</i> (07.036) in the drive is greater than 90 %.                                                                       |
| <b>Auto Tune</b>      | The autotune procedure has been initialized and an autotune in progress.                                                                                                                |
| <b>Limit Switch</b>   | Limit switch active. Indicates that a limit switch is active and that is causing the motor to be stopped.                                                                               |

## 13.7 Status indications

**Table 13-8 Status indications**

| Upper row string     | Description                                                                                                                                      | Drive output stage |
|----------------------|--------------------------------------------------------------------------------------------------------------------------------------------------|--------------------|
| <b>Inhibit</b>       | The drive is inhibited and cannot be run. The Safe Torque Off signal is not applied to Safe Torque Off terminals or Pr <b>06.015</b> is set to 0 | Disabled           |
| <b>Ready</b>         | The drive is ready to run. The drive enable is active, but the drive inverter is not active because the final drive run is not active            | Disabled           |
| <b>Stop</b>          | The drive is stopped / holding zero speed.                                                                                                       | Enabled            |
| <b>Run</b>           | The drive is active and running                                                                                                                  | Enabled            |
| <b>Scan</b>          | The drive is enabled in Regen mode and is trying to synchronize to the supply                                                                    | Enabled            |
| <b>Supply Loss</b>   | Supply loss condition has been detected                                                                                                          | Enabled            |
| <b>Deceleration</b>  | The motor is being decelerated to zero speed / frequency because the final drive run has been deactivated.                                       | Enabled            |
| <b>dc injection</b>  | The drive is applying dc injection braking                                                                                                       | Enabled            |
| <b>Position</b>      | Positioning / position control is active during an orientation stop                                                                              | Enabled            |
| <b>Trip</b>          | The drive has tripped and no longer controlling the motor. The trip code appears in the lower display                                            | Disabled           |
| <b>Active</b>        | The regen unit is enabled and synchronized to the supply                                                                                         | Enabled            |
| <b>Under Voltage</b> | The drive is in the under voltage state either in low voltage or high voltage mode                                                               | Disabled           |
| <b>Heat</b>          | The motor pre-heat function is active                                                                                                            | Enabled            |
| <b>Phasing</b>       | The drive is performing a 'phasing test on enable'.                                                                                              | Enabled            |

**Table 13-9 Option module and NV Media Card and other status indications at power-up**

| First row string                                                                                                                                                                                                                                                                                                                         | Second row string     | Status                              |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------|-------------------------------------|
| <b>Booting</b>                                                                                                                                                                                                                                                                                                                           | <b>Parameters</b>     | Parameters are being loaded         |
| Drive parameters are being loaded from a NV Media Card                                                                                                                                                                                                                                                                                   |                       |                                     |
| <b>Booting</b>                                                                                                                                                                                                                                                                                                                           | <b>User Program</b>   | User program being loaded           |
| User program is being loaded from a NV Media Card to the drive                                                                                                                                                                                                                                                                           |                       |                                     |
| <b>Booting</b>                                                                                                                                                                                                                                                                                                                           | <b>Option Program</b> | User program being loaded           |
| User program is being loaded from a NV Media Card to the option module in slot X                                                                                                                                                                                                                                                         |                       |                                     |
| <b>Writing To</b>                                                                                                                                                                                                                                                                                                                        | <b>NV Card</b>        | Data being written to NV Media Card |
| Data is being written to a NV Media Card to ensure that its copy of the drive parameters is correct because the drive is in Auto or Boot mode                                                                                                                                                                                            |                       |                                     |
| <b>Waiting For</b>                                                                                                                                                                                                                                                                                                                       | <b>Power System</b>   | Waiting for power stage             |
| The drive is waiting for the processor in the power stage to respond after power-up                                                                                                                                                                                                                                                      |                       |                                     |
| <b>Waiting For</b>                                                                                                                                                                                                                                                                                                                       | <b>Options</b>        | Waiting for an option module        |
| The drive is waiting for the Options Modules to respond after power-up                                                                                                                                                                                                                                                                   |                       |                                     |
| <b>Uploading From</b>                                                                                                                                                                                                                                                                                                                    | <b>Options</b>        | Loading parameter database          |
| At power-up it may be necessary to update the parameter database held by the drive because an option module has changed or because an applications module has requested changes to the parameter structure. This may involve data transfer between the drive an option modules. During this period 'Uploading From Options' is displayed |                       |                                     |

## 13.8 Programming error indications

Following are the error message displayed on the drive keypad when an error occurs during programming of drive firmware.

**Table 13-10 Programming error indications**

| Error String   | Reason                                                                                       | Solution                                                                             |
|----------------|----------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|
| <b>Error 1</b> | There is not enough drive memory requested by all the option modules.                        | Power down drive and remove some of the option modules until the message disappears. |
| <b>Error 2</b> | At least one option module did not acknowledge the reset request.                            | Power cycle drive                                                                    |
| <b>Error 3</b> | The boot loader failed to erase the processor flash                                          | Power cycle drive and try again. If problem persists, return drive                   |
| <b>Error 4</b> | The boot loader failed to program the processor flash                                        | Power cycle drive and try again. If problem persists, return drive                   |
| <b>Error 5</b> | One option module did not initialize correctly. Option module did not set Ready to Run flag. | Remove faulty option module.                                                         |

## 13.9 Displaying the trip history

The drive retains a log of the last ten trips that have occurred. *Trip 0* (10.020) to *Trip 9* (10.029) store the most recent 10 trips that have occurred where *Trip 0* (10.020) is the most recent and *Trip 9* (10.029) is the oldest. When a new trip occurs it is written to *Trip 0* (10.020) and all the other trips move down the log, with oldest being lost. The date and time when each trip occurs are also stored in the date and time log, i.e. *Trip 0 Date* (10.041) to *Trip 9 Time* (10.060). The date and time are taken from *Date* (06.016) and *Time* (06.017). Some trips have sub-trip numbers which give more detail about the reason for the trip. If a trip has a sub-trip number its value is stored in the sub-trip log, i.e. *Trip 0 Sub-trip Number* (10.070) to *Trip 9 Sub-trip Number* (10.079). If the trip does not have a sub-trip number then zero is stored in the sub-trip log.

If any parameter between Pr **10.020** and Pr **10.029** inclusive is read by serial communication, then the trip number in Table 13-5 is the value transmitted.

### NOTE

The trip logs can be reset by writing a value of 255 in Pr **10.038**.

## 13.10 Behaviour of the drive when tripped

If the drive trips, the output of the drive is disabled so the load coasts to a stop. If any trip occurs the following read only parameters are frozen until the trip is cleared. This is to help in diagnose the cause of the trip.

| Parameter     | Description                                |
|---------------|--------------------------------------------|
| <b>01.001</b> | Frequency / speed reference                |
| <b>01.002</b> | Pre-skip filter reference                  |
| <b>01.003</b> | Pre-ramp reference                         |
| <b>02.001</b> | Post-ramp reference                        |
| <b>03.001</b> | Frequency slaving demand / Final speed ref |
| <b>03.002</b> | Speed feedback                             |
| <b>03.003</b> | Speed error                                |
| <b>03.004</b> | Speed controller output                    |
| <b>04.001</b> | Current magnitude                          |
| <b>04.002</b> | Active current                             |
| <b>04.017</b> | Reactive current                           |
| <b>05.001</b> | Output frequency                           |
| <b>05.002</b> | Output voltage                             |
| <b>05.003</b> | Power                                      |
| <b>05.005</b> | DC bus voltage                             |
| <b>07.001</b> | Analog input 1*                            |
| <b>07.002</b> | Analog input 2*                            |
| <b>07.003</b> | Analog input 3*                            |

\*On *Unidrive M700 / 701* only.

If the parameters are not required to be frozen then this can be disabled by setting bit 4 of Pr **10.037**.

## 14 UL information

### 14.1 UL file reference

All models are UL Listed to both Canadian and US requirements. The UL file reference is: NMMS/7.E171230.

Products that incorporate the Safe Torque Off (STO) function are Certified for Functional Safety. The UL file reference is: FSPC.E171230.

### 14.2 Option modules, kits and accessories

Option Modules, Control Pods, Installation Kits and other accessories for use with these drives are UL Listed.

### 14.3 Enclosure ratings

With the exception of free-standing cubicle drives, all models are Open Type as supplied.

The drive enclosure is not classified as a fire enclosure. A separate fire enclosure must be provided. A UL/ NEMA Type 12 enclosure is suitable. Refer to relevant *Power Installation Guide for further information*.

When fitted with a conduit box the drives meet the requirements for UL Type 1. Type 1 enclosures are intended for indoor use, primarily to provide a degree of protection against limited amounts of falling dirt.

The drives meet the requirements for UL Type 12 when installed inside a Type 12 enclosure and through-hole mounted using the sealing kit and the high-IP insert (where provided).

When through-hole mounted, the drives have been evaluated as suitable for use in surrounding air temperatures up to 40 °C.

Remote Keypads are UL Type 12 when installed with the sealing washer and fixing kit provided.

When installed in a Type 1 or Type 12 enclosure, the drives may be operated in a compartment handling conditioned air. Refer to relevant *Power Installation Guide for further information*.

### 14.4 Mounting

Drives may be surface, through-panel or tile mounted using the appropriate brackets. Drives may be mounted singly or side by side with suitable space between them (bookcase mounting). Refer to relevant *Power Installation Guide for further information*.

### 14.5 Environment

Drives must be installed in a Pollution Degree 2 environment or better (dry, non-conductive pollution only).

The drives have been evaluated for use at ambient temperatures up to 40 °C. The drives have additionally been evaluated for 50 °C and 55 °C ambient air temperatures with a derated output. Refer to relevant *Power Installation Guide for further information*.

### 14.6 Electrical Installation

#### OVERVOLTAGE CATEGORY

OVC III

#### SUPPLY

The drives are suitable for use on a circuit capable of delivering not more than 100,000 RMS symmetrical amperes, 600 Volts AC Maximum.

#### TERMINAL TORQUE

Terminals must be tightened to the rated torque as specified in the Installation Instructions. Refer to relevant *Power Installation Guide for further information*.

#### WIRING TERMINALS

Drives must be installed using cables rated for 75 °C operation, copper wire only.

Where possible, UL Listed closed-loop connectors sized according to the field wiring shall be used for all field power wiring connections. Refer to relevant *Power Installation Guide for further information*.

#### GROUND CONNECTION INSTRUCTIONS

UL Listed closed-loop connectors sized according to the field wiring shall be used for grounding connections. Refer to relevant *Power Installation Guide for further information*.

#### BRANCH CIRCUIT PROTECTION

The fuses and circuit breakers required for branch circuit protection are specified in the Installation Instructions. Refer to relevant *Power Installation Guide for further information*.

#### OPENING OF BRANCH CIRCUIT

Opening of the branch-circuit protective device may be an indication that a fault has been interrupted. To reduce the risk of fire or electric shock, the equipment should be examined and replaced if damaged. If burnout of the current element of an overload relay occurs, the complete overload relay must be replaced.

Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electrical Code (NEC), The Canadian Electrical Code, and any additional local codes.

## REGENERATIVE OPERATION

Drives can be configured as an AC Regenerative Unit (also known as a Regen drive). Regen operation allows bi-directional power flow to and from the AC supply. The AC supply voltage must not exceed 600 Vac. Contact the supplier of the drive for more information on building a Regen system.

### 14.7 Motor overload protection and thermal memory retention

All drives incorporate internal overload protection for the motor load that does not require the use of an external or remote overload protection device.

The protection level is adjustable and the method of adjustment is provided in section 8.4 *Motor thermal protection* on page 108. Maximum current overload is dependent on the values entered into the current limit parameters (motoring current limit, regenerative current limit and symmetrical current limit entered as percentage) and the motor rated current parameter (entered in amperes).

The duration of the overload is dependent on motor thermal time constant. The maximum programmable time constant depends on the drive model. The method of adjustment of the overload protection is provided. Refer to the relevant *Power Installation Guide for further information*.

The drives are provided with user terminals that can be connected to a motor thermistor to protect the motor from high temperature, in the event of a motor cooling fan failure. Refer to the relevant *Power Installation Guide for further information*.

### 14.8 External Class 2 supply

The external power supply used to power the 24 V control circuit shall be marked: "UL Class 2". The power supply voltage shall not exceed 24 Vdc. Refer to the relevant *Power Installation Guide for further information*.

### 14.9 Modular Drive Systems

Drives with DC+ and DC- supply connections, rated 230 V or 480 V have been investigated for use in Modular Drive Systems as inverters when supplied by the converter sections from the Unidrive-M range. In these applications the inverters are required to be additionally protected by supplemental fuses.

Alternatively, the inverters may be supplied by converter models: Mentor MP25A, 45A, 75A, 105A, 155A or 210A.

Modular drives with frame sizes 9, 10 and 11 are not certified for Canada when used in a modular/parallel setup without DC fuses.

Contact the supplier of the drive for more information.

### 14.10 Requirement for Transient Surge Suppression

This requirement only applies to Frame Size 7 drives with rated input voltage = 575 V.

TRANSIENT SURGE SUPPRESSION SHALL BE INSTALLED ON THE LINE SIDE OF THIS EQUIPMENT AND SHALL BE RATED 575 Vac (PHASE TO GROUND), 575 Vac (PHASE TO PHASE), SUITABLE FOR OVERVOLTAGE CATEGORY III, AND SHALL PROVIDE PROTECTION FOR A RATED IMPULSE VOLTAGE TO WITHSTAND VOLTAGE PEAK OF 6 kV AND A CLAMPING VOLTAGE OF MAXIMUM 2400 V.

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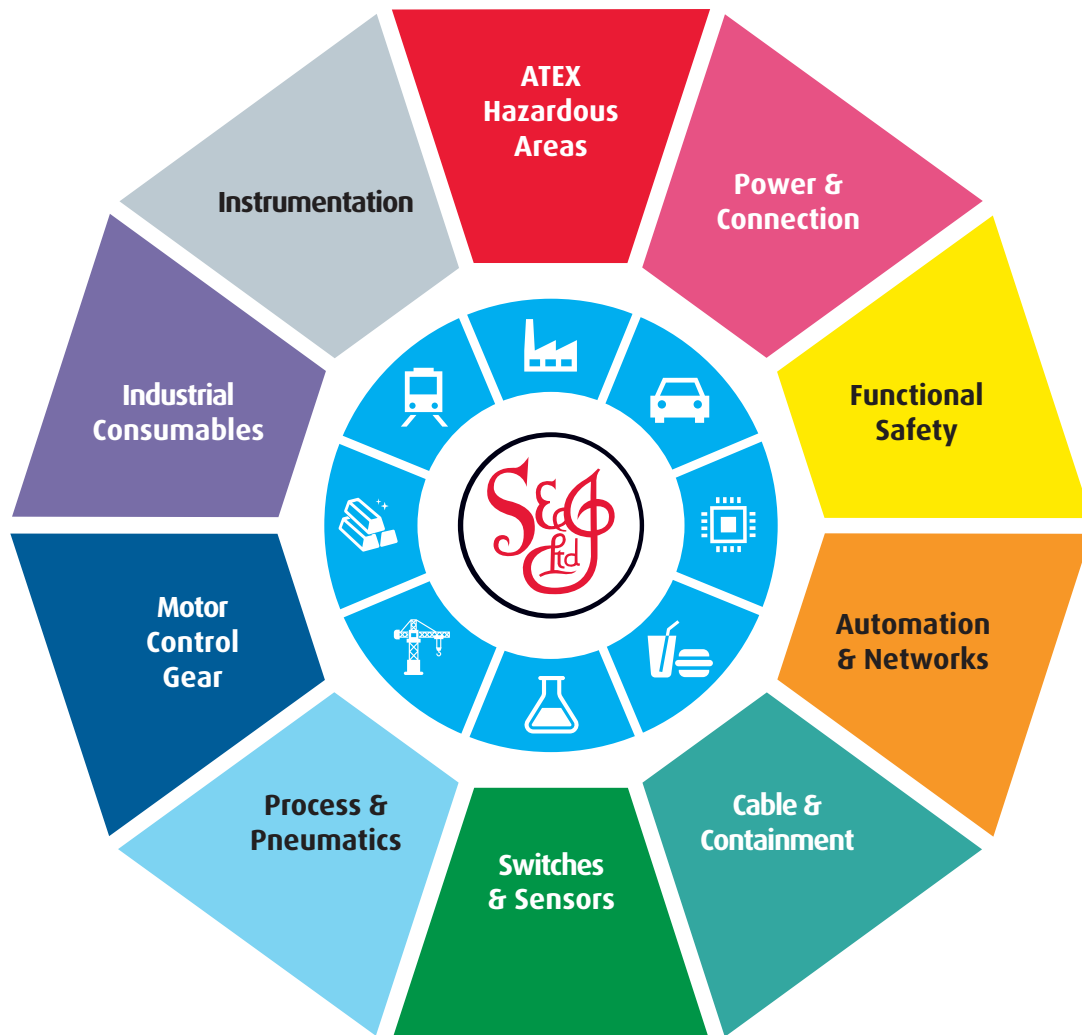
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